prior_montecarlo

May 10, 2019

1 Run and process the prior monte carlo and pick a "truth" realization

A great advantage of exploring a synthetic model is that we can enforce a "truth" and then evaluate how our various attempts to estimate it perform. One way to do this is to run a monte carlo ensemble of multiple parameter realizations and then choose one of them to represent the "truth". That will be accomplished in this notebook.

```
In [1]: import os
    import shutil
    import numpy as np
    import pandas as pd
    import matplotlib.pyplot as plt
    import matplotlib as mpl
    plt.rcParams['font.size']=12
    import flopy
    import pyemu
```

flopy is installed in /Users/jeremyw/Dev/gw1876/activities_2day_mfm/notebooks/flopy

1.0.1 set the t_d or "template directory" variable to point at the template folder and read in the PEST control file

1.0.2 Decide what pars are uncertain in the truth

We need to decide what our truth looks like - should the pilot points or the grid-scale pars be the source of spatial variability? or both?

```
In [3]: par = pst.parameter_data
    # grid pars
    #should_fix = par.loc[par.pargp.apply(lambda x: "gr" in x), "parnme"]
    # pp pars
    #should_fix = par.loc[par.pargp.apply(lambda x: "pp" in x), "parnme"]
    #pst.npar - should_fix.shape[0]
```

1.0.3 run the prior ensemble in parallel locally

This takes advantage of the program pestpp-swp which runs a parameter sweep through a set of parameters. By default, pestpp-swp reads in the ensemble from a file called sweep_in.csv which in this case we made just above.

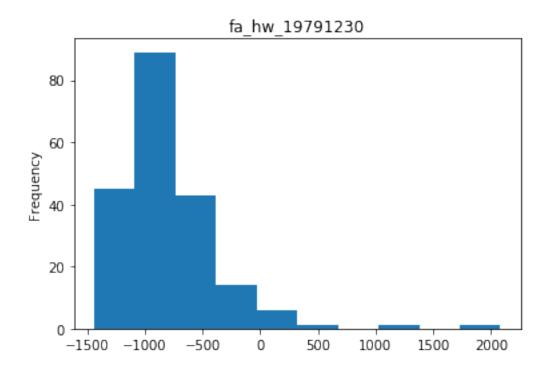
print('number of realization in the ensemble before dropping: ' + str(obs_df.shape[0])

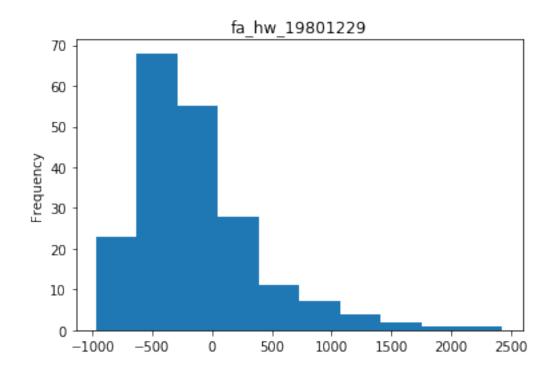
number of realization in the ensemble before dropping: 200

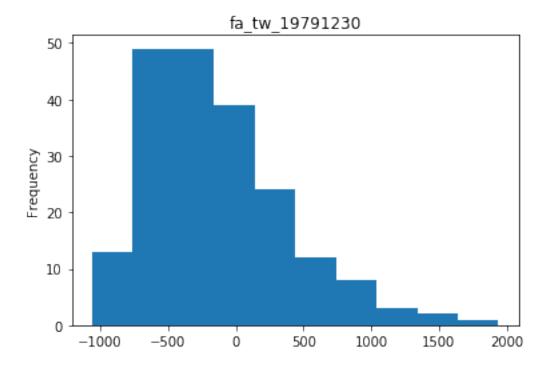
drop any failed runs

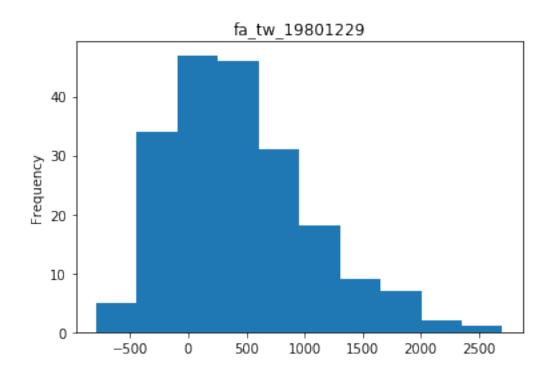
1.0.5 confirm which quantities were identified as forecasts

