Linear Regression

Data Science Dojo



Overview

- Difference between Regression and Classification
- Linear Regression
 - Motivating Example: Predicting Housing Prices
 - Hypothesis function
 - Cost Function
 - Gradient Descent
 - Probabilistic Interpretation
- Applying linear regression for hand digit recognition



Supervised Learning

■ Data: D = {
$$d_1$$
, d_2 , d_3 ,...., d_n }
 d_i = < x_i , y_i >

a set of n examples

 X_i

- Input vector
- Independent variables
- Explanatory variables
- Features
- Predictors

 y_i

- Output scalar
- Dependent variables
- Response
- Outcome



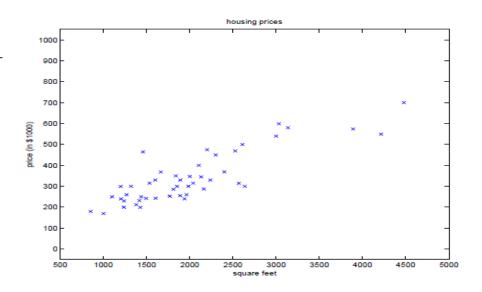
Supervised Learning

- Regression: X discrete or continuous → Y is continuous
 - Example: Prices, Weight, Height, signal measurement, temperature etc.
- Classification : X discrete or continuous → Y is discrete
- Objective: learn the mapping of $f: Xi \rightarrow Yi$



Predict Housing Prices

Living area (feet 2)	Price (1000\$s)
2104	400
1600	330
2400	369
1416	232
3000	540
÷	:



Can we learn to predict the price when the price of the house is not in the dataset?

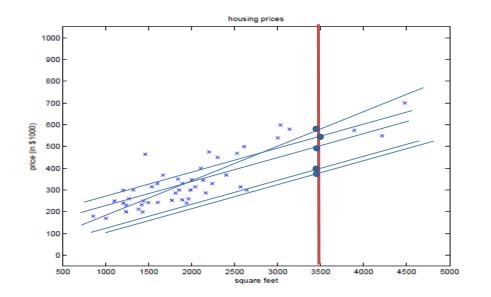
Living Area = 3500 sq. ft.

Price = ?



Predict Housing Prices

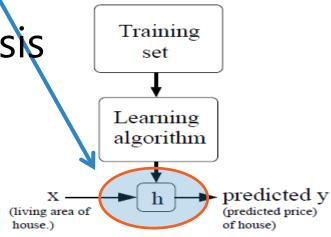
- Can we learn to predict the price when the price of the house is not in the dataset?
- Living Area = 3500 sq. ft. Price = ?
- Use the line that is somewhere in the middle
- How do we define somewhere in the middle?





Training Process In Linear Regression

- Objective: learn the mapping of $f: Xi \rightarrow Yi$
- Finding h is the goal hereh is known as the hypothesis

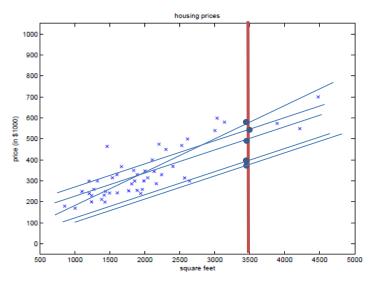




Predict Housing Prices

Living area (feet 2)		Price (1000\$s)	
$\mathbf{x}^{(1)}$	2104	400	y (1)
$X^{(2)}$	1600	330	$y^{(2)}$
$X^{(3)}$	2400	369	$y^{(3)}$
$X^{(4)}$	1416	232	$y^{(4)}$
$X^{(5)}$	3000	540	$y^{(5)}$
	:	:	•
	:	:	
$\mathbf{X}^{(m)}$			$\mathbf{y}^{(m)}$

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$



m = Total number of training examples $\theta_i = Parameters$



Hypothesis Function-Linear Regression

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

 $h_{\theta}(x^{i})$ is the prediction of the hypothesis h_{θ} for given input x^{i} y^{i} is the target values (what we would call labels in a classification problem)

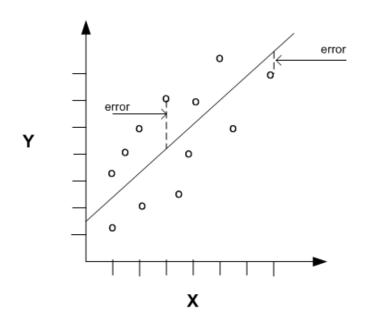
We want the prediction $h_{\theta}(x^i)$ to be as close to the true label y^i as possible.

