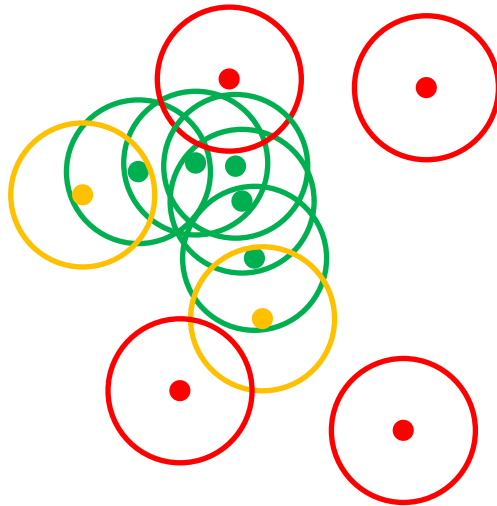


Dbscan 101

Dbscan

Introduction

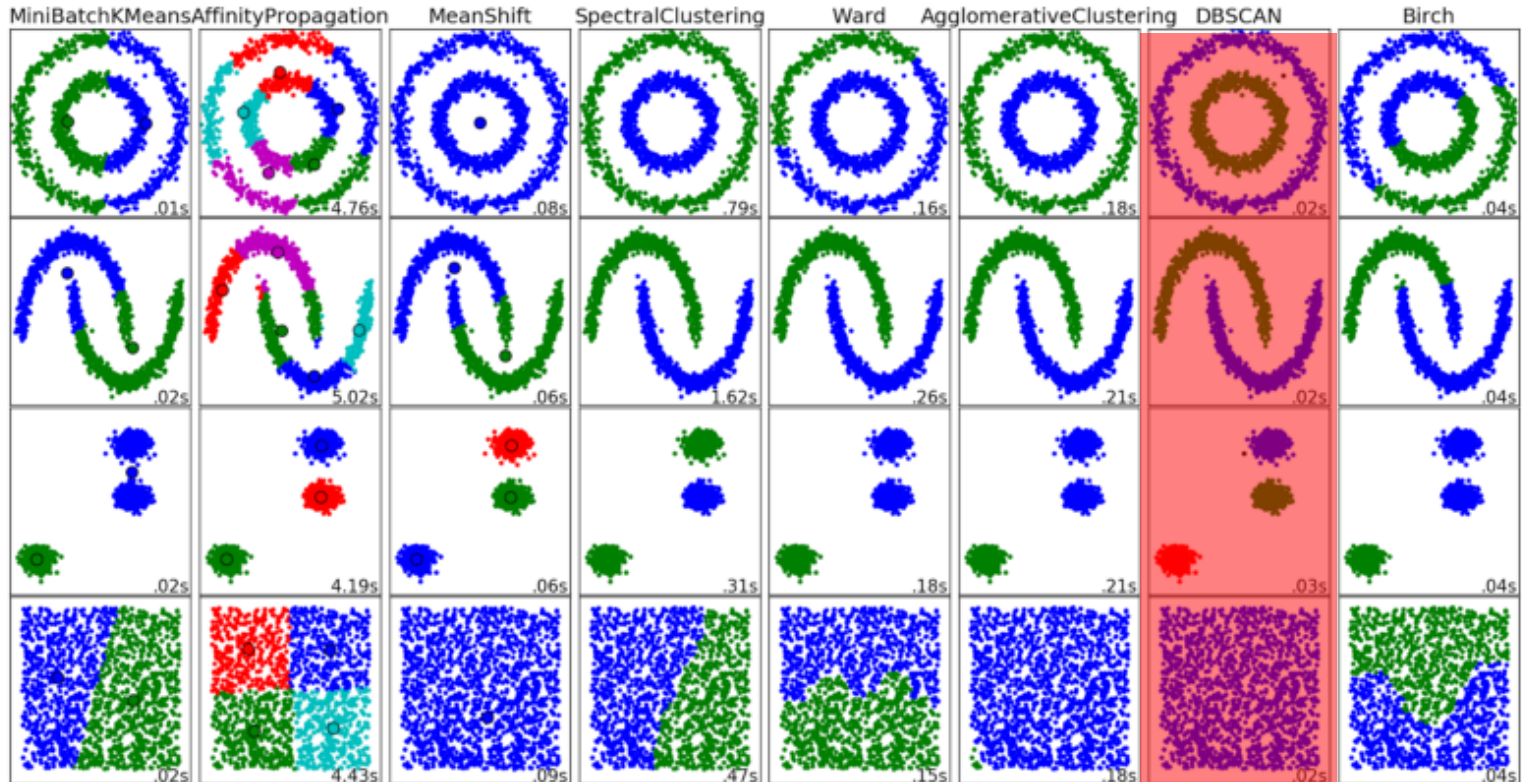
- **Density based Spatial Clustering of Applications with Noise**
 - identifies points in crowded regions
 - Core points
 - Reachable points
 - Non-reachable points
-
- Two parameters
 - min points
 - epsilon



Example:
minPoints=3
eps defines radius

Dbscan

Example

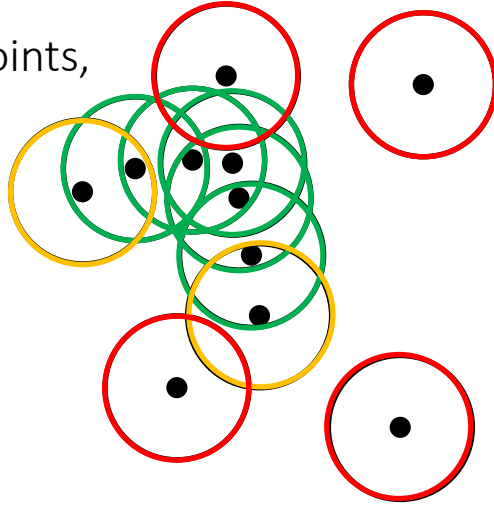


Source: <https://towardsdatascience.com/how-dbscan-works-and-why-should-i-use-it-443b4a191c80>

