Adam Starak

May 16, 2019

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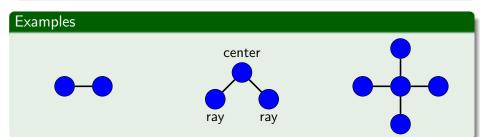




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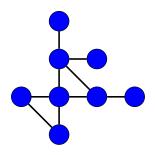
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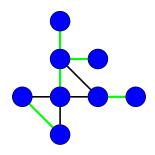


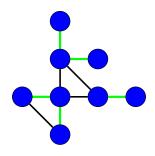
Definition

Given a graph G decide whether it has a Spanning Star Forest.

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Lemma

G contains a Spanning Star Forest if and only if it does not contain any isolated vertices.

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Corollary

Spanning Star Forest problem can be solved in linear time.

Minimal Spanning Star Forest

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Given a pair (G, k) decide whether there exists a Spanning Star Forest of at most \mathbf{k} .

Minimal Spanning Star Forest

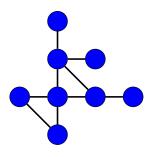
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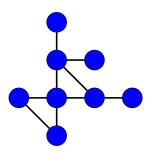
Dominating Set

Given a pair (G, k) find a set $D \subseteq V(G)$ such that $|D| \le k$ and every node is either in D or adjacent to D.

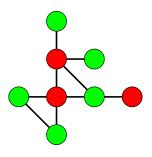
(G,3) for Dominating Set.



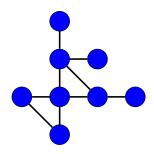
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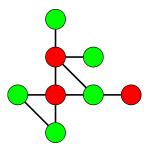
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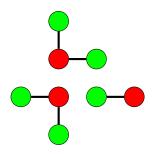
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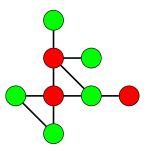
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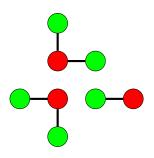
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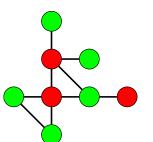
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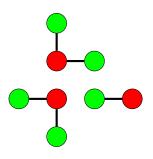
Observation

There is a relationship between:

(G,3) for Dominating Set.



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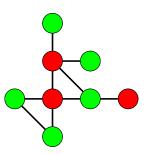


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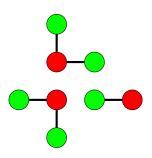
There is a relationship between:

• Centers and dominating vertices.

(G,3) for Dominating Set.



(G,3) for Minimal Spanning Star Forest.



Observation

There is a relationship between:

- Centers and dominating vertices.
- Rays and dominated vertices.

Theorem

Minimal Spanning Star Forest is NP-complete.

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Replace every isolated vertex \mathbf{v} with an isolated edge $(\mathbf{v}, \mathbf{v}')$.

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Reverse reduction

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$$(G', k') = \begin{cases} (G, 0), & \text{if } G \text{ contains an isolated vertex.} \\ (G, k), & \text{otherwise.} \end{cases}$$

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Dominating Set and Minimal Spanning Star Forest are interreductible.

Theorem

Unless SETH fails, there is no algorithm solving Dominating Set in time $\mathcal{O}^*(n^{k-\epsilon})$ for $\epsilon>0$.

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(G, k) - Dominating Set instance.

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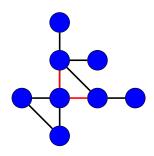
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Contradiction.

Spanning Star Forest Extension Problem

Definition

Given a graph G and a set of **forced edges** $M \subseteq E(G)$, find a Spanning Star Forest S such that $M \subseteq E(S)$.

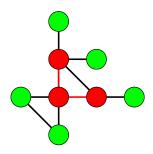


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$$R = V \setminus F$$



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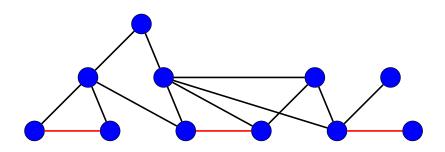
Corollary

After exhaustive application of the R3, M is a matching.

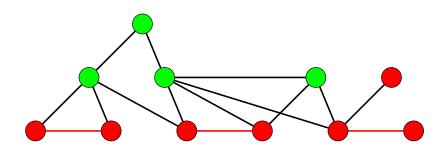
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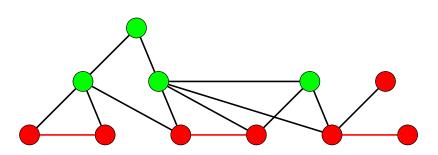
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Corollary

 G_P has always a solution.

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- (R4) Apply $G = G_{NP}$.

Theorem

There exists a reduction from CNF-SAT to SSFE.

 ϕ CNF-formula.

$$(x_1 \lor x_2 \lor \neg x_4) \land (\neg x_1 \lor x_3 \lor \neg x_5) \land (x_4 \lor x_5 \lor \neg x_1)$$

 ϕ CNF-formula.

Variable $x_i \rightarrow \text{vertices } x_i, \neg x_i \text{ and marked edge } (x_i, \neg x_i).$

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Spanning Star Forest Problem





SSFE is NP-complete

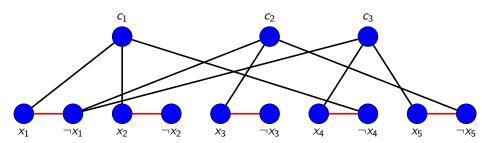
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literal $\neg x_k$ in clause $c_i \rightarrow \mathbf{edge} (\neg x_k, c_i)$.

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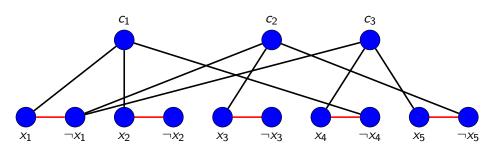
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 ϕ is satisfiable if and only there exists a SSFE.

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Observation

There is a relationship between:

- M and variables.
- R and clauses.

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Construction.

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 $(G', M') \rightarrow \text{Exhaustive application of (R1)-(R5)}.$

 $\phi \rightarrow$ formula of $|{\it M}'|$ variables and $|{\it R}|$ clauses.

Lemma

(G, M) has a SSF $\iff \phi$ is satisfiable.

Proof on the board.

Corollary

Spanning Star Forest Extension and CNF-SAT are interreductible.

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n variables	n marked edges
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Observation 1

Theorems for CNF-SAT paramterized by the number of **variables** can be transferred to Spanning Star Forest Extension parameterized by the number of **marked edges**.

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CNF-SAT	SSFE
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Observation 2

Theorems for CNF-Sat parameterized by the number of **clauses** can be transfered to Spanning Star Forest Extension parameterized by $|\mathbf{R}|$.



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Dominating Set	Minimal SSF
CNF-Sat <i>n</i> variables	SSFE M
CNF-Sat <i>m</i> clauses	SSFE R

Theorem

CNF-Sat with n variables doesn't admit any kernel.

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Consequently, nor does SSFE parameterized by |M|.

Proving nonexistence of a kernel for a problem ${\mathcal P}$

Design an algorithm \mathcal{A} :

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such that:

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Proof on the board.

Theorem

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CNF-Sat parameterized with *m* clauses has a linear kernel.

Consequently, so does SSFE parameterized by |R|.

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Proof on the board.

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$$< k + 2k^2$$
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Dynamic table. dp[t, f] where t is node from a tree decomposition and $f: X_t \to \{true, false\}$ defined as follows:

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$$f(v) = \begin{cases} true, & v \in F \text{ and } v \text{ is a center.} \\ true, & v \in R \text{ and } v \text{ is a part of a Star Tree.} \\ false, & \text{otherwise.} \end{cases}$$

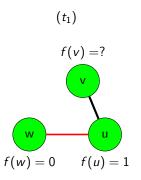
Dynamic table. dp[t, f] where t is node from a tree decomposition and $f: X_t \to \{true, false\}$ defined as follows:

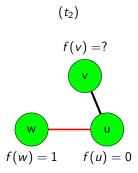
$$f(v) = \begin{cases} true, & v \in F \text{ and } v \text{ is a center.} \\ true, & v \in R \text{ and } v \text{ is a part of a Star Tree.} \\ false, & \text{otherwise.} \end{cases}$$

Assume we have everything finished **except for a join node**.

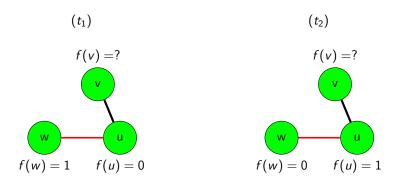
Join nodes t_1 , t_2

Join nodes t_1 , t_2



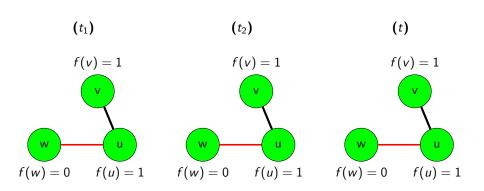


Join nodes t_1 , t_2

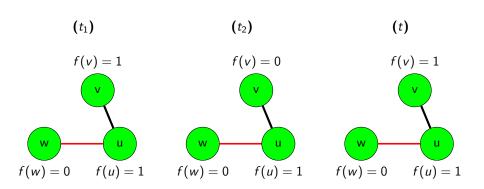


 C_1 = For every vertex $v \in (F \cap X_t)$ it holds $f(v) = f_1(v) = f_2(v)$

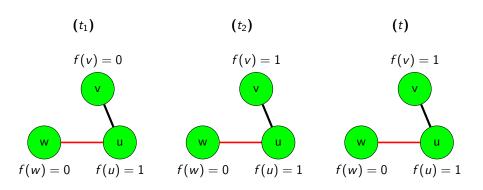
Join nodes t_1 , t_2



Join nodes t_1 , t_2



Join nodes t_1 , t_2



 $C_2 = \text{For all } v \in R \text{ it holds } f(v) = f_1(v) \lor f_2(v).$

$$dp[t,f] = \begin{cases} \bigvee_{f_1,f_2} dp[t_1,f_1] \wedge dp[t_2,f_2], & \text{if } C_1 \text{ and } C_2 \text{ holds.} \\ f_1,f_2 & \text{otherwise.} \end{cases}$$

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Assuming leaf, introduce and forget are easy:

Lower bound

SSFE parameterized by tw(G)

SSFE parameterized by treewidth can be solved in $\mathcal{O}^*(2^{tw(G)})$.

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Lower bound

Assuming SETH, $\mathcal{O}^*(2^{tw(G)})$ is optimal.

Proof on the board.