

Anomaly detection using R

MULTIVARIATE GAUSSIAN DISTRIBUTION BASED ANOMALY DETECT

유 충 현

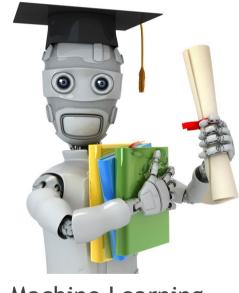
KRUG

AGENDA

- Problem motivation
- Gaussian distribution
- Algorithm
- Anomaly detection using the multivariate Gaussian distribution
- Developing and evaluating an anomaly detection system
- anomalyDensityEastimation class

일러두기

- 스라이드 및 이론 설명
 - Coursera 강좌 중 Machine Learning
- 구현 및 예제
 - S4를 적용하여 구현함



Machine Learning

Detection function / Visualization function

Anomaly detection example

Aircraft engine features:

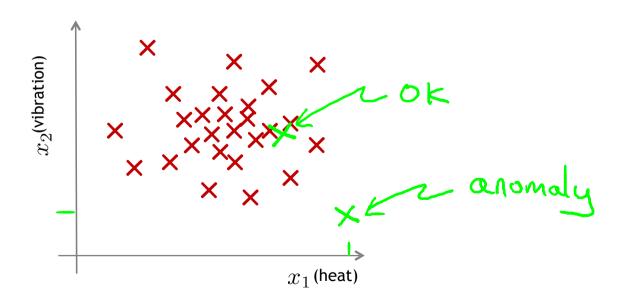
 x_1 = heat generated

 x_2 = vibration intensity

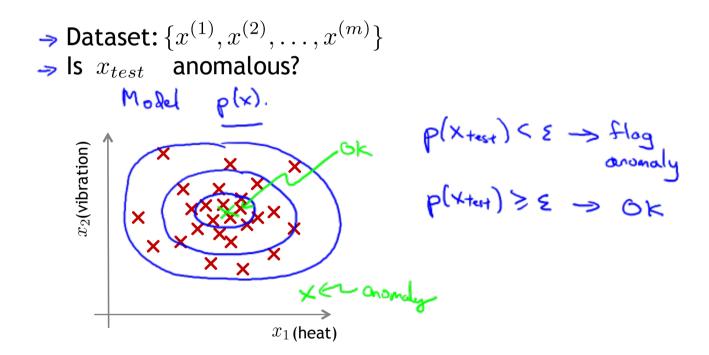
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Dataset: $\{x^{(1)}, x^{(2)}, \dots, x^{(m)}\}$

New engine: x_{test}



Density estimation



Anomaly detection example

Fraud detection:

```
x^{(i)} = features of user i 's activities Model p(x) from data. Identify unusual users by checking which have p(x)<\varepsilon
```

Manufacturing

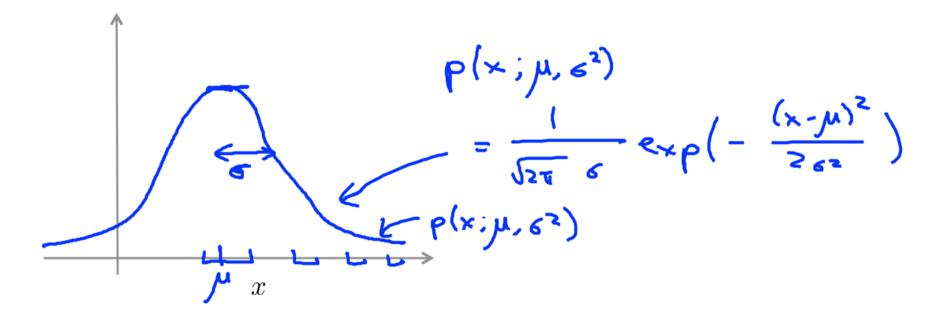
```
Monitoring computers in a data center. x^{(i)}= features of machine i
x^{(i)}= memory use, x_2 = number of disk accesses/sec, x_3= CPU load, x_4= CPU load/network traffic.
```

Gaussian(Normal) distribution

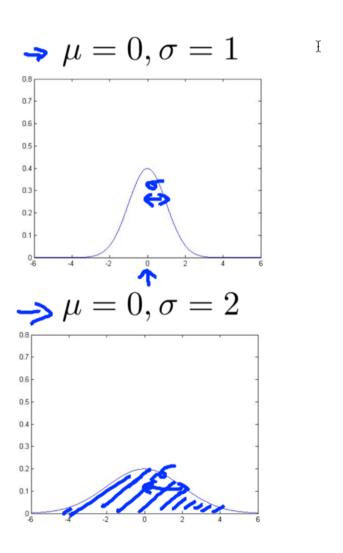
Gaussian (Normal) distribution

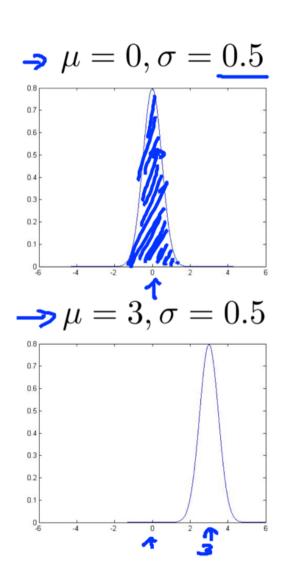
Say $x \in \mathbb{R}$. If x is a distributed Gaussian with mean μ , variance $\underline{\sigma}^2$.

$$\times \sim \mathcal{N}(M.6^2)$$
 5 standard deviation

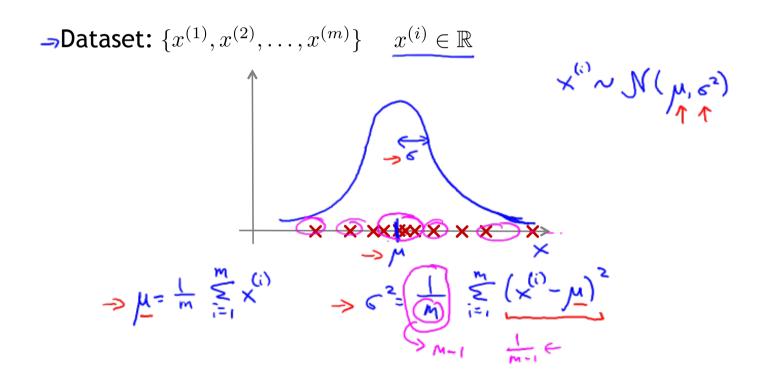


Gaussian distribution example





Parameter estimation



Density estimation

```
Training set: \{x^{(1)}, \dots, x^{(m)}\}

Each example is x \in \mathbb{R}^n

\Rightarrow p(x)
= p(x_1; \mu_1, \sigma_1^2) p(x_2; \mu_2, \sigma_2^2) p(x_3; \mu_3, \sigma_2^2) \cdots p(x_n; \mu_n, \sigma_n^2)
= p(x_1; \mu_1, \sigma_1^2) p(x_2; \mu_2, \sigma_2^2) p(x_3; \mu_3, \sigma_2^2) \cdots p(x_n; \mu_n, \sigma_n^2)
= \prod_{i=1}^n p(x_i; \mu_i, \sigma_1^2) p(x_i; \mu_1, \sigma_2^2) \cdots p(x_n; \mu_n, \sigma_n^2)
= \prod_{i=1}^n p(x_i; \mu_i, \sigma_1^2) p(x_i; \mu_1, \sigma_2^2) \cdots p(x_n; \mu_n, \sigma_n^2)
= \prod_{i=1}^n p(x_i; \mu_i, \sigma_1^2) p(x_i; \mu_1, \sigma_2^2) \cdots p(x_n; \mu_n, \sigma_n^2)
```

Anomaly detection algorithm

- 1. Choose features x_i that you think might be indicative of anomalous examples.
- 2. Fit parameters $\mu_1, \ldots, \mu_n, \sigma_1^2, \ldots, \sigma_n^2$

$$\mu_j = \frac{1}{m} \sum_{i=1}^{m} x_j^{(i)}$$

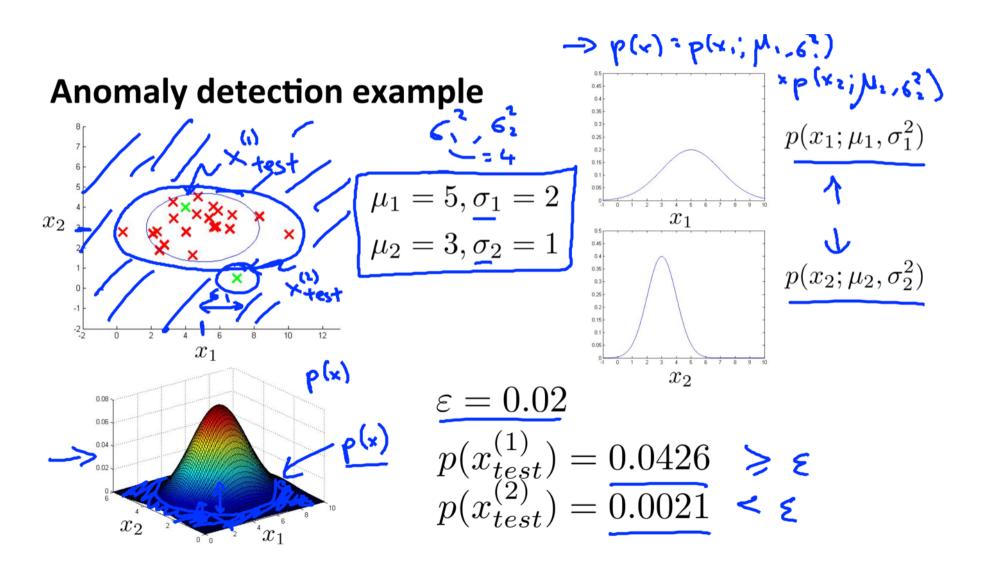
$$\sigma_j^2 = \frac{1}{m} \sum_{i=1}^m (x_j^{(i)} - \mu_j)^2$$

3. Given new example x, compute p(x):

$$p(x) = \prod_{j=1}^{n} p(x_j; \mu_j, \sigma_j^2) = \prod_{j=1}^{n} \frac{1}{\sqrt{2\pi}\sigma_j} \exp\left(-\frac{(x_j - \mu_j)^2}{2\sigma_j^2}\right)$$

Anomaly if $p(x) < \varepsilon$

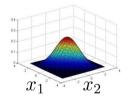
Anomaly detection example

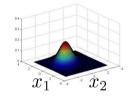


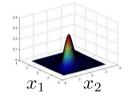
Multivariate Gaussian distribution

Parameters μ, Σ

$$p(x; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\right)$$





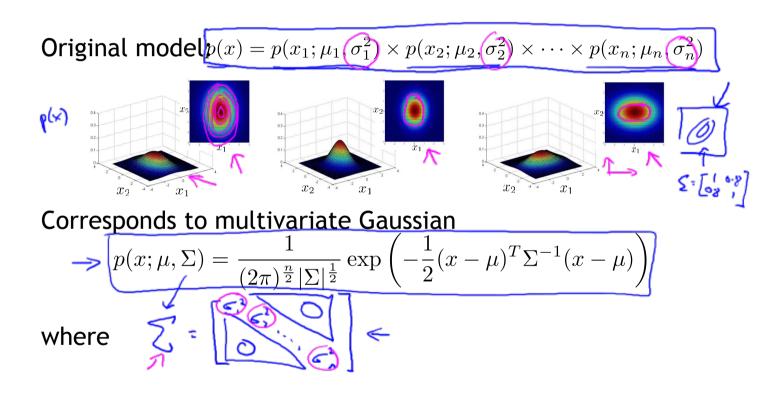


Parameter fitting:

Given training set $\{x^{(1)},x^{(2)},\ldots,x^{(m)}\}$

$$\mu = \frac{1}{m} \sum_{i=1}^{m} x^{(i)} \qquad \Sigma = \frac{1}{m} \sum_{i=1}^{m} (x^{(i)} - \mu)(x^{(i)} - \mu)^{T}$$

Relationship to original model



The importance of real-number evalution

When developing a learning algorithm (choosing features, etc.), making decisions is much easier if we have a way of evaluating our learning algorithm.

Assume we have some labeled data, of anomalous and non-anomalous examples. (y = 0 if normal, y = 1 if anomalous).

Training set: $x^{(1)}, x^{(2)}, \dots, x^{(m)}$ (assume normal examples/not anomalous)

Cross validation set: $(x_{cv}^{(1)}, y_{cv}^{(1)}), \dots, (x_{cv}^{(m_{cv})}, y_{cv}^{(m_{cv})})$ Test set: $(x_{test}^{(1)}, y_{test}^{(1)}), \dots, (x_{test}^{(m_{test})}, y_{test}^{(m_{test})})$

Aircraft engines example

Aircraft engines motivating example

```
10000 good (normal) engines
20 flawed engines (anomalous)
```

```
Training set: 6000 good engines CV: 2000 good engines ( y=0 ), 10 anomalous ( y=1 ) Test: 2000 good engines ( y=0 ), 10 anomalous ( y=1 )
```

Alternative:

```
Training set: 6000 good engines CV: 4000 good engines ( y=0 ), 10 anomalous ( y=1 )
```

Test: 4000 good engines ($y=0\,$), 10 anomalous ($y=1\,$)

Algorithm evalution

- \rightarrow Fit model $\underline{p(x)}$ on training set $\{\underline{x^{(1)},\ldots,x^{(m)}}\}$ $\xrightarrow{\text{test}}$, y $\xrightarrow{\text{test}}$, y $\xrightarrow{\text{test}}$ $\xrightarrow{\text{test}}$

$$y = \begin{cases} \frac{1}{0} & \text{if } p(x) < \varepsilon \text{ (anomaly)} \\ 0 & \text{if } p(x) \ge \varepsilon \text{ (normal)} \end{cases}$$

Possible evaluation metrics:

- -> True positive, false positive, false negative, true negative
- Precision/Recall

Can also use cross validation set to choose parameter ε

Algorithm evalution

$$prec = \frac{tp}{tp + fp}$$

$$rec = \frac{tp}{tp + fn},$$
(4)

$$rec = \frac{tp}{tp + fn}, (5)$$

where

- \bullet tp is the number of true positives: the ground truth label says it's an anomaly and our algorithm correctly classified it as an anomaly.
- fp is the number of false positives: the ground truth label says it's not an anomaly, but our algorithm incorrectly classified it as an anomaly.
- fn is the number of false negatives: the ground truth label says it's an anomaly, but our algorithm incorrectly classified it as not being anomalous.

$$F_1 = \frac{2 \cdot prec \cdot rec}{prec + rec},$$

class

- anomalyDensityEastimation
 - S4 class
 - detection & visualization
- slots
 - X : data. matrix object
 - param : density parameter. list object (mu, sigma2)
 - p: probability
 - y: training set's anomaly flag. vector (0=normality, 1=anomaly)
 - threshold: epsilon. list object
 - anomaly: detected observations

methods

- estimateGaussian
 - 확률밀도함수의 모수추정
- multivariateGaussian
 - multivariate Gaussian 확률 계산
- select Threshold
 - best epsilon, best F1 계산
- findAnomaly
 - anomaly detection
- plot
 - 2D multivariate Gaussian plotting

paramter estimation

```
> anomaly.trian <- new("anomalyDensityEastimation", X = X)</pre>
> anomaly.trian@param <- estimateGaussian(anomaly.trian)</pre>
> anomaly.trian@param
$mu
throughput latency
  14.11223 14.99771
$sigma2
         [,1] [,2]
[1,] 1.832631 0.000000
[2,] 0.000000 1.709745
```

select threshold

```
> anomaly.cv@threshold <- selectThreshold(anomaly.cv)
> anomaly.cv@threshold
$eps
[1] 8.990853e-05

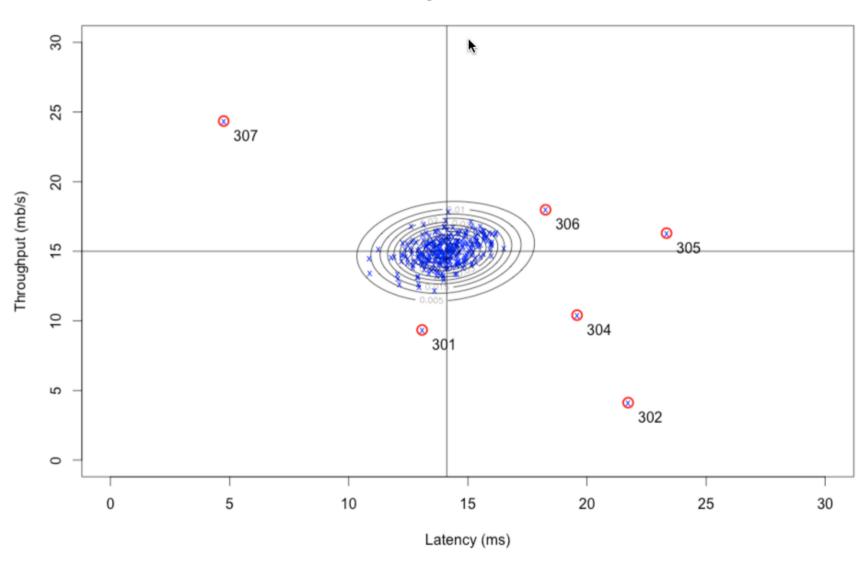
$F1
[1] 0.875
```

anomaly detect

```
> anomaly.trian@p <- multivariateGaussian(anomaly.trian)</pre>
> anomaly.trian@anomaly <- findAnomaly(anomaly.trian, anomaly.cv@threshold)</pre>
> anomaly.trian@anomaly
$idx
[17] 301 302 304 305 306 307
$value
     throughput latency
[1,] 13.079310 9.347878
[2,] 21.727134 4.126232
[3,] 19.582573 10.411619
[4,] 23.339868 16.298874
[5,] 18.261188 17.978309
[6,] 4.752613 24.350407
```

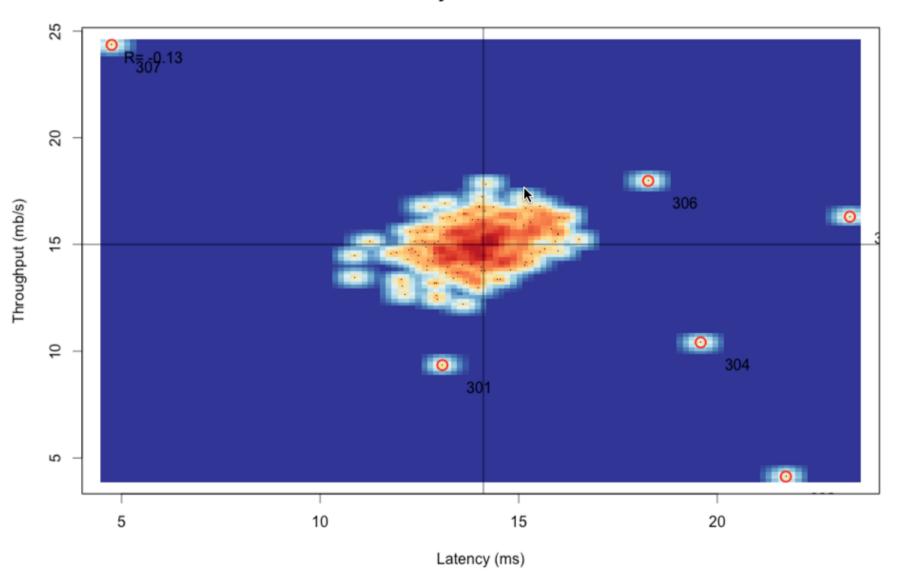
plotting visualization

Anomaly Detection Chart

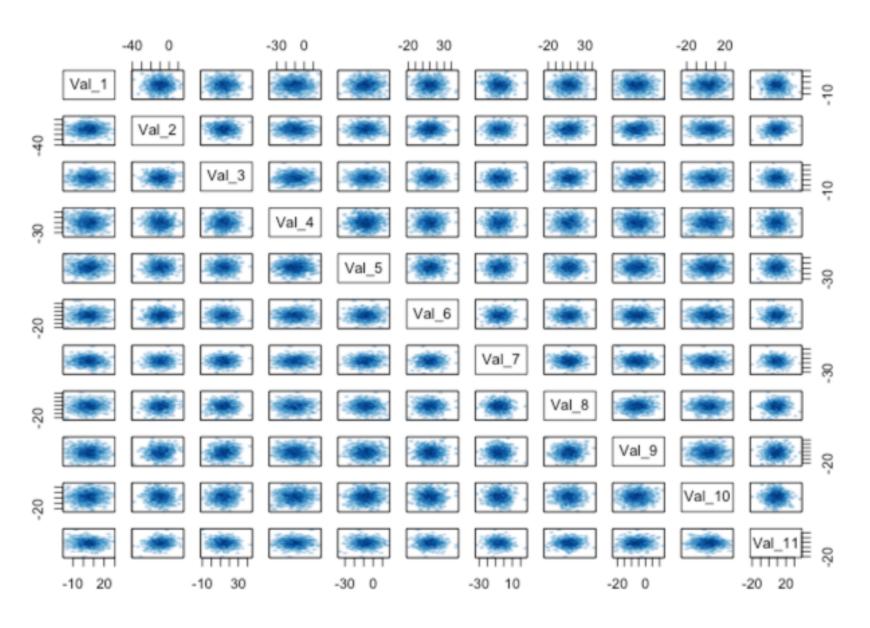


plotting visualization

Anomaly Detection Chart



plotting visualization



Demos

감사합니다