

AirWatcher Design document

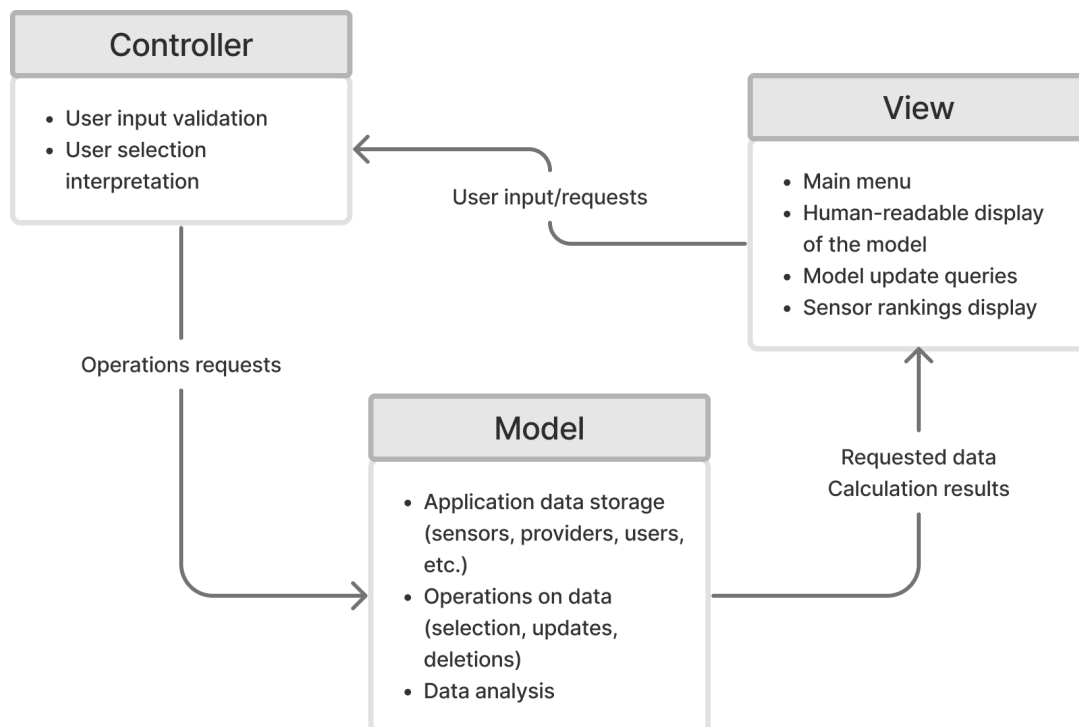
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Architecture

