

In [114...

```
import numpy as np
import matplotlib.pyplot as plt

# -----
# 1. Define arbitrary complex states  $|a\rangle$  and  $|b\rangle$ 
# -----
# Example complex states
a = np.array([1/np.sqrt(2), 1j/np.sqrt(2)]) #  $|a\rangle$ 
b = np.array([np.sqrt(0.6), np.sqrt(0.4)*np.exp(1j*np.pi/4)]) #  $|b\rangle$ 
#theta=np.pi / 2
#a=np.array([[1], [0]])
#b=np.array([[np.cos(theta)], [np.sin(theta)]])
print("state 1=",a)
print("state 2=",b)
```

```
state 1= [0.70710678+0.j          0.          +0.70710678j]
state 2= [0.77459667+0.j          0.4472136  +0.4472136j]
```

In [115...

```
# Normalize states
a = a / np.linalg.norm(a)
b = b / np.linalg.norm(b)
print("Normalized state 1=",a)
print("Normalized state 2=",b)
```

```
Normalized state 1= [0.70710678+0.j          0.          +0.70710678j]
Normalized state 2= [0.77459667+0.j          0.4472136  +0.4472136j]
```

In [116...

```
# Inner product  $\langle a|b\rangle$ 
X = np.vdot(a, b)
print("inner product of a and b as  $X=\langle a|b\rangle$ =",X)
```

```
inner product of a and b as  $X=\langle a|b\rangle$ = (0.8639503235220042-0.316227766016838j)
```

In [117...

```
# Projection of  $|b\rangle$  onto  $|a\rangle$ 
b_proj_on_a = X * a
```

In [118...

```
# -----
# 2. Skew Gram Matrix (2x2)
# -----
q0 = 0.5
q1 = 0.5
Gs = np.array([[-q0, -np.sqrt(q0*q1)*X],
               [np.sqrt(q0*q1)*X.conjugate(), q1]])
print("Skew Gram Matrix=\n",Gs)
# Eigenvalues and eigenvectors of SGM
eigvals, eigvecs = np.linalg.eig(Gs)
print("eigvals=",eigvals)
eigvecs_scaled = eigvecs * 0.5 # scale for plotting
```

```
Skew Gram Matrix=
[[-0.5          +0.j          -0.43197516+0.15811388j]
 [ 0.43197516+0.15811388j  0.5          +0.j          ]]
eigvals= [-0.1959527-2.15332782e-17j  0.1959527+4.92888538e-17j]
```

In [119...

```
# -----
# 3. Probabilities & Error Rate
# -----
eta_abs = np.abs(eigvals)
P_e = 0.5 * (1 - np.sum(eta_abs))
P_correct_0 = q0 + eigvals[0]
P_correct_1 = q1 + eigvals[1]

print("probability of error=",P_e)
```

```
print("probability of correct decision for 0=> P(0)=",P_correct_0)
print("probability of correct decision for 1=> P(1)=",P_correct_1)
```

probability of error= 0.30404730259178336

probability of correct decision for 0=>  $P(0) = (0.30404730259178336 - 2.153327820804061e-17j)$

probability of correct decision for 1=>  $P(1) = (0.6959526974082166 + 4.928885382366952e-17j)$

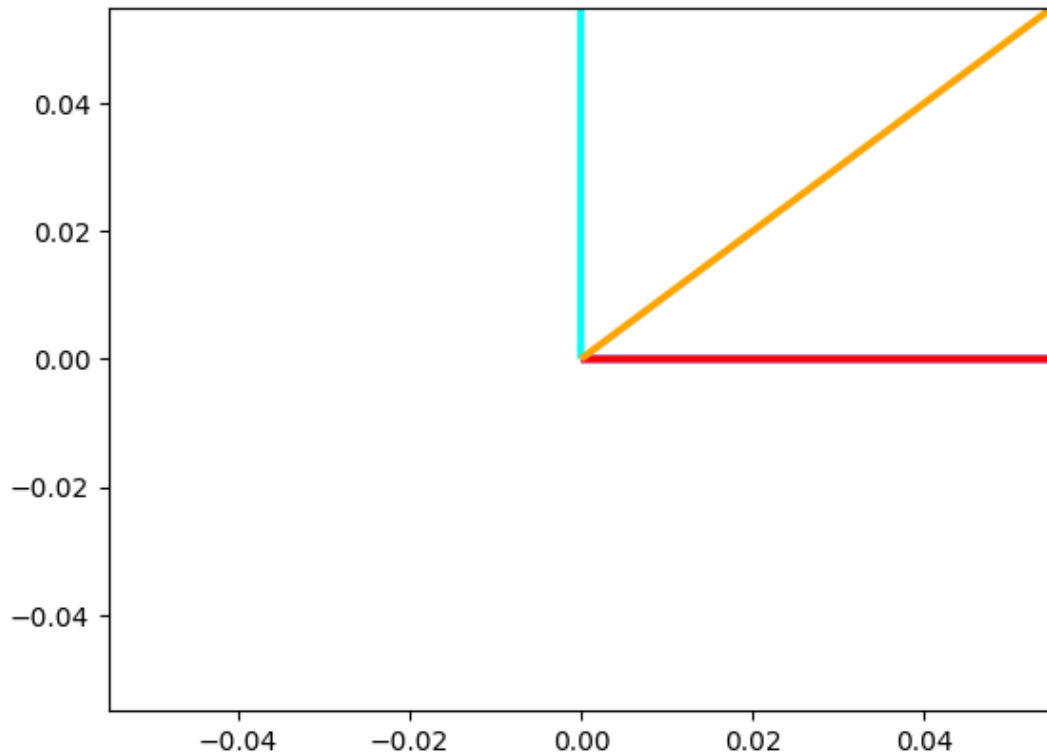
```
In [120... # -----
# 4. Plot everything in 2D (Re vs Im)
# -----
plt.figure(figsize=(8,6))
```

