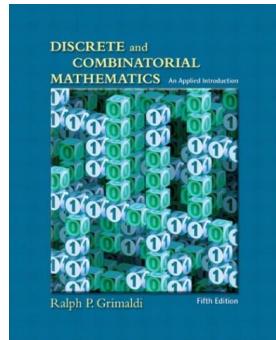
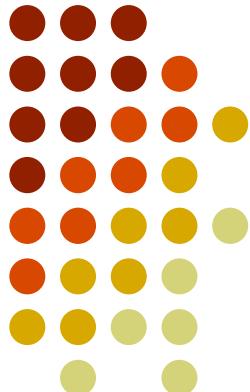


Discrete Mathematics

-- *Chapter 7: Relations: The Second Time Round*



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Outline

- Relations Revisited: Properties of Relations
- Computer Recognition: Zero-One Matrices and Directed Graphs
- **Partial Orders:** Hasse Diagrams
- **Equivalence Relations** and Partitions
- Finite State Machine: The Minimization Process
 - Application of equivalence relation
 - Minimization process: find a machine with the same function but fewer internal states



7.1 Relations Revisited: Properties of Relations

- Definition 7.1: For sets A, B, any subset of $A \times B$ is called a (binary) relation from A to B. Any subset of $A \times A$ is called a (binary) relation on A .
- **Ex 7.1**
 - Define the relation \mathfrak{R} on the set Z by $a\mathfrak{R}b$, if $a \leq b$.
 - For $x, y \in Z$ and $n \in Z^+$, the modulo n relation \mathfrak{R} is defined by $x\mathfrak{R}y$ if $x - y$ is a multiple of n , e.g., with $n=7$, $9\mathfrak{R}2$, $-3\mathfrak{R}11$, but $3 \not\mathfrak{R} 7$
- **Ex 7.2** : Language $A \subseteq \Sigma^*$. For $x, y \in A$, define $x\mathfrak{R}y$ if x is a prefix of y.

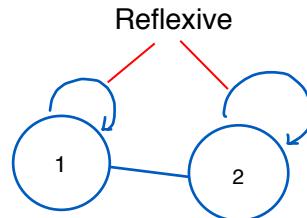


Relations Revisited: Properties of Relations

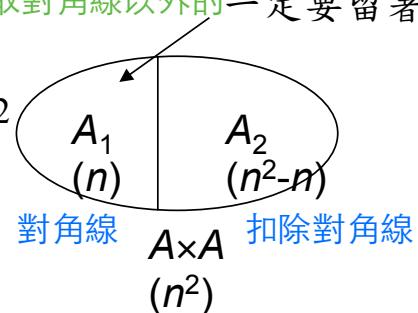
- Finite state machine $M = (S, I, O, v, w)$
 - Reachability
 - $s_1 \mathfrak{R} s_2$ if $v(s_1, x) = s_2, x \in I$. \mathfrak{R} denotes the first level of reachability.
 - $s_1 \mathfrak{R} s_2$ if $v(s_1, x_1 x_2) = s_2, x_1 x_2 \in I^2$. \mathfrak{R} denotes the second level of reachability.
 - Equivalence
 - 1-equivalence relation: $s_1 E_1 s_2$ if $w(s_1, x) = w(s_2, x)$ for $x \in I$.
 - k -equivalence relation: $s_1 E_k s_2$ if $w(s_1, y) = w(s_2, y)$ for $y \in I^k$.
 - If two states are k -equivalent for **all $k \in \mathbb{Z}^+$** , they are called equivalent.



Reflexive



- Definition 7.2: A relation \mathfrak{R} on a set A is called **reflexive** if $(x, x) \in \mathfrak{R}$, for all $x \in A$. 自己指向自己
- **Ex 7.4** : For $A = \{1, 2, 3, 4\}$, a relation $\mathfrak{R} \subseteq A \times A$ will be reflexive if and only if $\mathfrak{R} \subseteq \{(1, 1), (2, 2), (3, 3), (4, 4)\}$. But $\mathfrak{R}_1 = \{(1, 1), (2, 2), (3, 3)\}$ is not reflexive, $\mathfrak{R}_2 = \{(x, y) | x \leq y, x, y \in A\}$ is reflexive.
- **Ex 7.5** : Given a finite set A with $|A| = n$, we have $|A \times A| = n^2$, so there are 2^{n^2} relations on A . Among them $2^{(n^2-n)}$ are reflexive.
 - $A = \{a_1, a_2, \dots, a_n\}$ 對角線的留著，取或不取對角線以外的一定要留著
 - $A \times A = \{(a_i, a_j) | 1 \leq i, j \leq n\} = A_1 \cup A_2$
 - $A_1 = \{(a_i, a_i) | 1 \leq i \leq n\}$
 - $A_2 = \{(a_i, a_j) | i \neq j, 1 \leq i, j \leq n\}$





Symmetric

- Definition 7.3: A relation \mathfrak{R} on a set A is called symmetric if for all $x, y \in A$, if $(x, y) \in \mathfrak{R} \Rightarrow (y, x) \in \mathfrak{R}$.
- Ex 7.6 : $A = \{1, 2, 3\}$
 - $\mathfrak{R}_1 = \{(1, 2), (2, 1), (1, 3), (3, 1)\}$, symmetric, but not reflexive.
 - $\mathfrak{R}_2 = \{(1, 1), (2, 2), (3, 3), (2, 3)\}$, reflexive, but not symmetric.
 - $\mathfrak{R}_3 = \{(1, 1), (2, 2), (3, 3)\}$ and $\mathfrak{R}_4 = \{(1, 1), (2, 2), (3, 3), (2, 3), (3, 2)\}$, both reflexive and symmetric.
 - $\mathfrak{R}_5 = \{(1, 1), (2, 3), (3, 3)\}$, neither reflexive nor symmetric.

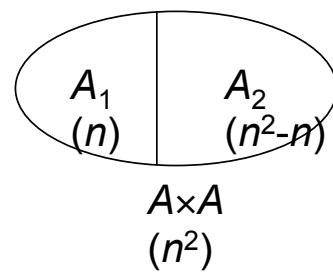


Symmetric

- To count the symmetric relations on $A = \{a_1, a_2, \dots, a_n\}$.
 - $A \times A = A_1 \cup A_2$, $A_1 = \{(a_i, a_i) | 1 \leq i \leq n\}$, $A_2 = \{(a_i, a_j) | i \neq j, 1 \leq i, j \leq n\}$
 - A_1 contains n pairs, and A_2 contains n^2-n pairs.
 - A_2 contains $(n^2-n)/2$ subsets $S_{i,j}$ of the form $\{(a_i, a_j), (a_j, a_i) | i < j\}$.
 - So, we have totally $2^n \times 2^{(1/2)(n^2-n)}$ symmetric relations on A.
 對角線 上三角
- If the relations are both reflexive and symmetric, we have $2^{(1/2)(n^2-n)}$ choices.

↓

1





Transitive

- Definition 7.4: A relation \mathfrak{R} on a set A is called **transitive** if $(x, y), (y, z) \in \mathfrak{R} \Rightarrow (x, z) \in \mathfrak{R}$ for all $x, y, z \in A$.
- Ex 7.8 : Define the relation \mathfrak{R} on the set Z^+ by $a \mathfrak{R} b$ if a divides b . This is a transitive and reflexive relation but not symmetric.
- Ex 7.9 : Define the relation \mathfrak{R} on the set Z by $a \mathfrak{R} b$ if $a \times b \geq 0$. What properties do they have?
 - Reflexive, symmetric
 - Not transitive, e.g., $(3, 0), (0, -7) \in \mathfrak{R}$, but $(3, -7)$ not



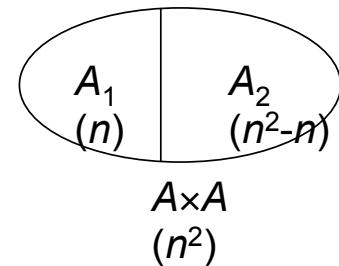
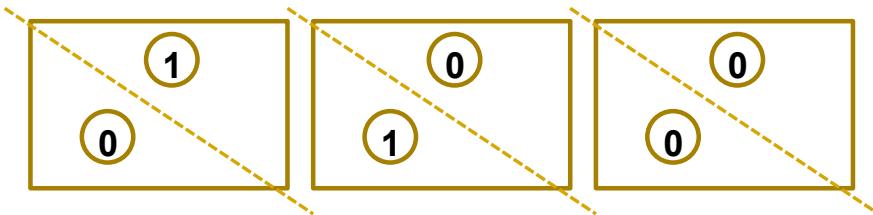
Antisymmetric

- Definition 7.5: A relation \mathfrak{R} on a set A is called **antisymmetric** if $(x, y) \in \mathfrak{R}$ and $(y, x) \in \mathfrak{R} \Rightarrow x = y$ for all $x, y \in A$.
 - Both **a** related to **b** and **b** related to **a**, if **a** and **b** are one and the same element from A
- **Ex 7.11** : Define the relation $(A, B) \in \mathfrak{R}$ if $A \subseteq B$. Then it is an anti-symmetric relation.
- Note that “*not symmetric*” is different from anti-symmetric.
- **Ex 7.12** : $A = \{1, 2, 3\}$, what properties do the following relations on A have?
 - $\mathfrak{R} = \{(1, 2), (2, 1), (2, 3)\}$ (not symmetric, not antisymmetric)
 - $\mathfrak{R} = \{(1, 1), (2, 2)\}$ (symmetric and antisymmetric)



Antisymmetric

- To count the antisymmetric relations on $A = \{a_1, a_2, \dots, a_n\}$.
 - $A \times A = A_1 \cup A_2$, $A_1 = \{(a_i, a_i) | 1 \leq i \leq n\}$, $A_2 = \{(a_i, a_j) | i \neq j, 1 \leq i, j \leq n\}$
 - A_1 contains n pairs, and A_2 contains n^2-n pairs.
 - A_2 contains $(n^2-n)/2$ subsets $S_{i,j}$ of the form $\{(a_i, a_j), (a_j, a_i) | i < j\}$.
 - Each element in A_1 can be selected or not.
 - Each element in $S_{i,j}$ can be selected **in three alternatives**: either (a_i, a_j) , or (a_j, a_i) , or none.
 - So, we have totally $2^n \times 3^{(1/2)(n^2-n)}$ anti-symmetric relations on A.