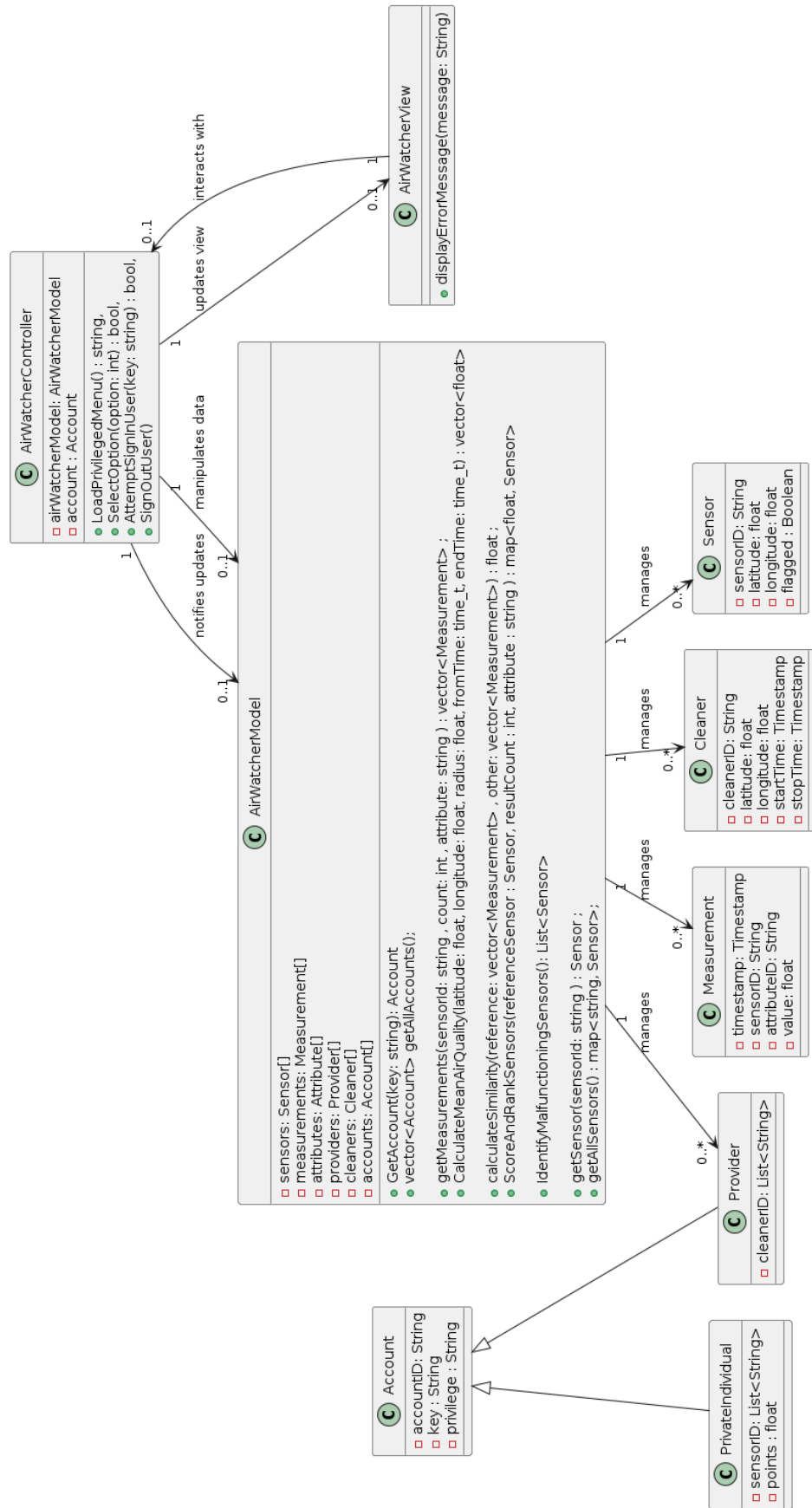
Considering the needs of the AirWatcher application, we have chosen the Model-View-Controller (MVC) pattern as the most suitable.

This architectural pattern fits the needs of the AirWatcher application best primarily because of its strong separation between presentation and interaction. The MVC architecture divides the application in 3 interconnected components allowing for better organization and maintenance of code. The model manages the data, the view handles the presentation layer, and the controller manages user input and interaction.

From a development and software maintenance standpoint, this pattern allows for separate expansion of the components independently from the others, ensuring scalability and constant coherence of the application.



