

Advanced statistical physics and new applications

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Chapter 1

Introduction

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...

We don't believe it right now, but this course will be useful to us.

We will have the notes allowed in the exam, but only hand written notes.

The lecture notes are oversized, to help us find things we like, to feed us with interesting things. However, only what we see during the course is to be known in the exam.

Chapter 2

Statistical dynamics

We know stat mechs in equilibrium (stationnary and reversible?). We want to do stat mechs including time.

There is always a level of description of our system described by what is called the "Master equation".

2.1 The physics behind a master equation

2.1.1 Phase space and Liouville equation

Imagine a physical system described by its phase space coordinates $\Gamma = \{q, p\}$, and its evolution is governed by Hamilton's equations of motion

$$q = \frac{\partial \mathcal{H}}{\partial p}, \quad p = -\frac{\partial \mathcal{H}}{\partial q} \quad (2.1)$$

where \mathcal{H} is the Hamiltonian encoding all dynamical informations of the system.

Let $\rho(\Gamma, t)$ be the phase space density. Then we have a conservation equation in the phase space

$$\partial_t \rho + \partial_\Gamma \cdot (\rho \dot{\Gamma}) = 0 \quad (2.2)$$

By expanding, we obtain

$$\partial_t \rho = \{\mathcal{H}, \rho\} \quad (2.3)$$

Because $\partial_\Gamma \cdot \dot{\Gamma} = 0$, the phase space flow is incompressible. This is the Liouville equation.

Sometimes, we write it

$$\partial_t \rho = -i\mathcal{L}\rho \quad (2.4)$$

as a linear operator, where $-i\mathcal{L}\cdot = \{\mathcal{H}, \cdot\}$

2.1.2 Projection operator

If at the microscopic level some degrees of freedom c have a distribution $\rho(c, t)$, then what happens to a "coarse-grained" quantity

$$C(c) : \mathbb{P}(\mathcal{C}, t) = \text{Prob}\{C(c) = \mathcal{C} \text{ at time } t\} \quad (2.5)$$

What we know is the evolution of $\rho(c, t)$:

$$\partial_t \rho = w\rho = \sum_{c'} w_{cc'} \rho(c', t) \quad (2.6)$$

with w some linear operator. How can we find an evolution for $\mathbb{P}(\mathcal{C}, t)$?

First, we can relate P to ρ :

$$P(\mathcal{C}, t) = \sum_c \delta_{\mathcal{C}, C(c)} \rho(c, t) \quad (2.7)$$

Idea:

$$\mathcal{P}f(c) = \frac{1}{\Omega(C(c))} \sum_{c'} \delta_{C(c), C(c')} f(c') \quad (2.8)$$

where

$$\Omega(\mathcal{C}) = \sum_c \delta_{\mathcal{C}, C(c)} \quad (2.9)$$

We can check that $\mathcal{P}^2 = \mathcal{P}$. Let $\bar{p}(c, t) = \mathcal{P}p(c, t)$, then one can access $P(\mathcal{C}, t)$ via

$$P(\mathcal{C}, t) = \sum_c \delta_{\mathcal{C}, C(c)} \bar{p}(c, t) \quad (2.10)$$

Now we split $p = \bar{p} + q$ with $\bar{p} = \mathcal{P}p$, $q = (1 - \mathcal{P})p$. and we can start from $\partial_t p = wp$ and thus arrive at

$$\begin{aligned} \partial_t \bar{p} &= \mathcal{P}w(\bar{p} + q) \\ \partial_t q &= (1 - \mathcal{P})w(\bar{p} + q) \Rightarrow \partial_t q - (1 - \mathcal{P})wq = (1 - \mathcal{P})w\bar{p} \end{aligned} \quad (2.11)$$

We solve the equation for q , and inject q as a functional of \bar{p} into

$$\partial_t \bar{p} = \mathcal{P}w\bar{p} + \mathcal{P}wq \quad (2.12)$$

we get

$$\partial_t \bar{p} = \mathcal{P}w\bar{p} + \int_0^t \bar{dt}' \mathcal{P}we^{(1-\mathcal{P})w(t-t')}(1 - \mathcal{P})w\bar{p}(t') \quad (2.13)$$

There is the emergence of a memory loss $e^{(1-\mathcal{P})w(t-t')}$. We can reconstruct an equation for $P(\mathcal{C}, t)$, which has the general form

$$\partial_t P = M^{(1)}P + \frac{0}{t} dt' M^{(2)}P(t') \quad (2.14)$$

where $M^{(2)}$ encodes the memory of the degrees of freedom lost in the description

$$M^{(2)}(t) \propto e^{(1-\mathcal{P})wt} \quad (2.15)$$

If the eigenvalues of $(1 - \mathcal{P})w$ are very large, this means that this memory is quickly lost

$$e^{-\frac{t}{\tau}} \sim_{\tau \sim 0} \tau \delta(t) \quad (2.16)$$

and then the equation for P reads

$$\partial_t P = M_{\text{eff}}P \quad (2.17)$$

If the physical system of interest is such that its typical time scale are much larger than those characterizing the interactions with the environment, then we end up on a linear, 1st order in time, diff equation for P . This is a master equation.

