

Gaussian & Nonlinearity

① Square Law: $X(t)$ Gaussian $\rightarrow \boxed{X^2} \rightarrow Y(t) = X^2(t) \geq 0$, not Gaussian.

$$E[Y(t)] = E[X^2] = R_X(t, t) = R_X(0)$$

$$R_Y(t, s) = E[Y(t)Y(s)] = E[X^2(t)X^2(s)] \quad \text{High-Order Moments (Gaussian)} \rightarrow \text{did } E[X^n] \text{ in 9th lecture}$$

Example: $(X_1, X_2, X_3, X_4) \sim \mathcal{N}$, $E[X_k] = 0$, $E[X_1 X_2 X_3 X_4] = ?$

we want to make it more general
to calculate moments between different r.v.s

$$E[X_1 X_2 X_3 X_4] = \int x_1 x_2 x_3 x_4 f_{X_1, X_2, X_3, X_4} dx_1 dx_2 dx_3 dx_4$$

more ideal than Σ^{-1} approach moments from $\phi_X(w)$ (Σ)
rather than distribution (Σ^{-1})
???

$$\exp\left(-\frac{1}{2}(x_1, x_2, x_3, x_4) \underbrace{\Sigma^{-1}}_{*} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}\right) \Rightarrow \phi_X(w) = \exp(jw^T \mu - \frac{1}{2}w^T \Sigma w) \stackrel{E[X]=0}{=} \exp(-\frac{1}{2}w^T \Sigma w)$$

$$X = (X_1, \dots, X_n)^T \Rightarrow \phi_X(w) = E[\exp(j(w_1 X_1 + \dots + w_n X_n))]$$

$$E[X_1] = \frac{1}{j} \frac{\partial}{\partial w_1} \phi_X(w_1, \dots, w_n) \Big|_{w_1 = \dots = w_n = 0}$$

$$\therefore E[X_k] = \frac{1}{j} \frac{\partial}{\partial w_k} \phi_X(w_1, \dots, w_n) \Big|_{w_1 = \dots = w_n = 0}$$

Moment

Distribution
 \Downarrow
Integral

Characteristic Function
 \Downarrow
Differential (Easier)

$$E[X_1^{\alpha_1} \dots X_n^{\alpha_n}] = \frac{1}{j^{\alpha_1 + \dots + \alpha_n}} \frac{\partial^{\alpha_1 + \dots + \alpha_n}}{\partial w_1^{\alpha_1} \dots \partial w_n^{\alpha_n}} \phi_X(w_1, \dots, w_n) \Big|_{w_1 = \dots = w_n = 0}$$

$$E[X_1 X_2 X_3 X_4] = j^{-4} \frac{\partial^4}{\partial w_1 \partial w_2 \partial w_3 \partial w_4} \phi_X(w) \Big|_{w=0} = \dots = E[X_1 X_2] E[X_3 X_4] + E[X_1 X_3] E[X_2 X_4] + E[X_1 X_4] E[X_2 X_3]$$

$$\frac{\partial^4}{\partial x_1 \partial x_2 \partial x_3 \partial x_4} E[\exp(jw^T X)] = \frac{\partial^4}{\partial w_1 \partial w_2 \partial w_3 \partial w_4} \exp(jw^T \mu_X - \frac{1}{2}w^T \Sigma w) \stackrel{\text{Suppose } \mu=0}{\text{normalized}} \frac{\partial^4}{\partial w_1 \partial w_2 \partial w_3 \partial w_4} \exp\left(-\frac{1}{2} \sum_{i=1}^4 \sum_{j=1}^4 w_i \Sigma_{ij} w_j\right)$$

$$= \frac{\partial^4}{\partial w_1 \partial w_2 \partial w_3 \partial w_4} \exp\left(-\frac{1}{2} \sum_i w_i^2 \Sigma_{ii} - \sum_{i < j} w_i w_j \Sigma_{ij}\right) = \frac{\partial^3}{\partial w_2 \partial w_3 \partial w_4} \left(-\sum_i w_i \Sigma_{i1}\right) \exp\left(-\frac{1}{2} \sum_i w_i^2 \Sigma_{ii} - \sum_{i < j} w_i w_j \Sigma_{ij}\right)$$

$$= \frac{\partial^2}{\partial w_3 \partial w_4} \left[-\Sigma_{21} + \left(-\sum_i w_i \Sigma_{i1}\right) \cdot \left(-\sum_j w_j \Sigma_{j2}\right)\right] \exp(\dots) = \frac{\partial^2}{\partial w_3 \partial w_4} \left[-\Sigma_{21} + \sum_i w_i \Sigma_{i1} \cdot \sum_j w_j \Sigma_{j2}\right] \exp(\dots)$$

$$= \frac{\partial}{\partial w_4} \left[\Sigma_{31} \cdot \sum_j w_j \Sigma_{j2} + \Sigma_{32} \cdot \sum_i w_i \Sigma_{i1} + \left(-\Sigma_{21} + \sum_i w_i \Sigma_{i1} \cdot \sum_j w_j \Sigma_{j2}\right) \left(-\sum_k w_k \Sigma_{k3}\right) \right] \exp(\dots)$$