Class diagram



Major usage scenarios

Scenario 1 : Analyzing sensor data

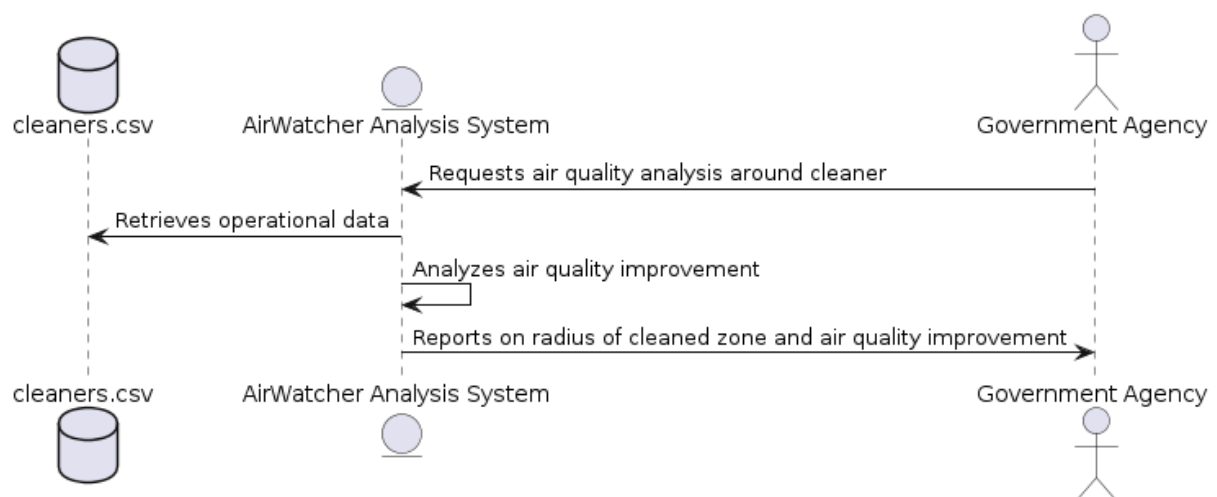
Description

The government agency wants to analyze data from one or multiple sensors to obtain data visualizations such as mean air quality over an area or air quality improvement over time.

Steps

1. An agent initiates the analysis process by selecting one or multiple sensor IDs.
2. The AirWatcher application retrieves the data associated with the selected sensors.
3. The application analyzes the requested data
4. Results of the analysis are displayed to the official.

Sequence diagram



Scenario 2 : Find similarity between sensors

Description

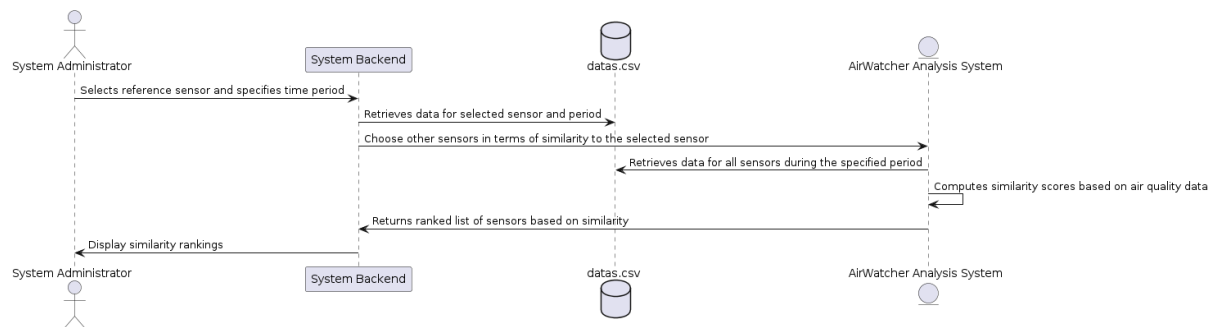
The government agency wants to identify similar areas in terms of air quality

Steps

1. An agent selects a reference sensor and a time period on which to perform the analysis
2. The AirWatcher application retrieves the data from all sensors in the specified period
3. The application computes a similarity score for each sensor

- The agent is presented with a list of sensors ranked by similarity to the reference

Sequence diagram



Scenario 3 : Identifying malfunctioning sensors

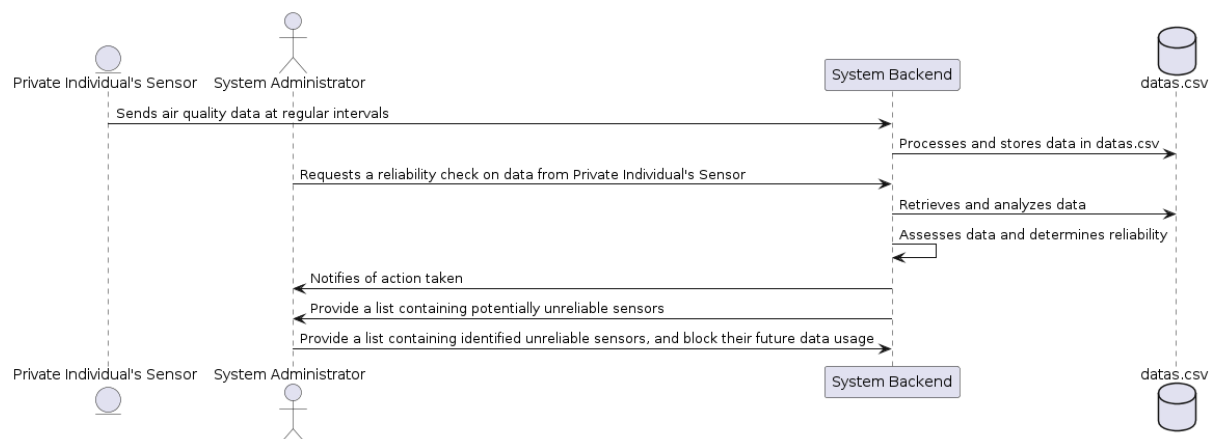
Description

The government agency wants to identify faulty or tampered-with sensors.

