prior_montecarlo

May 7, 2019

1 Run and process the prior monte carlo and pick a "truth" realization

A great advantage of exploring a synthetic model is that we can enforce a "truth" and then evaluate how our various attempts to estimate it perform. One way to do this is to run a monte carlo ensemble of multiple parameter realizations and then choose one of them to represent the "truth". That will be accomplished in this notebook.

```
In [1]: import os
    import shutil
    import numpy as np
    import pandas as pd
    import matplotlib.pyplot as plt
    import matplotlib as mpl
    plt.rcParams['font.size']=12
    import flopy
    import pyemu
```

flopy is installed in /Users/jeremyw/Dev/gw1876/activities_2day_mfm/notebooks/flopy

1.0.1 set the t_d or "template directory" variable to point at the template folder and read in the PEST control file

1.0.2 Decide what pars are uncertain in the truth

We need to decide what our truth looks like - should the pilot points or the grid-scale pars be the source of spatial variability? or both?

```
In [3]: par = pst.parameter_data
    # grid pars
    #should_fix = par.loc[par.pargp.apply(lambda x: "gr" in x), "parnme"]
    # pp pars
    #should_fix = par.loc[par.pargp.apply(lambda x: "pp" in x), "parnme"]
    #pst.npar - should_fix.shape[0]
```

1.0.3 run the prior ensemble in parallel locally

This takes advantage of the program pestpp-swp which runs a parameter sweep through a set of parameters. By default, pestpp-swp reads in the ensemble from a file called sweep_in.csv which in this case we made just above.

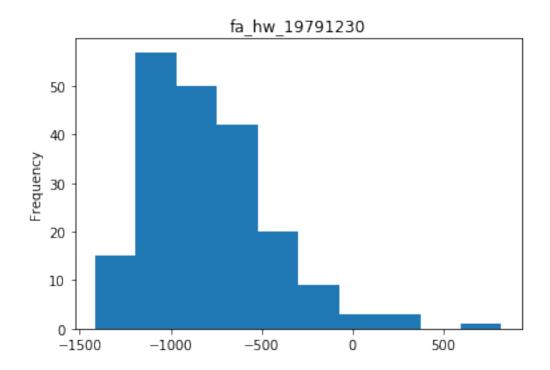
print('number of realization in the ensemble before dropping: ' + str(obs_df.shape[0])

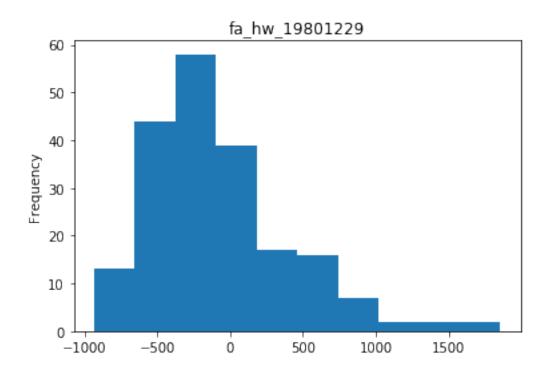
number of realization in the ensemble before dropping: 200

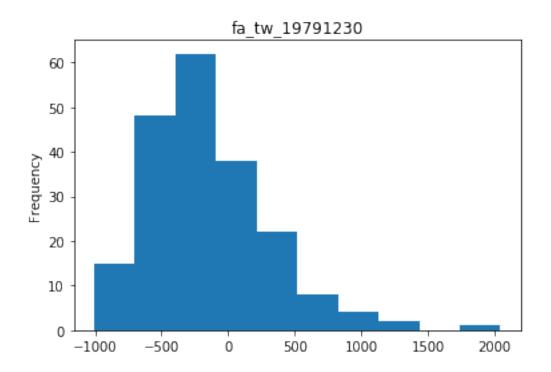
drop any failed runs

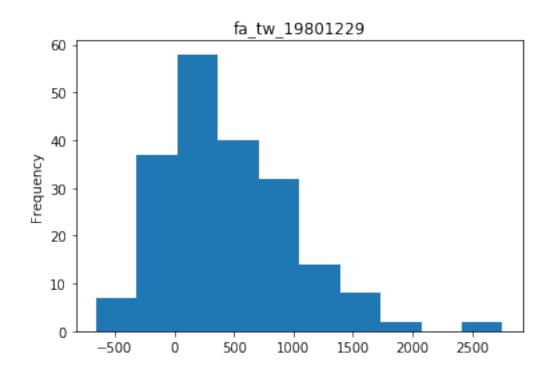
1.0.5 confirm which quantities were identified as forecasts

