## prior\_montecarlo

May 11, 2019

## 1 Run and process the prior monte carlo and pick a "truth" realization

A great advantage of exploring a synthetic model is that we can enforce a "truth" and then evaluate how our various attempts to estimate it perform. One way to do this is to run a monte carlo ensemble of multiple parameter realizations and then choose one of them to represent the "truth". That will be accomplished in this notebook.

```
In [1]: import os
    import shutil
    import numpy as np
    import pandas as pd
    import matplotlib.pyplot as plt
    import matplotlib as mpl
    plt.rcParams['font.size']=12
    import flopy
    import pyemu
```

flopy is installed in /Users/jeremyw/Dev/gw1876/activities\_2day\_mfm/notebooks/flopy

# 1.0.1 set the t\_d or "template directory" variable to point at the template folder and read in the PEST control file

## 1.0.2 Decide what pars are uncertain in the truth

We need to decide what our truth looks like - should the pilot points or the grid-scale pars be the source of spatial variability? or both?

```
In [3]: par = pst.parameter_data
    # grid pars
    #should_fix = par.loc[par.pargp.apply(lambda x: "gr" in x), "parnme"]
    # pp pars
    #should_fix = par.loc[par.pargp.apply(lambda x: "pp" in x), "parnme"]
    #pst.npar - should_fix.shape[0]
```

## 1.0.3 run the prior ensemble in parallel locally

This takes advantage of the program pestpp-swp which runs a parameter sweep through a set of parameters. By default, pestpp-swp reads in the ensemble from a file called sweep\_in.csv which in this case we made just above.

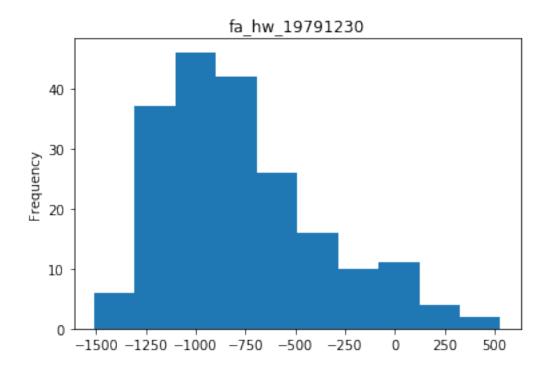
print('number of realization in the ensemble before dropping: ' + str(obs\_df.shape[0])

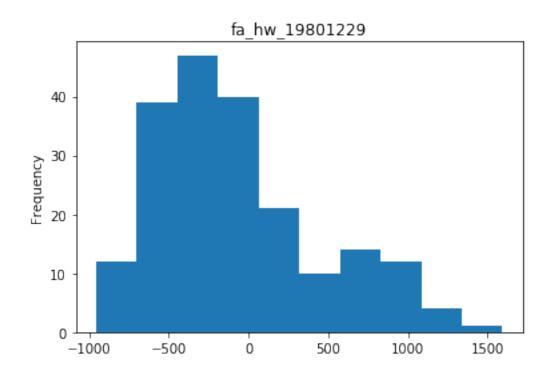
number of realization in the ensemble before dropping: 200

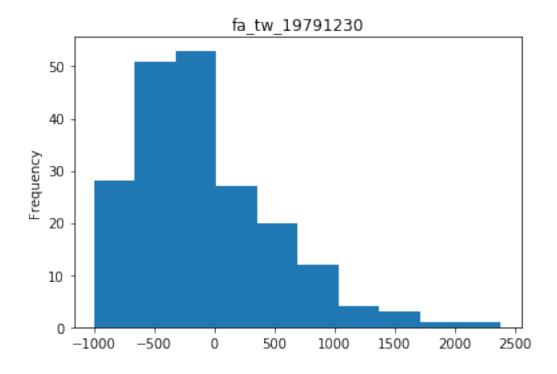
drop any failed runs

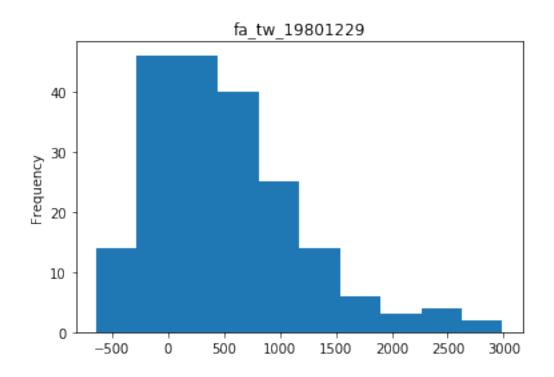
#### 1.0.5 confirm which quantities were identified as forecasts