Steps

- An agent signs in to the application and selects the faulty sensor analysis function
- The AirWatcher application performs an analysis over all recent sensor data
- The user is presented with a list of potential faulty sensors
- The user can review the sensors' data and flag them as malfunctioning. Their readings will not be taken into account from then on

Sequence diagram



Major algorithms

Rank sensors by similarity

Algorithm 1 Score and rank all sensors

```
1: function SCOREANDRANKSENSORS(referenceSensor: Sensor, timeFrame:
   Timestamp): List of Sensor
2:   similarityScores  $\leftarrow \{\}$ 
3:   for all sensor in allSensors do
4:     similarityScore  $\leftarrow$  CALCULATESIMILARITY(referenceSensor, sensor,
       timeFrame)
5:     add the sensor and its similarityScore to similarityScores
6:   end for
7:   Sort similarityScores
8:   rankedSensors  $\leftarrow \{\}$ 
9:   for all pair in similarityScores do
10:    add the sensor (first element of the pair) to rankedSensors
11:   end for
12:   return rankedSensors
13: end function
14:
15: function CALCULATESIMILARITY(referenceSensor: Sensor, sensor: Sensor,
   timeFrame: Timestamp): Double
16:   referenceData  $\leftarrow$  GETDATAWITHINTIMEFRAME(referenceSensor,
     timeFrame)
17:   sensorData  $\leftarrow$  GETDATAWITHINTIMEFRAME(sensor, timeFrame)
18:   similarityScore  $\leftarrow$  CALCULATESIMILARITYSCORE(referenceData, sen-
     sorData)
19:   return similarityScore
20: end function
```

Calculate mean air quality

Algorithm 1: Calculate Mean Air Quality

Description : Calculates the mean air quality within a circular area specified by the user, using the time bounds provided to determine the period for calculation

Input : Latitude: float;
Longitude: float;
Radius: float;
Time frame: Timestamp;

Output : Mean air quality : float

```
list of air quality measurements  $\leftarrow$  [ ];  
sum  $\leftarrow$  0;  
count  $\leftarrow$  0;  
foreach air quality measurement in the Time Frame do  
|   if the measurement is within a radius of Radius around (Longitude, Latitude)  
|   then  
|   |   Add the measurement to the list of measurements;  
|   end  
end  
if the list of measurements is not empty then  
|   foreach measurement in the list of measurements do  
|   |   sum  $\leftarrow$  sum + air quality of the measurement;  
|   |   count  $\leftarrow$  count + 1;  
|   end  
|   mean  $\leftarrow$  sum / count;  
end  
else  
|   No air quality measurements available for the specified period and location;  
|   Initialize mean to a default value or return an error;  
end  
Return mean;
```

Identify malfunctioning sensors

Algorithm 1: Identify malfunctioning sensors

Description : This algorithm evaluates the reliability of data from private sensors, identifying signs of tampering or malfunction. If deemed unreliable, the data is marked as invalid and excluded from future queries.;

Input : Data: file csv;

Tolerance: float csv;

Output : List of Sensor objects;

file \leftarrow Open csvFile;

sensorDict \leftarrow Empty Dictionary;

listInformation \leftarrow Empty List;

listOfpotentialunreliablesensors \leftarrow Empty List;

foreach *line in file* **do**

 sensorDetails \leftarrow Split line by ',';

 sensorID \leftarrow sensorDetails[0];

 Latitude \leftarrow ConvertToFloat(sensorDetails[1]);

 Longitude \leftarrow ConvertToFloat(sensorDetails[2]);

