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# Introduction to Forecasting

## BSAD 8310: Business Forecasting — Lecture 1

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## Why Forecasting Matters

Every business decision made today depends on expectations about tomorrow.

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## Operations & Supply Chain

- How much inventory should Walmart order for Black Friday?
- How many nurses does a hospital need next Tuesday night?
- When will this machine component fail?

## Finance & Risk

- Will credit card defaults rise next quarter?
- What will the Fed Funds rate be in 6 months?
- How volatile will equity returns be tomorrow?

## Marketing & Strategy

- How many units will this new product sell in year one?
- What is the customer lifetime value of this cohort?

## Macro & Public Policy

- Will GDP grow by 2% or 3% next year?
- What will unemployment be in Q4?

A decision is only as good as the forecast it rests on.

- **UK NHS (2020):** Initial COVID hospitalization forecasts off by  $4\times$  — led to procurement of excess ventilators and delayed other treatments.
- **Toys R Us (2017):** Systematically over-ordered inventory based on outdated demand forecasts — contributed to bankruptcy.
- **Target Canada (2015):** Inventory system forecasting errors caused shelves to be overstocked on some items, empty on others — a \$2B writedown.

**Overfitting is not the only failure mode.** Ignoring uncertainty (using a point forecast as if it were certain) is equally dangerous.

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## Fundamental challenges:

- **Uncertainty:** The future is inherently random. The best we can do is characterize the distribution of outcomes.
- **Nonlinearity:** Many economic relationships change over time or at a threshold.
- **Regime shifts:** Structural breaks (recessions, pandemics, policy changes) alter the data-generating process.
- **High dimensionality:** More potential predictors than observations (especially in ML half of course).

## Statistical challenges:

- Serial correlation:  $y_t$  and  $y_{t-1}$  are not independent.
- Non-stationarity: mean and variance may change over time.
- Sparse data: rare events (defaults, crises) have few observations.
- Evaluation: you can only evaluate out-of-sample.

This course: learn *when* and *why* each method works — not just how to run it.

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## The Forecasting Framework

A precise language for talking about prediction under uncertainty.

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A **time series** is an ordered sequence of observations  $\{y_1, y_2, \dots, y_T\}$  where  $t$  indexes time.

### Notation:

- $y_t$  — observed value at time  $t$
- $h$  — **forecast horizon** (periods ahead)
- $\mathcal{F}_t$  — **information set** at time  $t$  (all data available up to and including time  $t$ ; may include past values of predictors and economic indicators, not only the history of  $y_t$ )
- $\hat{y}_{t+h|t}$  — forecast of  $y_{t+h}$  made at time  $t$

### Examples:

- $h = 1$ : next month's sales
- $h = 12$ : sales 12 months from now
- $h = 1$  vs.  $h = 12$ : harder problem as  $h$  increases

The subscript notation  $\hat{y}_{t+h|t}$  is read “ $y$ -hat at  $t + h$  given  $t$ .”



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We want a single number  $\hat{y}_{t+h|t}$  to represent our best guess of  $y_{t+h}$ .

Suppose you must predict next month's retail sales. You can observe all history  $\{y_1, \dots, y_t\}$ .

**What single number would you report to minimize your average squared miss?**

*Hint: think about what the mean of a distribution minimizes.*

Under **squared error loss**, the optimal  $h$ -step-ahead forecast is:

$$\hat{y}_{t+h|t} = \mathbb{E}[y_{t+h} \mid \mathcal{F}_t]$$

the *conditional expectation* of  $y_{t+h}$  given all information at time  $t$ .

### Why the conditional expectation?

- The MSE-minimizing predictor of any random variable  $Z$  is  $\mathbb{E}[Z]$  — the mean.
- Conditioned on  $\mathcal{F}_t$ , that becomes  $\mathbb{E}[Z \mid \mathcal{F}_t]$ .
- Proof sketch:  $\mathbb{E}[(Z - c)^2]$  is minimized at  $c = \mathbb{E}[Z]$ ; condition on  $\mathcal{F}_t$ .

**Different loss functions yield different optimal forecasts.** MAE loss  $\Rightarrow$  conditional median. We will use MSE throughout unless stated otherwise.

*When is MAE preferable? Hint: asymmetric costs (e.g., stockout vs. over-stocking).*

The **forecast error** for a one-step-ahead forecast is:

$$e_t = y_t - \hat{y}_{t|t-1}$$

For  $h$ -step-ahead:  $e_{t+h} = y_{t+h} - \hat{y}_{t+h|t}$

### Properties of errors from the optimal forecast:

- $\mathbb{E}[e_t] = 0$  — unbiased (no systematic over- or under-prediction)
- $\text{Cov}(e_t, e_{t-k}) = 0$  for  $k \geq 1$  — errors are uncorrelated (if forecast is truly optimal)
- Errors that are autocorrelated reveal *unexploited information*

**Reserve  $\varepsilon_t$  for the true innovation (white noise) of a model.** Use  $e_t$  for the realized forecast error. These are different:  $e_t$  includes parameter estimation error;  $\varepsilon_t$  does not.

## Point forecast

$$\hat{y}_{t+1|t} = 42.7$$

- Single number
- Most common in practice
- Hides uncertainty

## Interval forecast

$$[38.2, 47.2]$$

- Lower + upper bound
- 95% coverage means: 95% of such intervals contain  $y_{t+1}$
- Calibration matters

## Density forecast

$$p(y_{t+1} \mid \mathcal{F}_t)$$

- Full distribution
- Most informative
- Harder to produce and evaluate

This course focuses on **point** and **interval** forecasts. Density forecasting is introduced in Lecture 6.

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## Time Series Patterns

Before fitting any model, understand the structure of the data.

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Any time series can be decomposed into (additive form):

$$y_t = T_t + S_t + C_t + I_t$$

Multiplicative form:  $y_t = T_t \times S_t \times C_t \times I_t$  (use when seasonal amplitude grows with level).

- $T_t$ : **Trend** — long-run movement (linear, quadratic, or stochastic)
- $S_t$ : **Seasonality** — regular, calendar-driven pattern
- $C_t$ : **Cycle** — medium-run fluctuations (business cycles)
- $I_t$ : **Irregular** — random shocks and one-offs

- **Retail sales:** strong trend + strong seasonality
- **Quarterly GDP:** trend + cycle (weak seasonality)
- **Daily stock returns:** nearly all irregular
- **Energy demand:** trend + seasonality + cycle

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**Seasonal period  $m$ :** the number of observations per year (or per recurring cycle).

Data frequency	Seasonal period $m$
Annual	1 (no seasonality)
Quarterly	4
Monthly	12
Weekly	52
Daily	7 or 365

**Ignoring seasonality is a common source of large forecast errors.** A non-seasonal model applied to monthly retail data will systematically under-forecast in December and over-forecast in January.

Lab 01 will visualize seasonality in US retail sales data. We will decompose the series using STL (Seasonal-Trend decomposition via LOESS).

A time series  $\{y_t\}$  is **weakly stationary** if:

1.  $\mathbb{E}[y_t] = \mu$  (constant mean)
2.  $\text{Var}(y_t) = \sigma^2 < \infty$  (constant variance)
3.  $\text{Cov}(y_t, y_{t-k}) = \gamma_k$  depends only on lag  $k$ , not on  $t$

### Why it matters:

- Most classical forecasting methods assume stationarity
- Non-stationary series produce *spurious* regressions

**Rule of thumb:** Visible trend or expanding variance  $\Rightarrow$  likely non-stationary.

Full treatment: **Lecture 4** (ARIMA Models).

*Is US retail sales stationary? What about daily S&P 500 returns vs. price levels?*



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## Benchmark Models

Always beat a simple baseline before claiming success.

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Before presenting any forecast model, establish what a **naïve benchmark** achieves. A model that does not beat the benchmark has zero value.

### Why benchmarks matter:

- Many series are hard to forecast — even “simple” models may be hard to beat.
- The M4 Competition (Makridakis et al. 2020): out of 61 methods, many sophisticated ML models failed to beat exponential smoothing.
- A benchmark defines the floor. Your goal is to clear it by a meaningful margin.

Naïve, Seasonal Naïve, Historical Mean, Random Walk with Drift. We will always compute these before evaluating any model.

$$\hat{y}_{t+h|t} = y_t \quad \text{for all } h \geq 1$$

Use the *most recent observation* as the forecast for all future periods.