Out[120... <Figure size 800x600 with 0 Axes>

<Figure size 800x600 with 0 Axes>

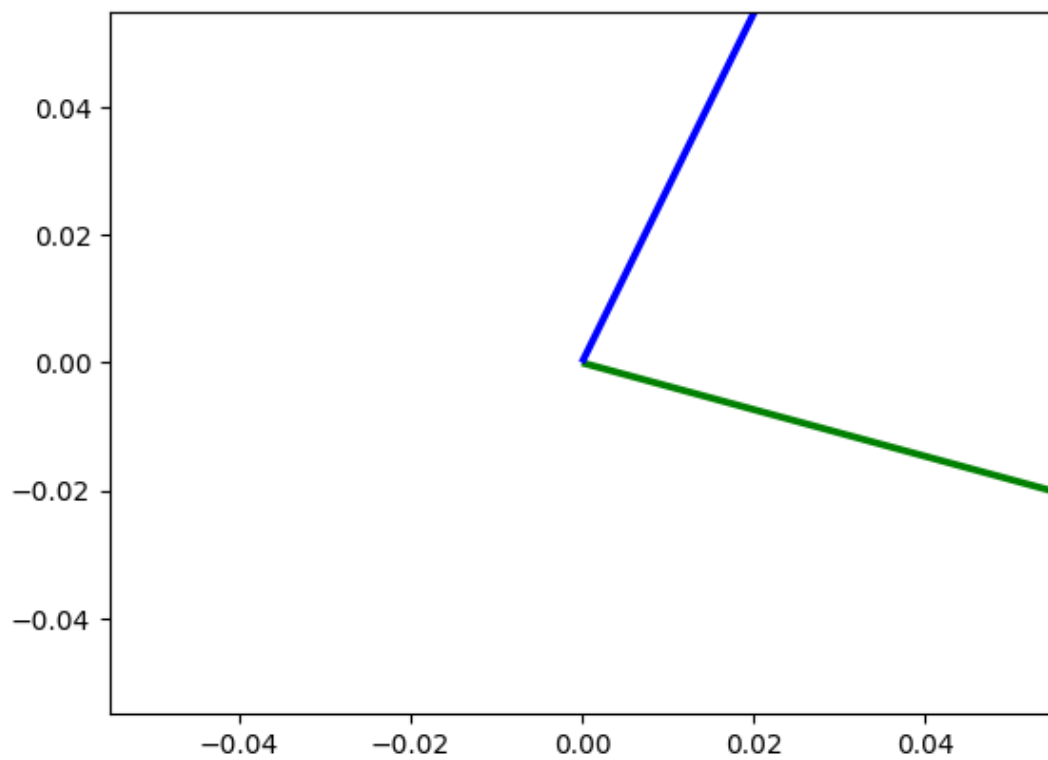
```
In [143... # Plot states (real vs imaginary parts)
plt.quiver(0,0,a[0].real,a[0].imag, angles='xy', scale_units='xy', scale=1, color='bl
plt.quiver(0,0,a[1].real,a[1].imag, angles='xy', scale_units='xy', scale=1, color='cy
plt.quiver(0,0,b[0].real,b[0].imag, angles='xy', scale_units='xy', scale=1, color='re
plt.quiver(0,0,b[1].real,b[1].imag, angles='xy', scale_units='xy', scale=1, color='or
```

Out[143... <matplotlib.quiver.Quiver at 0x224ac5741a0>



```
In [146... # Projection of |b> onto |a> (real vs imaginary)
plt.quiver(0,0,b_proj_on_a[0].real,b_proj_on_a[0].imag, angles='xy', scale_units='xy'
plt.quiver(0,0,b_proj_on_a[1].real,b_proj_on_a[1].imag, angles='xy', scale_units='xy'
```

Out[146... <matplotlib.quiver.Quiver at 0x224acbd7aa0>



In [147...

