

Lecture 23

V - vector space, $S \subset V$.

Then, any element of V is a linear combination of finitely many elements of S .

We can write a general element of S as $\sum_{w \in S} a_w \cdot w$ where it is to be understood that only finitely many of the a_w are non-zero.

When does the span grow?

Let V be a vector space and let $S \subset V$.

Let $v \in V$. We know that

$$\text{Span}(S) \subseteq \text{Span}(S \cup \{v\})$$

When is $\text{Span}(S \cup \{v\})$ strictly bigger than $\text{Span}(S)$?

Clearly, $v \in \text{Span}(S \cup \{v\})$. So, if $v \notin \text{Span}(S)$, then $\text{Span}(S \cup \{v\}) \neq \text{Span}(S)$.

Conversely, suppose $\text{Span}(S \cup \{v\})$ is strictly bigger than $\text{Span}(S)$.

Then we claim that $v \notin \text{Span}(S)$.

Indeed, suppose $v \in \text{Span}(S)$.

So, $v = \sum_{w \in S} a_w \cdot w$, $a_w \in \mathbb{R} \ \forall w$.

Any element $x \in \text{Span}(S \cup \{v\})$ is of the form $x = b_v \cdot v + \sum_{w \in S} b_w \cdot w$.

So $x = \sum_{w \in S} (b_v a_w + b_w) \cdot w$.

Thus $x \in \text{Span}(S)$.

Thus $\text{Span}(S \cup \{v\}) \subset \text{Span}(S)$
— contra.

So $v \notin \text{Span } S$.

So, we have proved:

Theorem $\text{Span}(S \cup \{v\}) \neq \text{Span}(S)$

$\iff v \notin \text{Span}(S)$

Linear independence

Let $S \subset V$.

Suppose $v \in S$ is such that
 $v \in \text{Span}(S \setminus \{v\})$.

Then $\text{Span}(S \setminus \{v\}) = \text{Span}(S)$.

Thus, v can be removed from S
without altering the span.

On the other hand, if $v \notin \text{Span}(S \setminus \{v\})$,
then removing v shrinks the span.

Defn: A set $S \subset V$ is said to be
linearly independent if for any
 $v \in S$, we have $v \notin \text{Span}(S \setminus \{v\})$.

This means that no element can
be written as a linear combination
of other elements.

No element can be thrown out
without altering the span.

Characterization of linear independence

Let V be a vector space.

Let $S \subset V$. Then, the following three conditions are equivalent.

- (1) S is linearly independent.
- (2) Any element of $\text{Span}(S)$ can be uniquely written in the form

$$\sum_{v \in S} a_v \cdot v$$

(3) If $\sum_{v \in S} a_v \cdot v = \bar{0}$, then we
must have $a_v = 0 \forall v$.
(In other words, there is no
collection of real numbers
 $\{a_v\}_{v \in S}$ such that at least
one of them is non-zero and
 $\sum a_v \cdot v = 0$.)

Proof of (1) \Rightarrow (3):

We assume S is linearly independent.

Suppose $\sum_{v \in S} a_v \cdot v = 0$ for some

choice of real numbers a_v .

We want to prove that $a_v = 0$ for all v .

Suppose, for some $v_0 \in S$, $a_{v_0} \neq 0$.

Then $a_{v_0} \cdot v_0 + \sum_{v \neq v_0} a_v \cdot v = 0$.

$$\text{So, } v_0 = \sum_{v \neq v_0} \left(\frac{-a_v}{a_{v_0}} \right) \cdot v.$$

Thus $v_0 \in \text{Span}(S \setminus \{v_0\})$ — contra.

Thus $a_v = 0 \quad \forall v \in S$.

Thus (3) is true.

This proves (1) \Rightarrow (3).

Proof of (3) \Rightarrow (1):

We assume (3) is true.

Suppose S is not linearly independent.

Thus, for some $v \in S$, we have

$v \in \text{Span}(S \setminus \{v\})$.

So $v = \sum_{\omega \neq v} a_\omega \cdot \omega$.

So, $-v + \sum_{\omega \neq v} a_\omega \cdot \omega = \overline{0}$.

In this expression, the coefficient of v is -1 , which is non-zero.

This contradicts our assumption that (3) is true.

Thus S must be linearly independent.

Thus (3) \Rightarrow (1).

Proof of (3) \Rightarrow (2):

Assume (3) is true.

If (2) is not true, some $v \in \text{Span}(S)$ has two distinct expressions

$$v = \sum_{w \in S} a_w \cdot w \quad \text{and} \quad v = \sum_{w \in S} b_w \cdot w.$$

$$\text{So } \overline{v} = \sum_{w \in S} (a_w - b_w) \cdot w.$$

As the two expressions are distinct, \exists some $w_0 \in S$ such that

$$a_{w_0} \neq b_{w_0}.$$

So $a_{w_0} - b_{w_0} \neq 0.$

As $\sum_{w \in S} (a_w - b_w) \cdot w = 0$, this shows

that (3) does not hold. — contra.

Thus (2) must be true.

Thus (3) \Rightarrow (2).

Proof of (2) \Rightarrow (3).

Assume (2). Suppose (3) is not true.

So there exists an equality
 $\sum_{w \in S} a_w \cdot w = \bar{0}$ where not all
 a_w are equal to 0.

But, we also have $\sum_{w \in S} 0 \cdot w = \bar{0}$.

This violates (2) (for $v = \bar{0}$) — contra.

So, we have proved

$$(1) \iff (3) \iff (2).$$

Thus the conditions are equivalent.

An expression of the form $\sum_{v \in S} a_v \cdot v$
is called a linear relation between
the elements of S .

If all $a_s = 0$, then we say
that it is the trivial relation.

If not, we call it a non-trivial
linear relation between the elements
of S.

Thus a set is linearly independent
if and only if there is no non-trivial
linear relation between its elements.

If a set is not linearly independent, we say that it is linearly dependent.

Examples :

(1) In \mathbb{R}^n , $\{e_1, \dots, e_n\}$ is a linearly independent set.

(2) $\{\vec{0}\}$ is linearly dependent.

(3) \emptyset is linearly independent.

Finite dimensional spaces

Recall that a space is finite dimensional if it has a finite spanning set.

Suppose V is a finite dimensional vector space and $S = \{v_1, \dots, v_n\}$ is a spanning set.

If S is not linearly independent, there is some v_i such that

$v_i \in \text{Span}(S \setminus \{v_i\})$.

So, $\text{Span}(S \setminus \{v_i\}) = \text{Span}(S) = V$.

Thus $S \setminus \{v_i\}$ is a smaller spanning set.

Again, if $S \setminus \{v_i\}$ is not linearly independent, we can remove another element to create an even smaller spanning set.

This can continue at most n times.

So, at some point, we must end up with a spanning set which is linearly independent.

Defn: V - a vector space.

A basis of V is a spanning set which is linearly independent.

We have proved that every finite dimensional vector space has a basis. In fact, any finite spanning set of a finite dimensional vector space has a subset which is a basis.

Fact :

For any vector space V , any spanning set of V contains a basis.

In particular, (taking the spanning set to be V itself) we see that any vector space has a basis.

(We will not prove this.)

Let V be a finite dimensional vector space.

Suppose $B = \{v_1, v_2, \dots, v_n\}$ is a basis. Then, any $v \in V$ can be uniquely written in the form $v = a_1v_1 + a_2v_2 + \dots + a_nv_n$. We fix the order v_1, \dots, v_n on the basis B .

We define a function $\varphi_B : V \rightarrow \mathbb{R}^n$

by $\varphi_B(v) = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}$

if $v = a_1v_1 + \dots + a_nv_n$.

As any such expression for v is unique, φ_B is well-defined.

It is easy to see that φ_B is a linear transformation.

Φ_B is a 1-1 function:

If $\Phi_B(v) = \Phi_B(w) = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}$, then

$$v = a_1v_1 + a_2v_2 + \dots + a_nv_n = w.$$

Φ_B is an onto function

Let $\begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \in \mathbb{R}^n$. Let $v = a_1v_1 + \dots + a_nv_n$

Then, $\Phi_B(v) = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}$

Thus, an ordered basis (i.e.
a basis with a given order)
 $B = (v_1, \dots, v_n)$ defines a
linear transformation $\phi_B: V \rightarrow \mathbb{R}^n$.

ϕ_B is 1-1 and onto.

$\phi_B^{-1}: \mathbb{R}^n \rightarrow V$ is given by

$$\phi_B^{-1}\left(\begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}\right) = a_1v_1 + \dots + a_nv_n.$$

Definition A linear transformation
 $T: V \rightarrow W$ is said to be an
isomorphism of vector spaces or
a linear isomorphism if T is
a 1-1 correspondence.

Exercise: If $T: V \rightarrow W$ is a linear
isomorphism, prove that T^{-1} is a
linear isomorphism.

Exercise Let $T: V \rightarrow W$ be a linear isomorphism.

Let $B = \{v_1, \dots, v_n\}$ be a subset of V .

(1) Prove that B is a spanning set of V if and only if $T(B)$ is a spanning set of W .

(2) Prove that B is linearly independent if and only if $T(B)$ is linearly independent.

Theorem Let $\{v_1, \dots, v_m\} \subseteq \mathbb{R}^n$ be a spanning set. Then $m \geq n$.

Proof: Let $v_i = \begin{bmatrix} a_{1i} \\ a_{2i} \\ \vdots \\ a_{ni} \end{bmatrix}$. Let $A = (a_{ij})_{i,j}$

So A is an $n \times m$ matrix.

Any element $B = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$ of \mathbb{R}^n can be

expressed as $x_1 v_1 + x_2 v_2 + \dots + x_m v_m$.

So the matrix equation $AX = B$ always has a solution.

Let C be the row-reduced echelon matrix associated to A .
So $C = EA$ for some invertible matrix E .

Choose $B = E^{-1}e_n$. ($e_n = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$)

Suppose $x = \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix}$ is a solution of

$$AX = B.$$

Thus $A \cdot x = E^{-1}e_n$.

So $EAx = EE^T e_n$.

$\Rightarrow Cx = e_n$.

If $m < n$, C has a zero row at the bottom.

So the product Cx must have a zero row at the bottom.

— contradiction.

So $m \geq n$.

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Theorem Let $\{v_1, \dots, v_m\}$ be a linearly independent set in \mathbb{R}^n .

Then, $n \geq m$.

Proof: As in the proof of the previous theorem, let $v_i = \begin{bmatrix} a_{1,i} \\ a_{2,i} \\ \vdots \\ a_{n,i} \end{bmatrix}$

and let $A = (a_{ij})_{ij}$

Let $B = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$ be in $\text{Span}(\{v_1, \dots, v_m\})$.

Then, as $\{v_1, \dots, v_n\}$ is linearly independent, the equation $x_1v_1 + \dots + x_nv_n = B$ has a unique solution.

So the matrix equation $AX = B$ has a unique solution. Suppose $m < n$. But we know that if $m > n$, there are infinitely many solutions if there exists a solution at all. — contra. //

Thus any basis of \mathbb{R}^n has exactly n elements.

Let V be a finite dimensional vector space with an ordered basis $B = (v_1, \dots, v_n)$.

This gives us an isomorphism $\varphi_B: V \rightarrow \mathbb{R}^n$. φ_B maps any basis of V to a basis of \mathbb{R}^n .

Thus, any basis of V has n elements.

We have proved:

Theorem Let V be a finite dimensional vector space. Then, any basis of V has the same number of elements.

Definition

Let V be a finite dimensional vector space. The dimension of V , written as $\dim(V)$, is the number of elements in a basis of V .