See lecture notes for more details

2.2 Master equation

The best book talking of the master equation is the one by N. Van Kampen, stochastic processes... libgen

2.2.1 Rates

We will use the notation \mathcal{C} to refer to "microscopic" configs. Let

$$W(\mathcal{C} \rightarrow \mathcal{C}', t)dt \quad (2.18)$$

be the probability that the system hops from config \mathcal{C} to config \mathcal{C}' between t and $t + dt$. Then the rate $r(\mathcal{C})$ at which the system escapes config \mathcal{C} is

$$r(\mathcal{C}) = \sum_{\mathcal{C}'} W(\mathcal{C} \rightarrow \mathcal{C}') \quad (2.19)$$

Then it is possible to write the evolution equation for $P(\mathcal{C}, t)$:

$$P(\mathcal{C}, t + dt) = P(\mathcal{C}, t)(1 - r(\mathcal{C})dt) + \sum_{\mathcal{C}'} P(\mathcal{C}', t)W(\mathcal{C}' \rightarrow \mathcal{C})dt \quad (2.20)$$

Implying

$$\partial_t P(\mathcal{C}, t) = \sum_{\mathcal{C}'} W(\mathcal{C}' \rightarrow \mathcal{C})P(\mathcal{C}', t) - r(\mathcal{C})P(\mathcal{C}, t) \quad (2.21)$$

This expresses a random walk on a directed graph with vertices \mathcal{C} and weights over edges given by the $W(\mathcal{C}, \mathcal{C}')$'s.

It is sometimes convenient to introduce

$$W_{\mathcal{C}\mathcal{C}'} = \begin{cases} W(\mathcal{C}' \rightarrow \mathcal{C}) & \text{if } \mathcal{C} \neq \mathcal{C}' \\ -r(\mathcal{C}) & \text{if } \mathcal{C} = \mathcal{C}' \end{cases} \quad (2.22)$$

A posteriori, we see that, of course, there is a probability conservation

$$\frac{d}{dt} \sum_{\mathcal{C}} P(\mathcal{C}, t) = \sum_{\mathcal{C}\mathcal{C}'} W_{\mathcal{C}\mathcal{C}'} P(\mathcal{C}', t) = 0 \quad (2.23)$$

because

$$\forall \mathcal{C}', \quad \sum_{\mathcal{C}} W_{\mathcal{C}\mathcal{C}'} = 0 = \sum_{\mathcal{C}} [W(\mathcal{C}' \rightarrow \mathcal{C}) - r(\mathcal{C})\delta_{\mathcal{C}\mathcal{C}'}] \quad (2.24)$$

Let $p_{\mathcal{C}} = 1$ for all \mathcal{C} , then

$$\sum_{\mathcal{C}} p_{\mathcal{C}} W_{\mathcal{C}\mathcal{C}'} = 0, \quad p^\dagger W = 0 \quad (2.25)$$

Hence the p vector is a left eigenvector of W with eigenvalue 0, hence there exists a right eigenvector $P_s s$ with eigenvalue 0. This is describing a steady-state. Let's restrict ourselves to strongly connected graphs of configurations (with irreducible dynamics), so as to avoid stationary probabilities being drained towards a specific subgraph.

If we write

$$P(t + dt) = (1 + Wdt)P(t) \quad (2.26)$$

we apply the Perron-Frobenius theorem to $M = (1 + Wdt)$, and we can conclude that there exists a positive number ρ that is an eigenvalue and all others are smaller.

$$l = \min_{\mathcal{C}} \sum_{\mathcal{C}'} M_{\mathcal{C}\mathcal{C}'}^\dagger \leq \rho \leq \max_{\mathcal{C}} \sum_{\mathcal{C}'} M_{\mathcal{C}\mathcal{C}'}^\dagger = 1 \quad (2.27)$$

Hence 0 is the largest eigenvalue of W , and the unique corresponding vector P_s has all its components of the same sign (we choose +).

2.2.2 Averages

In practice, given a master equation and a physical observable $B(\mathcal{C})$, it is possible to find the evolution of $\langle B \rangle$:

$$\langle B \rangle = \sum_{\mathcal{C}} B(\mathcal{C})P(\mathcal{C}, t) \quad (2.28)$$

such that

$$\begin{aligned} \frac{d \langle B \rangle}{dt} &= \sum_{\mathcal{C}\mathcal{C}'} B(\mathcal{C})W_{\mathcal{C}\mathcal{C}'}P(\mathcal{C}', t) \\ &= p^\dagger B W P \\ &= p^\dagger [B, W] P \end{aligned} \quad (2.29)$$

and a formal solution reads

$$\langle B(t) \rangle = \sum_{\mathcal{C}\mathcal{C}'} B(\mathcal{C})(e^{Wt})_{\mathcal{C}\mathcal{C}'}P(\mathcal{C}', 0) \quad (2.30)$$

Similarly,

$$\langle A(t_1)B(t_2) \rangle = p^\dagger A e^{W(t_1, t_2)} B e^{W t_2} P_{\text{init}} \quad (2.31)$$

2.2.3 Trajectories and histories

Let's see what the existence of rate actually mean: when the system is in state \mathcal{C} , then it stays there for a random duration before hopping to configuration \mathcal{C}' .

