prior_montecarlo

May 12, 2019

1 Run and process the prior monte carlo and pick a "truth" realization

A great advantage of exploring a synthetic model is that we can enforce a "truth" and then evaluate how our various attempts to estimate it perform. One way to do this is to run a monte carlo ensemble of multiple parameter realizations and then choose one of them to represent the "truth". That will be accomplished in this notebook.

```
In [1]: import os
    import shutil
    import numpy as np
    import pandas as pd
    import matplotlib.pyplot as plt
    import matplotlib as mpl
    plt.rcParams['font.size']=12
    import flopy
    import pyemu
```

flopy is installed in /Users/jeremyw/Dev/gw1876/activities_2day_mfm/notebooks/flopy

1.0.1 set the t_d or "template directory" variable to point at the template folder and read in the PEST control file

1.0.2 Decide what pars are uncertain in the truth

We need to decide what our truth looks like - should the pilot points or the grid-scale pars be the source of spatial variability? or both?

```
In [3]: par = pst.parameter_data
    # grid pars
    #should_fix = par.loc[par.pargp.apply(lambda x: "gr" in x), "parnme"]
    # pp pars
    #should_fix = par.loc[par.pargp.apply(lambda x: "pp" in x), "parnme"]
    #pst.npar - should_fix.shape[0]
```

1.0.3 run the prior ensemble in parallel locally

This takes advantage of the program pestpp-swp which runs a parameter sweep through a set of parameters. By default, pestpp-swp reads in the ensemble from a file called sweep_in.csv which in this case we made just above.

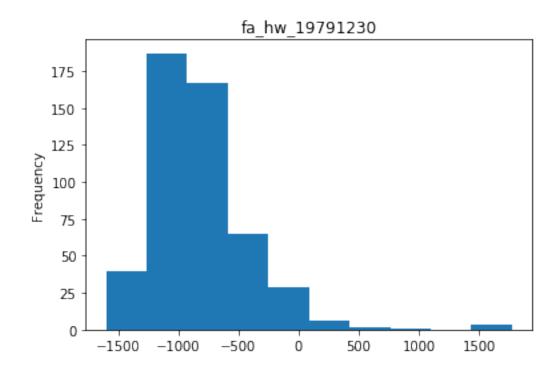
print('number of realization in the ensemble before dropping: ' + str(obs_df.shape[0])

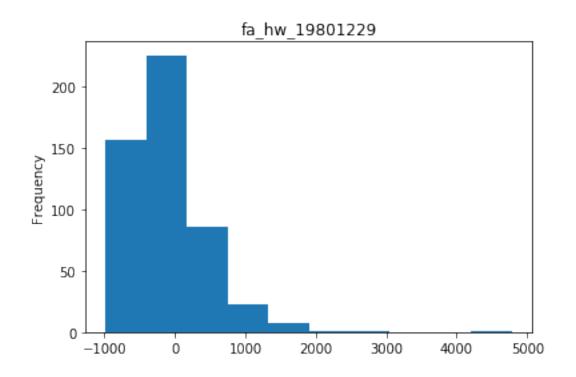
number of realization in the ensemble before dropping: 500

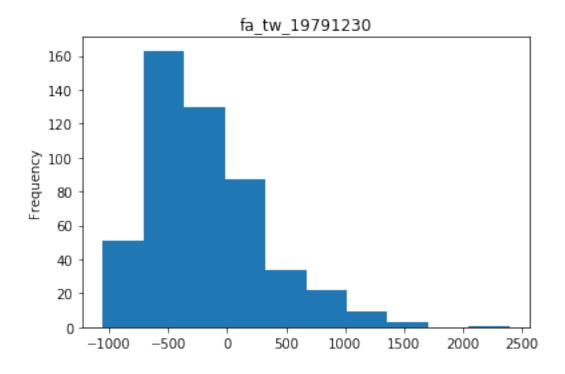
drop any failed runs

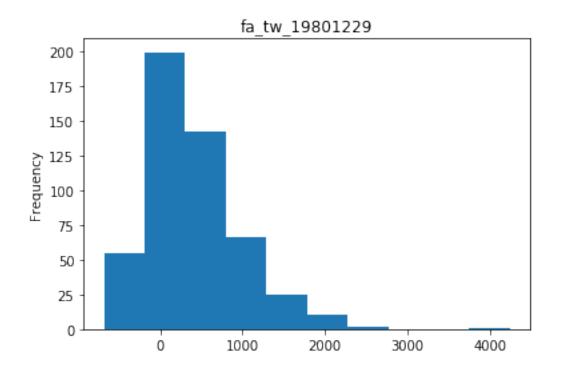
1.0.5 confirm which quantities were identified as forecasts

