

# Biological Vision and Applications

## Module 03-04: Bayesian Networks

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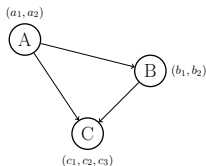


# Bayesian reasoning revisited

- Bayesian framework of reasoning
  - ▶ Create a system model in terms of  $n$  stochastic (random) variables
    - ▶  $\mathcal{X} = \{X_1, X_2, X_3, \dots, X_n\}$
    - ▶ A variable  $X_i$  can have  $k_i$  states.  $X_i : \{x_i^1, x_i^2, \dots, x_i^{k_i}\}$
  - ▶ Some variables are observable, some are hidden (to be inferred)
  - ▶ Inference is a result of probability updates based on the observed data
- The joint probability distribution table will contain  $\prod_i k_i - 1$  **independent** entries
- A trivial system with 10 binary variables will have  $2^{10} - 1 = 1023$  entries
  - ▶ That is a big number !

# Joint probability and conditional probability

| Joint probabilities |                    | Conditional probabilities |                     |
|---------------------|--------------------|---------------------------|---------------------|
| $P(a_1, b_1, c_1)$  | $P(a_2, b_1, c_1)$ | $P(a_1)$                  |                     |
| $P(a_1, b_1, c_2)$  | $P(a_2, b_1, c_2)$ | $P(b_1   a_1)$            | $P(b_1   a_2)$      |
| $P(a_1, b_1, c_3)$  | $P(a_2, b_1, c_3)$ | $P(c_1   a_1, b_1)$       | $P(c_1   a_2, b_1)$ |
| $P(a_1, b_2, c_1)$  | $P(a_2, b_2, c_1)$ | $P(c_1   a_1, b_2)$       | $P(c_1   a_2, b_2)$ |
| $P(a_1, b_2, c_2)$  | $P(a_2, b_2, c_2)$ | $P(c_2   a_1, b_1)$       | $P(c_2   a_2, b_1)$ |
| $P(a_1, b_2, c_3)$  | $P(a_2, b_2, c_3)$ | $P(c_2   a_1, b_2)$       | $P(c_2   a_2, b_2)$ |



*Non-circular dependency between variables assumed*

- Consider three variables
  - ▶ A:  $\{a_1, a_2\}$ , B:  $\{b_1, b_2\}$ , C:  $\{c_1, c_2, c_3\}$
- Joint probability table will have 11 independent entries
- Equivalently, they can be expressed with 11 conditional probabilities
- The joint probabilities can be computed from the conditional probabilities, e.g.

$$\begin{aligned} P(a_1, b_1, c_1) &= P(a_1, b_1).P(c_1 | a_1, b_1) \\ &= P(a_1).P(b_1 | a_1).P(c_1 | a_1, b_1) \end{aligned}$$

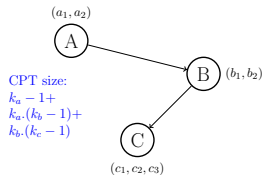
# Conditional Independence

Variables  $A$  and  $B$  are conditionally independent of each other, iff  $P(A.B) = P(A).P(B)$

Variables  $A$  and  $B$  are conditionally independent of each other given  $C$ , iff  $P(A.B | C) = P(A | C).P(B | C)$

Conditional probabilities

|                |                |
|----------------|----------------|
| $P(a_1)$       |                |
| $P(b_1   a_1)$ | $P(b_1   a_2)$ |
| $P(c_1   b_1)$ | $P(c_1   b_2)$ |
| $P(c_2   b_1)$ | $P(c_2   b_2)$ |



*This topology assumes  $A$  and  $C$  are conditionally independent, given  $B$*

- Many of the variables in real world are conditionally independent of each other given the state of some other variables 😊, e.g.,
  - ▶ Color of a fruit and its shape, given the fruit
  - ▶ ...
- Conditional independence simplifies probability computations
  - ▶ Another reason to work with conditional probabilities

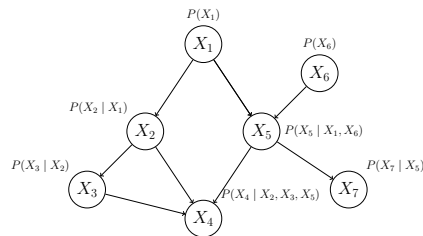
# Probabilistic Graphical Models

- Graphical models exploit conditional independence
- The variables are depicted as nodes in the graph
- Only the variables that are **not** conditionally independent are connected with edges
- Generally a graph is sparse
  - ▶ Size of the CPT is much smaller than exhaustive joint distribution table
- There are many probabilistic graphical models
  - ▶ Markov Field, Hidden Markov Model, [Bayesian Network](#), ...

