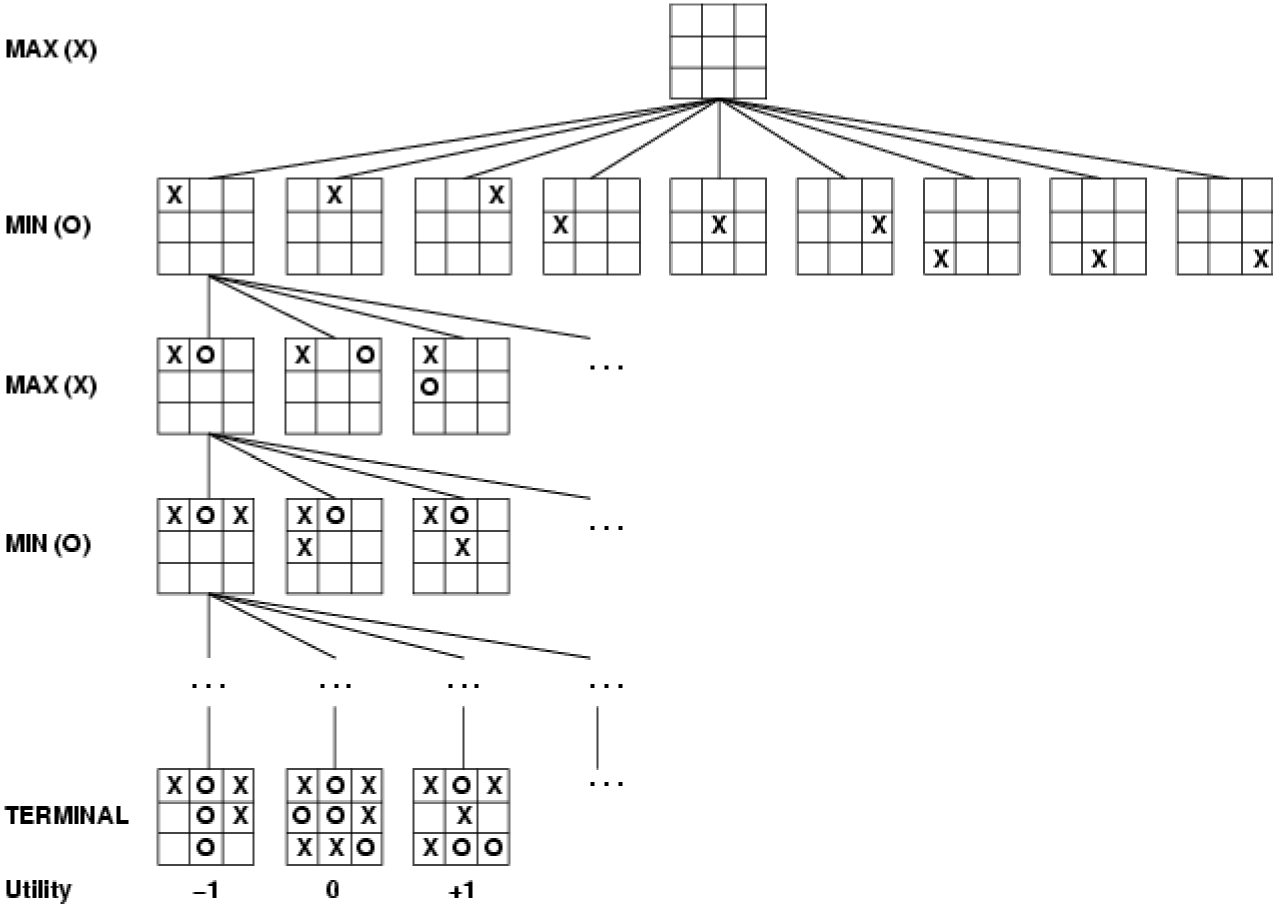
Adversarial Search

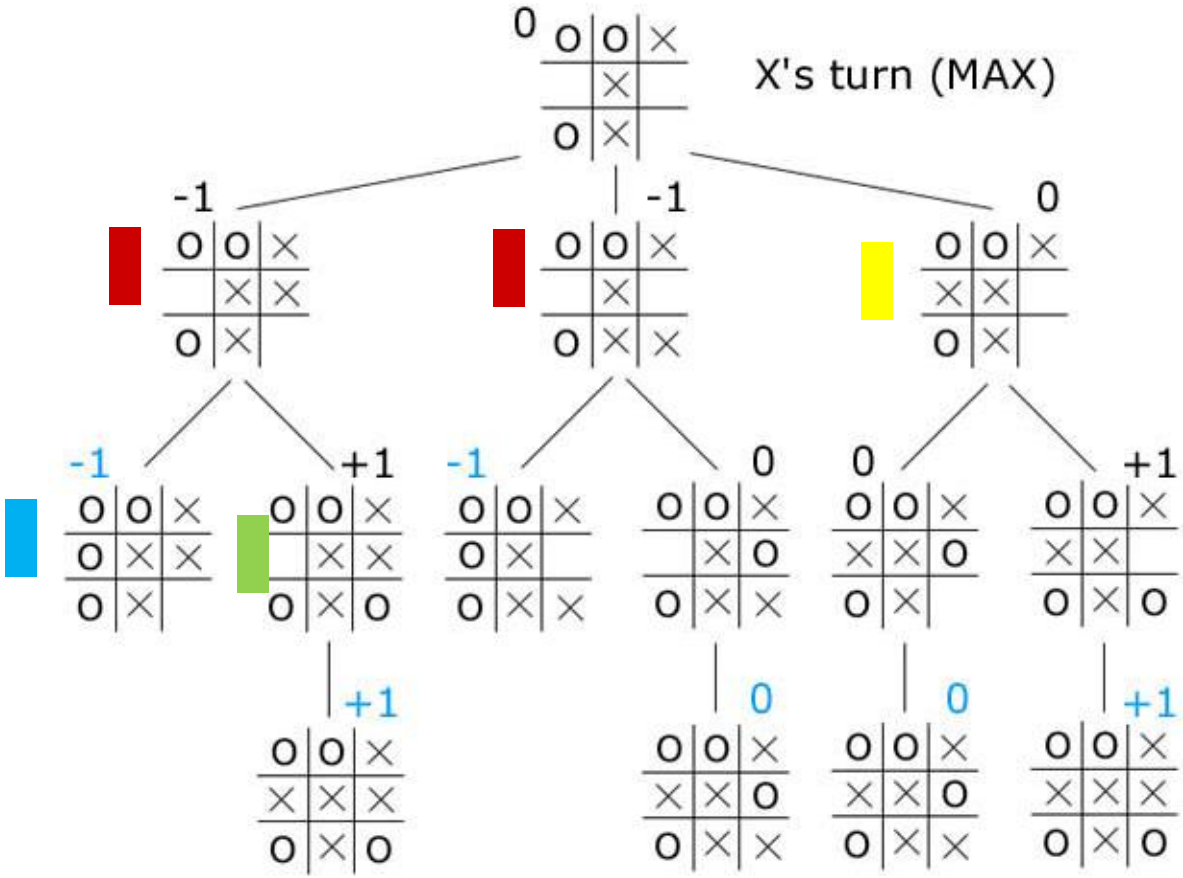
Games vs. search problems

- "Unpredictable" opponent → specifying a move for every possible opponent reply
- Time limits → unlikely to find goal, must approximate

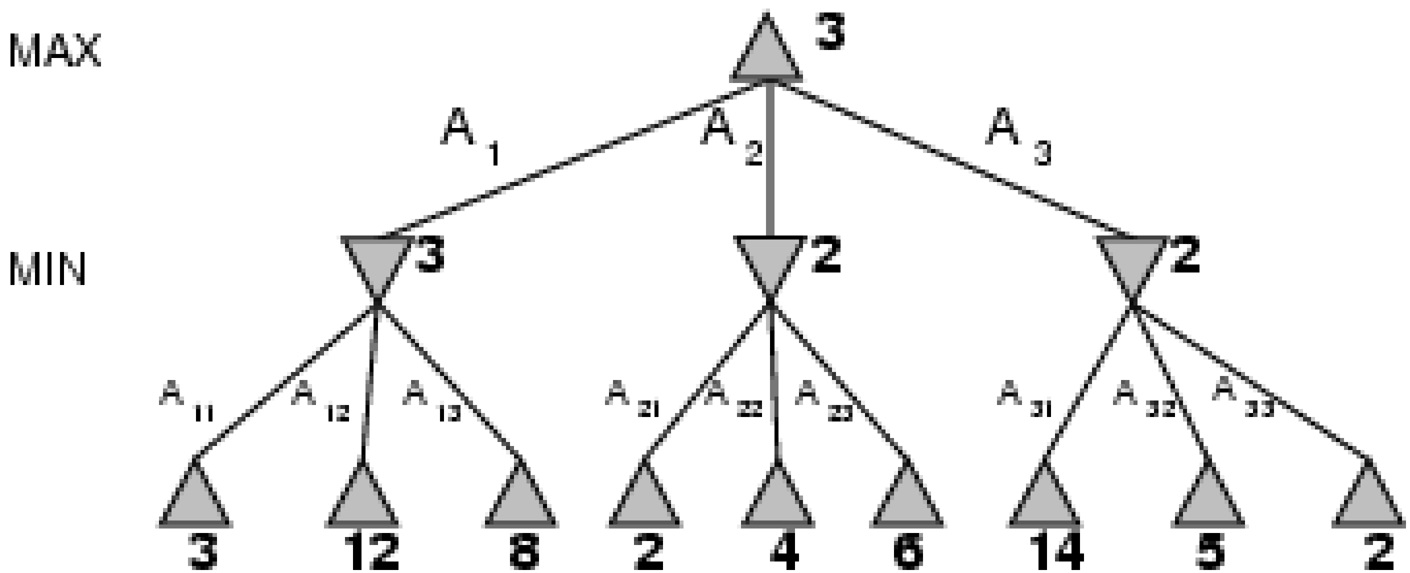
Game tree (2-player, deterministic, turns)



Game tree (2-player, deterministic, turns)



Minimax

- Perfect play for deterministic games
- Idea: choose move to position with highest minimax value
  = best achievable payoff against best play
- E.g., 2-ply game:
- 

Minimax algorithm

function MINIMAX-DECISION(*state*) **returns** *an action*

  $v \leftarrow$ MAX-VALUE(*state*)
  return the *action* in SUCCESSORS(*state*) with value v

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function MAX-VALUE(*state*) **returns** *a utility value*

  if TERMINAL-TEST(*state*) **then return** UTILITY(*state*)
  $v \leftarrow -\infty$
  for a, s in SUCCESSORS(*state*) **do**
    $v \leftarrow$ MAX(v, MIN-VALUE(s))
  return v

---

function MIN-VALUE(*state*) **returns** *a utility value*

  if TERMINAL-TEST(*state*) **then return** UTILITY(*state*)
  $v \leftarrow \infty$
  for a, s in SUCCESSORS(*state*) **do**
    $v \leftarrow$ MIN(v, MAX-VALUE(s))
  return v

Properties of minimax

- Complete?