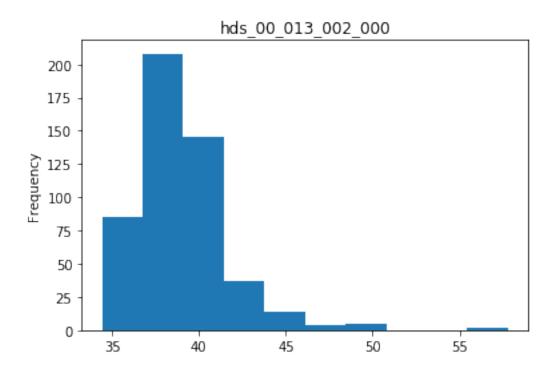
1.0.6 now we can plot the distributions of each forecast

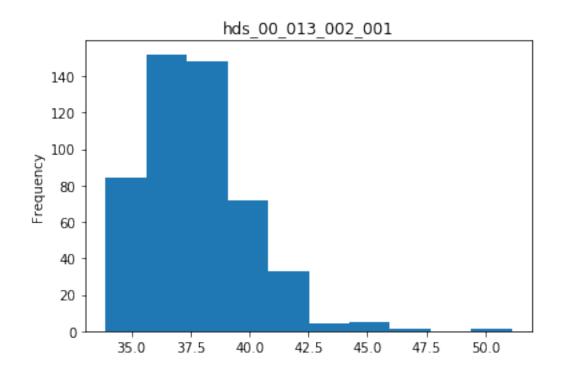


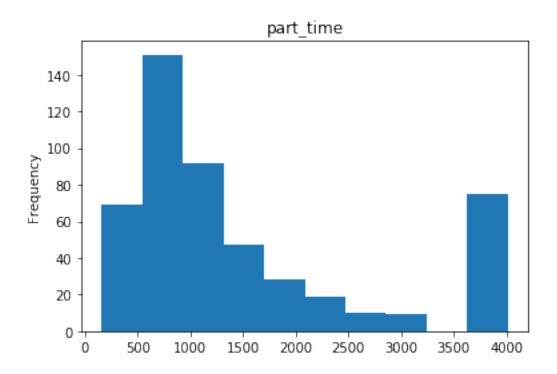


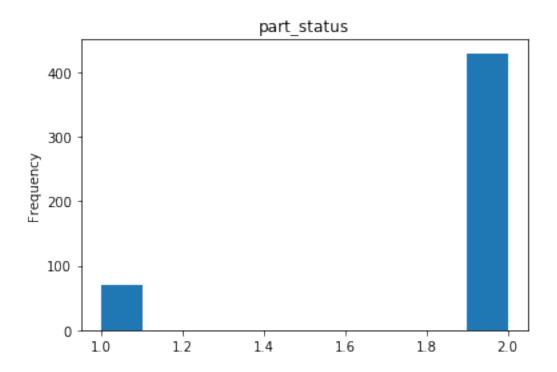






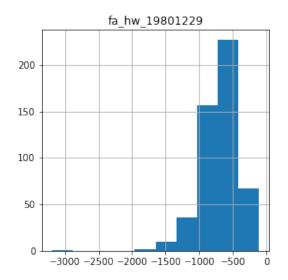


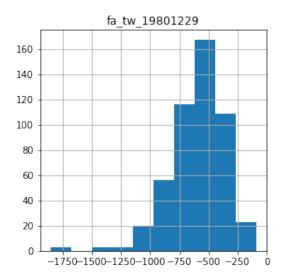


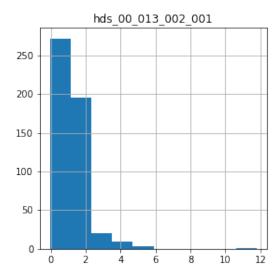


We see that under scenario conditions, many more realizations for the flow to the aquifer in the headwaters are postive (as expected). Lets difference these two:

```
In [10]: sfnames = [f for f in fnames if "1980" in f or "_001" in f]
    hfnames = [f for f in fnames if "1979" in f or "_000" in f]
    diff = obs_df.loc[:,hfnames].values - obs_df.loc[:,sfnames].values
    diff = pd.DataFrame(diff,columns=sfnames)
    diff.hist(figsize=(10,10))
    plt.show()
```







We now see that the most extreme scenario yields a large decrease in flow from the aquifer to the headwaters (the most negative value)

1.0.7 setting the "truth"

We just need to replace the observed values (obsval) in the control file with the outputs for one of the realizations on obs_df. In this way, we now have the nonzero values for history matching, but also the truth values for comparing how we are doing with other unobserved quantities. I'm going to pick a realization that yields an "average" variability of the observed gw levels:

idx hist_swgw

Out[11]:	run_id	
	318	158.7090
	262	217.6370
	375	259.8265
	77	267.3188
	18	274.6335
	244	281.7578
	92	290.7109
	155	294.9453
	19	297.6992
	101	303.7151
	466	311.5639
	197	316.1725
	420	319.5435
	394	327.7793
	161	336.5960
	97	349.8065
	201	351.5172
	65	356.3551
	418	357.8107
	258	358.4687
	332	360.7590
	136	368.0700
	33	368.8190
	36	372.1028
	241	379.1664
	38	381.2636
	355	382.4316
	465	384.3039
	400	385.1978
	60	387.0248
	189	4015.0000
	195	4015.0000
	196	4015.0000
	384	4015.0000
	412	4015.0000
	163	4015.0000
	362	4015.0000
	361	4015.0000
	252	4015.0000
	449	4015.0000
	251	4015.0000
	90	4015.0000
	91	4015.0000

```
247
                4015.0000
         112
                4015.0000
         242
                4015.0000
         434
                4015.0000
         453
                4015.0000
         352
                4015.0000
         354
                4015.0000
         240
                4015.0000
         428
                4015.0000
         356
                4015.0000
         357
                4015.0000
         239
                4015.0000
         151
                4015.0000
         419
                4015.0000
         154
                4015.0000
         132
                4015.0000
         306
                4015.0000
         Name: part_time, Length: 500, dtype: float64
In [12]: obs_df.loc[idx,pst.nnz_obs_names]
Out[12]: fo_39_19791230
                                9369.600000
         hds_00_002_009_000
                                  35.040295
         hds_00_002_015_000
                                  34.594372
         hds_00_003_008_000
                                  35.058357
         hds_00_009_001_000
                                  35.516644
         hds_00_013_010_000
                                  34.704311
         hds_00_015_016_000
                                  34.378880
         hds_00_021_010_000
                                  34.129391
         hds_00_022_015_000
                                  34.134243
         hds_00_024_004_000
                                  34.152634
         hds_00_026_006_000
                                  33.933083
         hds_00_029_015_000
                                  33.993011
         hds_00_033_007_000
                                  33.456963
         hds_00_034_010_000
                                  33.334564
         Name: 332, dtype: float64
   Lets see how our selected truth does with the sw/gw forecasts:
```

```
In [13]: obs_df.loc[idx,fnames]
```

```
Out[13]: fa_hw_19791230
                                -620.622650
         fa_hw_19801229
                                 109.754350
         fa_tw_19791230
                                1239.639600
         fa_tw_19801229
                                1936.065600
         hds_00_013_002_000
                                  35.594288
         hds_00_013_002_001
                                  34.781490
         part_time
                                 360.759000
                                   2.000000
         part_status
         Name: 332, dtype: float64
```

Assign some initial weights. Now, it is custom to add noise to the observed values...we will use the classic Gaussian noise...zero mean and standard deviation of 1 over the weight

```
In [14]: pst = pyemu.Pst(os.path.join(t_d,"freyberg.pst"))
        obs = pst.observation_data
        obs.loc[:,"obsval"] = obs_df.loc[idx,pst.obs_names]
        obs.loc[obs.obgnme=="calhead","weight"] = 10.0
        obs.loc[obs.obgnme=="calflux","weight"] = 1.0
```

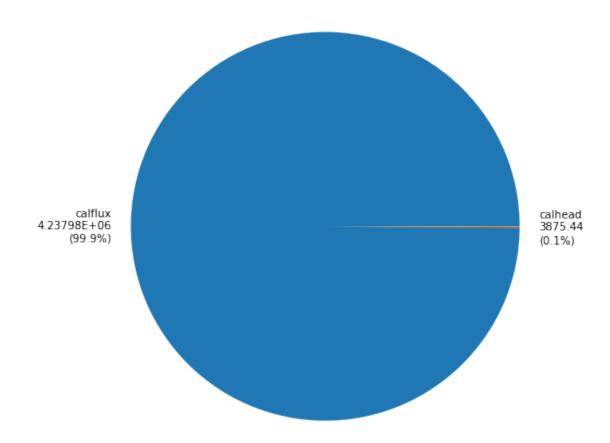
here we just get a sample from a random normal distribution with mean=0 and std=1. The argument indicates how many samples we want - and we choose pst.nnz_obs which is the the number of nonzero-weighted observations in the PST file

```
In [15]: np.random.seed(seed=0)
         snd = np.random.randn(pst.nnz_obs)
         noise = snd * 1./obs.loc[pst.nnz_obs_names,"weight"]
         pst.observation_data.loc[noise.index,"obsval"] += noise
         noise
Out[15]: obsnme
         fo_39_19791230
                               1.764052
         hds_00_002_009_000
                               0.040016
         hds_00_002_015_000
                               0.097874
         hds_00_003_008_000
                               0.224089
         hds_00_009_001_000
                               0.186756
         hds_00_013_010_000
                              -0.097728
         hds_00_015_016_000
                               0.095009
         hds_00_021_010_000
                              -0.015136
         hds_00_022_015_000
                              -0.010322
         hds_00_024_004_000
                               0.041060
         hds 00 026 006 000
                               0.014404
         hds_00_029_015_000
                               0.145427
         hds 00 033 007 000
                               0.076104
         hds_00_034_010_000
                               0.012168
         Name: weight, dtype: float64
```

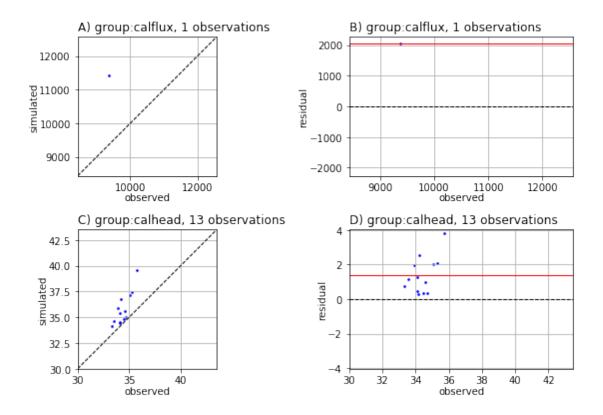
Then we write this out to a new file and run pestpp-ies to see how the objective function looks

Now we can read in the results and make some figures showing residuals and the balance of the objective function

