0.1 Prove that a n point Gauss-quadrature is exact for a polynomial up to order (2n-1)

Quadrature Exactness for polynomial of order n-1:

The integration of the form

$$I(f) = \int_{a}^{b} \omega(x)f(x)dx \tag{1}$$

is exact when

$$I(f) \approx Q(f) = \sum_{i=1}^{n} w(x_i) f(x_i). \tag{2}$$

A function approximated by the n point Lagrange interpolant can be represented as a (n-1)th order polynomial

$$f(x) \approx \sum_{i=1}^{n} f(x_i) \prod_{j=1, j \neq i}^{n} \frac{x - x_j}{x_i - x_j}$$

$$\tag{3}$$

Substituting into

$$I(f) = \int \omega(x) f(x) dx$$

$$\approx \int \omega(x) \sum_{i=1}^{n} f(x_i) \prod_{j=1, j \neq i}^{n} \frac{x - x_j}{x_i - x_j} dx$$

$$= \sum_{i=1}^{n} \left(\int \omega(x) \prod_{j=1, j \neq i}^{n} \frac{x - x_j}{x_i - x_j} dx \right) f(x_i)$$

$$= \sum_{i=1}^{n} w(x_i) f(x_i),$$
(4)

and don't forget w is not a continuous function of the domain x, instead only has discrete values as a function of x_i . Therefore this shows that the *quadrature is exact when the function* f *is a polynomial* of order (n-1).

Orthogonality:

Let p_i 's be orthogonal polynomials of maximum order n over [ab] such that

$$\int_{a}^{b} \omega(x) p_{i}(x) p_{j}(x) dx = c\delta_{ij}, \tag{5}$$

where c is a constant factor. Any polynomial $h_k(x)$ with order $k \leq (n-1)$ is a linear combination of p_k 's such that

$$\int_{a}^{b} \omega(x)h_{k}(x)p_{n}(x)dx = 0 \text{ for all } k = 0, 1, \dots, n - 1,$$
(6)

shows the terms in h_k are all orthogonal to p_n .

Quadrature Exactness for Orthogonality:

The orthogonality integration (??) is "exact" if it is done over the roots of $p_n(x)$,

$$\sum_{i=1}^{n} \omega(x_i) h_k(x_i) p_n(x_i) = \int_a^b \omega(x) h_k(x) p_n(x) dx = 0.$$
 (7)

Proof:

Using the two exactness conditions ((??) and (??)) and the orthogonal polynomials, we will prove that

 $I(f) \approx Q(f)$ for f of order 2n-1. The quotient form of polynomial $f(x) = p_n(x)q(x) + r(x)$, where q and r are both order $\leq n-1$,

$$I(f) = \int_{a}^{b} \omega f dx$$

$$= \int_{a}^{b} \omega q p_{n} dx + \int_{a}^{b} \omega r dx \quad \text{(quotient form)}$$

$$= 0 + \int_{a}^{b} \omega r dx \quad \text{(orthogonality)}$$

$$\approx \sum_{i} w(x_{i})q(x_{i})p_{n}(x_{i}) + \sum_{i} w(x_{i})r(x_{i}) \quad \text{(exactness (??) + (??))}$$

$$= \sum_{i} w(x_{i})f(x_{i}) = Q(f).$$
(8)

Concluding Remarks:

- The quadrature exactness can go up to order 2n-1 for f, and the weights are on the roots of orthogonal polynomials.
- If $\omega(x) = 1$ (associated with the Legendre orthogonal polynomials), then $I(f) = \int f dx$ is the regular integration for f.

Proof of Regression using orthonormal basis no better then arbitrary independent basis Suppose f_1 , f_2 are ON polynomial basis w.r.t. the operator \ll and $h_2 = c_1 f_1 + c_2 f_2$ is a polynomial of order 2. Notice that f_1 and h_2 are independent and could become a basis of $P_2(R)$.