Dbscan

Principle

1. Draw Circles of given eps-radius
2. If Circle contains $\geq \text{minPoints}$
→ core point
3. If Circle contains $< \text{minPoints}$,
but still reachable
→ Reachable point
4. Non-reachable points
→ Outliers or part of
other clusters



Example:
 $\text{minPoints}=3$
eps defines radius

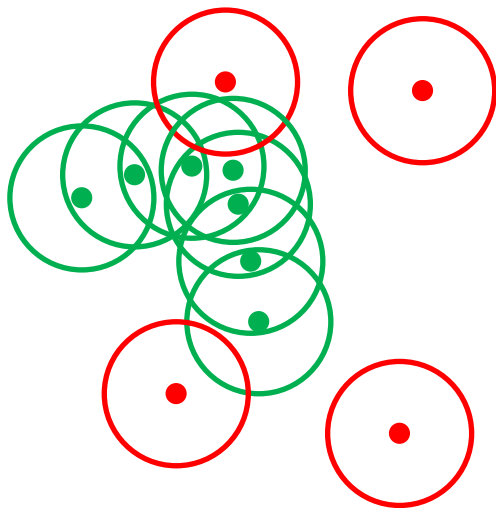
Dbscan

Parameter Impact: epsilon increased

Baseline:

minPoints=2

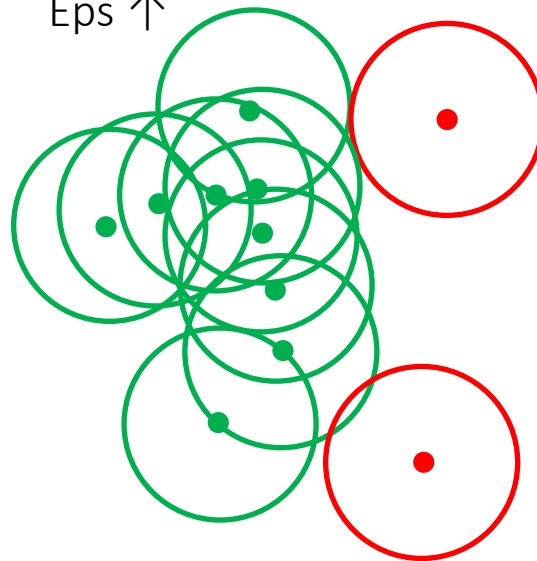
Eps defines radius



Parameter Study:

minPoints=2

Eps ↑



More Points are added to cluster

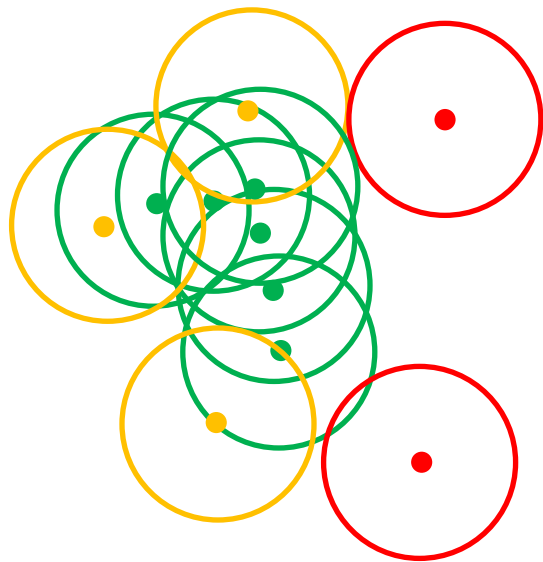
Dbscan

Parameter Impact: minPoints increased

Baseline:

minPoints = 3

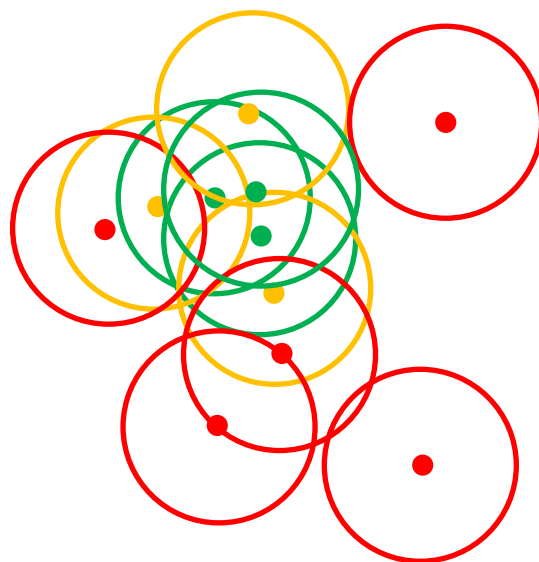
Eps defines radius



Parameter Study:

minPoints = 4

Eps constant



Cluster size decreases

Dbscan

Advantages / Disadvantages



- No pre-knowledge or assumption on cluster number
- Can detect complex shapes
- Applicable for outlier detection



- Border points can be part of either one (not completely deterministic)
- Quality relies on distance measure