How do we do that?



Cost Function

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

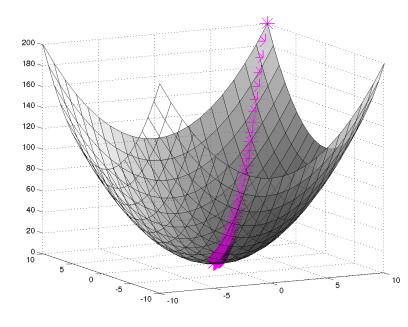


In Plain English

- find a linear line that is as close to the actual outputs as possible.
- Mathematically
 - Find linear function of X that minimizes the sum of squared residuals from Y.
 - a.k.a loss function



The Cost Function



Hypothesis: $h_{\theta}(x) = \theta_0 + \theta_1 x$

Cost Function: $J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$

Parameters: θ_0, θ_1

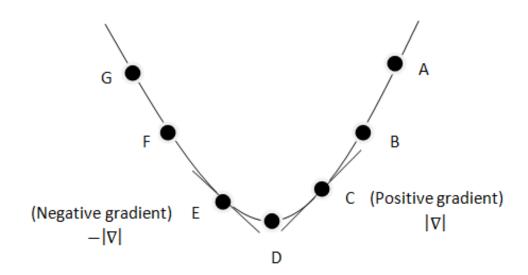
Goal: $\underset{\theta_0,\theta_1}{\text{minimize}} J(\theta_0,\theta_1)$



- Goal: $\min_{\theta_0,\theta_1} J(\theta_0,\theta_1)$
- Gradient descent starts with some initial θ and then performs an update for each value θ_j $\theta_j := \theta_j \alpha \left(\frac{\partial}{\partial \theta_j} J(\theta)\right)$
- Repeat until θ converges



$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta).$$





$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta).$$
 For $j=0$ and $j=1$

Repeat until converge {

$$\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m \left(h_\theta(x^{(i)}) - y^{(i)} \right)$$

$$\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m \left(h_\theta(x^{(i)}) - y^{(i)} \right) \cdot x^{(i)}$$

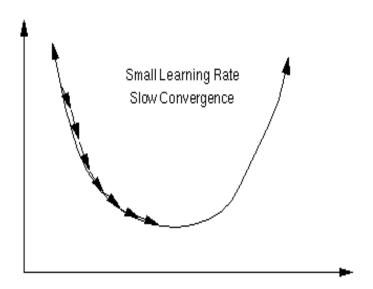


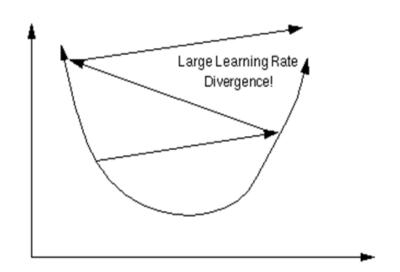
$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta).$$

- α is known as the learning rate
- Each time the algorithm takes a step in the direction of the steepest, $J(\theta)$ decreases.
- α determines how quickly or slowly the algorithm will converge to a solution

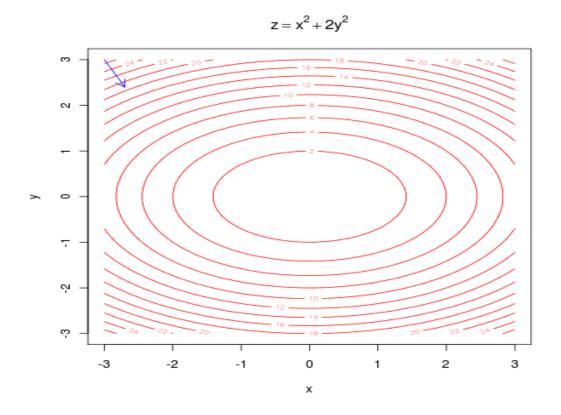


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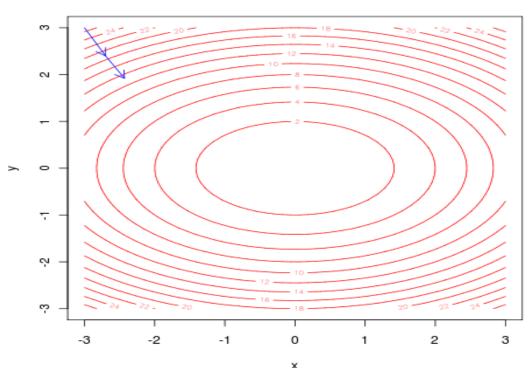