<Figure size 432x288 with 0 Axes>



<Figure size 576x756 with 0 Axes>

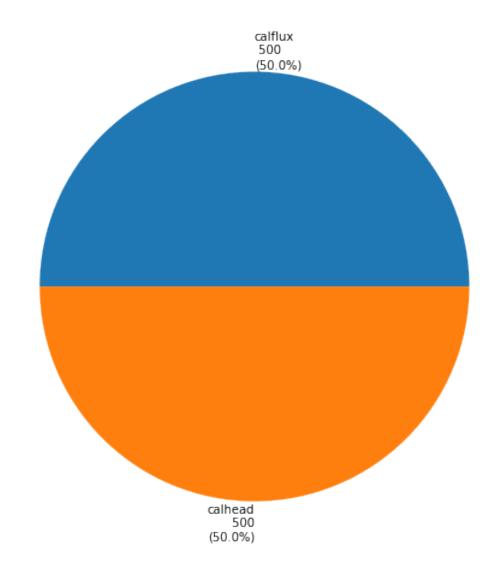


Out[17]:		name	group	measured	modelled	\
	name					
	fo_39_19791230	fo_39_19791230		9371.364052	11430.000000	
	hds_00_002_009_000	hds_00_002_009_000		35.080310	37.107498	
	hds_00_002_015_000	hds_00_002_015_000		34.692246	35.045185	
	hds_00_003_008_000	hds_00_003_008_000		35.282447	37.397289	
	hds_00_009_001_000	hds_00_009_001_000		35.703399	39.546417	
	hds_00_013_010_000	hds_00_013_010_000		34.606584	35.571774	
	hds_00_015_016_000	hds_00_015_016_000		34.473888	34.835716	
	hds_00_021_010_000	hds_00_021_010_000		34.114255	35.386250	
	hds_00_022_015_000	hds_00_022_015_000	calhead	34.123921	34.577492	
	hds_00_024_004_000	hds_00_024_004_000	calhead	34.193694	36.760464	
	hds_00_026_006_000	hds_00_026_006_000	calhead	33.947487	35.896149	
	hds_00_029_015_000	hds_00_029_015_000	calhead	34.138439	34.453842	
	hds_00_033_007_000	hds_00_033_007_000	calhead	33.533066	34.678810	
	hds_00_034_010_000	hds_00_034_010_000	calhead	33.346732	34.118073	
		residual weigh	τ			
	name	0050 005040	•			
	fo_39_19791230	-2058.635948 1.				
	hds_00_002_009_000	-2.027188 10.				
	hds_00_002_015_000	-0.352939 10.				
	hds_00_003_008_000	-2.114843 10.				
	hds_00_009_001_000	-3.843018 10.				
	hds_00_013_010_000	-0.965190 10.				
	hds_00_015_016_000	-0.361828 10.				
	hds_00_021_010_000	-1.271995 10.				
	hds_00_022_015_000	-0.453571 10.	0			
	hds_00_024_004_000	-2.566770 10.	0			
	hds_00_026_006_000	-1.948662 10.	0			
	hds_00_029_015_000	-0.315403 10.	0			
	hds_00_033_007_000	-1.145744 10.	0			
	hds_00_034_010_000	-0.771341 10.	0			

Publication ready figs - oh snap!

Depending on the truth you chose, we may have a problem - we set the weights for both the heads and the flux to reasonable values based on what we expect for measurement noise. But the contributions to total phi might be out of balance - if contribution of the flux measurement to total phi is too low, the history matching excersizes (coming soon!) will focus almost entirely on minimizing head residuals. So we need to balance the objective function. This is a subtle but very important step, especially since some of our forecasts deal with sw-gw exchange

```
In [18]: pc = pst.phi_components
    #target = {"calflux":0.3 * pc["calhead"]}
    target = {"calhead":500,"calflux":500}
    pst.adjust_weights(obsgrp_dict=target)
    pst.plot(kind='phi_pie')
Out[18]: <matplotlib.axes._subplots.AxesSubplot at 0x181fd71828>
```



Lets see what the new flux observation weight is:

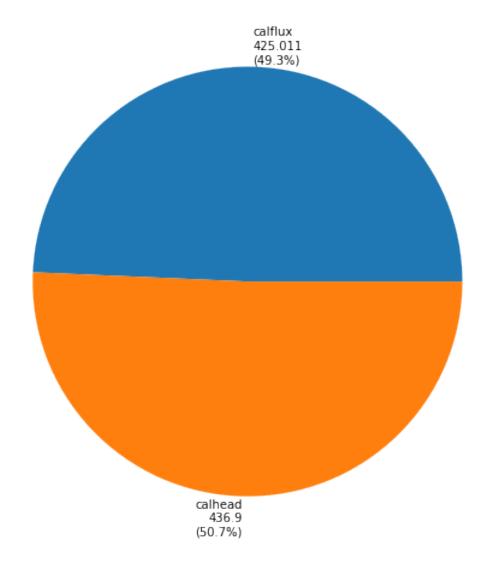
```
In [19]: pst.observation_data.loc[pst.nnz_obs_names,"weight"]
```

Out[19]: obsnme fo_39_19791230 0.010862 hds_00_002_009_000 3.591903 hds_00_002_015_000 3.591903 hds_00_003_008_000 3.591903 hds_00_009_001_000 3.591903 hds_00_013_010_000 3.591903 hds_00_015_016_000 3.591903 hds_00_021_010_000 3.591903 hds_00_022_015_000 3.591903

```
hds_00_024_004_000 3.591903
hds_00_026_006_000 3.591903
hds_00_029_015_000 3.591903
hds_00_033_007_000 3.591903
hds_00_034_010_000 3.591903
Name: weight, dtype: float64
```

Now, for some super trickery: since we changed the weight, we need to generate the observation noise using these new weights for the error model (so meta!)

```
In [20]: obs = pst.observation_data
         np.random.seed(seed=0)
         snd = np.random.randn(pst.nnz_obs)
         noise = snd * 1./obs.loc[pst.nnz_obs_names,"weight"]
         obs.loc[:,"obsval"] = obs df.loc[idx.pst.obs names]
         pst.observation_data.loc[noise.index,"obsval"] += noise
         noise
Out[20]: obsnme
         fo_39_19791230
                               162.407476
         hds_00_002_009_000
                                 0.111405
         hds_00_002_015_000
                                 0.272485
         hds_00_003_008_000
                                 0.623873
         hds_00_009_001_000
                                 0.519936
         hds_00_013_010_000
                                -0.272078
         hds 00 015 016 000
                                 0.264508
         hds 00 021 010 000
                                -0.042138
         hds 00 022 015 000
                                -0.028737
         hds_00_024_004_000
                                 0.114312
         hds_00_026_006_000
                                 0.040102
         hds_00_029_015_000
                                 0.404875
         hds_00_033_007_000
                                 0.211876
         hds_00_034_010_000
                                 0.033875
         Name: weight, dtype: float64
In [21]: pst.write(os.path.join(t_d, "freyberg.pst"))
         pyemu.os_utils.run("pestpp-ies freyberg.pst",cwd=t_d)
         pst = pyemu.Pst(os.path.join(t_d, "freyberg.pst"))
         print(pst.phi)
         pst.plot(kind='phi_pie')
         plt.show()
noptmax:0, npar_adj:14819, nnz_obs:14
861.9109104046662
```



Whew! confused yet? Ok, let's leave all this confusion behind...its mostly academic, just to make sure we are using weights that are in harmony with the noise we added to the truth...Just to make sure we have everything working right, we should be able to load the truth parameters, run the model once and have a phi equivalent to the noise vector:

we will run this with noptmax=0 to preform a single run. Pro-tip: you can use any of the pestpp-### binaries/executables to run noptmax=0