We can approximate the true sample y by least squares using both basis

$$y \approx g = a_1 f_1 + a_2 f_2 h = b_1 f_1 + b_2 h_2.$$
 (9)

Our goal is to see if h induces more error while approximating y by non-ON basis. From least squares $b = (A^T A)^{-1} A^T f$. To obtain the inverse of

$$A^{T}A = \begin{pmatrix} \langle f_1, f_1 \rangle & \langle f_1, h_2 \rangle \\ \langle h_2, f_1 \rangle & \langle h_2, h_2 \rangle \end{pmatrix}, \tag{10}$$

we apply Gauss-Jordan elimination

$$\begin{pmatrix}
\langle f_1, f_1 \rangle & \langle f_1, h_2 \rangle & 1 & 0 \\
\langle h_2, f_1 \rangle & \langle h_2, h_2 \rangle & 0 & 1
\end{pmatrix}$$

$$\sim \begin{pmatrix}
\langle f_1^2 \rangle & \langle f_1, h_2 \rangle & 1 & 0 \\
0 & \frac{\langle h_2^2 \rangle \langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2}{\langle f_1^2 \rangle} & \frac{-\langle h_2, f_1 \rangle}{\langle f_1^2 \rangle} & 1
\end{pmatrix}$$

$$\sim \begin{pmatrix}
\langle f_1^2 \rangle & 0 & \frac{\langle h_2^2 \rangle \langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2}{\langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{-\langle f_1^2 \rangle \langle f_1, h_2 \rangle}{\langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & \frac{\langle h_2^2 \rangle \langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2}{\langle f_1^2 \rangle} & \frac{-\langle h_2, f_1 \rangle}{\langle f_1^2 \rangle} & 1
\end{pmatrix}$$

$$\sim \begin{pmatrix}
1 & 0 & \frac{\langle h_2^2 \rangle}{\langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{-\langle f_1, h_2 \rangle}{\langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{-\langle h_2, f_1 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{\langle f_1^2 \rangle}{\langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{-\langle h_2, f_1 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{\langle f_1^2 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{-\langle h_2, f_1 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{\langle f_1^2 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{-\langle h_2, f_1 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{\langle f_1^2 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{-\langle h_2, f_1 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{\langle f_1^2 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{-\langle h_2, f_1 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{\langle f_1^2 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{-\langle h_2, f_1 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{\langle f_1^2 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{-\langle h_2, f_1 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{\langle f_1^2 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{-\langle h_2, f_1 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{\langle h_2^2 \rangle}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{\langle h_2^2 \rangle \langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{\langle h_2^2 \rangle \langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{\langle h_2^2 \rangle \langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} & \frac{\langle h_2^2 \rangle \langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{\langle h_2^2 \rangle \langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{\langle h_2^2 \rangle \langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{\langle h_2^2 \rangle \langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2}{\langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\
0 & 1 & \frac{\langle h_2^2 \rangle \langle f_1^2 \rangle - \langle f_1, h_2 \rangle^2}{\langle h_2^2 \rangle - \langle f_1, h_2$$

Therefore

$$\begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = \begin{pmatrix} \frac{\langle h_2^2 \rangle \langle f_1, f \rangle - \langle f_1, h_2 \rangle \langle h_2, f \rangle}{\langle f_1^2 \rangle \langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \\ \frac{-\langle h_2, f_1 \rangle \langle f_1, f \rangle + \langle f_1^2 \rangle \langle h_2, f \rangle}{\langle f_1^2 \rangle \langle h_2^2 \rangle - \langle f_1, h_2 \rangle^2} \end{pmatrix} = \begin{pmatrix} \langle f_1, f \rangle - \frac{c_1}{c_2} \langle f_2, f \rangle \\ \frac{\langle f_2, f \rangle}{c_2} \end{pmatrix}.$$
(12)

This shows that b_1 has some projection coming from f_2 . Substituting this into the equation gives h = g.