# XGBoost: A Scalable Tree Boosting System

Presenter: Tianqi Chen



#### Outline

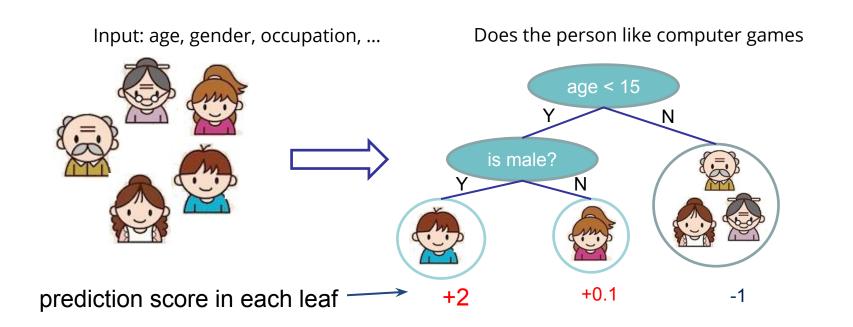
- Introduction
- What does XGBoost learn
- What can XGBoost System do for you
- Impact of XGBoost

#### Machine Learning Algorithms and Common Use-cases

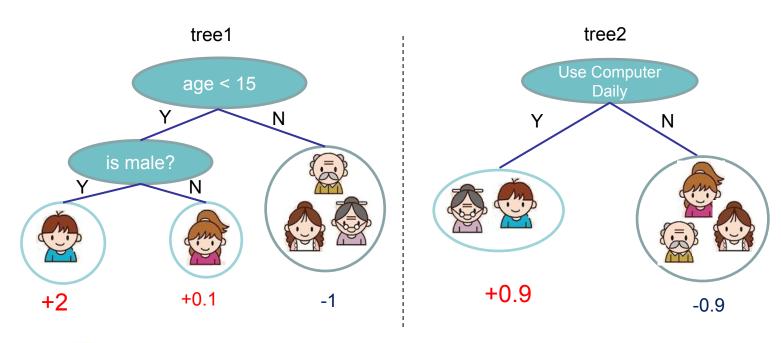
- Linear Models for Ads Clickthrough
- Factorization Models for Recommendation
- Deep Neural Nets for Images, Audios etc.
- **Trees** for tabular data: the *secret sauce* in machine learning
  - Anomaly detection
  - Ads clickthrough
  - Fraud detection
  - Insurance risk estimation
  - 0 ...

### Regression Tree

- Regression tree (also known as CART)
- This is what it would looks like for a commercial system



## When Trees forms a Forest (Tree Ensembles)





$$)=-1-0.9=-1.9$$

## Variant of algorithms to learn Tree Ensembles

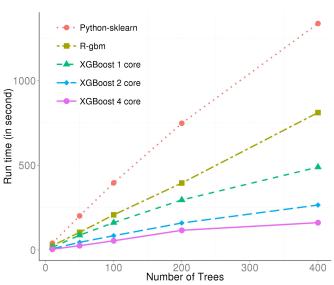
- Random Forest (*Breiman 1997*)
  - RandomForest packages in R and python
- Gradient Tree Boosting (Friedman 1999)
  - o R GBM
  - sklearn.ensemble.GradientBoostingClassifier
- Gradient Tree Boosting with Regularization (variant of original GBM)
  - Regularized Greedy Forest (RGF)
  - XGBoost

## Learning Trees: Advantage and Challenges

- Advantages of tree-based methods
  - Highly accurate: almost half of data science challenges are won by tree based methods.
  - Easy to use: invariant to input scale, get good performance with little tuning.
  - Easy to interpret and control
- Challenges on learning tree(ensembles)
  - Control over-fitting
  - Improve training speed and scale up to larger dataset

#### What is XGBoost

- A Scalable System for Learning Tree Ensembles
  - Model improvement
    - Regularized objective for better model
  - Systems optimizations
    - Out of core computing
    - Parallelization
    - Cache optimization
    - Distributed computing
  - Algorithm improvements
    - Sparse aware algorithm
    - Weighted approximate quantile sketch.
- In short, faster tool for learning better models



