

Non-Stationary Processes

- 1) Cyclostationary
- 2) Orthogonal Increment

$$X(t) \text{ w.s.s.} \Leftrightarrow E[X(t)] = m, \quad E[X(t)X(s)] = R_X(t-s)$$

$$R_X(t+T, s+T) = R_X(t, s), \quad \forall T \in \mathbb{R} \text{ (w.s.s.)} \xrightarrow[\text{condition}]{\text{relax this}} R_X(t+T, s+T) = R_X(t, s), \quad \exists T \in \mathbb{R} \quad \text{Cyclo-Stationary}$$

$$R_X(t+mT, s+mT) = R_X(t, s), \quad \forall m$$

Relation between WSS. & cyclostationary:

Randomization $\Theta \sim U(0, T)$. $\Theta, X(t)$ indep.

$$Y(t) = X(t + \Theta) : X(t) \text{ Cyclo} \Rightarrow Y(t) \text{ w.s.s.}$$

$$R_Y(t, s) = E[Y(t)Y(s)] = E[X(t+\Theta)X(s+\Theta)] = E_{\Theta} [E_X[X(t+\Theta)X(s+\Theta) | \Theta = \theta]] = E_{\Theta} [R_X(t+\theta, s+\theta)]$$

$$\xrightarrow{\Theta \sim U(0, T)} \frac{1}{T} \int_0^T R_X(t+\theta, s+\theta) d\theta$$

$$\forall T', R_Y(t+T', s+T') = \frac{1}{T} \int_0^T R_X(t+T'+\theta, s+T'+\theta) d\theta \xrightarrow{\theta' = T'+\theta} \frac{1}{T} \int_{T'}^{T'+T} R_X(t+\theta', s+\theta') d\theta'$$

$$= \frac{1}{T} \int_0^T R_X(t+\theta', s+\theta') d\theta' = R_Y(t, s)$$

$$\Rightarrow Y(t) \text{ w.s.s.}$$

Constellation (Phase + Amp. \rightarrow Symbol/Bitstream)

PAM (Pulse ^{Complex} Amplitude Modulation) BPSK, QPSK, QAM

$$X(t) = \sum_{k=-\infty}^{\infty} \alpha_k \phi(t-kT) \quad \alpha_k: \text{r.v. Information Symbol}$$

$$\phi(t): \text{Baseband Waveform.}$$

$$30 = 00$$

$$R_X(t, s) = E[X(t)X(s)] = E\left[\sum_k \sum_n \alpha_k \alpha_n \phi(t-kT) \phi(s-nT)\right] = \sum_k \sum_n E[\alpha_k \alpha_n] \phi(t-kT) \phi(s-nT)$$

$$\{\alpha_n\} \text{ WSS.} \rightarrow R_{\alpha}(k-n) \Rightarrow \sum_k \sum_n R_{\alpha}(k-n) \phi(t-kT) \phi(s-nT)$$

$$\text{Generally: } R_X(t+T', s+T') \neq R_X(t, s)$$

$$\text{But when } T' = T, R_X(t+T, s+T) = \sum_k \sum_n R_{\alpha}(k, n) \phi(t+T-kT) \phi(s+T-nT) \xrightarrow[n'=n-1]{k'=k-1} \sum_{k', n'} R_{\alpha}(k'+1, n'+1) \phi(t-k'T) \phi(s-n'T)$$

\uparrow
 $R_{\alpha}(k'-n')$

\uparrow

$R_X(t, s)$

$X(t)$: Cyclostationary stochastic processes.

$$\bar{X}(t) = X(t + \Theta), \quad \Theta \sim U(0, T)$$

$$R_{\bar{X}}(t, s) = \frac{1}{T} \int_0^T R_X(t + \theta, s + \theta) d\theta = \frac{1}{T} \int_0^T \sum_k \sum_n R_X(k - n) \phi(t - kT + \theta) \phi(s - nT + \theta) d\theta$$

$$k' = k - n, \quad n' = n$$

$$= \frac{1}{T} \int_0^T \sum_{k'} \sum_{n'} R_X(k') \phi(t + \theta - (n' + k')T) \phi(s + \theta - n'T) d\theta$$

$$\text{Let } \theta' = \theta - n'T : \frac{1}{T} \sum_{k'} \sum_{n'} R_X(k') \int_{-n'T}^{-(n'+1)T} \phi(t + \theta' - k'T) \phi(s + \theta') d\theta'$$

$$= \frac{1}{T} \sum_{k'} R_X(k') \cdot \sum_{n'=-\infty}^{+\infty} \int_{-n'T}^{-(n'+1)T} \phi(t + \theta' - k'T) \phi(s + \theta') d\theta' = \frac{1}{T} \sum_{k'} R_X(k') \int_{\mathbb{R}} \underbrace{\phi(t + \theta' - k'T) \phi(s + \theta')}_{\theta'' = s + \theta'} d\theta'$$

$$= \frac{1}{T} \sum_{k'} R_X(k') \int_{\mathbb{R}} \phi(t - k'T - s + \theta'') \phi(\theta'') d\theta''$$

$$= \frac{1}{T} \sum_{k'} R_X(k') R_{\phi}(t - s - k'T) = R_{\bar{X}}(t - s)$$

$$S_{\bar{X}}(\omega) = \int_{-\infty}^{+\infty} R_{\bar{X}}(\tau) \exp(-j\omega\tau) d\tau = \frac{1}{T} \int_{-\infty}^{+\infty} \left[\sum_k R_X(k) R_{\phi}(\tau - kT) \right] \exp(-j\omega\tau) d\tau = \frac{1}{T} \sum_k R_X(k) \cdot \int_{\mathbb{R}} R_{\phi}(\tau - kT) \exp(-j\omega\tau) d\tau$$