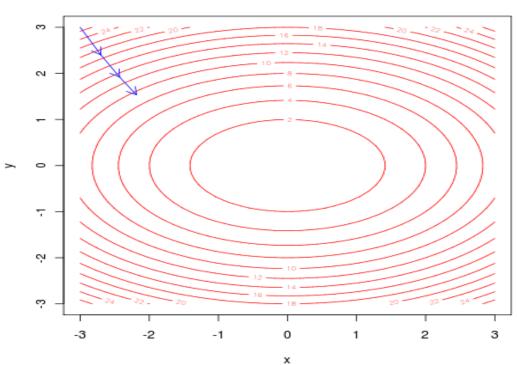


$$z=x^2+2y^2$$



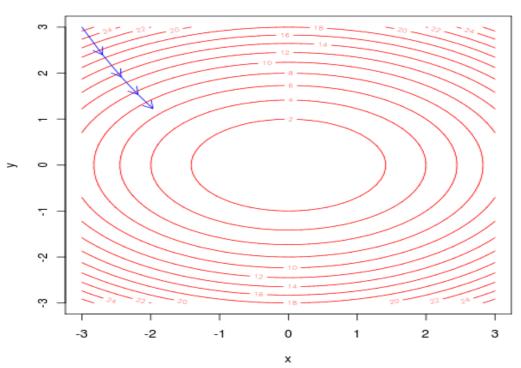


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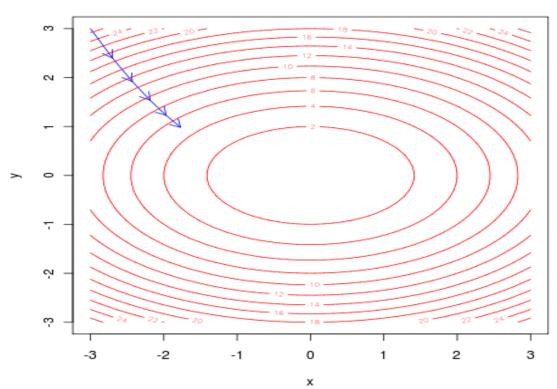


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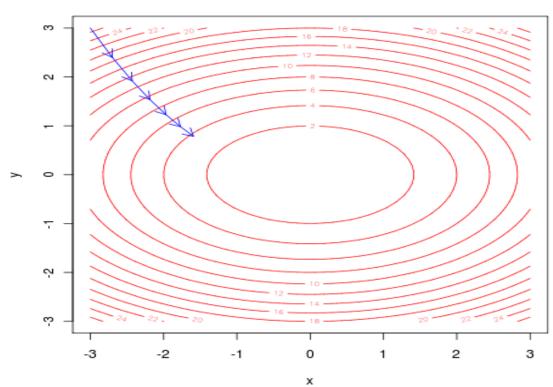


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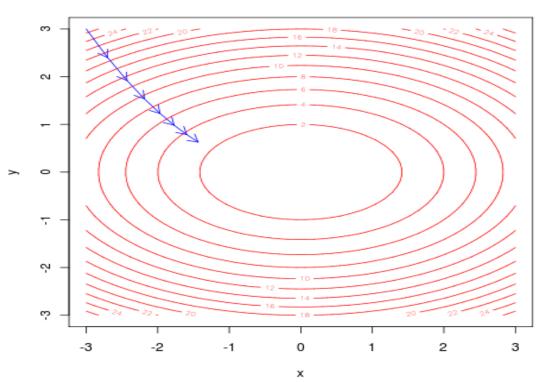


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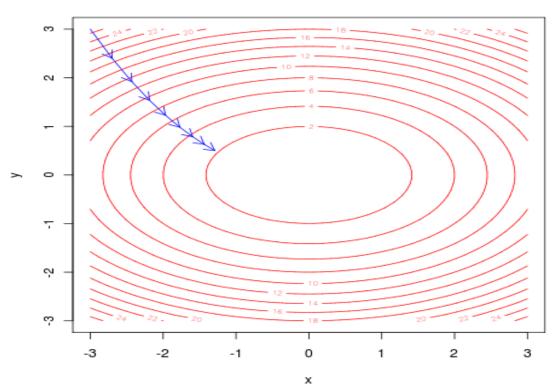