Since we substitute (w_1, w_2, w_3, w_4) with $(0, 0, 0, 0)$, we only search 1st-order w_4 terms.

$$E[X_1 X_2 X_3 X_4] = \Sigma_{31} \Sigma_{42} + \Sigma_{32} \Sigma_{41} + (-\Sigma_{21}) \cdot (-\Sigma_{43}) = \Sigma_{12} \Sigma_{34} + \Sigma_{13} \Sigma_{24} + \Sigma_{14} \Sigma_{23} \quad \text{Proved!}$$

$$E[X^2(t)X^2(s)] = R_X(t, t) R_X(s, s) + 2 R_X^2(t, s) \xrightarrow{\text{if } X \text{ is wss.}} R_X^2(0) + 2 R_X^2(t-s), \text{ PSD: } \dots$$

② Sign Function

$$\text{sgn}(x) = \begin{cases} 1, & x \geq 0 \\ -1, & x < 0 \end{cases}$$

Gaussian
 $X(t) \rightarrow \boxed{\text{sgn}(X)} \rightarrow Y(t)$
 $E[X(t)] = 0$

$$EY = 1 \cdot P(X(t) \geq 0) + (-1) \cdot P(X(t) < 0) = 0 \quad (f_X: \text{even function})$$

$$R_Y(t, s) = E[Y(t)Y(s)] = 1 \cdot P(Y(t)Y(s) = 1) + (-1) \cdot P(Y(t)Y(s) = -1) = 2P(Y(t)Y(s) = 1) - 1 = 2P(X(t)X(s) \geq 0) - 1$$

$$P(X(t)X(s) \geq 0) = \left(\int_{-\infty}^0 \int_{-\infty}^0 + \int_0^{\infty} \int_0^{\infty} \right) \frac{1}{2\pi \sigma_1 \sigma_2 \sqrt{1-\rho^2}} \exp\left[-\frac{1}{2(1-\rho^2)} \left(\left(\frac{x_1}{\sigma_1}\right)^2 + \left(\frac{x_2}{\sigma_2}\right)^2 - 2\rho \frac{x_1 x_2}{\sigma_1 \sigma_2} \right)\right] dx_1 dx_2$$

$$\text{let } x'_1 = \frac{x_1}{\sigma_1}, x'_2 = \frac{x_2}{\sigma_2} \quad = \left(\int_{-\infty}^0 \int_{-\infty}^0 + \int_0^{\infty} \int_0^{\infty} \right) \frac{1}{2\pi \sqrt{1-\rho^2}} \exp\left[-\frac{1}{2(1-\rho^2)} (x'^2_1 + x'^2_2 - 2\rho x'_1 x'_2)\right] dx'_1 dx'_2$$

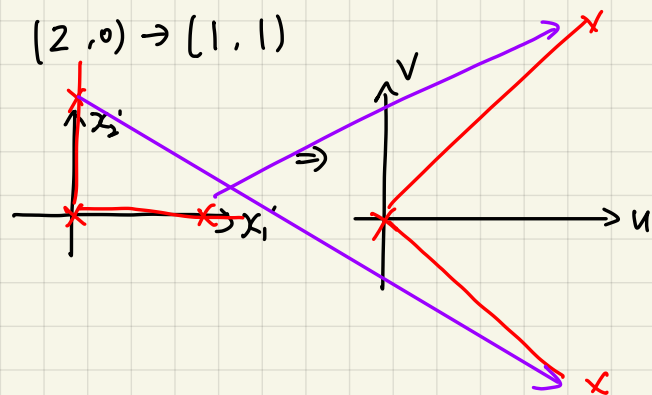
$$= 2 \cdot \int_0^{\infty} \int_0^{\infty} \frac{1}{2\pi \sqrt{1-\rho^2}} \exp\left[-\frac{1}{2(1-\rho^2)} (x'^2_1 + x'^2_2 - 2\rho x'_1 x'_2)\right] dx'_1 dx'_2$$

$$\text{let } \begin{cases} x'_1 = u+v \\ x'_2 = u-v \end{cases} \quad \begin{bmatrix} x'_1 \\ x'_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}, \quad |J| = \left| \frac{\partial(x'_1, x'_2)}{\partial(u, v)} \right| = \begin{vmatrix} 1 & 1 \\ 1 & -1 \end{vmatrix} = 2$$