Let $\Pi(\tau, \mathcal{C})d\tau$ be the probability to stay in state \mathcal{C} for a duration τ and to hop to some other state between τ and $\tau + d\tau$

$$\Pi(\tau, \mathcal{C}) = f(\mathcal{C}, \tau)r(\mathcal{C})d\tau \quad (2.32)$$

where f is the probability to stay a duration τ in state \mathcal{C} .

$$\begin{aligned} f(\mathcal{C}, \tau + d\tau) &= f(\mathcal{C}, \tau)(1 - r(\mathcal{C})d\tau) \\ f(\mathcal{C}, 0) &= 1 \\ \Rightarrow f(\mathcal{C}, \tau) &= e^{-r(\mathcal{C})\tau} \end{aligned} \quad (2.33)$$

Let's look at a typical realization of the Markov process over some time window $[0, t_{\text{obv}}]$.

$$\mathcal{C}_0 \xrightarrow{\tau_0} \mathcal{C}_1 \xrightarrow{\tau_1} \mathcal{C}_2 \xrightarrow{\tau_2} \dots \xrightarrow{\tau_{K-1}} \mathcal{C}_K \xrightarrow{\tau_K} \mathcal{C}_K \quad (2.34)$$

with K the number of hops over $[0, t_{\text{obs}}]$, which is a random variable. So K is random, the τ_i 's are random, and the \mathcal{C}_i 's are random.

The probability of observing this trajectory is

$$\begin{aligned} \mathcal{P}[\text{traj}] = & P_{\text{init}}(\mathcal{C}_0) \Pi(\tau_0, \mathcal{C}_0) d\tau_0 \frac{W(\mathcal{C}_0 \rightarrow \mathcal{C}_1)}{r(\mathcal{C}_0)} \Pi(\tau_1, \mathcal{C}_1) d\tau_1 \frac{W(\mathcal{C}_1 \rightarrow \mathcal{C}_2)}{r(\mathcal{C}_1)} \dots \\ & \frac{W(\mathcal{C}_{K-1} \rightarrow \mathcal{C}_K)}{r(\mathcal{C}_{K-1})} f(\mathcal{C}_K, \tau_K) \delta(\tau_0 + \tau_1 + \dots + \tau_K - t_{\text{obs}}) \end{aligned} \quad (2.35)$$

But simplifying everything, we can obtain easily as

$$\mathcal{P}[\text{traj}] = P_{\text{init}}(\mathcal{C}_0) e^{-\sum_{j=0}^{K-1} r(\mathcal{C}_j) \tau_j} \prod_{j=0}^{K-1} d\tau_j \delta(t_{\text{obs}} - \sum_j \tau_j) \prod_{j=0}^{K-1} W(\mathcal{C}_j \rightarrow \mathcal{C}_{j+1}) \quad (2.36)$$

For a given trajectory "traj" we can also consider the time reversed one traj^R :

$$\mathcal{P}[\text{traj}^R] = P_{\text{final}}(\mathcal{C}_K) e^{-\sum_{j=0}^{K-1} r(\mathcal{C}_j) \tau_j} \prod_{j=0}^{K-1} d\tau_j \delta(t_{\text{obs}} - \sum_j \tau_j) \prod_{j=0}^{K-1} W(\mathcal{C}_{j+1} \rightarrow \mathcal{C}_j) \quad (2.37)$$

From these probabilities, we define

$$\bar{Q}[\text{traj}] = \ln \left(\frac{\mathcal{P}[\text{traj}]}{\mathcal{P}[\text{traj}^R]} \right) \quad (2.38)$$

We want to show an intriguing property of $P(\bar{Q}, t) = \text{Prob}\{\bar{Q}[\text{traj}] = \bar{Q}\}$:

$$P(\bar{Q}, t) = \sum_{\text{traj}} \delta(\bar{Q} - \bar{Q}[\text{traj}]) \mathcal{P}[\text{traj}] \quad (2.39)$$

Noticing $\mathcal{P}[\text{traj}] = \mathcal{P}[\text{traj}^R] e^{\bar{Q}[\text{traj}]}$ and $\bar{Q}[\text{traj}] = -\bar{Q}[\text{traj}^R]$:

$$P(\bar{Q}, t) = \sum_{\text{traj}^R} \delta(\bar{Q} + \bar{Q}[\text{traj}]) e^{-\bar{Q}[\text{traj}^R]} \mathcal{P}[\text{traj}^R] \quad (2.40)$$

such that

$$P(\bar{Q}, t) = e^{\bar{Q}} P(-\bar{Q}, t) \quad (2.41)$$

(Eraus-Searles theorem, 1993)

