

# Summary for Finals

STAT 3013, Introduction to Probability

May 2, 2017

## Basic Properties

1. For any event  $A$  of sample space  $\Omega$ , the probability of  $A$ , denoted as  $P(A)$  satisfies (1)  $0 \leq P(A) \leq 1$ , (2)  $P(\Omega) = 1$  and (3) for mutually exclusive events,  $A_i, i \geq 1, P(\cup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$ .
2.  $P(A^c) = 1 - P(A)$ .  $P(A \cup B) = P(A) + P(B) - P(A \cap B)$ . (Principle of Inclusion-Exclusion or PIE).
3. A random variable whose set of possible values is either finite or countably infinite is called discrete. For a discrete random variable:  $p(x) = P(X = x)$  is called the probability mass function of  $X$ . Expectation is defined as  $E(X) = \sum_{x:p(x)>0} xp(x)$ .
4. For any function  $g$ ,  $E(g(X)) = \sum_{x:p(x)>0} g(x)p(x)$ .
5. The variance of *any* random variable  $X$ , denoted by  $Var(X)$ , is defined by:

$$Var(X) = E[(X - E[X])^2] = E[X^2] - (E[X])^2$$

## Conditional Probability and Independence

1. For any two events  $E$  and  $F$ , the conditional probability of  $E$  given  $F$  is denoted by

$$P(E | F) = P(E \cap F) / P(F).$$

2.  $P(E) = P(E | F)P(F) + P(E | F^c)P(F^c)$ .
3. **Bayes rule** Let  $F_i, i = 1, \dots, n$  be mutually exclusive events whose union is the sample space  $\Omega$ . Then:

$$P(F_j | E) = \frac{P(E | F_j)P(F_j)}{\sum_{i=1}^n P(E | F_i)P(F_i)}$$

4. Two events  $E$  and  $F$  are said to be independent if they satisfy  $P(E \cap F) = P(E)P(F)$ .

6. For  $k$  random variables  $X_1, \dots, X_k$  and constants  $c_1, \dots, c_k$ ,

$$E\left(\sum_{i=1}^k c_i X_i\right) = \sum_{i=1}^k c_i E(X_i)$$

7. If in addition,  $X_1, X_2, \dots, X_k$  are independent:

$$Var\left(\sum_{i=1}^k c_i X_i\right) = \sum_{i=1}^k c_i^2 Var(X_i)$$

8. **Tail sum method** For a nonnegative integer-valued random variable:

$$E(X) = \sum_{n=0}^{\infty} P(X > n)$$

## Discrete Random Variable

1. A real-valued function defined on the outcome of a probability experiment is called a random variable.
2. For *any* random variable  $X$ , the distribution function is  $F(x) = P(X \leq x)$ .

## Standard Discrete Distributions

1. **Binomial**( $n, p$ ) Number of heads in  $n$  coin tosses, each with probability  $p$ :

$$\text{PMF: } p(x) = \binom{n}{x} p^x (1-p)^{n-x}, x = 0, \dots, n.$$

$$E[X] = np, \text{Var}[X] = np(1 - p).$$

2. **Geometric**( $p$ ) Number of tosses to get the first head,  $P(\text{head}) = p$ .

$$\text{PMF: } p(x) = p(1 - p)^{x-1}, x = 1, 2, \dots, \\ E[X] = 1/p, \text{Var}[X] = (1 - p)/p^2.$$

3. Geometric is memoryless:  $P(X > m + n \mid X > m) = P(X > n)$ .

4. **Negative Binomial**( $r, p$ ) Number of tosses to get  $r$  heads,  $P(\text{head}) = p$ . Neg-Bin( $r, p$ ) is sum of  $r$  Geom( $p$ ) r.v.s.

$$\text{PMF: } p(x) = \binom{x-1}{r-1} p^r (1-p)^{x-r}, x \geq r \\ E[X] = r/p, \text{Var}[X] = r(1-p)/p^2.$$

5. **Poisson**( $\lambda$ ) Used to model number of events.

$$\text{PMF: } p(x) = \frac{e^{-\lambda} \lambda^x}{x!}, x \geq 0 \\ E[X] = \lambda, \text{Var}[X] = \lambda$$

6. **Hypergeometric**( $n, N, m$ ) Number of white balls selected when  $n$  balls are randomly chosen from an urn that contains  $N$  balls of which  $m$  are white. Let  $p = \frac{m}{N}$ .

$$\text{PMF: } p(x) = \frac{\binom{m}{x} \binom{N-m}{n-x}}{\binom{N}{n}}, x = 0, \dots, m \\ E[X] = np, \text{Var}[X] = \frac{N-n}{N-1} np(1-p).$$

7. An important property of the expected value is that the expected value of a sum of random variables is equal to the sum of their expected values:

$$E\left[\sum_{i=1}^n X_i\right] = \sum_{i=1}^n E[X_i]$$

8. If  $X \equiv X_n \sim \text{Bin}(n, p), n \rightarrow \infty, p = p_n \rightarrow 0, np_n \rightarrow \lambda$  for some  $0 < \lambda < \infty$ ,  $X_n \approx \text{Poisson}(\lambda)$ . This is called the **Poisson approximation to Binomial**. Useful for rare events modeling.

## Continuous Distributions

1. A random variable  $X$  is continuous if there is a nonnegative function  $f$ , called the probability density function of  $X$ , such that, for any set  $B$ ,

$$P(X \in B) = \int_B f(x) dx \equiv P(a \leq X \leq b) = \int_a^b f(x) dx$$

2. For a density  $f$ :  $\int_{-\infty}^{\infty} f(x) dx = 1$ . Useful for validating if a given function is a density and for finding normalizing constants.

3. Continuous random variable puts zero probability to discrete sets or single points.

4. If  $X$  is continuous, its CDF  $F(x)$  is differentiable and

$$\frac{d}{dx} F(x) = f(x)$$

5. The expected value of a continuous random variable  $X$  is defined by  $E[X] = \int_{-\infty}^{\infty} x f(x) dx$ .

6. For any function  $g$ :  $E[g(X)] = \int_{-\infty}^{\infty} g(x) f(x) dx$ .

7. **Uniform**( $a, b$ ): Denoted by  $X \sim \mathcal{U}(a, b)$

$$\text{PDF: } p(x) = \begin{cases} \frac{1}{b-a} & \text{if } a \leq x \leq b \\ 0 & \text{otherwise.} \end{cases}$$

$$E[X] = \frac{b+a}{2}, \text{Var}[X] = \frac{(b-a)^2}{12}$$

8. **Normal**( $\mu, \sigma$ ): Denoted by  $X \sim \mathcal{N}(\mu, \sigma)$

$$\text{PDF: } p(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \\ E[X] = \mu, \text{Var}[X] = \sigma^2.$$

9. If  $X \sim \mathcal{N}(\mu, \sigma)$ , then  $Z = \frac{X-\mu}{\sigma} \sim \mathcal{N}(0, 1)$ .

10.  $P(X \leq x) = P(Z \leq \frac{x-\mu}{\sigma}) \doteq \Phi(\frac{x-\mu}{\sigma})$ .

11. Probabilities about  $X$  can be expressed in terms of probabilities about the standard normal variable  $Z$ , obtained from **Normal Table**.

12. **Central Limit Theorem**: When  $n$  is large, the probability distribution function of a binomial random variable with parameters  $n$  and  $p$  can be approximated by that of a normal random variable having mean  $np$  and variance  $np(1-p)$ .