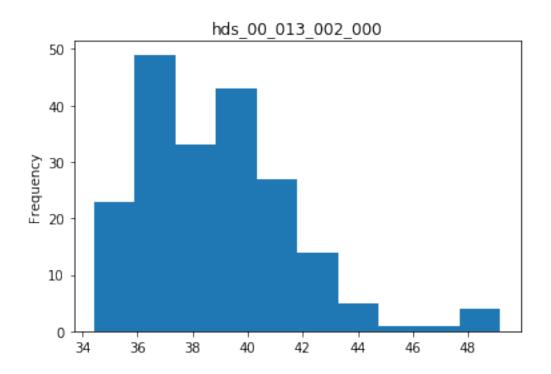
## 1.0.6 now we can plot the distributions of each forecast

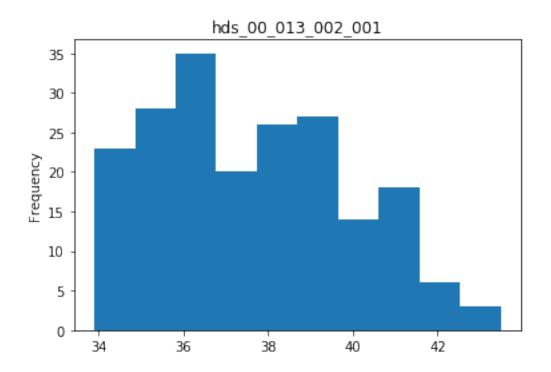


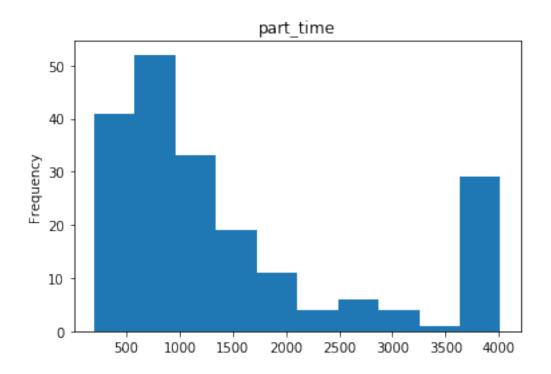


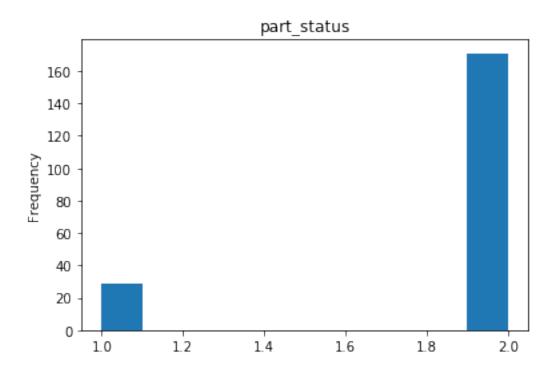






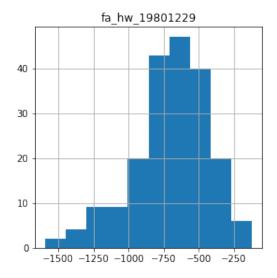


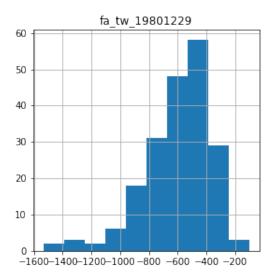


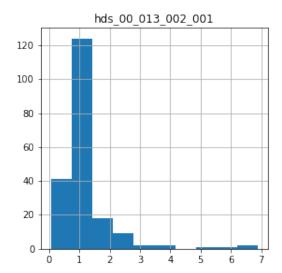


We see that under scenario conditions, many more realizations for the flow to the aquifer in the headwaters are postive (as expected). Lets difference these two:

```
In [10]: sfnames = [f for f in fnames if "1980" in f or "_001" in f]
    hfnames = [f for f in fnames if "1979" in f or "_000" in f]
    diff = obs_df.loc[:,hfnames].values - obs_df.loc[:,sfnames].values
    diff = pd.DataFrame(diff,columns=sfnames)
    diff.hist(figsize=(10,10))
    plt.show()
```







We now see that the most extreme scenario yields a large decrease in flow from the aquifer to the headwaters (the most negative value)

## 1.0.7 setting the "truth"

We just need to replace the observed values (obsval) in the control file with the outputs for one of the realizations on obs\_df. In this way, we now have the nonzero values for history matching, but also the truth values for comparing how we are doing with other unobserved quantities. I'm going to pick a realization that yields an "average" variability of the observed gw levels:

idx hist\_swgw

Out[11]:	run id	
	149	198.1387
	41	265.3273
	165	276.1939
	120	293.1571
	37	313.4481
	96	325.5403
	0	342.4888
	173	358.4053
	77	361.9629
	64	372.9315
	73	374.5064
	145	380.7252
	16	394.1340
	40	395.1985
	35	405.8629
	128	424.2145
	78	427.1186
	51	447.5162
	21	451.1969
	117	451.4228
	194	458.4655
	131	463.7558
	27	464.6402
	184	476.3412
	57	484.2876
	19	501.6304
	162	520.8668
	182	524.6132
	107	525.4871
	141	529.1481
	100	2467 0040
	192	3467.2040
	101	4015.0000
	17	4015.0000 4015.0000
	187 191	4015.0000
	118	4015.0000
	20	4015.0000
	193	4015.0000
	6	4015.0000
	3	4015.0000
	12	4015.0000
	183	4015.0000
	138	4015.0000
	100	

```
100
                4015.0000
         157
                4015.0000
         61
                4015.0000
         47
                4015.0000
         166
                4015.0000
         46
                4015.0000
         153
                4015.0000
         24
                4015.0000
         75
                4015.0000
         82
                4015.0000
         88
                4015.0000
         175
                4015.0000
         176
                4015.0000
         159
                4015.0000
         29
                4015.0000
         76
                4015.0000
         130
                4015.0000
         Name: part_time, Length: 200, dtype: float64
In [12]: obs_df.loc[idx,pst.nnz_obs_names]
Out[12]: fo_39_19791230
                                11302.000000
         hds_00_002_009_000
                                    36.058125
         hds_00_002_015_000
                                   35.212799
         hds_00_003_008_000
                                   36.083511
         hds_00_009_001_000
                                   37.389400
         hds_00_013_010_000
                                   35.048706
         hds_00_015_016_000
                                    34.838463
         hds_00_021_010_000
                                   34.814125
         hds_00_022_015_000
                                    34.552216
         hds_00_024_004_000
                                   35.209511
         hds_00_026_006_000
                                    34.681568
         hds_00_029_015_000
                                    34.122902
         hds_00_033_007_000
                                    33.345665
         hds_00_034_010_000
                                    33.317856
         Name: 194, dtype: float64
   Lets see how our selected truth does with the sw/gw forecasts:
```

```
In [13]: obs_df.loc[idx,fnames]
```

```
Out[13]: fa_hw_19791230
                               -826.113600
         fa_hw_19801229
                               -412.139600
         fa_tw_19791230
                                341.545050
         fa_tw_19801229
                                704.034190
         hds_00_013_002_000
                                 36.989079
         hds_00_013_002_001
                                 36.173130
         part_time
                                458.465500
                                  2.000000
         part_status
```

Name: 194, dtype: float64

Assign some initial weights. Now, it is custom to add noise to the observed values...we will use the classic Gaussian noise...zero mean and standard deviation of 1 over the weight

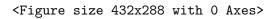
```
In [14]: pst = pyemu.Pst(os.path.join(t_d,"freyberg.pst"))
        obs = pst.observation_data
        obs.loc[:,"obsval"] = obs_df.loc[idx,pst.obs_names]
        obs.loc[obs.obgnme=="calhead","weight"] = 10.0
        obs.loc[obs.obgnme=="calflux","weight"] = 1.0
```