This leads to $\langle e^{-\bar{Q}} \rangle = 1$. We see that

$$\langle \bar{Q} \rangle = \sum_{\text{traj}} \bar{Q}[\text{traj}] \mathcal{P}[\text{traj}] = \sum_{\text{traj}} \mathcal{P}[\text{traj}] \ln \left(\frac{\mathcal{P}[\text{traj}]}{\mathcal{P}[\text{traj}]} \right) \quad (2.42)$$

\bar{Q} is somewhat a measure of how similar are the forward and backward processes. It is the Kullback-Lertler divergence/entropy. $\langle \bar{Q} \rangle$ somewhat quantifies the asymmetry of the arrow of time.

Reminder: $D(p||q) = \sum_i p_i \ln(\frac{p_i}{q_i}) \geq 0$ with equality iff $p_i = q_i$

When we look at \bar{Q} , we see two contributions.

$$\bar{Q} = \ln \left(\frac{P_{\text{init}}(\mathcal{C}_0)}{P_{\text{final}}(\mathcal{C}_K)} \right) + \sum_{j=0}^{K-1} \ln \left(\frac{W(\mathcal{C}_j \rightarrow \mathcal{C}_{j+1})}{W(\mathcal{C}_{j+1} \rightarrow \mathcal{C}_j)} \right) \quad (2.43)$$

The first term is a boundary term, whilst the second one (named Q_s) is time extensive since there are K terms, and

$$\frac{d \langle K \rangle}{dt} = \langle r(\mathcal{C}) \rangle \quad (2.44)$$

We see that Q_s does not contain any information on the τ_j 's, it only depend on the sequence of visited states. We thus call it a history instead of a trajectory.

2.2.4 Evolution of the Shannon entropy

The Shannon entropy over the configs \mathcal{C} is

$$S(t) = - \sum_{\mathcal{C}} P(\mathcal{C}, t) \ln(\mathcal{C}, t) \quad (2.45)$$

Wether it makes sense or not, we can always, always define and consider it. This quantity evolves according to (after simplifications)

$$\begin{aligned} \frac{dS}{dt} = & \frac{1}{2} \sum_{\mathcal{C}, \mathcal{C}'} [W(\mathcal{C} \rightarrow \mathcal{C}')P(\mathcal{C}, t) - W(\mathcal{C}' \rightarrow \mathcal{C})P(\mathcal{C}', t)] \times \ln \frac{W(\mathcal{C} \rightarrow \mathcal{C}')P(\mathcal{C}, t)}{W(\mathcal{C}' \rightarrow \mathcal{C})P(\mathcal{C}', t)} \\ & - \sum_{\mathcal{C}, \mathcal{C}'} W(\mathcal{C} \rightarrow \mathcal{C}') \ln \frac{W(\mathcal{C} \rightarrow \mathcal{C}')}{W(\mathcal{C}' \rightarrow \mathcal{C})} P(\mathcal{C}, t) \end{aligned} \quad (2.46)$$

The first term σ_{irr} is positive, and vanishes iff

$$W(\mathcal{C} \rightarrow \mathcal{C}')P(\mathcal{C}, t) = W(\mathcal{C}' \rightarrow \mathcal{C})P(\mathcal{C}', t) \quad (2.47)$$

When $P(\mathcal{C}, t)$ becomes stationnary, this property is verified by P_{ss} , promotes P_{ss} to the status of an "equilibrium definition"

$$P_{\text{eq}}(\mathcal{C})W(\mathcal{C} \rightarrow \mathcal{C}') = P_{\text{eq}}(\mathcal{C}')W(\mathcal{C}' \rightarrow \mathcal{C}) : \text{detailed balance} \quad (2.48)$$

The second term, $\frac{dS}{dt} = \sigma_{\text{irr}} - J_s$

$$\begin{aligned} J_s &= \sum_{\mathcal{C}, \mathcal{C}'} P(\mathcal{C}, t) W(\mathcal{C} \rightarrow \mathcal{C}') \ln \frac{W(\mathcal{C} \rightarrow \mathcal{C}')}{W(\mathcal{C}' \rightarrow \mathcal{C})} \\ &= \langle \frac{dQ_s}{dt} \rangle \end{aligned} \quad (2.49)$$

In the steady-state, $\frac{dS}{dt} = 0$,

$$\sigma_{\text{irr}} = J_s \geq 0 \quad (2.50)$$

with equality iff detailed balance is fulfilled by P_{ss} .

2.2.5 One dimensional walkers on a lattice

Let's begin with L sites with periodic boundary conditions, such that a particle hops to the left ($i - 1$) with probability p and to the right with probability q , and such that there is always maximum 1 particle per site.

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Given N particles and L sites, $P(\{n_i\}, t)$. What is the steady-state? Is it equilibrium?