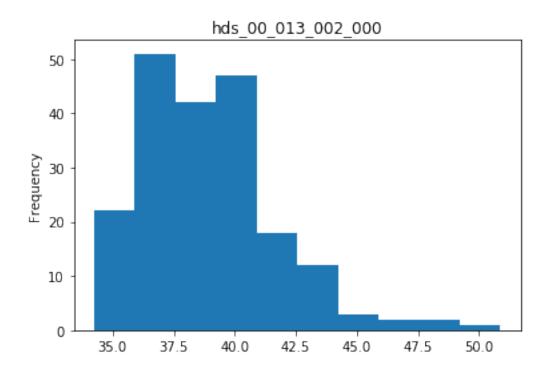
1.0.6 now we can plot the distributions of each forecast

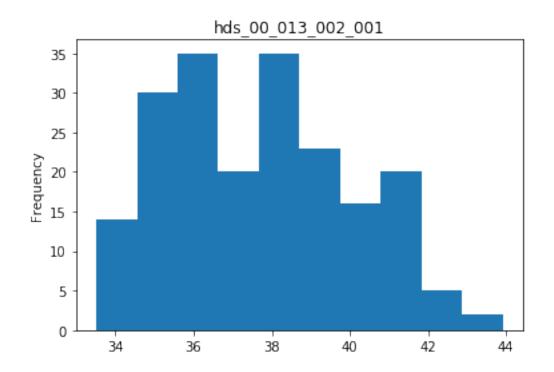


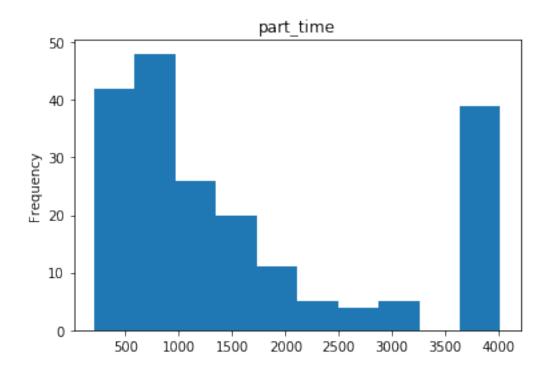


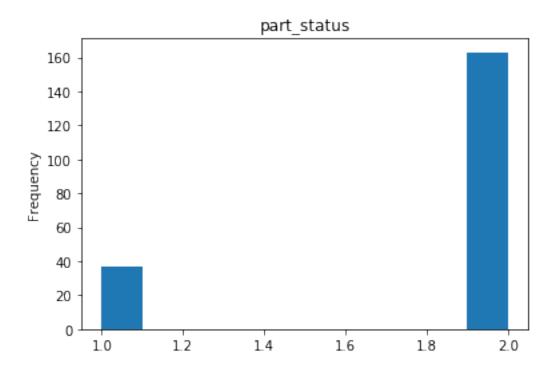






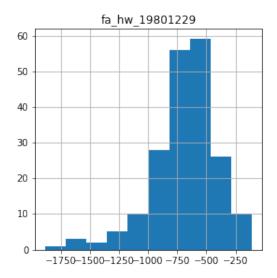


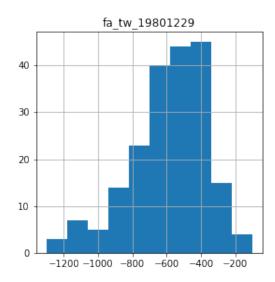


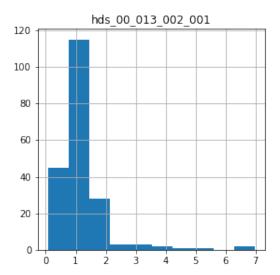


We see that under scenario conditions, many more realizations for the flow to the aquifer in the headwaters are postive (as expected). Lets difference these two:

```
In [10]: sfnames = [f for f in fnames if "1980" in f or "_001" in f]
    hfnames = [f for f in fnames if "1979" in f or "_000" in f]
    diff = obs_df.loc[:,hfnames].values - obs_df.loc[:,sfnames].values
    diff = pd.DataFrame(diff,columns=sfnames)
    diff.hist(figsize=(10,10))
    plt.show()
```







We now see that the most extreme scenario yields a large decrease in flow from the aquifer to the headwaters (the most negative value)

1.0.7 setting the "truth"

We just need to replace the observed values (obsval) in the control file with the outputs for one of the realizations on obs_df. In this way, we now have the nonzero values for history matching, but also the truth values for comparing how we are doing with other unobserved quantities. I'm going to pick a realization that yields an "average" variability of the observed gw levels:

idx hist_swgw

Out[11]:	run_id	
	149	207.9040
	165	237.0716
	191	280.1461
	97	286.6308
	77	289.1803
	16	304.0466
	173	326.0275
	186	332.5973
	180	355.7679
	145	357.3499
	78	359.7271
	107	378.5330
	17	391.6625
	156	399.4463
	76	410.1112
	0	415.2489
	96	437.2630
	46	439.3421
	2	442.4801
	35	442.4812
	64	452.2543
	128	453.5696
	141	464.6295
	93	469.9462
	21	480.9774
	117	482.3959
	6	489.8026
	73	492.7455
	11	501.1917
	62	517.6446
	0	4015 0000
	8	4015.0000
	118 190	4015.0000 4015.0000
	69	4015.0000
	193	4015.0000
	194	4015.0000
	12	4015.0000
	47	4015.0000
	75	4015.0000
	27	4015.0000
	82	4015.0000
	104	4015.0000
	153	4015.0000
	100	±010.0000

```
138
                4015.0000
         136
                4015.0000
         157
                4015.0000
         159
                4015.0000
         41
                4015.0000
         125
                4015.0000
         74
                4015.0000
         84
                4015.0000
                4015.0000
         166
         29
                4015.0000
         169
                4015.0000
         171
                4015.0000
         172
                4015.0000
         144
                4015.0000
         175
                4015.0000
         131
                4015.0000
         42
                4015.0000
         Name: part_time, Length: 200, dtype: float64
In [12]: obs_df.loc[idx,pst.nnz_obs_names]
Out[12]: fo_39_19791230
                                10555.000000
         hds_00_002_009_000
                                    34.847549
         hds_00_002_015_000
                                   34.639633
         hds_00_003_008_000
                                   34.861164
         hds_00_009_001_000
                                   35.161556
         hds_00_013_010_000
                                   34.661835
         hds_00_015_016_000
                                   34.569942
         hds_00_021_010_000
                                   34.571648
         hds_00_022_015_000
                                   34.439877
         hds_00_024_004_000
                                   34.609158
         hds_00_026_006_000
                                    34.521420
         hds_00_029_015_000
                                    34.297997
         hds_00_033_007_000
                                    34.187607
         hds_00_034_010_000
                                    33.842358
         Name: 64, dtype: float64
   Lets see how our selected truth does with the sw/gw forecasts:
```

```
In [13]: obs_df.loc[idx,fnames]
```

```
Out[13]: fa_hw_19791230
                               -992.855500
         fa_hw_19801229
                                -73.877930
         fa_tw_19791230
                               -256.953300
         fa_tw_19801229
                                368.869266
         hds_00_013_002_000
                                 35.032547
         hds_00_013_002_001
                                 34.416519
         part_time
                                452.254300
         part_status
                                  2.000000
```

Name: 64, dtype: float64

Assign some initial weights. Now, it is custom to add noise to the observed values...we will use the classic Gaussian noise...zero mean and standard deviation of 1 over the weight