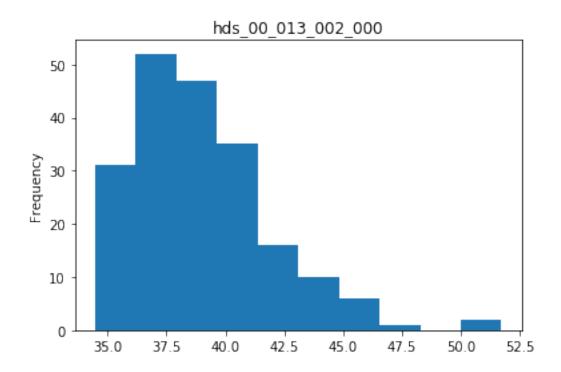
1.0.6 now we can plot the distributions of each forecast

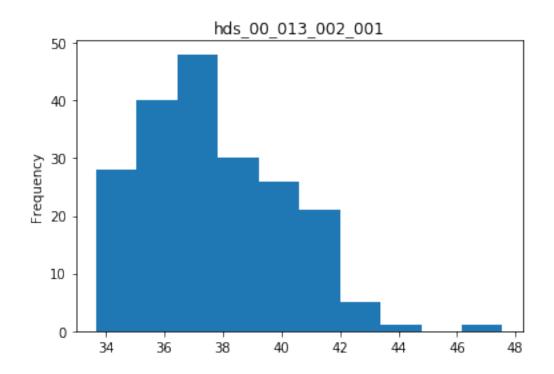


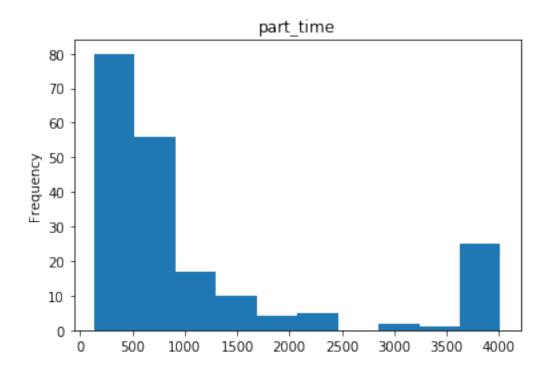


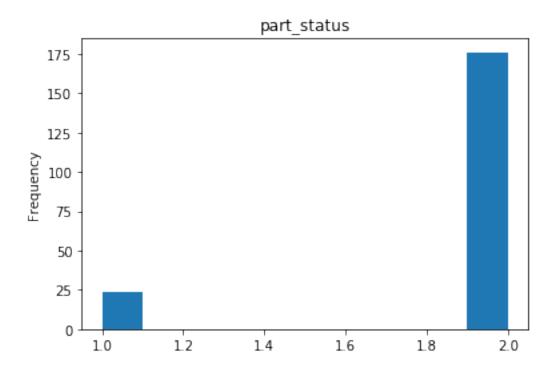






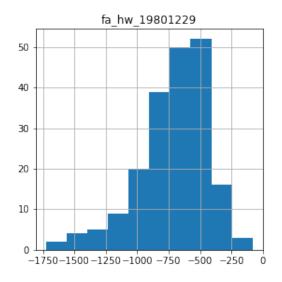


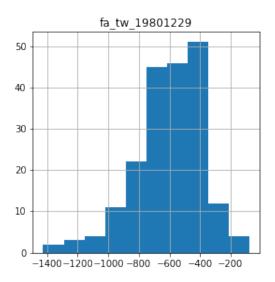


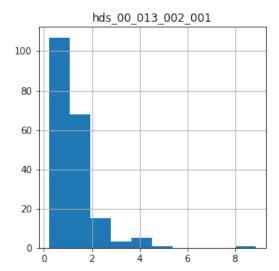


We see that under scenario conditions, many more realizations for the flow to the aquifer in the headwaters are postive (as expected). Lets difference these two:

```
In [10]: sfnames = [f for f in fnames if "1980" in f or "_001" in f]
    hfnames = [f for f in fnames if "1979" in f or "_000" in f]
    diff = obs_df.loc[:,hfnames].values - obs_df.loc[:,sfnames].values
    diff = pd.DataFrame(diff,columns=sfnames)
    diff.hist(figsize=(10,10))
    plt.show()
```







