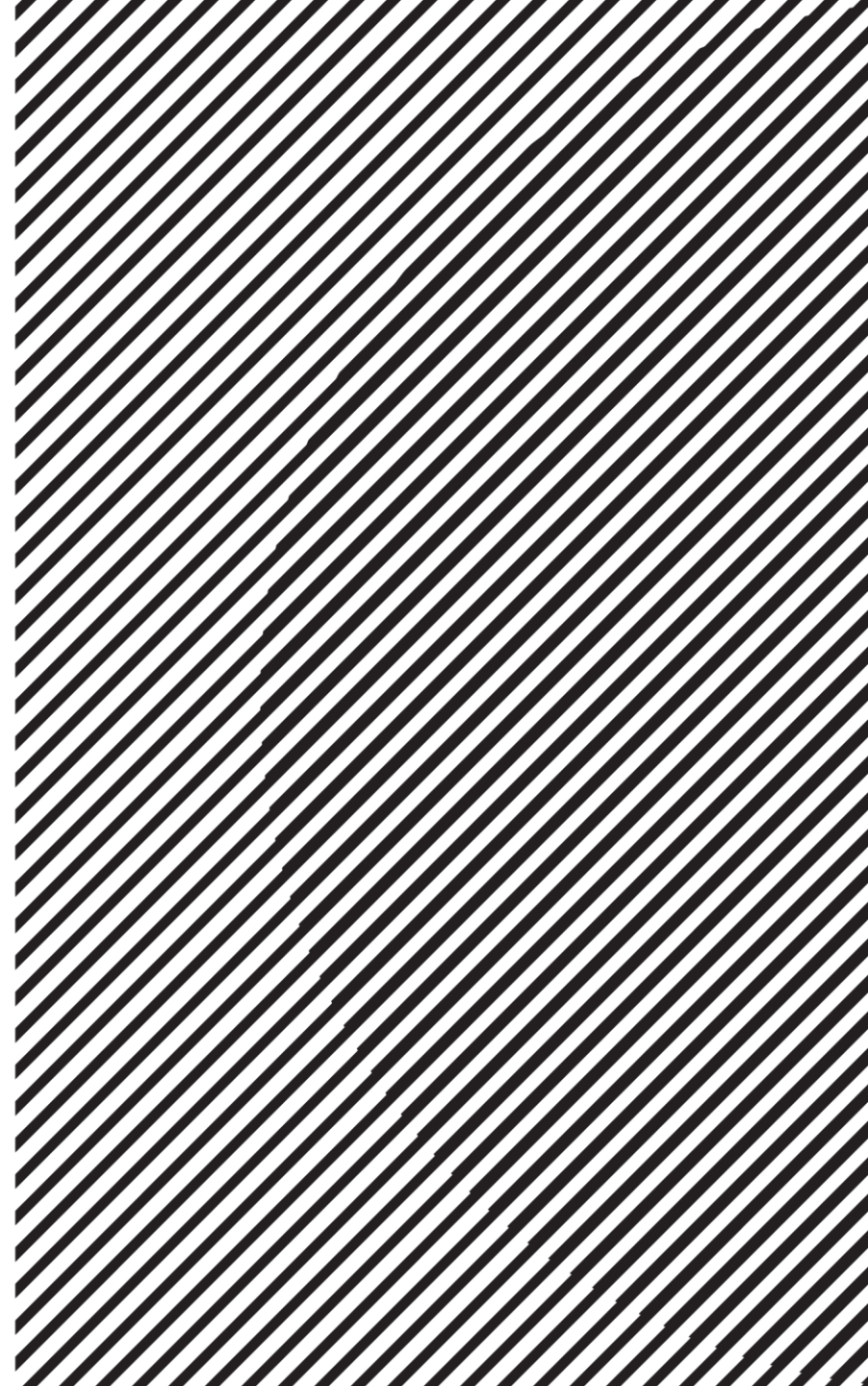


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# Linear Algebra

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# Diagonalization (대각화)

$$\begin{pmatrix} \star & 0 & 0 \\ 0 & \triangle & 0 \\ 0 & 0 & \square \end{pmatrix}$$

- We want to change a given square matrix  $A \in \mathbb{R}^{n \times n}$  into a diagonal matrix via the following form:

$$D = V^{-1}AV$$

where  $V \in \mathbb{R}^{n \times n}$  is an invertible matrix and  $D \in \mathbb{R}^{n \times n}$  is a diagonal matrix. This is called a diagonalization of  $A$ .

- It is not always possible to diagonalize  $A$ . For  $A$  to be diagonalizable, an invertible  $V$  should exist such that  $V^{-1}AV$  becomes a diagonal matrix.

# Finding $V$ and $D$

- How can we find an invertible  $P$  and the resulting diagonal matrix  $D = V^{-1}AV$ ?
- $D = V^{-1}AV \Rightarrow VD = AV$   $\rightarrow V^T$ 이 존재해야만 가능함.
- Let us represent the following:
- $V = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \cdots \quad \mathbf{v}_n]$  where  $\mathbf{v}_i$ 's are column vectors of  $V$
- $D = \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \lambda_n \end{bmatrix}$



## Finding $V$ and $D$

- $AV = A[\mathbf{v}_1 \quad \mathbf{v}_2 \quad \cdots \quad \mathbf{v}_n] = [A\mathbf{v}_1 \quad A\mathbf{v}_2 \quad \cdots \quad A\mathbf{v}_n]$

- $VD = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \cdots \quad \mathbf{v}_n] \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \lambda_n \end{bmatrix}$   
 $= [\lambda_1 \mathbf{v}_1 \quad \lambda_2 \mathbf{v}_2 \quad \cdots \quad \lambda_n \mathbf{v}_n]$

- $AV = VD \Leftrightarrow [A\mathbf{v}_1 \quad A\mathbf{v}_2 \quad \cdots \quad A\mathbf{v}_n] = [\lambda_1 \mathbf{v}_1 \quad \lambda_2 \mathbf{v}_2 \quad \cdots \quad \lambda_n \mathbf{v}_n]$



# Finding $V$ and $D$

- Equating columns, we obtain

$$A\mathbf{v}_1 = \lambda_1\mathbf{v}_1, A\mathbf{v}_2 = \lambda_2\mathbf{v}_2, \dots, A\mathbf{v}_n = \lambda_n\mathbf{v}_n$$

- Thus,  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$  should be **eigenvectors** and  $\lambda_1, \lambda_2, \dots, \lambda_n$  should be **eigenvalues**.
- Then, For  $VD = AV \Rightarrow D = V^{-1}AV$  to be true,  $V$  should be **invertible**.
- In this case, the resulting diagonal matrix  $D$  has eigenvalues as diagonal entries.

# Diagonalizable Matrix

$$D = V^{-1}AV$$

- For  $V$  to be invertible,  
 $V$  should be a **square** matrix in  $\mathbb{R}^{n \times n}$  and  
 $V$  should have  $n$  **linearly independent columns**.
- Recall columns of  $V$  are eigenvectors.  
Hence,  $A$  should have  $n$  linearly independent eigenvectors.
- It is not always the case, but if it is,  $A$  is diagonalizable.

다 선형  
독립여야  
함.



대각화 가능함.

# Eigendecomposition

고유값 분해

- If  $A$  is diagonalizable, we can write  $D = V^{-1}AV$ .
- We can also write  $A = VDV^{-1}$ .  
which we call eigendecomposition of  $A$ .
- $A$  being diagonalizable is equivalent to  $A$  having eigendecomposition.



# Linear Transformation via Eigendecomposition

- Suppose  $A$  is diagonalizable, thus having eigendecomposition

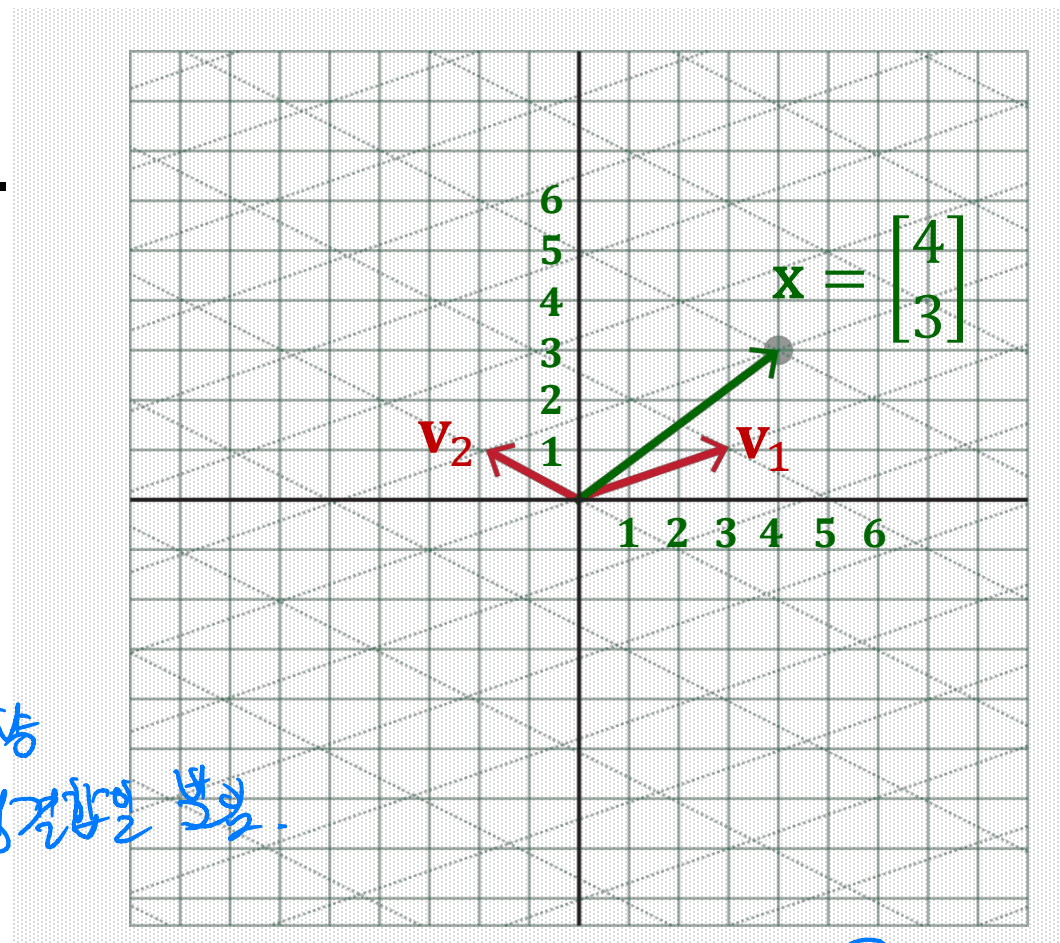
$$A = VDV^{-1}$$

- Consider the linear transformation  $T(\mathbf{x}) = A\mathbf{x}$ .
- $T(\mathbf{x}) = A\mathbf{x} = VDV^{-1}\mathbf{x} = V(D(V^{-1}\mathbf{x}))$ .



# Change of Basis

- Suppose  $A\mathbf{v}_1 = -1\mathbf{v}_1$  and  $A\mathbf{v}_2 = 2\mathbf{v}_2$ .
- $T(\mathbf{x}) = A\mathbf{x} = VDV^{-1}\mathbf{x} = V(D(V^{-1}\mathbf{x}))$
- Let  $\mathbf{y} = V^{-1}\mathbf{x}$ . Then,  
 $V\mathbf{y} = \mathbf{x}$
- $\mathbf{y}$  is a new coordinate of  $\mathbf{x}$  with respect to a new basis of eigenvectors  $\{\mathbf{v}_1, \mathbf{v}_2\}$ .



$$\mathbf{x} = \begin{bmatrix} 4 \\ 3 \end{bmatrix} = 4 \overset{v_1}{\begin{bmatrix} 1 \\ 0 \end{bmatrix}} + 3 \overset{v_2}{\begin{bmatrix} 0 \\ 1 \end{bmatrix}} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 4 \\ 3 \end{bmatrix} = P\mathbf{y} = [\mathbf{v}_1 \quad \mathbf{v}_2] \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = 2\mathbf{v}_1 + 1\mathbf{v}_2 \Rightarrow \mathbf{y} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

# Element-wise Scaling

D가 대각행렬 이므로

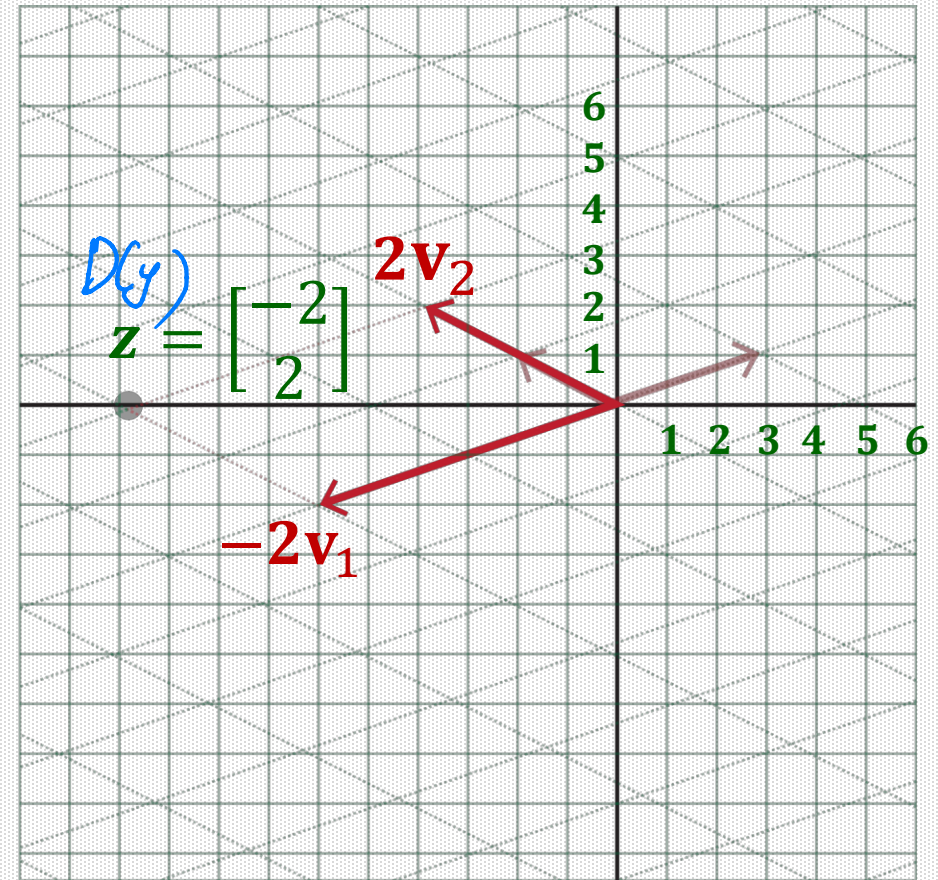
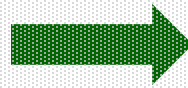
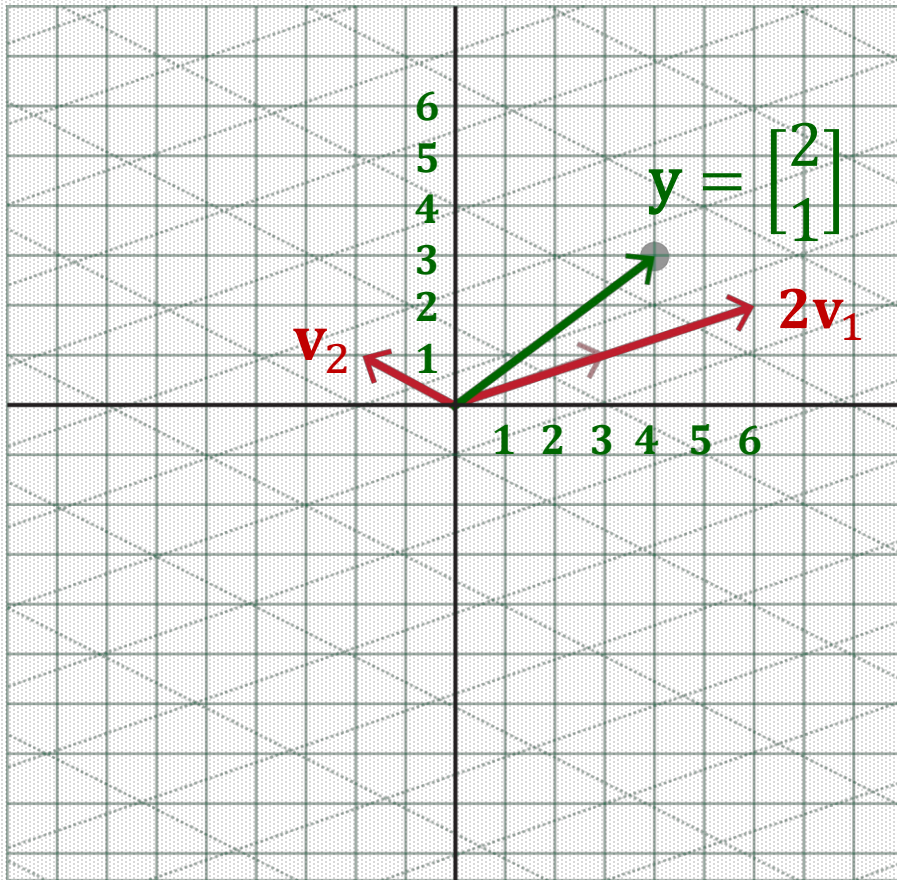
각 원소에 대한 scaling인 것이다.  
상식적임.

- $T(\mathbf{x}) = V(D(V^{-1}\mathbf{x})) = V(D\mathbf{y})$
- Let  $\mathbf{z} = D\mathbf{y}$ . This computation is a simple **Element-wise scaling** of  $\mathbf{y}$ .

- **Example:** Suppose  $D = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}$ . Then

$$\mathbf{z} = D\mathbf{y} = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} (-1) \times 2 \\ 2 \times 1 \end{bmatrix} = \begin{bmatrix} -2 \\ 2 \end{bmatrix}$$

# Dimension-wise Scaling



# Back to Original Basis

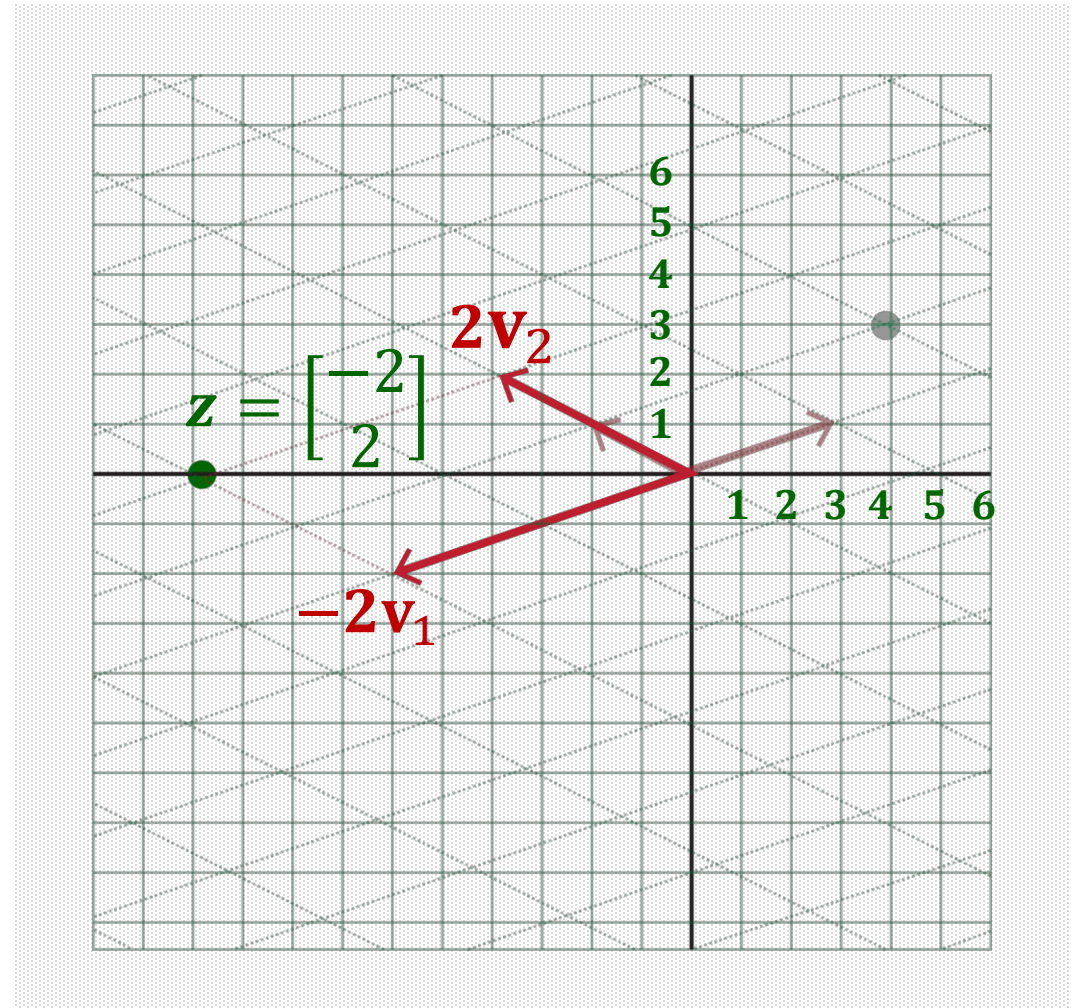
- $T(\mathbf{x}) = V(D\mathbf{y}) = V\mathbf{z}$
- $\mathbf{z}$  is still a coordinate based on the new basis  $\{\mathbf{v}_1, \mathbf{v}_2\}$ .
- $V\mathbf{z}$  converts  $\mathbf{z}$  to another coordinates based on the original standard basis.
- That is,  $V\mathbf{z}$  is a linear combination of  $\mathbf{v}_1$  and  $\mathbf{v}_2$  using the coefficient vector  $\mathbf{z}$ .
- That is,

$$V\mathbf{z} = [\mathbf{v}_1 \quad \mathbf{v}_2] \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \mathbf{v}_1 z_1 + \mathbf{v}_2 z_2$$

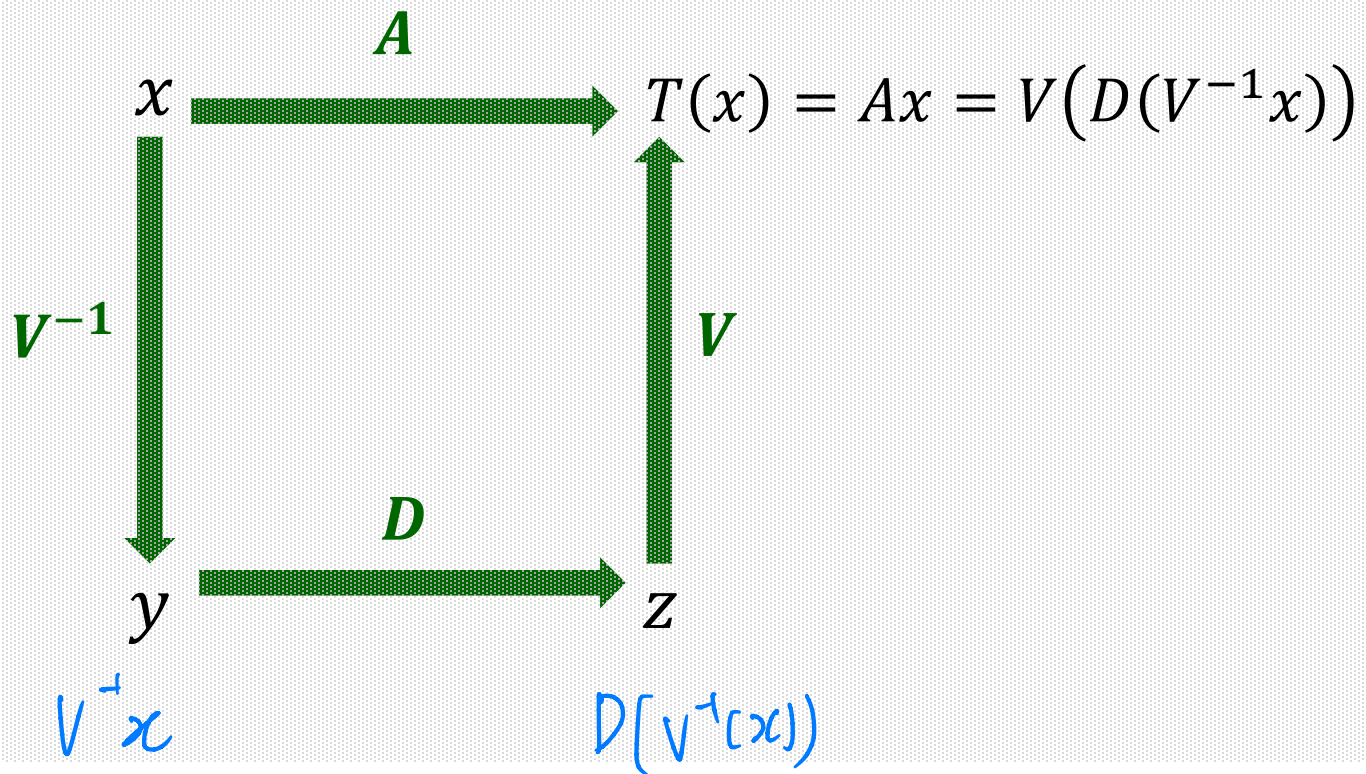
$D(V^T \mathbf{x})$  column vector 00

# Back to Original Basis

- $T(\mathbf{x}) = V\mathbf{z} = [\mathbf{v}_1 \quad \mathbf{v}_2] \begin{bmatrix} -2 \\ 2 \end{bmatrix}$   
 $= -2\mathbf{v}_1 + 2\mathbf{v}_2$   
 $= -2 \begin{bmatrix} 3 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} -2 \\ 1 \end{bmatrix}$   
 $= \begin{bmatrix} -10 \\ 0 \end{bmatrix}$



# Overview of Transformation using Eigendecomposition



# Linear Transformation via $A^k$

- Now, consider recursive transformation  $A \times A \times \cdots \times A \mathbf{x} = A^k \mathbf{x}$ .
- If  $A$  is diagonalizable,  $A$  has eigendecomposition

$$A = VDV^{-1}$$

- $A^k = (VDV^{-1})(VDV^{-1}) \cdots (VDV^{-1}) = \underline{\underline{VD^kV^{-1}}}$

- $D^k$  is simply computed as

↳ 계산을 간편하게!

$$D^k = \begin{bmatrix} \lambda_1^k & 0 & \cdots & 0 \\ 0 & \lambda_2^k & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \lambda_n^k \end{bmatrix}$$



# Linear Transformation via $A^k$

- $A^k \mathbf{x} = VD^kV^{-1}\mathbf{x}$  can be computed in the similar manner to the previous example.
- It is much faster to compute  $V \left( D^k (V^{-1}\mathbf{x}) \right)$  than to compute  $A^k \mathbf{x}$ .





# Further Study

- Determining whether a matrix  $A \in \mathbb{R}^{n \times n}$  diagonalizable.
  - Geometric multiplicity should be equal to algebraic multiplicity.
  - As a special case,  $A$  has  $n$  distinct eigenvalues,  $A$  is diagonalizable.
  - Lay Ch5.3
- Solving  $(A - \lambda I)\mathbf{x} = \mathbf{0}$  for a given eigenvalue  $\lambda$ 
  - Lay Ch1.5