We can guess the steady state is a uniform distribution on each sites $P(\{n_i\}) = \frac{1}{\binom{L}{N}}$, and it is at equilibrium iff $p = q$.

Let's make sure our guess is good:

$$\begin{aligned} \partial_t P(\mathcal{C} = \{n_i\}, t) &= p \sum_i n_i (1 - n_{i+1}) P(\dots) \\ &\quad + q \sum_i n_i (1 - n_{i-1}) P(\dots) \\ &\quad - p \sum_i n_i (1 - n_i) P(\{n_i\}, t) - q \sum_i n_i (1 - n_{i+1}) P(\{n_i\}, t) \end{aligned} \quad (2.51)$$

The two first terms account for particles coming there coming from elsewhere, and the two last account for particles leaving. And indeed, $P_{ss}(\{n_i\}) = \text{cst}$ solves it in the steady-state.

How about $\bar{Q}_s[\text{traj}]$?

$$\begin{aligned} \bar{Q}_s[\text{traj}] &= \sum_{i=0}^{K-1} \ln \frac{W(\mathcal{C}_i \rightarrow \mathcal{C}_{i+1})}{W(\mathcal{C}_{i+1} \rightarrow \mathcal{C}_i)} \\ &= \left(\ln \frac{q}{p} \right) \times (\text{nb of hops to the right}) + \left(\ln \frac{p}{q} \right) \times (\text{nb of hops to the left}) \\ &= \ln \frac{q}{p} \times (\text{Total integrated particle current}) \end{aligned} \quad (2.52)$$

$\ln \frac{q}{p}$ is the driving force of the current, or the affinity in term of chemistry. We thus understand the \bar{Q} as an entropy creation, as a force times a current.

If we parametrize $p = D_0 e^{-E/2}$, $q = D_0 e^{E/2}$ then

$$\frac{d \langle Q_s \rangle}{dt} = J_s = E \times \langle \text{particle current} \rangle \quad (2.53)$$

2.3 First passage properties and adjoint master equation

2.3.1 Backward master equation

We are interested in $P(\mathcal{C}, t | \mathcal{C}', t')$ = the probability to be in state \mathcal{C} at time t , starting from \mathcal{C}' at time t' .

$$P(\mathcal{C}, t | \mathcal{C}', t) = \delta_{\mathcal{C}\mathcal{C}'} \quad (2.54)$$

$$\partial_t P(\mathcal{C}, t | \mathcal{C}', t') = \sum_{\mathcal{C}''} W_{\mathcal{C}\mathcal{C}''} P(\mathcal{C}'', t | \mathcal{C}', t') \quad (2.55)$$

$$P(\mathcal{C}, t | \mathcal{C}', t') = \left[e^{W(t-t')} \right]_{\mathcal{C}\mathcal{C}'} \quad (2.56)$$

And it's possible to track the evolution

$$\begin{aligned}\partial_{t'} P(\mathcal{C}, t | \mathcal{C}', t') &= \sum_{\mathcal{C}''} P(\mathcal{C}, t | \mathcal{C}'', t') W_{\mathcal{C}'' \mathcal{C}'} \\ &= -(W^\dagger)_{\mathcal{C}' \mathcal{C}''} P(\mathcal{C}, t | \mathcal{C}'', t')\end{aligned}\tag{2.57}$$

Hence W^\dagger propagates backward in time.

2.3.2 First passage probability and first passage time

Let \mathcal{A} be a set of absorbing configurations. We ask about the survival probability $S(\mathcal{C}, t)$ that starting from \mathcal{C} such that $\mathcal{C} \notin \mathcal{A}$ the system is still alive at time t . In practice,

$$S(\mathcal{C}, t) = \sum_{\mathcal{C}'' \notin \mathcal{A}} P(\mathcal{C}'', t | \mathcal{C}, 0)\tag{2.58}$$

with boundary conditions

$$\forall \mathcal{C} \in \mathcal{A}, S(\mathcal{C}, t) = 0, \quad \forall \mathcal{C} \notin \mathcal{A}, S(\mathcal{C}, 0) = 1\tag{2.59}$$

Using the master equation, we see that

$$\begin{aligned}\partial_t S(\mathcal{C}, t) &= \sum_{\mathcal{C}''} W_{\mathcal{C}'' \mathcal{C}} S(\mathcal{C}'', t) \\ \partial_t S &= W^\dagger S\end{aligned}\tag{2.60}$$

We have the set of equations

$$\begin{aligned}S(\mathcal{C}, t) &= 1 - \int_0^t dt' F_{\mathcal{A}}(\mathcal{C}, t') \\ -\frac{dS}{dt} &= F_{\mathcal{A}}\end{aligned}\tag{2.61}$$

We are interested in $T_{\mathcal{A}}(\mathcal{C})$ = average time of first passage to \mathcal{A} starting from \mathcal{C} .

$$T_{\mathcal{A}} = \int_0^{+\infty} dt \, t \, F_{\mathcal{A}}(\mathcal{C}, t)\tag{2.62}$$