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#### What does XGBoost learn

- A self-contained derivation of general gradient boosting algorithm
- Resembles the original GBM derivation by *Friedman*
- Only preliminary of calculus is needed

## ML 101: Elements of Supervised Learning

- **Model**: how to make prediction  $\hat{y}_i = f(x_i)$ 
  - Linear model:  $\hat{y}_i = \sum_j w_j x_{ij}$
- Parameters: the things we need to learn from data
  - Linear model:  $\Theta = \{w_j | j = 1, \dots, d\}$
- Objective Function:  $Obj(\Theta) = L(\Theta) + \Omega(\Theta)$

**Training Loss** measures how well model fit on training data

**Regularization**, measures complexity of model

• Linear model:  $L(\Theta) = \sum_i (\hat{y}_i - y_i)^2$  ,  $\Omega(\Theta) = \lambda \|w\|_2^2$ 

## Elements of Tree Learning

Model: assuming we have K trees

$$\hat{y}_i = \sum_{k=1}^K f_k(x_i), \quad f_k \in \mathcal{F}$$

Space of Regression trees

• Objective  $Obj = \sum_{i=1}^{n} l(y_i, \hat{y}_i) + \sum_{k=1}^{K} \Omega(f_k)$ 

**Training Loss** measures how well model fit on training data

**Regularization**, measures complexity of trees

## Trade off in Learning

$$Obj = \sum_{i=1}^{n} l(y_i, \hat{y}_i) + \sum_{k=1}^{K} \Omega(f_k)$$

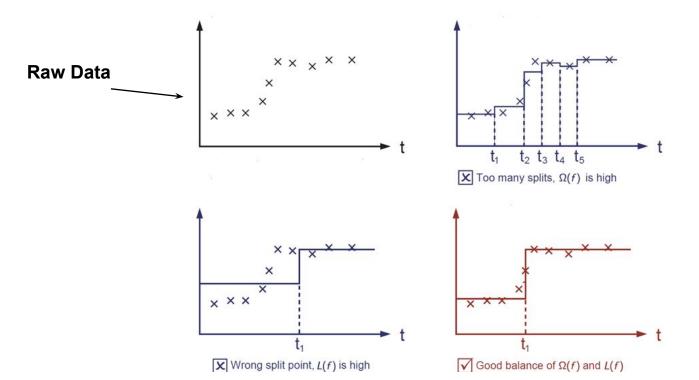
**Training Loss** measures how well model fit on training data

**Regularization**, measures complexity of trees

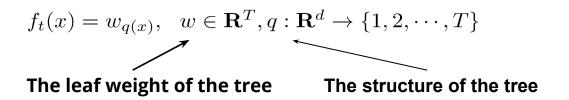
- Optimizing training loss encourages predictive models
  - Fitting well in training data at least get you close to training data which is hopefully close to the underlying distribution
- Optimizing regularization encourages simple models
  - Simpler models tends to have smaller variance in future predictions, making prediction stable

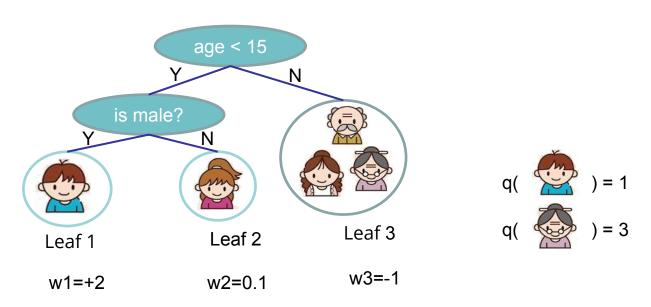
## Why do we need regularization

Consider the example of learning tree on a single variable t



## Define Complexity of a Tree





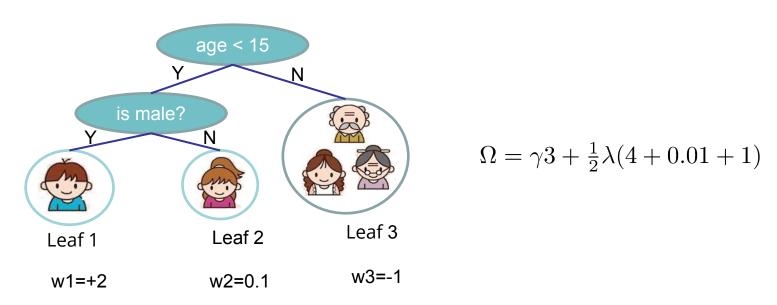
## Define Complexity of a Tree (cont')

Objective in XGBoost

$$\Omega(f_t) = \gamma T + \frac{1}{2}\lambda \sum_{j=1}^{T} w_j^2$$

**Number of leaves** 

L2 norm of leaf scores



#### How can we learn tree ensembles

- Objective:  $\sum_{i=1}^{n} l(y_i, \hat{y}_i) + \sum_{k} \Omega(f_k), f_k \in \mathcal{F}$
- We can not use methods such as SGD.
- Solution: Additive Training (Boosting)
  - Start from constant prediction, add a new function each time

$$\hat{y}_{i}^{(0)} = 0 
\hat{y}_{i}^{(1)} = f_{1}(x_{i}) = \hat{y}_{i}^{(0)} + f_{1}(x_{i}) 
\hat{y}_{i}^{(2)} = f_{1}(x_{i}) + f_{2}(x_{i}) = \hat{y}_{i}^{(1)} + f_{2}(x_{i}) 
\dots$$

$$\hat{y}_i^{(t)} = \sum_{k=1}^t f_k(x_i) = \hat{y}_i^{(t-1)} + f_t(x_i) \quad \longleftarrow$$

Model at training round t Keep functions added in previous round

## **Additive Training**

- How do we decide which f to add: Optimize the objective!
- The prediction at round t is  $\hat{y}_i^{(t)} = \hat{y}_i^{(t-1)} + f_t(x_i)$

This is what we need to decide in round t

$$Obj^{(t)} = \sum_{i=1}^{n} l(y_i, \hat{y}_i^{(t)}) + \sum_{i=1}^{t} \Omega(f_i)$$
  
=  $\sum_{i=1}^{n} l(y_i, \hat{y}_i^{(t-1)}) + f_t(x_i) + \Omega(f_t) + constant$ 

Goal: find  $f_t$  to minimize this

Consider square loss

$$Obj^{(t)} = \sum_{i=1}^{n} \left( y_i - (\hat{y}_i^{(t-1)} + f_t(x_i)) \right)^2 + \Omega(f_t) + const$$
  
=  $\sum_{i=1}^{n} \left[ 2(\hat{y}_i^{(t-1)} - y_i) f_t(x_i) + f_t(x_i)^2 \right] + \Omega(f_t) + const$ 

This is usually called residual from previous round

# Taylor Expansion Approximation of Loss

• Goal 
$$Obj^{(t)} = \sum_{i=1}^{n} l\left(y_i, \hat{y}_i^{(t-1)} + f_t(x_i)\right) + \Omega(f_t) + constant$$

- Take Taylor expansion of the objective
  - Recall  $f(x + \Delta x) \simeq f(x) + f'(x)\Delta x + \frac{1}{2}f''(x)\Delta x^2$
  - Define  $g_i = \partial_{\hat{y}^{(t-1)}} l(y_i, \hat{y}^{(t-1)}), \quad h_i = \partial^2_{\hat{y}^{(t-1)}} l(y_i, \hat{y}^{(t-1)})$

$$Obj^{(t)} \simeq \sum_{i=1}^{n} \left[ l(y_i, \hat{y}_i^{(t-1)}) + g_i f_t(x_i) + \frac{1}{2} h_i f_t^2(x_i) \right] + \Omega(f_t) + constant$$

In terms of square loss

$$g_i = \partial_{\hat{y}^{(t-1)}} (\hat{y}^{(t-1)} - y_i)^2 = 2(\hat{y}^{(t-1)} - y_i) \ h_i = \partial_{\hat{y}^{(t-1)}}^2 (y_i - \hat{y}^{(t-1)})^2 = 2$$



#### Our New Goal

Objective, with constants removed

$$\sum_{i=1}^{n} \left[ g_i f_t(x_i) + \frac{1}{2} h_i f_t^2(x_i) \right] + \Omega(f_t)$$

$$g_i = \partial_{\hat{y}^{(t-1)}} l(y_i, \hat{y}^{(t-1)}), \quad h_i = \partial_{\hat{y}^{(t-1)}}^2 l(y_i, \hat{y}^{(t-1)})$$

- Define the instance set in leaf j as
  - Regroup the objective by leaf

$$Obj^{(t)} \simeq \sum_{i=1}^{n} \left[ g_{i} f_{t}(x_{i}) + \frac{1}{2} h_{i} f_{t}^{2}(x_{i}) \right] + \Omega(f_{t})$$

$$= \sum_{i=1}^{n} \left[ g_{i} w_{q(x_{i})} + \frac{1}{2} h_{i} w_{q(x_{i})}^{2} \right] + \gamma T + \lambda \frac{1}{2} \sum_{j=1}^{T} w_{j}^{2}$$

$$= \sum_{j=1}^{T} \left[ \left( \sum_{i \in I_{j}} g_{i} \right) w_{j} + \frac{1}{2} \left( \sum_{i \in I_{j}} h_{i} + \lambda \right) w_{j}^{2} \right] + \gamma T$$

This is sum of T independent quadratic function

#### The Structure Score

• Two facts about single variable quadratic function

$$argmin_x Gx + \frac{1}{2}Hx^2 = -\frac{G}{H}, \ H > 0$$
  $\min_x Gx + \frac{1}{2}Hx^2 = -\frac{1}{2}\frac{G^2}{H}$ 

• Let us define  $G_j = \sum_{i \in I_j} g_i$   $H_j = \sum_{i \in I_j} h_i$ 

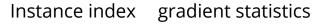
$$Obj^{(t)} = \sum_{j=1}^{T} \left[ (\sum_{i \in I_j} g_i) w_j + \frac{1}{2} (\sum_{i \in I_j} h_i + \lambda) w_j^2 \right] + \gamma T$$
  
=  $\sum_{j=1}^{T} \left[ G_j w_j + \frac{1}{2} (H_j + \lambda) w_j^2 \right] + \gamma T$ 

• Assume the structure of tree ( q(x) ) is fixed, the optimal weight in each leaf, and the resulting objective value are

$$w_j^* = -\frac{G_j}{H_j + \lambda} \qquad Obj = -\frac{1}{2} \sum_{j=1}^T \frac{G_j^2}{H_j + \lambda} + \gamma T$$

This measures how good a tree structure is!

#### The Structure Score Calculation





g1, h1



g2, h2



g3, h3

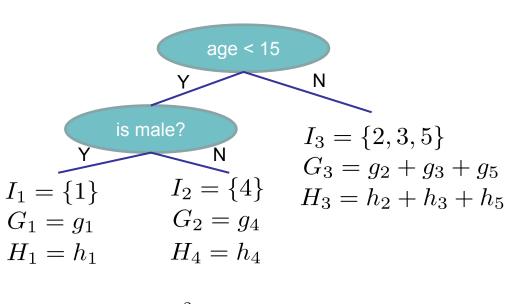


g4, h4



5

g5, h5



$$Obj = -\sum_{j} \frac{G_{j}^{2}}{H_{j} + \lambda} + 3\gamma$$

The smaller the score is, the better the structure is

## Searching Algorithm for Single Tree

- Enumerate the possible tree structures q
- Calculate the structure score for the q, using the scoring eq.

$$Obj = -\frac{1}{2} \sum_{j=1}^{T} \frac{G_j^2}{H_i + \lambda} + \gamma T$$

• Find the best tree structure, and use the optimal leaf weight

$$w_j^* = -\frac{G_j}{H_i + \lambda}$$

But... there can be infinite possible tree structures...

