

$$1-1 \quad H(X) = \sum_{x \in X} -p(x) \log_2(p(x)).$$

1) 공정한 주사위.

$$6 \left(\frac{1}{6} \log_2 6 \right) = \log_2 6.$$

2) 모든 눈이 6인 주사위.

$$1 \log_2 1 = 0.$$

3) 짝수 눈의 4를 확률의 2배로 볼 수 있는 주사위.

$$(1+1+1+1) + (2+2+2+2) = 2.$$

$$a = \frac{1}{4}$$

$$3 \left(\frac{1}{4} \log_2 4 \right) + 3 \left(\frac{1}{4} \log_2 \frac{1}{2} \right)$$

$$qA = L$$

$$\frac{1}{3} \log_2 4 + \frac{1}{3} (\log_2 4 - \log_2 2) = \log_2 4 - \frac{1}{3}$$

4) 1이 4를 확률의 0.5, 나머지 눈의 4를 확률의 각각 0.1.

$$\frac{1}{2} \log_2 (2) + 5 \left(\frac{1}{6} \log_2 6 \right) = \frac{1}{2} + \frac{1}{2} \log_2 10 = \log_2 \sqrt{10}$$

$$\frac{1}{2} (1 + \log_2 10)$$

$$\log_2 \sqrt{10}$$

1-2

$$H(X) = \sum_{x \in X} -p(x) \log_2(p(x)).$$

1) $0 \leq H(X)$ 증명

$$H(X) = \sum_{x \in X} -p(x) \log_2(p(x)).$$

양수

음수 ($\because \log_2(0.1)$ 음수)

$$2) H(X) \leq \log_2 |X|$$

현재 엔트로피는 균등분포에서 발생한다.

$$H(X) = -\sum_{i=1}^n \frac{1}{n} \log_2 \frac{1}{n} = -n \cdot \frac{1}{n} \log_2 \frac{1}{n} = \log_2 n$$

$$H(X) \leq \log_2 |X|$$

압은 1인

1-3

$$H(X) = \sum_{x \in X} P(x) \log_2 \left(\frac{1}{P(x)} \right).$$

1)				$Y=0$	$Y=1$	
$X=0$	0.6	$H(X) = \frac{6}{10} \log_2 \frac{10}{6} + \frac{4}{10} \log_2 \frac{10}{4}$		0.55	0.45	$H(Y) = \frac{55}{100} \log_2 \frac{100}{55} + \frac{45}{100} \log_2 \frac{100}{45}$
$X=1$	0.4	$= 0.99297 \text{ bits}$				$= 0.99297 \text{ bits}$

2) $H(X, Y)$

$$\frac{55}{100} \log_2 \frac{100}{55} + \frac{45}{100} \log_2 \frac{100}{45} + \frac{1}{10} \log_2 10 + \frac{3}{10} \log_2 \frac{10}{3} = 1.78223 \text{ bits}.$$

3) $H(X|Y)$

$$H(X|Y) = H(X, Y) - H(Y) = 1.78223 - 0.99297 = 0.78926 \text{ bits}.$$

4) $I(X; Y)$

$$H(X) - H(X|Y) = 0.99095 - 0.78926 = 0.20169 \text{ bits}.$$

5)

$I(X; Y) = H(X) - H(X|Y)$ 라, Y (결과 예측)를 알았을 때 X (시험 발생 여부)에 대한 불확실성이 얼마나 줄었는지를 나타낸다.

$I(X; Y) = 0 \rightarrow Y$ 를 알았도 X 에 대한 불확실성이 줄어들지 않는다.

$I(X; Y) = H(X) \rightarrow Y$ 를 알면 X 는 무관하다.

2-1

$$A = \begin{bmatrix} 2 & 0 & 0 \\ 1 & 2 & 1 \\ -1 & 0 & 1 \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} 2-\lambda & 0 & 0 \\ 1 & 2-\lambda & 1 \\ -1 & 0 & 1-\lambda \end{bmatrix} \quad \det(A - \lambda I) = (2-\lambda)^2(1-\lambda) \quad \lambda = 2, 1$$

① $\lambda = 2$ 인 경우

$$(A - 2I)\vec{v} = 0 \Rightarrow \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 1 \\ -1 & 0 & -1 \end{bmatrix} \vec{v} = 0 \quad \vec{v}_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \quad \vec{v}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

② $\lambda = 1$ 인 경우

$$(A - I)\vec{v} = 0 \Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ -1 & 0 & 0 \end{bmatrix} \vec{v} = 0 \quad \vec{v}_3 = \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$$

$$P = \begin{bmatrix} -1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & -1 \end{bmatrix}, \quad D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

2-3)

$$B = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad B = U \Sigma V^T$$

U : BB^T 의 고유벡터들로 구성된 2×2 직교행렬.

Σ : 특이값을 대각 원자로 하는 2×3 행렬.

V : B^TB 의 고유벡터들로 구성된 3×3 직교행렬

$$B^TB = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{특성방정식: } \det(B^TB - \lambda I) = 0$$

$$\lambda_1 = 2, \lambda_2 = 0, \lambda_3 = 1$$

$$v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, v_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, v_3 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Sigma = \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$U = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$V = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

3-1

$$J(w) = \sum_{i=1}^n \left[-y^{(i)} \log \hat{y}^{(i)} - (1 - y^{(i)}) \log (1 - \hat{y}^{(i)}) \right]$$

$$\hat{y}^{(i)} = \sigma(w^T x^{(i)}) = \frac{1}{1 + e^{-w^T x^{(i)}}} \text{ 가 } w \text{의 } \hat{y}^{(i)} \text{ convex임을 보이자.}$$

$$\hat{y}^{(i)} = \sigma(w^T x^{(i)})$$

$$J(z) = \frac{1}{1 + e^{-z}} \Rightarrow J'(z) = \frac{1}{(1 + e^{-z})^2}$$

$$L(w) = -y \log(\hat{y}) - (1-y) \log(1-\hat{y}) \Rightarrow L(w) = L(w^T x)$$

$$\nabla_w L(w) = (\hat{y} - y) x$$

$$\nabla_w^T L(w) = (\hat{y} - y) \cdot x x^T \geq 0 \Rightarrow \text{convexity}$$

3-2

$$f(x) = x^4 - 2x^3 - 3x^2 + x$$

$$x_0 = 1, \quad \gamma = 0.2$$

$$x_{t+1} = x_t - \gamma \nabla f(x_t)$$

$$f'(x) = 4x^3 - 6x^2 - 6x + 1$$

$$x_1 = x_0 - \gamma f'(x_0) \text{ where } x_0 = 1.$$

$$f'(1) = 4 - 6 - 6 + 1 = -7 \Rightarrow x_1 = 2.4$$

$$f'(2.4) = 4(2.4)^3 - 6(2.4)^2 - 6(2.4) + 1 = -7.336$$

$$x_2 = 2.4 - 0.2 \cdot 7.336 = \boxed{0.9328}$$

3-3

$$\min f(x, y) = x^2 + y^2 \quad \text{s.t. } xy = 2.$$

Step 1. 라그랑주 함수 설정

$$L(x, y, \lambda) = f(x, y) + \lambda \cdot g(x, y) = x^2 + y^2 + \lambda (xy - 2)$$

Step 2. 이 함수의 Stationary point 찾기.

$$\begin{aligned} \frac{\partial L}{\partial x} = 2x + \lambda &= 0 \rightarrow \lambda = -2x \\ \frac{\partial L}{\partial y} = 2y + \lambda &= 0 \rightarrow \lambda = -2y \\ \frac{\partial L}{\partial \lambda} = x + y - 2 &= 0 \end{aligned} \quad \left. \begin{array}{l} \lambda = -2x \\ \lambda = -2y \end{array} \right\} \rightarrow x = y$$

$$\rightarrow x = y = 1.$$

$$f(x, y) = x^2 + y^2 = 1^2 + 1^2 = 2.$$

$$\text{Stationary point } (x, y, \lambda) = (1, 1, 2)$$

최소값: 2.