Because after an integration by part,

$$T_{\mathcal{A}}(\mathcal{C}) = \int_0^{+\infty} dt \, S(\mathcal{C}, t)\tag{2.63}$$

then we can show that

$$W^\dagger T_{\mathcal{A}} = -1\tag{2.64}$$

or

$$(W^\dagger)_{\mathcal{C} \mathcal{C}'} T_{\mathcal{A}}(\mathcal{C}') = -1\tag{2.65}$$

Chapter 3

Stochastic dynamics

3.1 What is the question?

We start with a micro system, very very hard to describe. We consider a big colloid of the order of the μm described by (\vec{R}, \vec{P}) in a bath of small molecules of water i of size $\sim 3.4\text{\AA}$ described by (\vec{r}_i, \vec{p}_i) . We can accurately write this system in term of a large Hamiltonian

$$\mathcal{H} = \mathcal{H}_0(\vec{R}, \vec{P}) + \mathcal{H}_1((\vec{r}_i, \vec{p}_i)_i) + \sum_i V_i(\vec{r}_i, \vec{p}_i, \vec{R}, \vec{P}) \quad (3.1)$$

where the first term describes the dynamics of the colloid, the second term describes the dynamics of the water molecules, and the last term describes the interactions between the two. Moreover, we know that at a higher level of description, if the system is static, we have

$$P(\vec{R}, \vec{P}) = \frac{1}{Z} e^{-\beta \mathcal{H}(\vec{R}, \vec{P})} \quad (3.2)$$

where there is no information left about the bath whatsoever, no trivial information. This is in general the objective of statistical physics, discarding useless information.

Now, the question is whether or not it is possible to obtain an equation similar to the Boltzmann distribution, but describing the time evolution of the colloid. To do so, the idea is to split the molecules of water surrounding the colloid into multiple small regions, in packages sufficiently big to forget about the interactions between the packages, but sufficiently small to have a large number of them around the colloid.

Remark. This is only possible because there are several orders of difference between the water molecules and the colloid. The correlation length of water molecules is about 10\AA , so we can do packages of size 100\AA and still have around a hundred packages envelopping the colloid. The following thinking couldn't be possible if there was no such difference in magnitude.

When such division into packages is possible, we can assert that the strength

put by the water molecules onto the colloid is equal to

$$\begin{aligned}\vec{F}_b &= \sum_i \vec{F}_i = \sum_{\text{region}} \sum_{i \in \text{region}} \vec{F}_i \\ &\simeq \langle \vec{F}_b \rangle + \text{gaussian fluctuation}\end{aligned}\quad (3.3)$$

where $\langle \vec{F}_b \rangle$ corresponds to the visquous friction, and is an average at fixed (\vec{R}, \vec{P}) over all possible (\vec{r}_i, \vec{p}_i) .

In view of this, we expect that after coarse-graining, we get something like

$$M \frac{d^2 \vec{R}}{dt^2} = -\frac{\partial \mathcal{H}_0}{\partial \vec{R}} + \langle \vec{F}_b \rangle + \text{noise} \quad (3.4)$$

where the first term is due to the physics of the colloid itself, the second one corresponds to the drag, and the last term corresponds to the random action of the water particles on the body.

3.2 Master equation, again

3.2.1 For one and several continuous variables

We now denote a config \mathcal{C} by a d -dimensional vector x . We will often assume $d = 1$, as the generalisation can be done easily. The master equation writes

$$\partial_t P(x, t) = \int dx' w(x' \rightarrow x) P(x', t) - \int dx' w(x \rightarrow x') P(x, t) \quad (3.5)$$

We choose to write w as a function of the length $w(x \rightarrow x') = w(x, x' - x)$.

$$\partial_t P(x, t) = \int dr w(x - r, r) P(x - r, t) - \int dr w(x, r) P(x, t) \quad (3.6)$$

We expand w for low r

$$\partial_t P(x, t) = \sum_{n \geq 1} \frac{(-1)^n}{n!} \partial_x^n \left[\int dr r^n w(x, r) P(x, t) \right] \quad (3.7)$$

So defining

$$a_n(x) = \int dr r^n w(x, r) \quad (3.8)$$

The master equation rewrites

$$\partial_t P = \sum_{n \geq 1} \frac{(-1)^n}{n!} \partial_x^n (a_n(x) P(x, t)) \quad (3.9)$$

So as expected from a conserved current, we have

$$\partial_t P = -\partial_\mu J^\mu \quad (3.10)$$

Where

$$J^\mu = \text{probability current} \quad (3.11)$$

which is defined up to a quantity. There is a name for a_n : it is the Kramers-Moyal coefficient of order n .

3.2.2 Infinitesimal jumps

Assume that at $t = t_0$, the system is at $x(t_0) = x_0$. Then run over the dynamics over $[t_0, t_0 + \Delta t]$. Then ask about the random variable

$$\Delta x = x(t_0 + \Delta t) - x(t_0) \quad (3.12)$$

when Δt is small. We certainly want to solve

$$\partial_t P = -\partial_x J \quad (3.13)$$

with $p(x, t|x_0, t_0)$ verifying

$$p(x, t_0|x_0, t_0) = \delta(x - x_0) \quad (3.14)$$

$$\langle \Delta x^k \rangle = \int dx (x - x_0)^k p(x, t_0 + \Delta t|x_0, t_0) \quad (3.15)$$

where

$$p(x, t_0 + \Delta t|x_0, t_0) = p(x, t_0|x_0, t_0) + \Delta t \partial_t p + O(\Delta t^2) \quad (3.16)$$

So $\forall k \geq 1$

$$\langle \Delta x^k \rangle = \Delta t \sum \frac{1}{n!} \int dx \frac{d^n}{dx^n} (x - x_0)^k \delta(x - x_0) a(x_0) \quad (3.17)$$

Which gives

$$\frac{\langle \Delta x^k \rangle}{\Delta t} =_{\Delta t \rightarrow 0} a_k(x_0) \quad (3.18)$$

So $a_k(x_0)$ is the k^{th} momentum of the displacement over $[t_0, t_0 + \Delta t]$

3.2.3 Approximation

If we think of the example of the colloid, we expect Δx to be small with respect to the scale over which the colloid evolves.

As a first idea, we can truncate

$$\partial_t p = -\partial_x J = -\text{partial}_x a_1(x) p(x, t) \quad (3.19)$$

because

$$a_n(x) = \int dr r^n w(x, r) \quad (3.20)$$

is small. At this level of truncation we end up on a deterministic propagation equation in which the probability cloud moves as a block. If we truncate at order 2:

$$\partial_t p = -\partial_x (a_1(x) p) + \frac{1}{2} \partial^2 (a_2(x) p) \quad (3.21)$$

This is a diffusion equation: Fokker-Planck equation. In high dimension, we see a diffusion equation on a curved spacetime, where the metric of the spacetime is encoded in a_2

$$\partial_t p = -\partial_\mu (a_1^\mu p) + \frac{1}{2} \partial_\mu \partial_\nu (a_2^{\mu\nu} p) \quad (3.22)$$

However, we cannot expand at higher order: if we truncate at order $k \geq 3$, the positivity of p is not ensured. This is very important, since p is a probability. Hence, we have no choice but to keep our expansion (very limited) at order 1 or 2, or to keep the whole equation.

3.3 Langevin's equation

3.3.1 Gaussian random variables

A Gaussian random variable ξ has a probability density

$$P(\vec{\xi}) = \frac{1}{Z} e^{-\frac{1}{2} \vec{\xi}^\dagger \Gamma \vec{\xi}} \quad (3.23)$$

with Γ a positive definite symmetric matrix, and

$$Z = (2\pi)^{M/2} / \sqrt{\det \Gamma} \quad (3.24)$$

where M is the dimension of $\vec{\xi}$. With this we can define

$$G[h] = \langle e^{h^\dagger \xi} \rangle = e^{\frac{1}{2} h^\dagger \Gamma^{-1} h} \quad (3.25)$$

We know picture a Gaussian variable as a discrete time process in which $m = 1, \dots, M$ is viewed as a time slice index: $t_m = m\Delta t$. Eventually, we want to take the $\Delta t \rightarrow 0$ limit, or $M \rightarrow +\infty$, while keeping $t_{\text{obs}} = M\Delta t = \text{fixed}$. Hence, we write

$$\begin{aligned} d^M \xi P(\xi) &= Z^{-1} d\xi^1 \dots \xi_M e^{-\frac{1}{2} \sum_{mn} \xi_m \Gamma_{mn} \xi_n} \\ &= Z^{-1} d\xi^1 \dots \xi_M e^{-\frac{1}{2} \int dt dt' \xi(t) \Gamma(t, t') \xi(t')} \end{aligned} \quad (3.26)$$

with $t = m\Delta t$, $\xi(t) = \frac{1}{\sqrt{\Delta t}} \xi_m$, $\Gamma(t, t') = \frac{1}{\Delta t} \Gamma_{mm'}$.

Usually, one writes

$$\frac{1}{Z} d\xi^1 \dots \xi_M = \mathcal{D}\xi \quad (3.27)$$

The matrix $\Gamma(t, t')$ is called a noise kernel, and if $G(t, t')$ (Green's propagator) is its inverse:

$$\int dt'' \Gamma(t, t'') G(t'', t') = \delta(t - t') \quad (3.28)$$

where we have introduced

$$G(t, t') = \frac{G_{t/\Delta t, t'/\Delta t}}{\Delta t} = \langle \xi(t), \xi(t') \rangle \quad (3.29)$$

If the $\Delta t \rightarrow 0$ limit exists when computing averages and correlations of physical quantities, $\xi(t)$ is called a Gaussian process.

One exemple that will come back very often is one for which

$$\Gamma(t, t') = G(t, t') = \delta(t - t') \quad (3.30)$$

In this case, ξ is a Gaussian white noise. For instance, if we are interested in

$$x_M = \Delta t^{1/2} \sum_{m=1}^M \xi_m \quad (3.31)$$

then for $\Gamma_{nm} = \delta_{nm}$ we have

$$\begin{aligned} \langle x_M \rangle &= 0 \\ \langle x_M^2 \rangle &= M\Delta t = t_{\text{obs}} \end{aligned} \quad (3.32)$$

This can be recovered with the continuum limit

$$x(t_{\text{obs}}) = \int_0^{t_{\text{obs}}} ds \xi(s) \quad (3.33)$$

3.3.2 Stochastic Differential Equation

Let x_0 be fixed, and define x_n via the following recursion relation

$$x_{n+1} = x_n + f(x_n)\Delta t + g(x_n)\sqrt{\Delta t}\eta_n \quad (3.34)$$

with f, g given functions, and η_n a Gaussian process such that $\langle \eta_n \eta_m \rangle = \delta_{nm}$.

In the continuum limit, this reads, with $x(t) = x_{t/\Delta t}$

$$\Delta x = x(t + \Delta t) - x(t) = f(x(t))\Delta t + g(x(t))\sqrt{\Delta t}\eta_m \quad (3.35)$$

where

$$\sqrt{\Delta t}\eta_m = \Delta\eta = \int_t^{t+\Delta t} ds \, \eta(s) \quad (3.36)$$

with

$$\eta(s) = \frac{\eta_{s/\Delta t}}{\sqrt{\Delta t}} \quad (3.37)$$

$\Delta\eta$ is Gaussian with variance Δt

$$\begin{aligned} \langle \Delta\eta \rangle &= 0 \\ \langle \Delta\eta^2 \rangle &= \int_t^{t+\Delta t} ds ds' \langle \eta(s)\eta(s') \rangle = \Delta t \end{aligned} \quad (3.38)$$

It is tempting and natural to write

$$\frac{dx}{dt} = f(x(t)) + g(x(t))\eta(t) \quad (3.39)$$

We immediatly see that it is NOT fine to assume x is differentiable:

$$\frac{\Delta x}{\Delta t} \sim O\left(\frac{1}{\sqrt{\Delta t}}\right) \quad (3.40)$$

it explodes. The continuum limit of

$$\Delta x = f(x(t))\Delta t + g(x(t))\Delta\eta \Rightarrow \dot{x} = f + g\eta \quad (3.41)$$

is full of traps. Suppose we are given $\alpha \in [0, 1]$, then

$$\Delta x = f(x(t) + \alpha\Delta x)\Delta t + g(x(t) + \alpha\Delta x)\Delta\eta \quad (3.42)$$

then it looks like as $\Delta t \rightarrow 0$, $\dot{x} = f + g\eta$. So given an equation of the form $\dot{x} = f + g\eta$, we do not have a way of a priori knowing what is the intended discretized form, so we make it explicit by dressing the $=$ sign with α

3.3.3 Infinitesimal jumps

Let's focus on the statistics of the infinitesimal jumps $\Delta x = x(t_0 + \Delta t) - x_0$, with $x(t_0) = x_0$ fixed. We assume that

$$\begin{aligned} \Delta x &= f(x(t_0))\Delta t + g(x(t_0))\Delta\eta \\ \Rightarrow \langle \Delta x \rangle &= f(x(t_0))\Delta t \Rightarrow \lim_{\Delta t \rightarrow 0} \frac{\langle \Delta x \rangle}{\Delta t} = f(x_0) \\ \Rightarrow \lim_{\Delta t \rightarrow 0} \frac{\langle \Delta x^2 \rangle}{\Delta t} &= g^2(x_0) \end{aligned} \quad (3.43)$$

Moreover, we can compute that for any $k \geq 3$, we have $\lim_{\Delta t \rightarrow 0} \frac{\langle \Delta x^k \rangle}{\Delta t} = 0$

We know that the statistical properties of $x(t)$ are identical to those of a process governed by the following master's equation

$$\partial_t p = -\partial_x(a_1(x)p) + \frac{1}{2}\partial_x^2(a_2(x)p) \quad (3.44)$$

in which we have chosen

$$a_1(x) = f(x) \quad a_2(x) = g^2(x) \quad (3.45)$$

3.3.4 Stochastic calculus

Since there is a variety of discretized processes that lead to the same (visually speaking) continuous SDE (stochastic differential equation), we'd like to understand better the connections between these various discretizations. We shall now take $0 \leq \alpha \leq 1$, and consider

$$\Delta x = x(t + \Delta t) - x(t) = f(x(t) + \alpha \Delta t) \Delta t + g(x(t) + \alpha \Delta x) \Delta \eta \quad (3.46)$$

Our goal is to find, if it exists, the corresponding Fokker-Planck equation.

Chapter 4

Time-reversal

Chapter 5

Metastability

Chapter 6

Mean-field

Chapter 7

Field theories

Chapter 8

Exactly solvable models