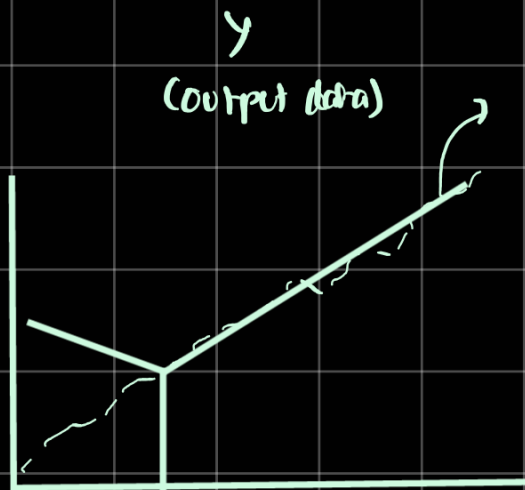


Deep Learning
↓
Supervised Unsupervised Reinforced L (AAs)

unsupervised

reinforced

L
(ACWS)



line that fits
the dots say
 $F(x)$

$$y = mx + c$$

$$f(x) = mx + c$$

where
m, c are
parameters.

Observed values-

$$x_1 \rightarrow y_1$$

$$x_2 \rightarrow y_2$$

$$x_n \rightarrow y_n$$

To find $FC(n) \rightarrow$ the best possible line that describes $FC(n)$

x	y	$F(x)$	y'
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Let $F(u)$ be y'

x_1	y_1	$m x_1 + c$
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n_2	y_2	m_2	ρC
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→ The error we get between the graph and ideal line is $|y - y'|$ → since abs is not differentiable

we take $\frac{d}{dx} (y - y')^2$ as the error.

∴ Error for each corresponding coordinate

$$(x_1, y_1) \rightarrow \frac{d}{dx} (y - y_1')^2$$

$$(x_2, y_2) \rightarrow \frac{d}{dx} (y - y_2')^2$$

⋮

for 'n' such elements

$$\sum_{i=1}^n \frac{d}{dx} (y - y_i')^2$$

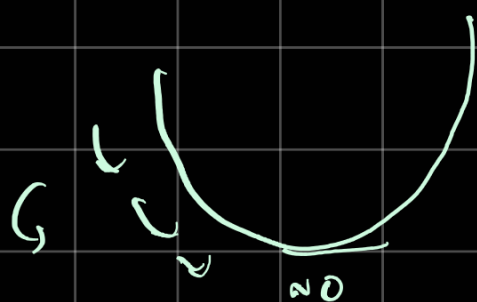
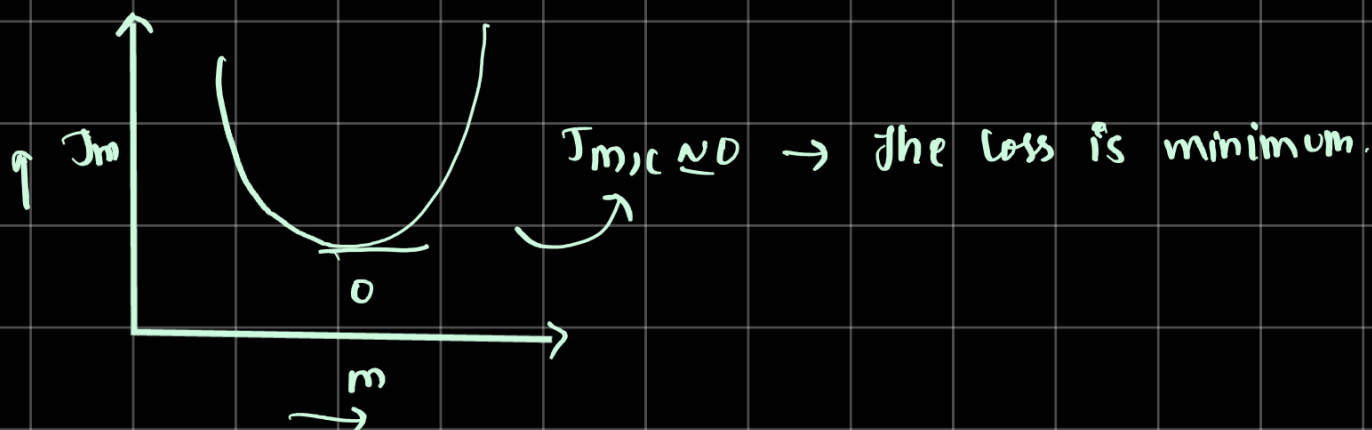
$$\sum_{i=1}^n \text{Error}$$

{ where $\frac{d}{dx} (y - y_i')$ error

Thus, mean squared error is

$$\frac{1}{n} \sum_{i=1}^n \frac{d}{dx} (y - y_i')^2$$

$$\therefore \text{Loss function } J_{m, l}() = \frac{1}{n} \sum_{i=1}^n \frac{d}{dx} (y - y_i')^2$$



Here we are searching
on the curve
through descending
thus, it's called
gradient descent.