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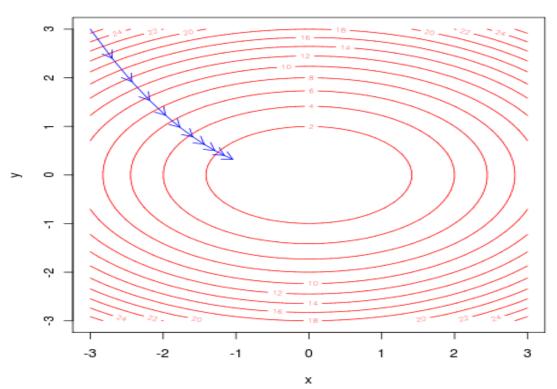


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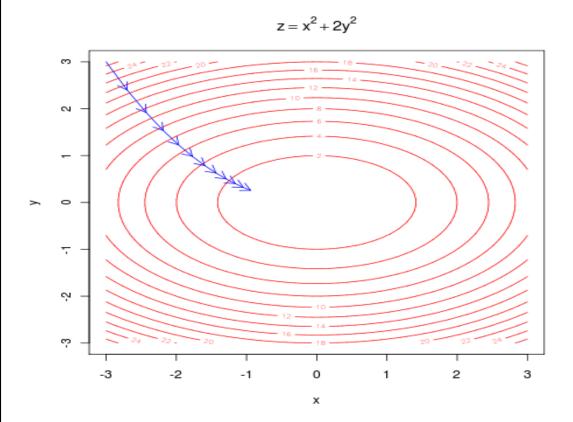




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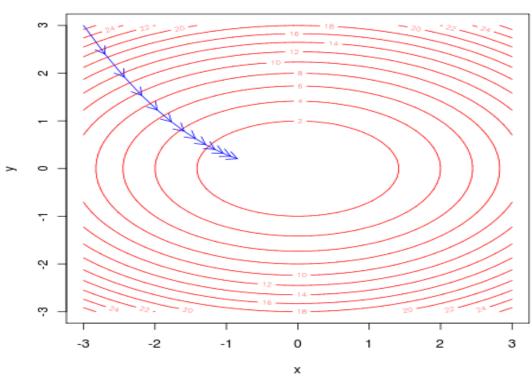






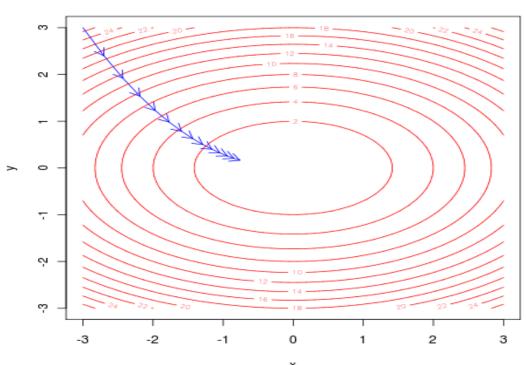






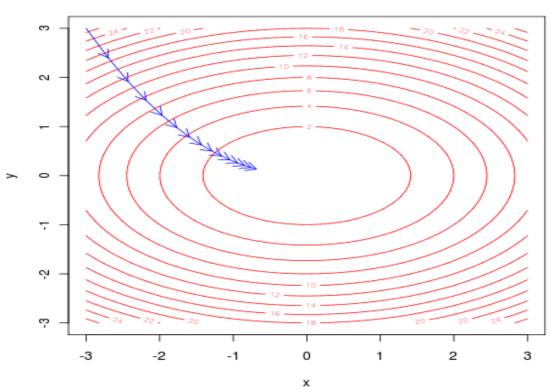


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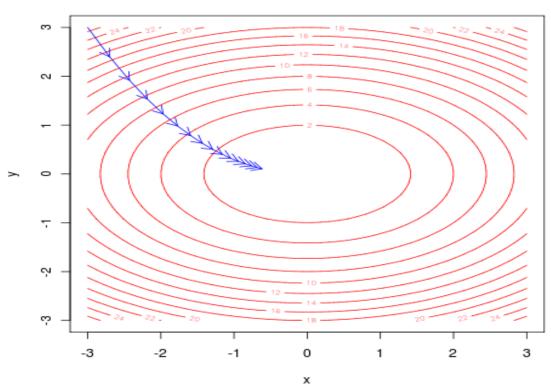