### Properties:

- Equivalent to a **random walk** model:  
 $y_t = y_{t-1} + \varepsilon_t$
- Optimal under the random walk hypothesis
- Standard benchmark for financial prices
- Forecast does not change with  $h$  (flat forecast function)

### When to use:

- ✓ Asset prices, exchange rates
- ✓ When you have very little history
- ✗ Series with strong trend or seasonality

Python: `y_hat = y_train.iloc[-1]`

$$\hat{y}_{t+h|t} = y_{t+h-12}$$

Use the *value from the same month one year ago*.

General form for arbitrary  $h$  and period  $m$ :  $\hat{y}_{t+h|t} = y_{t+h-m \cdot \lceil h/m \rceil}$

### Properties:

- Captures seasonality without modeling it explicitly
- Standard benchmark for monthly business data
- Automatically handles any seasonal period  $m$

### When to use:

- ✓ Retail sales, electricity demand
- ✓ Any series with clear seasonal pattern
- ✗ Non-seasonal series (use naïve instead)

Python: shift by seasonal period using  
`pd.Series.shift(m)`

$$\hat{y}_{t+h|t} = \bar{y}_t = \frac{1}{t} \sum_{s=1}^t y_s \quad \text{for all } h \geq 1$$

Forecast with the *average of all past observations*.

### Properties:

- Optimal under the assumption that  $y_t$  is i.i.d.
- Produces a constant, flat forecast
- Variance of forecast error decreases as  $t$  grows (more data  $\Rightarrow$  better estimate of  $\mu$ )

### When to use:

- ✓ Stationary series with no pattern
- ✓ Very long history, very stable series
- ✗ Any series with trend or seasonality

Python: `y_hat = y_train.mean()`

$$y_t = c + y_{t-1} + \varepsilon_t \implies \hat{y}_{t+h|t} = y_t + h\hat{c}$$

where  $\hat{c} = (y_T - y_1)/(T - 1)$  is the estimated average period-to-period change.

## Properties:

- Combines naïve with a linear trend component
- Forecast function: linear extrapolation from last observation
- Special case of Holt's linear exponential smoothing (Lecture 3) with  $\alpha = 1$ ,  $\beta = 1$

## Which benchmark to use?

No trend, no season  $\rightarrow$  Mean  
Trend, no season  $\rightarrow$  RW + Drift  
Season, no trend  $\rightarrow$  Seasonal Naïve  
Trend + Season  $\rightarrow$  Seasonal Naïve  
Asset prices  $\rightarrow$  Naïve

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## Forecast Evaluation

Forecasting without evaluation is not science — it is storytelling.

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Given  $T$  out-of-sample observations  $\{y_{T+1}, \dots, y_{T+H}\}$  and forecasts  $\{\hat{y}_{T+1|T}, \dots, \hat{y}_{T+H|T+H-1}\}$ :

**Scale-dependent metrics:**

$$\text{MSE} = \frac{1}{H} \sum_{h=1}^H e_{T+h}^2$$

$$\text{RMSE} = \sqrt{\text{MSE}}$$

$$\text{MAE} = \frac{1}{H} \sum_{h=1}^H |e_{T+h}|$$

RMSE and MAE are in the same units as  $y_t$ .

Use to compare models on the *same* series.

**Metric choice:** RMSE/MAE for same-series; MAPE across series; MASE vs. seasonal naïve. Prefer RMSE for costly outliers; MAE for robust comparison.

**Scale-free metric:**

$$\text{MAPE} = \frac{1}{H} \sum_{h=1}^H \left| \frac{e_{T+h}}{y_{T+h}} \right| \times 100\%$$

MAPE: cross-series comparison; undefined at  $y_{T+h} = 0$ ; asymmetric.

**RMSE vs. MAE:** RMSE penalizes large errors more heavily. If large errors are very costly, prefer RMSE.



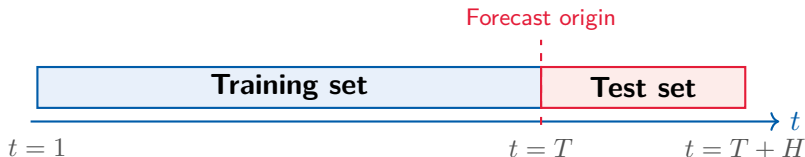
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**Never evaluate a forecast model on the data used to fit it.** In-sample fit measures how well you memorized the past, not how well you can predict the future.

**Correct time series train/test split:**

- Use observations  $1, \dots, T$  to estimate the model
- Evaluate on  $T + 1, \dots, T + H$  (held-out future observations)
- *Never* randomly shuffle observations — time order must be preserved

**Common mistake:** Using `sklearn`'s `KFold` on time series data. This randomly assigns observations to folds, allowing future data to “train” the model. Always use `TimeSeriesSplit`. Full treatment in **Lecture 7**.



- Model estimated on  $\{y_1, \dots, y_T\}$
- Forecasts  $\{\hat{y}_{T+1|T}, \dots, \hat{y}_{T+H|T}\}$  evaluated against realized values
- Typical test set size: **10–20%** of the series, or a fixed future window

Walk-forward (rolling-origin) evaluation: Lecture 6.

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Hyndman and Koehler (2006) propose the **Mean Absolute Scaled Error**:

$$\text{MASE} = \frac{\text{MAE}}{\frac{1}{T-m} \sum_{t=m+1}^T |y_t - y_{t-m}|}$$

- Denominator: in-sample MAE of the seasonal naïve forecast
- $\text{MASE} < 1$ : model beats seasonal naïve
- $\text{MASE} > 1$ : model is *worse* than the naïve benchmark
- Works when  $y_t = 0$  (unlike MAPE)
- Symmetric — positive and negative errors treated equally

MASE is the standard metric in the M-competitions (Makridakis et al. 2020). We will use it in Lecture 6 for model comparison.

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## Course Roadmap

What we will cover, and how it fits together.

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## Part I: Classical Econometric Forecasting

1. **Introduction** ← today
2. Regression-Based Forecasting
3. Exponential Smoothing (ETS)
4. ARIMA Models
5. Multivariate Methods (VAR, ARIMAX)
6. Forecast Evaluation & Combination

Focus: theory + properties + principled model selection.

## Part II: Predictive Analytics & Machine Learning

7. ML Introduction & Cross-Validation
8. Regularization (LASSO, Ridge, Elastic Net)
9. Tree-Based Methods (RF, XGBoost)
10. Neural Networks & LSTM
11. Feature Engineering
12. Capstone & Applications

Focus: scalability, data-driven model selection, real-world pipelines.

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## Python throughout:

- `statsmodels` — ARIMA, ETS, VAR, statistical tests
- `scikit-learn` — ML models, cross-validation, pipelines
- `pandas` — data manipulation
- `matplotlib` — visualization
- `numpy` — numerical computing

**Lab format:** Jupyter notebooks. Each lab implements the methods from the preceding lecture.

## What you will be able to do:

- ✓ Select and justify a forecasting method for a business problem
- ✓ Implement ARIMA, ETS, LASSO, and RF models in Python
- ✓ Evaluate and compare models rigorously
- ✓ Communicate forecast uncertainty to stakeholders
- ✓ Avoid the most common forecasting mistakes

Forecasting underpins every forward-looking business decision. Bad forecasts have measurable, costly consequences.

The optimal point forecast (under squared loss) is the **conditional expectation**:



$$\hat{y}_{t+h|t} = \mathbb{E}[y_{t+h} \mid \mathcal{F}_t].$$

Always establish **benchmark performance** first. A model that does not beat naïve is not useful.

**Evaluate out-of-sample only.** Never shuffle time series; always use `TimeSeriesSplit`.

Metric choice matters: RMSE penalizes large errors; MAPE allows cross-series comparison; MASE benchmarks against naïve.

*Next: Regression-Based Forecasting — when and how do predictor variables improve on these benchmarks?*

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-  Hyndman, Rob J. and Anne B. Koehler (2006). “Another Look at Measures of Forecast Accuracy”. In: *International Journal of Forecasting* 22.4, pp. 679–688.
  -  Makridakis, Spyros, Evangelos Spiliotis, and Vassilios Assimakopoulos (2020). “The M4 Competition: 100,000 Time Series and 61 Forecasting Methods”. In: *International Journal of Forecasting* 36.1, pp. 54–74.