→ loss function → multiple parameters

Say $F(x) = y' = mx' + c$
 \downarrow
 $m, c \rightarrow$ parameters.

Thus, we do a partial derivative.

Ex: $J = \frac{1}{2n} \sum_{i=1}^n (y_i - (mx_i + c))^2$

$\frac{\partial J}{\partial m} = ?$

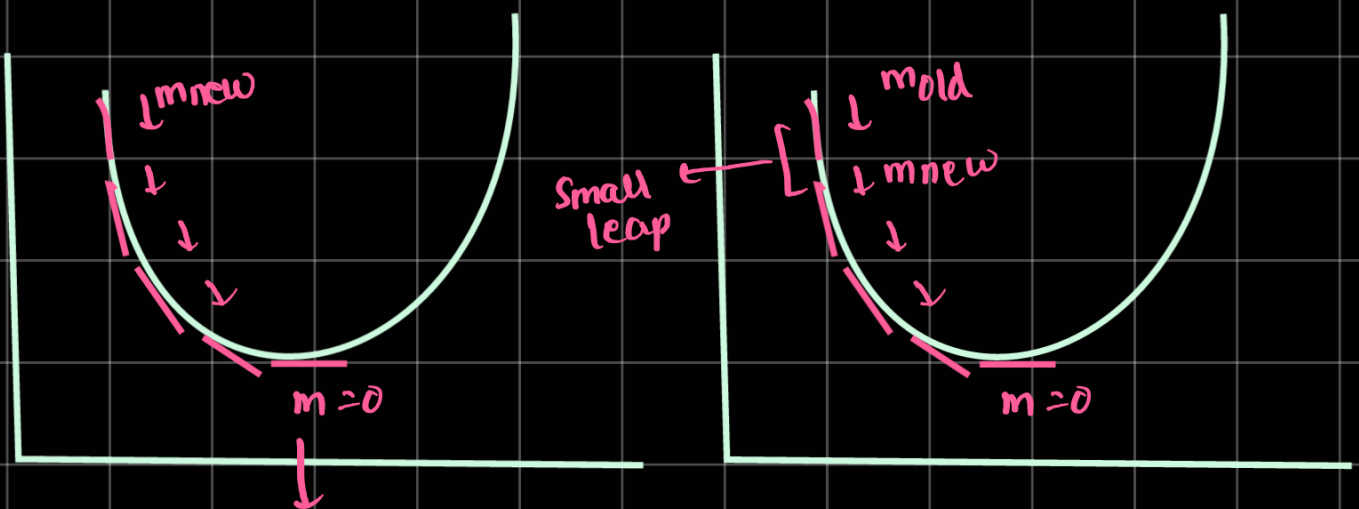
$\frac{\partial J}{\partial c} = ?$

$\frac{\partial J}{\partial m} = \frac{1}{2n} \sum_{i=1}^n 2(y_i - (mx_i + c))(-x_i)$

$$\frac{\partial J}{\partial m} = \frac{1}{n} \sum_{i=1}^n x_i (y_i - (mx_i + c)) (-x_i)$$

$$\hookrightarrow m_{\text{new}} = m_{\text{old}} - \left[\frac{\partial J}{\partial m} \right] \eta \quad \leftarrow \text{Gradient descent.}$$

$$c_{\text{new}} = c_{\text{old}} - \left[\frac{\partial J}{\partial c} \right] \eta$$



→ Here we are traversing the curve till we reach $m=0$

→ For which we are optimising the direction → through sign of slope
length of traversal → by finding optimum constant through partial diff

↳ Since it is difficult to calculate every possible

Gradient
descent

↓
stochastic
G.D

↘ ~~Batch~~ ^{Batch}
G.D → Random
Batch

↓
Each batch

is representative
of entire data

↓
4, 16, 32, 64, 52,
1024

→ $x_1, x_2, x_3, \dots, x_n$

$\theta_0, \theta_1 x_1, \theta_2 x_2, \dots, \theta_n x_n$

↳ feature engineering

Loss function → how far mathematically is my function
from my ideal value.