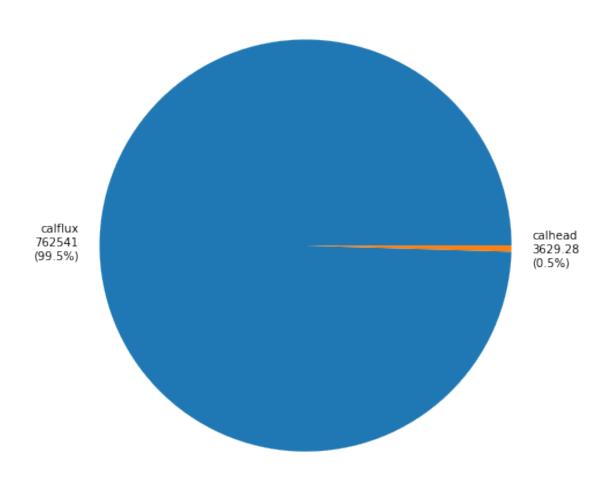
```
In [14]: pst = pyemu.Pst(os.path.join(t_d,"freyberg.pst"))
        obs = pst.observation_data
        obs.loc[:,"obsval"] = obs_df.loc[idx,pst.obs_names]
        obs.loc[obs.obgnme=="calhead","weight"] = 10.0
        obs.loc[obs.obgnme=="calflux","weight"] = 1.0
```

here we just get a sample from a random normal distribution with mean=0 and std=1. The argument indicates how many samples we want - and we choose pst.nnz_obs which is the the number of nonzero-weighted observations in the PST file

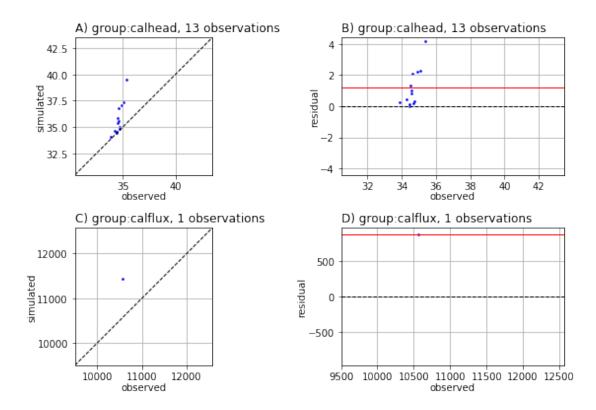
```
In [15]: np.random.seed(seed=0)
         snd = np.random.randn(pst.nnz_obs)
         noise = snd * 1./obs.loc[pst.nnz_obs_names,"weight"]
         pst.observation_data.loc[noise.index,"obsval"] += noise
         noise
Out[15]: obsnme
         fo_39_19791230
                               1.764052
         hds_00_002_009_000
                               0.040016
         hds_00_002_015_000
                               0.097874
         hds_00_003_008_000
                               0.224089
         hds_00_009_001_000
                               0.186756
         hds_00_013_010_000
                              -0.097728
         hds_00_015_016_000
                               0.095009
         hds_00_021_010_000
                              -0.015136
         hds_00_022_015_000
                              -0.010322
         hds_00_024_004_000
                               0.041060
         hds 00 026 006 000
                               0.014404
         hds_00_029_015_000
                               0.145427
         hds 00 033 007 000
                               0.076104
         hds_00_034_010_000
                               0.012168
         Name: weight, dtype: float64
```

Then we write this out to a new file and run pestpp-ies to see how the objective function looks

Now we can read in the results and make some figures showing residuals and the balance of the objective function