Antisymmetric

- **Ex 7.13** : Define the relation \mathfrak{R} on the functions by $f \mathfrak{R} g$ if f is dominated by g (or $f \in O(g)$). What are their properties?
 - Reflexive
 - Transitive
 - not symmetric (e.g., $g=n, f=n^2, g=O(f)$, but $f \neq O(g)$)
 - not antisymmetric (e.g., $g(n)=n, f(n)=n+5, f \mathfrak{R} g$ and $g \mathfrak{R} f$, but $f \neq g$)



Example

- $A = \{a_1, a_2, \dots, a_n\}$, students in class discrete math.
- a relation R on a set A , if $(a_i, a_j) \in R$, the midterm score $(a_i) \geq$ midterm score (a_j)
 - No equal score
- R is reflexive
- R is transitive
- R is not symmetric
- R is antisymmetric



Partial Order

- Definition 7.6: A relation \mathfrak{R} is called a partial order (partial ordering relation), if \mathfrak{R} is *reflexive, anti-symmetric and transitive*.
- (A, R) is a **partially ordered set / poset** if R is a partial ordering on A . Typical notation: (A, \leq) ;
 - “**no loops**”
- If $a \leq b$ or $b \leq a$, the elements a and b are **comparable**.
- If all pairs are comparable, \leq is a **total ordering** or **chain**.



Partial Order

- **Ex 7.15 :** Let A be the set of positive integers divisors of n , the relation \mathfrak{R} on A by $a \mathfrak{R} b$ if a divides b , it defines a *partial order*. How many ordered pairs does it occur in \mathfrak{R} .
 - E.g. $n=12$, $A = \{1, 2, 3, 4, 6, 12\}$, $\mathfrak{R} = \{(1, 1), (1, 2), (1, 3), (1, 4), (1, 6), (1, 12), (2, 2), (2, 4), (2, 6), (2, 12), (3, 3), (3, 6), (3, 12), (4, 4), (4, 12), (6, 6), (6, 12), (12, 12)\}$
 - If $(a, b) \in \mathfrak{R}$, then $a = 2^m \cdot 3^n$ and $b = 2^p \cdot 3^q$ with $0 \leq m \leq p \leq 2$, $0 \leq n \leq q \leq 1$.
 - Selection of size 2 from a set of size 3, with **repetition**.

$$\binom{3+2-1}{2} = \binom{4}{2} = 6 \text{ for } m, p; \binom{2+2-1}{2} = \binom{3}{2} = 3 \text{ for } n, q$$

$$\therefore \text{total} = 6 \cdot 3 = 18 \text{ ordered pairs}$$

- For $n = p_1^{e_1} p_2^{e_2} \cdots p_k^{e_k} \Rightarrow$ the number of ordered pairs = $\prod_{i=1}^k \binom{(e_i+1)+2-1}{2} = \prod_{i=1}^k \binom{e_i+2}{2}$

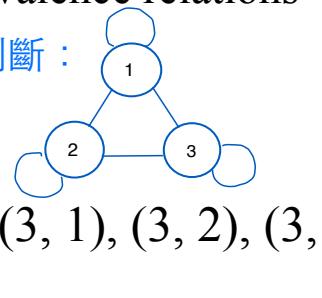
Maximal element



Equivalence relation

- Definition 7.7. A relation \mathfrak{R} is called an equivalence relation, if \mathfrak{R} is *reflexive, symmetric and transitive*.
- Given an equivalence relation R on A , for each $a \in A$ the equivalence class $[a]$ is defined by $\{x \mid (x,a) \in R\}$.
 - E.g., Modulo 3 equivalences on \mathbb{Z} , such that $[0] = \{\dots, -6, -3, 0, 3, 6, \dots\}$ and $[1] = \{\dots, -5, -2, 1, 4, 7, \dots\}$
- Ex 7.16(b): If $A = \{1, 2, 3\}$, the following are all equivalence relations
 - $\mathfrak{R}_1 = \{(1, 1), (2, 2), (3, 3)\}$
 - $\mathfrak{R}_2 = \{(1, 1), (2, 2), (3, 3), (2, 3), (3, 2)\}$
 - $\mathfrak{R}_3 = \{(1, 1), (1, 3), (2, 2), (3, 1), (3, 3)\}$
 - $\mathfrak{R}_4 = \{(1, 1), (1, 2), (1, 3), (2, 1), (2, 2), (2, 3), (3, 1), (3, 2), (3, 3)\}$

畫點判斷：





Examples

- **Ex 7.16 (c):** For a finite set A , $A \times A$ is the largest equivalence relation on A . If $A = \{a_1, a_2, \dots, a_n\}$, then the equality relation $\mathfrak{R} = \{(a_i, a_i) | 1 \leq i \leq n\}$ is the smallest equivalence relation on A .
- **Ex 7.16 (d):** Let $A = \{1, 2, 3, 4, 5, 6, 7\}$, $B = \{x, y, z\}$, and $f: A \rightarrow B$ be the onto function. $f = \{(1, x), (2, z), (3, x), (4, y), (5, z), (6, y), (7, x)\}$. Define the relation \mathfrak{R} on A by $a \mathfrak{R} b$ if $f(a) = f(b)$.
 \mathfrak{R} is reflexive, symmetric, and transitive, so it is an equivalence relation.
(e.g., $f(a)=f(b), f(b)=f(c) \Rightarrow f(a)=f(c)$)
使用equivalence relation 分群 : $f1 = \{(1,x) (3,x) (7,x)\}$, $f2 = \{(4,y) (6,y)\}$, $f3 = \{(2,z) (5,z)\}$
- **Ex 7.16 (e):** If \mathfrak{R} is a relation on A , then \mathfrak{R} is both an equivalence relation and a partial order relation iff \mathfrak{R} is the equality relation on A .
 - equality relation $\{(a_i, a_i) | a_i \in A\}$ 對角線

滿足reflexive, symmetric, transitive, antisymmetric



7.2 Computer Recognition: Zero-One Matrices and Directed Graphs

- Definition 7.8: Let relations $\mathfrak{R}_1 \subseteq A \times B$ and $\mathfrak{R}_2 \subseteq B \times C$. The composite relation $\mathfrak{R}_1 \circ \mathfrak{R}_2$ is a relation defined by $\mathfrak{R}_1 \circ \mathfrak{R}_2 = \{(x, z) \mid \exists y \in B \text{ such that } (x, y) \in \mathfrak{R}_1 \text{ and } (y, z) \in \mathfrak{R}_2\}$. 有順序性
(Note the different ordering with function composition.)
 $f : A \rightarrow B, \quad g : B \rightarrow C, \quad g \circ f : A \rightarrow C$
- Ex 7.17 : Consider $\mathfrak{R}_1 = \{(1, x), (2, x), (3, y), (3, z)\}$ and $\mathfrak{R}_2 = \{(w, 5), (x, 6)\}$, and $\mathfrak{R}_3 = \{(w, 5), (w, 6)\}$. $\mathfrak{R}_1 \circ \mathfrak{R}_2 = \{(1, 6), (2, 6)\}$, and $\mathfrak{R}_1 \circ \mathfrak{R}_3 \cancel{\in} ?$
- Ex 7.18 : Let A be the set of employees {L. Alldredge, ...} at a computer center, while B denotes a set of programming language {C++, Java, ...}, and C is a set of projects $\{p_1, p_2, \dots\}$, consider $\mathfrak{R}_1 \subseteq A \times B$, $\mathfrak{R}_2 \subseteq B \times C$. What is the means of $\mathfrak{R}_1 \circ \mathfrak{R}_2$?

join operation in database



Composite Relation

- Theorem 7.1: $\mathfrak{R}_1 \subseteq A \times B$, $\mathfrak{R}_2 \subseteq B \times C$, and $\mathfrak{R}_3 \subseteq C \times D \Rightarrow \mathfrak{R}_1 \circ (\mathfrak{R}_2 \circ \mathfrak{R}_3) = (\mathfrak{R}_1 \circ \mathfrak{R}_2) \circ \mathfrak{R}_3$
- Definition 7.9. We define the powers of relation \mathfrak{R} by (a) $\mathfrak{R}^1 = \mathfrak{R}$; (b) $\mathfrak{R}^{n+1} = \mathfrak{R} \circ \mathfrak{R}^n$.
- **Ex 7.19** : If $\mathfrak{R} = \{(1, 2), (1, 3), (2, 4), (3, 2)\}$, then $\mathfrak{R}^2 = \{(1, 4), (1, 2), (3, 4)\}$, $\mathfrak{R}^3 = ?$ and $\mathfrak{R}^4 = ?$

$$\begin{aligned}\mathfrak{R}^3 &= \{(1, 4)\} \\ \text{and for } n \geq 4, \mathfrak{R}^n &= \emptyset\end{aligned}$$

$$\begin{aligned}\mathfrak{R}^2 &= \mathfrak{R} \circ \mathfrak{R} \\ \mathfrak{R}^3 &= \mathfrak{R}^2 \circ \mathfrak{R}\end{aligned}$$



Relation Matrix

- Definition 7.10: An $m \times n$ zero-one matrix $E = (e_{ij})_{m \times n}$ is a rectangular array of numbers arranged in m rows and n columns, where each e_{ij} denotes the entry in the i th row and j th column of E , and each such entry is 0 or 1.
- **Relation matrix:** A relation can be represented by an $m \times n$ zero-one matrix.
1 : 存在relation 0 : 無relation
- **Ex 7.21 :** Consider $\mathfrak{R}_1 = \{(1, x), (2, x), (3, y), (3, z)\}$, $\mathfrak{R}_2 = \{(w, 5), (x, 6)\}$, and $\mathfrak{R}_1 \circ \mathfrak{R}_2$ to be represented by relation matrices?

$$M(\mathfrak{R}_1) = \begin{pmatrix} (w) & (x) & (y) & (z) \\ (1) & 0 & 1 & 0 & 0 \\ (2) & 0 & 1 & 0 & 0 \\ (3) & 0 & 0 & 1 & 1 \\ (4) & 0 & 0 & 0 & 0 \end{pmatrix}, \quad M(\mathfrak{R}_2) = \begin{pmatrix} (5) & (6) & (7) \\ (w) & 1 & 0 & 0 \\ (x) & 0 & 1 & 0 \\ (y) & 0 & 0 & 0 \\ (z) & 0 & 0 & 0 \end{pmatrix}$$

$$M(\mathfrak{R}_1) \cdot M(\mathfrak{R}_2) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{pmatrix} (5) & (6) & (7) \\ (1) & 0 & 1 & 0 \\ (2) & 0 & 1 & 0 \\ (3) & 0 & 0 & 0 \\ (4) & 0 & 0 & 0 \end{pmatrix} = M(\mathfrak{R}_1 \circ \mathfrak{R}_2).$$

Boolean addition' with $1+1=1$

OR



Relation Matrix

- **Ex 7.22:** If $\mathfrak{R}=\{(1, 2), (1, 3), (2, 4), (3, 2)\}$, then what are the relation matrices of \mathfrak{R}^2 , \mathfrak{R}^3 and \mathfrak{R}^4 ?

$$M(\mathfrak{R}) = \begin{bmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$(M(\mathfrak{R}))^4 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$(M(\mathfrak{R}))^2 = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$



Relation Matrix

- Let A be a set with $|A| = n$ and \mathfrak{R} be a relation on A . If $M(\mathfrak{R})$ is the relation matrix for \mathfrak{R} , then
 - $M(\mathfrak{R}) = \mathbf{0}$ if and only if $\mathfrak{R} = \emptyset$.
 - $M(\mathfrak{R}) = \mathbf{1}$ if and only if $\mathfrak{R} = A \times A$.
 - $M(\mathfrak{R}^m) = [M(\mathfrak{R})]^m$
- Definition 7.11: Let $E = (e_{ij})_{m \times n}$, $F = (f_{ij})_{m \times n}$ be two $m \times n$ zero-one matrices. We say that E precedes, or is less than, F , written as $E \leq F$, if $e_{ij} \leq f_{ij}$ for all i, j .
- Ex 7.23 : $E \leq F$. How many zero-one matrices G do have the results of $E \leq G$?

$$E = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \quad F = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \quad G = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

$$2^3=8$$



Relation Matrix

- Definition 7.12: $I_n = (\delta_{ij})_{n \times n}$ is the $n \times n$ zero-one matrix, where

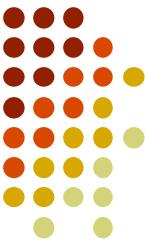
$$\delta_{ij} = \begin{cases} 1, & \text{if } i = j, \\ 0, & \text{if } i \neq j, \end{cases}$$

- Definition 7.13: $A = (a_{ij})_{m \times n}$ is a zero-one matrix, the transpose of A , written A^{tr} , is the matrix $(a^*_{ji})_{n \times m}$ where $a^*_{ji} = a_{ij}$

- Ex 7.24 :

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \\ 1 & 1 \end{bmatrix} \quad A^{\text{tr}} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

- **Theorem 7.2:** If M denote the relation matrix for \mathfrak{R} on A , then
 - (A) \mathfrak{R} is reflexive if and only if $I_n \leq M$.
 - (B) \mathfrak{R} is symmetric if and only if $M = M^{\text{tr}}$.
 - (C) \mathfrak{R} is transitive if and only if $M^2 \leq M$.
 - (D) \mathfrak{R} is anti-symmetric if and only if $M \cap M^{\text{tr}} \leq I_n$.



Directed Graph

relation具有方向性

- Definition 7.14. A directed graph can be denoted as $G = (V, E)$, where V is the vertex set and E is the edge set.
 - (a, b) : if $a, b \in V$, $(a, b) \in E$, then there is a edge from a to b . Vertex a is called source (origin) of the edge, and b is terminating vertex.
 - (a, a) : is called a loop.
- $V = \{1, 2, 3, 4, 5\}$, $E = \{(1, 1), (1, 2), (1, 4), (3, 2)\}$
 - Isolated vertex: vertex 5 in Fig. 7.1.
- Single undirected edge $\{a, b\} = \{b, a\}$ in Fig. 7.2 (b) is used to represent the two directed edges shown in Fig. 7.2 (a).

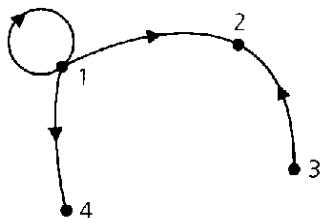


Figure 7.1

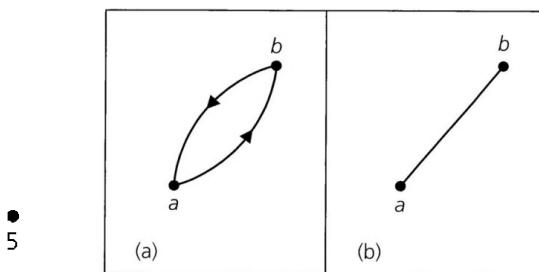


Figure 7.2



Directed Graph

- Ex 7.26 precedence graph

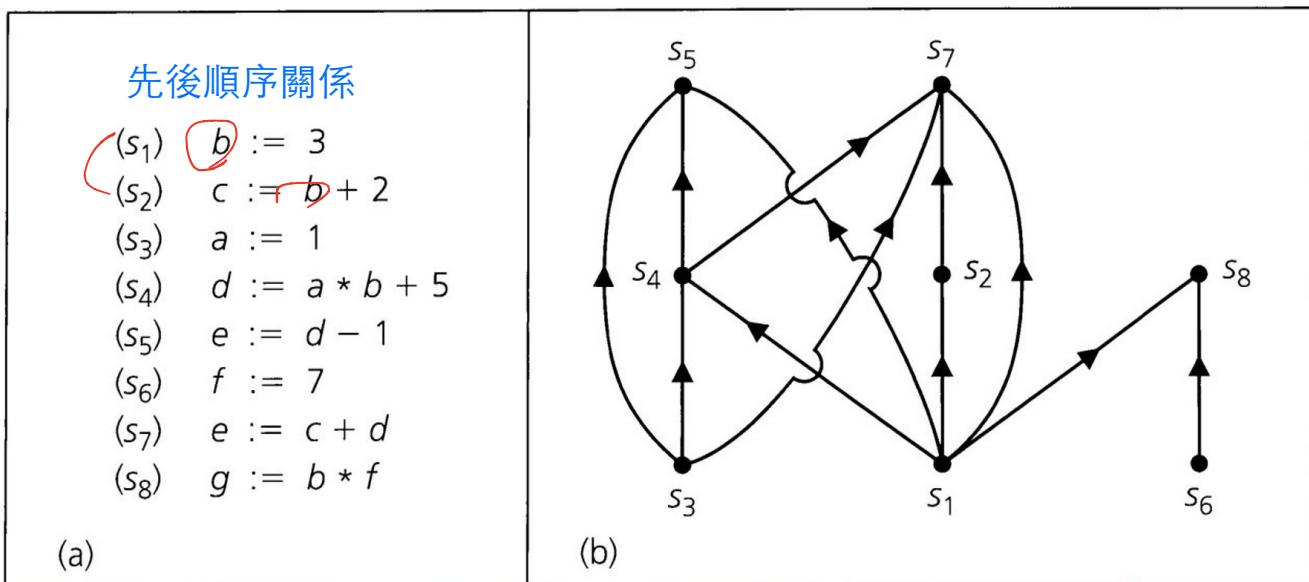


Figure 7.3



Directed Graph

- Ex 7.27 : $R = \{(1,1),(1,2),(2,3),(3,2),(3,3),(3,4),(4,2)\}$
 - directed graph in Fig. 7.4 (a)
 - (associated) undirected graph in Fig. 7.4 (b)
 - **path**: In the connected graph, any two vertices x, y , with $x \neq y$, there is a **path** starting at x and ending at y .
 - **cycle**: a closed path starts and terminates at the same vertex, containing at least three edges.
 - E.g.: $\{3, 4\}$, $\{4, 2\}$, and $\{2, 3\}$

No repeated vertex

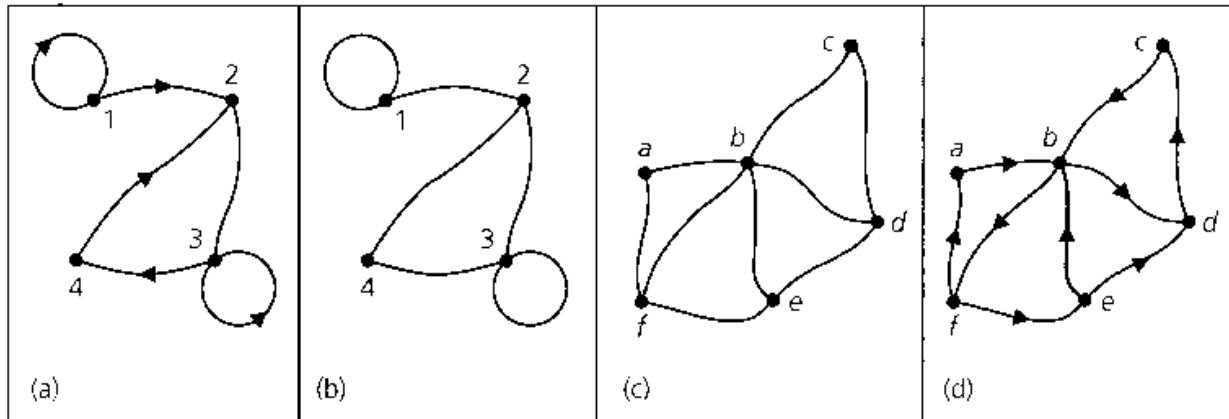


Figure 7.4



Directed Graph

- Definition 7.15: A directed graph G on V is called **strongly connected**, if for all $x, y \in V$, where $x \neq y$, there is a path (in G) of directed edges from x to y .
 - e.g., Fig. 7.5
- **Disconnected graph:** is the union of two connected pieces called the components of the graph.
 - e.g., Fig. 7.6

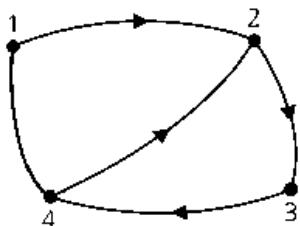


Figure 7.5

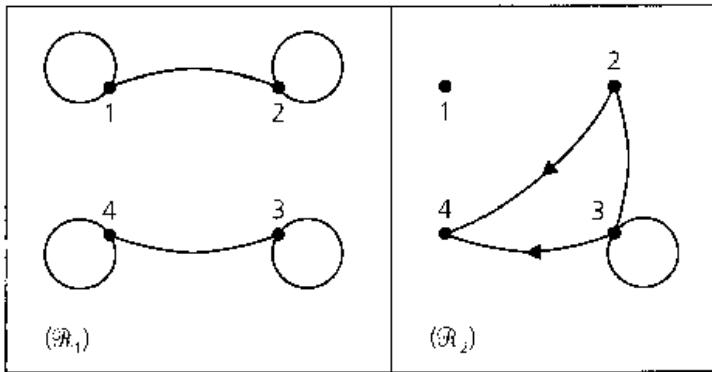


Figure 7.6



Directed Graph

- **Complete graph:** the graphs of undirected graphs that are loop-free and have an edge for every pair of distinct vertices, which are denoted by K_n .
 - e.g., Fig. 7.7

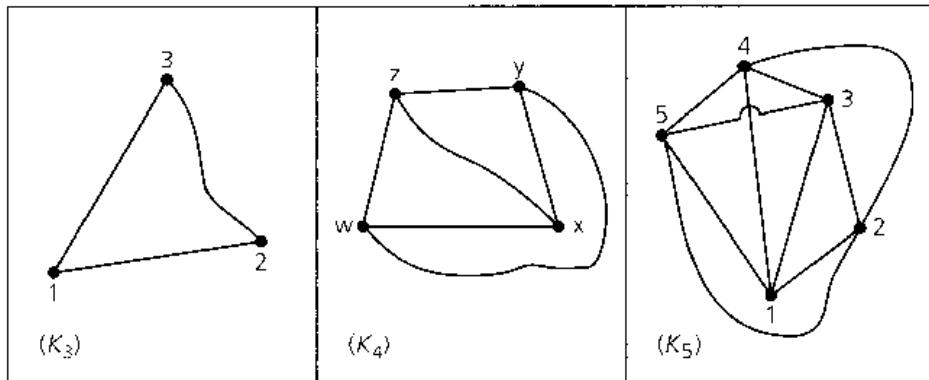
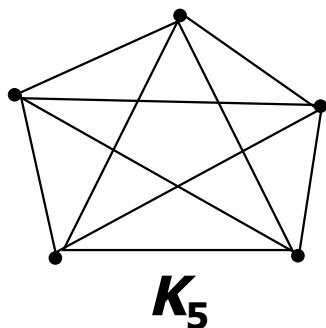
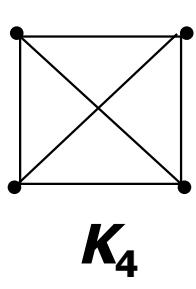
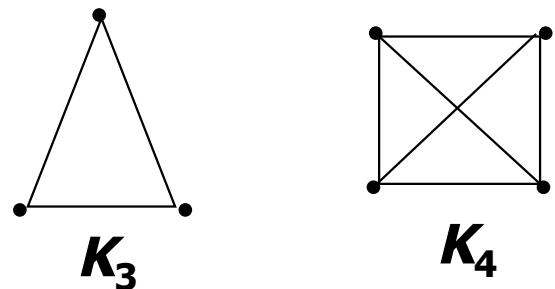
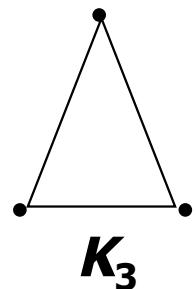
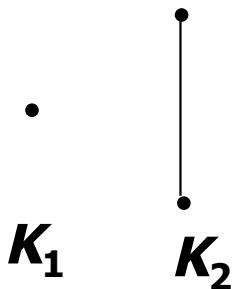


Figure 7.7





Directed Graph

- **Ex 7.30** : \mathfrak{R} is reflexive if and only if its directed graph contains a loop at each vertex. 每點都有一個loop指向自己
 - e.g., Fig 7.8, $A = \{1, 2, 3\}$ and $\mathfrak{R} = \{(1,1), (1, 2), (2, 2), (3, 3), (3, 1)\}$
- **Ex 7.31** : \mathfrak{R} is symmetric if and only if its directed graph may be drawn only by loops and undirected edges. 不會有direct edge
 - e.g., Fig 7.9, $A = \{1, 2, 3\}$ and $\mathfrak{R} = \{(1,1), (1, 2), (2, 1), (2, 3), (3, 2)\}$
- **Ex 7.32** : \mathfrak{R} is anti-symmetric if and only if for any $x \neq y$ the graph contains at most one of the edges (x, y) or (y, x)
 - e.g., Fig 7.10, $A = \{1, 2, 3\}$ and $\mathfrak{R} = \{(1,1), (1, 2), (2, 3), (1, 3)\}$

任兩點間最多只有1個direct edge (可無edge)

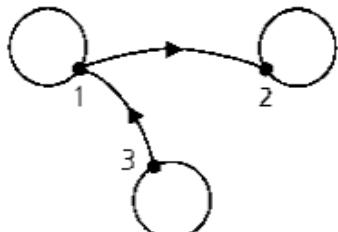


Figure 7.8

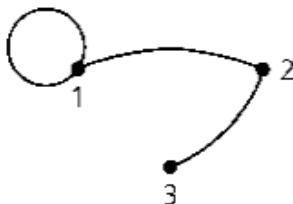


Figure 7.9

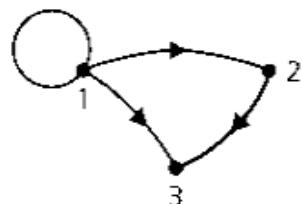


Figure 7.10



Directed Graph

- **Ex 7.32** : \mathfrak{R} is transitive if and only if for all $x, y \in A$, if there is a **path** from x to y in the associated graph, then there is an edge (x, y) also.
 - e.g., Fig 7.10, $A = \{1, 2, 3\}$ and $\mathfrak{R} = \{(1, 1), (1, 2), (2, 3), (1, 3)\}$
- **Ex 7.33** : Fig 7.11, a relation is an equivalence relation if and only if its graph is one complete graph augmented by loops at every vertex or consists of disjoint union of complete graphs augmented by loops at each vertex.
 - e.g., Fig 7.11, $A = \{1, 2, 3, 4, 5\}$ and $\mathfrak{R}_1 = \{(1,1), (1, 2), (2, 1), (2, 2), (3, 3), (3, 4), (4, 3), (4, 4), (5, 5)\}$, $\mathfrak{R}_2 = \{(1,1), (1, 2), (1, 3), (2, 1), (2, 2), (2, 3), (3, 1), (3, 2), (3, 3), (4, 4), (4, 5), (5, 4), (5, 5)\}$.

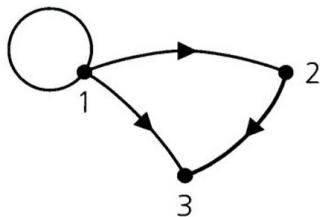


Figure 7.10

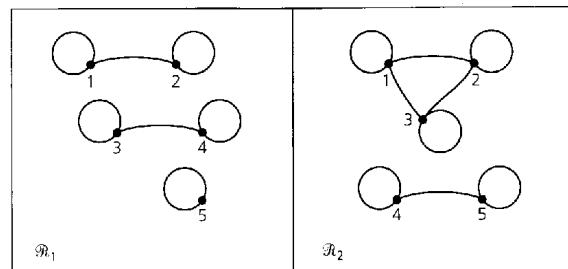


Figure 7.11



Directed Graph

reflexive: loop on each vertex

symmetric: undirected edge + loops

transitive: one path → one edge

equivalence: disjoint union of complete graphs +
loops at every vertex

directed graphs ←→ relations



adjacency matrices ←→ relation matrices



7.3 Partial Orders: Hasse Diagrams

- Definition: Let A be a set with \mathfrak{R} a relation on A . The pair (A, \mathfrak{R}) is called a **partially ordered set**, or poset, if relation \mathfrak{R} on A is partially ordered.
 - If A is called a poset, we understand that there is a partially order \mathfrak{R} on A that makes A into this set.

natural counting: **N**

$$x+5=2 \quad : \mathbf{Z}$$

$$2x+3=4 \quad : \mathbf{Q}$$

$$x^2-2=0 \quad : \mathbf{R}$$

$$x^2+1=0 \quad : \mathbf{C}$$

Something was lost when we went from **R** to **C**. We have lost **the ability to "order"** the elements in **C**.

$$2+i < 1+2i ?$$



7.3 Partial Orders: Hasse Diagrams

- **Ex 7.34** : Let A be the set of courses offered at a college. Define the relation \mathfrak{R} on A by $x\mathfrak{R}y$ if x, y are the same course or if x is a prerequisite for y .
- **Ex 7.35** : Define \mathfrak{R} on $A = \{1, 2, 3, 4\}$ by $x\mathfrak{R}y$ if x divide y . Then $\mathfrak{R} = \{(1, 1), (2, 2), (3, 3), (4, 4), (1, 2), (1, 3), (1, 4), (2, 4)\}$ is a partial order, and (A, \mathfrak{R}) is a poset.
- **Ex 7.36** : PERT (Program Evaluation and Review Technique) network is first used by U.S. Navy in 1950.
 - E.g., Let A be the set of tasks that must be performed to build a house. Define the relation \mathfrak{R} on A by $x\mathfrak{R}y$ if x, y are the same task or if x must be performed before y .



Partial Orders: Hasse Diagrams

- **Ex 7.37** : Figure 7.17 (b) illustrates a simpler diagram for (a), called the **Hasse diagram**. The directions are assumed to go from the bottom to the top.

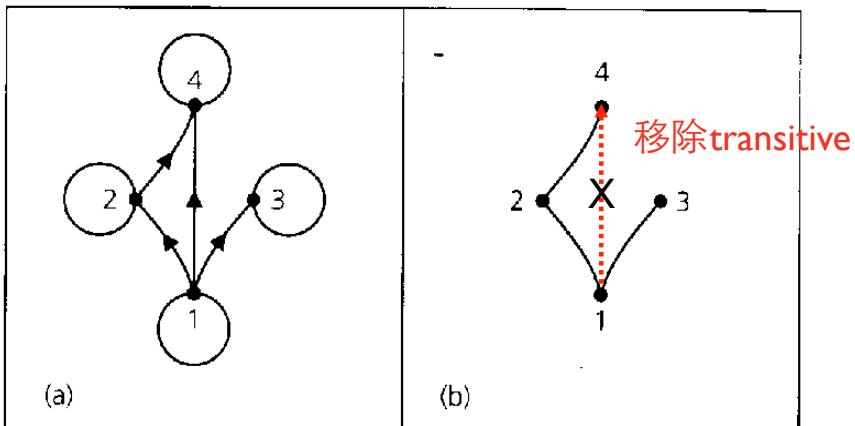
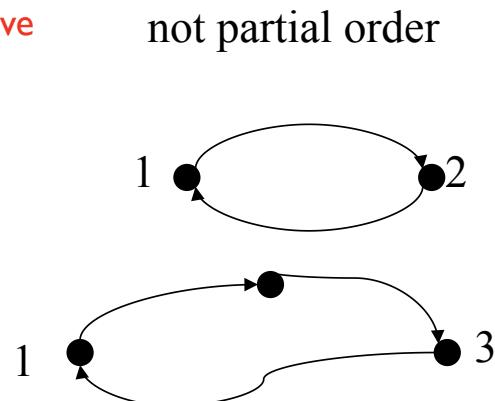


Figure 7.17





Hasse Diagram

- If (A, \mathfrak{R}) is a poset, we construct a Hasse diagram for \mathfrak{R} on A by drawing a line segment from x up to y , if
 - $x\mathfrak{R}y$
 - there is no other z such that $x\mathfrak{R}z$ and $z\mathfrak{R}y$. (*in between x and y*)
- **Ex 7.38** : In Fig. 7.18 we have the Hasse diagrams for the following four posets.
 - (a) \mathfrak{R} is the subset relation on A is the power set of U with $U = \{1, 2, 3\}$
 - (b), (c), and (d) are the divide relations.

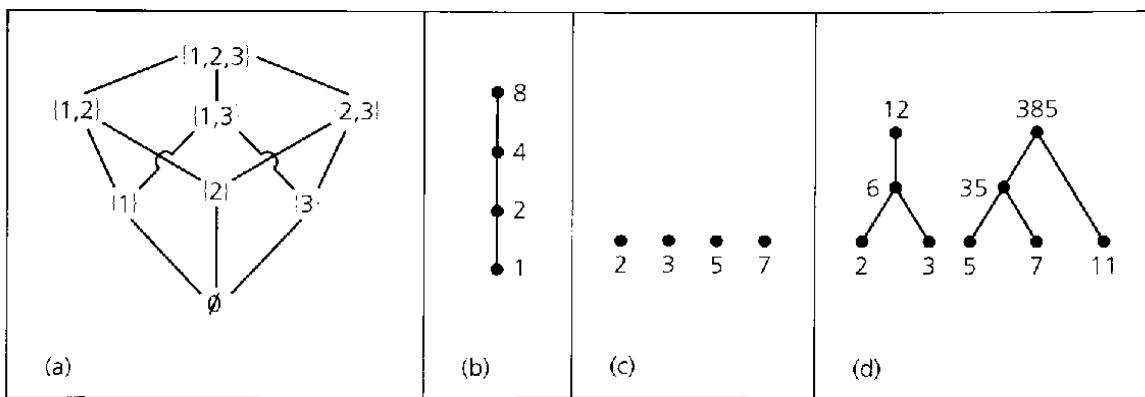


Figure 7.18



Totally Ordered

- Definition 7.16. If (A, \mathfrak{R}) is a poset, we say that A is **totally ordered** (linearly ordered) if for all $x, y \in A$ either $x \mathfrak{R} y$ or $y \mathfrak{R} x$. In this case, \mathfrak{R} is called a total order.
- **Ex 7.40**
 - a) On the set \mathbb{N} , the relation \mathfrak{R} defined by $x \mathfrak{R} y$ if $x \leq y$ is a total order.
 - b) The subset relation is a partial order but not total order, e.g., $\{1, 2\}, \{1, 3\} \in A$, but $\{1, 2\} \not\subset \{1, 3\}$ or $\{1, 3\} \not\subset \{1, 2\}$.
 - c) Fig 7.19 is a total order.

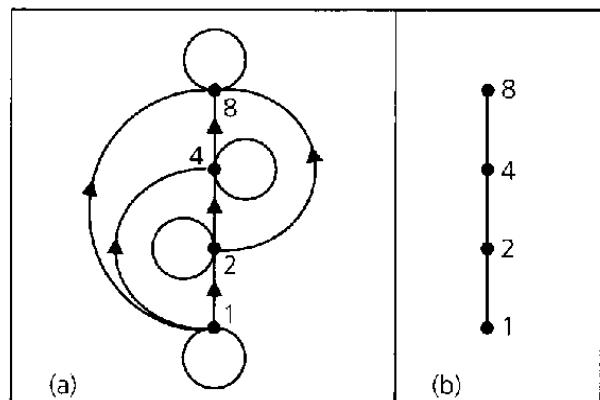


Figure 7.19



Topological Sorting

- Given a Hasse diagram for a partial order relation \mathfrak{R} , how to find a total order \mathfrak{S} for which $\mathfrak{R} \subseteq \mathfrak{S}$.

$$3! \times 2! = 12 \text{種 total order}$$

$(k = 1) \quad H_1$	$(k = 2) \quad H_2$	$(k = 3) \quad H_3$	$(k = 4) \quad H_4$	$(k = 5) \quad H_5$	$(k = 6) \quad H_6$	$(k = 7) \quad H_7$
 $3!$	 $3!$	 $2!$	 $2!$			
D	$F < D$	$G < F < D$	$C < G < F < D$	$A < C < G < F < D$	$B < A < C < G < F < D$	$E < B < A < C < G < F < D$

Figure 7.21

Not unique, 12 answers



Topological Sorting

- For a partial order \mathfrak{R} on a set A with $|A| = n$
 - Step 1: Set $k = 1$. Let H_1 be the Hasse diagram of the partial order.
 - Step 2: Select a vertex v_k in H_k such that no edge in H_k starts at v_k .
 - Step 3: If $k = n$, the process is completed and we have a total order
$$\mathfrak{S} : v_n < v_{n-1} < \cdots < v_1$$
that contains \mathfrak{R} .
 - If $k < n$, then remove from H_k the vertex v_k and all edges of H_k that terminate at v_k . Call the result H_{k+1} . Increase k by 1 and return to step (2).



Topological Sorting

● Ex 7.41

任何一點 [+] 一定會比 [-] 號多

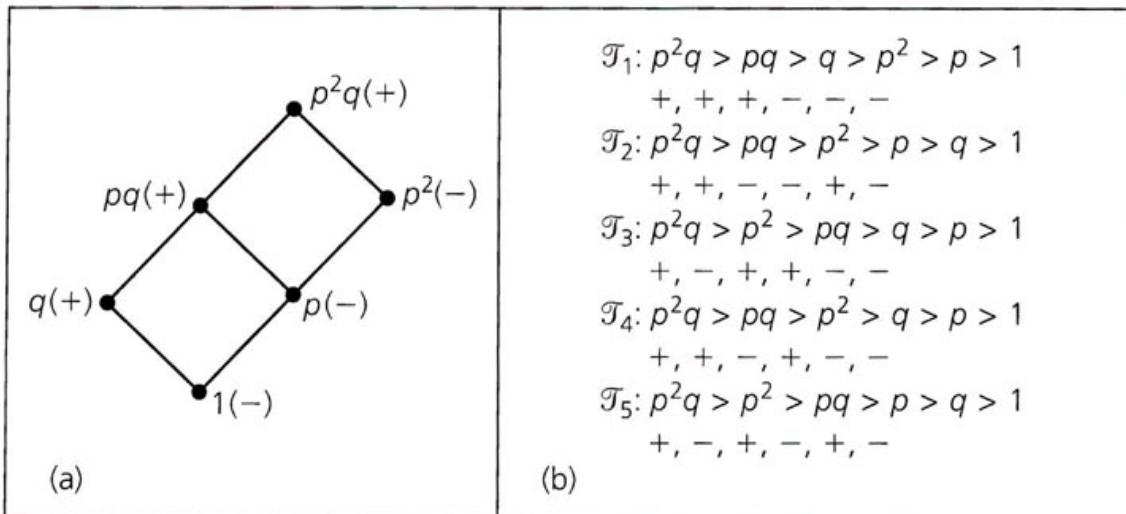


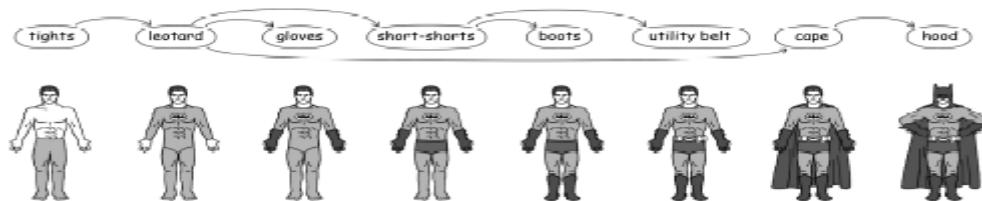
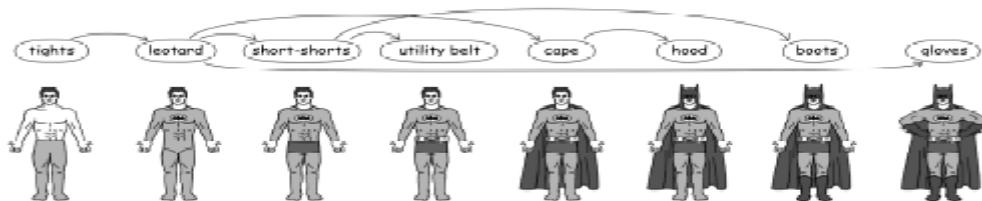
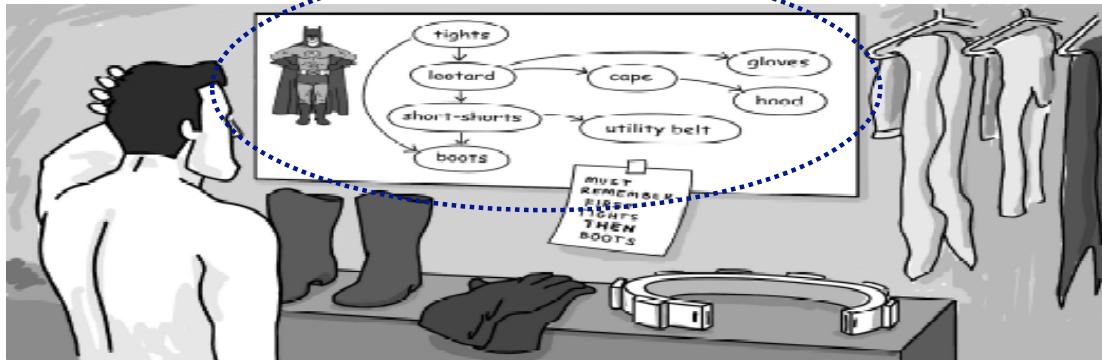
Figure 7.22

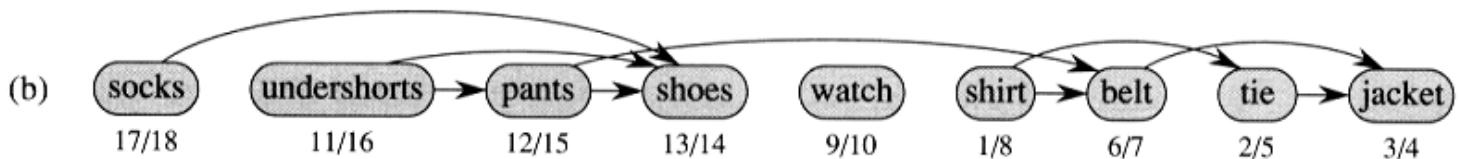
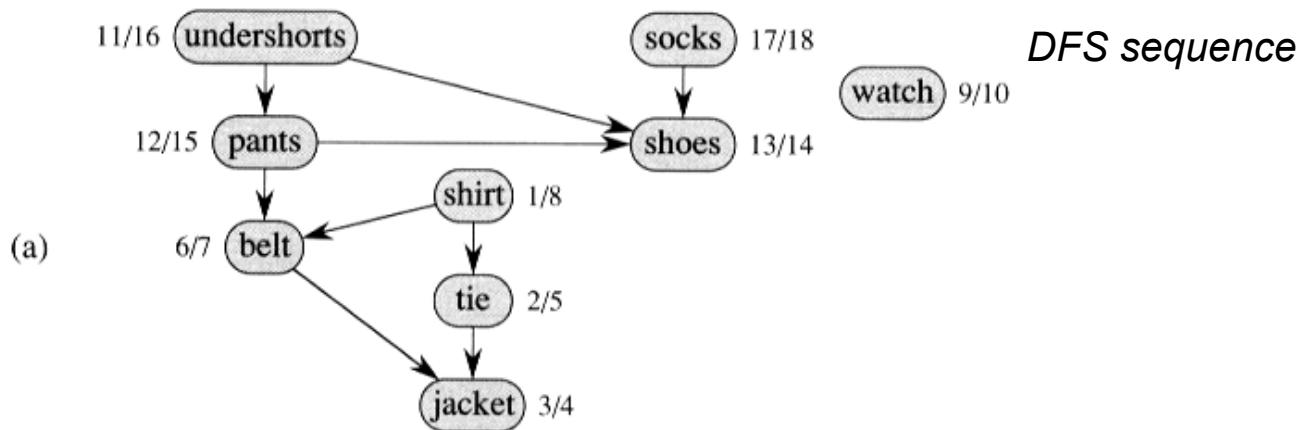
More practices, exercise 7.27



EX: Dressing in the morning

Topological Sort

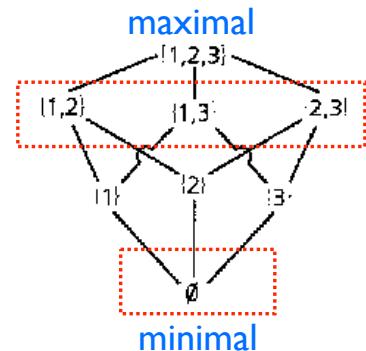






Maximal and Minimal

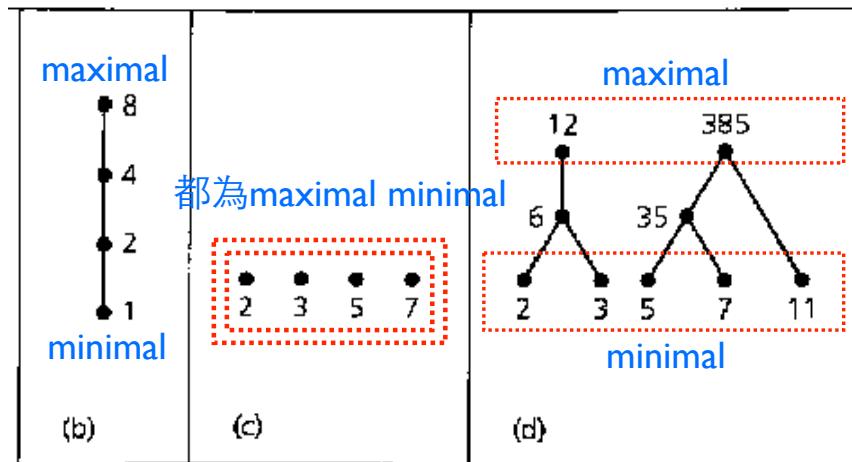
- Definition 7.17: If (A, \mathfrak{R}) is a poset, then x is a maximal element of A if for all $a \in A$, $a \neq x \Rightarrow x \mathfrak{R} a$. Similarly, y is a minimal element of A if for all $b \in A$, $b \neq y \Rightarrow b \mathfrak{R} y$. Proper subset : subset 不能和原本的 set 相同
- Ex 7.42 : $U = \{1, 2, 3\}$, $A = P(U)$.
 - For the poset (A, \subseteq) , U is the maximal and \emptyset is the minimal.
 - Let B be the proper subsets of $\{1, 2, 3\}$. Then we have multiple maximal elements $\{1, 2\}$, $\{1, 3\}$, and $\{2, 3\}$ for the poset (B, \subseteq) , and \emptyset is still the only minimal element.
- Ex 7.43 : For the poset (\mathbb{Z}, \leq) , we have neither a maximal nor a minimal element. The poset (\mathbb{N}, \leq) , has no maximal element but a minimal element 0.





Maximal and Minimal

- Ex 7.44 : How about the poset in (b), (c), and (d) of Fig. 7.18? Do they have maximal or minimal elements?
- Theorem 7.3: If (A, \mathfrak{R}) is a poset and A is finite, then A has both a maximal and a minimal element.





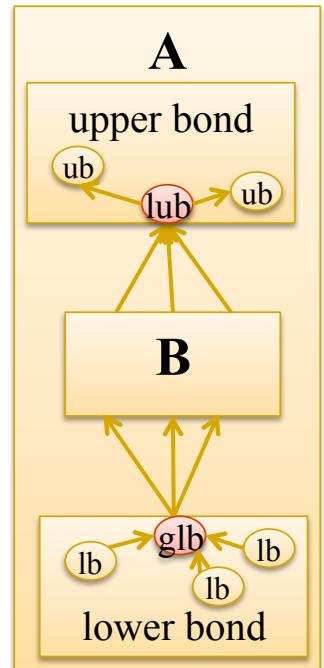
Least and Greatest

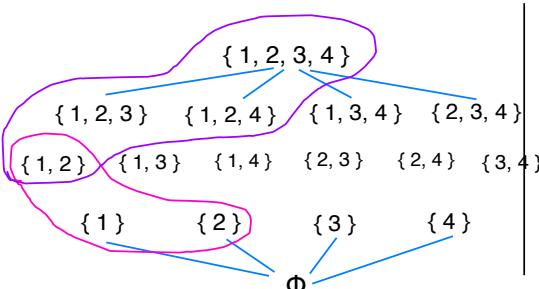
- Definition 7.18: If (A, \mathfrak{R}) is a poset, then x is a **least** element of A if for all $a \in A$, $x \mathfrak{R} a$. Similarly, y is a **greatest** element of A if for all $a \in A$, $a \mathfrak{R} y$.
- **Ex 7.45 :** $U = \{1, 2, 3\}$, $A = P(U)$.
 - For the poset (A, \subseteq) , U is the greatest and ϕ is the least.
 - Let B be the nonempty subsets of U . Then we have U as the greatest element and three minimal elements for the poset (B, \subseteq) , but no least element.
- Theorem 7.4: If poset (A, \mathfrak{R}) has a **greatest or a least element**, then that element is **unique**.
 - **Proof:** Assume x and y are both greatest elements.
Since x is a greatest element, $y \mathfrak{R} x$. Likewise, $x \mathfrak{R} y$ while y is a greatest element. As \mathfrak{R} is antisymmetric, it follows $x = y$.



Lower and Upper Bound

- Definition 7.19: If (A, \mathfrak{R}) is a poset with $B \subseteq A$, then
 - $x \in A$ is called a **lower bound** of B if $x \mathfrak{R} b$ for all $b \in B$
 - $y \in A$ is called an **upper bound** of B if $b \mathfrak{R} y$ for all $b \in B$
- An element $x' \in A$ is called a **greatest lower bound** (**glb**) of B if for all other lower bounds x'' of B we have $x'' \mathfrak{R} x'$. Similarly, an element $x' \in A$ is called a **least upper bound** (**lub**) of B if for all other upper bounds x'' of B we have $x' \mathfrak{R} x''$.
- Theorem 7.5: If (A, \mathfrak{R}) is a poset and $B \subseteq A$, then B has **at most one** lub (glb).





Lower and Upper Bound

- Ex 7.47 :** Let $U = \{1, 2, 3, 4\}$ with $A = P(U)$ and let \mathfrak{R} be the **subset relation** on B . If $B = \{\{1\}, \{2\}, \{1, 2\}\}$, then what are the upper bounds of B , lower bounds of B , the greatest lower bound and the least upper bound?

 - Upper bounds: $\{1, 2\}$, $\{1, 2, 3\}$, $\{1, 2, 4\}$, and $\{1, 2, 3, 4\}$
 - lub: $\{1, 2\}$
 - glb = ϕ

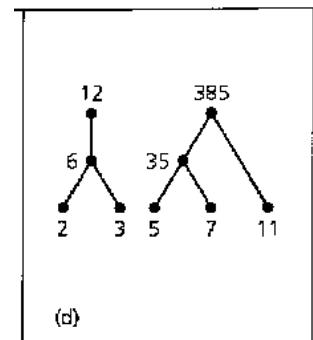
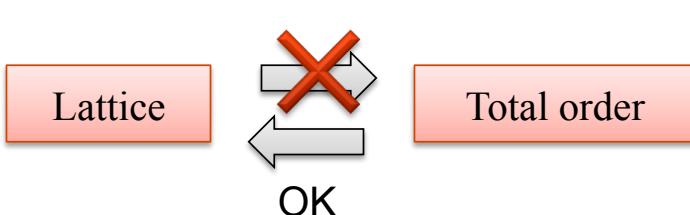
$\{2, 3, 4\}$ is not.
- Ex 7.48 :** Let \mathfrak{R} be the “ \leq ” relation on A . What are the results for the following cases?

 - $A = \mathbf{R}$ and $B = [0, 1] \Rightarrow$ lub:1, glb:0
 - $A = \mathbf{R}$ and $B = \{q \in \mathbf{Q} \mid q^2 < 2\} \Rightarrow$ lub: $\sqrt{2}$, glb: $-\sqrt{2}$
 - $A = \mathbf{Q}$ and $B = \{q \in \mathbf{Q} \mid q^2 < 2\} \Rightarrow$? *No lub and glb*



Lattice

- Definition 7.20. The poset (A, \mathfrak{R}) is called a **lattice** if for *all* $x, y \in A$ the elements $\text{lub}\{x, y\}$ and $\text{glb}\{x, y\}$ both exist in A .
- **Ex 7.49** : For $A = \mathbb{N}$ and $x, y \in \mathbb{N}$, define $x \mathfrak{R} y$ by $x \leq y$. Then $\text{lub}\{x, y\} = \max\{x, y\}$, $\text{glb}\{x, y\} = \min\{x, y\}$, and (\mathbb{N}, \leq) is a lattice.
- **Ex 7.50** : For the poset $(P(\mathbf{U}), \subseteq)$, if $S, T \subseteq \mathbf{U}$, we have $\text{lub}\{S, T\} = S \cup T$ and $\text{glb}\{S, T\} = S \cap T$ and it is a lattice.
- **Ex 7.51**: consider the poset in Example 7.38(d). Here we find that $\text{lub}\{2, 3\} = 6$ exists, but there is no glb for the elements 2 and 3.
 - This partial order is not a lattice.





7.4 Equivalence Relations and Partitions

- Equivalence relation: reflexive, symmetric, and transitive
- Examples:
 - For any set $A \neq \phi$, the relation of equality is an equivalence relation on A .
 - “sameness” among the elements of A
 - Let the relation on \mathbf{Z} defined by $x \mathfrak{R} y$ if $x-y$ is a multiple of 2, then \mathfrak{R} is an equivalence relation on \mathbf{Z} , where all even integers are related, as are all odd integers.
 - The above relation **splits** \mathbf{Z} into two subsets:
 $\{..., -3, -1, 1, 3, ...\} \cup \{..., -4, -2, 0, 2, 4, ...\}$



Partition

- Definition 7.21. Given a set A and index set I , let $\phi \neq A_i \subseteq A$ for $i \in I$.
 - Then $\{A_i\}_{i \in I}$ is a **partition** of A if (a) $A = \bigcup_{i \in I} A_i$ and (b) $A_i \cap A_j = \phi$ for $i \neq j$.
 - Each subset A_i is called a cell (block) of the partition.
- **Ex 7.52** : $A = \{1, 2, \dots, 10\}$
 - $A_1 = \{1, 2, 3, 4, 5\}, A_2 = \{6, 7, 8, 9, 10\}$.
 - $A_i = \{i, i+5\}, 1 \leq i \leq 5$.
- **Ex 7.53** : Let $A = \mathbf{R}$, for each $i \in \mathbf{Z}$, let $A_i = [i, i+1)$. Then $\{A_i\}_{i \in \mathbf{Z}}$ is a partition of \mathbf{R} .



Equivalence Class

- Definition 7.22: Let \mathfrak{R} be an equivalence relation on a set A . For each $x \in A$, the **equivalence class** of x , denoted $[x]$, is defined by $[x] = \{y \in A \mid y \mathfrak{R} x\}$
- Ex 7.54 : Define the relation \mathfrak{R} on \mathbf{Z} by $x \mathfrak{R} y$ if $4 \mid (x-y)$.
 - $[0] = \{\dots, -8, -4, 0, 4, \dots\} = \{4k \mid k \in \mathbf{Z}\}$
 - $[1] = \{\dots, -7, -3, 1, 5, \dots\} = \{4k+1 \mid k \in \mathbf{Z}\}$
 - $[2] = \{\dots, -6, -2, 2, 6, \dots\} = \{4k+2 \mid k \in \mathbf{Z}\}$
 - $[3] = \{\dots, -5, -1, 3, 7, \dots\} = \{4k+3 \mid k \in \mathbf{Z}\}$
- Ex 7.55 : Define the relation \mathfrak{R} on \mathbf{Z} by $a \mathfrak{R} b$ if $a^2 = b^2$, \mathfrak{R} is an equivalence relation.
 - $[n] = [-n] = \{-n, n\}$

$$Z = \{0\} \cup \left(\bigcup_{n \in \mathbf{Z}^+} \{-n, n\} \right)$$

(1) $x \mathfrak{R} y$?
(2) $[x] = [y]?$



Equivalence Class

- **Theorem 7.6:** If \mathfrak{R} is an equivalence relation on a set A and $x, y \in A$, then
 - (a) $x \in [x]$
 - (b) $x \mathfrak{R} y$ if and only if $[x] = [y]$
 - (c) $[x] = [y]$ or $[x] \cap [y] = \emptyset$. (identical or disjoint)
- **Ex 7.56 :**
 - Let $A = \{1, 2, 3, 4, 5\}$, $\mathfrak{R} = \{(1, 1), (2, 2), (2, 3), (3, 2), (3, 3), (4, 4), (4, 5), (5, 4), (5, 5)\}$. $[1] = \{1\}$, $[2] = \{2, 3\} = [3]$, $[4] = \{4, 5\} = [5]$. Then, we have $A = [1] \cup [2] \cup [4]$.
 - Consider an onto function $f: A \rightarrow B$. $f(\{1, 3, 7\}) = x$; $f(\{4, 6\}) = y$; $f(\{2, 5\}) = z$. The relation \mathfrak{R} defined on A by $a \mathfrak{R} b$ if $f(a) = f(b)$. **equivalence class**
 - $A = [1] \cup [4] \cup [2] = f^{-1}(x) \cup f^{-1}(y) \cup f^{-1}(z)$.
- **Ex 7.58 :** If an equivalence relation \mathfrak{R} on $A = \{1, 2, 3, 4, 5, 6, 7\}$ induces the partition $A = \{1, 2\} \cup \{3\} \cup \{4, 5, 7\} \cup \{6\}$, what is \mathfrak{R} ? [2007台大資工]
 - $[1] = \{1, 2\} = [2] = \{(1, 1), (2, 2), (1, 2), (2, 1)\}$
 - $\mathfrak{R} = (\{1, 2\} \times \{1, 2\}) \cup (\{3\} \times \{3\}) \cup (\{4, 5, 7\} \times \{4, 5, 7\}) \cup (\{6\} \times \{6\})$
 - $|\mathfrak{R}| = 2^2 + 1^2 + 3^2 + 1^2 = 15$ {(1,1), (2,2)} v.s. {1,2}x{1,2}



Equivalence and Partition

- **Theorem 7.7:** If A is a set, then
 - (a) any equivalence relation \mathfrak{R} on A induces a partition of A ; and
 - (b) any partition of A gives rise to an equivalence relation \mathfrak{R} on A .
- **Theorem 7.8:** For any set A , there is one-to-one correspondence between the set of equivalence relations on A and the set of partitions of A .

equivalence relation 會將 index 分群
Partition 也會

- Ex 7.59 :

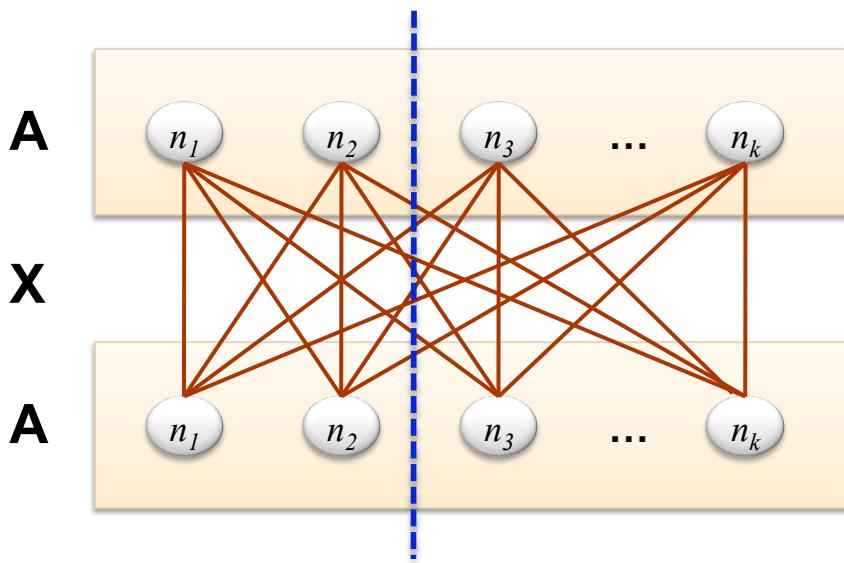
- (a) If $A = \{1, 2, 3, 4, 5, 6\}$, how many relations on A are equivalence relations? (identical containers)
 - *a partition of A : a distribution of the (distinct) elements of A into identical containers with no container left empty* $\sum_{i=1}^6 S(6, i) = 203$
- (b) How many of the equivalence relations in part (a) satisfy $1, 2 \in [4]$?

$$\sum_{i=1}^4 S(4, i) = 15$$

$$\{ \underline{1}, \underline{2}, \underline{4}, \underline{3}, \underline{5}, \underline{6} \}$$



Equivalence and Partition



$$k=10$$

$$k^2$$

$$100$$

$$2^2 + (k-2)^2 \mathbf{4+64=68}$$

r partitions?



7.5 Finite State Machines: The Minimization Process

- Two finite state machines of the same function may have different number of internal states.
 - Some of these states are redundant.
- A process of transforming a given machine into one that has *no redundant internal states* is called the minimization process.
 - Rely on the concepts of *equivalence relation* and *partition*.



Finite State Machines: The Minimization Process

- 1-Equivlence: Given the finite state machine $M = \{S, I, O, v, w\}$, we define the **relation E_1** on S by $s_1 E_1 s_2$ if $w(s_1, x) = w(s_2, x)$ for all $x \in I$.
- The relation E_1 is an equivalence relation on S , and it partitions S into subsets such that two states are in the same subset if they produce the same output for each $x \in I$. 單位長度為1
- Here s_1 and s_2 are called 1-equivlent.

給定長度為1的訊號，可得到相同的output



Finite State Machines: The Minimization Process

- For the states S , we define the k -equivalence relation E_k on S by $s_1 E_k s_2$ if $w(s_1, x) = w(s_2, x)$ for all $x \in I^k$. 單位長度為 k
- The relation E_k is an equivalence relation on S , and it partitions S into subsets such that two states are in the same subset if they produce the same output for each $x \in I^k$. k 越大 partition 越多 (partition 會越分越細)
- We call two states s_1 and s_2 equivalent if they are k -equivalent for all $k \geq 1$.

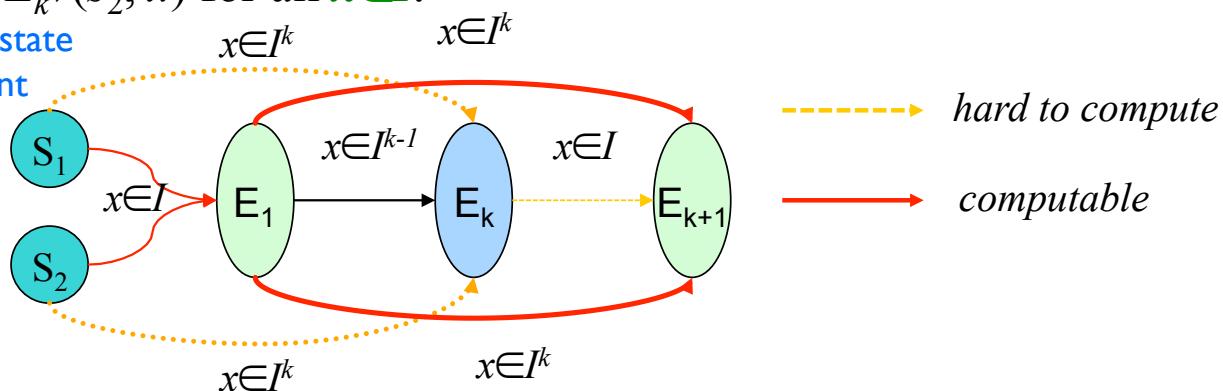


Finite State Machines: The Minimization Process

- Goal: Determine the partition of S induced by E and select one state for each equivalent class.
- Observations:
 - If two states are not 2-equivalent, they can not be 3-equivalent.
 - For $s_1, s_2 \in S$, where $s_1 E_k s_2$, we find that $s_1 E_{k+1} s_2$ if and only if $v(s_1, x) E_k v(s_2, x)$ for all $x \in I$.

