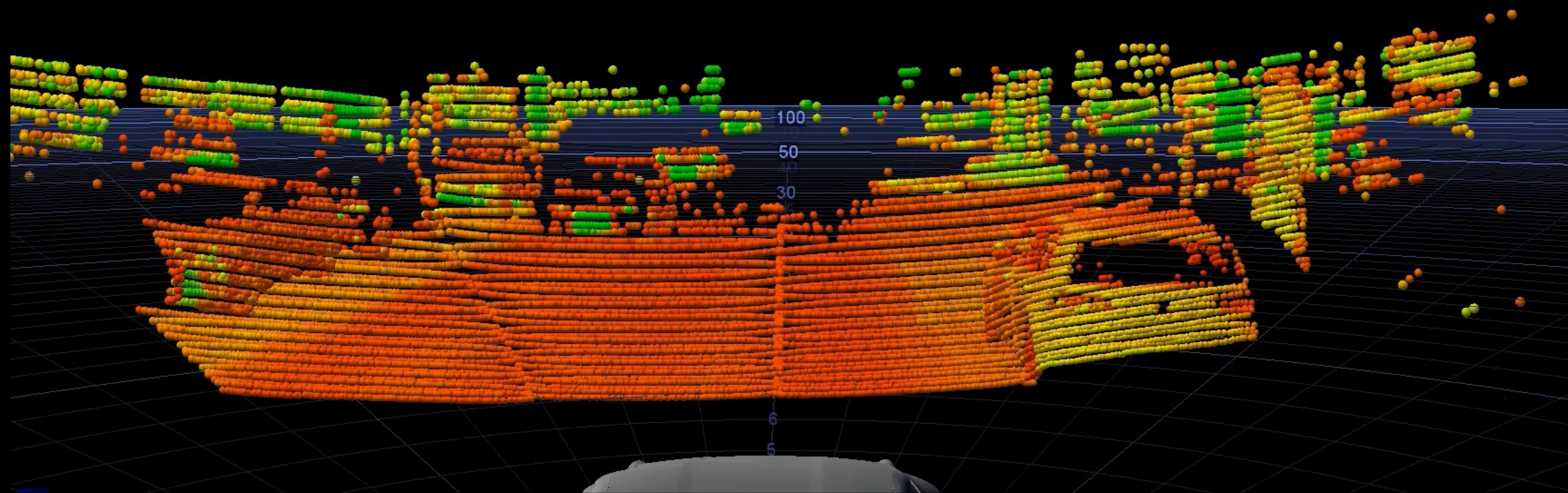


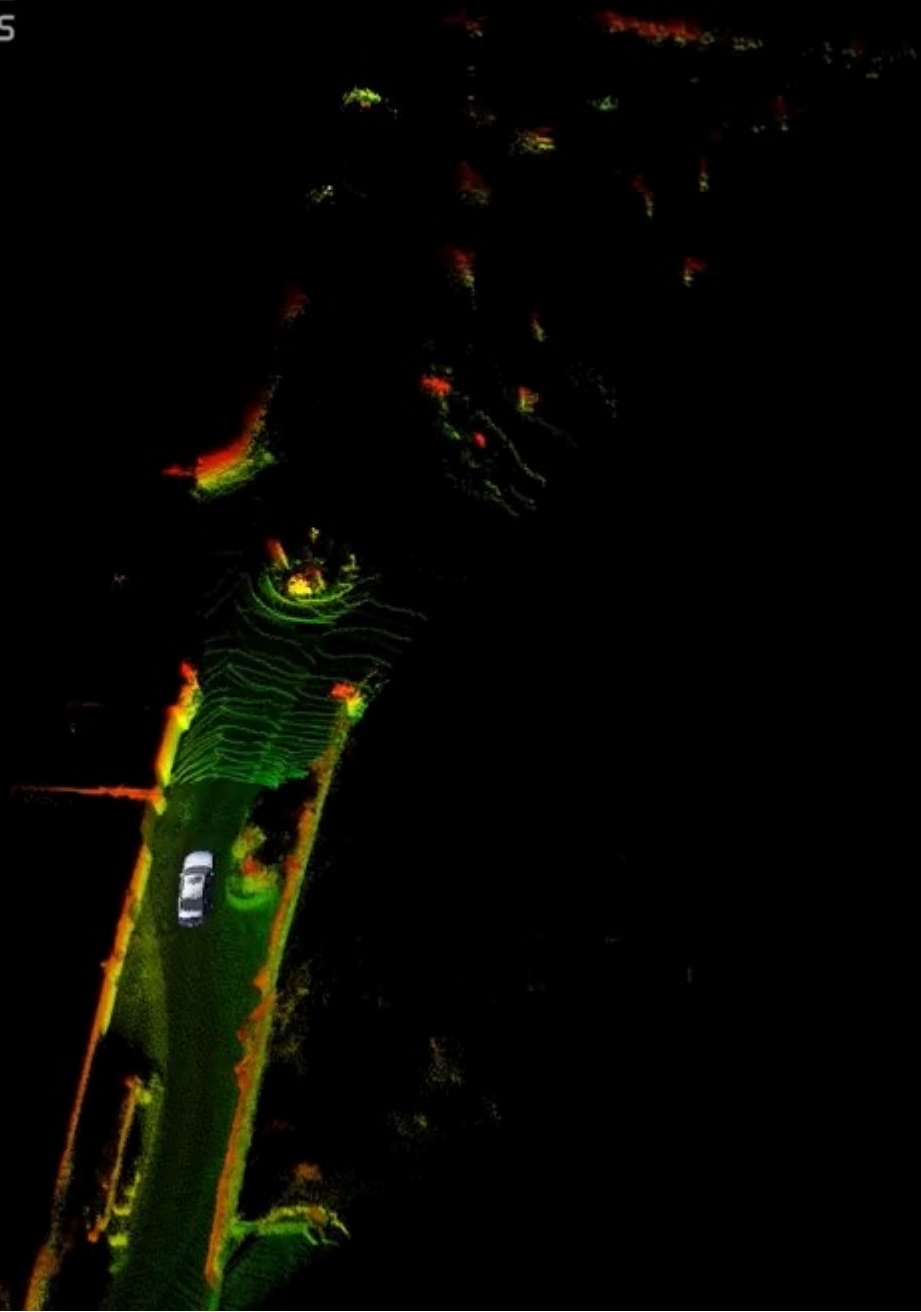
The background image shows a white Volvo car parked on a city street. A small, grey, box-like sensor unit is placed on the ground next to the car. In the background, there is a city skyline with several tall buildings. The right side of the image is decorated with a pattern of blue dots of varying sizes.

DataHack 2018 Challenge

Sep 25, 2018

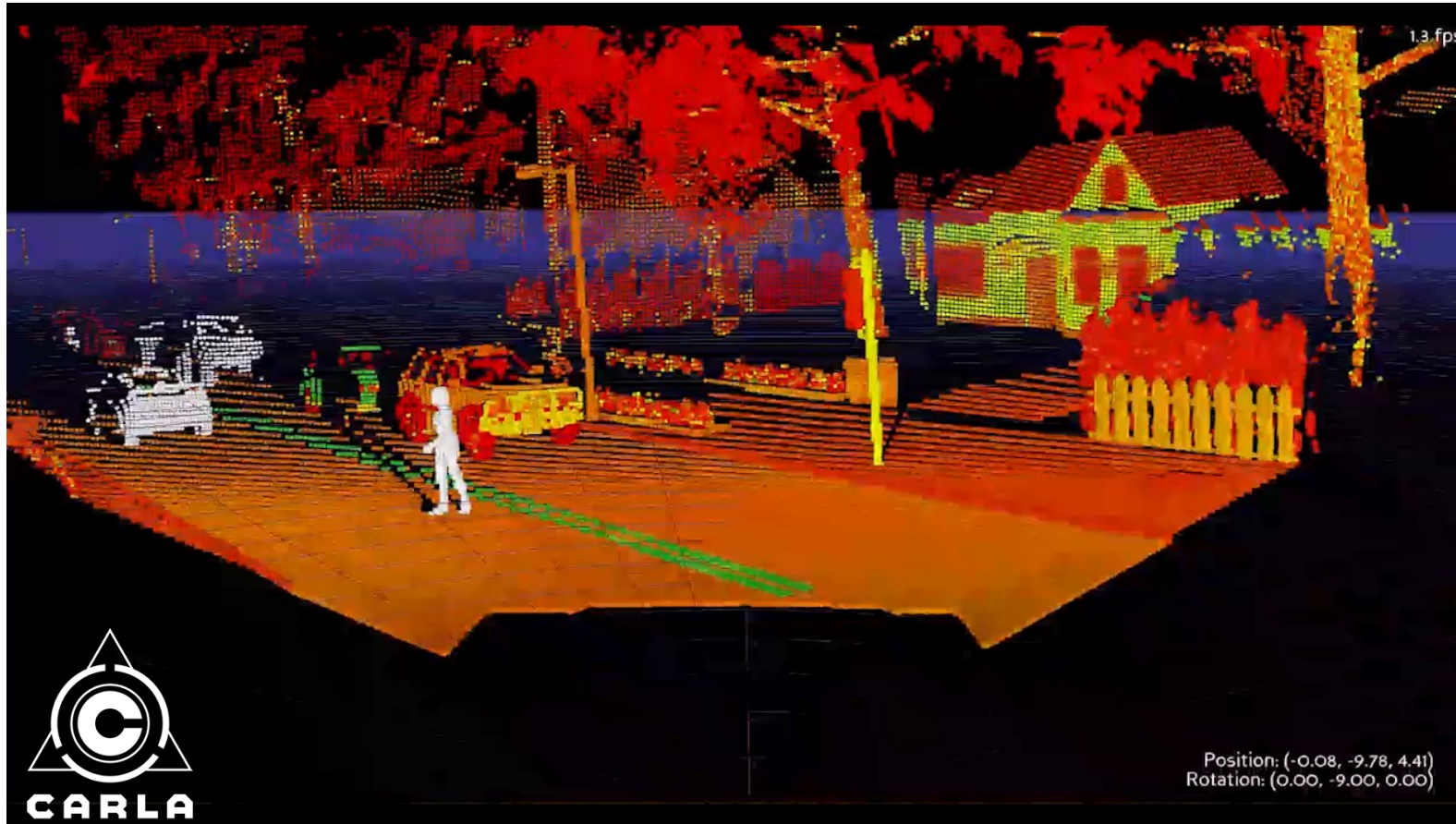
Rigid Motion
Detection





The Challenge

Label all points that belong to moving objects (e.g. pedestrians, cars)




















Dataset

Multiple videos of urban drive

Each frame consists of 3 files

1. Point cloud
2. Ego motion
3. Ground truth labels

Name	Date modified	Type	Size
 0003000_egomotion.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	1 KB
 0003000_labels.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	88 KB
 0003000_pointcloud.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	651 KB
 0003001_egomotion.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	1 KB
 0003001_labels.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	87 KB
 0003001_pointcloud.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	646 KB
 0003002_egomotion.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	1 KB
 0003002_labels.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	87 KB
 0003002_pointcloud.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	641 KB
 0003003_egomotion.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	1 KB
 0003003_labels.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	86 KB
 0003003_pointcloud.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	637 KB
 0003004_egomotion.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	1 KB
 0003004_labels.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	86 KB
 0003004_pointcloud.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	634 KB
 0003005_egomotion.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	1 KB
 0003005_labels.csv	20-Sep-18 10:45 AM	Microsoft Excel C...	86 KB

What You Get

You don't need to be a 3D/point cloud expert!

In our repo (python – all open source):

1. RotationTranslationData class
2. 3d point cloud viewer
3. Readers and code examples
4. Evaluation

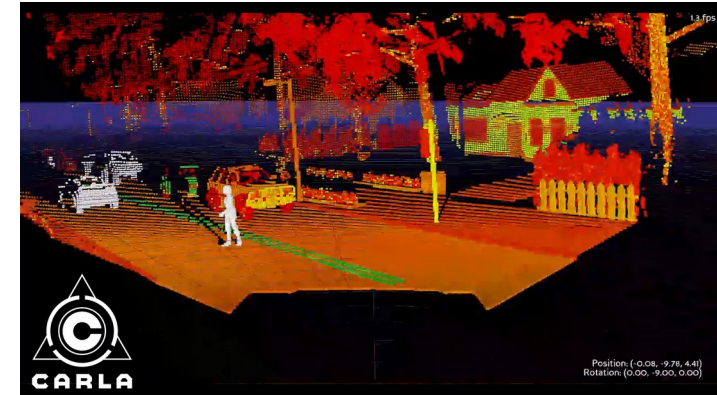
<https://github.com/InnovizTech/DataHack2018> coming soon...

What You Get

You don't need to be a 3D/point cloud expert!

In our repo (python - all open source):

1. RotationTranslationData class
2. 3d point cloud viewer
3. Readers and code examples
4. Evaluation



```
from visualizations.vis import pcshow
import numpy as np
from infra import utils

if __name__ == '__main__':
    video_dir = 'video_dir'
    frame_indices = utils.extract_frame_indices(video_dir)
    for idx in frame_indices:
        pc_file_name = utils.frame_to_filename(video_dir, idx, 'pointcloud')
        pc = utils.read_data(video_dir, idx, 'pointcloud')
        label = utils.read_data(video_dir, idx, 'labels')
        labeled_pc = np.concatenate((pc, label), -1)
        pcshow(labeled_pc)
```

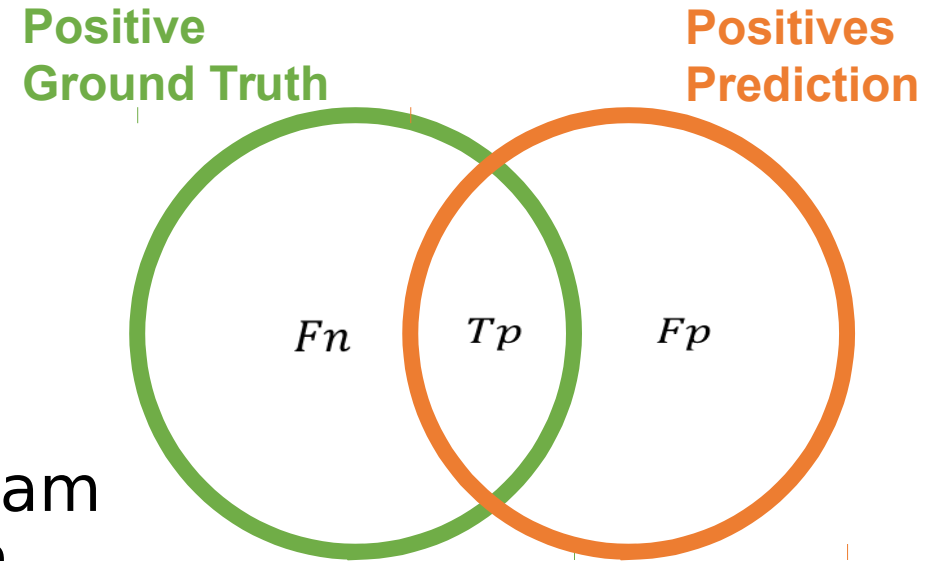
<https://github.com/InnovizTech/DataHack2018> coming soon...

Evaluation

IOU based evaluation

80% of the test set includes ego-motion

Awards will be granted to best scoring team and team with the most creative solution.



$$IOU = \frac{\text{intersection}}{\text{union}} = \frac{Tp}{Tp + Fn + Fp}$$

THANK YOU.

INNOVIZ

ENABLING THE AUTONOMOUS CAR REVOLUTION