<Figure size 576x756 with 0 Axes>



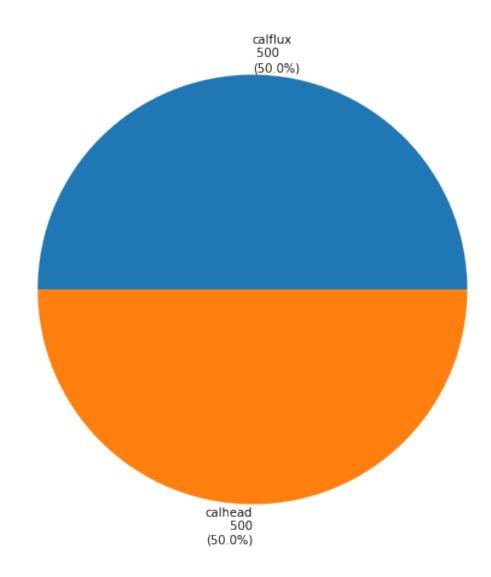
Out[17]:
name group measured modelled \

name				
fo_39_19791230	fo_39_19791230	calflux	10556.764052	11430.000000
hds_00_002_009_000	hds_00_002_009_000	calhead	34.887565	37.107498
hds_00_002_015_000	hds_00_002_015_000	calhead	34.737507	35.045185
hds_00_003_008_000	hds_00_003_008_000	calhead	35.085253	37.397289
hds_00_009_001_000	hds_00_009_001_000	calhead	35.348312	39.546417
hds_00_013_010_000	hds_00_013_010_000	calhead	34.564107	35.571774
hds_00_015_016_000	hds_00_015_016_000	calhead	34.664951	34.835716
hds_00_021_010_000	hds_00_021_010_000	calhead	34.556512	35.386250
hds_00_022_015_000	hds_00_022_015_000	calhead	34.429555	34.577492
hds_00_024_004_000	hds_00_024_004_000	calhead	34.650217	36.760464
hds_00_026_006_000	hds_00_026_006_000	calhead	34.535824	35.896149
hds_00_029_015_000	hds_00_029_015_000	calhead	34.443424	34.453842
hds_00_033_007_000	hds_00_033_007_000	calhead	34.263711	34.678810
hds_00_034_010_000	hds_00_034_010_000	calhead	33.854525	34.118073
	residual weight			
name				
fo_39_19791230	-873.235948 1.0			
hds_00_002_009_000	-2.219933 10.0			
hds_00_002_015_000	-0.307678 10.0			
hds_00_003_008_000	-2.312036 10.0			
hds_00_009_001_000	-4.198105 10.0			
hds_00_013_010_000	-1.007667 10.0			
hds_00_015_016_000	-0.170765 10.0			
hds_00_021_010_000	-0.829738 10.0			
hds_00_022_015_000	-0.147937 10.0			
hds_00_024_004_000	-2.110246 10.0			
hds_00_026_006_000	-1.360325 10.0			
hds_00_029_015_000	-0.010418 10.0			
hds_00_033_007_000	-0.415100 10.0			
hds_00_034_010_000	-0.263547 10.0			

Publication ready figs - oh snap!

Depending on the truth you chose, we may have a problem - we set the weights for both the heads and the flux to reasonable values based on what we expect for measurement noise. But the contributions to total phi might be out of balance - if contribution of the flux measurement to total phi is too low, the history matching excersizes (coming soon!) will focus almost entirely on minimizing head residuals. So we need to balance the objective function. This is a subtle but very important step, especially since some of our forecasts deal with sw-gw exchange

```
In [18]: pc = pst.phi_components
    #target = {"calflux":0.3 * pc["calhead"]}
    target = {"calhead":500,"calflux":500}
    pst.adjust_weights(obsgrp_dict=target)
    pst.plot(kind='phi_pie')
Out[18]: <matplotlib.axes._subplots.AxesSubplot at 0x10ec8f2b0>
```



Lets see what the new flux observation weight is:

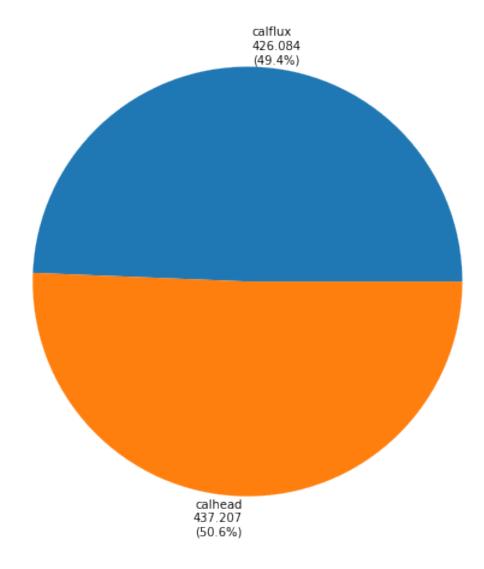
```
In [19]: pst.observation_data.loc[pst.nnz_obs_names,"weight"]
```

Out[19]: obsnme fo_39_19791230 0.025607 hds_00_002_009_000 3.711718 hds_00_002_015_000 3.711718 hds_00_003_008_000 3.711718 hds_00_009_001_000 3.711718 hds_00_013_010_000 3.711718 hds_00_015_016_000 3.711718 hds_00_021_010_000 3.711718 hds_00_022_015_000 3.711718

```
hds_00_024_004_000 3.711718
hds_00_026_006_000 3.711718
hds_00_029_015_000 3.711718
hds_00_033_007_000 3.711718
hds_00_034_010_000 3.711718
Name: weight, dtype: float64
```

Now, for some super trickery: since we changed the weight, we need to generate the observation noise using these new weights for the error model (so meta!)

```
In [20]: obs = pst.observation_data
         np.random.seed(seed=0)
         snd = np.random.randn(pst.nnz_obs)
         noise = snd * 1./obs.loc[pst.nnz_obs_names,"weight"]
         obs.loc[:,"obsval"] = obs df.loc[idx.pst.obs names]
         pst.observation_data.loc[noise.index,"obsval"] += noise
         noise
Out[20]: obsnme
         fo_39_19791230
                               68.890299
         hds_00_002_009_000
                                0.107809
         hds_00_002_015_000
                                0.263689
         hds_00_003_008_000
                                0.603735
         hds_00_009_001_000
                                0.503152
         hds_00_013_010_000
                               -0.263295
         hds 00 015 016 000
                                0.255970
         hds_00_021_010_000
                               -0.040778
         hds_00_022_015_000
                               -0.027809
         hds_00_024_004_000
                                0.110622
         hds_00_026_006_000
                                0.038808
         hds_00_029_015_000
                                0.391806
         hds_00_033_007_000
                                0.205037
         hds_00_034_010_000
                                0.032781
         Name: weight, dtype: float64
In [21]: pst.write(os.path.join(t_d, "freyberg.pst"))
         pyemu.os_utils.run("pestpp-ies freyberg.pst",cwd=t_d)
         pst = pyemu.Pst(os.path.join(t_d, "freyberg.pst"))
         print(pst.phi)
         pst.plot(kind='phi_pie')
         plt.show()
noptmax:0, npar_adj:14819, nnz_obs:14
863.2909159111605
```



Whew! confused yet? Ok, let's leave all this confusion behind...its mostly academic, just to make sure we are using weights that are in harmony with the noise we added to the truth...Just to make sure we have everything working right, we should be able to load the truth parameters, run the model once and have a phi equivalent to the noise vector:

we will run this with noptmax=0 to preform a single run. Pro-tip: you can use any of the pestpp-### binaries/executables to run noptmax=0

17.528847196782618

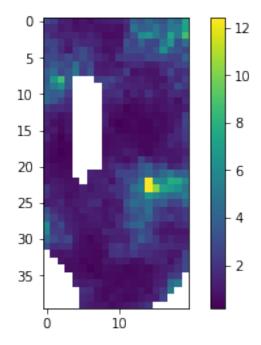
Out[23]:			name	group	measured	modelled	\
	name						
	fo_39_19791230	fo_39_	19791230	calflux	10623.890299	10555.000000	
	hds_00_002_009_000	hds_00_002	_009_000	calhead	34.955359	34.847549	
	hds_00_002_015_000	hds_00_002	_015_000	calhead	34.903322	34.639633	
	hds_00_003_008_000	hds_00_003	_008_000	calhead	35.464899	34.861164	
	hds_00_009_001_000	hds_00_009	_001_000	calhead	35.664708	35.161556	
	hds_00_013_010_000	hds_00_013	_010_000	calhead	34.398539	34.661835	
	hds_00_015_016_000	hds_00_015	_016_000	calhead	34.825912	34.569942	
	hds_00_021_010_000	hds_00_021	_010_000	calhead	34.530869	34.571648	
	hds_00_022_015_000	hds_00_022	_015_000	calhead	34.412068	34.439877	
	hds_00_024_004_000	hds_00_024	_004_000	calhead	34.719780	34.609158	
	hds_00_026_006_000	hds_00_026	_006_000	calhead	34.560227	34.521420	
	hds_00_029_015_000	hds_00_029	_015_000	calhead	34.689803	34.297997	
	hds_00_033_007_000	hds_00_033	_007_000	calhead	34.392643	34.187607	
	hds_00_034_010_000	hds_00_034	_010_000	calhead	33.875139	33.842358	
		residual	weight				
	name						
	fo_39_19791230	68.890299	0.025607				
	hds_00_002_009_000	0.107809	3.711718				
	hds_00_002_015_000	0.263689	3.711718				
	hds_00_003_008_000	0.603735	3.711718				
	hds_00_009_001_000	0.503152	3.711718				
	hds_00_013_010_000	-0.263295	3.711718				
	hds_00_015_016_000	0.255970	3.711718				
	hds_00_021_010_000	-0.040778	3.711718				
	hds_00_022_015_000	-0.027809	3.711718				
	hds_00_024_004_000	0.110622	3.711718				
	hds_00_026_006_000	0.038808	3.711718				
	hds_00_029_015_000	0.391806	3.711718				
	hds_00_033_007_000	0.205037	3.711718				
	hds_00_034_010_000	0.032781	3.711718				

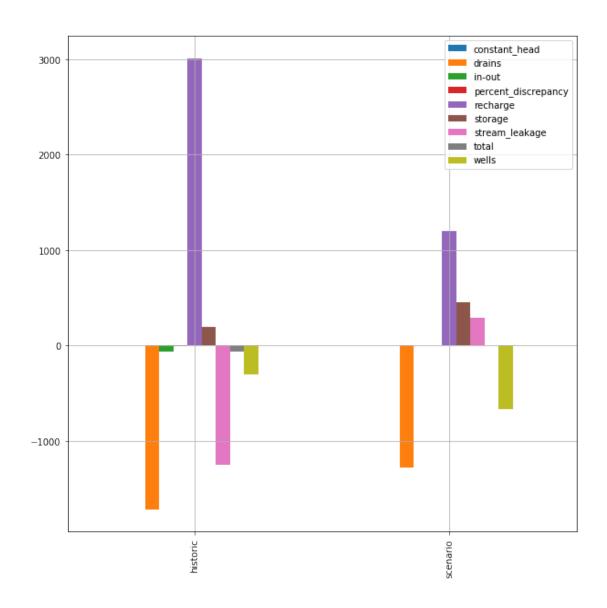
The residual should be exactly the noise values from above.Lets load the model (that was just run using the true pars) and check some things

```
In [24]: m = flopy.modflow.Modflow.load("freyberg.nam",model_ws=m_d)
In [25]: a = m.upw.hk[0].array
    #a = m.rch.rech[0].array
```

```
a = np.ma.masked_where(m.bas6.ibound[0].array==0,a)
print(a.min(),a.max())
c = plt.imshow(a)
plt.colorbar()
plt.show()
```

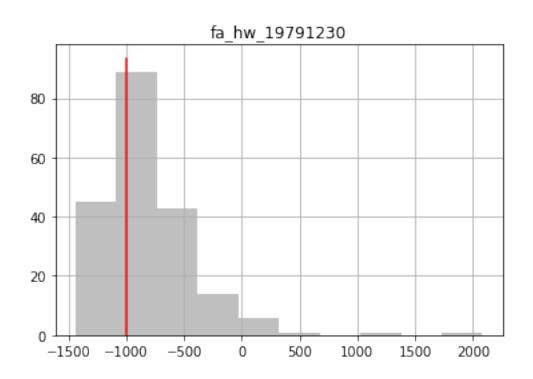
0.1996812 12.40834

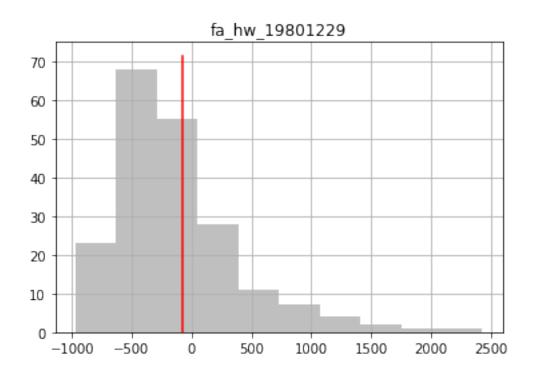


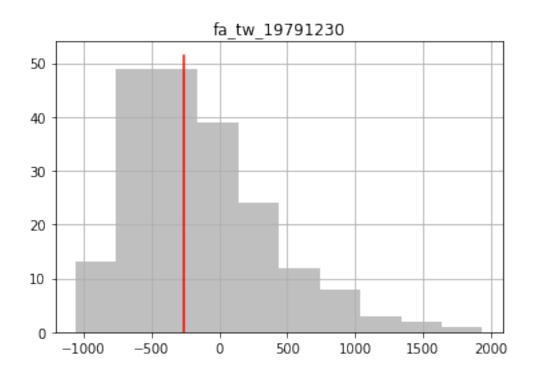


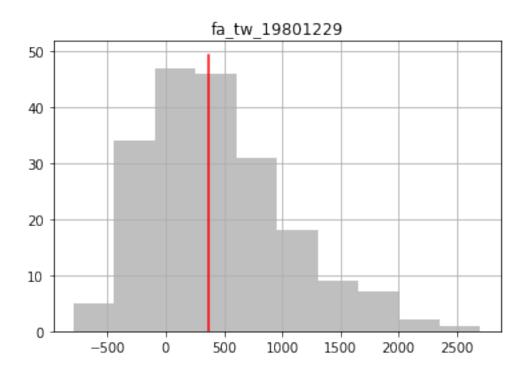
1.0.8 see how our existing observation ensemble compares to the truth

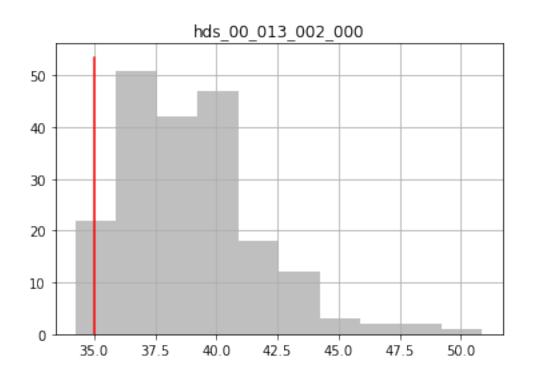
forecasts:

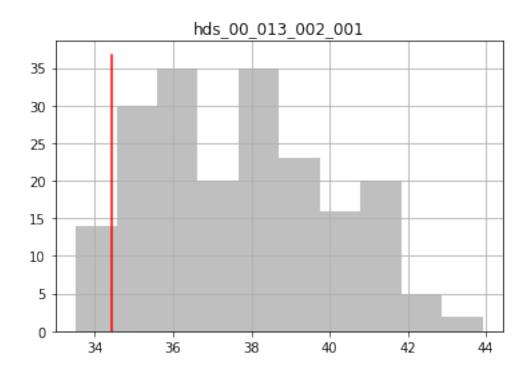


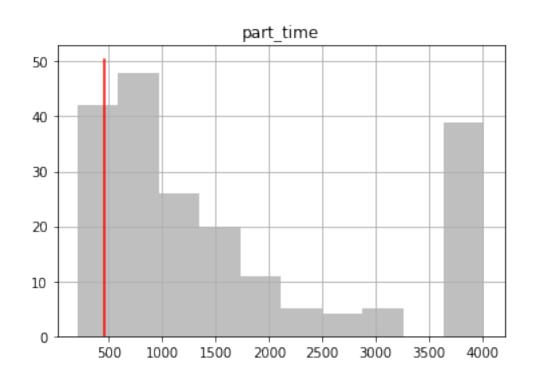


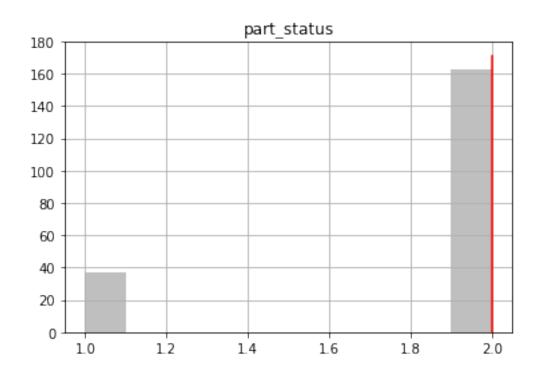












observations:

