

Homework 4 Yu Gao

1. (a) Denote A as: $\begin{bmatrix} A_{11} & A_{12} & \cdots & A_{1m} \\ A_{21} & A_{22} & \cdots & A_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ A_{p1} & A_{p2} & \cdots & A_{pm} \end{bmatrix}$ X as: $\begin{bmatrix} x_{11} & x_{12} & \cdots & x_{1n} \\ x_{21} & x_{22} & \cdots & x_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ x_{m1} & x_{m2} & \cdots & x_{mn} \end{bmatrix}$ B as: $\begin{bmatrix} B_{11} & B_{12} & \cdots & B_{1n} \\ B_{21} & B_{22} & \cdots & B_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ B_{q1} & B_{q2} & \cdots & B_{qn} \end{bmatrix}$

Therefore $AX = \begin{bmatrix} A_{1,:} X_{:,1} & A_{1,:} X_{:,2} & \cdots & A_{1,:} X_{:,n} \\ A_{2,:} X_{:,1} & A_{2,:} X_{:,2} & \cdots & A_{2,:} X_{:,n} \\ \vdots & \vdots & \ddots & \vdots \\ A_{p,:} X_{:,1} & A_{p,:} X_{:,2} & \cdots & A_{p,:} X_{:,n} \end{bmatrix} = \begin{bmatrix} (Ax)_{1,:} \\ (Ax)_{2,:} \\ \vdots \\ (Ax)_{p,:} \end{bmatrix}$ $B^T = \begin{bmatrix} B_{11} & B_{12} & \cdots & B_{1n} \\ B_{21} & B_{22} & \cdots & B_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ B_{qn} & B_{qn} & \cdots & B_{qn} \end{bmatrix}$

$$AXB^T = \begin{bmatrix} (Ax)_{1,:} B_{1,:} & (Ax)_{1,:} B_{2,:} & \cdots & (Ax)_{1,:} B_{n,:} \\ (Ax)_{2,:} B_{1,:} & (Ax)_{2,:} B_{2,:} & \cdots & (Ax)_{2,:} B_{n,:} \\ \vdots & \vdots & \ddots & \vdots \\ (Ax)_{p,:} B_{1,:} & (Ax)_{p,:} B_{2,:} & \cdots & (Ax)_{p,:} B_{n,:} \end{bmatrix} = \begin{bmatrix} (Ax)_{1,:} B_{1,:} \\ (Ax)_{2,:} B_{1,:} \\ \vdots \\ (Ax)_{p,:} B_{1,:} \end{bmatrix}$$

a $qp \times 1$ matrix

Therefore $\text{vec}(AXB^T) = \begin{bmatrix} (Ax)_{1,:} B_{1,:} \\ (Ax)_{2,:} B_{1,:} \\ \vdots \\ (Ax)_{p,:} B_{1,:} \end{bmatrix}$

$$\begin{bmatrix} B_{11}A_{11} & B_{11}A_{12} & \cdots & B_{11}A_{1m} & \cdots & B_{1n}A_{11} & \cdots & B_{1n}A_{1m} \\ B_{11}A_{21} & B_{11}A_{22} & \cdots & B_{11}A_{2m} & \cdots & B_{1n}A_{21} & \cdots & B_{1n}A_{2m} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots & \ddots & \vdots \\ B_{q1}A_{11} & B_{q1}A_{12} & \cdots & B_{q1}A_{1m} & \cdots & B_{qn}A_{11} & \cdots & B_{qn}A_{1m} \\ B_{q1}A_{21} & B_{q1}A_{22} & \cdots & B_{q1}A_{2m} & \cdots & B_{qn}A_{21} & \cdots & B_{qn}A_{2m} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots & \ddots & \vdots \\ B_{q1}A_{p1} & B_{q1}A_{p2} & \cdots & B_{q1}A_{pm} & \cdots & B_{qn}A_{p1} & \cdots & B_{qn}A_{pm} \end{bmatrix}$$

Also $B \otimes A = \begin{bmatrix} B_{1,:} A \\ B_{2,:} A \\ \vdots \\ B_{q,:} A \end{bmatrix} = \begin{bmatrix} B_{11}A & \cdots & B_{1n}A \\ B_{21}A & \cdots & B_{2n}A \\ \vdots & \ddots & \vdots \\ B_{q1}A & \cdots & B_{qn}A \end{bmatrix} = \begin{bmatrix} B_{11}A_{11} & B_{11}A_{12} & \cdots & B_{11}A_{1m} & \cdots & B_{1n}A_{11} & \cdots & B_{1n}A_{1m} \\ B_{11}A_{21} & B_{11}A_{22} & \cdots & B_{11}A_{2m} & \cdots & B_{1n}A_{21} & \cdots & B_{1n}A_{2m} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots & \ddots & \vdots \\ B_{q1}A_{11} & B_{q1}A_{12} & \cdots & B_{q1}A_{1m} & \cdots & B_{qn}A_{11} & \cdots & B_{qn}A_{1m} \\ B_{q1}A_{21} & B_{q1}A_{22} & \cdots & B_{q1}A_{2m} & \cdots & B_{qn}A_{21} & \cdots & B_{qn}A_{2m} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots & \ddots & \vdots \\ B_{q1}A_{p1} & B_{q1}A_{p2} & \cdots & B_{q1}A_{pm} & \cdots & B_{qn}A_{p1} & \cdots & B_{qn}A_{pm} \end{bmatrix}$

$\text{vec}(X) = \begin{bmatrix} x_{:,1} \\ x_{:,2} \\ \vdots \\ x_{:,n} \end{bmatrix}$ (a $mn \times 1$ matrix) = $\begin{bmatrix} x_{11} \\ x_{21} \\ \vdots \\ x_{m1} \end{bmatrix}$

$B \otimes A \cdot \text{vec}(X) = \begin{bmatrix} B_{11}A_{11}x_{11} + B_{11}A_{12}x_{21} + \cdots + B_{11}A_{1m}x_{m1} \\ B_{11}A_{21}x_{11} + B_{11}A_{22}x_{21} + \cdots + B_{11}A_{2m}x_{m1} \\ \vdots \\ B_{q1}A_{p1}x_{11} + B_{q1}A_{p2}x_{21} + \cdots + B_{q1}A_{pm}x_{m1} \end{bmatrix}$

a $qp \times 1$ matrix

Then look back at the representation of $\text{vec}(AxB^T)$

$$(Ax)_{1,:} B_{1,:} = A_{1,:} x_{:,1} B_{1,1} + A_{1,:} x_{:,2} B_{1,2} + \cdots + A_{1,:} x_{:,n} B_{1,n}$$

$$= A_{11} x_{11} B_{11} + A_{12} x_{21} B_{11} + \cdots + A_{11} x_{12} B_{12} + A_{12} B_{22} B_{12} + \cdots + A_{1m} x_{mn} B_{1n}$$

which equals to the first row of $B \otimes A \cdot \text{vec}(x)$

Similarly $(Ax)_{p,:} B_{q,:}$ is the pq^{th} row of $B \otimes A \cdot \text{vec}(x)$

That is to say: $\text{Vec}(Ax B^T) = B \otimes A \cdot \text{Vec}(x)$

2. (a) To find the eigenvalues of B : $\det(B - I\lambda) = \det(A + xx' - I\lambda) = 0$

$\lambda \neq A_{ii}$ for any i , then $A - \lambda I$ is invertible

$$\det(A + xx' - \lambda I) = \det((A - \lambda I)(I + \underbrace{(A - \lambda I)^{-1}xx'}_{w'x}))$$

Based on the property that $\det(I + w'x) = 1 + w'x$, the representation can be simplified to:

$$\det(A - \lambda I) \cdot (1 + x'(A - \lambda I)^{-1}x)$$

Therefore $x'(A - \lambda I)^{-1}x = -1$ must be satisfied.

The eigenvalues of B must satisfy: $x'(\lambda I - A)^{-1}x = 1$

Assume that the eigenvalues of A are: $\alpha_{11}, \alpha_{22}, \alpha_{33}, \dots, \alpha_{nn}$

$$\frac{x_1^2}{\lambda - \alpha_{11}} + \frac{x_2^2}{\lambda - \alpha_{22}} + \dots + \frac{x_n^2}{\lambda - \alpha_{nn}} = 1$$

(b) The eigenvalues of A are: $\alpha_{11} = 1, \alpha_{22} = 2, \alpha_{33} = 3$

To satisfy $x'(\lambda I - A)^{-1}x = 1$

$$\begin{bmatrix} 1 & -1 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{\lambda-1} & 0 & 0 \\ 0 & \frac{1}{\lambda-2} & 0 \\ 0 & 0 & \frac{1}{\lambda-3} \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} = 1$$

$$\lambda^3 - 9\lambda^2 + 23\lambda - 17 = 0$$

Solving it by Julia: $\lambda_1 = 5.21, \lambda_2 = 2.46, \lambda_3 = 1.3$

3. (a) Denote $A = [q_1 \ q_2]$ $x = \begin{bmatrix} \alpha \\ \beta \end{bmatrix}$

The goal is to find $\min \|Ax - b\|_2$

According to LLS solution, $\hat{x} = A^+ b$

The SVD of A can be written as $A = \sum_{i=1}^2 1 \cdot q_i \cdot e_i^T$

Therefore $A^+ = \sum_{i=1}^2 1 \cdot e_i \cdot q_i^T$

$$\hat{x} = \sum_{i=1}^2 1 \cdot e_i \cdot q_i^T \cdot b = A^T \cdot b$$

$$(b) r = b - A\hat{x} = b - A \cdot A^+ \cdot b = b \cdot (I - A \cdot A^+)$$

$$\begin{aligned} A'r &= A'(I - A \cdot A^+)b \\ &= [A' - A'A A^+]b \end{aligned}$$

$$\text{Since } A' = A' A A^+$$

$$A'(b - A\hat{x}) = 0 \cdot b = 0 \Rightarrow \begin{cases} q_1' \cdot r = 0 \\ q_2' \cdot r = 0 \end{cases} \quad r \text{ is orthogonal to both } q_1 \text{ and } q_2$$

$$4. A = U_r \Sigma_r V_r' \Rightarrow A^+ = V_r \Sigma_r^{-1} U_r' \text{ (compact SVD)}$$

$$(A^+ b)' (I - A^+ A)x = b' U_r \Sigma_r^{-1} V_r' (I - V_r V_r')x = 0$$

Therefore $(I - A^+ A)x$ and $A^+ b$ are orthogonal vectors.

5. (a) Based on the definition of convex function, if $f(x) = \|Ax - b\|_2$ is a convex function:

$$\|A(\alpha x_1 + (1-\alpha)x_2) - b\|_2 \leq \alpha \|Ax_1 - b\|_2 + (1-\alpha) \|Ax_2 - b\|_2$$

To prove the inequality equation:

$$\text{As for left side: } \|A(\alpha x_1 + (1-\alpha)x_2) - b\|_2 = \|(A(\alpha x_1 + (1-\alpha)x_2) - b)(\alpha + 1 - \alpha)\|_2$$

$$= \|(A\alpha x_1 - ab) + [A(1-\alpha)x_2 - b(1-\alpha)]\|_2$$

Given the property that $\|x+y\|_2 \leq \|x\|_2 + \|y\|_2$, the inequality:

$$\begin{aligned} \|(A\alpha x_1 - ab) + [A(1-\alpha)x_2 - b(1-\alpha)]\|_2 &\leq \|\alpha(Ax_1 - b)\|_2 + \|(1-\alpha)(Ax_2 - b)\|_2 \\ &\leq \alpha \|Ax_1 - b\|_2 + (1-\alpha) \|Ax_2 - b\|_2 \end{aligned}$$

(b) Set two matrix M, N

We have to prove that:

$$\sigma_1(\alpha M + (1-\alpha)N) \leq \alpha \sigma_1(M) + (1-\alpha) \sigma_1(N)$$

Based on the hint: $\sigma_1(\alpha M + (1-\alpha)N) = \max_{\|u\|_2=1} \|(\alpha M + (1-\alpha)N) \cdot u \|_2$

$$\leq \max_{\|u\|_2=1} \left(\|\alpha Mu\|_2 + \|(1-\alpha)Nu\|_2 \right) = \max_{\|u\|_2=1} (\alpha \|Mu\|_2 + (1-\alpha) \|Nu\|_2)$$
$$= \max_{\|u\|_2=1} \alpha \|Mu\|_2 + \max_{\|u\|_2=1} (1-\alpha) \|Nu\|_2 = \alpha \sigma_1(M) + (1-\alpha) \sigma_1(N)$$

Therefore, $\sigma_1(\cdot)$ is a convex function.

b. (a) $x = \begin{bmatrix} 5 \\ 15 \\ 25 \\ 35 \\ 45 \\ 55 \\ 65 \\ 75 \end{bmatrix}$ math: $y = [457 \quad 465 \quad 474 \quad 488 \quad 501 \quad 509 \quad 515 \quad 521 \quad 534 \quad 564]$

$$\min \|y - \beta_0\|_2$$
$$\min \|y - \beta_1 x\|_2$$
$$\min \|y - \beta_1 x - \beta_0\|_2$$
$$\min \|y - \beta_2 x^2 - \beta_1 x - \beta_0\|_2$$

```
In [2]: A0=zeros(length(income), 3)
A0[:, 2]=zeros(length(income))
A0[:, 3]=zeros(length(income))

A1=zeros(length(income), 3)
A1[:, 2]=income

A2=zeros(length(income), 3)
A2[:, 2]=income
A2[:, 3]=zeros(length(income))

A3=zeros(length(income), 3)
A3[:, 2]=income
A3[:, 3]=income.^2

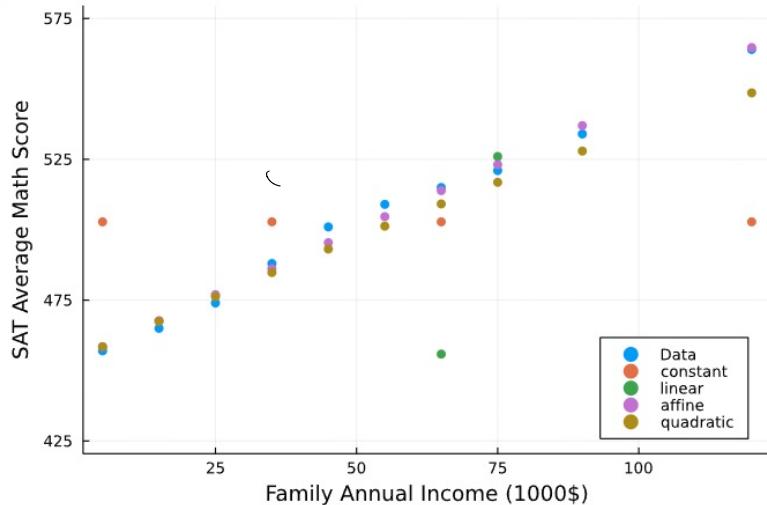
X0=A0\math
X1=A1\math
X2=A2\math
X3=A3\math

@show X0, X1, X2, X3
```

(X0, X1, X2, X3) = ([502.7999999999995, 0.0, 0.0], [0.0, 7.013164556962025, 0.0], [453.8597721297108, 0.9234005258545132, 0.0], [0.011169658642309185], [451.11444428602186, 1.0584447335413263, -0.0011169658642309185])

Out[2]: ([502.7999999999995, 0.0, 0.0], [0.0, 7.013164556962025, 0.0], [453.8597721297108, 0.9234005258545132, 0.0], [451.11444428602186, 1.0584447335413263, -0.0011169658642309185])

Out[3]:



(b)

Constant Fit	Linear Fit	Affine Fit	Quadratic Fit
502.7999999999995	0	453.8597721297108	451.11444428602186
0	7.013164556962025	0.9234005258545132	1.0584447335413263
0	0	0	-0.0011169658642309

7. (a)

```
In [6]: using LinearAlgebra
T = LinRange(0, 2.16)
f = 0.5 * exp.(0.8*T)

A15 = [TT^j for TT in T, j=0:length(T)-1]
A2 = A15[:, 1:3]
X15 = pinv(A15)*f
X2 = pinv(A2)*f

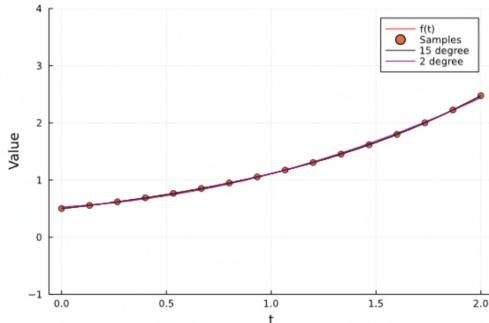
t = LinRange(0, 2, 501)
y= 0.5*exp.(0.8*t)

using Plots
plot(t, y, color=:red, label = "f(t)", ylim=(-1, 4))
scatter!(T,f,marker=:circle, label="Samples")

a15 = [tt^j for tt in t, j=0:length(T)-1]
a2 = a15[:, 1:3]

plot!(t, (a15*X15),color=:black,label="15 degree")
plot!(t, (a2*X2),color=:purple,label="2 degree", xaxis="t", yaxis="Value")
```

Out[6]:

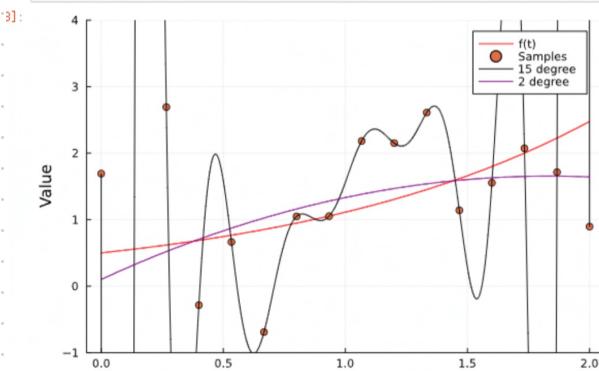


$$y \triangleq \begin{bmatrix} f(t_1) \\ \vdots \\ f(t_{15}) \end{bmatrix} \quad A \triangleq \begin{bmatrix} 1 & t_1 & t_1^2 & \cdots & t_1^d \\ \vdots & \vdots & \ddots & \vdots \\ 1 & t_{15} & t_{15}^2 & \cdots & t_{15}^d \end{bmatrix} \in \mathbb{R}^{16 \times (d+1)} \quad x \triangleq \begin{bmatrix} x_1 \\ \vdots \\ x_{d+1} \end{bmatrix} \in \mathbb{R}^{d+1}$$

As the above diagram shows, the least-square coefficients obtained when $d=2$ and $d=15$ are almost the same.

(b)

```
3]: using LinearAlgebra
using Random; seed!
seed! (3); e=randn(length(T))
T = LinRange(0, 2, 16)
f = 0.5 * exp.(0.8*T) + e
A15 = [TT^j for TT in T, j=0:length(T)-1]
A2 = A15[:, 1:3]
X15 = pinv(A15)*f
X2 = pinv(A2)*f
t = LinRange(0, 2, 501)
y = 0.5*exp.(0.8*t)
using Plots
plot(t, y, color=:red, label = "f(t)", ylim=(-1, 4))
scatter!(T, f, marker=:circle, label="Samples")
a15 = [tt^j for tt in t, j=0:length(T)-1]
a2 = a15[:, 1:3]
plot!(t, (a15*X15), color=:black, label="15 degree")
plot!(t, (a2*X2), color=:purple, label="2 degree", xaxis="t", yaxis="Value")
```



When noise is added, polynomial for $d=15$ passes each sample point precisely. The error is zero, but large relative to the function.

(c)

polynomial degree:	$d=2$	$d=15$
Residual norm $\ A\hat{x}(b) - b\ _2$ noiseless (a)	0.3502105199189893	0.0001622183167221819
Residual norm $\ A\hat{x}(y) - y\ _2$ noisy (b)	6.191069208724523	1047.713599472052
Fitting error $\ A\hat{x}(y) - b\ _2$	4.641460505926311	4.641460505926311

(d) because $A_{15} = [A_2 \ A_{3:15}]$ so $R(A_2) \subseteq R(A_{15})$