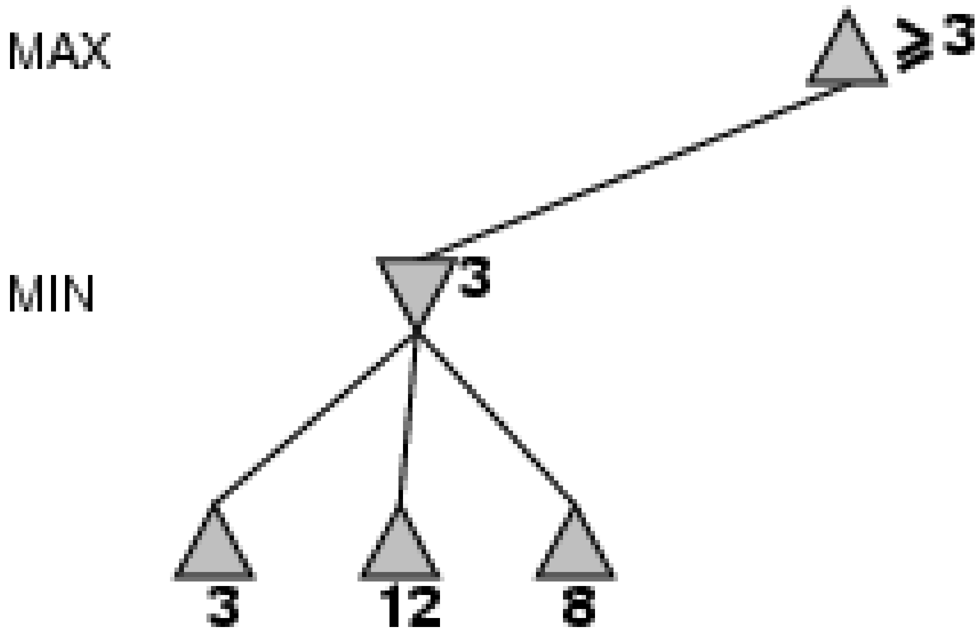
  Yes (if tree is finite)
- Optimal?
- Yes (against an optimal opponent)
- Time complexity?

  $O(b^m)$
- Space complexity?

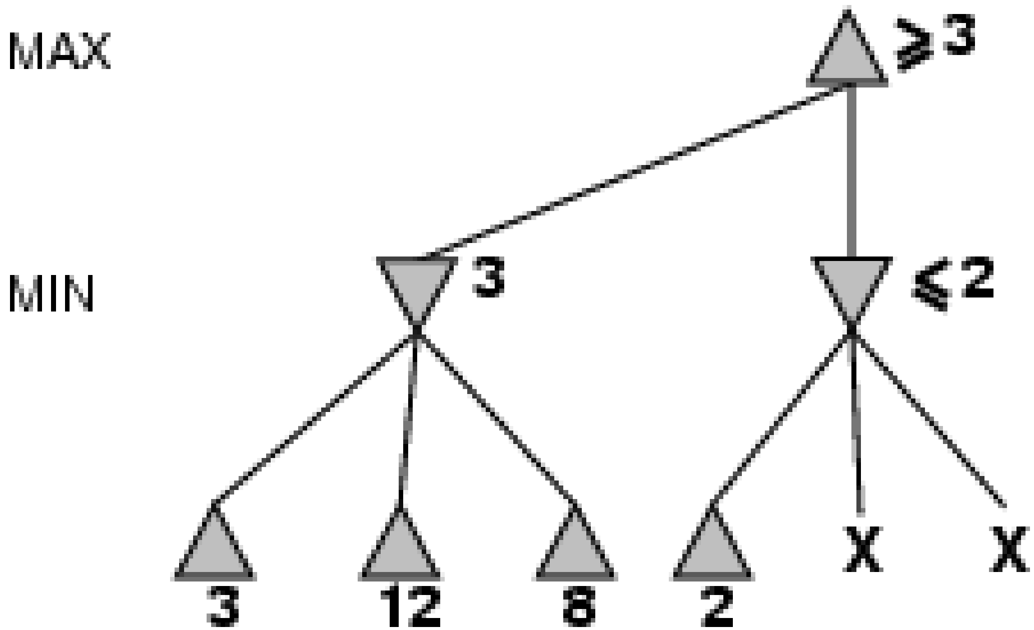
  O(bm) (depth-first exploration)

- For chess, $b \approx 35$, $m \approx 100$ for "reasonable" games
  → exact solution completely infeasible

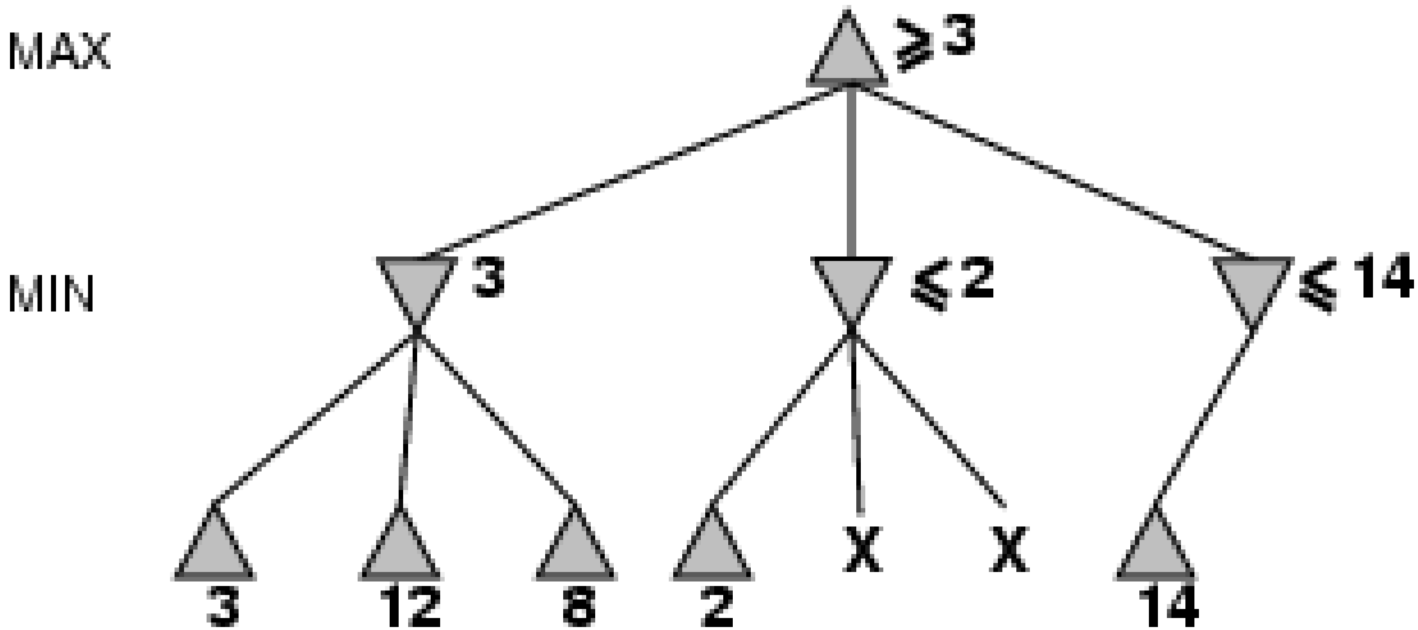
α-β pruning example



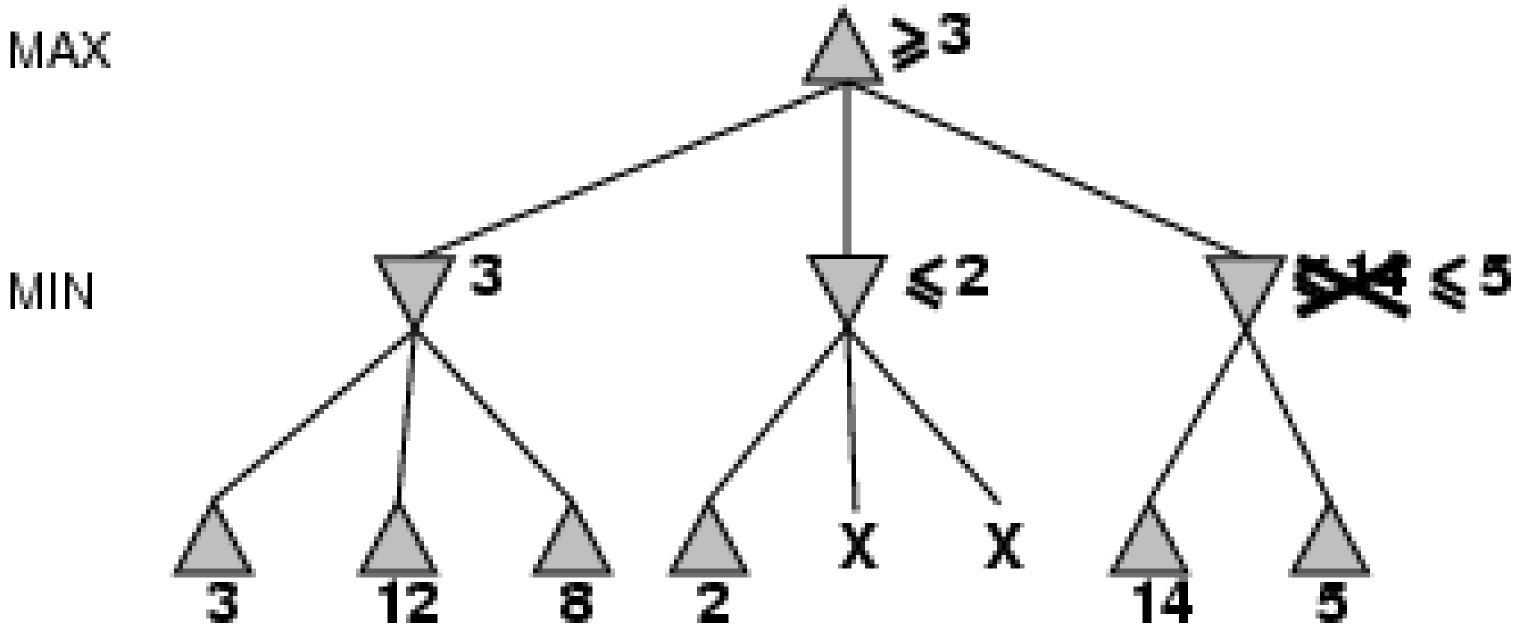
α-β pruning example



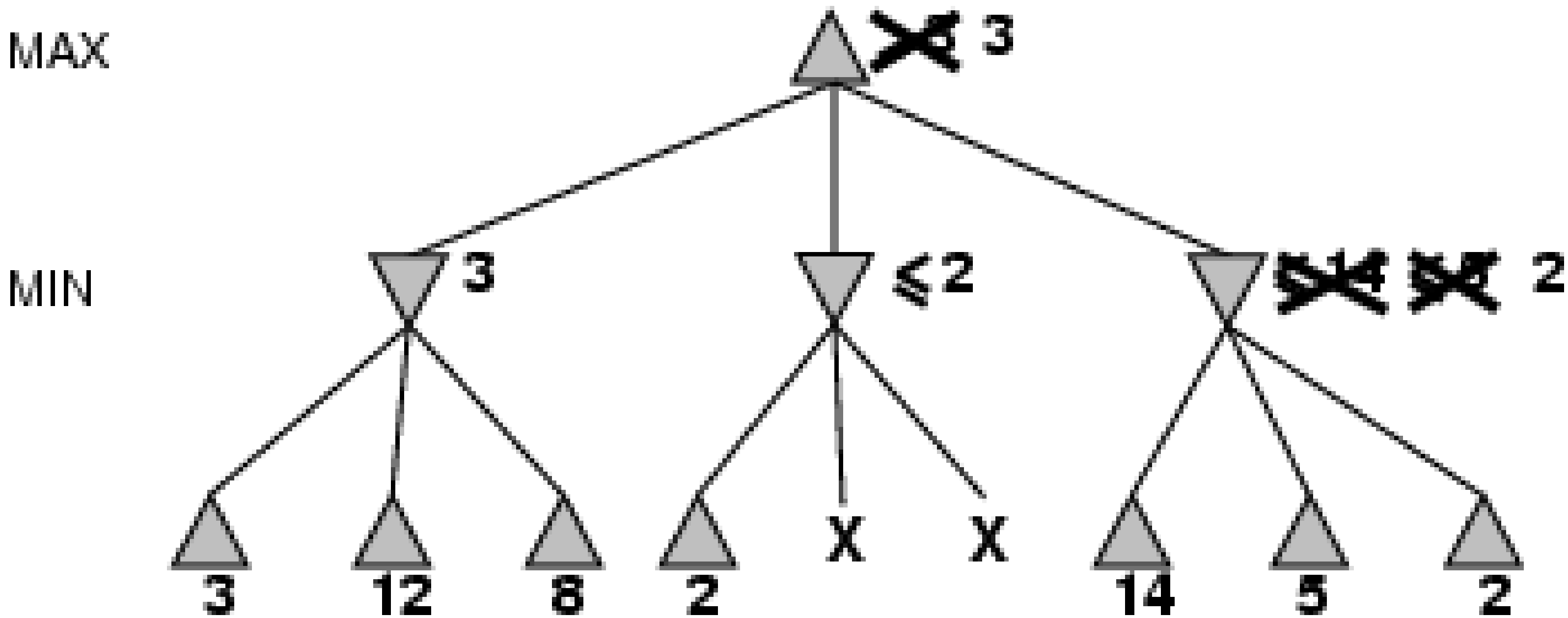
α-β pruning example



α-β pruning example



α-β pruning example

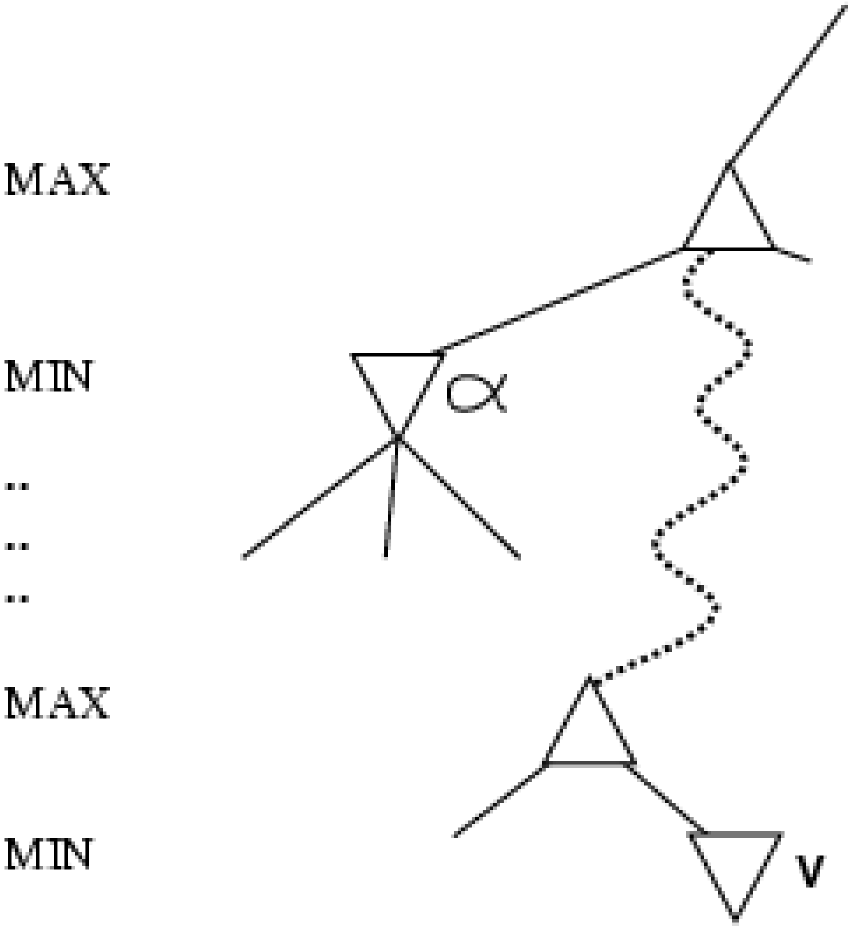


Properties of α-β

- Pruning does not affect final result
- Good move ordering improves effectiveness of pruning
- With "perfect ordering," time complexity = $O(b^{m/2})$
  → doubles depth of search
- A simple example of the value of reasoning about which computations are relevant (a form of metareasoning)

Why is it called α-β?

- α is the value of the best (i.e., highest-value) choice found so far at any choice point along the path for *max*
- If *v* is worse than α, *max* will avoid it
  → prune that branch
- Define β similarly for *min*



The α-β algorithm

function ALPHA-BETA-SEARCH(*state*) **returns** *an action*
  inputs: *state*, current state in game

  $v \leftarrow$ MAX-VALUE(*state*, $-\infty$, $+\infty$)
  return the *action* in SUCCESSORS(*state*) with value v

---

function MAX-VALUE(*state*, α, β) **returns** *a utility value*
  inputs: *state*, current state in game
    α, the value of the best alternative for MAX along the path to *state*
    β, the value of the best alternative for MIN along the path to *state*

  if TERMINAL-TEST(*state*) **then return** UTILITY(*state*)
  $v \leftarrow -\infty$
  for a, s in SUCCESSORS(*state*) **do**
    $v \leftarrow$ MAX(v, MIN-VALUE(s, α, β))
    if $v \geq \beta$ **then return** v
    $\alpha \leftarrow$ MAX(α, v)
  return v

The α-β algorithm

function $\text{Min-Value}(state, \alpha, \beta)$ **returns** *a utility value*
  inputs: *state*, current state in game
    α, the value of the best alternative for MAX along the path to *state*
    β, the value of the best alternative for MIN along the path to *state*

  if $\text{Terminal-Test}(state)$ **then return** $\text{Utility}(state)$
  $v \leftarrow +\infty$
  for a, s in $\text{Successors}(state)$ **do**
    $v \leftarrow \text{Min}(v, \text{Max-Value}(s, \alpha, \beta))$
    if $v \leq \alpha$ **then return** v
    $\beta \leftarrow \text{Min}(\beta, v)$
  return v

Resource limits

Suppose we have 100 secs, explore 10^4 nodes/sec

→ 10^6 nodes per move

Standard approach:

- cutoff test:

  e.g., depth limit

- evaluation function

  = estimated desirability of position

Evaluation functions

- For chess, typically linear weighted sum of features

$$Eval(s) = w_1 f_1(s) + w_2 f_2(s) + \ldots + w_n f_n(s)$$

- e.g., $w_1 = 9$ with

  $f_1(s)$ = (number of white queens) – (number of black queens), etc.

Cutting off search

MinimaxCutoff is identical to *MinimaxValue* except

1. *Terminal?* is replaced by *Cutoff?*
2. *Utility* is replaced by *Eval*

Does it work in practice?

$b^m = 10^6$, $b=35 \rightarrow m=4$ [10^^154]

4-ply lookahead is a hopeless chess player!

- 4-ply ≈ human novice
- 8-ply ≈ typical PC, human master
- 12-ply ≈ Deep Blue, Kasparov

Deterministic games in practice

- Chess: Deep Blue defeated human world champion Garry Kasparov in a six-game match in 1997. Deep Blue searches 200 million positions per second, uses very sophisticated evaluation, and undisclosed methods for extending some lines of search up to 40 ply.

Summary

- Games are fun to work on!
- They illustrate several important points about AI
- perfection is unattainable → must approximate