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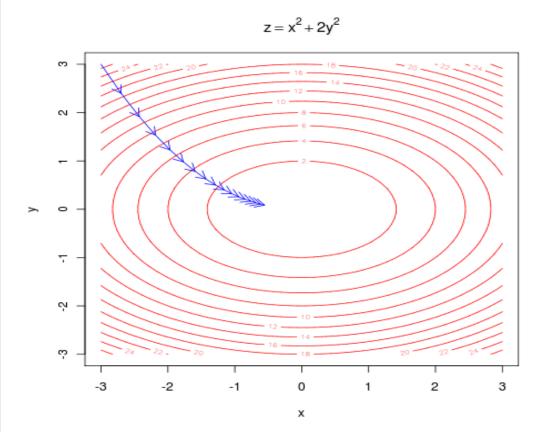




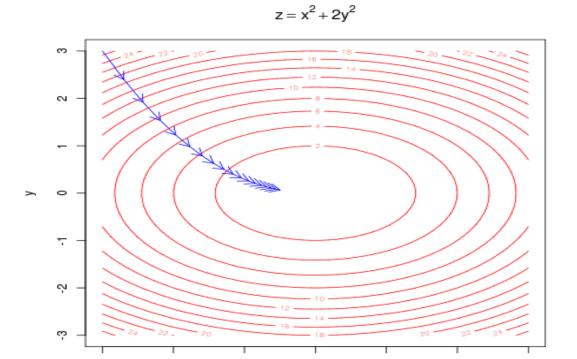
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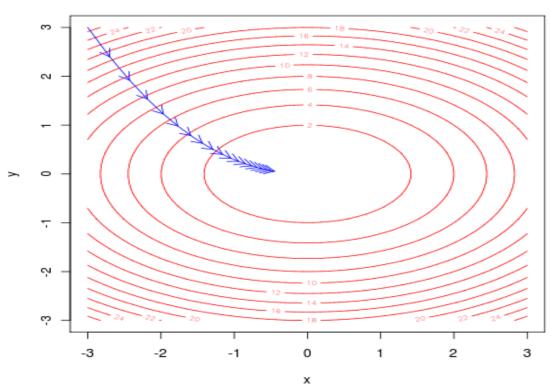




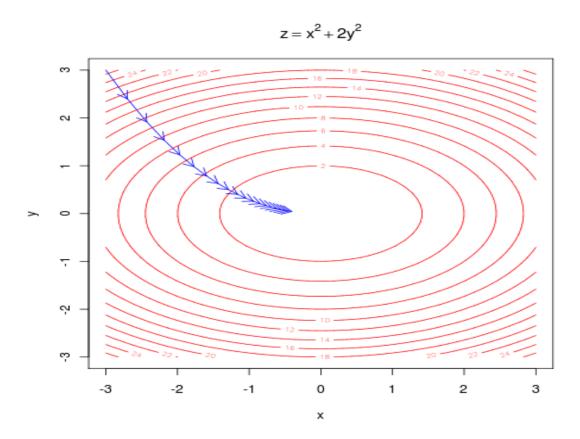
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$$z=x^2+2y^2$$

