

## Lecture 25

Let  $V$  be a vector space.

An  $m \times n$  matrix with entries in  $V$

is rectangular arrangement, with  $m$  rows and  $n$  columns, of  $mn$  elements of  $V$ .

$$\begin{bmatrix} v_{11} & v_{12} & \dots & v_{1n} \\ \vdots & & & \\ \vdots & & & \\ \vdots & & & \\ v_{m1} & \cdots & \cdots & v_{mn} \end{bmatrix}$$

$v_{ij} \in V$   
for all  
 $i, j$

The set of such matrices is denoted by  $M_{m \times n}(V)$ .

This is actually a vector space, with addition and scalar multiplication being defined component-wise.

We will mostly be concerned with the case  $m=1$  (row matrices).

Convention A  $1 \times 1$  matrix with entries in  $V$  is of the form  $[v]$ , where  $v \in V$ . In this case, we will identify it with the vector  $v$  and not write the brackets.

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Matrices with vector entries will generally be written with "curly" letters:  $\mathcal{A}, \mathcal{B}, \mathcal{C}, \mathcal{D}$ , etc.

## Matrix multiplication

Given an element of  $M_{m \times n}(V)$ , it can be multiplied on the left or right by matrices with entries from  $\mathbb{R}$  (with appropriate sizes).

e.g.

$$\begin{bmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} = \begin{bmatrix} v_{11} + 4v_{12} & 2v_{11} + 5v_{12} & 3v_{11} + 6v_{12} \\ v_{21} + 4v_{22} & 2v_{21} + 5v_{22} & 3v_{21} + 6v_{22} \end{bmatrix}$$

Notice that we use scalar multiplication to multiply a real number with a vector.

This operation is associative and distributes over addition in the appropriate sense.

$$\text{e.g. } (A \cdot B) \cdot c = A \cdot (B \cdot c)$$

$A, B$  - entries from  $\mathbb{R}$ .

$c$  - entries from  $V$ .

## An ordered basis as a row matrix

Given a basis of  $V$  with a chosen ordering of its elements, we will view it as a row matrix.

So, an ordered basis  $\beta$  of an  $n$ -dim vector space  $V$  is a  $1 \times n$  matrix of the form  $[v_1, \dots, v_n]$  where  $\{v_1, \dots, v_n\}$  is a basis.

Given an ordered basis  $B$ , to any  $v \in V$ , we associate a column matrix in  $M_{n \times 1}(\mathbb{R}) = \mathbb{R}^n$ . We write  $v$  as a linear combination of the basis elements.

$$v = a_1 v_1 + a_2 v_2 + \cdots + a_n v_n.$$

The numbers  $a_1, a_2, \dots, a_n$  are uniquely determined.

Then the column matrix associated to  $v$  is  $\begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}$ .

We call this the matrix representation of  $v$  with respect to  $B$  and is denoted by  $M_B(v)$ .

So, we have a function

$$\varphi_B: V \rightarrow \mathbb{R}^n, \quad \varphi_B(v) = M_B(v).$$

We saw (in Lecture 24) that  
 this is a linear isomorphism  
 with inverse given by  $\Psi_B: \mathbb{R}^n \rightarrow V$ ,  
 $\Psi_B \left( \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \right) = a_1 v_1 + \cdots + a_n v_n.$

Observe that  $[a_1 v_1 + \cdots + a_n v_n]$   
 $= [v_1, \dots, v_n] \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}$

So, for any vector  $v$ , we see that

$$[v] = \mathcal{B} \cdot M_{\mathcal{B}}(v).$$

By our convention, we write  $[v]$  as just  $v$  and so we have the formula

$$v = \mathcal{B} \cdot M_{\mathcal{B}}(v)$$

Remark The fact that  $\Psi_B$  is a 1-1 correspondence tells us that if for  $x, y \in \mathbb{R}^n$ , we have  $B \cdot x = B \cdot y$ , then  $x = y$ . So  $B$  can be "cancelled" from both sides.

Note that this is only true when  $B$  is an ordered basis.

Example Suppose  $V = \mathbb{R}^n$ .

Let  $B$  be the standard basis

$[e_1, e_2, \dots, e_n]$ .

Then if  $v = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}$ , we see that

$$v = a_1 e_1 + a_2 e_2 + \dots + a_n e_n.$$

So  $M_B(v) = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}$ , which is  $v$  itself!

Example The vectors  $v_1 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$  and  $v_2 = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$ .

are linearly independent and so form a basis of  $\mathbb{R}^2$ . Let  $B = [v_1, v_2]$ .

Let  $v = \begin{bmatrix} 4 \\ 5 \end{bmatrix}$ . What is  $M_B(v)$ ?

We want to find  $x_1, x_2$  such that

$$x_1 \begin{bmatrix} 2 \\ 3 \end{bmatrix} + x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 5 \end{bmatrix}$$

This is a system of linear equations represented by

$$\left[ \begin{array}{cc|c} 2 & 4 & 4 \\ 3 & 1 & 5 \end{array} \right].$$

We can solve this by row reduction or Cramer's rule and find that the only solution is  $x_1 = \frac{8}{5}$ ,  $x_2 = \frac{1}{5}$

So  $M_B(v) = \begin{bmatrix} \frac{8}{5} \\ \frac{1}{5} \end{bmatrix}.$

## Matrix representation for row of vectors

Given a row matrix of vectors,

say  $\mathcal{A} = [\omega_1, \dots, \omega_m]$  and an ordered basis  $\mathcal{B} = [v_1, \dots, v_n]$ , we define the matrix representation of  $\mathcal{A}$  with respect to  $\mathcal{B}$ , denoted by  $M_{\mathcal{B}}(\mathcal{A})$  to be the  $n \times m$  matrix whose  $i$ -th column is  $M_{\mathcal{B}}(\omega_i)$ .

Thus, we get a function

$$M_{1 \times m}(V) \rightarrow M_{n \times m}(\mathbb{R})$$

$$A \mapsto M_B(A).$$

So  $M_B(A) = [M_B(w_1) \ M_B(w_2) \ \dots \ M_B(w_n)]$

These are columns, not  
single entries

Fact :

$$A = B \cdot M_B(A)$$

(Try to  
prove  
this!)

Example Let  $V = \mathbb{R}^n$ .

Let  $B = [e_1, \dots, e_n]$ .

Then, for any matrix  $A = [v_1, \dots, v_m]$ ,  
the matrix  $M_B(A)$  is the  $n \times m$   
matrix, whose  $i^{th}$  column is  
 $M_B(v_i)$ . But we saw earlier that  
when  $B$  is the standard basis,  
 $M_B(v_i)$  is  $v_i$  itself.

So,  $M_{\mathcal{B}}(A)$  has  $v_i$  as its  $i^{\text{th}}$  column.

So, if  $V = \mathbb{R}^2$ ,  $\mathcal{B} = [e_1, e_2]$  and  $A = \left[ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 2 \end{bmatrix} \right]$ , then

$$M_{\mathcal{B}}(A) = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 3 & 2 \end{bmatrix}.$$

Example  $V = \mathbb{R}^2$ .  $B = \left[ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right]$

Suppose  $A = \left[ \begin{bmatrix} 0 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ -1 \end{bmatrix} \right]$

$$\begin{bmatrix} 0 \\ 2 \end{bmatrix} = (-2) \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} \rightsquigarrow \begin{bmatrix} -2 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} -1 \\ 1 \end{bmatrix} = (-3) \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} \rightsquigarrow \begin{bmatrix} -3 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ -1 \end{bmatrix} = 11 \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} + (-6) \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 11 \\ -6 \end{bmatrix}$$

$$\text{So } M_B(A) = \begin{bmatrix} -2 & -3 & 11 \\ 2 & 2 & -6 \end{bmatrix}$$

$$\left[ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right] \cdot \begin{bmatrix} -2 & -3 & 11 \\ 2 & 2 & -6 \end{bmatrix}$$

<sup>"</sup>  
 $\overset{\textcolor{violet}{M}_B(A)}$

$$= \left[ \begin{bmatrix} 0 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ -1 \end{bmatrix} \right] = A.$$

Theorem Let  $V$  be a vector space. Let  $B_1$  and  $B_2$  be two ordered bases of  $V$ . Then,

$$M_{B_2}(v) = M_{B_2}(B_1) \cdot M_{B_1}(v).$$

Proof  $B_2 \cdot M_{B_2}(v) = v.$

$$\begin{aligned} B_2 \cdot (M_{B_2}(B_1) \cdot M_{B_1}(v)) &= (B_2 \cdot M_{B_2}(B_1)) \cdot M_{B_1}(v) \\ &= B_1 \cdot M_{B_1}(v) = v. \end{aligned}$$

Thus,

$$\beta_2 \cdot M_{\beta_2}(v) = \beta_2 \cdot M_{\beta_2}(\beta_1) \cdot M_{\beta_1}(v).$$

As  $\beta_2$  is an ordered basis, we know that it can be "cancelled" on the left.

So,  $M_{\beta_2}(v) = M_{\beta_2}(\beta_1) \cdot M_{\beta_1}(v).$

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Theorem V- fin. dim vector space

Let  $B_1$  and  $B_2$  be two ordered bases. Then the matrix  $M_{B_2}(B_1)$  is invertible, and its inverse is  $M_{B_1}(B_2)$ .

Proof :  $B_1 = B_2 \cdot M_{B_2}(B_1)$

$$= B_1 \cdot M_{B_1}(B_2) \cdot M_{B_2}(B_1).$$

So

$$B_1 \cdot I_n = B_1 \cdot (M_{B_1}(B_2) \cdot M_{B_2}(B_1))$$

(n = \dim V).

Thus (since  $B_1$  can be  
"cancelled"),

$$I_n = M_{B_1}(B_2) \cdot M_{B_2}(B_1).$$

This proves the theorem. //

Remark Conversely an invertible matrix  $A$  is of the form  $M_{B_2}(B_1)$

for some choice of  $B_1$  and  $B_2$ .

Indeed, take  $B_2 = \text{standard basis}$

$$\begin{aligned} & \text{of } \mathbb{R}^n \\ &= [e_1 \dots e_n] \end{aligned}$$

As  $A$  is invertible, the columns of  $A$  are linearly independent, and

so they form a basis of  $\mathbb{R}^n$ .

Suppose the columns of A are

$v_1, \dots, v_n$  (in that order).

Take  $B_1 = [v_1, v_2, \dots, v_n]$

Then  $M_{B_2}(B_1) = A$ .

## Linear transformations

Recall that if  $A \in M_{m \times n}(\mathbb{R})$ ,

then  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  defined by

$T(x) = Ax$  is a linear

transformation.

The  $i^{th}$  column of  $A$  is  $Ae_i = T(e_i)$ .

Conversely, if  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  is any linear transformation, let  $A$  be the  $m \times n$  matrix whose  $i^{th}$  column is  $T(e_i)$ .

Then  $T(e_i) = Ae_i$  for all  $i$ .

So, if  $x = x_1e_1 + x_2e_2 + \dots + x_ne_n$ ,

then  $T(x) = x_1T(e_1) + x_2T(e_2) + \dots + x_nT(e_n)$

$$= A(x_1e_1) + A(x_2e_2) + \dots + A(x_ne_n)$$

$$= A(x_1e_1 + \dots + x_ne_n) = Ax.$$

Thus we have a 1-1 correspondence

$$\left\{ \begin{array}{l} \text{linear transformations} \\ T: \mathbb{R}^n \rightarrow \mathbb{R}^m \end{array} \right\} \leftrightarrow M_{m \times n}(\mathbb{R}).$$

Give two abstract finite dim. vector spaces  $V$  and  $W$ , and a linear transformation  $T: V \rightarrow W$ , we cannot immediately associate a matrix to it. We need to choose ordered bases for  $V$  and  $W$ . Let  $B$  be an ordered basis for  $V$  and  $C$  be an ordered basis for  $W$ .

Let  $B = [v_1, \dots, v_n]$

and  $E = [w_1, \dots, w_m]$

These bases give isomorphisms

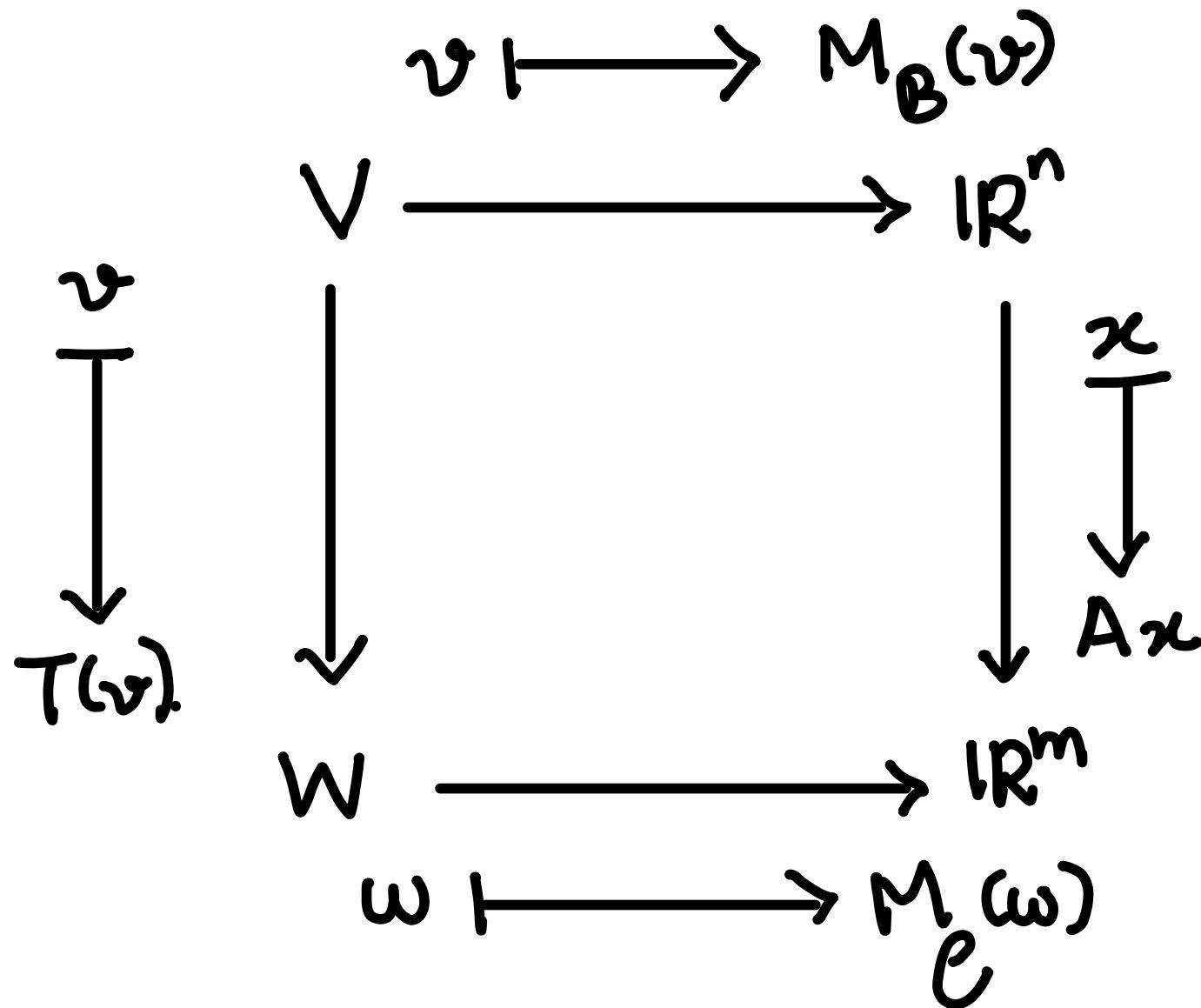
$V \rightarrow \mathbb{R}^n$  and  $W \rightarrow \mathbb{R}^m$ .

Then  $T: V \rightarrow W$  corresponds to  
a linear transformation  $\mathbb{R}^n \rightarrow \mathbb{R}^m$ .

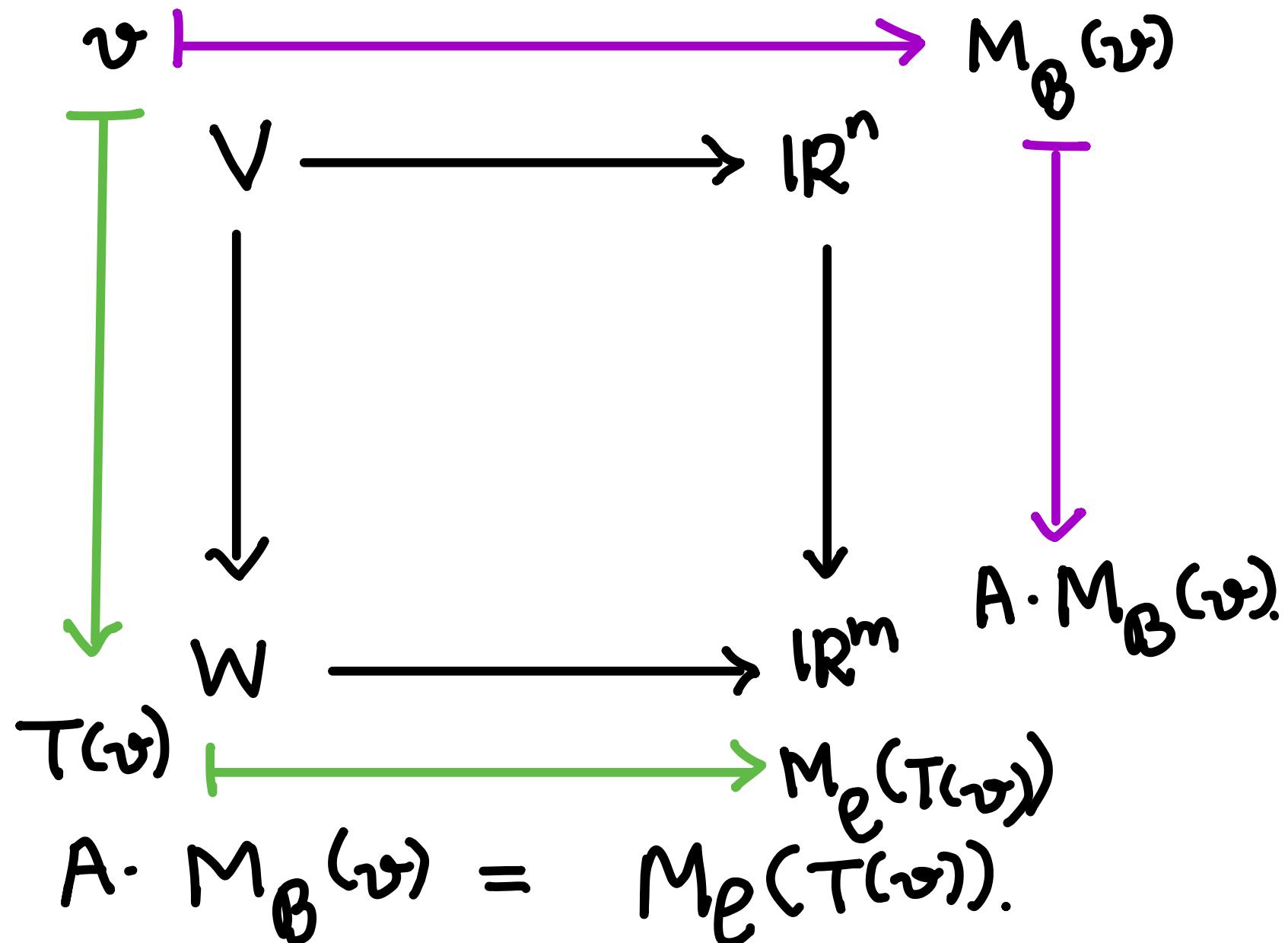
We want to calculate the matrix  
of this transformation.

Let us denote this matrix by  $A$ .

We have the following diagram



Let us see what happens to  $v \in V$ .



Thus  $A$  is a matrix such that  $M_e(T(v)) = A \cdot M_B(v)$  for all  $v \in V$ .

Let  $e_1, \dots, e_n$  be the standard basis vectors in  $\mathbb{R}^n$ .

Then  $M_B(v_i) = e_i$  for all  $i$ ,  
 $1 \leq i \leq n$ .

So  $M_e(T(v_i)) = Ae_i$ , which is the  $i$ -th column of  $A$ .

Thus  $A$  is the  $m \times n$  matrix  
whose  $i$ -th column is  $M_e^B(T(v_i))$ .

We will denote this matrix by  
 $M_e^B(T)$ . (This is the matrix  
representation of  $T$  with respect  
to  $B$  and  $C$ .)

Note that

$$T(v) = e \cdot M_e(T(v)).$$

$$\begin{aligned} \text{As } M_e(T(v)) &= A \cdot M_B(v) \\ &= M_e^B(T) \cdot M_B(v), \end{aligned}$$

we get

$$T(v) = e \cdot M_e^B(T) \cdot M_B(v)$$

## Changing bases

Suppose  $B_1$  and  $B_2$  are ordered bases on  $V$ .

Suppose  $e_1$  and  $e_2$  are ordered bases on  $W$ .

What is the relation between  
 $M_{e_1}^{B_1}(\tau)$  and  $M_{e_2}^{B_2}(\tau)$  ?

$$T(v) = e_1 \cdot M_{e_1}^{B_1}(T) \cdot M_{B_1}(v)$$

We know that  $e_1 = e_2 \cdot M_{e_2}(e_1)$

and  $M_{B_1}(v) = M_{B_1}(B_2) \cdot M_{B_2}(v).$

So  $T(v) = e_2 \cdot M_{e_2}(e_1) \cdot M_{e_1}^{B_1} \cdot M_{B_1}(B_2) \cdot M_{B_2}(v)$

Also  $T(v) = e_2 \cdot M_{e_2}^{B_2}(T) \cdot M_{B_2}(v).$

So,

$$e_2 \cdot M_{e_2}^{B_2}(T) \cdot M_{B_2}(v) = e_2 \cdot M(e_i) \cdot M_{e_i}^{B_i}(T) \cdot M_{B_i}(B_2) \cdot M_{B_2}(v).$$

Cancelling  $e_2$ , we get

$$M_{e_2}^{B_2}(T) \cdot M_{B_2}(v) = M(e_i) \cdot M_{e_i}^{B_i}(T) \cdot M_{B_i}(B_2) \cdot M_{B_2}(v)$$

for all  $v \in V$ .

Choose  $v$  such that  $M_{B_2}(v) = e_i$

Then we see that

$$M_{e_2}^{B_2}(T) \cdot e_i = M_{e_2}(e_i) \cdot M_{e_1}^{B_1}(T) \cdot M_{B_1}(B_2) \cdot e_i$$

Thus, the matrices  $M_{e_2}^{B_2}(T)$  and  $M_{e_2}(e_i) \cdot M_{e_1}^{B_1}(T) \cdot M_{B_1}(B_2)$  have the same  $i$ -th column for any  $i$ .

So

$$M_{e_2}^{B_2}(T) = M_{e_2}(e_i) \cdot M_{e_1}^{B_1}(T) \cdot M_{B_1}(B_2)$$