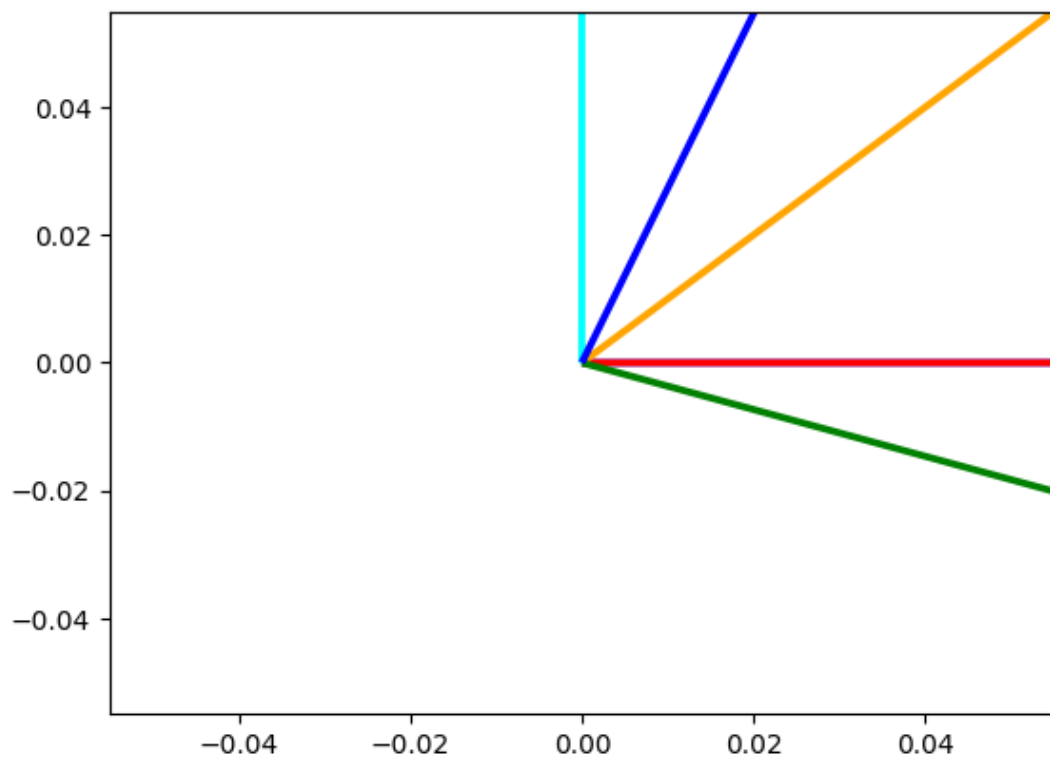
```
# Plot states (real vs imaginary parts)
plt.quiver(0,0,a[0].real,a[0].imag, angles='xy', scale_units='xy', scale=1, color='blue')
plt.quiver(0,0,a[1].real,a[1].imag, angles='xy', scale_units='xy', scale=1, color='cyan')
plt.quiver(0,0,b[0].real,b[0].imag, angles='xy', scale_units='xy', scale=1, color='red')
plt.quiver(0,0,b[1].real,b[1].imag, angles='xy', scale_units='xy', scale=1, color='orange')

# Projection of |b> onto |a> (real vs imaginary)
plt.quiver(0,0,b_proj_on_a[0].real,b_proj_on_a[0].imag, angles='xy', scale_units='xy', scale=1, color='blue')
plt.quiver(0,0,b_proj_on_a[1].real,b_proj_on_a[1].imag, angles='xy', scale_units='xy', scale=1, color='cyan')

# -----
# 4.
```

Out[147...

&lt;matplotlib.quiver.Quiver at 0x224ae7aca70&gt;

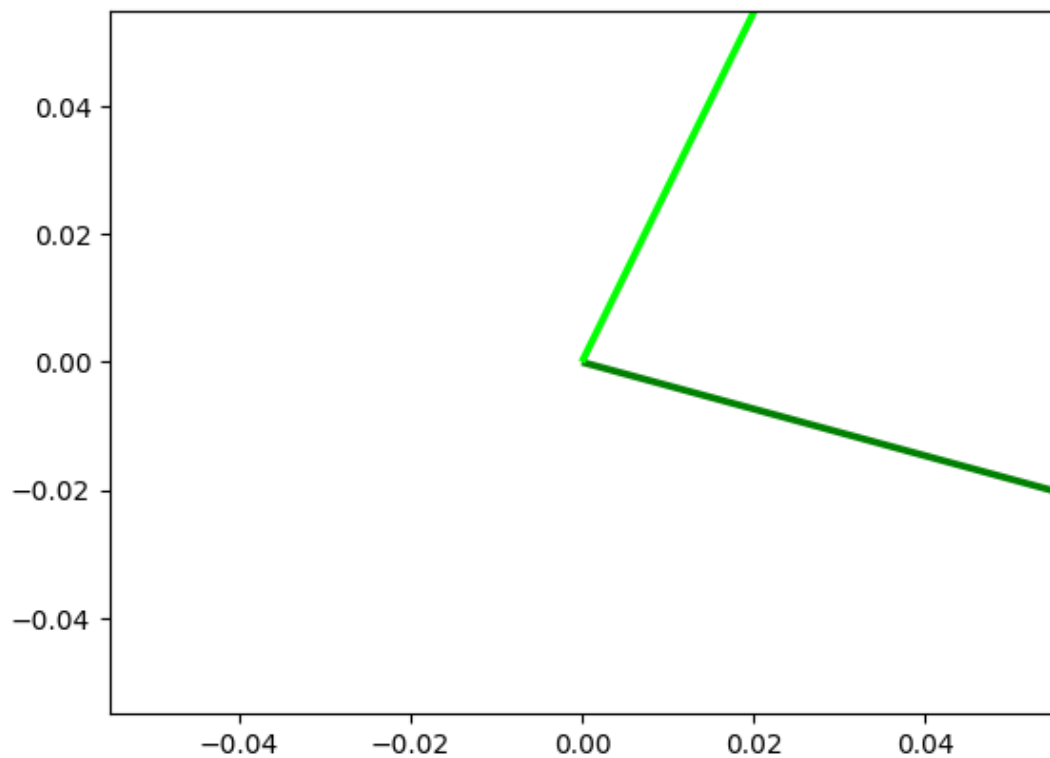


In [134...

```
# Projection of |b> onto |a> (real vs imaginary)
plt.quiver(0,0,b_proj_on_a[0].real,b_proj_on_a[0].imag, angles='xy', scale_units='xy')
plt.quiver(0,0,b_proj_on_a[1].real,b_proj_on_a[1].imag, angles='xy', scale_units='xy')
```

Out[134...

```
<matplotlib.quiver.Quiver at 0x224ad1fd640>
```



In [133...

```
# -----
# 4. Plotting
# -----
plt.figure(figsize=(15,15))

# |a> and |b>
plt.quiver(0,0,a[0],a[1], angles='xy', scale_units='xy', scale=0.5, color='blue', lab
```

```

plt.quiver(0,0,b[0],b[1], angles='xy', scale_units='xy', scale=0.5, color='red', label='|b>')

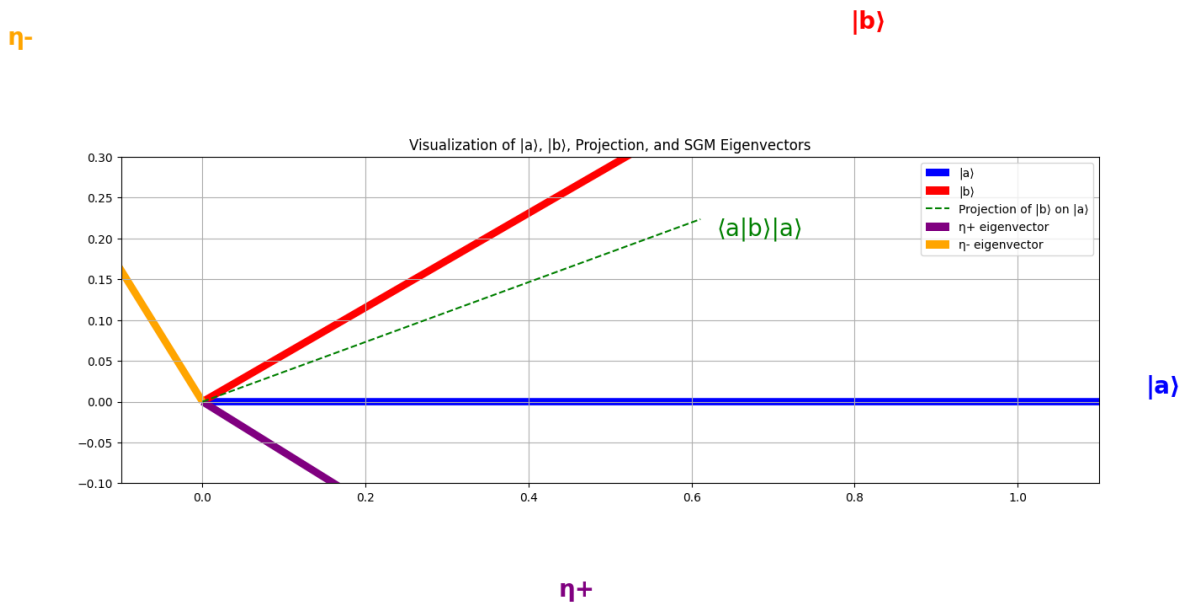
# Projection as dashed line
plt.plot([0, b_proj_on_a[0]], [0, b_proj_on_a[1]], 'g--', label='Projection of |b> on |a>')

# SGM eigenvectors
plt.quiver(0,0,eigvecs_scaled[0,0],eigvecs_scaled[1,0], angles='xy', scale_units='xy', scale=1, color='purple', label='η+')
plt.quiver(0,0,eigvecs_scaled[0,1],eigvecs_scaled[1,1], angles='xy', scale_units='xy', scale=1, color='orange', label='η-')

# Labels
plt.text(a[0]+0.45,a[1]+0.01,'|a>', color='blue',fontsize=20,fontweight='bold')
plt.text(b[0]+0.02,b[1]+0.01,'|b>', color='red',fontsize=20,fontweight='bold')
plt.text(b_proj_on_a[0]+0.02,b_proj_on_a[1]-0.02,'⟨a|b⟩|a>', color='green',fontsize=20,fontweight='bold')
plt.text(eigvecs_scaled[0,0]+0.02,eigvecs_scaled[1,0]+0.02,'η+', color='purple',fontsize=20,fontweight='bold')
plt.text(eigvecs_scaled[0,1]+0.02,eigvecs_scaled[1,1]+0.02,'η-', color='orange',fontsize=20,fontweight='bold')

plt.xlim(-0.1,1.1)
plt.ylim(-0.1,0.3)
plt.gca().set_aspect('equal')
plt.grid(True)
plt.title('Visualization of |a>, |b>, Projection, and SGM Eigenvectors')
plt.legend()
plt.show()

```

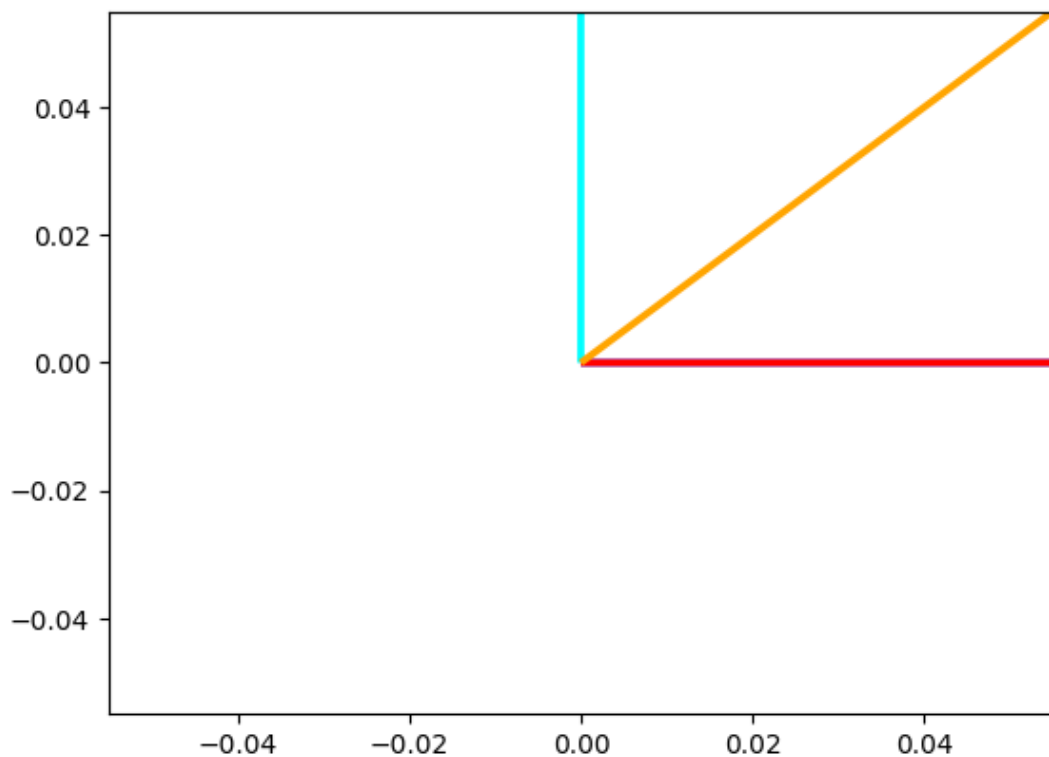


```

In [141]: # Plot states (real vs imaginary parts)
plt.quiver(0,0,a[0].real,a[0].imag, angles='xy', scale_units='xy', scale=1, color='blue', label='|a>')
plt.quiver(0,0,a[1].real,a[1].imag, angles='xy', scale_units='xy', scale=1, color='cyan', label='|a>')
plt.quiver(0,0,b[0].real,b[0].imag, angles='xy', scale_units='xy', scale=1, color='red', label='|b>')
plt.quiver(0,0,b[1].real,b[1].imag, angles='xy', scale_units='xy', scale=1, color='orange', label='|b>')

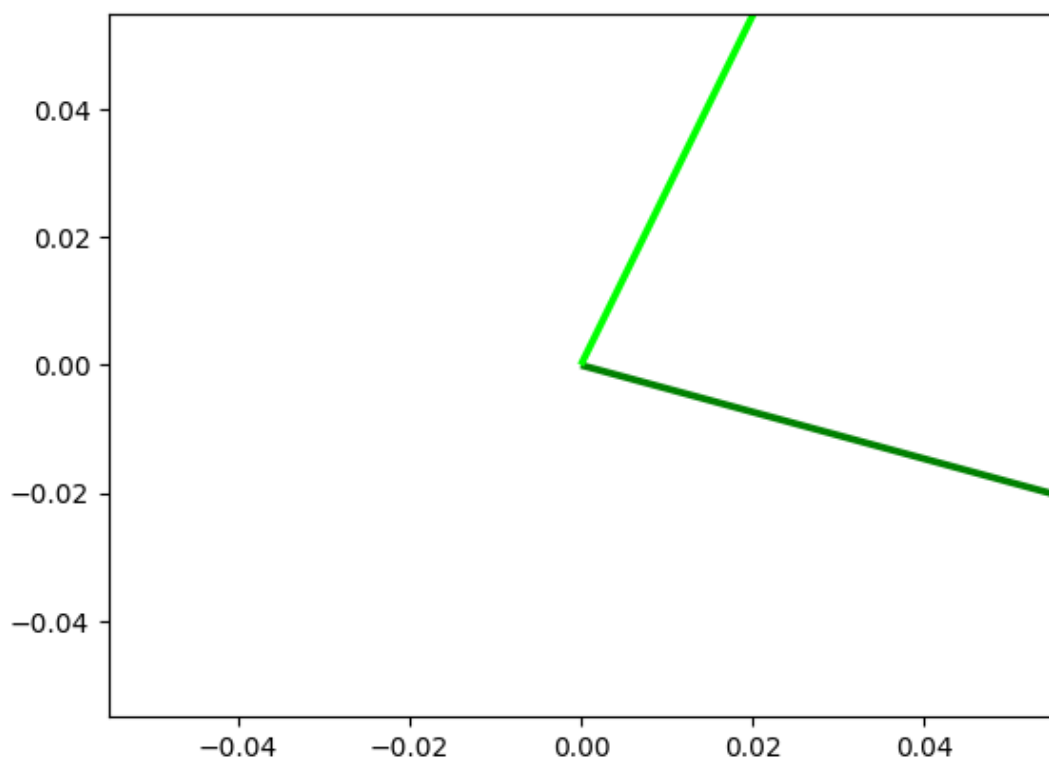
```

Out[141]: <matplotlib.quiver.Quiver at 0x224ac5465a0>



In [140... *# Projection of |b> onto |a> (real vs imaginary)*  
`plt.quiver(0,0,b_proj_on_a[0].real,b_proj_on_a[0].imag, angles='xy', scale_units='xy',`  
`plt.quiver(0,0,b_proj_on_a[1].real,b_proj_on_a[1].imag, angles='xy', scale_units='xy')`

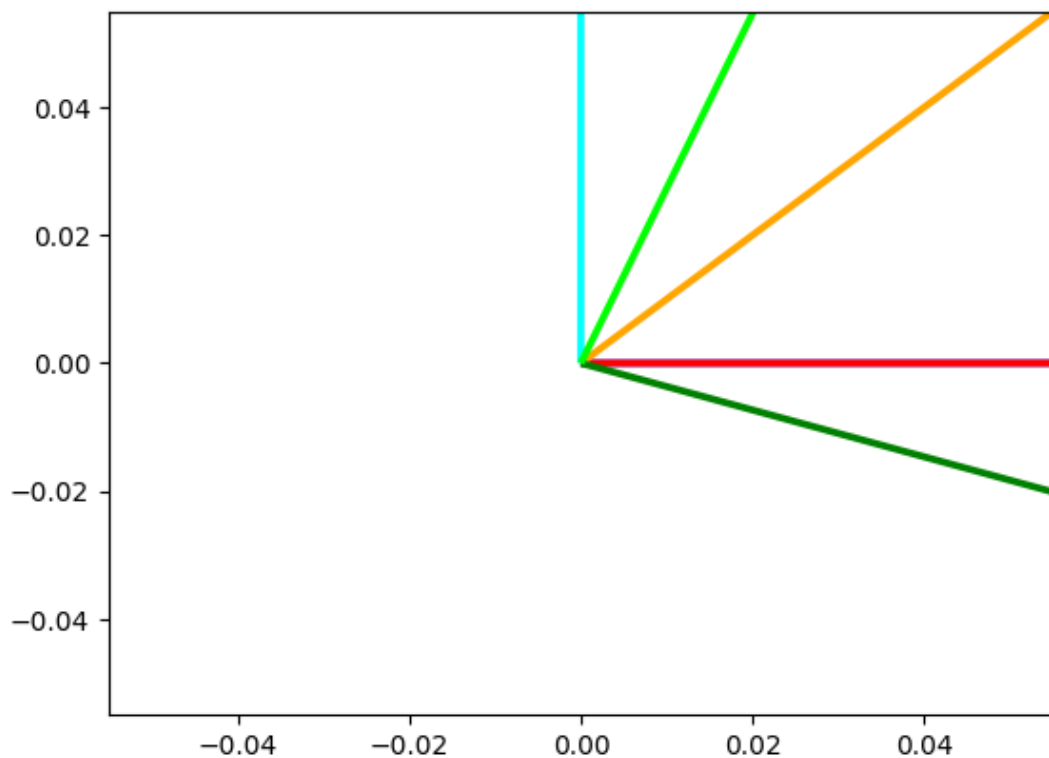
Out[140... <matplotlib.quiver.Quiver at 0x224acae1970>



In [139... *# Plot states (real vs imaginary parts)*  
`plt.quiver(0,0,a[0].real,a[0].imag, angles='xy', scale_units='xy', scale=1, color='bl`  
`plt.quiver(0,0,a[1].real,a[1].imag, angles='xy', scale_units='xy', scale=1, color='cy`  
`plt.quiver(0,0,b[0].real,b[0].imag, angles='xy', scale_units='xy', scale=1, color='re`  
`plt.quiver(0,0,b[1].real,b[1].imag, angles='xy', scale_units='xy', scale=1, color='or`  
  
*# Projection of |b> onto |a> (real vs imaginary)*

```
plt.quiver(0,0,b_proj_on_a[0].real,b_proj_on_a[0].imag, angles='xy', scale_units='xy')
plt.quiver(0,0,b_proj_on_a[1].real,b_proj_on_a[1].imag, angles='xy', scale_units='xy')
```

Out[139... <matplotlib.quiver.Quiver at 0x224ac4b9970>



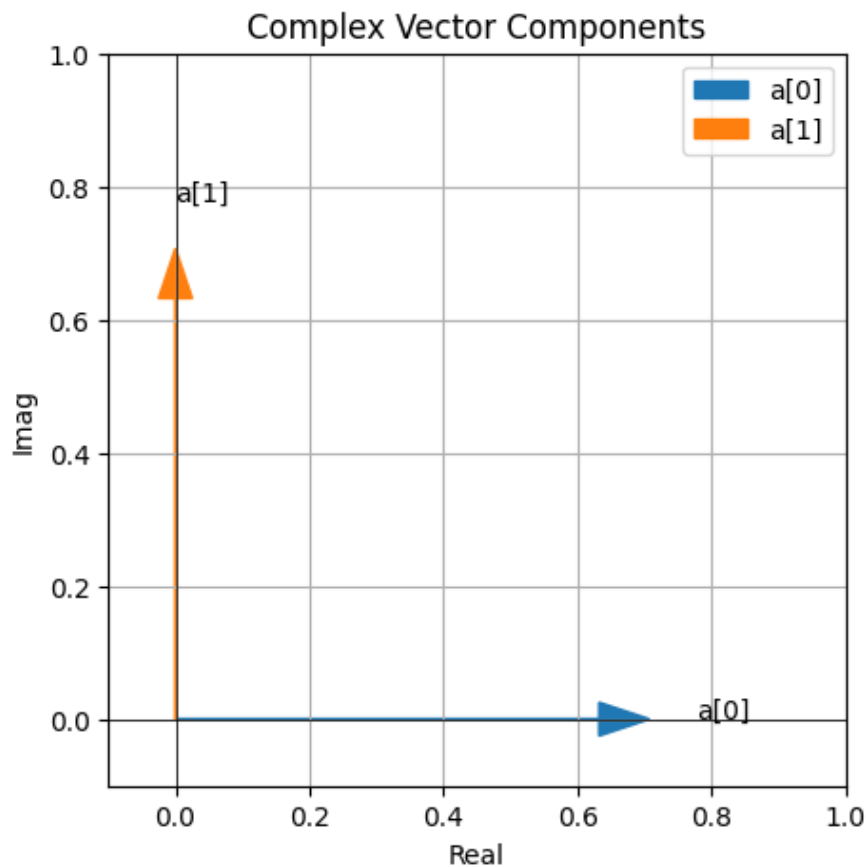
In [ ]:

```
In [124... import matplotlib.pyplot as plt
import numpy as np

# Define the vector
a = np.array([1/np.sqrt(2), 1j/np.sqrt(2)])

# Plot the complex components
fig, ax = plt.subplots(figsize=(5,5))
for i, val in enumerate(a):
    ax.arrow(0, 0, val.real, val.imag, head_width=0.05, length_includes_head=True, color='red')
    ax.text(val.real*1.1, val.imag*1.1, f"a[{i}]")

# Axes and grid
ax.set_xlim(-0.1, 1)
ax.set_ylim(-0.1, 1)
ax.axhline(0, color='black', linewidth=0.5)
ax.axvline(0, color='black', linewidth=0.5)
ax.set_xlabel('Real')
ax.set_ylabel('Imag')
ax.set_title('Complex Vector Components')
ax.grid(True)
ax.legend()
plt.show()
```



In [125...

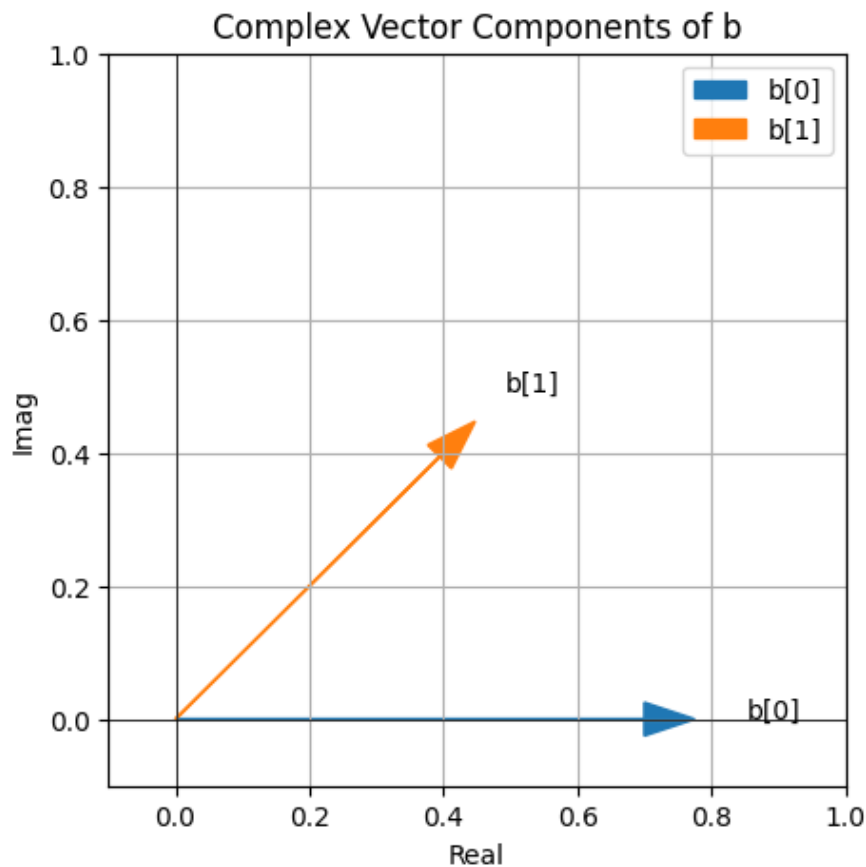
```
import matplotlib.pyplot as plt
import numpy as np

# Define the vector
b = np.array([np.sqrt(0.6), np.sqrt(0.4) * np.exp(1j * np.pi / 4)])

# Plot the complex components
fig, ax = plt.subplots(figsize=(5,5))
for i, val in enumerate(b):
    ax.arrow(0, 0, val.real, val.imag, head_width=0.05, length_includes_head=True, color='black')
    ax.text(val.real*1.1, val.imag*1.1, f"b[{i}]")

# Axes and grid
ax.set_xlim(-0.1, 1)
ax.set_ylim(-0.1, 1)
ax.axhline(0, color='black', linewidth=0.5)
ax.axvline(0, color='black', linewidth=0.5)
ax.set_xlabel('Real')
ax.set_ylabel('Imag')
ax.set_title('Complex Vector Components of b')
ax.grid(True)
ax.legend()
plt.show()
```





```
In [ ]: a = np.array([2+2j, 1-1j])
print(a)
print(np.linalg.norm(a)) # ≈ 3.162
a_normalized = a / np.linalg.norm(a)
print(np.linalg.norm(a_normalized)) # = 1
```

```
In [ ]: import numpy as np
import matplotlib.pyplot as plt

# Example vectors (already normalized if needed)
a = np.array([1/np.sqrt(2), 1j/np.sqrt(2)])
b = np.array([np.sqrt(0.6), np.sqrt(0.4) * np.exp(1j * np.pi / 4)])

# Normalize vectors
a = a / np.linalg.norm(a)
b = b / np.linalg.norm(b)

# Compute projection of b onto a
b_proj_on_a = np.vdot(a, b) * a # a† b * a

# Plot the vectors
fig, ax = plt.subplots(figsize=(6,6))

# Original vectors
ax.arrow(0, 0, a[0].real, a[0].imag, head_width=0.05, color='C0', label='a[0]')
ax.arrow(0, 0, a[1].real, a[1].imag, head_width=0.05, color='C1', label='a[1]')
ax.arrow(0, 0, b[0].real, b[0].imag, head_width=0.05, color='C2', label='b[0]')
ax.arrow(0, 0, b[1].real, b[1].imag, head_width=0.05, color='C3', label='b[1]')

# Projection vector (same dimension as a)
ax.arrow(0, 0, b_proj_on_a[0].real, b_proj_on_a[0].imag, head_width=0.05, color='r',
ax.arrow(0, 0, b_proj_on_a[1].real, b_proj_on_a[1].imag, head_width=0.05, color='r',

# Axes
```

```

ax.axhline(0, color='black', linewidth=0.5)
ax.axvline(0, color='black', linewidth=0.5)
ax.set_xlabel('Real')
ax.set_ylabel('Imag')
ax.set_title('Projection of b onto a in Complex Plane')
ax.set_xlim(-0.2, 1)
ax.set_ylim(-0.2, 1)
ax.grid(True)
ax.legend()
plt.show()

```

```

In [ ]: import numpy as np

# Example normalized vectors
a = np.array([1/np.sqrt(2), 1j/np.sqrt(2)])
b = np.array([np.sqrt(0.6), np.sqrt(0.4) * np.exp(1j * np.pi / 4)])

# Normalize just to be safe
a = a / np.linalg.norm(a)
b = b / np.linalg.norm(b)

# Inner product (overlap)
X = np.vdot(a, b) # a† b

# Example probabilities/weights
q0 = 0.5
q1 = 0.5

# Construct Gs
Gs = np.array([[-q0, -np.sqrt(q0*q1)*X],
               [np.sqrt(q0*q1)*X.conjugate(), q1]])

print("G_s =\n", Gs)

# Check Hermitian property
is_hermitian = np.allclose(Gs, Gs.conj().T)
print("\nIs G_s Hermitian?", is_hermitian)

# Eigenvalues
eigvals = np.linalg.eigvals(Gs)
print("\nEigenvalues of G_s:", eigvals)

```

```

In [ ]:

```