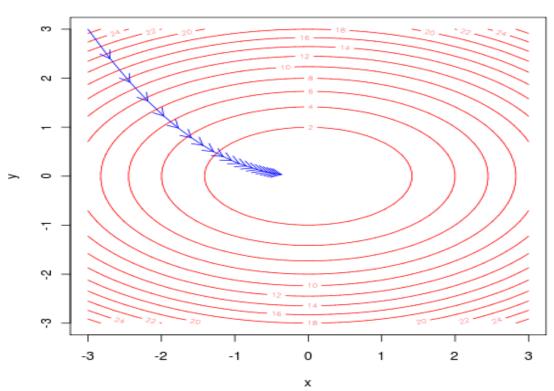




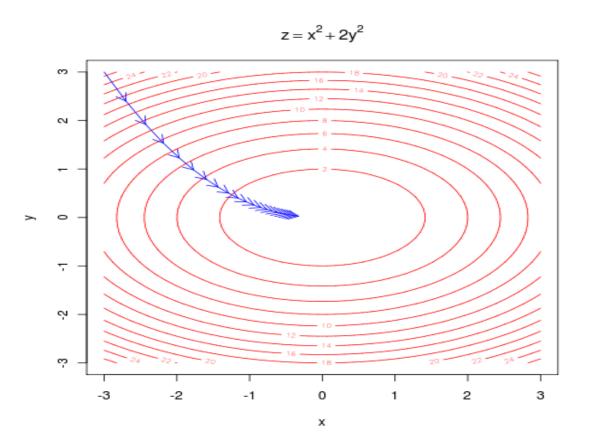




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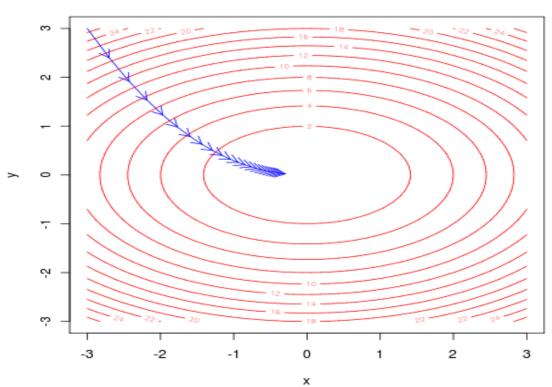






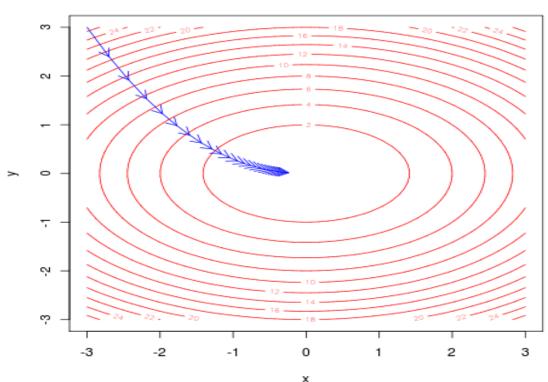


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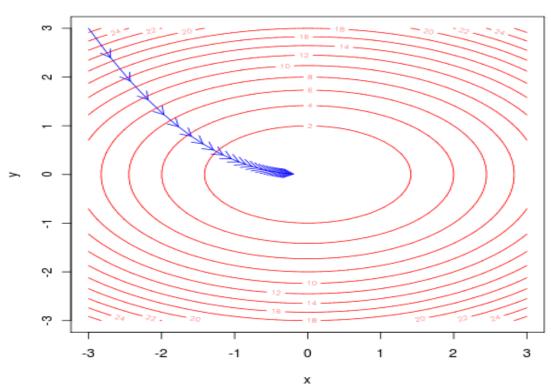


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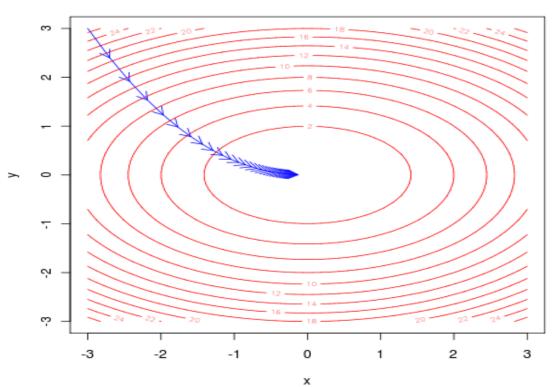


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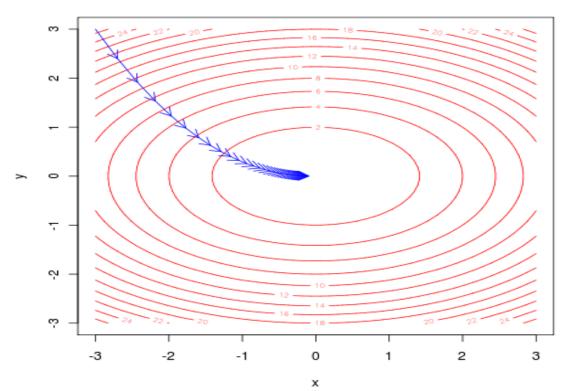


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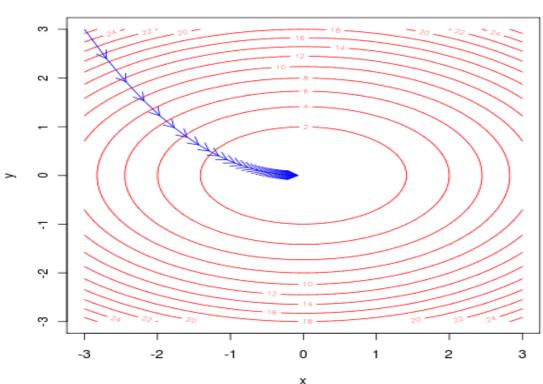


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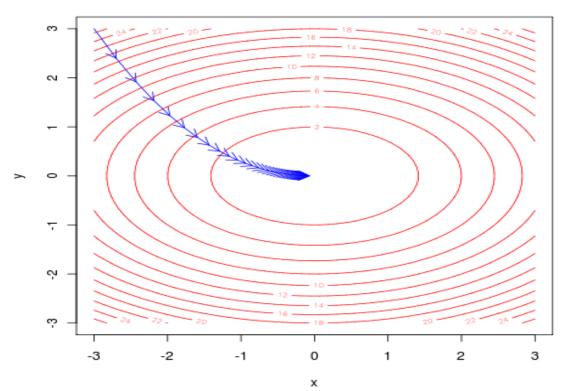


$$z=x^2+2y^2$$





$$z=x^2+2y^2$$





Multivariate Linear Regression



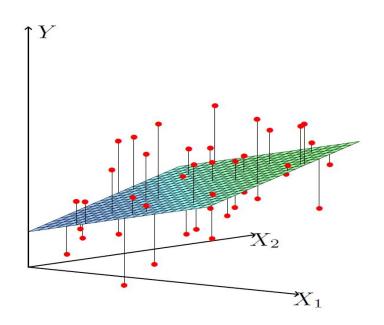
Predict Housing Prices – With Two Features

x^{i}_{1} x	ⁱ 2	y^i
Living area (feet ²)	#bedrooms	Price (1000\$s)
2104	3	400
1600	3	330
2400	3	369
1416	2	232
3000	4	540
:	:	A linear function is just
$h_{\theta}(x) =$	one of the choices to approximate the target variable.	

 θ is the space of linear functions mapping the space of input variables to the output/target variables
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unleash the data scientist in you

Predict Housing Prices – With Two Features



When we have two features, the linearity is in plane instead of line.



Algebraic Notation

The function approximating the target variable y is given by:

$$\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix}$$

$$\theta^T = [\theta_0 \, \theta_1 \theta_2]$$

$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2$$

as

$$h(x) = \sum_{i=0}^{n} \theta_i x_i = \theta^T x,$$

$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ x_1 \\ x_2 \end{bmatrix}$$

$$\theta^T x = [\theta_0 \, \theta_1 \theta_2] \begin{bmatrix} x_0 \\ x_1 \\ x_2 \end{bmatrix} = \sum_{i=0}^n \theta_i x_i$$



Batch Gradient Descent

For ONE training examples, we get the following update rule:

$$\theta_j := \theta_j + \alpha \left(y^{(i)} - h_{\theta}(x^{(i)}) \right) x_j^{(i)}.$$

What do we observe here about the magnitude of the update?

For ALL training examples, we get the following update rule:

```
Repeat until convergence { \theta_j := \theta_j + \alpha \sum_{i=1}^m \left( y^{(i)} - h_{\theta}(x^{(i)}) \right) x_j^{(i)} \qquad \text{(for every } j\text{)}. }
```



Stochastic Gradient Descent

Consider the following algorithm:

```
Loop {  for i=1 to m, \{ \\ \theta_j := \theta_j + \alpha \left(y^{(i)} - h_\theta(x^{(i)})\right) x_j^{(i)} \qquad (for every j).  } }
```

- This algorithm updates the parameters θ_j using each training example instead of all training examples.
- If the training set is big i.e., m is large, this technique converges quicker than batch gradient descent.
- Stochastic gradient descent may oscillate around the minimum of $J(\theta)$ and may not completely converge



Batch vs. Stochastic Gradient Descent

Batch Gradient Descent

```
Repeat until convergence { \theta_j := \theta_j + \alpha \sum_{i=1}^m \left(y^{(i)} - h_\theta(x^{(i)})\right) x_j^{(i)} \qquad \text{(for every $j$)}. }
```

- To update each parameter value, scan through the whole training data
- Converges to the minimum value slowly
- Preferred for small datasets

Stochastic Gradient Descent

```
Loop { for i=1 to m, \{ \\ \theta_j := \theta_j + \alpha \left(y^{(i)} - h_\theta(x^{(i)})\right) x_j^{(i)} \qquad (for every j).  }
```

- Update the parameter values with one training example at a time
- Converges to the 'proximity' of minimum value fast but may keep oscillating near the minimum
- Preferred for large datasets



- We will discuss why the least-squares cost function $J(\theta)$ is a reasonable choice.
- Assume that the inputs and the target variable are related by the following equation:

$$y^{(i)} = \theta^T x^{(i)} + \epsilon^{(i)}$$



- Where the e^i term captures the un-modeled effects:
 - Random noise
 - Some relevant feature not taken into consideration
- Assumptions:
 - ϵ^i is IID (Independently and Identically Distributed)
 - Normal distribution with mean 0 and variance σ^2
 - variance σ^2 is random

$$\epsilon^i = N(0, \sigma^2)$$



■ The density of ϵ^i is given by $p(\epsilon^{(i)}) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(\epsilon^{(i)})^2}{2\sigma^2}\right)$

We can rewrite:

$$p(y^{(i)}|x^{(i)};\theta) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(y^{(i)} - \theta^T x^{(i)})^2}{2\sigma^2}\right)$$

This is the distribution of y^i given x^i and parameterized by θ

$$y^{(i)} \mid x^{(i)}; \theta \sim \mathcal{N}(\theta^T x^{(i)}, \sigma^2)$$



• Probability of observing the data as a function of θ is given by:

$$L(\theta) = L(\theta; X, \vec{y}) = p(\vec{y}|X; \theta).$$

- This is known as the likelihood function
- Due to the independence assumption, we can rewrite:

$$L(\theta) = \prod_{i=1}^{m} p(y^{(i)} \mid x^{(i)}; \theta)$$
$$= \prod_{i=1}^{m} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(y^{(i)} - \theta^{T} x^{(i)})^{2}}{2\sigma^{2}}\right).$$



Maximizing The Likelihood Function

- Principle of maximum likelihood: Choose θ that makes the observed data as high probability as possible. In other words, choose θ that maximizes $L(\theta)$.
- For mathematical ease, we can maximize the log of the likelihood function $L(\theta)$ instead.



Maximizing The Log Likelihood Function

$$\ell(\theta) = \log L(\theta)$$

$$= \log \prod_{i=1}^{m} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(y^{(i)} - \theta^{T} x^{(i)})^{2}}{2\sigma^{2}}\right)$$

$$= \sum_{i=1}^{m} \log \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(y^{(i)} - \theta^{T} x^{(i)})^{2}}{2\sigma^{2}}\right)$$

$$= m \log \frac{1}{\sqrt{2\pi}\sigma} - \frac{1}{\sigma^{2}} \cdot \frac{1}{2} \sum_{i=1}^{m} (y^{(i)} - \theta^{T} x^{(i)})^{2}.$$

$$\frac{1}{2} \sum_{i=1}^{m} (y^{(i)} - \theta^{T} x^{(i)})^{2}.$$

Maximizing $L(\theta)$ is equivalent to minimizing $J(\theta)$

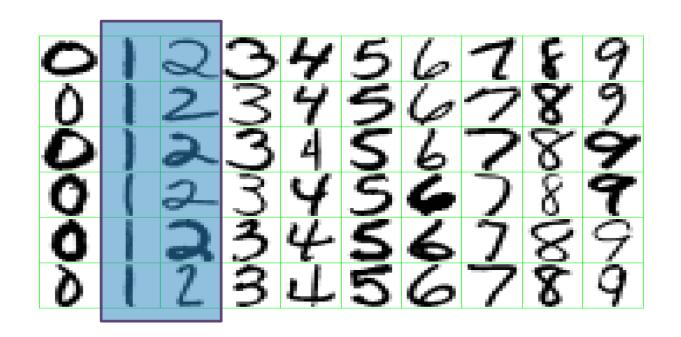


Linear Regression Using R

- We will learn how to use linear regression for handwritten digit recognition now
- Distinguishing between 2s and 3s
- We will see some R code
 - For processing the inputs
 - Applying linear regression to learn a hypothesis
- You can download R by searching 'R download'



Example: Handwritten Digit Recognition





Extracting Features For Learning



```
\{x_1, x_2, x_3, \dots, X_{256}, y = \text{'three'}\}
```

- Each xi corresponds to a feature value in the image
- y is a label of the training data; can be numeric or categorical, '3' or 'three'
- Each image is converted to row vectors and the appropriate learning algorithm is used
- Convention
 - x_i represents the ith feature in a training sample
 - y represents the label for the training sample



QUESTIONS