$$= \frac{1}{T} \sum_k R_X(k) \exp(-j\omega kT) \int_{\mathbb{R}} R_{\phi}(\tau') \exp(-j\omega\tau') d\tau'$$

$$= \frac{1}{T} S_X(\omega) \cdot S_{\phi}(\omega) = \frac{1}{T} S_X(\omega) |\Phi(\omega)|^2$$

$$Z(t) = \sum_k \alpha_k \delta(t - kT) \quad Z(t) \rightarrow \boxed{\phi(t)} \rightarrow ? \quad Z(t) * \phi(t) = \sum_k \alpha_k \phi(t - kT)$$

2) Orthogonal Increment

$$X(t), \quad \forall t_1 < t_2 \leq t_3 < t_4, \quad X(t_4) - X(t_3) \perp X(t_2) - X(t_1) : E[(X(t_4) - X(t_3))(X(t_2) - X(t_1))] = 0$$

$$R_X(t, s) = E[X(t)X(s)] \xrightarrow[\substack{S < t \\ X(0)=0}}{=} E[(X(t) - X(s) + X(s) - X(0))(X(s) - X(0))] = E[X^2(s)]$$

$$R_X(t, s) = E[X^2(\min(t, s))] = g(\min(t, s)) \rightarrow \text{Characteristic Property of Orthogonal Increment.}$$

$$\text{i.e. if } R_X(t, s) = g(\min(t, s)), \quad X(t) \text{ has Orthogonal Increment} \\ (\forall t, s)$$

$$E[(X(t_4) - X(t_3))(X(t_2) - X(t_1))] = R_X(t_4, t_2) + R_X(t_3, t_1) - R_X(t_3, t_2) - R_X(t_4, t_1)$$

$$t_4 > t_3 \geq t_2 > t_1 \quad \text{if } R_X(t, s) = g(\min(t, s)), \text{ then} \\ = g(t_2) + g(t_1) - g(t_2) - g(t_1) = 0$$

\therefore Orthogonal Increment

Example of Orthogonal Increment: Brownian Motion

def. of Brownian Motion:

- ① $B(0) = 0$ ② Orthogonal Increment ③ $B(t) - B(s) \sim N(0, \sigma^2(t-s))$

$$R_B(t,s) = E(B^2(s)) = \sigma^2 s = \sigma^2 \min(t,s)$$

$$Y(t) = \frac{d}{dt} B(t) \text{ (Not Rigorous)}$$

$$B(s) - B(0) \sim N(0, \sigma^2(s-0)) = N(0, \sigma^2 s)$$

$$E(B(s)) = 0, \quad E(B^2(s)) = \text{var}(B(s)) = \sigma^2 s$$

$$R_Y(t,s) = E[Y(t)Y(s)]$$

$$= E\left[\frac{d}{dt} Y(t) \frac{d}{ds} Y(s)\right]$$

$$= \frac{\partial^2}{\partial t \partial s} E[Y(t)Y(s)]$$

$$R_Y(t,s) = -\frac{\sigma^2}{2} \frac{\partial^2}{\partial t \partial s} |t-s| \quad \left(\frac{d}{dx}|x| = \text{sgn}(x)\right)$$

$$= -\frac{\sigma^2}{2} \frac{\partial}{\partial s} \left(\frac{\partial}{\partial t} |t-s|\right)$$

$$= -\frac{\sigma^2}{2} \frac{\partial}{\partial s} (\text{sgn}(t-s)) \quad \left(\frac{d}{dx} \text{sgn}(x) = 2\delta(x)\right)$$

$$= -\frac{\sigma^2}{2} [2\delta(t-s)]$$

$$= \sigma^2 \delta(t-s)$$

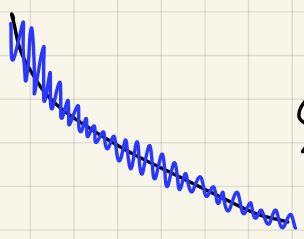
$$= \frac{\partial^2}{\partial t \partial s} R_B(t,s) = \sigma^2 \frac{\partial^2}{\partial t \partial s} \min(t,s) = \sigma^2 \frac{\partial^2}{\partial t \partial s} \left(\frac{1}{2}(s+t-|s-t|)\right)$$

$$= -\frac{1}{2} \sigma^2 \frac{\partial^2}{\partial t \partial s} |t-s|$$

$$V(x) = \begin{cases} 1, & x \geq 0 \\ 0, & x < 0 \end{cases}, \quad \frac{dV(x)}{dx} = \delta(x), \quad \text{sgn}(x) = V(x) - V(-x)$$

derivative is $\delta(\cdot)$ function \Rightarrow White Noise
(Brownian Motion)

Orthogonal Increment $\xrightarrow{\text{differential}}$ W.S.S.



Stationary lies in \rightarrow ~~envelope~~ (Trend \Rightarrow Non-Stationary)
 \rightarrow glitches (Brownian Motion $\xrightarrow[\text{High-Pass Filter}]{\text{Derivative}}$ W.S.S.)

Isometry with Complex Exponentials (Oscillating)
 \therefore W.S.S. \rightarrow High-Frequency

任何事都是有道理的，
区别是有没有必要知道它，
和有没有能力去知道它。