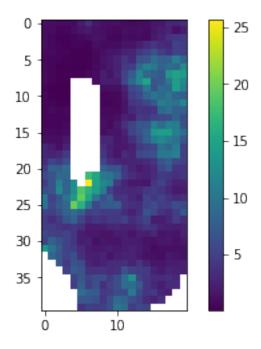
17.528847233972552

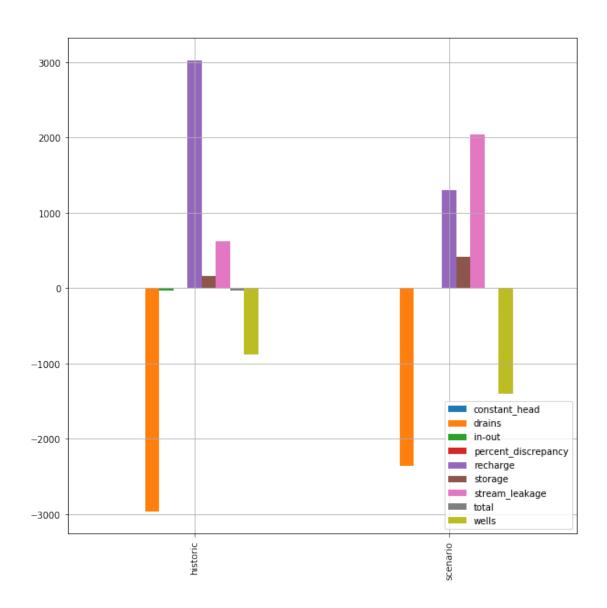
Out[23]:			name	group	measured	modelled	\
	name	£- 20 1	0701020	141	0520 007476	0260 600000	
	fo_39_19791230		9791230	calflux	9532.007476	9369.600000	
	hds_00_002_009_000	hds_00_002_	_	calhead	35.151700	35.040295	
	hds_00_002_015_000	hds_00_002_	_	calhead	34.866856	34.594372	
	hds_00_003_008_000	hds_00_003_	_	calhead	35.682231	35.058357	
	hds_00_009_001_000	hds_00_009_	_	calhead	36.036579	35.516644	
	hds_00_013_010_000	hds_00_013_	_	calhead	34.432233	34.704311	
	hds_00_015_016_000	hds_00_015_	_	calhead	34.643388	34.378880	
	hds_00_021_010_000	hds_00_021_		calhead	34.087252	34.129391	
	hds_00_022_015_000	hds_00_022_		calhead	34.105506	34.134243	
	hds_00_024_004_000	hds_00_024_	_	calhead	34.266946	34.152634	
	hds_00_026_006_000	hds_00_026_	_	calhead	33.973185	33.933083	
	hds_00_029_015_000	hds_00_029_	_	calhead	34.397887	33.993011	
	hds_00_033_007_000	hds_00_033_	007_000	calhead	33.668838	33.456963	
	hds_00_034_010_000	hds_00_034_	010_000	calhead	33.368439	33.334564	
		residual	weigh	t			
	name						
	fo_39_19791230	162.407476	0.01086				
	hds_00_002_009_000	0.111405	3.59190				
	hds_00_002_015_000	0.272485	3.59190				
	hds_00_003_008_000	0.623873	3.59190				
	hds_00_009_001_000	0.519936	3.59190				
	hds_00_013_010_000	-0.272078	3.59190	3			
	hds_00_015_016_000	0.264508	3.59190	3			
	hds_00_021_010_000	-0.042138	3.59190	3			
	hds_00_022_015_000	-0.028737	3.59190	3			
	hds_00_024_004_000	0.114312	3.59190	3			
	hds_00_026_006_000	0.040102	3.59190	3			
	hds_00_029_015_000	0.404875	3.59190	3			
	hds_00_033_007_000	0.211876	3.59190	3			
	hds_00_034_010_000	0.033875	3.59190	3			

The residual should be exactly the noise values from above.Lets load the model (that was just run using the true pars) and check some things

```
a = np.ma.masked_where(m.bas6.ibound[0].array==0,a)
print(a.min(),a.max())
c = plt.imshow(a)
plt.colorbar()
plt.show()
```

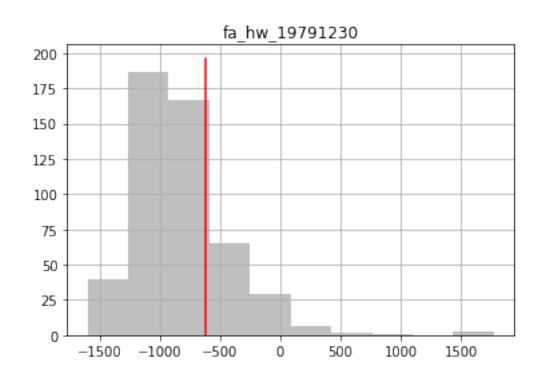
0.09253527 25.65187

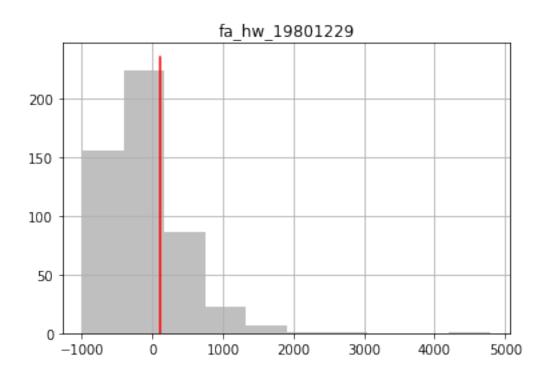


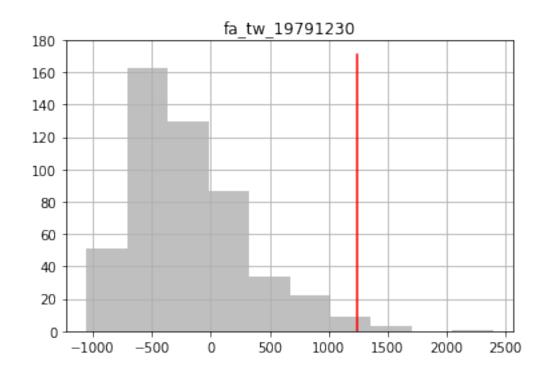


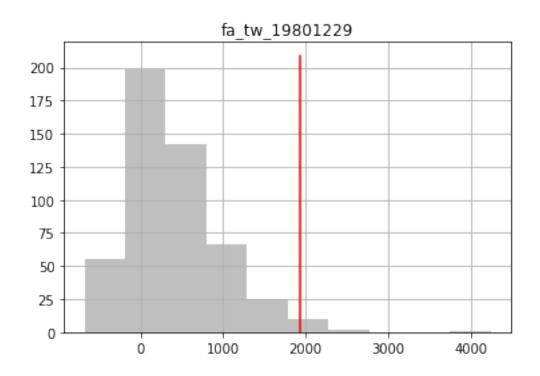
1.0.8 see how our existing observation ensemble compares to the truth

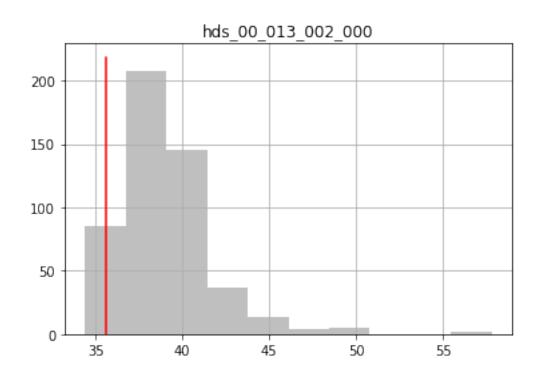
forecasts:

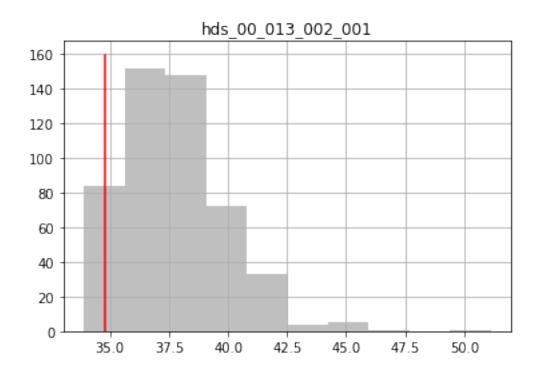


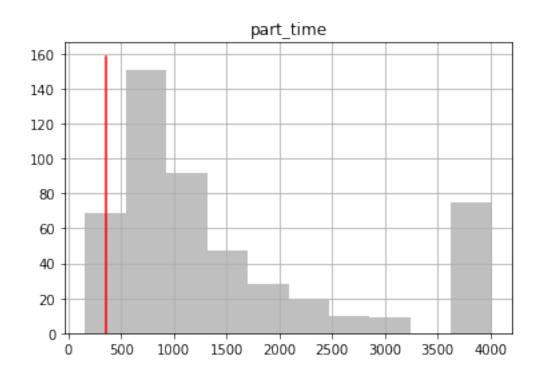


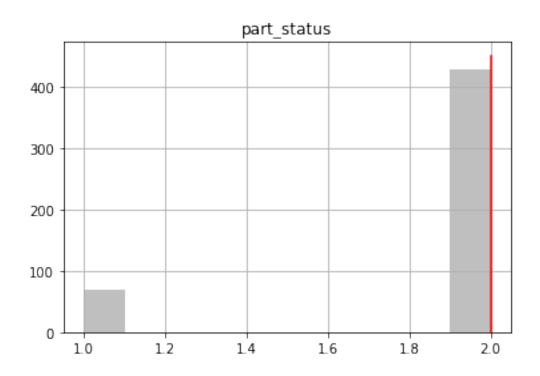












observations:

