

1. a) A:  $y_n = |x_{n-1} + x_{n+1}|$

b:  $y_n = \frac{1}{2}(x_{2n} + x_{2n+1})$

c:  $y_n = \frac{3x_{n-1} + x_{n-2}}{x_{n-3}}$

d:  $y_n = \prod_{i=0}^8 x_{n-i}$

e:  $y_n = \sum_{i=-\infty}^{\infty} x_i \delta_{i-n+2} = x_{n-2}$

f:  $y_n = x_n \cdot e^{n/14}$

g:  $y_n = x_n \cdot u_n$

h:  $y_n = x_n + \cos(0.7\pi n)$

c) Causal Systems

→ C; D; E; F; G; H.

Since they only depend on  $x_n, x_{n+1}, x_{n-2}, \dots$

d) Memory less Systems

F; G; H

Since they only depend on  $x_n$ .

a) Linear Systems

B; E; F; G; H.

Suppose the system is T and we have  $\{y_i\} = T\{x_i\}$  &  
 $\{y'_i\} = T\{x'_i\}$

if  $T\{ax_i + bx'_i\} = a\{y_i\} + b\{y'_i\}$  then system T is linear.

This doesn't hold for multiplication and division by samples like in C & D.

B may be linear depending on the input i.e. if both  $\{x_i\}$  &  $\{x'_i\}$  are monotonically increasing or decreasing

Q. b) Time Invariant System

A; B; C; D; E; ~~F; G~~

2.) Using the Polynomial Representation of a ~~series~~ Sequence

Let  $\{a_n\}$  be the ~~the~~ and  $\{b_n\}$  be the sequences with finite non-zero values.

For convenience let  $a_0 \neq 0$  &  $b_0 \neq 0$  i.e. the first non-zero position for both is 0. Following from this, last non-zero positions are  $a_{m-1} \neq 0$  &  $b_{l-1} \neq 0$ .

Define Polynomials  $A(v)$  &  $B(v)$  as

$$A(v) = \sum_{i=0}^{m-1} a_i v^i \quad \&$$

$$B(v) = \sum_{j=0}^{l-1} b_j v^j$$

Multiplying the polynomials to convolve the two series

$$\begin{aligned} C(v) &= A(v) \cdot B(v) \\ &= \left( \sum_{i=0}^{m-1} a_i v^i \right) \cdot \left( \sum_{j=0}^{l-1} b_j v^j \right) \end{aligned}$$

Clearly, this will be of the form.

$$C(v) = \sum_{i=0}^{m+l-2} c_i v^i$$

i.e. the highest power (exponent) will be  $(v^{m-1})(v^{l-1}) = v^{m+l-2}$   
and the smallest " " " "  $(v^0)(v^0) = v^0$ .

Thus the length will be  $(m+l-2) - 0 + 1 = \underline{\underline{m+l-1}}$

3. a) Consider a sine wave sampled at twice the frequency.  
 $\{a_n\} = \{\dots, 0, 1, 0, -1, \dots\}$  (an infinite sequence)  
 &

$$\{b_n\} = \{0, x, y, x, y\}$$

Note: Trivial Proof later on.

Representing the sequence a polynomial.

$$A(v) = \sum_{i=-\infty}^{\infty} a_i v^i$$

since  $a_i$  repeats.

$$\begin{aligned} A(v) &= \sum_{i=-\infty}^{\infty} v^{4i} (0 \cdot v^0 + 1 \cdot v^1 + 0 \cdot v^2 - 1 \cdot v^3) \\ &= \sum_{i=-\infty}^{\infty} v^{4i} (v - v^3) \end{aligned}$$

&  $B(v) = xv + yv^2 + xv^3 + yv^4$

Let  $\{c_n\} = \{a_n\} * \{b_n\}$  and we get polynomial  $C(v)$  from  $\{c_n\}$ .  
 then

$$\begin{aligned} C(v) &= A(v) \cdot B(v) \\ &= (xv + yv^2 + xv^3 + yv^4) \cdot \left( \sum_{i=-\infty}^{\infty} v^{4i} (v - v^3) \right) \end{aligned}$$