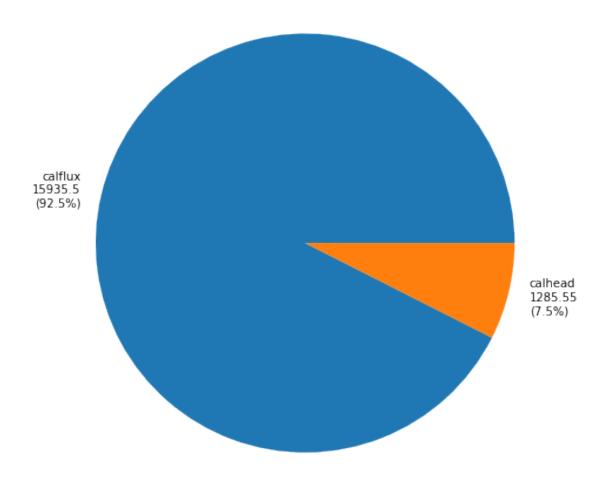
here we just get a sample from a random normal distribution with mean=0 and std=1. The argument indicates how many samples we want - and we choose pst.nnz\_obs which is the the number of nonzero-weighted observations in the PST file

```
In [15]: np.random.seed(seed=0)
         snd = np.random.randn(pst.nnz_obs)
         noise = snd * 1./obs.loc[pst.nnz_obs_names,"weight"]
         pst.observation_data.loc[noise.index,"obsval"] += noise
         noise
Out[15]: obsnme
         fo_39_19791230
                               1.764052
         hds_00_002_009_000
                               0.040016
         hds_00_002_015_000
                               0.097874
         hds_00_003_008_000
                               0.224089
         hds_00_009_001_000
                               0.186756
         hds_00_013_010_000
                              -0.097728
         hds_00_015_016_000
                               0.095009
         hds_00_021_010_000
                              -0.015136
         hds_00_022_015_000
                              -0.010322
         hds_00_024_004_000
                               0.041060
         hds 00 026 006 000
                               0.014404
         hds_00_029_015_000
                               0.145427
         hds 00 033 007 000
                               0.076104
         hds_00_034_010_000
                               0.012168
         Name: weight, dtype: float64
```

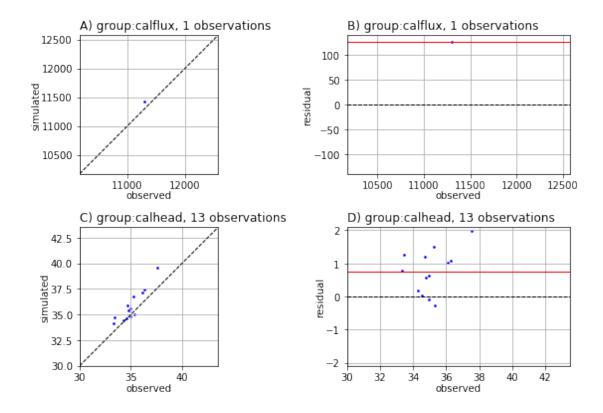
Then we write this out to a new file and run pestpp-ies to see how the objective function looks

Now we can read in the results and make some figures showing residuals and the balance of the objective function





## <Figure size 576x756 with 0 Axes>



Out[17]:			name	group	measured	modelled	\
	name						
	fo_39_19791230	fo_39_19	9791230	calflux	11303.764052	11430.000000	
	hds_00_002_009_000	hds_00_002_0	009_000	calhead	36.098140	37.107498	
	hds_00_002_015_000	hds_00_002_0	015_000	calhead	35.310673	35.045185	
	hds_00_003_008_000	hds_00_003_0	000_800	calhead	36.307601	37.397289	
	hds_00_009_001_000	hds_00_009_0	001_000	calhead	37.576156	39.546417	
	hds_00_013_010_000	hds_00_013_0	010_000	calhead	34.950978	35.571774	
	hds_00_015_016_000	hds_00_015_0	016_000	calhead	34.933472	34.835716	
	hds_00_021_010_000	hds_00_021_0	010_000	calhead	34.798989	35.386250	
	hds_00_022_015_000	hds_00_022_0	015_000	calhead	34.541894	34.577492	
	hds_00_024_004_000	hds_00_024_0	004_000	calhead	35.250571	36.760464	
	hds_00_026_006_000	hds_00_026_0	000_000	calhead	34.695973	35.896149	
	hds_00_029_015_000	hds_00_029_0	015_000	calhead	34.268329	34.453842	
	hds_00_033_007_000	hds_00_033_0	007_000	calhead	33.421769	34.678810	
	hds_00_034_010_000	hds_00_034_0	010_000	calhead	33.330023	34.118073	
		residual	weight				
	name						
	fo_39_19791230	-126.235948	1.0				
	hds_00_002_009_000	-1.009358	10.0				
	hds_00_002_015_000	0.265488	10.0				
	hds_00_003_008_000	-1.089689	10.0				
	hds_00_009_001_000	-1.970261	10.0				
	hds_00_013_010_000	-0.620795	10.0				
	hds_00_015_016_000	0.097755	10.0				
	hds_00_021_010_000	-0.587260	10.0				
	hds_00_022_015_000	-0.035598	10.0				
	hds_00_024_004_000	-1.509893	10.0				
	hds_00_026_006_000	-1.200176	10.0				
	hds_00_029_015_000	-0.185513	10.0				
	hds_00_033_007_000	-1.257041	10.0				
	hds_00_034_010_000	-0.788049	10.0				

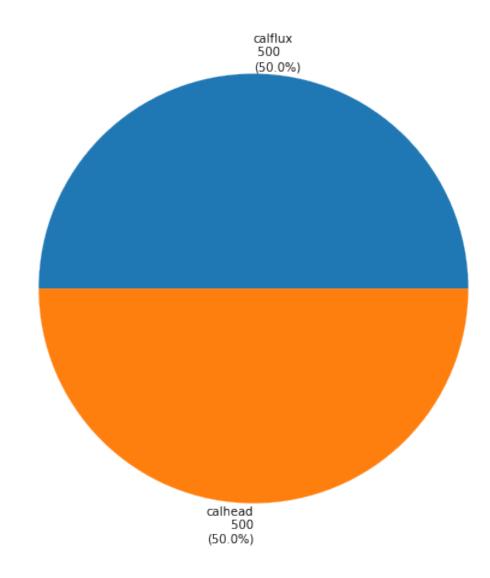
Publication ready figs - oh snap!

Depending on the truth you chose, we may have a problem - we set the weights for both the heads and the flux to reasonable values based on what we expect for measurement noise. But the contributions to total phi might be out of balance - if contribution of the flux measurement to total phi is too low, the history matching excersizes (coming soon!) will focus almost entirely on minimizing head residuals. So we need to balance the objective function. This is a subtle but very important step, especially since some of our forecasts deal with sw-gw exchange

```
In [18]: pc = pst.phi_components
         #target = {"calflux":0.3 * pc["calhead"]}
        target = {"calhead":500,"calflux":500}
```

```
pst.adjust_weights(obsgrp_dict=target)
pst.plot(kind='phi_pie')
```

Out[18]: <matplotlib.axes.\_subplots.AxesSubplot at 0x181d85e5c0>



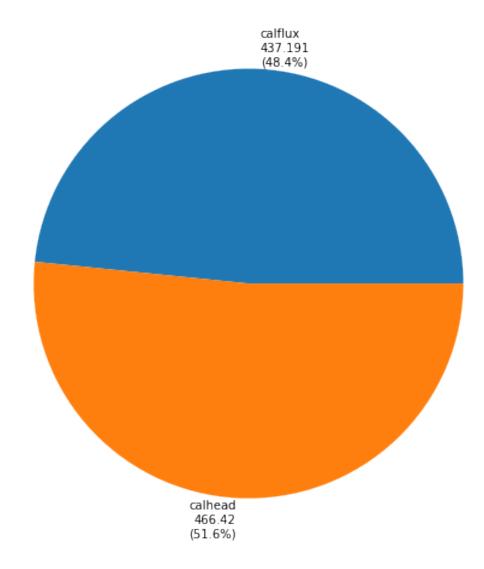
Lets see what the new flux observation weight is:

```
In [19]: pst.observation_data.loc[pst.nnz_obs_names,"weight"]
```

```
hds_00_009_001_000
                      6.236491
hds_00_013_010_000
                      6.236491
hds_00_015_016_000
                      6.236491
hds_00_021_010_000
                      6.236491
hds 00 022 015 000
                      6.236491
hds_00_024_004_000
                      6.236491
hds 00 026 006 000
                      6.236491
hds_00_029_015_000
                      6.236491
hds_00_033_007_000
                      6.236491
hds_00_034_010_000
                      6.236491
Name: weight, dtype: float64
```

Now, for some super trickery: since we changed the weight, we need to generate the observation noise using these new weights for the error model (so meta!)

```
In [20]: obs = pst.observation_data
         np.random.seed(seed=0)
         snd = np.random.randn(pst.nnz_obs)
         noise = snd * 1./obs.loc[pst.nnz_obs_names,"weight"]
         obs.loc[:,"obsval"] = obs_df.loc[idx,pst.obs_names]
         pst.observation_data.loc[noise.index,"obsval"] += noise
         noise
Out[20]: obsnme
         fo_39_19791230
                               9.958857
         hds 00 002 009 000
                               0.064164
         hds_00_002_015_000
                               0.156937
         hds_00_003_008_000
                               0.359320
         hds 00 009 001 000
                               0.299457
         hds_00_013_010_000
                              -0.156703
         hds_00_015_016_000
                               0.152343
         hds_00_021_010_000
                              -0.024270
         hds_00_022_015_000
                              -0.016551
         hds_00_024_004_000
                               0.065838
         hds_00_026_006_000
                               0.023097
         hds_00_029_015_000
                               0.233188
         hds 00 033 007 000
                               0.122030
         hds_00_034_010_000
                               0.019510
         Name: weight, dtype: float64
In [21]: pst.write(os.path.join(t_d, "freyberg.pst"))
         pyemu.os_utils.run("pestpp-ies freyberg.pst",cwd=t_d)
         pst = pyemu.Pst(os.path.join(t_d, "freyberg.pst"))
         print(pst.phi)
         pst.plot(kind='phi_pie')
         plt.show()
noptmax:0, npar_adj:14819, nnz_obs:14
903.6102175392298
```



Whew! confused yet? Ok, let's leave all this confusion behind...its mostly academic, just to make sure we are using weights that are in harmony with the noise we added to the truth...Just to make sure we have everything working right, we should be able to load the truth parameters, run the model once and have a phi equivalent to the noise vector:

we will run this with noptmax=0 to preform a single run. Pro-tip: you can use any of the pestpp-### binaries/executables to run noptmax=0

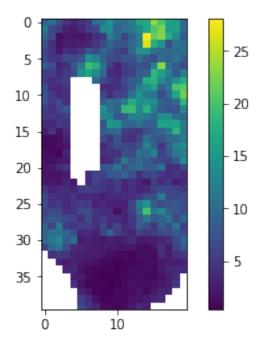
#### 17.52884697222985

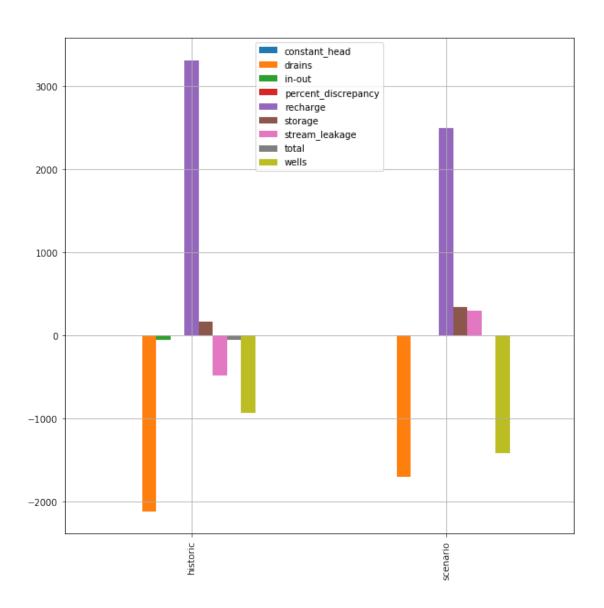
Out[23]:			name	group	measured	modelled	\
	name						
	fo_39_19791230	fo_39	_19791230	calflux	11311.958857	11302.000000	
	hds_00_002_009_000	hds_00_00	2_009_000	calhead	36.122288	36.058125	
	hds_00_002_015_000	hds_00_00	2_015_000	calhead	35.369736	35.212799	
	hds_00_003_008_000	hds_00_00	3_008_000	calhead	36.442831	36.083511	
	hds_00_009_001_000	hds_00_00	9_001_000	calhead	37.688857	37.389400	
	hds_00_013_010_000	hds_00_01	3_010_000	calhead	34.892003	35.048706	
	hds_00_015_016_000	hds_00_01	hds_00_015_016_000 hds_00_021_010_000		34.990806	34.838463	
	hds_00_021_010_000	hds_00_02			34.789855	34.814125	
	hds_00_022_015_000	hds_00_02	2_015_000	calhead	34.535665	34.552216	
	hds_00_024_004_000	hds_00_02	4_004_000	calhead	35.275349	35.209511	
	hds_00_026_006_000	hds_00_02	6_006_000	calhead	34.704665	34.681568	
	hds_00_029_015_000	hds_00_02	9_015_000	calhead	34.356090	34.122902	
	hds_00_033_007_000	hds_00_03	3_007_000	calhead	33.467695	33.345665	
	hds_00_034_010_000	hds_00_03	hds_00_034_010_000		33.337366	33.317856	
		residual	weight				
	name						
	fo_39_19791230	9.958857	0.177134				
	hds_00_002_009_000	0.064164	6.236491				
	hds_00_002_015_000	0.156937	6.236491				
	hds_00_003_008_000	0.359320	6.236491				
	hds_00_009_001_000	0.299457	6.236491				
	hds_00_013_010_000	-0.156703	6.236491				
	hds_00_015_016_000	0.152343	6.236491				
	hds_00_021_010_000	-0.024270	6.236491				
	hds_00_022_015_000	-0.016551	6.236491				
	hds_00_024_004_000	0.065838	6.236491				
	hds_00_026_006_000	0.023097	6.236491				
	hds_00_029_015_000	0.233188	6.236491				
	hds_00_033_007_000	0.122030	6.236491				
	hds_00_034_010_000	0.019510	6.236491				
	<del>-</del>						

The residual should be exactly the noise values from above. Lets load the model (that was just run using the true pars) and check some things

```
a = np.ma.masked_where(m.bas6.ibound[0].array==0,a)
print(a.min(),a.max())
c = plt.imshow(a)
plt.colorbar()
plt.show()
```

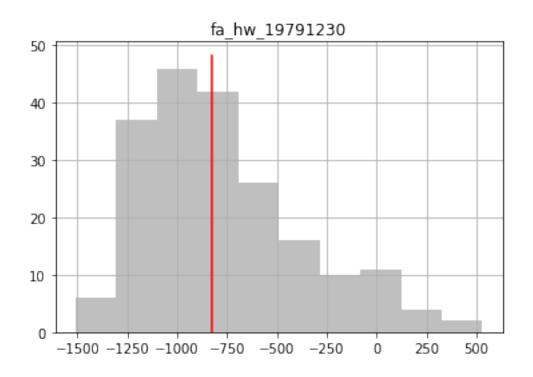
## 0.4185674 28.04684

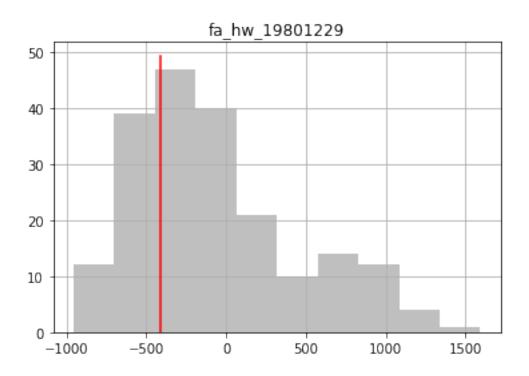


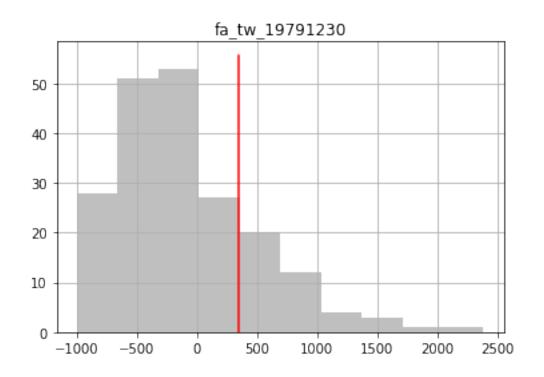


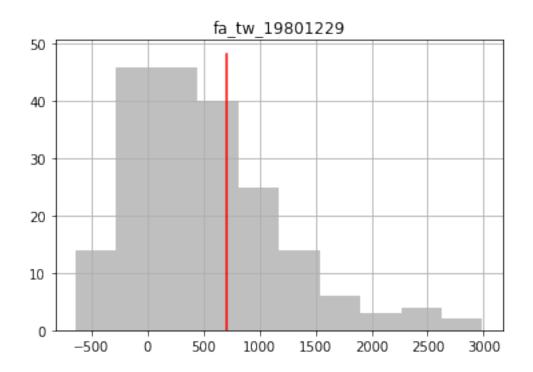
## 1.0.8 see how our existing observation ensemble compares to the truth

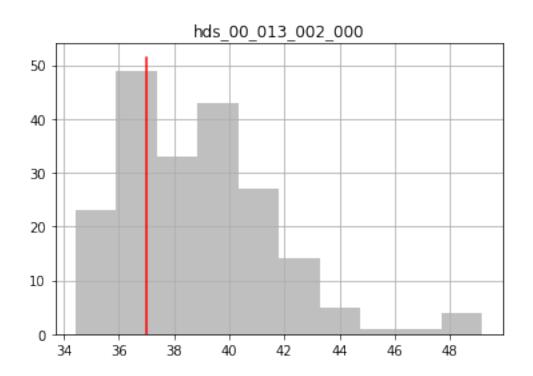
forecasts:

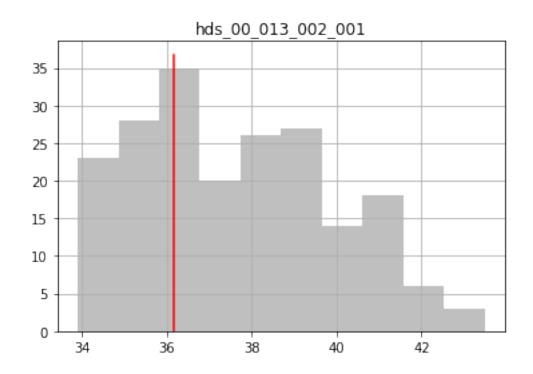


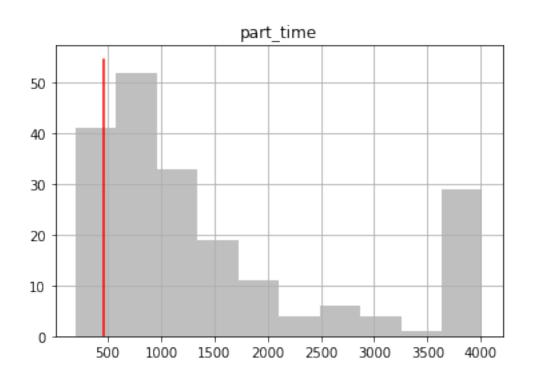


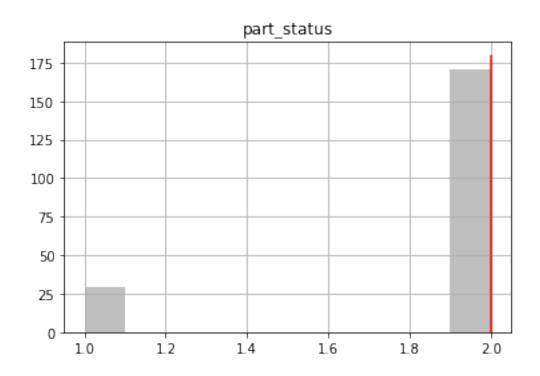












observations:

