## Lecture 16

Systems of linear equations:

 $a_{11}X_1 + a_{12}X_2 + \cdots$ 

 $a_{21}X_1 + a_{22}X_2 + \cdots + a_{2n}X_n = b_2$ 

ai, bie IR for all i,j. Xi are variables.

 $+ a_{in} X_n = b_i$ 

 $a_{mn} X_n = b_m$ 

Example 
$$m=2, n=2$$
  
 $2X_1 + 3X_2 = 5$  — (1)  
 $-X_1 + X_2 = 7$  — (2)  
Add  $2 \times Eqn(2)$  to Eqn(1).

Solve eqn (3) for X2

 $0 + 5x_2 = 19$  — (3) Eqn (3)  $x_1 + x_2 = 7$  eqn (1)

 $- \times_{1} + \times_{2} = 7$ 

 $-X_1 + X_2 = 7$ 

$$X_2 = 19/5$$
  
Substitute the value of  $X_2$  in eqn (2) and solve for  $X_1$ .  
 $-X_1 + 19/5 = 7$   
So  $X_1 = 19/5 - 7 = -16/5$ 

Solution: {(-16/5, 19/5)}

Example: 
$$m=3$$
,  $n=2$ 
 $X_1 - X_2 = 3$  — (1)
 $2X_1 - 3X_2 = 1$  — (2)
 $-X_1 + 2X_2 = -1$  — (3)
Add (-2)x Eqn(1) to Eq

Add  $(-2) \times \text{Eqn}(1)$  to Eqn(2).  $0 - X_2 = -5$  — (4) | Replaces eqn(2). Add eqn(1) to eqn(3).  $0 + X_2 = 2$  — (5) | Replaces eqn (3). Now we have the system

 $X_{1} - X_{2} = 3$  $- X_2 = -5$ 

 $X_{2} = 2$ 

This system has no solutions.

Solution set =  $\phi = \{ \}$ .

Example 
$$m = 2$$
,  $n = 3$ 

$$X_{1} + X_{2} - X_{3} = 4 - (1)$$

$$2X_{1} - X_{2} + 3X_{3} = 1 - (2)$$

 $2X_1 - X_2 + 3X_3 = 1 - (2)$ Add (-2) x eqn (1) to eqn(2).  $X_1 + X_2 - X_3 = 4 - (1)$ 

 $0 - 3X_2 + 5X_3 = -7$  (3) Divide eqn (3) by (-3).

$$X_1 + X_2 - X_3 = 4 - (1)$$
 $X_2 - (5/3)X_3 = 7/3 - (4)$ 

Add  $(-1) \times eqn(4)$  for eqn (1).

 $X_1 + 0 + (2/3)X_3 = 5/3 - (5)$ 
 $X_2 - (5/3)X_3 = 7/3$ .

Choose any value for  $X_3$  and Solve for  $X_1$  and  $X_2$ .

Suppose we set  $X_3 = t$  for some  $t \in IR$ . Then, we get  $X_1 = \frac{5}{3} - \frac{2}{3}t$ 

and  $X_2 = \frac{7}{3}t$ .

Solution set:

$$\{(\frac{5}{3}-\frac{2}{3}t,\frac{7}{3}+\frac{5}{3}t,t)| t \in \mathbb{R} \}$$

Thus, we see that when we solve a system of linear equations, one of three things could happen: (1) Unique solution.

(3) Family of solutions

(2) No solution.

Understanding the method We are given a system(A) of equations. We perform some operations and create a system (B) What is the relationship between the solutions of (A) and (B) ?

Example Consider the system (A) consisting

 $(X-1)^2 = 25.$ 

of squaring both sides.

We get the system (B):

of one equation: X-1=5.

Suppose we perform the operation

But only 6 is a solution of (A). So, these two systems are not <u>equivalent</u>. Every solution of (A) must satisfy (B), but not the other way around.

Solutions of (B) are 6 and -4.

But suppose there exist some other operations which allow us to obtain system (A) from System (B). Then, every solution of (B) is a solution of (A). So the systems

are equivalent

## Example

System A: 
$$X_1 + X_2 = 5$$
 — (1)  
 $2x_1 - x_2 = 2$  — (2).

$$2x_{1} - x_{2} = 2 - (2)$$
Operation: Replace eqn(1)
$$eqn(1) + 3 \times eqn(2).$$

$$(x_{1} + x_{2}) + 3(2x_{1} - x_{2}) = 5 + 3(2)$$

$$(3)$$

 $2\times_1 - \times_2 = 2$ 

Notice that eqn (3) is "implied" by eqn (1) and eqn(2). In other words, any solution of eqn (1) and eqn (2) is

a solution of eqn (3).

So, every solution of (A) is a solution of (B).

System B:  $7x_1 - 2x_2 = 11 - (3)$   $2x_1 - x_2 = 2 - (2)$ Perform the following operation on (B): Replace eqn (3) by

Let us call the new system as (C).

eqn(3) - 3xeqn(2)

By the same argument as before, every solution of (B) is a solution of CC). But (C) is the same as (A).

 $(7x_1 - 2x_2) - 3(2x_1 - x_2) = 11 - 3(2)$  $x_1 + x_2 = 5$  So, systems (A) and (B) are equivalent, i.e. they have the same solution sets. This is because we obtained (B) from (A) by using a

reversible operation.

Not all operations are reversible. For example, if we start

with X - 1 = 5 and square

But if we start with  $(x-1)^2=25$ ,

as square roots are not unique.

both sides, we get  $(X-1)^2 = 25$ .

we cannot deduce X-1=5

From  $(X-1)^2 = 25$ , we can only get the statement X-1=5 OR X-1=-5

This is because squaring is not a reversible operation.

They are as follows: (1) Replace eqn (i) by eqn(i)+ ax eqn(j) for some a E IR. Inverse: Replace equ(i) by eqn(i) + (-a) x eqn(j).

We will only use reversible operations

on systems of linear equations.

(2) Interchange eqn(i) and eqn(j).

<u>Inverse</u>: Interchange eqn (i) and
eqn (j).

(3) Replace eqn(i) by  $a \times eqn(i)$  for some  $a \neq 0$ .

<u>Inverse</u>: Replace eqn(i) by (1/a) x eqn(i).

## Key idea

Consider the system

 $a_{11}X_1 + a_{12}X_2 + \cdots$ 

$$a_{11}X_{1} + a_{12}X_{2} + \cdots + a_{1n}X_{n} = b_{1}$$

$$a_{21}X_{1} + a_{22}X_{2} + \cdots + a_{2n}X_{n} = b_{2}$$

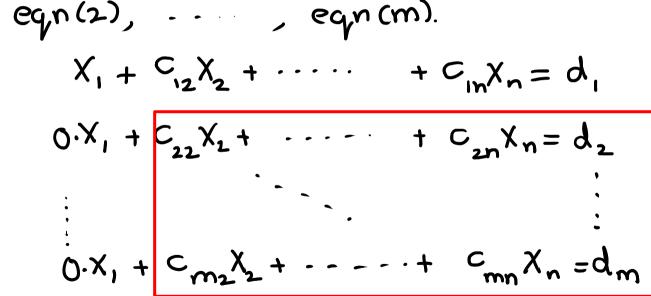
$$a_{21}X_1 + a_{22}X_2 + \cdots + a_{2n}X_n = b_2$$
  
 $a_{m1}X_1 + a_{m2}X_2 + \cdots + a_{mn}X_n = b_2$ 

 $a_{mn}X_n = b_m$ Suppose  $a_n \neq 0$ .

Then, we can replace eqn (1) by  $\left(\frac{1}{a_{i,j}}\right)$  x eqn(1) to reduce to a situation where the coefficient of X, in eqn (1) is 1. Now perform the operations eqn(i)  $\longrightarrow$  eqn(i) + (-a<sub>i</sub>,) eqn(1)

for i = 2, 3, ..., m.

This will eliminate 
$$X_1$$
 from eqn(2), --- , eqn(m).  
 $X_1 + C_{12}X_2 + \cdots + C_{1n}X_n = d_1$ 



Consider the system consisting of eqn(2), eqn(3), ..., eqn(m).

This is a smaller system with (n-1) variables and (m-1) equations.

Solve this smaller system for  $X_2, \dots, X_n$  and substitute in eqn(1). Solve eqn(1) for  $X_1$ .

What if  $a_{11} = 0$ ? Find some i such that  $a_{ij} \neq 0$ . Interchange equ(1) and equ(i). If  $a_{ij} = 0$  for all i, then X, is not really there in any equation. Move on to X2.

How do we solve the smaller system we obtained?  $C_{22}X_2 + \cdots + C_{2n}X_n = d_2$ 

 $C_{m_2}X_2 + \cdots + C_{m_n}X_n = d_m$ Use the same procedure. Start with  $X_2$  instead of  $X_1$ .

We will then end up with an even smaller system with (n-2) variables and (m-2) equations. ··· and so on. How does this process end?

( Next time ).