## Greedy Learning of the Tree

- In practice, we grow the tree greedily
  - Start from tree with depth 0
  - For each leaf node of the tree, try to add a split. The change of objective after adding the split is

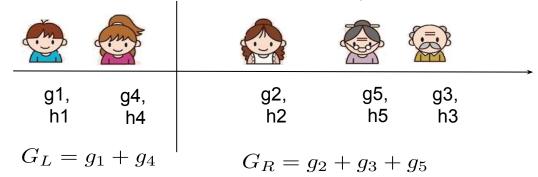
    The complexity cost by

$$Gain = \frac{G_L^2}{H_L + \lambda} + \frac{G_R^2}{H_R + \lambda} - \frac{(G_L + G_R)^2}{H_L + H_R + \lambda} - \gamma$$
 introducing additional leaf the score of left child the score of right child the score of if we do not split

Remaining question: how do we find the best split?

# Efficient Finding of the Best Split

• What is the gain of a split rule  $x_j < a$ ? Say  $x_j$  is age



- All we need is sum of g and h in each side, and calculate
- Left to right linear scan over sorted instance is enough to decide the best split along the feature

## Pruning and Regularization

Recall the gain of split, it can be negative!

$$Gain = \frac{G_L^2}{H_L + \lambda} + \frac{G_R^2}{H_R + \lambda} - \frac{(G_L + G_R)^2}{H_L + H_R + \lambda} \gamma$$

- When the training loss reduction is smaller than regularization
- Trade-off between simplicity and predictiveness
- Pre-stopping
  - Stop split if the best split have negative gain
  - But maybe a split can benefit future splits..
- Post-Prunning
  - Grow a tree to maximum depth, recursively prune all the leaf splits with negative gain

## XGBoost Model Recap

- A regularized objective for better generalization
- Additive solution for generic objective function
- Structure score to search over structures.
- Why take all the pain in deriving the algorithm
  - Know your model
  - Clear definitions in algorithm offers clear and extendible modules in software

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## What can XGBoost can do for you

- Push the limit of computation resources to solve one problem
  - Gradient tree boosting
- Automatic handle missing value
- Interactive Feature analysis
- Extendible system for more functionalities
- Deployment on the Cloud

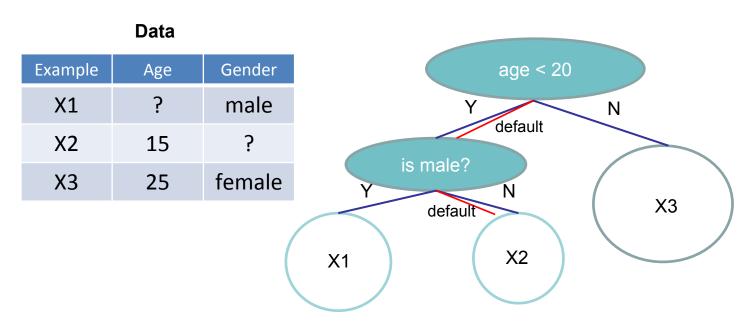
## Getting Started (python)

```
import xgboost as xgb
# read in data
dtrain = xgb.DMatrix('demo/data/agaricus.txt.train')
dtest = xgb.DMatrix('demo/data/agaricus.txt.test')
# specify parameters via map
param = {'max_depth':2, 'eta':1, 'silent':1, 'objective':'binary:logistic' }
num round = 2
bst = xgb.train(param, dtrain, num_round)
# make prediction
preds = bst.predict(dtest)
```

## Getting Started (R)

```
# Load data
data(agaricus.train, package='xgboost')
data(agaricus.test, package='xgboost')
train <- agaricus.train</pre>
test <- agaricus.test
# fit model
bst <- xgboost(data = train$data, label = train$label, max.depth = 2, eta = 1, nround = 2,</pre>
               nthread = 2, objective = "binary:logistic")
# predict
pred <- predict(bst, test$data)</pre>
```

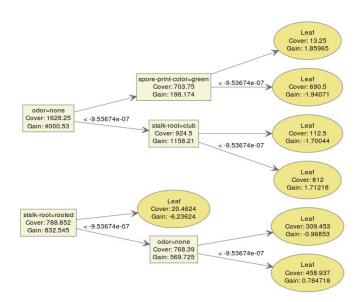
## Automatic Missing Value Handling



XGBoost learns the best direction for missing values

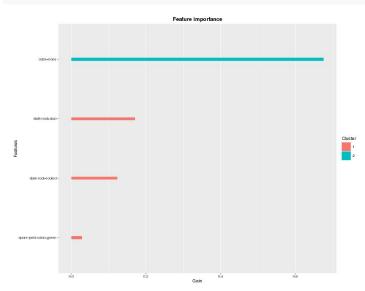
## Inspect Your Models

```
bst <- xgboost(data = train$data, label = train$label, max.depth = 2,
eta = 1, nthread = 2, nround = 2, objective = "binary:logistic")
xgb.plot.tree(feature_names = agaricus.train$data@Dimnames[[2]], model = bst)
```



## Feature Importance Analysis

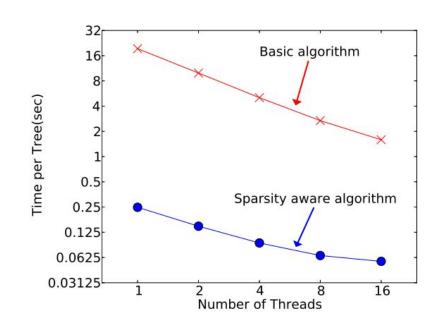
```
bst <- xgboost(data = train$data, label = train$label, max.depth = 2,
eta = 1, nthread = 2, nround = 2,objective = "binary:logistic")
importance_matrix <- xgb.importance(agaricus.train$data@Dimnames[[2]], model = bst)
xgb.plot.importance(importance_matrix)
```



## Automatic Sparse Data Optimization

- Useful for categorical encoding and other cases (e.g. Bag of words)
- User do not need to worry about large sparse matrices

Impact of sparse aware vs basic algorithm on allstate dataset



## Extendibility: Customized Objective Function

- XGBoost solves wide range of objectives
  - Binary classification
  - Ranking
  - Multi-class classification
- Customize objective function

```
loglossobj <- function(preds, dtrain) {
# dtrain is the internal format of the training data
# We extract the labels from the training data
labels <- getinfo(dtrain, "label")
# We compute the 1st and 2nd gradient, as grad and hess
preds <- 1/(1 + exp(-preds))
grad <- preds - labels
hess <- preds * (1 - preds)
# Return the result as a list
return(list(grad = grad, hess = hess))
}
model <- xgboost(data = train$data, label = train$label, nrounds = 2, objective = loglossobj, eval_metric = "error")
```

## Extendibility: Modular Library

- Plugin system
  - Enable you to plugin customized data loader, metrics, learners
  - Optionally build with some of the plugins
  - https://github.com/dmlc/xgboost/tree/master/plugin
- Modular library to for even more extensions
  - Recent pull request of supporting DART (dropout in tree boosting)
    - Reuse of all data loading and tree learning modules
    - Around 300 lines of additional code

# Extendibility on Language API: Early Stopping

```
bst <- xgb.cv(data = train$data, label = train$label, nfold = 5,
             nrounds = 20, objective = "binary:logistic",
             early.stop.round = 3, maximize = FALSE)
## [0] train-error:0.000921+0.000343 test-error:0.001228+0.000686
## [1] train-error:0.001228+0.000172 test-error:0.001228+0.000686
## [2] train-error:0.000653+0.000442 test-error:0.001075+0.000875
## [3] train-error:0.000422+0.000416
                                     test-error:0.000767+0.000940
## [4] train-error:0.000192+0.000429
                                     test-error:0.000460+0.001029
## [5] train-error:0.000192+0.000429
                                     test-error:0.000460+0.001029
## [6] train-error:0.000000+0.000000
                                     test-error:0.000000+0.000000
## [7] train-error:0.000000+0.000000
                                     test-error:0.000000+0.000000
## [8] train-error:0.000000+0.000000
                                     test-error:0.000000+0.000000
## [9] train-error:0.000000+0.000000 test-error:0.000000+0.000000
## Stopping. Best iteration: 7
```

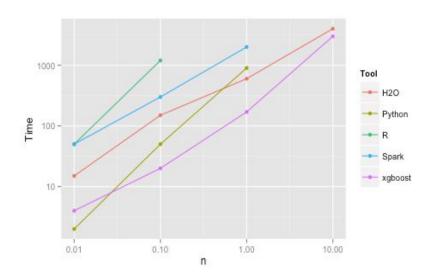
This feature is contributed by users, because they can directly hack the R/python API easily:)

Many more similar examples

## Faster Training Speed via Parallel Training

- Push limit of machine in all cases
- Low memory footprint
- Hackable native codes
  - Instead of everything in backend
  - Early-stopping
  - Checkpointing
  - Customizable objective

#### Minimum benchmark from szilard/benchm-ml



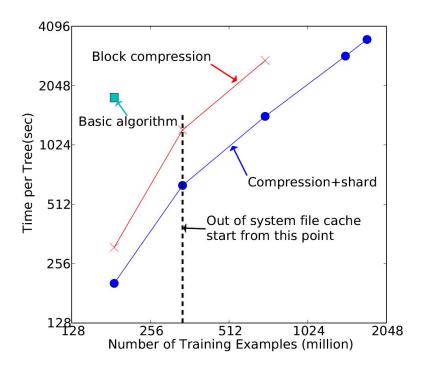
## XGBoost with Out of Core Computation

- Impact of out of core optimizations
- On a single EC2 machine with two SSD

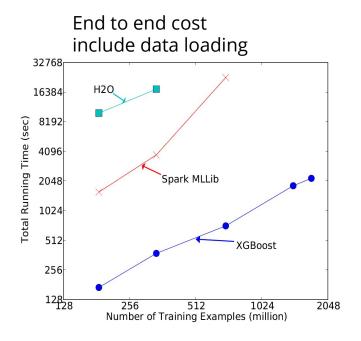


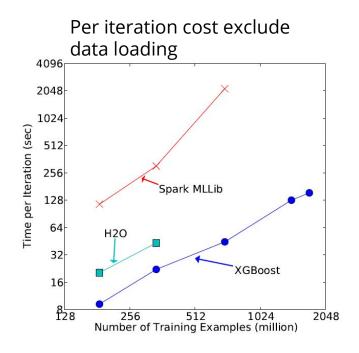






#### Distributed XGBoost vs Other Solutions





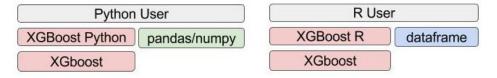
- 16 AWS m3.2xlarge machines
- Missing data points are due to out of memory

## What can XGBoost **cannot** do for you

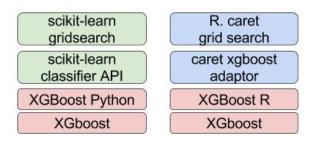
- Feature engineering
- Hyper parameter tuning
- A lot more cases ...

#### What XGBoost does instead...

- Deeply integrate with existing ecosystem
- Directly interact with native data structures



Expose native standard APIs

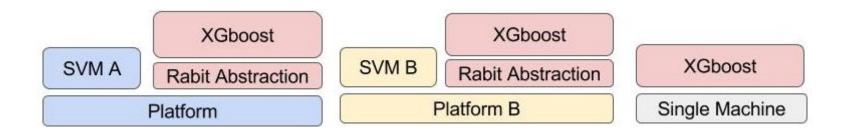


# Unix Philosophy in Machine Learning

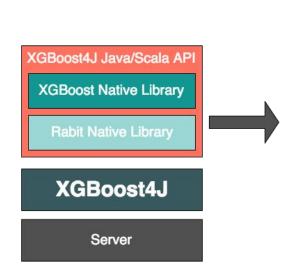
- XGBoost focuses on one thing and does its best for you.
- In order to be useful for the users, XGBoost also have to **be open and integrate well with other systems by common interface**.
- Always be modular, extendible, so we can keep up to the state of art easily.

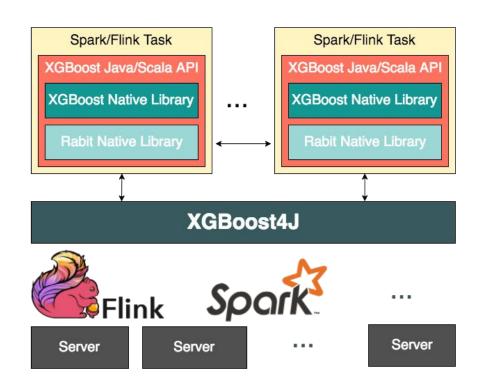
#### XGBoost on DataFlow

Unified package across language, platform and cloud service



#### XGBoost on DataFlow (cont')





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#### Industry Use cases

Used by Google, MS Azure, Tencent, Alibaba, ...

#### Quotes from some users:

- Hanjing Su from Tencent data platform team: "We use distributed XGBoost for click through prediction in wechat shopping and lookalikes. The problems involve hundreds millions of users and thousands of features. XGBoost is cleanly designed and can be easily integrated into our production environment, reducing our cost in developments."
- CNevd from autohome.com ad platform team: "Distributed XGBoost is used for click through rate prediction in our display advertising, XGBoost is highly efficient and flexible and can be easily used on our distributed platform, our ctr made a great improvement with hundred millions samples and millions features due to this awesome XGBoost"

## Machine Learning Challenge Winning Solutions

- The most frequently used tool by data science competition winners
  - 17 out of 29 winning solutions in kaggle last year used XGBoost
  - O Solve wide range of problems: store sales prediction; high energy physics event classification; web text classification; customer behavior prediction; motion detection; ad click through rate prediction; malware classification; product categorization; hazard risk prediction; massive online course dropout rate prediction
- Present and Future of KDDCup. Ron Bekkerman (KDDCup 2015 chair): "Something dramatic happened in Machine Learning over the past couple of years. It is called XGBoost a package implementing Gradient Boosted Decision Trees that works wonders in data classification. Apparently, every winning team used XGBoost, mostly in ensembles with other classifiers. Most surprisingly, the winning teams report very minor improvements that ensembles bring over a single well-configured XGBoost.."
- A lot contributions from the kaggle community

## DMLC: Distributed Machine Learning Common

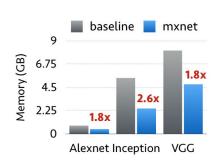
- DMLC is a group to collaborate on open-source machine learning projects, with a goal of making cutting-edge large-scale machine learning widely available. The contributors includes researchers, PhD students and data scientists who are actively working on the field.
- XGBoost for effective tree boosting
- dmlc
   mxnet for deep learning
- Support of other core system components for largescale ML

# MXNet for Deep Learning

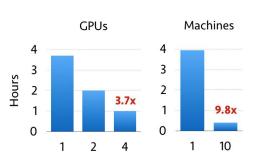
#### Portable



#### **Efficient**



#### Scalable



http://mxnet.dmlc.ml

#### Contribute to XGBoost and Other DMLC Projects

- Contribute code to improve the package
- Create tutorials on how the usecases
- Share your experience
  - Awesome XGBoost https://github.com/dmlc/xgboost/tree/master/demo

## Acknowledgement

- XGBoost Committers
  - o Tong He, Bing Xu, Michael Benesty, Yuan Tang, Scott Lundberg
- Contributors of XGBoost
- Users in the XGBoost Community

# Thank You