Linear transform: $(0, 0) \rightarrow (0, 0)$

$(0, 2) \rightarrow (1, -1)$

$(2, 0) \rightarrow (1, 1)$



$$= 2 \cdot \int_0^{\infty} \int_{-u}^u \frac{1}{2\pi \sqrt{1-\rho^2}} \exp\left[-\frac{1}{2(1-\rho^2)} (2u^2 + 2v^2 - 2\rho(u^2 - v^2))\right] 2 du dv$$

$$= 4 \int_0^{\infty} \int_{-u}^u \frac{1}{2\pi \sqrt{1-\rho^2}} \exp\left[-\frac{1}{1-\rho^2} ((1-\rho)u^2 + (1+\rho)v^2)\right] du dv$$

$$= 4 \int_0^{\infty} \int_{-u}^u \frac{1}{2\pi \sqrt{1-\rho^2}} \exp\left[-\frac{u^2}{1+\rho} - \frac{v^2}{1-\rho}\right] du dv$$

$$\text{let } u' = \frac{u}{\sqrt{1+\rho}}, v' = \frac{v}{\sqrt{1-\rho}} \quad = 4 \int_0^{\infty} \int_{-\frac{\sqrt{1-\rho}}{\sqrt{1+\rho}} u'}^{\frac{\sqrt{1-\rho}}{\sqrt{1+\rho}} u'} \frac{1}{2\pi} \exp(-u'^2 - v'^2) du' dv'$$

$$(1, 1) \rightarrow \left(\frac{1}{\sqrt{1+\rho}}, \frac{1}{\sqrt{1-\rho}}\right)$$

$$(1, -1) \rightarrow \left(\frac{1}{\sqrt{1+\rho}}, \frac{-1}{\sqrt{1-\rho}}\right)$$

polar coord. $\begin{cases} u' = r \cos \theta \\ v' = r \sin \theta \end{cases}$

$$= 4 \int_0^{\infty} \int_{-\phi}^{\phi} \frac{1}{2\pi} \exp(-r^2) r dr d\theta \quad (\phi = \tan^{-1} \sqrt{\frac{1-\rho}{1+\rho}})$$

$$= 4 \cdot \frac{1}{2\pi} \cdot 2\phi \cdot \frac{1}{2} = \frac{2\phi}{\pi}$$

$$\therefore P(X(t)X(s) \geq 0) = \frac{1}{2} + \frac{\sin^{-1}(\rho)}{\pi}$$

"Arcsin Law"

$$\begin{cases} R_Y(t, s) = 2 \cdot \left(\frac{1}{2} + \frac{\sin^{-1}(\rho)}{\pi} \right) - 1 = \frac{2}{\pi} \sin^{-1}(\rho) \\ \rho = \frac{R_X(t-s)}{R_X(0)} \end{cases}$$

$$\rho = \frac{E[X(t)X(s)]}{[E[X^2(t)]E[X^2(s)]]^{1/2}} = \frac{R_X(t-s)}{R_X(0)}$$

$$\cos \theta = \frac{1 - \tan^2 \frac{\theta}{2}}{1 + \tan^2 \frac{\theta}{2}}$$

$$\tan^2 \phi = \frac{1+\rho}{1-\rho}, \quad 1 + \tan^2 \phi = \frac{2}{1-\rho}$$

$$\rho = 1 - \frac{2}{1 + \tan^2 \phi} \Rightarrow \frac{1 - \tan^2 \phi}{1 + \tan^2 \phi} = -\rho$$

$$\therefore \cos 2\phi = -\rho, \quad 2\phi = \cos^{-1}(-\rho)$$

$$\sin^{-1}(x) + \cos^{-1}(x) = \frac{\pi}{2}$$

$$\Rightarrow 2\phi = \cos^{-1}(-\rho) = \frac{\pi}{2} - \sin^{-1}(-\rho) = \frac{\pi}{2} + \sin^{-1}(\rho)$$

Useful Tool dealing with Gaussian Linearity:

$g(x_1, x_2)$ general non-linear function, $(X_1, X_2) \sim N(0, 0, \sigma_1^2, \sigma_2^2, \rho)$

$$\frac{\partial E[g(X_1, X_2)]}{\partial \rho} = \sigma_1 \sigma_2 E\left[\frac{\partial^2 g(X_1, X_2)}{\partial x_1 \partial x_2}\right]$$

Price Theorem

Use Price Thm. to solve $E[\text{sgn}(X(t))\text{sgn}(X(s))]$

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$$\textcircled{1} g(x_1, x_2) = \text{sgn}(x_1) \text{sgn}(x_2) \quad \textcircled{2} \frac{\partial^2 g(x_1, x_2)}{\partial x_1 \partial x_2} = 2\delta(x_1) \cdot 2\delta(x_2)$$

$$\textcircled{3} E\left[\frac{\partial^2 g(x_1, x_2)}{\partial x_1 \partial x_2}\right] = \iint 4\delta(x_1)\delta(x_2) \frac{1}{2\pi b_1 b_2 \sqrt{1-\rho^2}} \exp\left(\frac{-1}{2(1-\rho^2)}\left(\frac{x_1^2}{b_1^2} + \frac{x_2^2}{b_2^2} - 2\rho\left(\frac{x_1}{b_1}\right)\left(\frac{x_2}{b_2}\right)\right)\right) dx_1 dx_2$$

$$= \frac{2}{\pi b_1 b_2 \sqrt{1-\rho^2}}$$

$$\Rightarrow \frac{\partial E[g(x_1, x_2)]}{\partial \rho} = b_1 b_2 \cdot E\left[\frac{\partial^2 g(x_1, x_2)}{\partial x_1 \partial x_2}\right] = \frac{2}{\pi} \frac{1}{\sqrt{1-\rho^2}}$$

$$\Rightarrow E[g(x_1, x_2)] = \int_0^{\rho} \frac{2}{\pi} \frac{1}{\sqrt{1-\rho^2}} d\rho + \underbrace{E[g(x_1, x_2)]}_{E[\text{sgn}(x_1) \cdot \text{sgn}(x_2)] = 0} \Big|_{\rho=0} = \frac{2}{\pi} \sin^{-1} \rho$$

Apply Price Thm. to 1st Example: $E[X^2(t)X^2(s)]$

$$g(x_1, x_2) = x_1^2 x_2^2 \quad \frac{\partial^2 g}{\partial x_1 \partial x_2} = 4x_1 x_2 \quad E\left[\frac{\partial^2 g}{\partial x(t) \partial x(s)}\right] = 4E[X(t)X(s)] = 4R_X(t-s)$$

$$\begin{cases} b_1^2 = EX_1^2 = E[X^2(t)] = R_X(0) \\ b_2^2 = R_X(0) \end{cases} \quad \therefore \frac{\partial E[g]}{\partial \rho} = b_1 b_2 E\left[\frac{\partial^2 g}{\partial x(t) \partial x(s)}\right] = R_X(0) \cdot 4R_X(t-s) \xrightarrow{\rho = \frac{R_X(t-s)}{R_X(0)}} 4R_X^2(0) \cdot \rho$$

$$\therefore E[g] = \int_0^{\rho} 4R_X^2(0) \rho d\rho + \underbrace{E[g(X(t), X(s))]}_{E[X^2(t)]E[X^2(s)] = R_X^2(0)} \Big|_{\rho=0} = 2R_X^2(0)\rho^2 + R_X^2(0) = R_X^2(0) + 2R_X^2(t-s)$$

$$\text{ReLU}(x) = \begin{cases} x, & x \geq 0 \\ 0, & x < 0 \end{cases}$$

Price Thm. can be applied to $\text{ReLU}(x)$ as well. $\left(\frac{\partial \text{ReLU}(x)}{\partial x} = u(x)\right)$

Prove Price Theorem:

$$E[g(x_1, x_2)] = \int_{\mathbb{R}} \int_{\mathbb{R}} g(x_1, x_2) \cdot \frac{1}{2\pi b_1 b_2 \sqrt{1-\rho^2}} \exp\left(-\frac{1}{2(1-\rho^2)}\left(\frac{x_1^2}{b_1^2} + \frac{x_2^2}{b_2^2} - 2\rho\frac{x_1 x_2}{b_1 b_2}\right)\right) dx_1 dx_2$$

$\frac{\partial E[g(x_1, x_2)]}{\partial \rho}$ Can't be computed directly from $E[g(x_1, x_2)]$, since ρ is all mingled together.

Complexity comes from Σ^{-1} (inversion of covariance matrix)

To obviate such complexity, we should harness characteristic function $\phi_X(\omega) = E[\exp(j\omega^T X)]$

$$\phi(w_1, w_2) = \exp\left(-\frac{1}{2}(w_1, w_2) R \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}\right) = \exp\left(-\frac{1}{2}(G_1^2 w_1^2 + G_2^2 w_2^2 + 2\rho G_1 G_2 w_1 w_2)\right)$$

p's differential is doable

$$E[g(X_1, X_2)] = \int_{\mathbb{R}} \int_{\mathbb{R}} g(x_1, x_2) \cdot \left[\iint_{\mathbb{R}^2} \phi_{x_1 x_2}(w_1, w_2) \exp(-j(w_1 x_1 + w_2 x_2)) dw_1 dw_2 \right] dx_1 dx_2$$

$$\frac{\partial E[g(X_1, X_2)]}{\partial \rho} = \iint_{\mathbb{R}^2} g(x_1, x_2) \cdot \left[\iint_{\mathbb{R}^2} -G_1 G_2 w_1 w_2 \cdot \phi_{x_1 x_2}(w_1, w_2) \exp(-j(w_1 x_1 + w_2 x_2)) dw_1 dw_2 \right] dx_1 dx_2$$

$$= G_1 G_2 \cdot \iint_{\mathbb{R}^2} g(x_1, x_2) \cdot \frac{\partial^2}{\partial x_1 \partial x_2} \left[\iint_{\mathbb{R}^2} \phi_{x_1 x_2}(w_1, w_2) \exp(-j(w_1 x_1 + w_2 x_2)) dw_1 dw_2 \right] dx_1 dx_2$$

$$= G_1 G_2 \iint_{\mathbb{R}^2} g(x_1, x_2) \cdot \frac{\partial^2}{\partial x_1 \partial x_2} f_{x_1 x_2}(x_1, x_2) dx_1 dx_2$$

Assumption: $\lim_{\substack{x_1 \rightarrow \infty, \\ x_2 \rightarrow \infty}} g(x_1, x_2) f(x_1, x_2) = 0$, 边缘是0

$$\frac{\partial}{\partial x_i} g \cdot f = 0, \quad g \cdot \frac{\partial}{\partial x_i} f = 0 \quad (i=1,2)$$

$$= G_1 G_2 \iint_{\mathbb{R}^2} \left[\frac{\partial^2}{\partial x_1 \partial x_2} g(x_1, x_2) \right] \cdot f_{x_1 x_2}(x_1, x_2) dx_1 dx_2$$

2x Integration by parts, (-1)^2 = 1 (minus sign goes away)

$$= G_1 G_2 E\left[\frac{\partial^2}{\partial x_1 \partial x_2} g(X_1, X_2)\right]$$

$$\therefore \frac{\partial E[g(X_1, X_2)]}{\partial \rho} = G_1 G_2 E\left[\frac{\partial^2}{\partial x_1 \partial x_2} g(X_1, X_2)\right] \quad \text{Proved}$$

Exercise: $X(t) \xrightarrow{\text{Gaussian}} \boxed{\exp(X)} \rightarrow Y(t)$

$$R_Y(t, s) = ?$$

$$\exp(x_1 x_2) \exp(-x_1^2 - x_2^2) \rightarrow 0 \quad (\text{Satisfies Price Thm. assumption})$$

$$1) \quad g(x_1, x_2) = \exp(x_1) \exp(x_2) \quad 2) \quad \frac{\partial^2 g}{\partial x_1 \partial x_2} = \exp(x_1) \exp(x_2) \quad 3) \quad E\left[\frac{\partial^2 g}{\partial x_1 \partial x_2}\right] = \exp(x_1) \exp(x_2)$$

$$4) \quad \frac{\partial E[g]}{\partial \rho} = E[g] \quad 5) \quad E[g] = g_0 \exp(\rho)$$

Through $\Phi_X(w)$:

$$E[\exp(X_1 + X_2)] = \phi_X(w_1 = w_2 = -j) = \exp(j w^T \mu - \frac{1}{2} w^T \Sigma_X w) = \exp(\mu_1 + \mu_2 + \frac{1}{2}(\Sigma_{11} + \Sigma_{12} + \Sigma_{21} + \Sigma_{22}))$$

Nonlinear with Gaussian

Polynomial: Partial Derivative on Charac. Func.

Triangular: Decompose into Complex Exponential (Charac. Func.)

ReLU: Price Thm.

Mostly Every \Rightarrow Price Thm.

Func. (satisfies its assumption)