See Koller. [Probabilistic Graphical Models \(book\)](#) / [Couseru course](#)

# Bayesian Networks (BN)

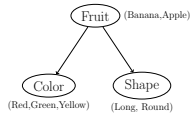
Models a probabilistic reasoning problem with cause-effect relationship



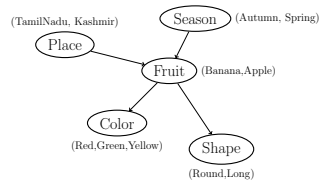
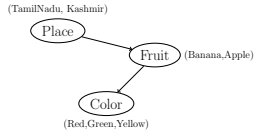
CPT Size:  
 $k_1 - 1 +$   
 $k_1 \cdot (k_2 - 1) +$   
 $k_2 \cdot (k_3 - 1) +$   
 $k_2 k_3 k_5 \cdot (k_4 - 1) +$   
...

- A Directed Acyclic Graph (DAG)
- Nodes represent events in a system
  - ▶  $X_i = (x_i^1, x_i^2, \dots, x_i^{k_i})$
  - ▶ Some nodes are observable
  - ▶ Others need to be inferred
- Edges represent **causal** relations between the events
- Conditional probabilities  $P(X_i | \text{Pa}(X_i))$  are associated with every node
  - ▶ where  $\text{Pa}(X_i)$  represents the parent set of node  $X_i$

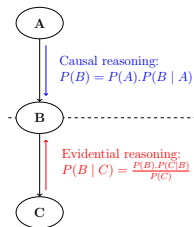
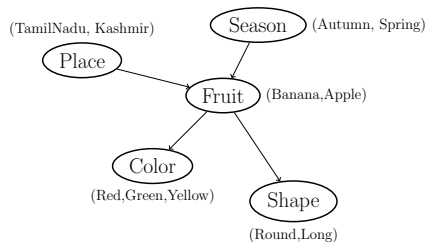
# Examples of BN



- Naïve Bayesian Network



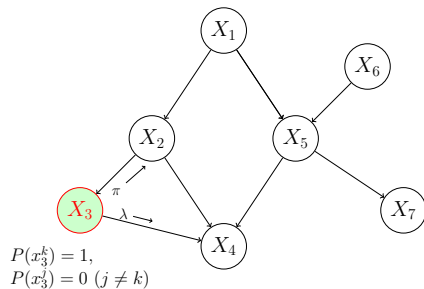
# Causal inference and Evidential inference



- Fruit is inferred from
  - ▶ Causal reasoning: Where you are, what is the season (contextual cues)
  - ▶ Evidential reasoning: It's color and shape (visual cues)
- Bayesian network supports both types of reasoning



# Inferencing with Bayesian Networks

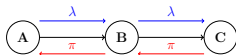


- Hand compute probabilities
  - ▶ There can be multiple (undirected) paths between a pair of nodes
  - ▶ Extremely complex
- Pearl's belief propagation algorithm
  - ▶  $\pi$  and  $\lambda$  messages
    - ▶ Probabilities of neighboring nodes updated
  - ▶ Traverses recursively in the network
    - ▶ Till no more nodes left / blocked

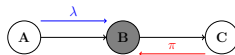
Pearl's algorithm

# Network topology and Belief propagation

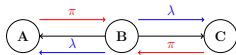
## D-Separation



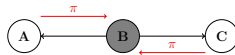
A causes B, B causes C, State of B is unknown  
Belief flows between A and C



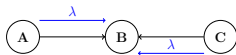
A causes B, B causes C, State of B is known  
The path between A and C is blocked by B



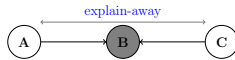
B is the cause of A and C, state of B is unknown  
Belief flows between A and C



A and C are causes of B, state of B is known  
The path between A and C is blocked by B



A and C are causes of B, state of B is unknown  
A and C are conditionally independent

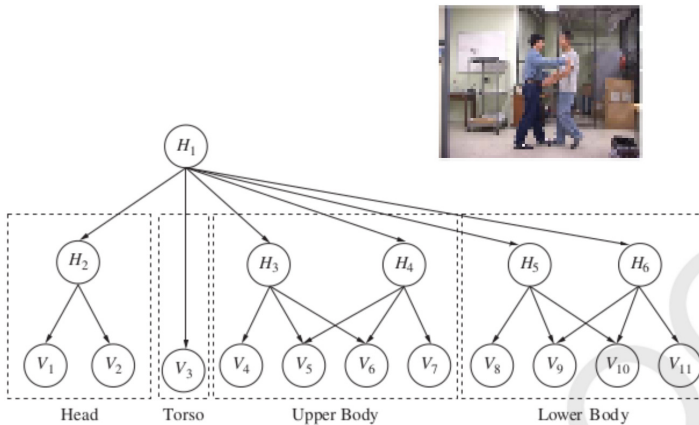


A and C are causes of B, state of B is known  
A explains away C, and vice-versa

- Belief flows between two nodes in a network if there is an unblocked path between them
- If there are no unblocked path between two nodes, they are said to be d-separated

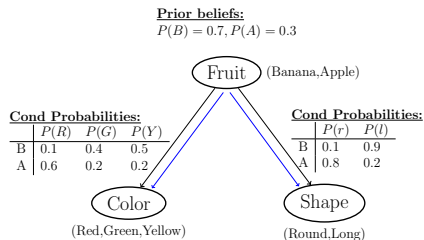
# Hierarchical organization in Bayesian Network

## Example



# Simple Bayesian Network Example

Prior beliefs, Conditional probabilities and likelihoods



- We need to evaluate the two hypotheses
  - ▶ Fruit is either Banana or Apple
- From the given data, we can find the marginal probabilities (likelihoods)

Colors:

$$P(\text{Red}) = P(R | B) \times P(B) + P(R | A) \times P(A) = 0.25$$

$$P(\text{Green}) = 0.34$$

$$P(\text{Yellow}) = 0.41$$

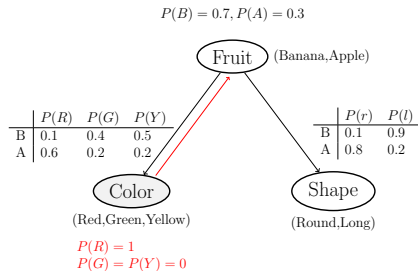
Shapes:

$$P(\text{Round}) = 0.31$$

$$P(\text{Long}) = 0.69$$

# Simple Bayesian Network Example

## Posteriors



- We see a fruit to be red

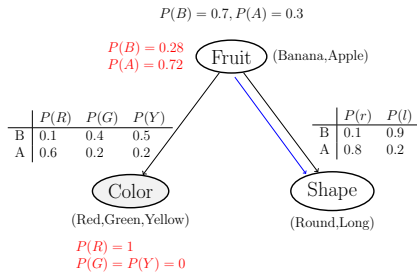
Fruits: (un-normalized)  
 $P(Banana | Red) = P(R | B) \times P(B)$   
 $= 0.1 \times 0.7 = 0.07$

$P(Apple | Red) = 0.18$

Fruits: (normalized)  
 $P(Banana | Red) = 0.28$   
 $P(Apple | Red) = 0.72$

# Simple Bayesian Network Example

## Posteriors (contd.)



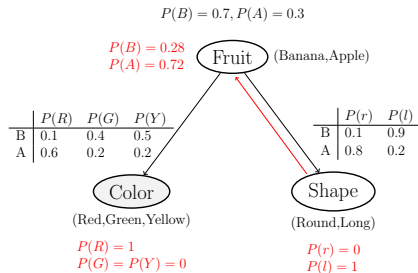
- Change in probability of fruits changes posterior probability of shapes

Shapes:

$$\frac{P(Round)}{P(Long)} = 0.60$$
$$P(Long) = 0.40$$

# Simple Bayesian Network Example

## Posteriors (contd.)



- Now we see the fruit to be **long**

Fruits: (un-normalized)

$$P(\text{Banana} \mid \text{Red}, \text{Long}) = P(l \mid B) \times P(B) = 0.9 \times 0.28 = 0.25$$
$$P(\text{Apple} \mid \text{Red}, \text{Long}) = 0.14$$

Fruits: (normalized)

$$P(\text{Banana} \mid \text{Red}, \text{Long}) = 0.63$$
$$P(\text{Apple} \mid \text{Red}, \text{Long}) = 0.37$$

Quiz 03-04

End of Module 03-04