判斷 s_1 s_2 的 next state

是否為 k -equivalent





An Algorithm for the Minimization of a Finite State Machine

原來被切開的，不需再做測試，只需測試未被分開的部分

1. Set $k = 1$. $s_1 E_1 s_2$ when s_1 and s_2 have the same output rows. (P_i be the partitions of S induced by E_i)
2. Having determined P_k , we want to obtain P_{k+1} . Determine the states that are $(k+1)$ -equivalent. Note that if $s_1 E_k s_2$, then $s_1 E_{k+1} s_2$ if and only if $v(s_1, x) E_k v(s_2, x)$ for all $x \in I$.
3. If $P_{k+1} = P_k$, the process is completed.
If $P_{k+1} \neq P_k$, $k = k+1$, goto step 2.

從next state去推k-equivalent (得到最終partition結果) => 化簡state



Minimization of a Finite State Machine

- **Ex 7.60** : M is given by the state table shown in Table 7.1.
 - Looking at the output rows: which states are 1-equivalent?
 - P_1 partitions S as $P_1: \{s_1\}, \{s_2, s_5, s_6\}, \{s_3, s_4\}$
 - $P_2: \{s_1\}, \{s_2, s_5\}, \{s_6\}, \{s_3, s_4\}$ (Table 7.2), $P_2 \neq P_1$, continue
 - $P_3: \{s_1\}, \{s_2, s_5\}, \{s_6\}, \{s_3, s_4\}$, $P_3 = P_2$, stop

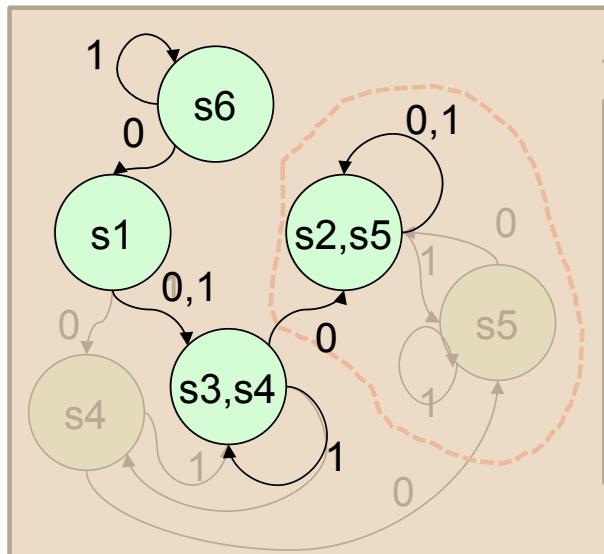


Table 7.1

	ν		ω	
	0	1	0	1
s_1	s_4	s_3	0	1
s_2	s_5	s_2	1	0
s_3	s_2	s_4	0	0
s_4	s_5	s_3	0	0
s_5	s_2	s_5	1	0
s_6	s_1	s_6	1	0

Table 7.2

	ν		ω	
	0	1	0	1
s_1	s_3	s_3	0	1
s_2	s_2	s_2	1	0
s_3	s_2	s_3	0	0
s_6	s_1	s_6	1	0

See also 15.2 Karnaugh Maps, a similar idea



More Minimization example

- In Ex 6.20: Construct a machine that recognizes each occurrence of the sequence 111.

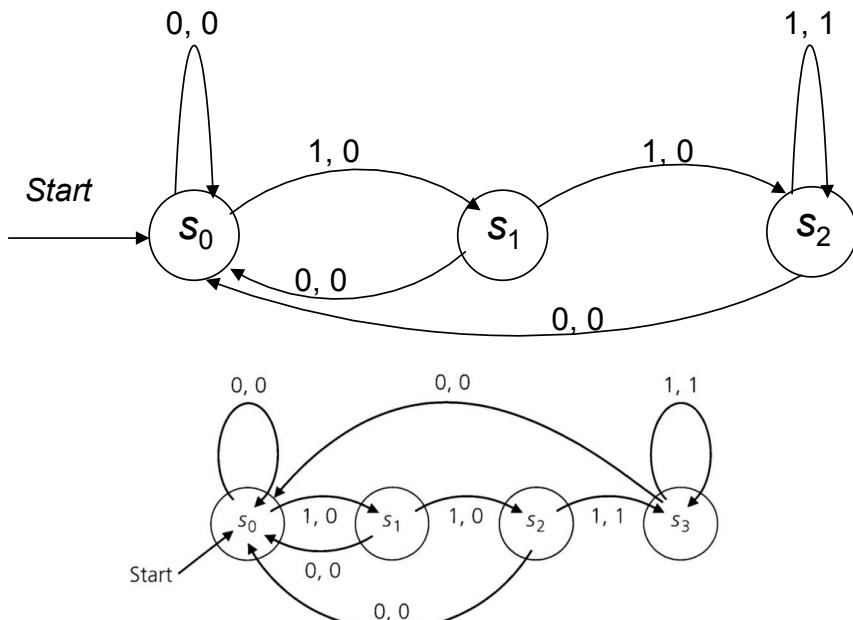


Figure 6.10

	\mathcal{V}		\mathcal{W}	
	0	1	0	1
s_0	s_0	s_1	0	0
s_1	s_0	s_2	0	0
s_2	s_0	s_3	0	1
s_3	s_0	s_3	0	1

$$P_1: \{s_0, s_1\}, \{s_2, s_3\}$$

$$P_2: \{s_0\}, \{s_1\}, \{s_2, s_3\}$$

$$P_3: \{s_0\}, \{s_1\}, \{s_2, s_3\}$$



Refinement

- Definition 7.23: If P_1 and P_2 are partitions of set A , then P_2 is called a refinement of P_1 , denoted as $P_2 \leq P_1$, if every cell of P_2 is contained in a cell of P_1 .
- When $P_2 \leq P_1$ and $P_2 \neq P_1$, we write $P_2 < P_1$.
 - In Example 7.60, $P_3 = P_2 < P_1$
- Theorem 7.9: In the minimization process, if $P_{k+1} = P_k$, then $P_{r+1} = P_r$ for all $r \geq k+1$.



Distinguishing String

- If $s_1 \in E_k s_2$ but $s_1 \notin E_{k+1} s_2$, then we have a string $x = x_1 x_2 \dots x_k x_{k+1} \in I^{k+1}$ such that $w(s_1, x) \neq w(s_2, x)$ but $w(s_1, x_1 x_2 \dots x_k) = w(s_2, x_1 x_2 \dots x_k)$. We call this string x as **distinguishing string**. 不為一
- $s_1 \in E_{k+1} s_2 \Rightarrow \exists x_1 \in I, [w(s_1, x_1) \neq w(s_2, x_1)]$
x讓s1 s2不為k-equivalent



Distinguishing String

- **Ex 7.61** : From Example 7.60, $s_2 E_1 s_6$ but $s_2 \not E_2 s_6$, so we seek a distinguishing string of length 2.
- $x = 00$ is the minimal distinguishing string for s_2 and s_6
 - $w(s_2, 00) = 11 \neq 10 = w(s_6, 00)$

next state 不為 equivalent

$$P_2: \{s_1\}, \{s_2, s_5\}, \{s_3, s_4\}, \{s_6\}$$

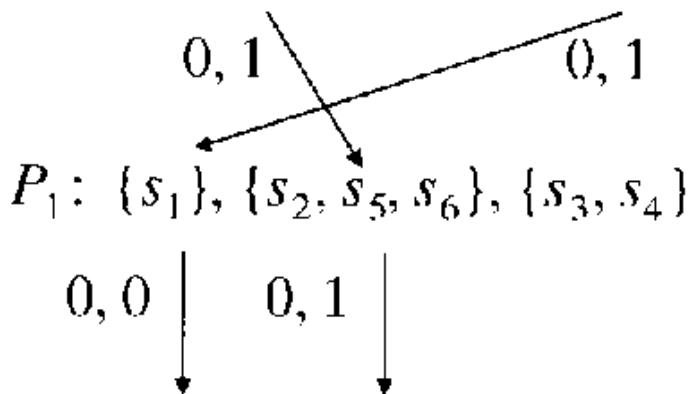


Table 7.1

	ν		ω	
	0	1	0	1
s_1	s_4	s_3	0	1
s_2	s_5	s_2	1	0
s_3	s_2	s_4	0	0
s_4	s_5	s_3	0	0
s_5	s_2	s_5	1	0
s_6	s_1	s_6	1	0



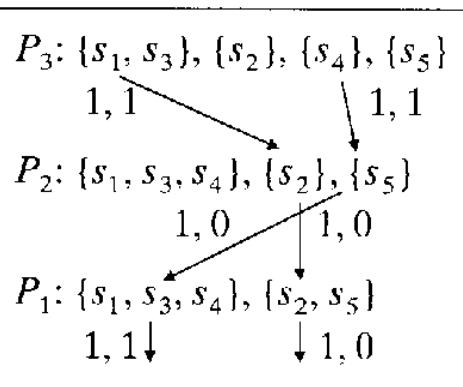
Distinguishing String

- **Ex 7.62** : s_1 and s_4 are 2-equivalent but are not 3-equivalent.
- $x = 111$ is the minimal distinguishing string for s_1 and s_4
- $w(s_1, 111) = 100 \neq 101 = w(s_4, 111)$

Table 7.3

	ν		ω	
	0	1	0	1
s_1	s_4	s_2	0	1
s_2	s_5	s_2	0	0
s_3	s_4	s_2	0	1
s_4	s_3	s_5	0	1
s_5	s_2	s_3	0	0

(a)



(b)

$X=11$ to distinguish s_2 and s_5

typo

- 2) Then $v(s_1, 1) \not\in v(s_4, 1) \Rightarrow \exists x_2 \in \mathcal{F}$ (here $x_2 = 1$) with $v(s_1, 1), 1 \not\in v(s_4, 1), 1$, or $v(s_1, 11) \not\in v(s_4, 11)$. We used the partitions P_2 and P_1 to obtain $x_2 = 1$.
- 3) Now we use the partition P_1 where we find that for $x_3 = 1 \in \mathcal{F}$.