

prior_montecarlo

May 3, 2019

1 Run and process the prior monte carlo and pick a “truth” realization

```
In [1]: import os
import shutil
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
import flogy
import pyemu
```

flogy is installed in /Users/jeremyw/Dev/gw1876/activities_2day_mfm/notebooks/flogy

```
In [2]: t_d = "template"
pst = pyemu.Pst(os.path.join(t_d, "freyberg.pst"))
```

1.0.1 Decide what pars are uncertain in the truth

We need to decide what our truth looks like - should the pilot points or the grid-scale pars be the source of spatial variability? or both?

```
In [3]: par = pst.parameter_data
# grid pars
#should_fix = par.loc[par.pargp.apply(lambda x: "gr" in x), "parname"]
# pp pars
#should_fix = par.loc[par.pargp.apply(lambda x: "pp" in x), "parname"]
#pst.npar - should_fix.shape[0]
```

```
In [4]: pe = pyemu.ParameterEnsemble.from_binary(pst=pst, filename=os.path.join(t_d, "prior.jcb"))
#pe.loc[:, should_fix] = 1.0
pe.to_csv(os.path.join(t_d, "sweep_in.csv"))
```

new binary format detected...

1.0.2 run the prior ensemble in parallel locally

```
In [5]: m_d = "master_prior_sweep"
#pyemu.os_utils.start_slaves(t_d, "pestpp-swp", "freyberg.pst", num_slaves=20, slave_root=
```

1.0.3 Load the output ensemble and plot a few things

```
In [6]: obs_df = pd.read_csv(os.path.join(m_d, "sweep_out.csv"), index_col=0)
        obs_df.shape
```

```
Out[6]: (200, 4465)
```

drop any failed runs

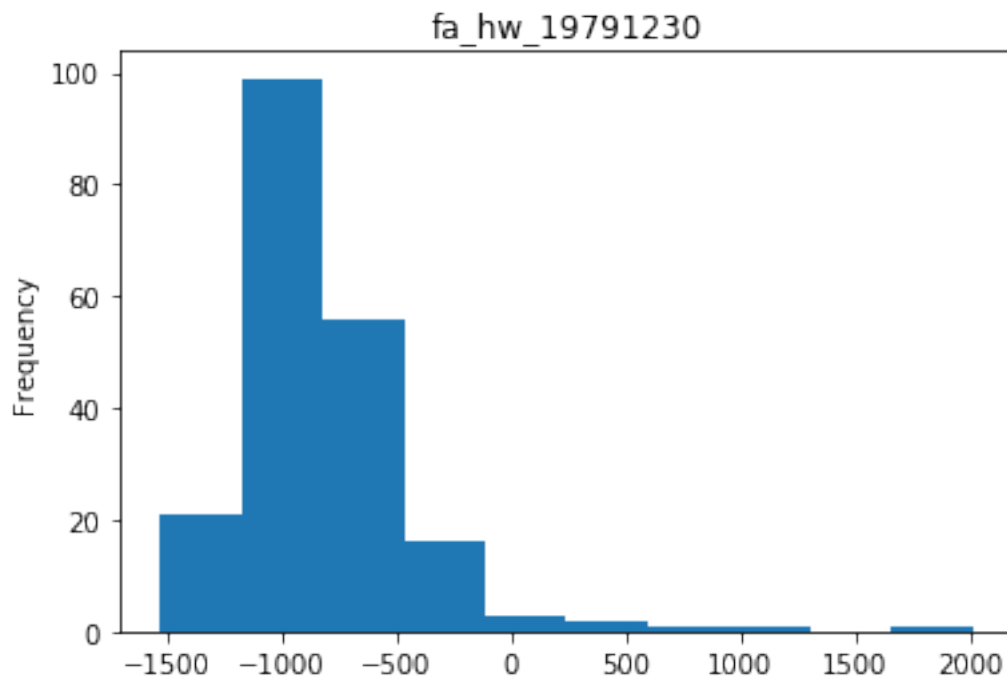
```
In [7]: obs_df = obs_df.loc[obs_df.failed_flag==0,:]
        obs_df.shape
```

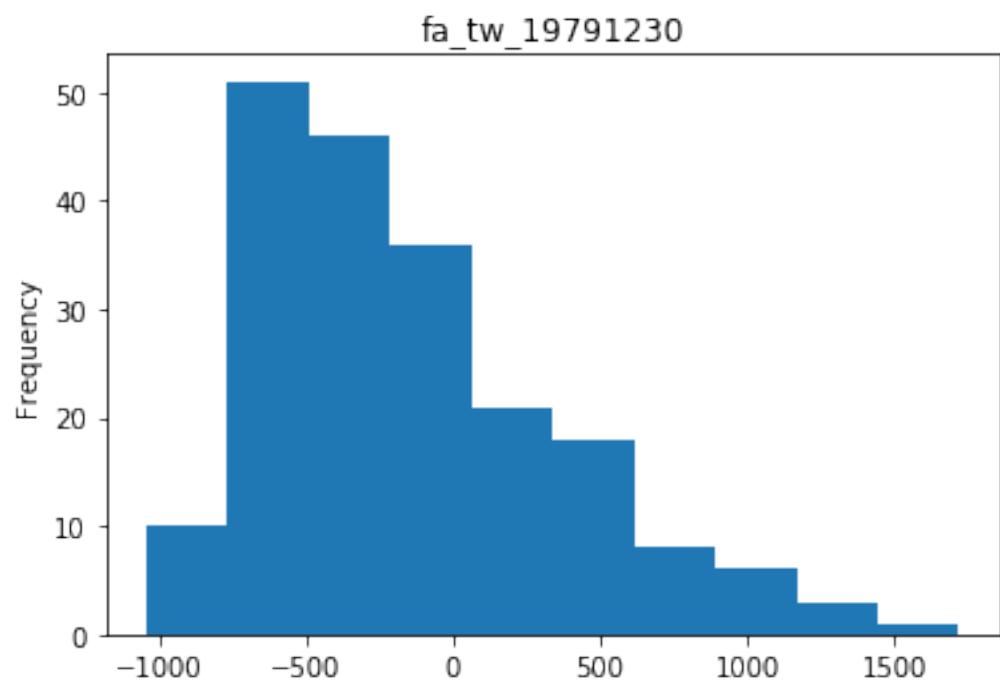
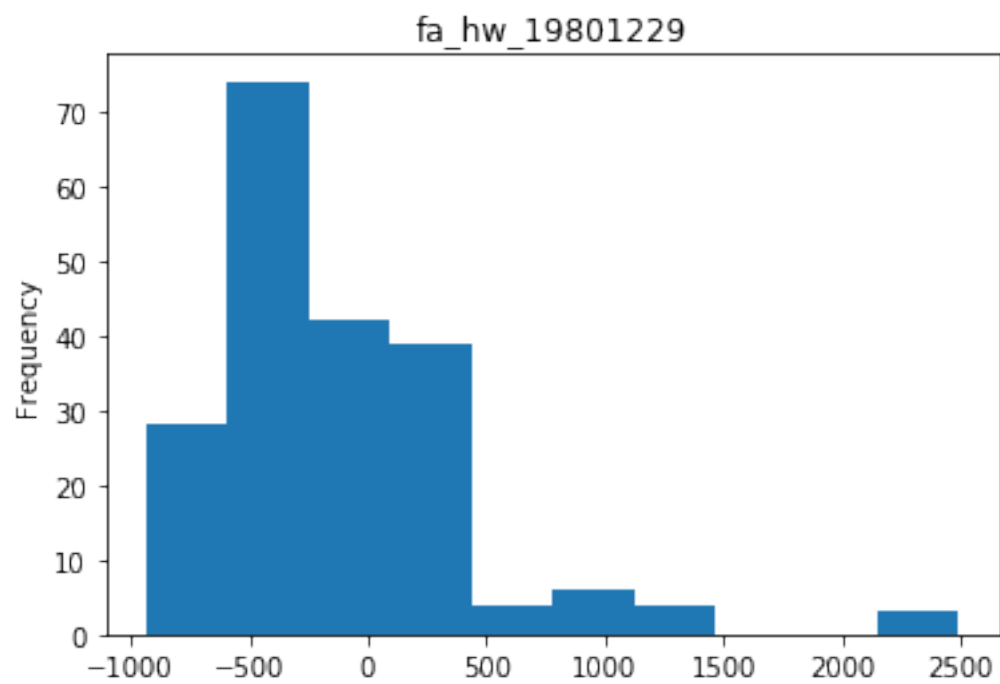
```
Out[7]: (200, 4465)
```