 Time frame \leftarrow ConvertToTimestamp(sensorDetails[3]);

 airQualityValue \leftarrow ConvertToFloat(sensorDetails[4]);

 listInformation[0] \leftarrow Latitude;

 listInformation[1] \leftarrow Longitude;

 listInformation[2] \leftarrow Time frame;

 listInformation[3] \leftarrow airQualityValue;

 sensorDict[sensorID] \leftarrow listInformation;

end

foreach *element in sensorDict* **do**

if (*abs(Calcul*

mean(element[1][0],element[1][1],1000,element[1][2])-element[1][3]) isbigger

than Tolerance) **then**

 Append element[0] to listOfPotentialUnreliableSensors;

end

end

Return listOfpotentialunreliablesensors;

Unit tests

Function 1: rankSensorsBySimilarity

Description:

- What it should do: Rank all sensors in terms of similarity to a selected sensor based on data generated during a specified period.
- Context (Pre-conditions):
 - The function requires sensor data from the specified period.
 - The function needs a selected sensor to compare against.

- Result (Post-conditions):
 - The function returns a ranked list of sensors based on their similarity to the selected sensor.

Use Cases:

	Input	Expected Output
1. Base Case - No Sensors Found	No sensors available in the database.	An empty list.
2. Single Sensor Available	Only one sensor is available in the database.	A list containing the single sensor with a similarity degree of 100%.
3. General Case - Multiple Sensors Available	Multiple sensors available in the database with varying degrees of similarity.	An ordered list of sensors based on their similarity degree, from most similar to least similar.
4. No Similar Sensors Found	No sensor is similar to the given sensor.	An empty list.
5. No Sensors Available	No sensors available in the database.	An empty list.
6. All Sensors Have Same Similarity	All available sensors have the same similarity degree with the given sensor.	A list containing all sensors, with identical similarity degrees for each.

Function 2: calculateMeanAirQuality

Description:

- What it should do: Calculate the mean air quality for a specified area and time period.
- Context (Pre-conditions):
 - The function requires a list of air quality measurements within the specified area and time period.
- Result (Post-conditions):

- The function returns the mean air quality value for the specified area and time period.

Use Cases:

	Input	Expected Output
1. No Measurements Available	No air quality measurements available within the specified time frame and location.	Return a default value or raise an error indicating no measurements available.
2. Single Measurement Available	Only one air quality measurement available within the specified time frame and location.	Return the air quality value of the single measurement as the mean.
3. Multiple Measurements Available	Multiple air quality measurements available within the specified time frame and location.	Calculate the mean air quality value based on all available measurements and return it.
4. Maximum Number of Measurements	Maximum number of air quality measurements available within the specified time frame and location.	Ensure the algorithm can handle the maximum number of measurements without performance issues or errors.
5. No Measurements within Radius	No air quality measurements available within the specified radius of the given location.	Return a default value or raise an error indicating no measurements available within the specified radius.
6. Invalid Time Frame	Invalid time frame provided (e.g., end time before start time).	Proper error handling and error message indicating the invalid time frame.
7. Invalid Location	Invalid location provided (e.g., latitude or longitude out of range).	Proper error handling and error message indicating the invalid location.

Function 3: identifyMalfunctioningSensors

Description:

- What it should do: Identify malfunctioning sensors based on their data and predefined thresholds.
- Context (Pre-conditions):
 - The function requires sensor data and predefined thresholds for identifying malfunctioning sensors.
- Result (Post-conditions):
 - The function returns a list of sensors flagged as malfunctioning.

Use Cases:

	Input	Expected Output
1. No Malfunctioning Sensors	All sensors are functioning properly.	Return an empty list indicating no malfunctioning sensors.
2. Single Malfunctioning Sensor	One sensor is malfunctioning.	Return a list containing the ID of the malfunctioning sensor.
3. Multiple Malfunctioning Sensors	Multiple sensors are malfunctioning.	Return a list containing the IDs of all malfunctioning sensors.
4. No Sensors Available	No sensors are available.	Return an empty list indicating no sensors available.
5. Large Number of Sensors	Large number of sensors, some of which are malfunctioning.	Verify the function's performance with a large number of sensors and ensure all malfunctioning sensors are correctly identified.