

Biological Vision and Applications

Module 05-05: Context-based model

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Context-based Model

A comprehensive model for top-down + bottom-up attention

- We have seen the equation earlier
 - ▶ $P(O \mid v_l, v_c) = \frac{1}{P(v_l \mid v_c)} \cdot P(v_l \mid O, v_c) \cdot P(O \mid v_c)$
- $P(v_l \mid v_c)$:
 - ▶ Independent of object hypothesis O
 - ▶ Represents probability of the observed feature v_l in context v_c
 - ▶ It's inverse represents bottom-up saliency
 - ▶ Information-theoretic / Bayesian models ... bring in experiential factor

Top-down saliency

- We shall now contrate on the numerator:
 - ▶ $N = P(v_I | O, v_c).P(O | v_c)$
- $O = (o, x, \sigma)$ (class, location, appearance)
 - ▶ $P(O | v_c) = P(\sigma | x, o, v_c).P(x | o, v_c).P(o | v_c)$
- $N = P(v_I | O, v_c).P(\sigma | x, o, v_c).\underline{P(x | o, v_c).P(o | v_c)}$
 - ▶ $P(o | v_c)$: Prob of an object class to appear in a context
 - ▶ $P(x | o, v_c)$: Prob of an object class to appear at a certain location in a context
 - ▶ ... given that it appears
- $P(x | o, v_c).P(o | v_c) = P(o, x | v_c)$:
 - ▶ Represents the task-specific context-driven saliency of location

Appearance model

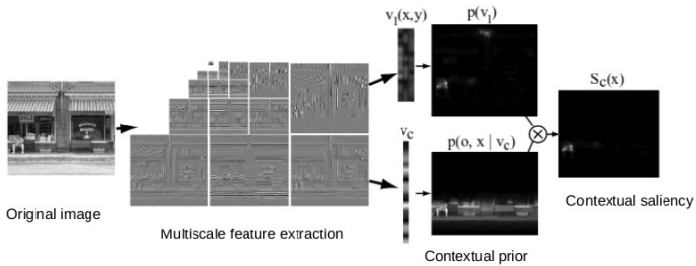
- We are left with the terms: $P(v_I | O, v_c).P(\sigma | x, o, v_c)$
 - ▶ $P(\sigma | x, o, v_c)$: Scale and appearance of the object at a certain location
 - ▶ ... given that it appears at a certain location
 - ▶ $P(v_I | O, v_c) = P(v_I | O) = P(v_I | o, x, \sigma)$: The expected visual features
 - ▶ ... given that the object appears at a certain location with a certain appearance

In Summary

- $P(O | v) = P(O | v_l, v_c) = \frac{1}{P(v_l | v_c)} \cdot P(v_l | O, v_c) \cdot P(O | v_c)$
- Substituting (o, x, σ) for O
 - ▶ $P(O | v) = \frac{1}{P(v_l | v_c)} \cdot \frac{P(v_l | O, v_c) \cdot P(\sigma | x, o, v_c)}{P(v_l | o, x, \sigma)} \cdot \frac{P(x | o, v_c) \cdot P(o | v_c)}{P(o | v_c)}$
- Bottom-up saliency (s_b): $\frac{1}{P(v_l | v_c)}$
- Top-down saliency (s_t): $P(o, x | v_c) = P(x | o, v_c) \cdot P(o | v_c)$
- Appearance model (a): $P(\sigma | x, o, v_c) \cdot P(v_l | o, x, \sigma)$
- Overall saliency (where): $s_b \times s_t$
- Feature to look for (what): a

Local Computations

Image conspicuity



Global Computations

Quiz 05-05

End of Module 05-05