We now see that the most extreme scenario yields a large decrease in flow from the aquifer to the headwaters (the most negative value)

1.0.7 setting the "truth"

We just need to replace the observed values (obsval) in the control file with the outputs for one of the realizations on obs_df. In this way, we now have the nonzero values for history matching, but also the truth values for comparing how we are doing with other unobserved quantities. I'm going to pick a realization that yields an "average" variability of the observed gw levels:

```
Out[11]: 193
In [12]: obs_df.loc[idx,pst.nnz_obs_names]
                                12065.000000
Out[12]: fo_39_19791230
         hds_00_002_009_000
                                   40.873676
         hds_00_002_015_000
                                   35.360447
         hds_00_003_008_000
                                   41.228016
         hds_00_009_001_000
                                   44.455975
         hds_00_013_010_000
                                   37.670860
         hds_00_015_016_000
                                   35.308788
         hds_00_021_010_000
                                   36.780243
         hds_00_022_015_000
                                   34.332844
         hds_00_024_004_000
                                   39.176395
         hds_00_026_006_000
                                   38.244102
         hds_00_029_015_000
                                   34.879692
         hds_00_033_007_000
                                   37.037766
         hds_00_034_010_000
                                   36.083714
         Name: 193, dtype: float64
```

Lets see how our selected truth does with the sw/gw forecasts:

In [13]: obs_df.loc[idx,fnames]

part_time 948.015500 part_status 2.000000

Name: 193, dtype: float64

Assign some initial weights. Now, it is custom to add noise to the observed values...we will use the classic Gaussian noise...zero mean and standard deviation of 1 over the weight

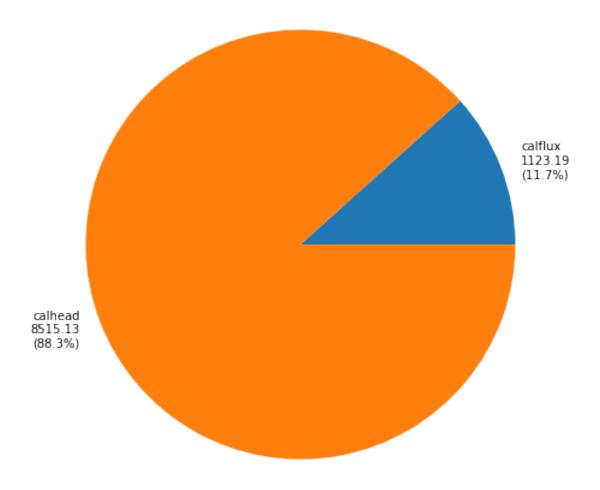
```
In [14]: pst = pyemu.Pst(os.path.join(t_d,"freyberg.pst"))
      obs = pst.observation_data
      obs.loc[:,"obsval"] = obs_df.loc[idx,pst.obs_names]
      obs.loc[obs.obgnme=="calhead","weight"] = 10.0
      obs.loc[obs.obgnme=="calflux","weight"] = 0.05
```

here we just get a sample from a random normal distribution with mean=0 and std=1. The argument indicates how many samples we want - and we choose pst.nnz_obs which is the the number of nonzero-weighted observations in the PST file

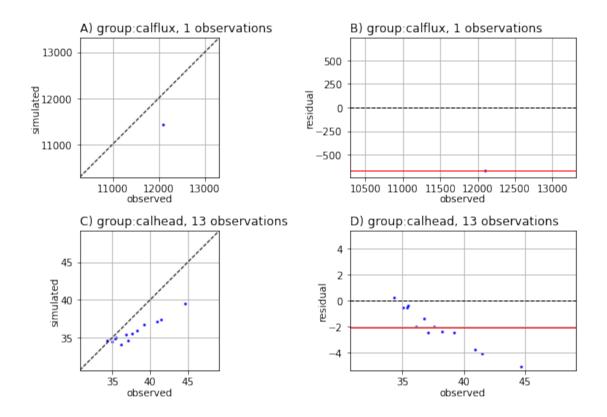
```
Out[15]: obsnme
                               35.281047
         fo_39_19791230
         hds_00_002_009_000
                                0.040016
         hds_00_002_015_000
                                0.097874
         hds 00 003 008 000
                                0.224089
         hds_00_009_001_000
                                0.186756
         hds_00_013_010_000
                               -0.097728
         hds_00_015_016_000
                                0.095009
         hds_00_021_010_000
                               -0.015136
         hds_00_022_015_000
                               -0.010322
         hds_00_024_004_000
                                0.041060
         hds_00_026_006_000
                                0.014404
         hds_00_029_015_000
                                0.145427
         hds_00_033_007_000
                                0.076104
         hds_00_034_010_000
                                0.012168
         Name: weight, dtype: float64
```

Then we write this out to a new file and run pestpp-ies to see how the objective function looks

Now we can read in the results and make some figures showing residuals and the balance of the objective function



<Figure size 576x756 with 0 Axes>



hds_00_002_009_000	hds_00_002_009_000	calhead	40.913692	37.107498
hds_00_002_015_000	hds_00_002_015_000	calhead	35.458321	35.045185
hds_00_003_008_000	hds_00_003_008_000	calhead	41.452105	37.397289
hds_00_009_001_000	hds_00_009_001_000	calhead	44.642730	39.546417
hds_00_013_010_000	hds_00_013_010_000	calhead	37.573133	35.571774
hds_00_015_016_000	hds_00_015_016_000	calhead	35.403797	34.835716
hds_00_021_010_000	hds_00_021_010_000	calhead	36.765107	35.386250
hds_00_022_015_000	hds_00_022_015_000	calhead	34.322522	34.577492
hds_00_024_004_000	hds_00_024_004_000	calhead	39.217455	36.760464
hds_00_026_006_000	hds_00_026_006_000	calhead	38.258507	35.896149
hds_00_029_015_000	hds_00_029_015_000	calhead	35.025119	34.453842
hds_00_033_007_000	hds_00_033_007_000	calhead	37.113869	34.678810
hds_00_034_010_000	hds_00_034_010_000	calhead	36.095881	34.118073

	residual	weight
name		
fo_39_19791230	670.281047	0.05
hds_00_002_009_000	3.806194	10.00
hds_00_002_015_000	0.413136	10.00
hds_00_003_008_000	4.054816	10.00
hds_00_009_001_000	5.096313	10.00
hds_00_013_010_000	2.001359	10.00
hds_00_015_016_000	0.568081	10.00
hds_00_021_010_000	1.378858	10.00
hds_00_022_015_000	-0.254970	10.00
hds_00_024_004_000	2.456992	10.00
hds_00_026_006_000	2.362358	10.00
hds_00_029_015_000	0.571277	10.00
hds_00_033_007_000	2.435059	10.00
hds_00_034_010_000	1.977809	10.00

Publication ready figs - oh snap!

Depending on the truth you chose, we may have a problem - we set the weights for both the heads and the flux to reasonable values based on what we expect for measurement noise. But the contributions to total phi might be out of balance - if contribution of the flux measurement to total phi is too low, the history matching excersizes (coming soon!) will focus almost entirely on minimizing head residuals. So we need to balance the objective function. This is a subtle but very important step, especially since some of our forecasts deal with sw-gw exchange

Just to make sure we have everything working right, we should be able to load the truth parameters, run the model once and have a phi equivalent to the noise vector:

we will run this with noptmax=0 to preform a single run. Pro-tip: you can use any of the pestpp-### binaries/executables to run noptmax=0

```
In [20]: pyemu.os_utils.run("pestpp-ies.exe test.pst",cwd=m_d)
         pst = pyemu.Pst(os.path.join(m_d,"test.pst"))
        print(pst.phi)
        pst.res.loc[pst.nnz_obs_names,:]
```

17.528847219729652

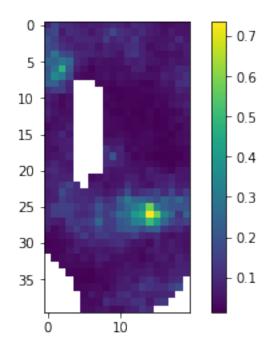
Out[20]:			name	group	measured	modelled	\
	name						
	fo_39_19791230	fo_39_	19791230	calflux	12100.281047	12065.000000	
	hds_00_002_009_000	hds_00_002	_009_000	calhead	40.913692	40.873676	
	hds_00_002_015_000	hds_00_002	_015_000	calhead	35.458321	35.360447	
	hds_00_003_008_000	hds_00_003	_008_000	calhead	41.452105	41.228016	
	hds_00_009_001_000	hds_00_009	_001_000	calhead	44.642730	44.455975	
	hds_00_013_010_000	hds_00_013	_010_000	calhead	37.573133	37.670860	
	hds_00_015_016_000	hds_00_015	_016_000	calhead	35.403797	35.308788	
	hds_00_021_010_000	hds_00_021	_010_000	calhead	36.765107	36.780243	
	hds_00_022_015_000	hds_00_022	_015_000	calhead	34.322522	34.332844	
	hds_00_024_004_000	hds_00_024	_004_000	calhead	39.217455	39.176395	
	hds_00_026_006_000	hds_00_026	_006_000	calhead	38.258507	38.244102	
	hds_00_029_015_000	hds_00_029	_015_000	calhead	35.025119	34.879692	
	hds_00_033_007_000	hds_00_033	_007_000	calhead	37.113869	37.037766	
	hds_00_034_010_000	hds_00_034	_010_000	calhead	36.095881	36.083714	
		residual	weight				
	name						
	fo_39_19791230	35.281047	0.05				
	hds_00_002_009_000	0.040016	10.00				
	hds_00_002_015_000	0.097874	10.00				
	hds_00_003_008_000	0.224089	10.00				
	hds_00_009_001_000	0.186756	10.00				
	hds_00_013_010_000	-0.097728	10.00				
	hds_00_015_016_000	0.095009	10.00				
	hds_00_021_010_000	-0.015136	10.00				
	hds_00_022_015_000	-0.010322	10.00				
	hds_00_024_004_000	0.041060	10.00				
	hds_00_026_006_000	0.014404	10.00				
	hds_00_029_015_000	0.145427	10.00				
	hds_00_033_007_000	0.076104	10.00				
	hds_00_034_010_000	0.012168	10.00				

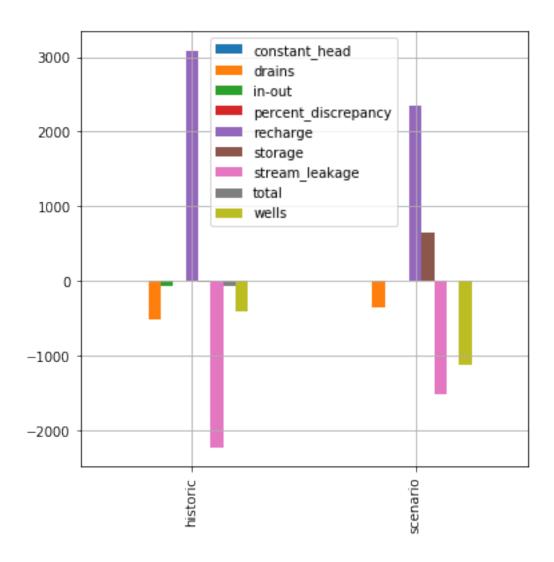
The residual should be exactly the noise values from above. Lets load the model (that was just run using the true pars) and check some things

```
In [21]: m = flopy.modflow.Modflow.load("freyberg.nam",model_ws=m_d)
```

```
In [22]: a = m.upw.vka[1].array
    #a = m.rch.rech[0].array
    a = np.ma.masked_where(m.bas6.ibound[0].array==0,a)
    print(a.min(),a.max())
    c = plt.imshow(a)
    plt.colorbar()
    plt.show()
```

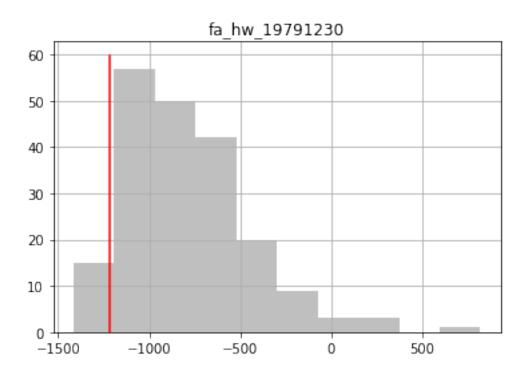
0.01317227 0.735812

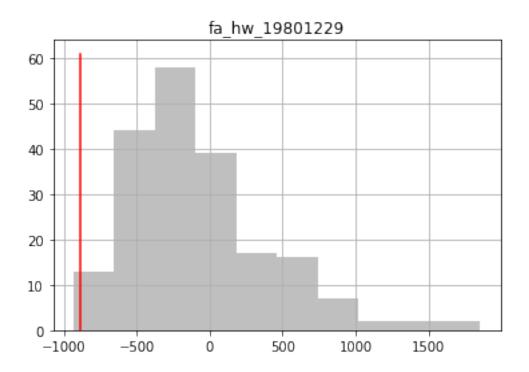


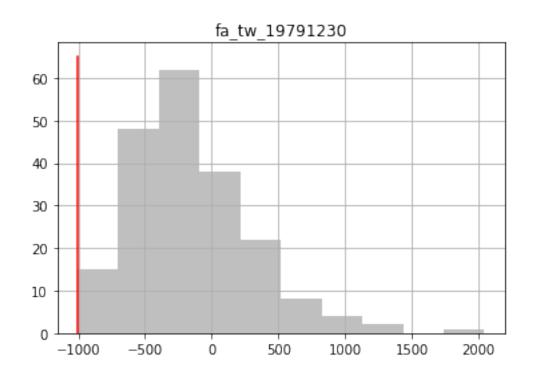


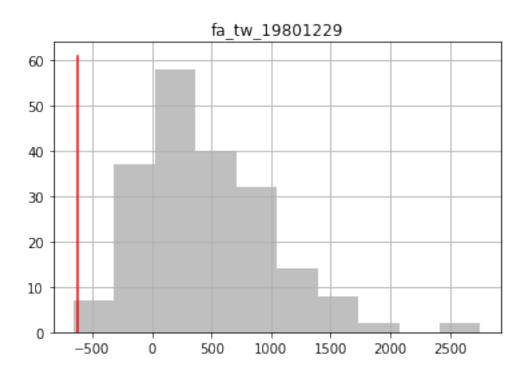
1.0.8 see how our existing observation ensemble compares to the truth

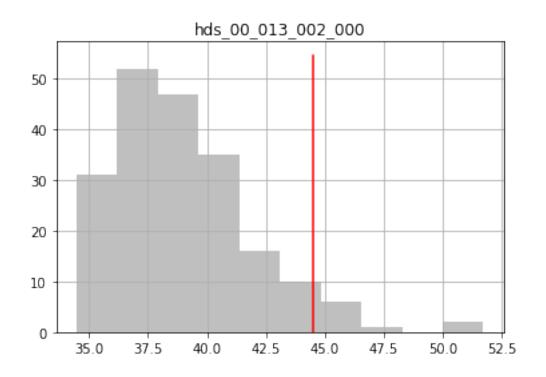
forecasts:

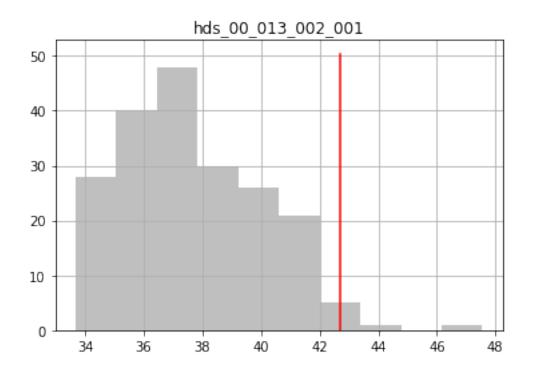


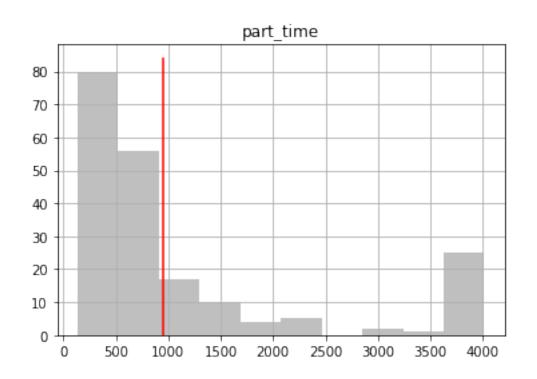


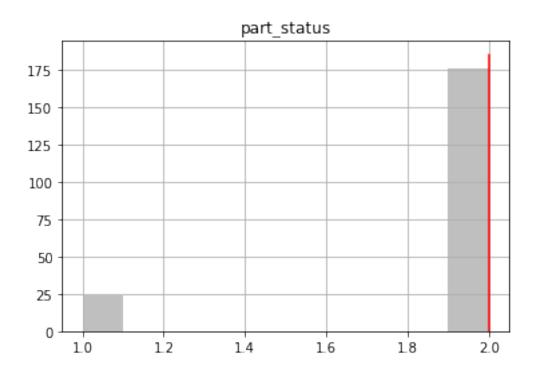












observations:

