prior_montecarlo

April 29, 2019

1 Run and process the prior monte carlo and pick a "truth" realization

```
In [1]: import os
    import shutil
    import numpy as np
    import pandas as pd
    import flopy
    import pyemu

flopy is installed in /Users/jeremyw/Dev/gw1876/activities_2day_mfm/notebooks/flopy

In [2]: t_d = "template"
    pst = pyemu.Pst(os.path.join(t_d,"freyberg.pst"))
```

1.0.1 Decide what pars are uncertain in the truth

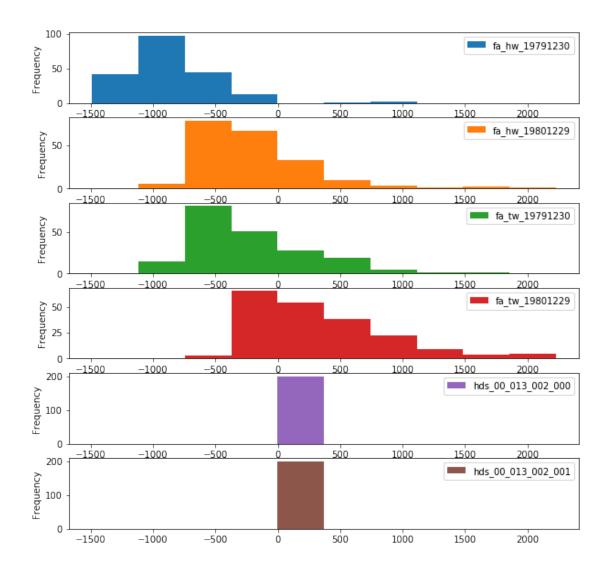
We need to decide what our truth looks like - should the pilot points or the grid-scale pars be the source of spatial variability?

```
In [3]: par = pst.parameter_data
    # grid pars
    #should_fix = par.loc[par.pargp.apply(lambda x: "gr" in x), "parnme"]
    # pp pars
    should_fix = par.loc[par.pargp.apply(lambda x: "pp" in x), "parnme"]
    #pst.npar - should_fix.shape[0]
In [4]: pe = pyemu.ParameterEnsemble.from_binary(pst=pst,filename=os.path.join(t_d,"prior.jcb" pe.loc[:,should_fix] = 1.0
    pe.to_csv(os.path.join(t_d,"sweep_in.csv"))
```

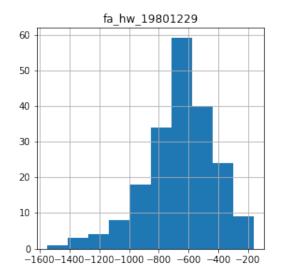
1.0.2 run the prior ensemble in parallel locally

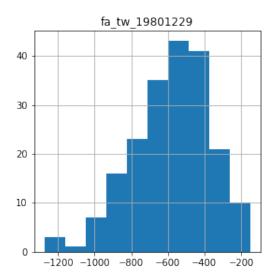
1.0.3 Load the output ensemble and plot a few things

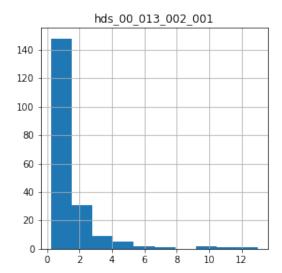
```
In [6]: obs_df = pd.read_csv(os.path.join(m_d, "sweep_out.csv"),index_col=0)
        obs_df.shape
Out[6]: (200, 4462)
  drop any failed runs
In [7]: obs_df = obs_df.loc[obs_df.failed_flag==0,:]
        obs df.shape
Out[7]: (200, 4462)
In [8]: fnames = pst.pestpp options["forecasts"].split(',')
        fnames
Out[8]: ['fa_hw_19791230',
         'fa_hw_19801229',
         'fa_tw_19791230',
         'fa_tw_19801229',
         'hds_00_013_002_000',
         'hds_00_013_002_001']
In [9]: obs_df.loc[:,fnames].plot(kind="hist",subplots=True,figsize=(10,10),sharex=False)
Out[9]: array([<matplotlib.axes._subplots.AxesSubplot object at 0x1091e2da0>,
               <matplotlib.axes._subplots.AxesSubplot object at 0x181e73a7f0>,
               <matplotlib.axes._subplots.AxesSubplot object at 0x109209d68>,
               <matplotlib.axes._subplots.AxesSubplot object at 0x10922b320>,
               <matplotlib.axes._subplots.AxesSubplot object at 0x109f16898>,
               <matplotlib.axes._subplots.AxesSubplot object at 0x109ee7e10>],
              dtype=object)
```



We see that under scenario conditions, many more realizations for the flow to the aquifer in the headwaters are postive (as expected). Lets difference these two:







We now see that the most extreme scenario yields a large decrease in flow from the aquifer to the headwaters (the most negative value)

1.0.4 setting the "truth"

We just need to replace the observed values (obsval) in the control file with the outputs for one of the realizations on obs_df. In this way, we now have the nonzero values for history matching, but also the truth values for comparing how we are doing with other unobserved quantities. Im going to pick a realization that yields an "average" variability of the observed gw levels:

```
Out[11]: 46
In [12]: obs_df.loc[idx,pst.nnz_obs_names]
Out[12]: fo_39_19791230
                                11925.000000
         hds 00 002 009 000
                                   35.557449
         hds_00_002_015_000
                                   34.771416
         hds_00_003_008_000
                                   35.705761
         hds 00 009 001 000
                                   37.410831
         hds_00_013_010_000
                                   35.260769
         hds_00_015_016_000
                                   34.869968
         hds_00_021_010_000
                                   35.211872
         hds_00_022_015_000
                                   34.578663
         hds_00_024_004_000
                                   36.148964
         hds_00_026_006_000
                                   35.571796
         hds_00_029_015_000
                                   34.557293
         hds_00_033_007_000
                                   34.680103
         hds_00_034_010_000
                                   34.403061
         Name: 46, dtype: float64
   Lets see how our selected truth does with the swgw forecasts:
In [13]: obs_df.loc[idx,fnames]
Out[13]: fa_hw_19791230
                               -1289.170400
         fa_hw_19801229
                                -690.416200
         fa_tw_19791230
                                -573.743640
         fa_tw_19801229
                                -160.726405
         hds_00_013_002_000
                                  37.478226
         hds_00_013_002_001
                                  36.462036
         Name: 46, dtype: float64
In [14]: pst = pyemu.Pst(os.path.join(t_d, "freyberg.pst"))
         obs = pst.observation_data
         obs.loc[:,"obsval"] = obs df.loc[idx,pst.obs names]
         obs.loc[obs.obgnme=="calhead","weight"] = 5.0
         obs.loc[obs.obgnme=="calflux", "weight"] = 0.035
         obs.weight.value_counts()
Out[14]: 0.000
                  4420
         5.000
                    13
         0.035
                     1
         Name: weight, dtype: int64
   Now, it is custom to add noise to the observed values...we will use the classic Gaussian
noise...zero mean and standard deviation of 1 over the weight
In [15]: # this should give the same standard normal draws each time
         np.random.seed(seed=0)
         snd = np.random.randn(pst.nnz_obs)
```

snd

```
0.14404357,
                              1.45427351, 0.76103773, 0.12167502])
In [16]: noise = snd * 1./obs.loc[pst.nnz_obs_names,"weight"]
         noise
Out[16]: obsnme
         fo 39 19791230
                               50.401496
         hds_00_002_009_000
                                 0.080031
         hds_00_002_015_000
                                 0.195748
         hds_00_003_008_000
                                 0.448179
         hds_00_009_001_000
                                 0.373512
         hds_00_013_010_000
                               -0.195456
         hds_00_015_016_000
                                 0.190018
         hds_00_021_010_000
                               -0.030271
         hds_00_022_015_000
                               -0.020644
         hds_00_024_004_000
                                 0.082120
         hds_00_026_006_000
                                 0.028809
         hds_00_029_015_000
                                 0.290855
         hds_00_033_007_000
                                 0.152208
         hds_00_034_010_000
                                 0.024335
         Name: weight, dtype: float64
  Only run this block once!!!
In [17]: pst.observation data.loc[noise.index,"obsval"] += noise
         pst.write(os.path.join(t_d, "freyberg.pst"))
         pyemu.os_utils.run("pestpp-ies freyberg.pst",cwd=t_d)
In [18]: pst = pyemu.Pst(os.path.join(t_d, "freyberg.pst"))
         print(pst.phi)
         pst.res.loc[pst.nnz obs names,:]
559.6226991936528
Out[18]:
                                                                              modelled \
                                                               measured
                                            name
                                                    group
         name
                                 fo_39_19791230
                                                  calflux
                                                           11975.401496
                                                                          11430.000000
         fo_39_19791230
                             hds_00_002_009_000
                                                  calhead
         hds_00_002_009_000
                                                              35.637481
                                                                             37.107498
         hds_00_002_015_000
                             hds_00_002_015_000
                                                  calhead
                                                              34.967163
                                                                             35.045185
                                                  calhead
         hds_00_003_008_000
                             hds_00_003_008_000
                                                              36.153940
                                                                             37.397289
         hds_00_009_001_000
                             hds_00_009_001_000
                                                  calhead
                                                              37.784343
                                                                             39.546417
                                                  calhead
         hds_00_013_010_000
                             hds_00_013_010_000
                                                              35.065313
                                                                             35.571774
         hds_00_015_016_000
                             hds_00_015_016_000
                                                  calhead
                                                              35.059986
                                                                             34.835716
         hds_00_021_010_000
                             hds_00_021_010_000
                                                  calhead
                                                              35.181601
                                                                             35.386250
         hds_00_022_015_000
                             hds_00_022_015_000
                                                  calhead
                                                              34.558019
                                                                             34.577492
         hds_00_024_004_000
                             hds_00_024_004_000
                                                  calhead
                                                              36.231084
                                                                             36.760464
```

0.40015721,

0.97873798, 2.2408932,

0.95008842, -0.15135721, -0.10321885,

1.86755799,

0.4105985 ,

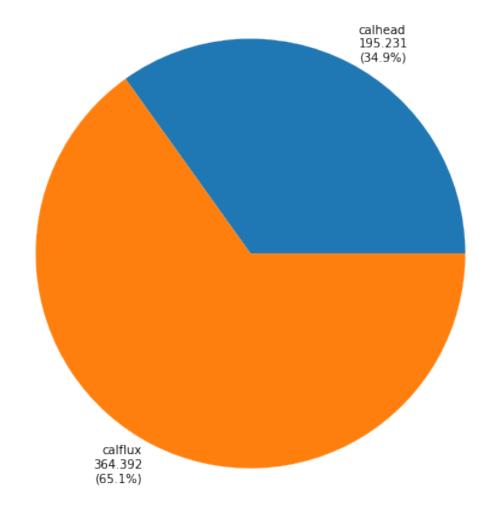
Out[15]: array([1.76405235,

-0.97727788,

```
hds_00_026_006_000
                    hds_00_026_006_000
                                        calhead
                                                    35.600605
                                                                  35.896149
hds_00_029_015_000
                    hds_00_029_015_000
                                        calhead
                                                    34.848148
                                                                  34.453842
hds_00_033_007_000
                    hds_00_033_007_000
                                        calhead
                                                    34.832311
                                                                  34.678810
hds_00_034_010_000
                    hds_00_034_010_000
                                        calhead
                                                    34.427396
                                                                  34.118073
```

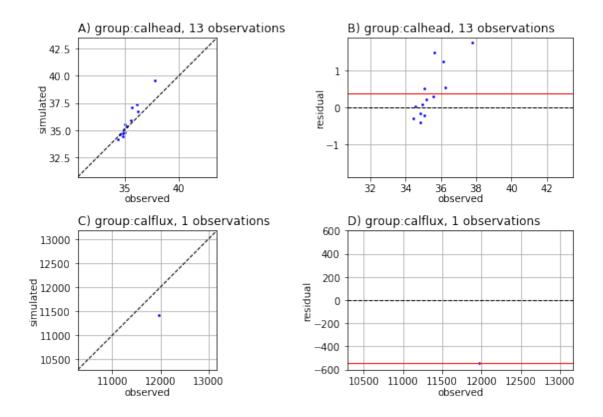
residual weight name fo_39_19791230 545.401496 0.035 hds_00_002_009_000 -1.470017 5.000 hds_00_002_015_000 5.000 -0.078022 hds_00_003_008_000 5.000 -1.243350 hds_00_009_001_000 -1.762074 5.000 hds_00_013_010_000 -0.506460 5.000 hds_00_015_016_000 0.224270 5.000 hds_00_021_010_000 -0.204649 5.000 hds_00_022_015_000 -0.019473 5.000 hds_00_024_004_000 -0.529380 5.000 5.000 hds_00_026_006_000 -0.295544 hds_00_029_015_000 0.394305 5.000 hds 00 033 007 000 0.153501 5.000 hds_00_034_010_000 0.309323 5.000

Out[19]: <matplotlib.axes._subplots.AxesSubplot at 0x109f59be0>



In [20]: figs = pst.plot(kind="1to1")

<Figure size 576x756 with 0 Axes>



Publication ready figs - oh snap!

Just to make sure we have everything working right, we should be able to load the truth parameters, run the model once and have a phi equivalent to the noise vector:

17.528847278524836

	name	group	measured	modelled	\
name					
fo_39_19791230	fo_39_19791230	calflux	11975.401496	11925.000000	
hds_00_002_009_000	hds_00_002_009_000	calhead	35.637481	35.557449	
hds_00_002_015_000	hds_00_002_015_000	calhead	34.967163	34.771416	
hds_00_003_008_000	hds_00_003_008_000	calhead	36.153940	35.705761	
hds_00_009_001_000	hds_00_009_001_000	calhead	37.784343	37.410831	
hds_00_013_010_000	hds_00_013_010_000	calhead	35.065313	35.260769	
hds_00_015_016_000	hds_00_015_016_000	calhead	35.059986	34.869968	
hds_00_021_010_000	hds_00_021_010_000	calhead	35.181601	35.211872	
hds_00_022_015_000	hds_00_022_015_000	calhead	34.558019	34.578663	
hds_00_024_004_000	hds_00_024_004_000	calhead	36.231084	36.148964	
hds_00_026_006_000	hds_00_026_006_000	calhead	35.600605	35.571796	
hds_00_029_015_000	hds_00_029_015_000	calhead	34.848148	34.557293	
hds_00_033_007_000		calhead	34.832311	34.680103	
hds_00_034_010_000	hds_00_034_010_000	calhead	34.427396	34.403061	
	residual weight				
name					
hds_00_034_010_000	0.024335 5.000				
	fo_39_19791230 hds_00_002_009_000 hds_00_002_015_000 hds_00_003_008_000 hds_00_009_001_000 hds_00_013_010_000 hds_00_015_016_000 hds_00_021_010_000 hds_00_022_015_000 hds_00_024_004_000 hds_00_026_006_000 hds_00_029_015_000 hds_00_033_007_000 hds_00_034_010_000	name fo_39_19791230 fo_39_19791230 hds_00_002_009_000 hds_00_002_009_000 hds_00_002_015_000 hds_00_002_015_000 hds_00_003_008_000 hds_00_003_008_000 hds_00_013_010_000 hds_00_013_010_000 hds_00_015_016_000 hds_00_015_016_000 hds_00_021_010_000 hds_00_021_010_000 hds_00_022_015_000 hds_00_022_015_000 hds_00_024_004_000 hds_00_024_004_000 hds_00_029_015_000 hds_00_029_015_000 hds_00_033_007_000 hds_00_033_007_000 hds_00_034_010_000 hds_00_034_010_000 hds_00_002_015_000 0.080031 5.000 hds_00_003_008_000 0.448179 5.000 hds_00_013_010_000 0.195456 5.000 hds_00_015_016_000 0.19018 5.000 hds_00_022_015_000 0.082120 5.000 hds_00_022_015_000 0.028499 5.000 hds_00_025_015_000 0.028809 5.000 hds_00_021_010_000 0.028809 5.000 hds_00_022_015_000 0.028809 5.000	name fo_39_19791230 fo_39_19791230 calflux hds_00_002_009_000 hds_00_002_009_000 calhead hds_00_002_015_000 hds_00_002_015_000 calhead hds_00_003_008_000 hds_00_003_008_000 calhead hds_00_009_001_000 hds_00_009_001_000 calhead hds_00_013_010_000 hds_00_013_010_000 calhead hds_00_015_016_000 hds_00_015_016_000 calhead hds_00_021_010_000 hds_00_015_016_000 calhead hds_00_021_010_000 hds_00_021_010_000 calhead hds_00_022_015_000 hds_00_022_015_000 calhead hds_00_024_004_000 hds_00_022_015_000 calhead hds_00_026_006_000 hds_00_026_006_000 calhead hds_00_029_015_000 hds_00_029_015_000 calhead hds_00_033_007_000 hds_00_033_007_000 calhead hds_00_034_010_000 hds_00_034_010_000 calhead hds_00_034_010_000 hds_00_034_010_000 calhead hds_00_002_015_000 0.195748 5.000 hds_00_003_008_000 0.448179 5.000 hds_00_003_008_000 0.448179 5.000 hds_00_013_010_000 -0.195456 5.000 hds_00_013_010_000 -0.195456 5.000 hds_00_021_010_000 -0.030271 5.000 hds_00_022_015_000 0.082120 5.000 hds_00_024_004_000 0.082120 5.000 hds_00_029_015_000 0.290855 5.000 hds_00_029_015_000 0.290855 5.000 hds_00_003_007_000 0.152208 5.000	name fo_39_19791230 fo_39_19791230 calflux 11975.401496 hds_00_002_009_000 hds_00_002_009_000 calhead 35.637481 hds_00_002_015_000 hds_00_002_015_000 calhead 34.967163 hds_00_003_008_000 hds_00_009_001_000 calhead 36.153940 hds_00_009_001_000 hds_00_009_001_000 calhead 37.784343 hds_00_013_010_000 hds_00_013_010_000 calhead 35.065313 hds_00_021_010_000 hds_00_021_010_000 calhead 35.065313 hds_00_021_010_000 hds_00_021_010_000 calhead 35.065313 hds_00_022_015_000 hds_00_022_015_000 calhead 35.059986 hds_00_022_015_000 hds_00_022_015_000 calhead 35.181601 hds_00_022_015_000 hds_00_022_015_000 calhead 35.600605 hds_00_024_004_000 hds_00_024_004_000 calhead 35.600605 hds_00_029_015_000 hds_00_023_007_000 calhead 34.848148 hds_00_033_007_000 hds_00_033_007_000 calhead 34.82311 hds_0	name fo_39_19791230

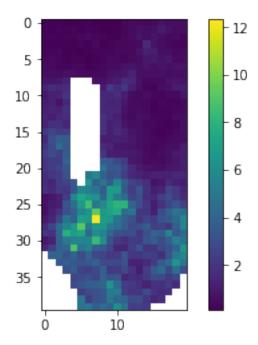
The residual should be exactly the noise values from above. Lets load the model (that was just run using the true pars) and check some things

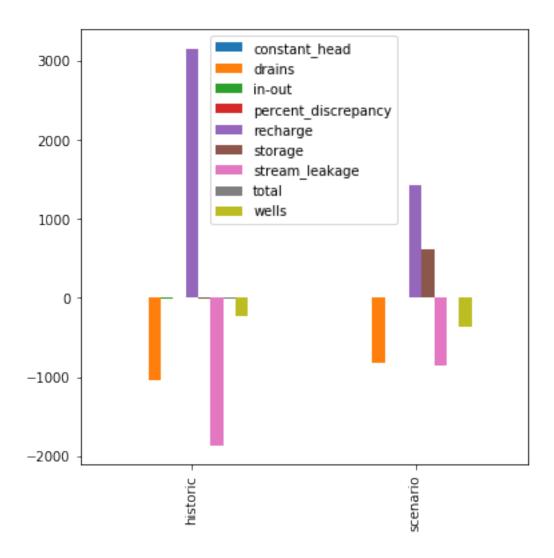
```
In [22]: m = flopy.modflow.Modflow.load("freyberg.nam",model_ws=m_d)
```

```
In [23]: a = m.upw.hk[0].array
    #a = m.rch.rech[0].array
    a = np.ma.masked_where(m.bas6.ibound[0].array==0,a)
    print(a.min(),a.max())
    c = plt.imshow(a)
    plt.colorbar(c)
```

Out[23]: <matplotlib.colorbar.Colorbar at 0x181ffa67f0>

0.1282324 12.32662



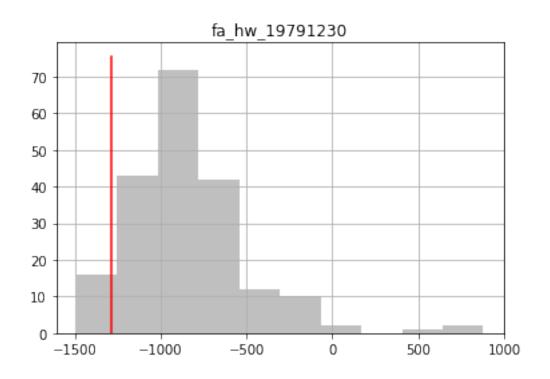


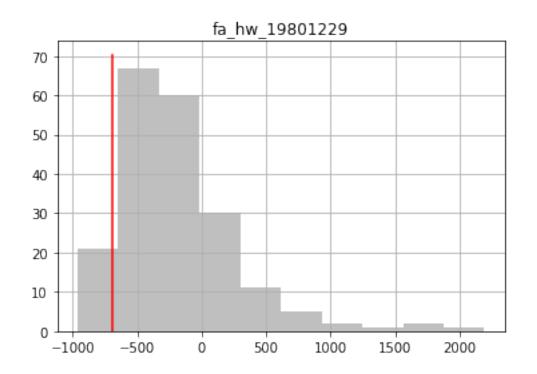
1.0.5 see how our existing observation ensemble compares to the truth

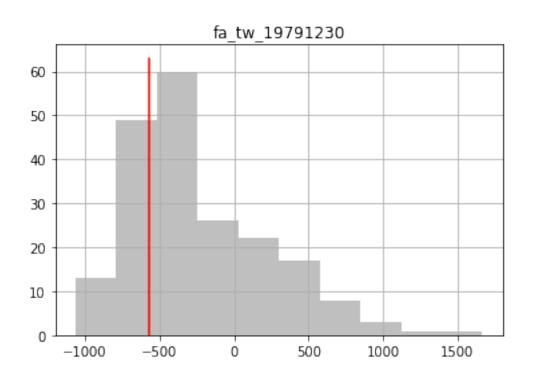
sw-gw outputs:

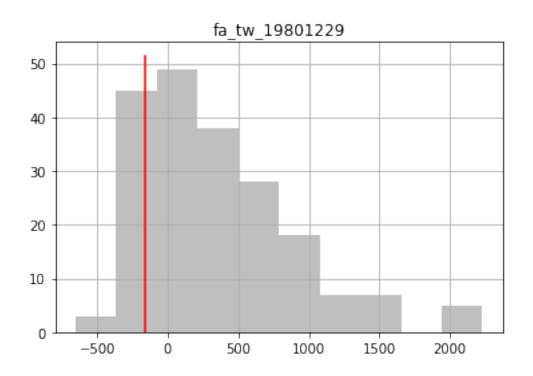
```
In [25]: obs = pst.observation_data

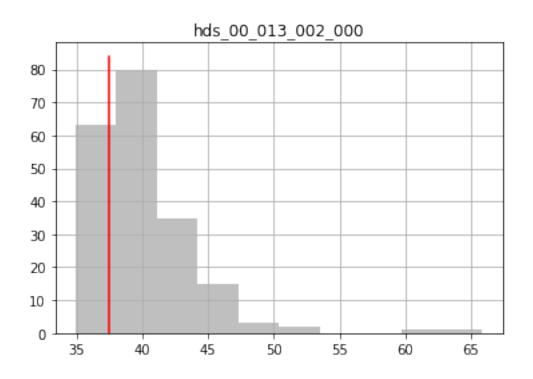
for forecast in fnames:
    ax = plt.subplot(111)
    obs_df.loc[:,forecast].hist(ax=ax,color="0.5",alpha=0.5)
    ax.plot([obs.loc[forecast,"obsval"],obs.loc[forecast,"obsval"]],ax.get_ylim(),"r",
    ax.set_title(forecast)
    plt.show()
```

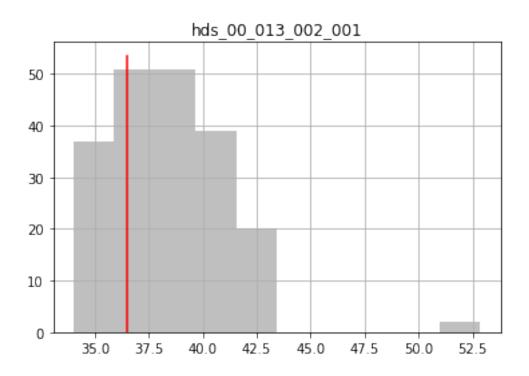












observations:

