

Step-1

Permutation matrix: Matrix P has single 1 in every row and every column. It has the rows of identity matrix I in any order.

Step-2

Let matrix P is a rotation matrix which multiplies to a vector (x, y, z) to give (z, y, x) . Determine P and P^3 .

Matrix P if multiplied to the vector (x, y, z) puts last column first by shifting other columns. This gives the permutation matrix P defined as follows. Therefore,

$$P = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

Step-3

Now do the following calculations:

$$P \cdot P = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$P^2 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

$$P^2 \cdot P = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$P^3 = I$$

Therefore, $P^3 = I$.

Step-4

Next consider the rotation axis $a = (1, 1, 1)$ that doesn't move but equals to Pa . determine the angle of rotation from $v = (2, 3, -5)$ to $Pv = (-5, 2, 3)$.

Matrix P if multiplied to the vector $v = (2, 3, -5)$ puts last column first by shifting other columns. This gives the permutation matrix P as defined above.

Also, above calculation, $\mathbf{P}^3 = \mathbf{I}$, shows that after taking three rotations matrix equals to identity matrix. This implies that three rotations equals to 360° , so one rotation will make an angle of $360^\circ/3 = 120^\circ$.

Therefore, angle of rotation from \mathbf{v} to $\mathbf{P} \cdot \mathbf{v}$ around $\mathbf{a} = (1, 1, 1)$ is $\boxed{120^\circ}$.