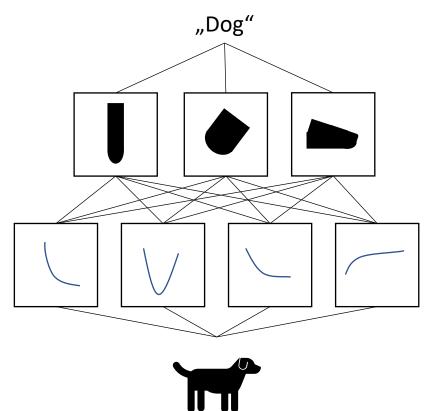
#### Introduction

- Type of deep learning network
- Most commonly applied for computer vision
- CNNs learn local patterns
- Local patterns translational invariant
- Layers learn different hierarchical patterns (from simple to complex)

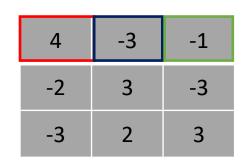




Convolution

| 0 | 1 | 0 | 1 | 1 |
|---|---|---|---|---|
| 0 | 0 | 1 | 1 | 0 |
| 1 | 1 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 1 |
| 0 | 0 | 1 | 1 | 0 |

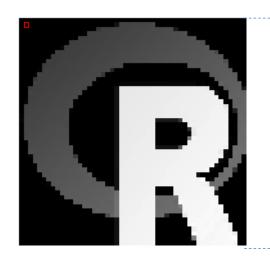
|   | 0 | 1  | 0 |
|---|---|----|---|
| X | 1 | -4 | 1 |
|   | 0 | 1  | 0 |



Input Image Matrix

Convolutional Filter (Edge Detector)

Convolution - Example



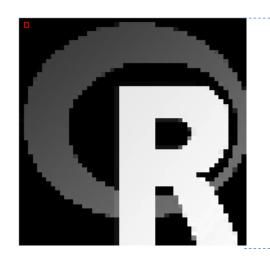
| 0 | 1  | 0 |
|---|----|---|
| 1 | -4 | 1 |
| 0 | 1  | 0 |



Input Image

**Edge Detector** 

Convolution - Example



| 1/9 | 1/9 | 1/9 |
|-----|-----|-----|
| 1/9 | 1/9 | 1/9 |
| 1/9 | 1/9 | 1/9 |



Input Image

Blur Filter

Convolution - Stride

- Stride equals step size
- Example: Stride = 2

| 0 | 1 | 0 | 1 | 1 |
|---|---|---|---|---|
| 0 | 0 | 1 | 1 | 0 |
| 1 | 1 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 1 |
| 0 | 0 | 1 | 1 | 0 |

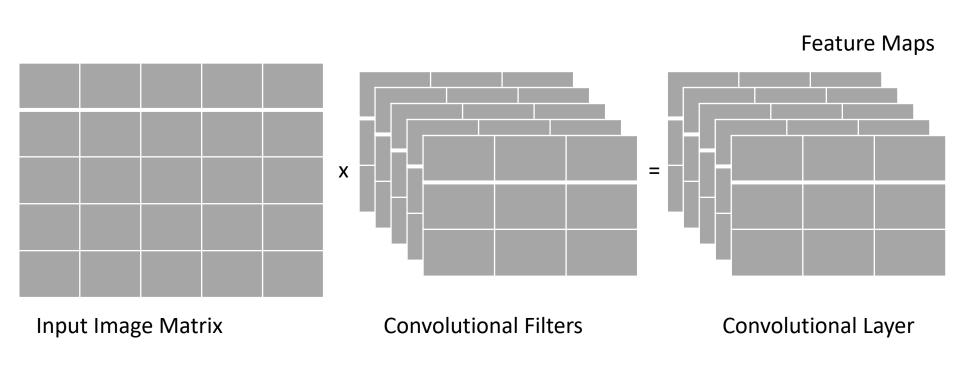
|   | 0 | 1  | 0 |
|---|---|----|---|
| ( | 1 | -4 | 1 |
|   | 0 | 1  | 0 |

| 4  | -1 |
|----|----|
| -3 | 3  |

Input Image Matrix

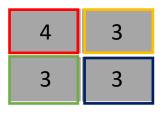
Convolutional Filter (Edge Detector)

Convolutional Layer



Max Pooling

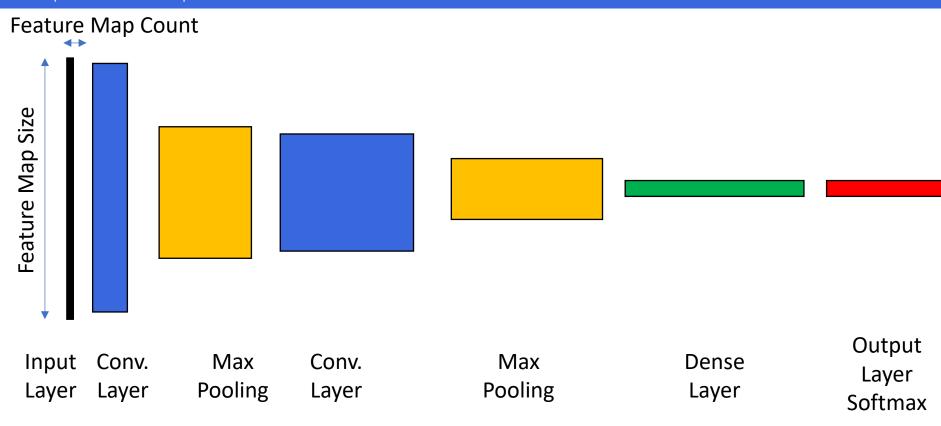
| 4  | -3 | -1 |
|----|----|----|
| -2 | 3  | -3 |
| -3 | 2  | 3  |



Feature Map

Max Pooling

Example Network Setup



#### **Example Network Setup**

- Count of feature maps increase with layers from (from 32 to 64)
- Size of feature maps decreases (from 148x148 to 16x16)
- Very typical for CNNs

| Layer (type)  | Output | Shape         | Param # |
|---|--------|---------------|---------|
| conv2d_19 (Conv2D)  | (None, | 148, 148, 32) | 320     |
| max_pooling2d_16 (MaxPooling2   | (None, | 74, 74, 32)   | 0       |
| conv2d_20 (Conv2D)  | (None, | 72, 72, 32)   | 9248    |
| max_pooling2d_17 (MaxPooling2   | (None, | 36, 36, 32)   | 0       |
| conv2d_21 (Conv2D)  | (None, | 34, 34, 64)   | 18496   |
| conv2d_22 (Conv2D)  | (None, | 32, 32, 64)   | 36928   |
| max_pooling2d_18 (MaxPooling2   | (None, | 16, 16, 64)   | 0       |
| dropout_17 (Dropout)  | (None, | 16, 16, 64)   | 0       |
| flatten_7 (Flatten)   | (None, | 16384)        | 0       |
| dense_13 (Dense)  | (None, | 512)          | 8389120 |
| dropout_18 (Dropout)  | (None, | 512)          | 0       |
| dense_14 (Dense)  | (None, | 10)           | 5130    |
| Total params: 8,459,242 Trainable params: 8,459,242 Non-trainable params: 0 |        |               |         |

Advantages / Disadvantages



- Most powerful technique for computer vision tasks
- Achieves high quality predictions

- Many parameters
- Requires a lot of experience
- Very computationally expensive