$\forall i \in \mathbb{Z}$ .

$$\begin{aligned} c_{4i} &= \text{coeff } v^{4i} \text{ in } [(xv + yv^2 + xv^3 + yv^4) \cdot v^{4i-4} \cdot (v - v^3)] \\ &\Rightarrow (xv + yv^2 + xv^3 + yv^4) \cdot (v^{4i-3} - v^{4i-1}) \\ &\Rightarrow (xv^{4i} - xv^{4i} + \dots) \\ &\Rightarrow (0 \cdot v^{4i} + \dots) \\ &= 0 \end{aligned}$$

$$\begin{aligned} \text{similarly for } c_{4i+1} &= \text{coeff of } v^{4i+1} \text{ in } [(xv + yv^2 + xv^3 + yv^4) \cdot (v^{4i-3} - v^{4i-1})] \\ &\Rightarrow -yv^2 \cdot v^{4i-1} + yv^4 \cdot v^{4i-3} \\ &\Rightarrow 0 \cdot v^{4i+1} \\ &= 0. \end{aligned}$$

for  $C_{4i+2}$  = coeff of  $v^{4i+2}$  in

$$[(xv + yv^2 + xv^3 + yv^4) \cdot (v^{4i-3} - v^{4i-1}) + (xv + yv^2 + xv^3 + yv^4) \cdot (v^{4i+1} - v^{4i+3})]$$

$$\Rightarrow xv^3(-v^{4i-1}) + xv \cdot v^{4i+1}$$

$$\Rightarrow 0 \cdot v^{4i+2}$$

$$= 0$$

Similarly for  $C_{4i+3} \Rightarrow$  coeff of  $v^{4i+3}$  in

$$[(xv + yv^2 + xv^3 + yv^4)(v^{4i-3} - v^{4i-1}) + (xv + yv^2 + xv^3 + yv^4)(v^{4i+1} - v^{4i+3})]$$

$$\Rightarrow yv^4(-v^{4i-1}) + yv^2 \cdot v^{4i+1}$$

$$\Rightarrow 0 \cdot v^{4i+3}$$

Thus after convolution  $\forall i \in \mathbb{Z}$ .  $C_{4i}, C_{4i+1}, C_{4i+2}$  &  $C_{4i+3} = 0$   
and therefore  $\{C_n\}$  is all zeros.

—x—

Trivial Proof

$\{a_n\}$       0 1 0 -1 0 1

Reverse  $\{b_n\}$       0 y x y x 0

$0 + y + 0 + (-y) + 0 + 0 = 0$

$\{a_n\}$       0 -1 0 1 0 -1

Reverse  $\{b_n\}$       0 y x y x 0

$0 + (-y) + 0 + y + 0 + 0 = 0$

0 1 0 -1 0 1 0

0 y x y x 0

$0 + 0 + (-x) + 0 + x + 0 = 0$

-1 0 1 0 -1 0

0 y x y x 0

$0 + y + x + 0 + (-x) + 0 = 0$

4) a) when we are sampling at frequency  $f_s$ , we can only effectively extract frequencies in the interval  $n \frac{f_s}{2} < f < (n+1) \frac{f_s}{2}$  for all natural No.  $n$ , and this is done to prevent aliasing.

Therefore, for the sampling frequencies provides (16 kHz, 32 kHz & 48 kHz) we want 23 kHz & 25 kHz to lie in the same interval.

This is true for only 32 kHz for the interval for  $n=1$ ,  $f_s = 32000$ ,  $\Rightarrow [16 \text{ kHz}, < f < 32 \text{ kHz}]$

b) Intuitively, a DFT is sampling the DTFT at  $\frac{6f_s}{n}$ ,

$0 \frac{f_s}{n}, 1 \frac{f_s}{n}, 2 \frac{f_s}{n} \dots \frac{f_s}{2}$  and these correspond to  $x_0, x_1, x_2 \dots x_{n/2}$   
and  $|x_k| = |x_{n-k}|$

~~Rem~~ Note:  $f_s = 160 \text{ kHz}$  &  $n = 512$

$\therefore$  for the 23 kHz whistle

$|x_{74}|$  should have max value as it corresponds to  $74 \cdot \frac{160,000}{512} = 23125.0 \text{ Hz}$ .

This is closest to the actual peak at 23 kHz.

& for 25 kHz whistle

$|x_{80}|$  would have the peak & in this case

$\frac{80}{512} \cdot 160000 = 25 \text{ kHz}$  and would be equal to the actual peak.

c) The FFT which is a faster variant of the Discrete Fourier Transform (DFT) simply samples the Discrete Time Fourier Transform (DTFT) at  $0 \cdot \frac{f_s}{n}, 1 \cdot \frac{f_s}{n} \dots \frac{f_s}{2}$  frequencies, and these correspond to  $X_0, X_1, \dots, X_{N/2}$ .

The DTFT has a peak where ever the true frequency lies in this case at 23 kHz & 25 kHz respectively. However ~~start to~~ in the case of 23 kHz we aren't quite able to hit it exactly and the ~~best~~ closest we get is  $|X_{74}|$  corresponding to 23125 Hz. Thus the value is lower than that we see at  $|X_{80}|$  for 25 kHz where we hit the peak exactly.

There is a big difference in the value mainly because the ~~gr~~ gradient on either side is quite steep causing values to drop significantly if you move in either direction.

Thus, even if both whistles have equal sound-pressure amplitude and the microphone is equally sensitive, still 25 kHz tone will show higher peak.

d) In order to reduce the relative amplitude difference in the FFT peaks of the two tones we can apply a hann window  $\{ w_i = \frac{1 - \cos(2\pi \frac{i}{n-1})}{2} \}$ , where we ~~to~~ multiply

every input item  $x_i$  with  $w_i$  which results in shorter peaks however, the peaks are flatter and thus ~~if~~ even if we don't hit the ~~peak value~~ correct frequency we can still get close to the actual peak value.

4)e)  $Q$  is defined as <sup>a</sup>the ratio of ~~the~~ quantity that is the ratio of the center (peak) frequency ( $f_0$ ) to the  $-3$  dB bandwidth  $bw$ ,

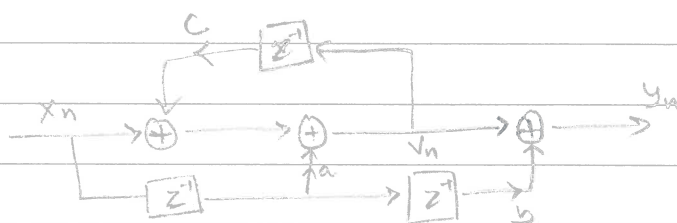
$$Q = \frac{f_0}{bw}$$

Using  $Q = 30$ ,  $f_s = 160 \text{ KHz}$ ,  $f_0 = 25 \text{ KHz}$  we get a 2nd

order peak filter with zeros at  $[1, -1]$  & poles at  $0.5466 \pm j 0.8179$ , in the z-transform.

$$H(z) = \frac{0.0161(1 - z^{-2})}{1 - 1.093z^{-1} + 0.9677z^{-2}}$$

5)



$$v_n = x_n + a x_{n-1} + C v_{n-1}$$

Applying Z transform.

$$V(z) = X(z) + a z^{-1} X(z) + C z^{-1} V(z)$$

$$\Rightarrow V(z)(1 - C z^{-1}) = X(z)(1 + a z^{-1})$$

$$\Rightarrow \frac{V(z)}{X(z)} = \frac{1 + a z^{-1}}{1 - C z^{-1}} = \frac{z + a}{z - C} \quad (*)$$

$$y_n = v_n + b x_{n-2}$$

Applying Z-transform.

$$Y(z) = V(z) + b z^{-2} X(z)$$

$$\Rightarrow \frac{Y(z)}{X(z)} = \frac{V(z)}{X(z)} + b z^{-2}$$

$$H(z) = \frac{Y(z)}{X(z)} = H(z) = \frac{z+a}{z-c} + bz^{-2}$$

[from (\*) & def  
of  $H(z) = \frac{Y(z)}{X(z)}$ ]

$$\Rightarrow H(z) = bz^{-2} + \frac{1+az^{-1}}{1-cz^{-1}}$$

$$= \frac{1+az^{-1} + bz^{-2} - bcz^{-3}}{1-cz^{-1}}$$

→

$$h: \{x_n\} \rightarrow \{y_n\} \quad \text{with} \quad y_n + y_{n-1} = x_n - x_{n-4}$$

6) a) Using the polynomial representation of sequences.

$$\text{let } X(v) = \sum_{n=-\infty}^{\infty} x_n v^n \quad \text{then } \{x_{n-1}\} \equiv X(v) \cdot v$$

$$\& \{s_n\} \equiv 1. \& \{s_{n-4}\} = v^4$$

$$\therefore \text{with } h[s_n] \Rightarrow y_n + y_{n-1} = s_n - s_{n-4}$$

let  $Y(v)$  be polynomial for  $\{y_n\}$ .

then

$$Y(v) + vY(v) = 1 - v^4$$

$$\Rightarrow Y(v) + vY(v) = 1 - v^4$$

$$\Rightarrow Y(v) = \frac{1-v^4}{1+v} = -\left(\frac{v^4-1}{v+1}\right)$$

$$= -\frac{(v^2+1)(v-1)(v+1)}{(v+1)}$$

$$= 1-v+v^2-v^3$$

$$\therefore y_n = s_n - s_{n-1} + s_{n-2} - s_{n-3}$$

$$y_n = \begin{cases} 0, & n < 0 \\ 1, & n = 0 \\ -1, & n = 1 \\ 1, & n = 2 \\ -1, & n = 3 \\ 0, & n > 3 \end{cases}$$

$$y_n = \begin{cases} 0, & n < 0 \\ 1, & n = 0 \\ -1, & n = 1 \\ 1, & n = 2 \\ -1, & n = 3 \\ 0, & n > 3 \end{cases}$$

This is the impulse response



6) b) let  $U(v)$  be polynomial repr for  $U_n = \begin{cases} 0, & n < 0 \\ 1, & n \geq 0 \end{cases}$

$$\therefore U(v) = 1 + v + v^2 + \dots \\ = \sum_{n=0}^{\infty} v^n$$

applying  $\{u_n\}$  to  $h \Rightarrow y_n + y_{n-1} = u_n - u_{n-4}$

let  $Y(v)$  be the polynomial representing the output ~~seq~~ seq  
then

$$Y(v) + v(Y(v)) = U(v) - v^4 U(v) \\ \Rightarrow Y(v)(1+v) = U(v)(1-v^4) \\ \Rightarrow Y(v) = U(v) \cdot \left( \frac{1-v^4}{1+v} \right)$$

$$= U(v) \cdot (1 - v + v^2 - v^3) \\ = \sum_{n=0}^{\infty} v^n \cdot (1 - v + v^2 - v^3)$$

$$= \sum_{n=0}^{\infty} v^n - \sum_{n=0}^{\infty} v^{n+1} + \sum_{n=0}^{\infty} v^{n+2} - \sum_{n=0}^{\infty} v^{n+3} \\ = 1 + \cancel{\sum_{n=0}^{\infty} v^{n+1}} - \cancel{\sum_{n=0}^{\infty} v^{n+1}} + \cancel{v^2} + \sum_{n=0}^{\infty} v^{n+2} - \cancel{\sum_{n=0}^{\infty} v^{n+3}} \\ = 1 + v^{n+2} \\ \neq 0$$

$$\sum_{n=0}^{\infty} v^{i+n} = v^i + v^{i+1} + \dots \\ = v^i + \sum_{n=0}^{\infty} v^{i+1+n}$$

$$\therefore \{y_n\} = \delta_n + \delta_{n-2}$$

or  $y_n = \begin{cases} 0, & n < 0 \\ 1, & n = 0 \\ 0, & n = 1 \\ 1, & n = 2 \\ 0, & n \geq 2 \end{cases}$  The step response.

$$c) H(z) = \frac{Y(z)}{X(z)}$$

given  $y_n + y_{n-1} = x_n - x_{n-4}$ .

applying Z transform.

$$Y(z) + z^{-1} Y(z) = X(z) - z^{-4} X(z)$$

$$\Rightarrow Y(z) \cdot (1 + z^{-1}) = X(z)(1 - z^{-4})$$

$$\Rightarrow \frac{Y(z)}{X(z)} = H(z) = \frac{1 - z^{-4}}{1 + z^{-1}}$$

$$d) H(z) = \frac{(1 + z^{-2})(1 - z^{-1})(1 + z^{-1})}{(1 + z^{-1})}$$

we can eliminate the factor  $(1 + z^{-1})$

$$H(z) = (1 + z^{-2})(1 - z^{-1})$$

This means that the system ~~has~~ overlapping zeros & pole value is ~~of~~ defin.

$H(z)$  is no longer undefined at  $z = -1$ , since we eliminated the factors.

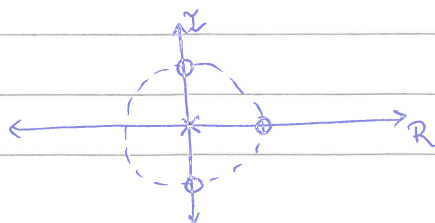
e) ~~H~~

$$e) H(z) = (1 + z^2)(1 - z^{-1})$$

$$= (1 + jz^{-1})(1 - jz^{-1})(1 - z^{-1})$$

$$= (1 + jz^{-1})(1 - jz^{-1})(1 - z^{-1})$$

Thus  $H(z)$  has zero at ~~(1, ±j)~~ on the unit circle and 3 poles at  $z = 0$ .



f) we have zeros at  $\omega = \frac{\pi}{2}, 0, -\frac{\pi}{2}$  for

$\therefore$  any DC value will be rejected  $\hookrightarrow$ .

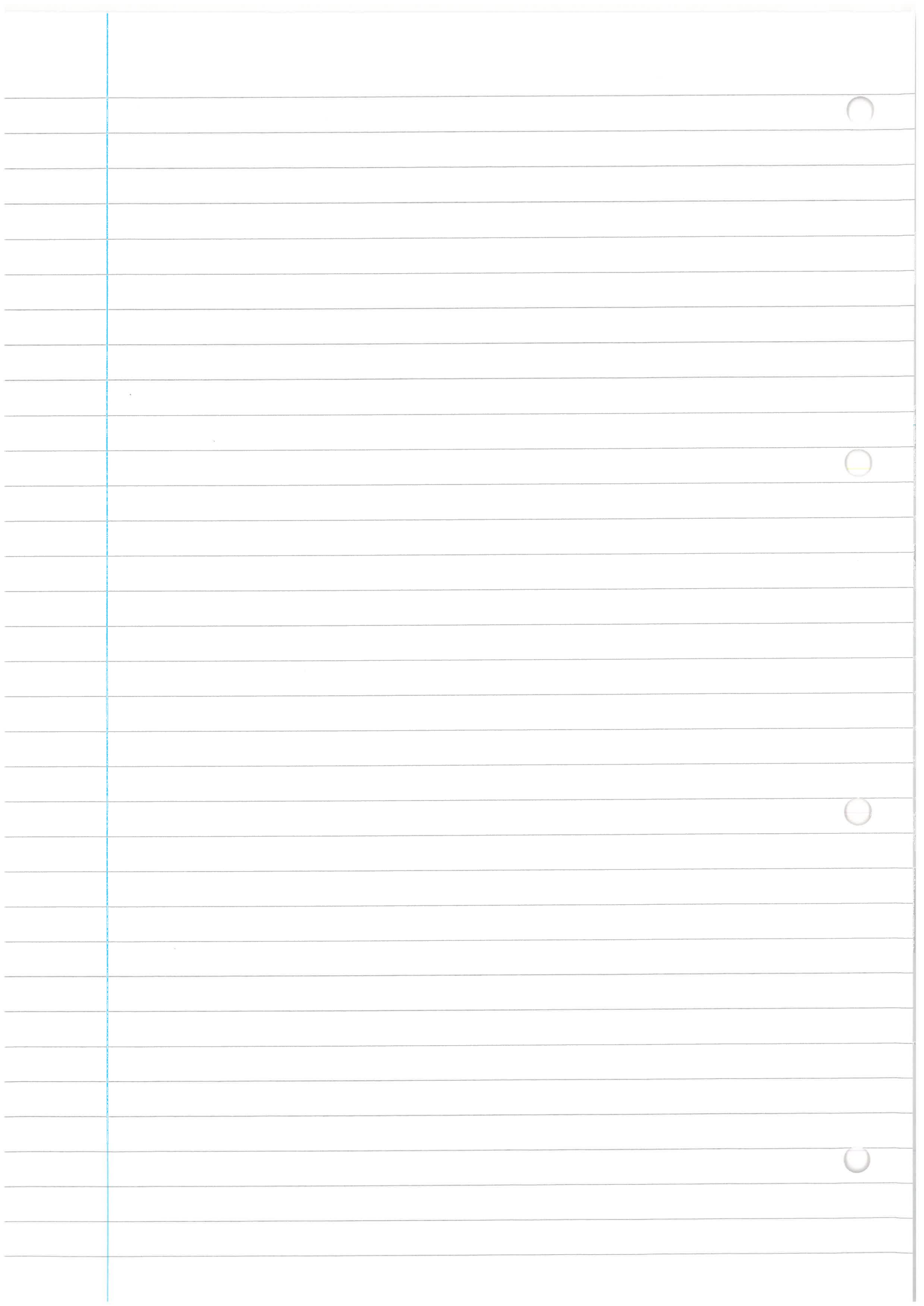
$$\theta = \frac{2\pi f}{f_s} = \frac{\pi}{2} \Rightarrow \frac{2\pi}{8000} f = \frac{\pi}{2} \Rightarrow f = 2000 \text{ Hz}$$

$\hookrightarrow$  2000 Hz freq will be rejected

Trivially we can see that  $H(-1) = 4$

$\therefore$  for  $\frac{2\pi f}{f_s} = \pi$  the amplitude will be quadrupled.

$$\hookrightarrow f = \frac{\pi \cdot 8000}{2\pi} = 4 \text{ kHz.}$$



3) b) No. Not all non-zero LTI systems  $T$  can have an inverse LTI system  $T^{-1}$ . We know that LTI systems being applied to a sequence is ~~akin~~ the same as convolution with its impulse response. i.e. let  $\{a_n\} = T\{s_n\}$  then for any arbitrary sequence  $\{x_n\}$ ,  $T\{x_n\} = \{a_n\} * \{x_n\}$

By this, assume we have an LTI system with impulse response as one of the sequences from part (a).

And let  $\{x_n\}$ , the input, be the other sequence.

As shown before this will result in an all zero sequence which isn't invertible.

Further, the zeros and poles of the LTI system  $T$  & the inverse LTI system  $T^{-1}$  has to be within the Unit Circle else the inverse ~~isn't~~ can't be feasibly built.