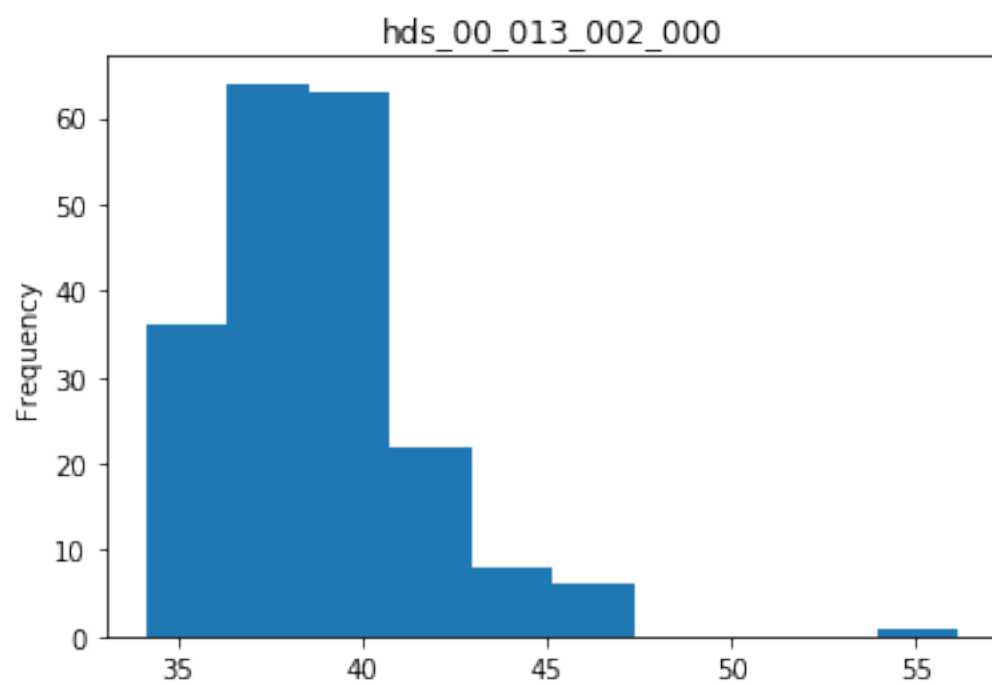
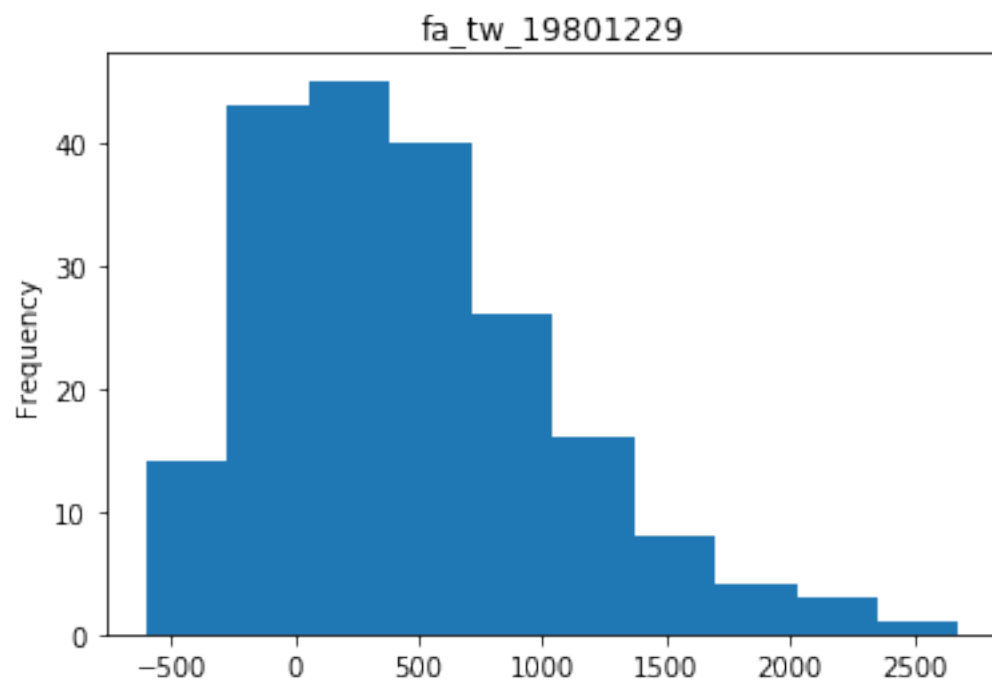
```
In [8]: fnames = pst.pestpp_options["forecasts"].split(',')
        fnames
```

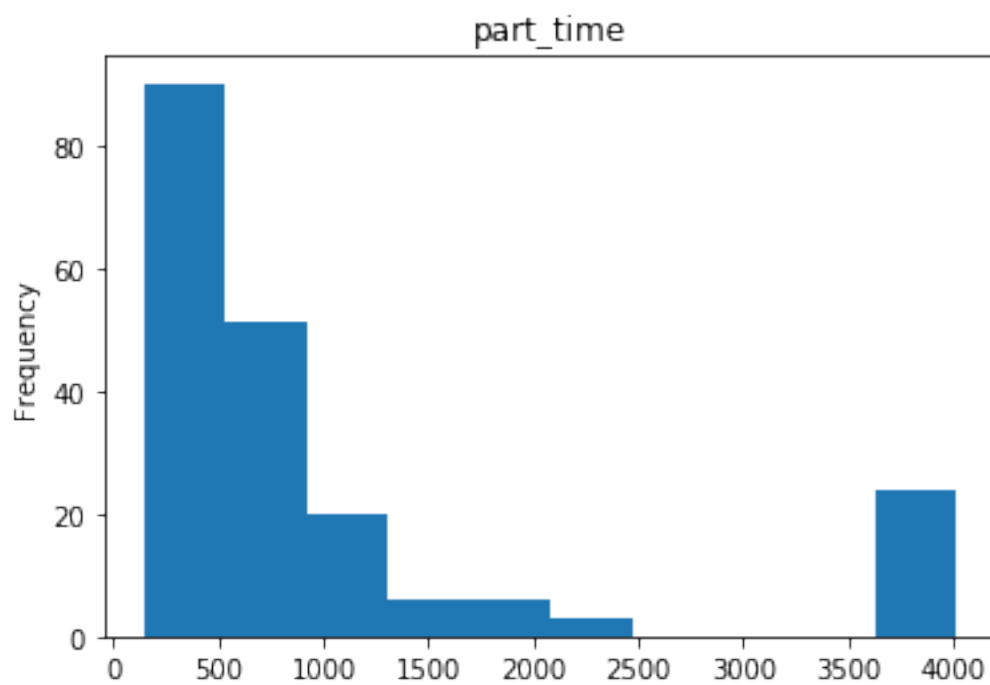
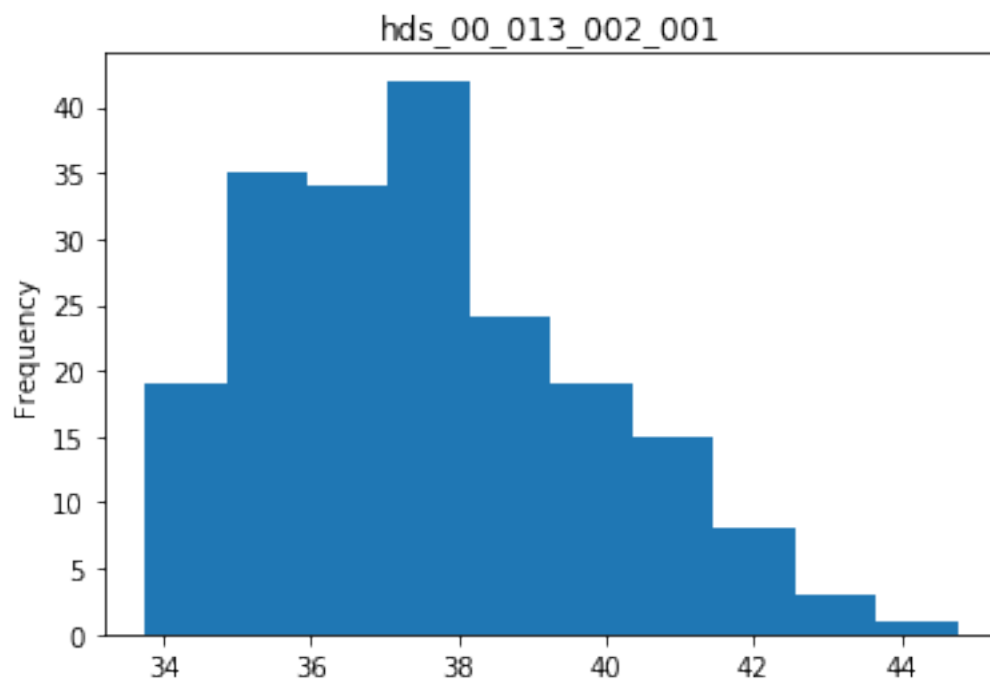
```
Out[8]: ['fa_hw_19791230',
        'fa_hw_19801229',
        'fa_tw_19791230',
        'fa_tw_19801229',
        'hds_00_013_002_000',
        'hds_00_013_002_001',
        'part_time',
        'part_status']
```

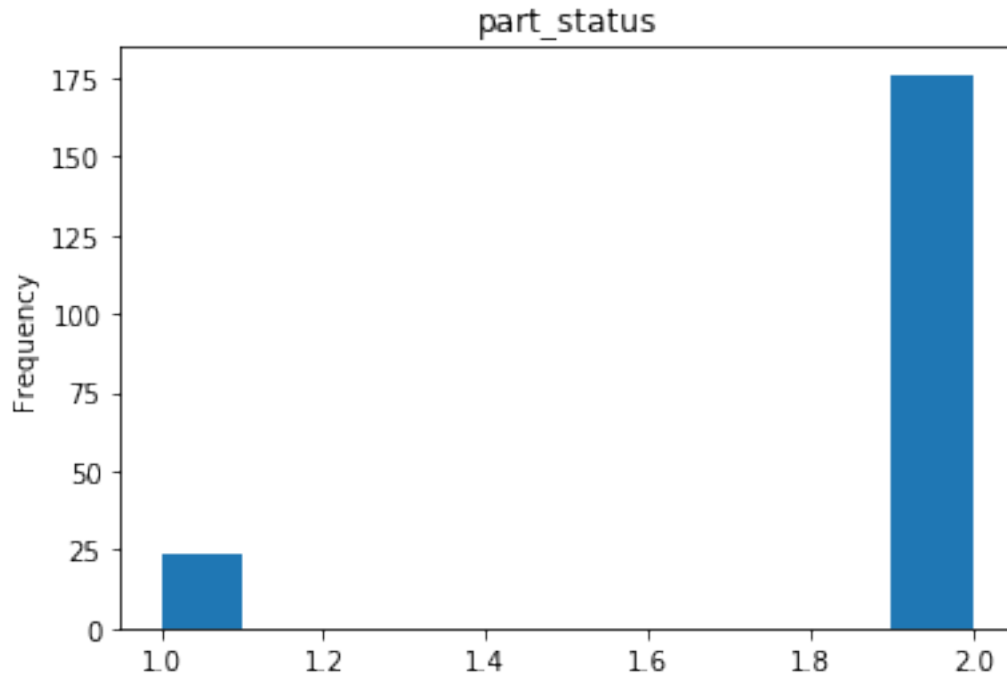
```
In [9]: for forecast in fnames:
        ax = obs_df.loc[:,forecast].plot(kind="hist")
        ax.set_title(forecast)
        plt.show()
```







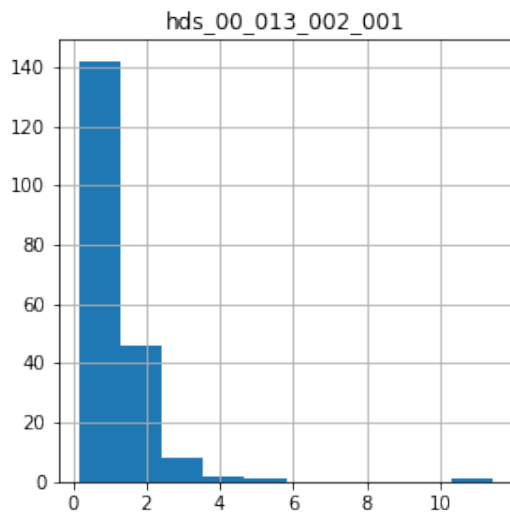
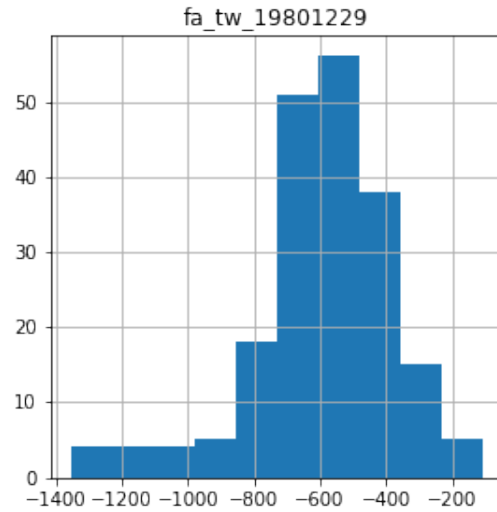
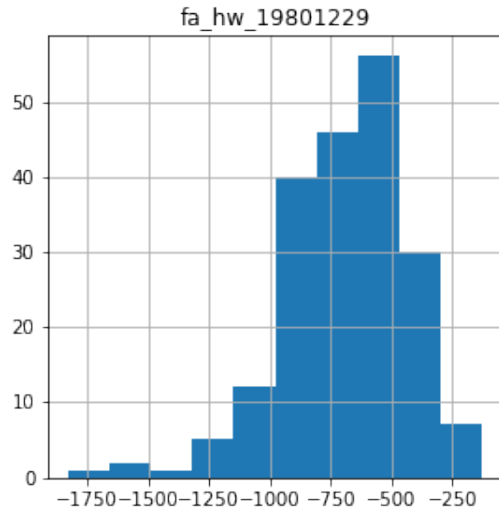




We see that under scenario conditions, many more realizations for the flow to the aquifer in the headwaters are postive (as expected). Lets difference these two:

```
In [10]: sfnames = [f for f in fnames if "1980" in f or "_001" in f]
          hfnames = [f for f in fnames if "1979" in f or "_000" in f]
          diff = obs_df.loc[:,hfnames].values - obs_df.loc[:,sfnames].values
          diff = pd.DataFrame(diff,columns=sfnames)
          diff.hist(figsize=(10,10))
```

```
Out[10]: array([[<matplotlib.axes._subplots.AxesSubplot object at 0x1031c9a90>,
                  <matplotlib.axes._subplots.AxesSubplot object at 0x1031e9c88>],
                [<matplotlib.axes._subplots.AxesSubplot object at 0x1818cf0208>,
                  <matplotlib.axes._subplots.AxesSubplot object at 0x1818d06780>]],
            dtype=object)
```



We now see that the most extreme scenario yields a large decrease in flow from the aquifer to the headwaters (the most negative value)

1.0.4 setting the “truth”

We just need to replace the observed values (obsval) in the control file with the outputs for one of the realizations on obs_df. In this way, we now have the nonzero values for history matching, but also the truth values for comparing how we are doing with other unobserved quantities. Im going to pick a realization that yields an “average” variability of the observed gw levels:

```
In [11]: # choose the realization with a low historic gw to sw headwater flux
hist_swgw = obs_df.loc[:, "fa_hw_19791230"].sort_values()
idx = hist_swgw.index[10]
idx
```

```
Out[11]: 23
```

```
In [12]: obs_df.loc[idx,pst.nnz_obs_names]
```

```
Out[12]: fo_39_19791230      11553.000000
          hds_00_002_009_000    36.390945
          hds_00_002_015_000    34.901199
          hds_00_003_008_000    36.633041
          hds_00_009_001_000    38.894932
          hds_00_013_010_000    35.846367
          hds_00_015_016_000    34.909328
          hds_00_021_010_000    35.402809
          hds_00_022_015_000    34.446541
          hds_00_024_004_000    36.218941
          hds_00_026_006_000    35.067863
          hds_00_029_015_000    34.225922
          hds_00_033_007_000    34.120350
          hds_00_034_010_000    33.842617
          Name: 23, dtype: float64
```

Lets see how our selected truth does with the swgw forecasts:

```
In [13]: obs_df.loc[idx,fnames]
```

```
Out[13]: fa_hw_19791230      -1250.952650
          fa_hw_19801229      -383.912850
          fa_tw_19791230       97.419300
          fa_tw_19801229      841.068200
          hds_00_013_002_000    39.332623
          hds_00_013_002_001    37.060593
          part_time            1046.316000
          part_status          2.000000
          Name: 23, dtype: float64
```

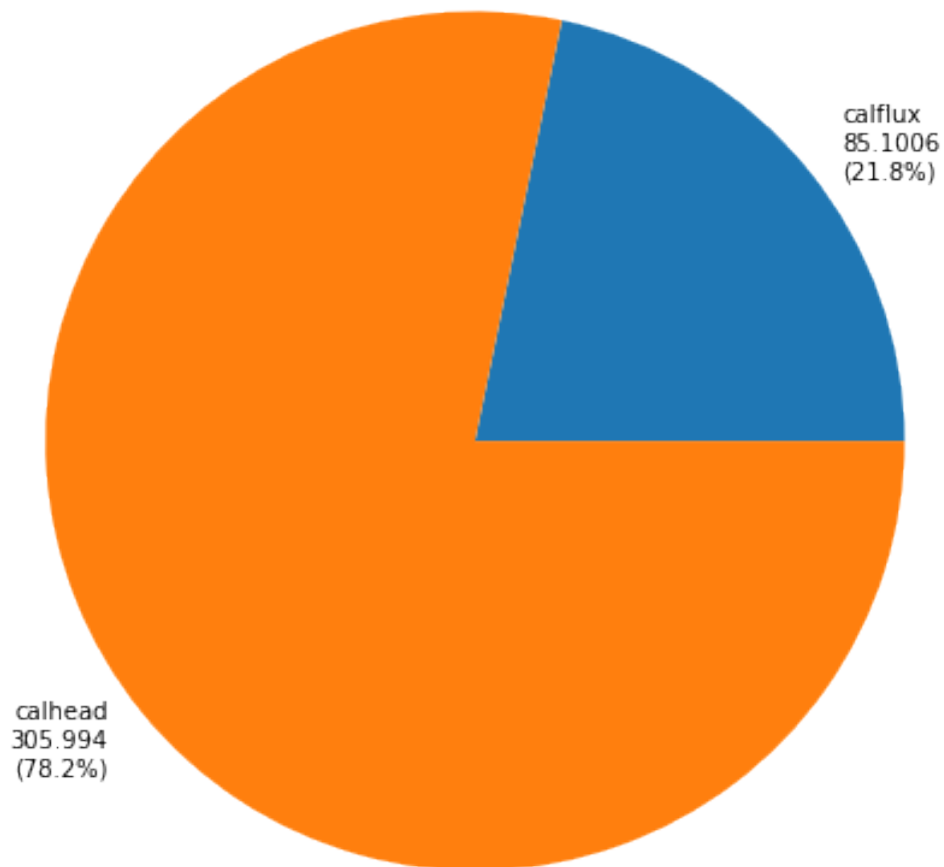
Assign some initial weights. Now, it is custom to add noise to the observed values... we will use the classic Gaussian noise... zero mean and standard deviation of 1 over the weight

```
In [14]: pst = pyemu.Pst(os.path.join(t_d,"freyberg.pst"))
          obs = pst.observation_data
          obs.loc[:, "obsval"] = obs_df.loc[idx,pst.obs_names]
          obs.loc[obs.obgnme=="calhead", "weight"] = 10.0
          obs.loc[obs.obgnme=="calflux", "weight"] = 0.075
          np.random.seed(seed=0)
          snd = np.random.randn(pst.nnz_obs)
          noise = snd * 1./obs.loc[pst.nnz_obs_names, "weight"]
          #pst.observation_data.loc[noise.index, "obsval"] += noise
          pst.write(os.path.join(t_d,"freyberg.pst"))
          pyemu.os_utils.run("pestpp-ies freyberg.pst", cwd=t_d)
```

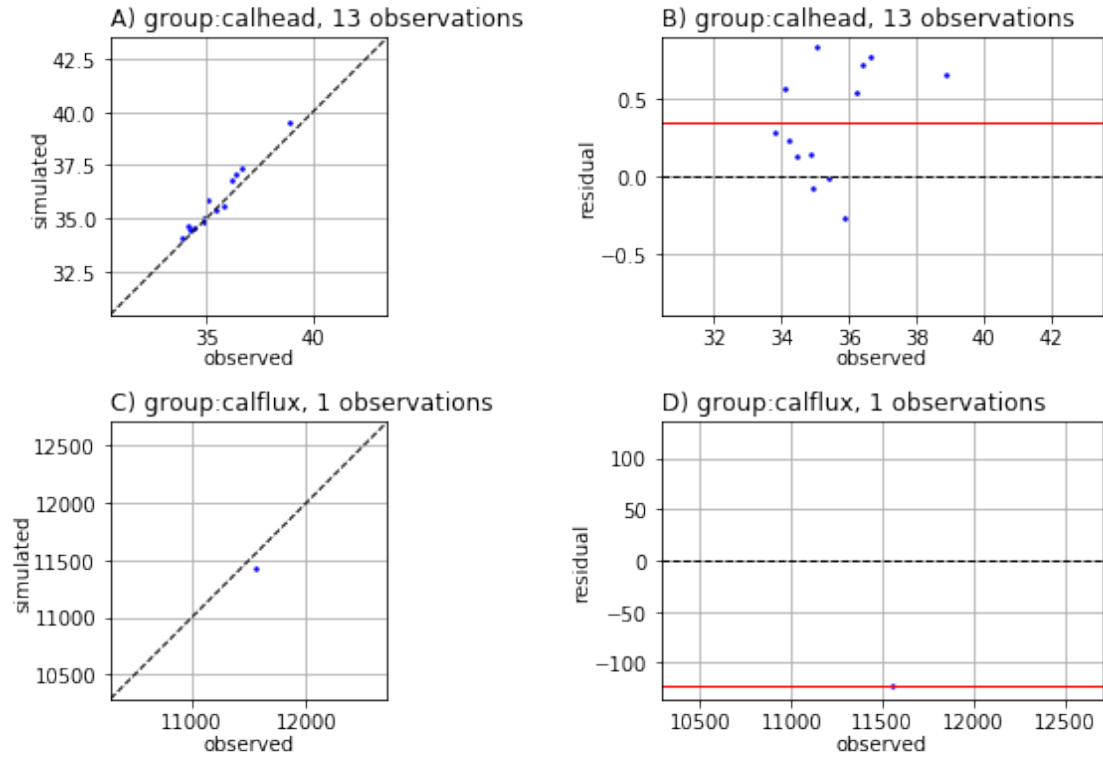


```
In [15]: pst = pyemu.Pst(os.path.join(t_d,"freyberg.pst"))
print(pst.phi)
pst.plot(kind='phi_pie')
pst.res.loc[pst.nnz_obs_names,:]
figs = pst.plot(kind="1to1")
```

391.0941587400599



<Figure size 576x756 with 0 Axes>



Publication ready figs - oh snap!

Just to make sure we have everything working right, we should be able to load the truth parameters, run the model once and have a ϕ equivalent to the noise vector:

```
In [16]: par_df = pd.read_csv(os.path.join(m_d,"sweep_in.csv"),index_col=0)
pst.parameter_data.loc[:, "parval1"] = par_df.loc[idx,pst.par_names]
pst.write(os.path.join(m_d,"test.pst"))
pyemu.os_utils.run("pestpp-ies.exe test.pst", cwd=m_d)
pst = pyemu.Pst(os.path.join(m_d,"test.pst"))
print(pst.phi)
pst.res.loc[pst.nnz_obs_names,:]
```

8.972208849493734e-17

```
Out [16]:
```

	name	group	measured	modelled \
name				
fo_39_19791230	fo_39_19791230	calflux	11553.000000	11553.000000
hds_00_002_009_000	hds_00_002_009_000	calhead	36.390945	36.390945
hds_00_002_015_000	hds_00_002_015_000	calhead	34.901199	34.901199
hds_00_003_008_000	hds_00_003_008_000	calhead	36.633041	36.633041
hds_00_009_001_000	hds_00_009_001_000	calhead	38.894932	38.894932
hds_00_013_010_000	hds_00_013_010_000	calhead	35.846367	35.846367
hds_00_015_016_000	hds_00_015_016_000	calhead	34.909328	34.909328
hds_00_021_010_000	hds_00_021_010_000	calhead	35.402809	35.402809
hds_00_022_015_000	hds_00_022_015_000	calhead	34.446541	34.446541
hds_00_024_004_000	hds_00_024_004_000	calhead	36.218941	36.218941
hds_00_026_006_000	hds_00_026_006_000	calhead	35.067863	35.067863
hds_00_029_015_000	hds_00_029_015_000	calhead	34.225922	34.225922
hds_00_033_007_000	hds_00_033_007_000	calhead	34.120350	34.120350
hds_00_034_010_000	hds_00_034_010_000	calhead	33.842617	33.842617

	residual	weight
name		
fo_39_19791230	0.000000e+00	0.075
hds_00_002_009_000	4.296865e-10	10.000
hds_00_002_015_000	1.796892e-10	10.000
hds_00_003_008_000	1.640643e-10	10.000
hds_00_009_001_000	-2.128928e-10	10.000
hds_00_013_010_000	-3.242207e-10	10.000
hds_00_015_016_000	3.066418e-10	10.000
hds_00_021_010_000	-6.640732e-11	10.000
hds_00_022_015_000	4.804690e-10	10.000
hds_00_024_004_000	1.367155e-10	10.000
hds_00_026_006_000	-3.554703e-10	10.000
hds_00_029_015_000	1.406235e-10	10.000
hds_00_033_007_000	-3.320366e-11	10.000
hds_00_034_010_000	8.789414e-11	10.000

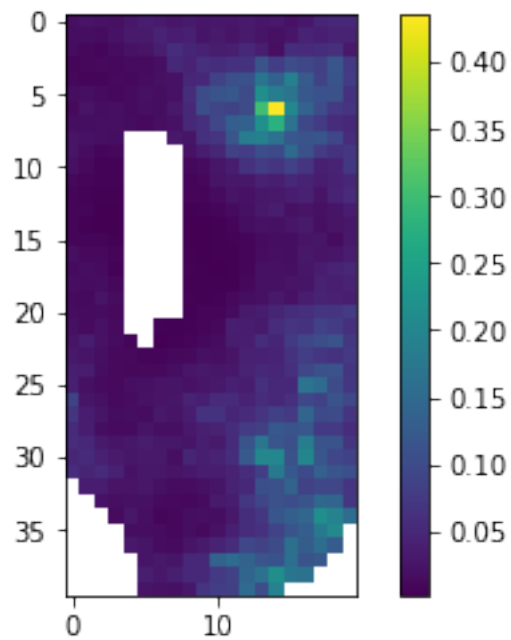
The residual should be exactly the noise values from above. Lets load the model (that was just run using the true pars) and check some things

```
In [17]: m = flopy.modflow.Modflow.load("freyberg.nam",model_ws=m_d)
```

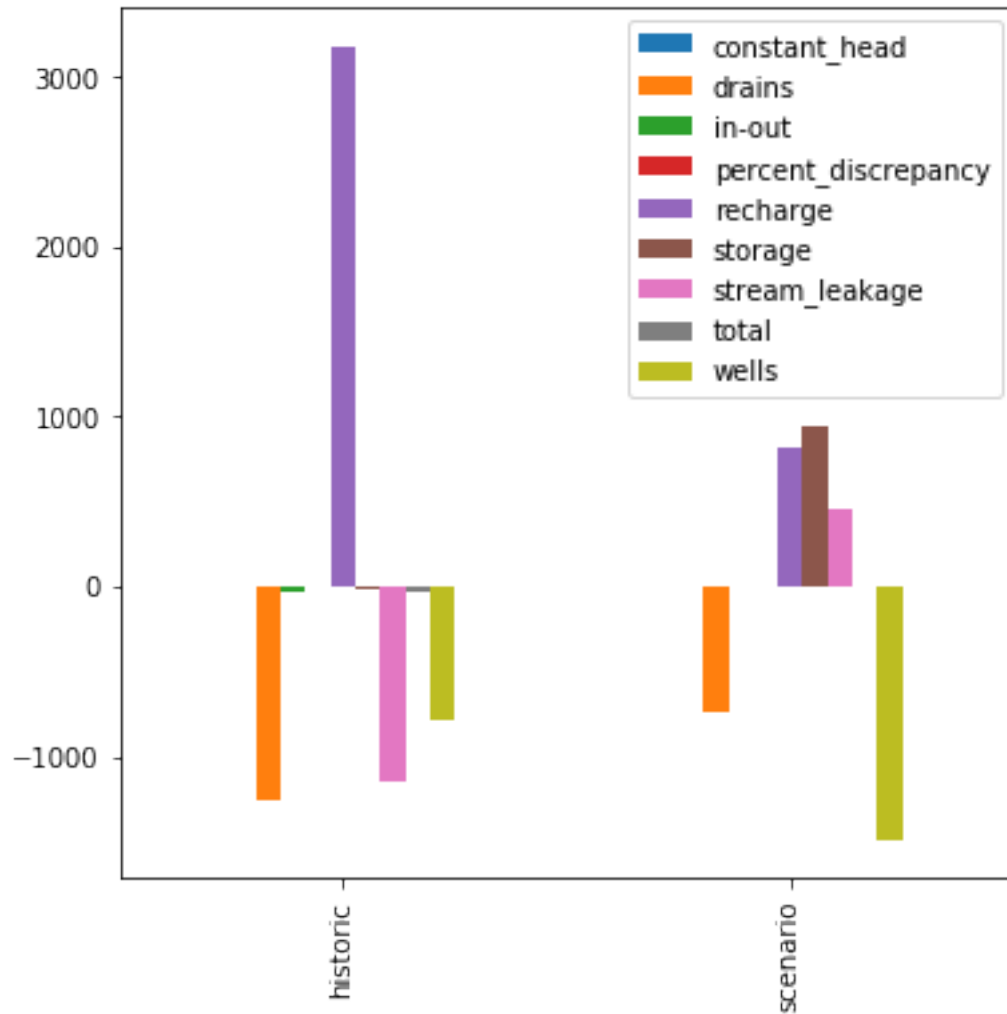
```
In [18]: a = m.upw.vka[1].array
         #a = m.rch.rech[0].array
         a = np.ma.masked_where(m.bas6.ibound[0].array==0,a)
         print(a.min(),a.max())
         c = plt.imshow(a)
         plt.colorbar(c)
```

0.002020436 0.4354167

Out[18]: <matplotlib.colorbar.Colorbar at 0x1819bcd208>



```
In [19]: lst = flopy.utils.MfListBudget(os.path.join(m_d,"freyberg.list"))
         df = lst.get_dataframes(diff=True)[0]
         ax = df.plot(kind="bar",figsize=(6,6))
         a = ax.set_xticklabels(["historic","scenario"],rotation=90)
```

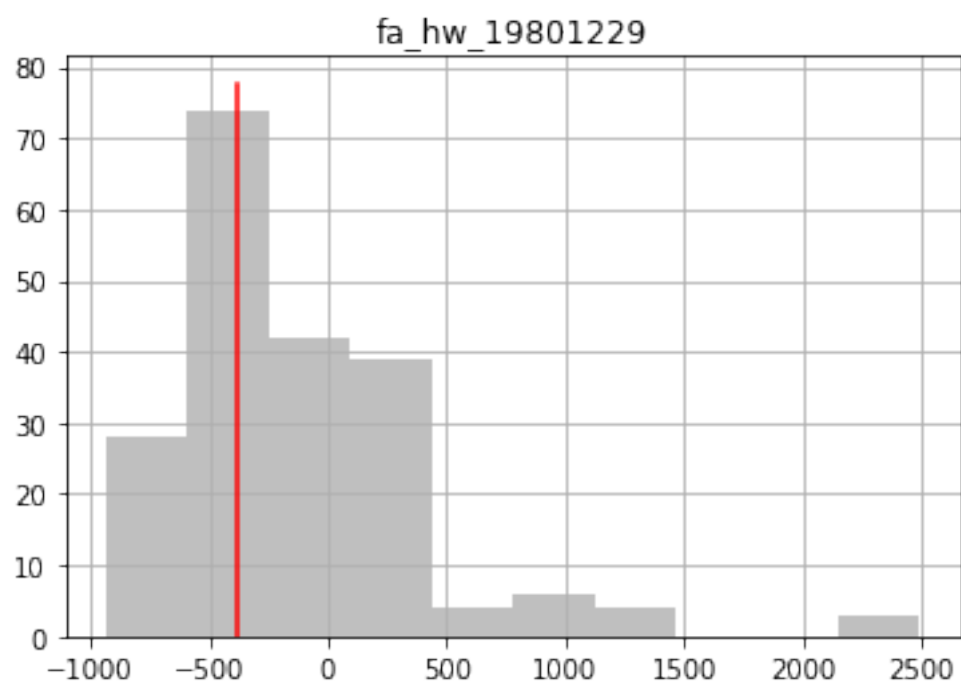
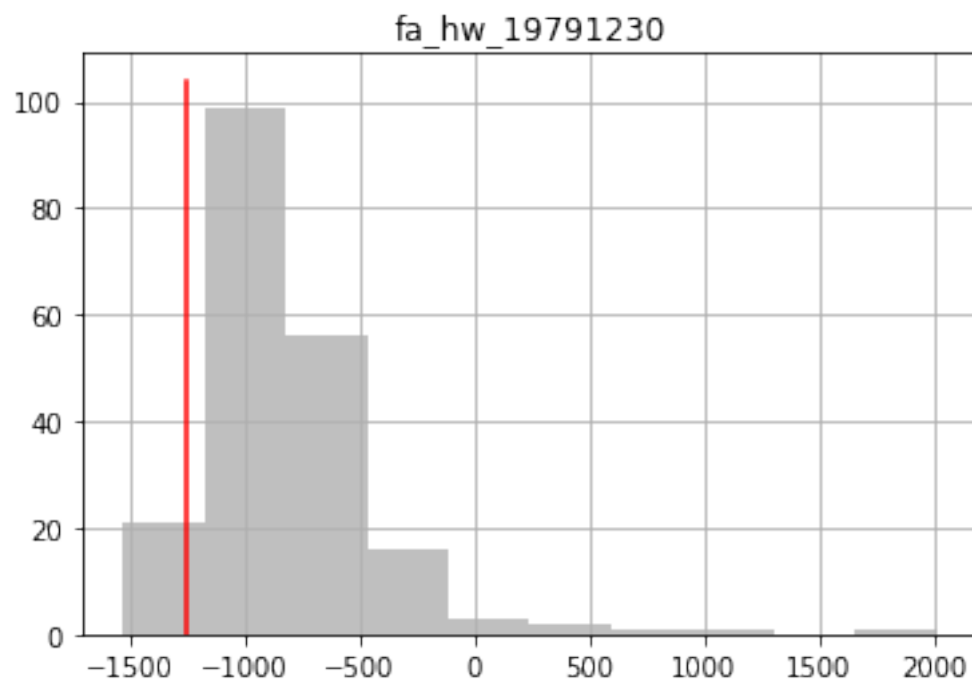


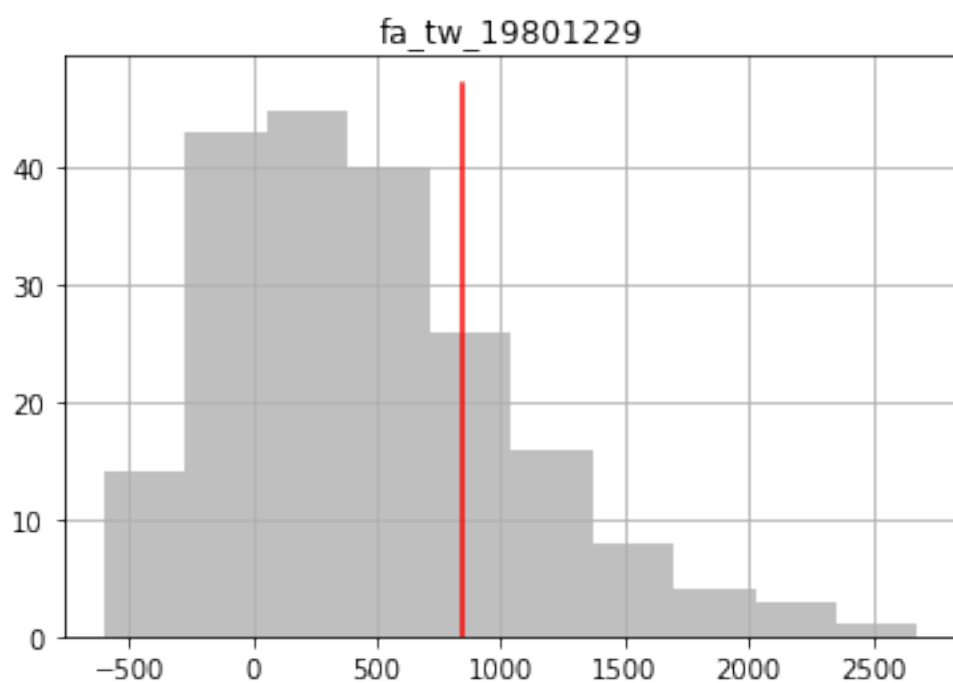
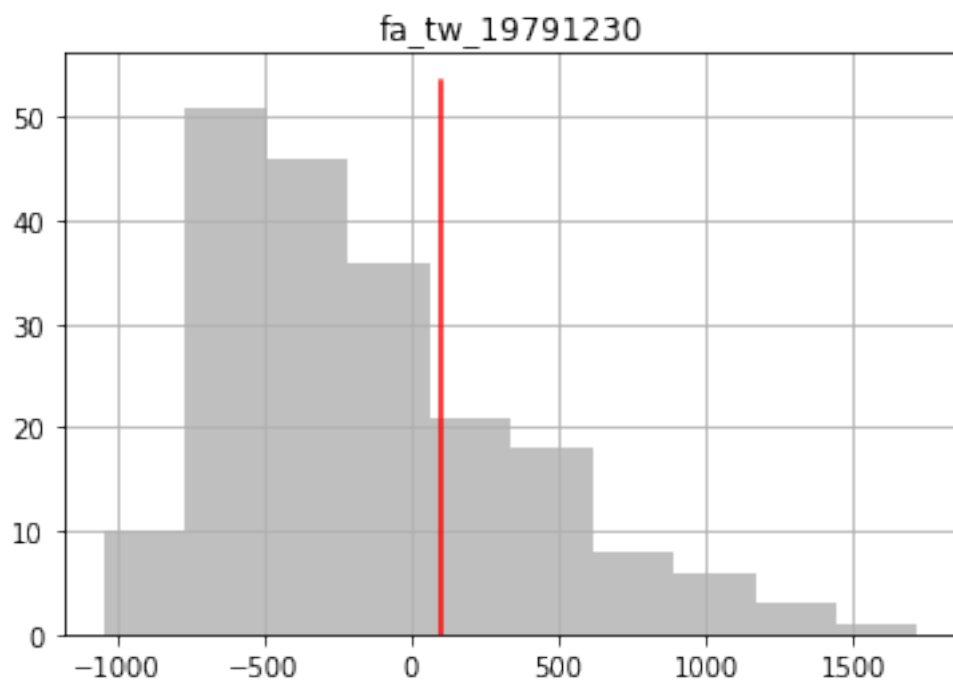
1.0.5 see how our existing observation ensemble compares to the truth

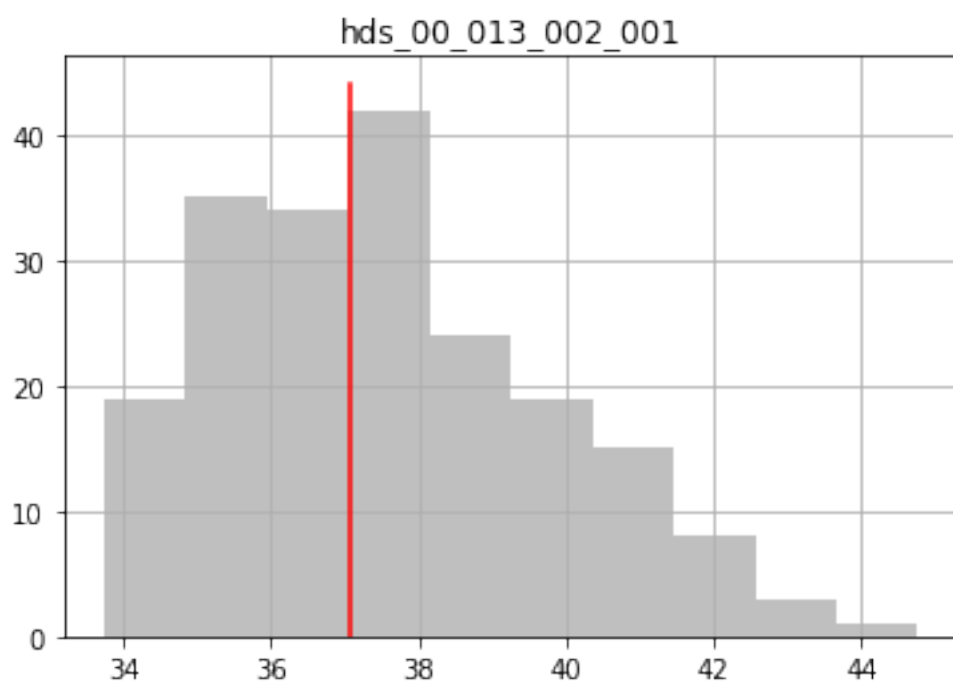
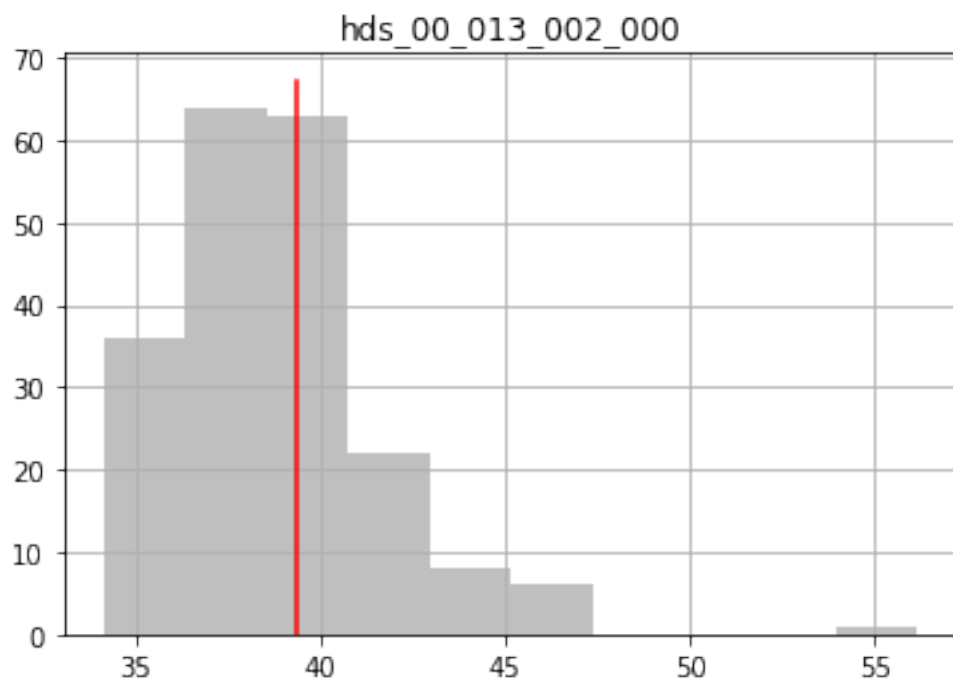
sw-gw outputs:

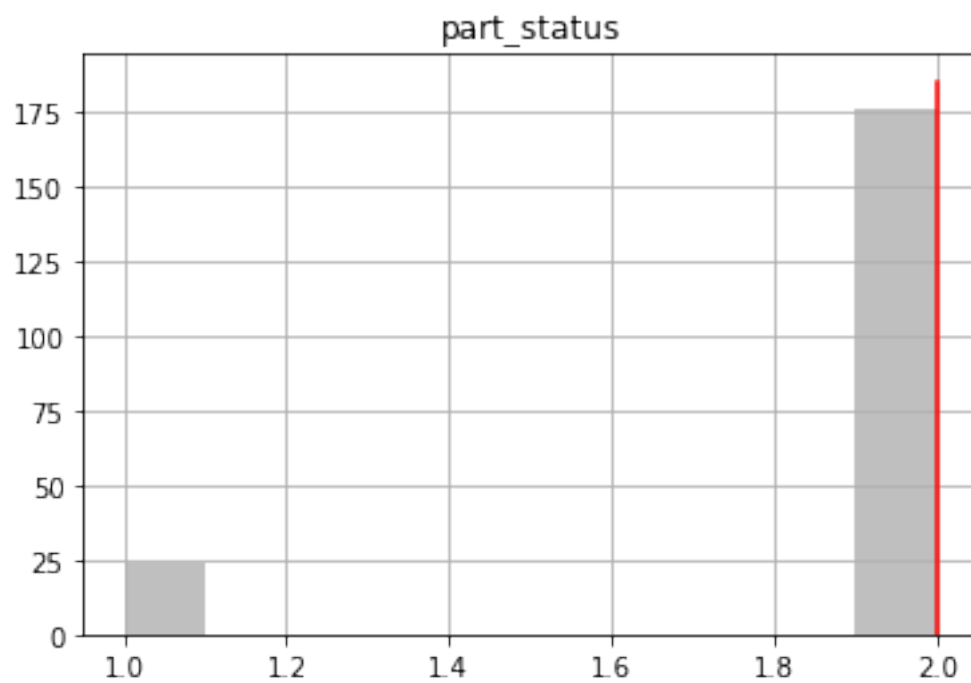
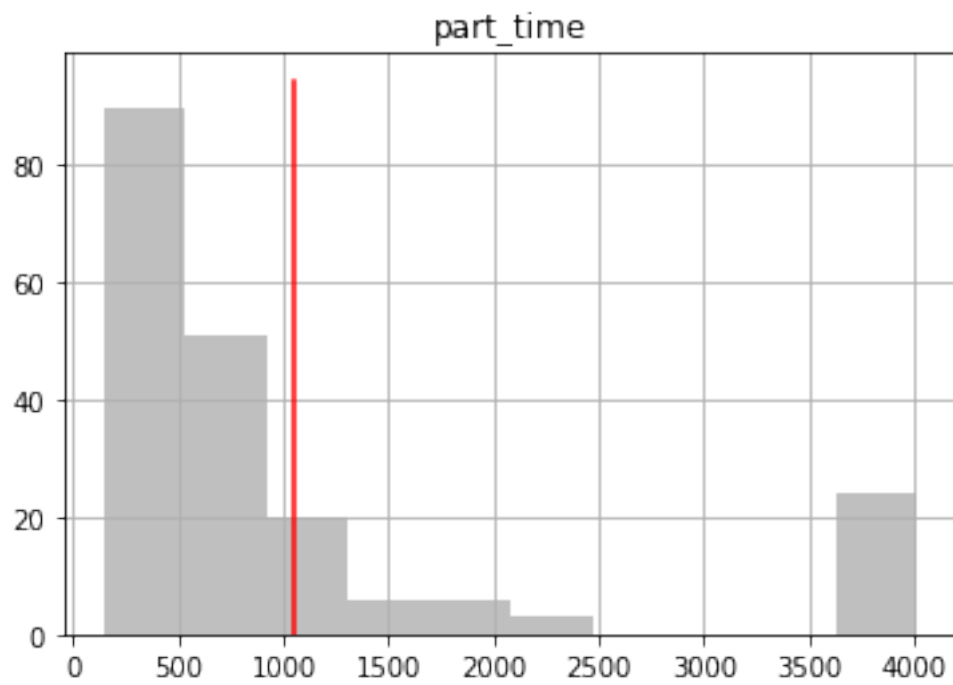
```
In [20]: obs = pst.observation_data
```

```
for forecast in fnames:
    ax = plt.subplot(111)
    obs_df.loc[:,forecast].hist(ax=ax,color="0.5",alpha=0.5)
    ax.plot([obs.loc[forecast,"obsval"],obs.loc[forecast,"obsval"]],ax.get_ylim(),"r")
    ax.set_title(forecast)
    plt.show()
```









observations:

```

In [21]: for oname in pst.nnz_obs_names:
          ax = plt.subplot(111)
          obs_df.loc[:, oname].hist(ax=ax, color="0.5", alpha=0.5)
          ax.plot([obs.loc[oname, "obsval"], obs.loc[oname, "obsval"]], ax.get_ylim(), "r")
          ax.set_title(oname)
          plt.show()

```

