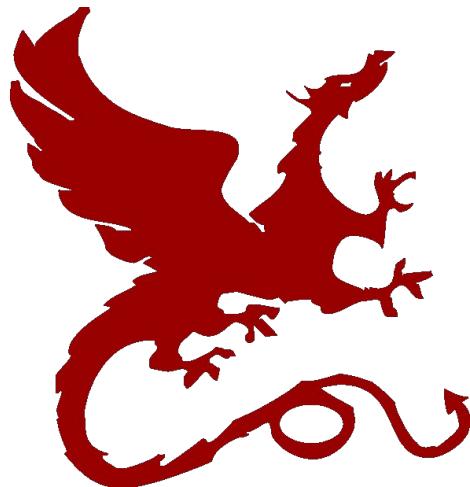


# Algorithms for NLP



## Classification II

Sachin Kumar - CMU

Slides: Dan Klein – UC Berkeley, Taylor  
Berg-Kirkpatrick – CMU,



# Minimize Training Error?

---

- A loss function declares how costly each mistake is

$$\ell_i(\mathbf{y}) = \ell(\mathbf{y}, \mathbf{y}_i^*)$$

- E.g. 0 loss for correct label, 1 loss for wrong label
- Can weight mistakes differently (e.g. false positives worse than false negatives or Hamming distance over structured labels)
- We could, in principle, minimize training loss:

$$\min_{\mathbf{w}} \sum_i \ell_i \left( \arg \max_{\mathbf{y}} \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) \right)$$

- This is a hard, discontinuous optimization problem

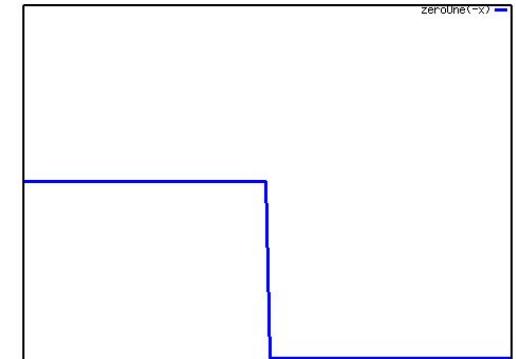


# Objective Functions

- What do we want from our weights?

- Depends!
- So far: minimize (training) errors:

$$\sum_i step \left( \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) - \max_{\mathbf{y} \neq \mathbf{y}_i^*} \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) \right)$$



- This is the “zero-one loss”
  - Discontinuous, minimizing is NP-complete
- Maximum entropy and SVMs have other objectives related to zero-one loss



# Linear Models: Maximum Entropy

- Maximum entropy (logistic regression)

- Use the scores as probabilities:

$$P(y|x, w) = \frac{\exp(w^\top f(y))}{\sum_{y'} \exp(w^\top f(y'))}$$

←———— Make positive  
←———— Normalize

- Maximize the (log) conditional likelihood of training data

$$L(w) = \log \prod_i P(y_i^* | x_i, w) = \sum_i \log \left( \frac{\exp(w^\top f_i(y_i^*))}{\sum_y \exp(w^\top f_i(y))} \right)$$

$$= \sum_i \left( w^\top f_i(y_i^*) - \log \sum_y \exp(w^\top f_i(y)) \right)$$



# Maximum Entropy II

---

- Motivation for maximum entropy:
  - Connection to maximum entropy principle (sort of)
  - Might want to do a good job of being uncertain on noisy cases...
  - ... in practice, though, posteriors are pretty peaked
- Regularization (smoothing)

$$\max_{\mathbf{w}} \sum_i \left( \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) - \log \sum_{\mathbf{y}} \exp(\mathbf{w}^\top \mathbf{f}_i(\mathbf{y})) \right) - k \|\mathbf{w}\|^2$$

$$\min_{\mathbf{w}} k \|\mathbf{w}\|^2 - \sum_i \left( \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) - \log \sum_{\mathbf{y}} \exp(\mathbf{w}^\top \mathbf{f}_i(\mathbf{y})) \right)$$



# Log-Loss

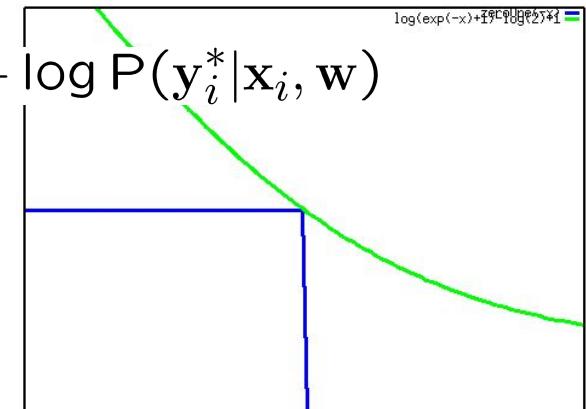
- If we view maxent as a minimization problem:

$$\min_{\mathbf{w}} k \|\mathbf{w}\|^2 + \sum_i - \left( \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) - \log \sum_{\mathbf{y}} \exp(\mathbf{w}^\top \mathbf{f}_i(\mathbf{y})) \right)$$

- This minimizes the “log loss” on each example

$$- \left( \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) - \log \sum_{\mathbf{y}} \exp(\mathbf{w}^\top \mathbf{f}_i(\mathbf{y})) \right) = - \log P(\mathbf{y}_i^* | \mathbf{x}_i, \mathbf{w})$$

$$step \left( \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) - \max_{\mathbf{y} \neq \mathbf{y}_i^*} \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) \right)$$



- One view: log loss is an *upper bound* on zero-one loss



# Maximum Margin

Note: exist other choices of how to penalize slacks!

- Non-separable SVMs

- Add slack to the constraints
- Make objective pay (linearly) for slack:

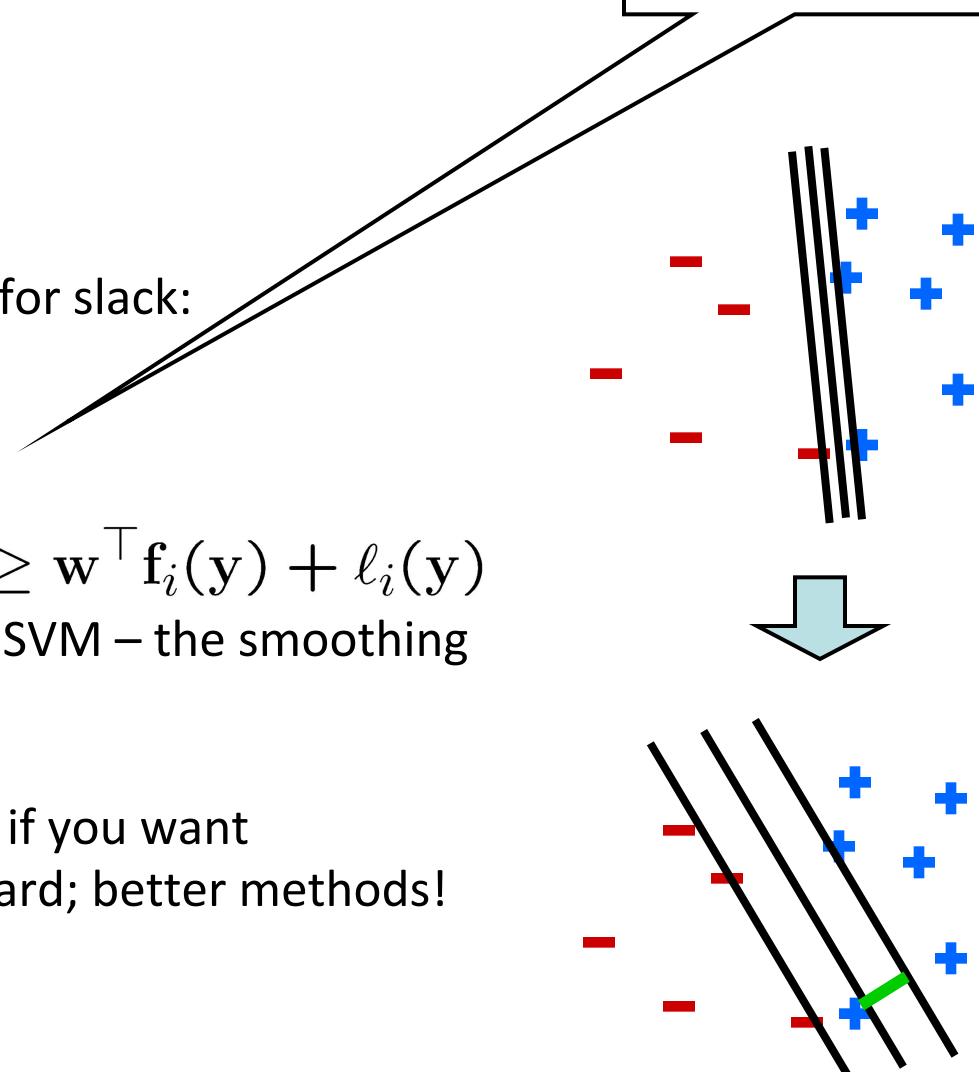
$$\min_{\mathbf{w}, \xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \xi_i$$

$$\forall i, \mathbf{y}, \quad \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) + \xi_i \geq \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) + \ell_i(\mathbf{y})$$

- C is called the *capacity* of the SVM – the smoothing knob

- Learning:

- Can still stick this into Matlab if you want
- Constrained optimization is hard; better methods!
- We'll come back to this later





# Remember SVMs...

---

- We had a **constrained** minimization

$$\min_{\mathbf{w}, \xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \xi_i$$

$$\forall i, \mathbf{y}, \quad \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) + \xi_i \geq \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) + \ell_i(\mathbf{y})$$

- ...but we can solve for  $\xi_i$

$$\forall i, \mathbf{y}, \quad \xi_i \geq \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) + \ell_i(\mathbf{y}) - \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*)$$

$$\forall i, \quad \xi_i = \max_{\mathbf{y}} (\mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) + \ell_i(\mathbf{y})) - \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*)$$

- Giving

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \left( \max_{\mathbf{y}} (\mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) + \ell_i(\mathbf{y})) - \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) \right)$$



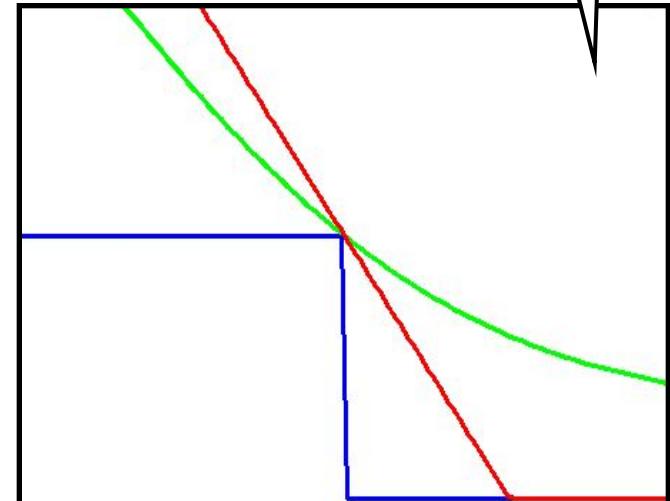
# Hinge Loss

Plot really only right  
in binary case

- Consider the per-instance objective:

$$\min_{\mathbf{w}} k \|\mathbf{w}\|^2 + \sum_i \left( \max_{\mathbf{y}} (\mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) + \ell_i(y)) - \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) \right)$$

- This is called the “hinge loss”
  - Unlike maxent / log loss, you stop gaining objective once the true label wins by enough
  - You can start from here and derive the SVM objective
  - Can solve directly with sub-gradient decent (e.g. Pegasos: Shalev-Shwartz et al 07)



$$\mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) - \max_{\mathbf{y} \neq \mathbf{y}_i^*} (\mathbf{w}^\top \mathbf{f}_i(\mathbf{y}))$$



# Subgradient Descent

---

- Recall gradient descent

We want to solve

$$\min_{x \in \mathbb{R}^n} f(x),$$

for  $f$  convex and differentiable

**Gradient descent:** choose initial  $x^{(0)} \in \mathbb{R}^n$ , repeat:

$$x^{(k)} = x^{(k-1)} - t_k \cdot \nabla f(x^{(k-1)}), \quad k = 1, 2, 3, \dots$$

- Doesn't work for non-differentiable functions



# Subgradient Descent

---

A **subgradient** of convex  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  at  $x$  is any  $g \in \mathbb{R}^n$  such that

$$f(y) \geq f(x) + g^T(y - x), \quad \text{all } y$$

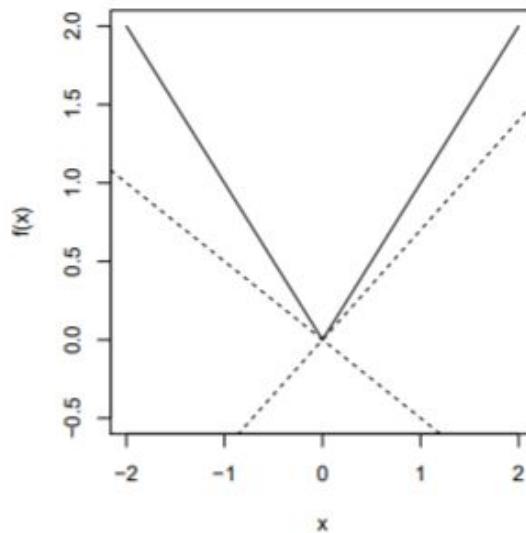
- Always exists
- If  $f$  differentiable at  $x$ , then  $g = \nabla f(x)$  uniquely
- Actually, same definition works for nonconvex  $f$  (however, subgradient need not exist)



# Subgradient Descent

## ■ Example

Consider  $f : \mathbb{R} \rightarrow \mathbb{R}$ ,  $f(x) = |x|$



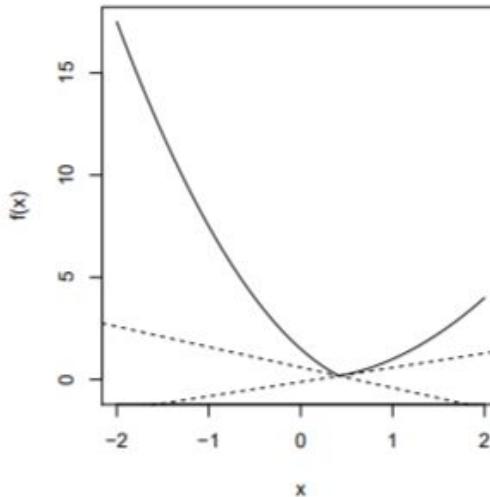
- For  $x \neq 0$ , unique subgradient  $g = \text{sign}(x)$
- For  $x = 0$ , subgradient  $g$  is any element of  $[-1, 1]$



# Subgradient Descent

## ■ Example

Let  $f_1, f_2 : \mathbb{R}^n \rightarrow \mathbb{R}$  be convex, differentiable, and consider  
 $f(x) = \max\{f_1(x), f_2(x)\}$



- For  $f_1(x) > f_2(x)$ , unique subgradient  $g = \nabla f_1(x)$
- For  $f_2(x) > f_1(x)$ , unique subgradient  $g = \nabla f_2(x)$
- For  $f_1(x) = f_2(x)$ , subgradient  $g$  is any point on the line segment between  $\nabla f_1(x)$  and  $\nabla f_2(x)$



# Subgradient Descent

---

Given convex  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ , not necessarily differentiable

**Subgradient method:** just like gradient descent, but replacing gradients with subgradients. I.e., initialize  $x^{(0)}$ , then repeat

$$x^{(k)} = x^{(k-1)} - t_k \cdot g^{(k-1)}, \quad k = 1, 2, 3, \dots,$$

where  $g^{(k-1)}$  is any subgradient of  $f$  at  $x^{(k-1)}$

Subgradient method is not necessarily a descent method, so we keep track of best iterate  $x_{\text{best}}^{(k)}$  among  $x^{(1)}, \dots, x^{(k)}$  so far, i.e.,

$$f(x_{\text{best}}^{(k)}) = \min_{i=1, \dots, k} f(x^{(i)})$$

# Structure



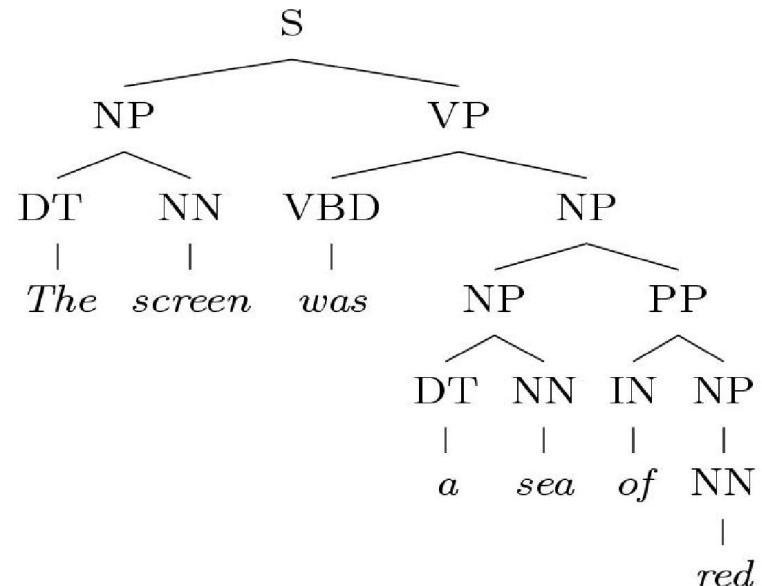
# CFG Parsing

**X**

*The screen was  
a sea of red*



**Y**



Recursive structure



# Generative vs Discriminative

---

- Generative Models have many advantages
  - Can model both  $p(x)$  and  $p(y|x)$
  - Learning is often clean and analytical: frequency estimation in penn treebank
- Disadvantages?
  - Force us to make rigid independence assumptions (context free assumption)



# Generative vs Discriminative

---

- We get more freedom in defining features - no independence assumptions required
- Disadvantages?
  - Computationally intensive
  - Use of more features can make decoding harder



# Structured Models

---

$$\text{prediction}(\mathbf{x}, \mathbf{w}) = \arg \max_{\mathbf{y} \in \mathcal{Y}(\mathbf{x})} \text{score}(\mathbf{y}, \mathbf{w})$$



space of feasible outputs

Assumption:

$$\text{score}(\mathbf{y}, \mathbf{w}) = \mathbf{w}^\top \mathbf{f}(\mathbf{y}) = \sum_p \mathbf{w}^\top \mathbf{f}(\mathbf{y}_p)$$

Score is a sum of local “part” scores

Parts = nodes, edges, productions



# Efficient Decoding

---

- Common case: you have a black box which computes

$$\text{prediction}(x) = \arg \max_{y \in \mathcal{Y}(x)} w^\top f(y)$$

at least approximately, and you want to learn  $w$

- Easiest option is the structured perceptron [Collins 01]
  - Structure enters here in that the search for the best  $y$  is typically a combinatorial algorithm (dynamic programming, matchings, ILPs, A\* ...)
  - Prediction is structured, learning update is not



# Max-Ent, Structured, Global

---

$$P(y|x, w) = \frac{\exp(w^\top f(y))}{\sum_{y'} \exp(w^\top f(y'))}$$

$$L(w) = -k||w||^2 + \sum_i \left( w^\top f_i(y_i^*) - \log \sum_y \exp(w^\top f_i(y)) \right)$$

- Assumption: Score is sum of local “part” scores

$$score(y, w) = w^\top f(y) = \sum_p w^\top f(y_p)$$



# Max-Ent, Structured, Global

---

$$\frac{\partial L(\mathbf{w})}{\partial \mathbf{w}} = -2k\mathbf{w} + \sum_i \left( \mathbf{f}_i(\mathbf{y}_i^*) - \sum_{\mathbf{y}} P(\mathbf{y}|\mathbf{x}_i) \mathbf{f}_i(\mathbf{y}) \right)$$

- what do we need to compute the gradients?
  - Log normalizer
  - Expected feature counts (inside outside algorithm)
- How to decode?
  - Search algorithms like viterbi (CKY)



# Max-Ent, Structured, Local

---

- We assume that we can arrive at a globally optimal solution by making locally optimal choices.
- We can use arbitrarily complex features over the history and lookahead over the future.
- We can perform very efficient parsing, often with linear time complexity
- Shift-Reduce parsers



# Structured Margin (Primal)

---

Remember our primal margin objective?

$$\min_w \quad \frac{1}{2} \|w\|_2^2 + C \sum_i \left( \max_y (w^\top f_i(y) + \ell_i(y)) - w^\top f_i(y_i^*) \right)$$

Still applies with structured output space!



# Structured Margin (Primal)

---

Just need efficient loss-augmented decode:

$$\bar{y} = \operatorname{argmax}_y (w^\top f_i(y) + \ell_i(y))$$

$$\min_w \quad \frac{1}{2} \|w\|_2^2 + C \sum_i (w^\top f_i(\bar{y}) + \ell_i(\bar{y}) - w^\top f_i(y_i^*))$$

$$\nabla_w = w + C \sum_i (f_i(\bar{y}) - f_i(y_i^*))$$

Still use general subgradient descent methods! (Adagrad)



# Structured Margin

---

- Remember the constrained version of primal:

$$\begin{aligned} \min_{\mathbf{w}, \xi} \quad & \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \xi_i \\ \forall i, \mathbf{y} \quad & \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) \geq \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) + \ell_i(\mathbf{y}) - \xi_i \end{aligned}$$



# Many Constraints!

- We want:

$$\arg \max_y w^\top f('It \text{ was } red', y) = \begin{smallmatrix} S \\ A \\ B \\ C \\ D \end{smallmatrix}$$

- Equivalently:

$$w^\top f('It \text{ was } red', \begin{smallmatrix} S \\ A \\ B \\ C \\ D \end{smallmatrix}) > w^\top f('It \text{ was } red', \begin{smallmatrix} S \\ A \\ B \\ D \\ F \end{smallmatrix})$$

$$w^\top f('It \text{ was } red', \begin{smallmatrix} S \\ A \\ B \\ C \\ D \end{smallmatrix}) > w^\top f('It \text{ was } red', \begin{smallmatrix} S \\ A \\ B \\ C \\ D \end{smallmatrix})$$

...

$$w^\top f('It \text{ was } red', \begin{smallmatrix} S \\ A \\ B \\ C \\ D \end{smallmatrix}) > w^\top f('It \text{ was } red', \begin{smallmatrix} S \\ E \\ F \\ G \\ H \end{smallmatrix})$$

} a lot!



# Structured Margin - Working Set

---

- It's enough if we enforce the **active constraints**.  
The others will be fulfilled automatically.
- We don't know which ones are active for the optimal solution.
- But it's likely to be only a small number  $\leftarrow$  can of course be formalized.

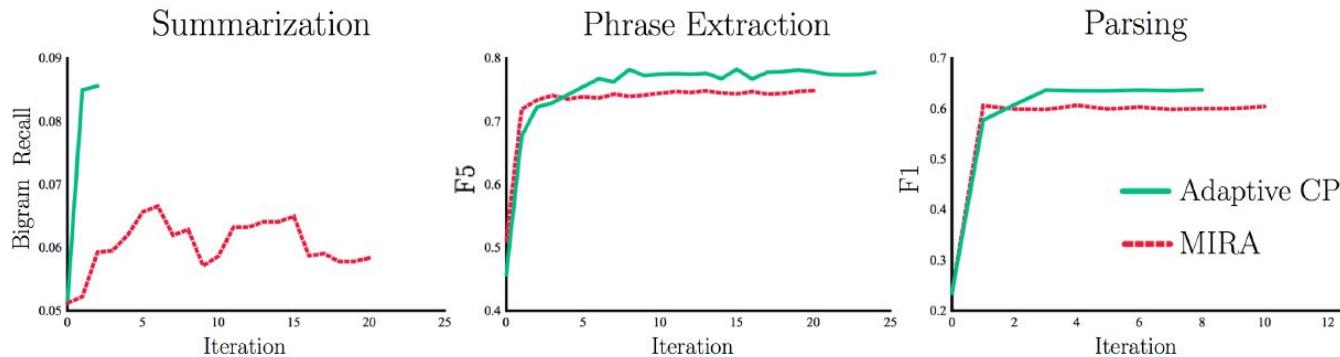
Keep a set of potentially active constraints and update it iteratively:

- Start with working set  $S = \emptyset$  (no constraints)
- Repeat until convergence:
  - ▶ Solve S-SVM training problem with constraints from  $S$
  - ▶ Check, if solution violates any of the *full* constraint set
    - ★ if no: we found the optimal solution, *terminate*.
    - ★ if yes: add most violated constraints to  $S$ , *iterate*.

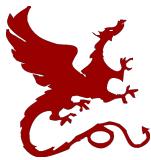


# Working Set S-SVM

- Working Set n-slack Algorithm
- Working Set 1-slack Algorithm
- Cutting Plane 1-Slack Algorithm [Joachims et al 09]
  - Requires Dual Formulation
  - Much faster convergence
  - In practice, works as fast as perceptron, more stable training



# Duals and Kernels



# Nearest Neighbor Classification

- Nearest neighbor, e.g. for digits:

- Take new example
  - Compare to all training examples
  - Assign based on closest example

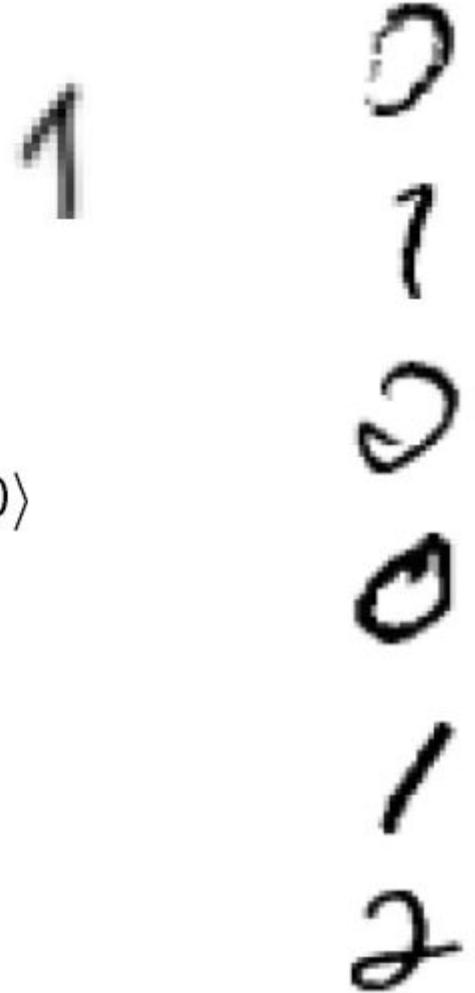
- Encoding: image is vector of intensities:

$$\mathbf{1} = \langle 0.0 \ 0.0 \ 0.3 \ 0.8 \ 0.7 \ 0.1 \dots 0.0 \rangle$$

- Similarity function:

- E.g. dot product of two images' vectors

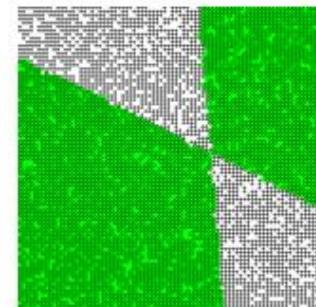
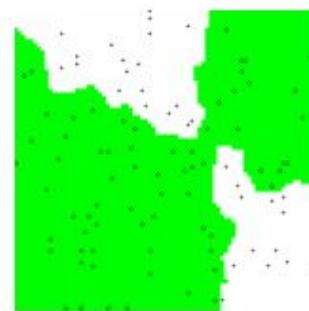
$$\text{sim}(x, y) = x^\top y = \sum_i x_i y_i$$





# Non-Parametric Classification

- Non-parametric: more examples means (potentially) more complex classifiers
- How about K-Nearest Neighbor?
  - We can be a little more sophisticated, averaging several neighbors
  - But, it's still not really error-driven learning
  - The magic is in the distance function
- Overall: we can exploit rich similarity functions, but not objective-driven learning





# A Tale of Two Approaches...

---

- Nearest neighbor-like approaches
  - Work with data through similarity functions
  - No explicit “learning”
- Linear approaches
  - Explicit training to reduce empirical error
  - Represent data through features
- Kernelized linear models
  - Explicit training, but driven by similarity!
  - Flexible, powerful, very very slow



# Perceptron, Again

- Start with zero weights
- Visit training instances one by one
  - Try to classify

$$\hat{y} = \arg \max_{y \in \mathcal{Y}(x)} w^\top f_i(y)$$

- If correct, no change!
- If wrong: adjust weights

$$w \leftarrow w + f_i(y_i^*)$$

$$w \leftarrow w - f_i(\hat{y})$$

$$w \leftarrow w + (f_i(y_i^*) - f_i(\hat{y}))$$

$$w \leftarrow w + \Delta_i(\hat{y}) \quad \textit{mistake vectors}$$



# Perceptron Weights

- What is the final value of  $w$ ?

$$w \leftarrow w + \Delta_i(y)$$

- Can it be an arbitrary real vector?
- No! It's built by adding up feature vectors (mistake vectors).

$$w = \Delta_i(y) + \Delta_{i'}(y') + \dots$$

$$w = \sum_{i,y} \alpha_i(y) \Delta_i(y) \quad \textit{mistake counts}$$

- Can reconstruct weight vectors (the **primal representation**) from update counts (the **dual representation**) for each  $i$

$$\alpha_i = \langle \alpha_i(y_1) \ \alpha_i(y_2) \ \dots \ \alpha_i(y_n) \rangle$$



# Dual Perceptron

$$\mathbf{w} = \sum_{i,y} \alpha_i(\mathbf{y}) \Delta_i(\mathbf{y})$$

- Track mistake counts rather than weights
- Start with zero counts ( $\alpha$ )
- For each instance  $x$ 
  - Try to classify

$$\hat{\mathbf{y}} = \arg \max_{\mathbf{y} \in \mathcal{Y}(\mathbf{x})} \mathbf{w}^\top \mathbf{f}(\mathbf{y})$$

$$\hat{\mathbf{y}} = \arg \max_{\mathbf{y} \in \mathcal{Y}(\mathbf{x}_i)} \sum_{i', \mathbf{y}'} \alpha_{i'}(\mathbf{y}') \Delta_{i'}(\mathbf{y}')^\top \mathbf{f}_i(\mathbf{y})$$

- If correct, no change!
- If wrong: raise the mistake count for this example and prediction

$$\alpha_i(\hat{\mathbf{y}}) \leftarrow \alpha_i(\hat{\mathbf{y}}) + 1$$

$$\mathbf{w} \leftarrow \mathbf{w} + \Delta_i(\hat{\mathbf{y}})$$



# Dual/Kernelized Perceptron

- How to classify an example  $\mathbf{x}$ ?

$$\begin{aligned} score(\mathbf{y}) &= \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) = \left( \sum_{i', \mathbf{y}'} \alpha_{i'}(\mathbf{y}') \Delta_{i'}(\mathbf{y}') \right)^\top \mathbf{f}_i(\mathbf{y}) \\ &= \sum_{i', \mathbf{y}'} \alpha_{i'}(\mathbf{y}') (\Delta_{i'}(\mathbf{y}')^\top \mathbf{f}_i(\mathbf{y})) \\ &= \sum_{i', \mathbf{y}'} \alpha_{i'}(\mathbf{y}') (\mathbf{f}_{i'}(\mathbf{y}_{i'}^*)^\top \mathbf{f}_i(\mathbf{y}) - \mathbf{f}_{i'}(\mathbf{y}')^\top \mathbf{f}_i(\mathbf{y})) \\ &= \sum_{i', \mathbf{y}'} \alpha_{i'}(\mathbf{y}') (K(\mathbf{y}_{i'}^*, \mathbf{y}) - K(\mathbf{y}', \mathbf{y})) \end{aligned}$$

- If someone tells us the value of  $K$  for each pair of candidates, never need to build the weight vectors



# Issues with Dual Perceptron

---

- Problem: to score each candidate, we may have to compare to *all* training candidates

$$score(\mathbf{y}) = \sum_{i', \mathbf{y}'} \alpha_{i'}(\mathbf{y}') \left( K(\mathbf{y}_{i'}^*, \mathbf{y}) - K(\mathbf{y}', \mathbf{y}) \right)$$

- Very, very slow compared to primal dot product!
- One bright spot: for perceptron, only need to consider candidates we made mistakes on during training
- Slightly better for SVMs where the alphas are (in theory) sparse
- This problem is serious: fully dual methods (including kernel methods) tend to be extraordinarily slow
- Of course, we can (so far) also accumulate our weights as we go...



# Kernels: Who cares?

---

- So far: a very strange way of doing a very simple calculation
- “Kernel trick”: we can substitute any\* similarity function in place of the dot product
- Lets us learn new kinds of hypotheses

\* Fine print: if your kernel doesn't satisfy certain technical requirements, lots of proofs break. E.g. convergence, mistake bounds. In practice, illegal kernels *sometimes* work (but not always).



# Example: Kernels

---

- Quadratic kernels

$$\begin{aligned} K(x, x') &= (x \cdot x' + 1)^2 \\ &= \sum_{i,j} x_i x_j x'_i x'_j + 2 \sum_i x_i x'_i + 1 \end{aligned}$$

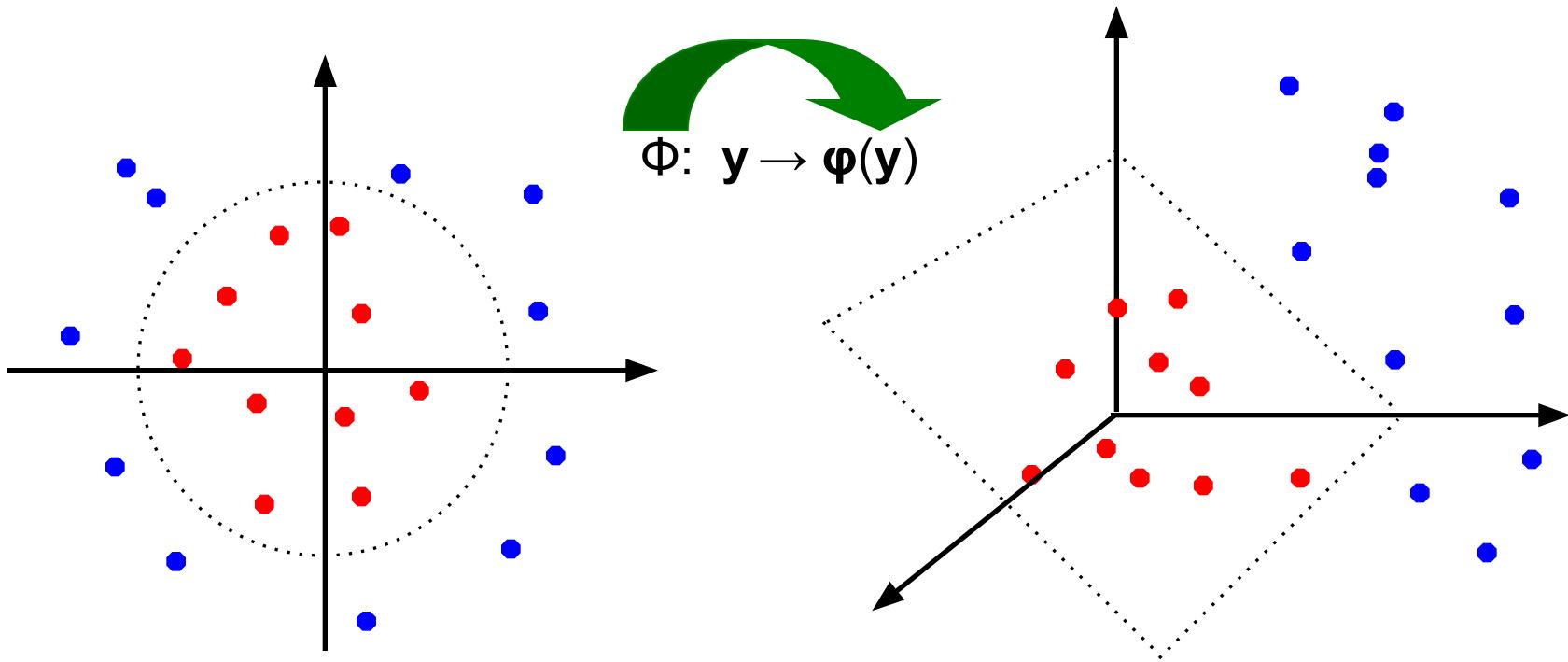


$$K(\mathbf{y}, \mathbf{y}') = (\mathbf{f}(\mathbf{y})^\top \mathbf{f}(\mathbf{y}') + 1)^2$$



# Non-Linear Separators

- Another view: kernels map an original feature space to some higher-dimensional feature space where the training set is (more) separable





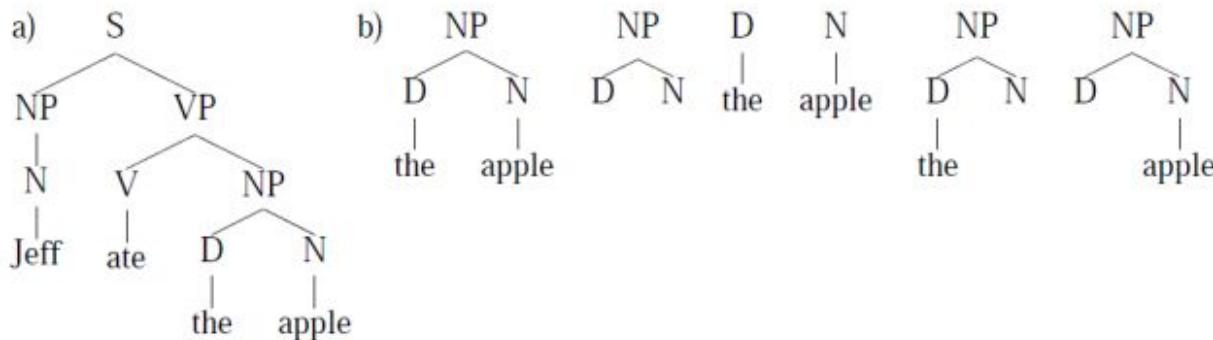
# Why Kernels?

---

- Can't you just add these features on your own (e.g. add all pairs of features instead of using the quadratic kernel)?
  - Yes, in principle, just compute them
  - No need to modify any algorithms
  - But, number of features can get large (or infinite)
  - Some kernels not as usefully thought of in their expanded representation, e.g. RBF or data-defined kernels [Henderson and Titov 05]
- Kernels let us compute with these features implicitly
  - Example: implicit dot product in quadratic kernel takes much less space and time per dot product
  - Of course, there's the cost for using the pure dual algorithms...



# Tree Kernels



- Want to compute number of common subtrees between  $T, T'$
- Add up counts of all pairs of nodes  $n, n'$ 
  - Base: if  $n, n'$  have different root productions, or are depth 0:

$$C(n_1, n_2) = 0$$

- Base: if  $n, n'$  are share the same root production:

$$C(n_1, n_2) = \lambda \prod_{j=1}^{nc(n_1)} (1 + C(ch(n_1, j), ch(n_2, j)))$$



# Dual Formulation of SVM

- We want to optimize: (separable case for now)

$$\min_{\mathbf{w}} \quad \frac{1}{2} \|\mathbf{w}\|^2$$

$$\forall i, \mathbf{y} \quad \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) \geq \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) + \ell_i(\mathbf{y})$$

- This is hard because of the constraints
- Solution: method of Lagrange multipliers
- The *Lagrangian* representation of this problem is:

$$\min_{\mathbf{w}} \max_{\alpha \geq 0} \quad \Lambda(\mathbf{w}, \alpha) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i, \mathbf{y}} \alpha_i(\mathbf{y}) (\mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) - \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) - \ell_i(\mathbf{y}))$$

- All we've done is express the constraints as an adversary which leaves our objective alone if we obey the constraints but ruins our objective if we violate any of them



# Dual Formulation II

- Duality tells us that

$$\min_{\mathbf{w}} \max_{\alpha \geq 0} \quad \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i,y} \alpha_i(y) (\mathbf{w}^\top \mathbf{f}_i(y^*) - \mathbf{w}^\top \mathbf{f}_i(y) - \ell_i(y))$$

has the same value as

$Z(\alpha)$

$$\max_{\alpha \geq 0} \underbrace{\min_{\mathbf{w}}}_{\text{ }} \quad \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i,y} \alpha_i(y) (\mathbf{w}^\top \mathbf{f}_i(y^*) - \mathbf{w}^\top \mathbf{f}_i(y) - \ell_i(y))$$

- This is useful because if we think of the  $\alpha$ 's as constants, we have an unconstrained min in  $\mathbf{w}$  that we can solve analytically.
- Then we end up with an optimization over  $\alpha$  instead of  $\mathbf{w}$  (easier).



# Dual Formulation III

- Minimize the Lagrangian for fixed  $\alpha$ 's:

$$\Lambda(\mathbf{w}, \alpha) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i,y} \alpha_i(y) (\mathbf{w}^\top \mathbf{f}_i(y^*) - \mathbf{w}^\top \mathbf{f}_i(y) - \ell_i(y))$$

$$\begin{aligned} \frac{\partial \Lambda(\mathbf{w}, \alpha)}{\partial \mathbf{w}} &= \mathbf{w} - \sum_{i,y} \alpha_i(y) (\mathbf{f}_i(y^*) - \mathbf{f}_i(y)) \\ \frac{\partial \Lambda(\mathbf{w}, \alpha)}{\partial \mathbf{w}} = 0 &\quad \Rightarrow \quad \mathbf{w} = \sum_{i,y} \alpha_i(y) (\mathbf{f}_i(y^*) - \mathbf{f}_i(y)) \end{aligned}$$

- So we have the Lagrangian as a function of only  $\alpha$ 's:

$$\min_{\alpha \geq 0} Z(\alpha) = \frac{1}{2} \left\| \sum_{i,y} \alpha_i(y) (\mathbf{f}_i(y^*) - \mathbf{f}_i(y)) \right\|^2 - \sum_{i,y} \alpha_i(y) \ell_i(y)$$



# Back to Learning SVMs

---

- We want to find  $\alpha$  which minimize

$$\min_{\alpha \geq 0} \Lambda(\alpha) = \frac{1}{2} \left\| \sum_{i,y} \alpha_i(y) (f_i(y^i) - f_i(y)) \right\|^2 - \sum_{i,y} \alpha_i(y) \ell_i(y)$$

$$\forall i, \quad \sum_y \alpha_i(y) = C$$



# What are these alphas?

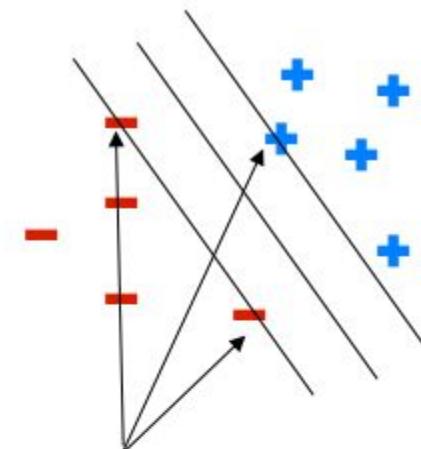
- Each candidate corresponds to a primal constraint

$$\min_{\mathbf{w}, \xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \xi_i$$

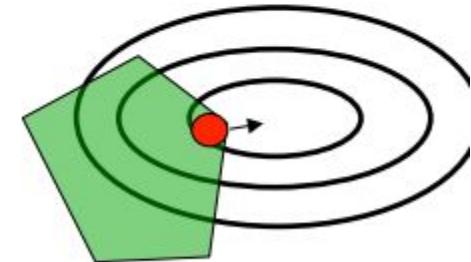
$$\forall i, \mathbf{y} \quad \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) \geq \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) + \ell_i(\mathbf{y}) - \xi_i$$

- In the solution, an  $\alpha_i(\mathbf{y})$  will be:
  - Zero if that constraint is inactive
  - Positive if that constraint is active
  - i.e. positive on the support vectors
- Support vectors contribute to weights:

$$\mathbf{w} = \sum_{i,y} \alpha_i(\mathbf{y}) (\mathbf{f}_i(\mathbf{y}_i^*) - \mathbf{f}_i(\mathbf{y}))$$

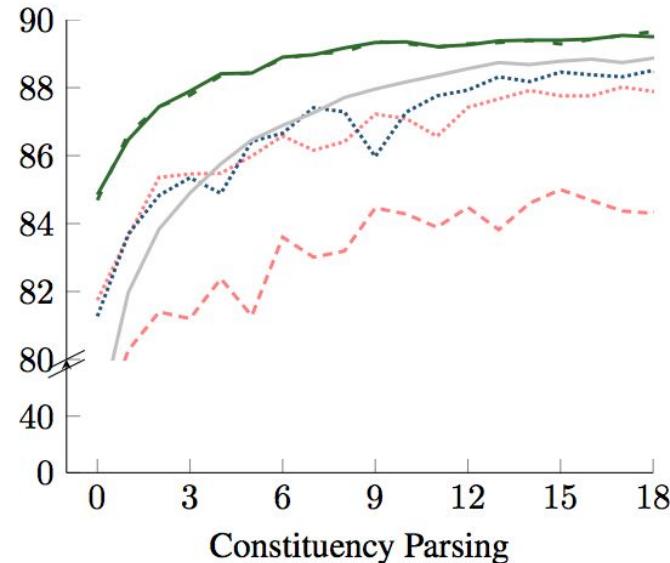


*Support vectors*





# Comparison



Margin	---	Cutting Plane
	....	Online Cutting Plane
	- - -	Online Primal Subgradient & $L_1$
	—	Online Primal Subgradient & $L_2$
Mistake Driven	---	Averaged Perceptron
	....	MIRA
	- - -	Averaged MIRA (MST built-in)
Llhood	—	Stochastic Gradient Descent



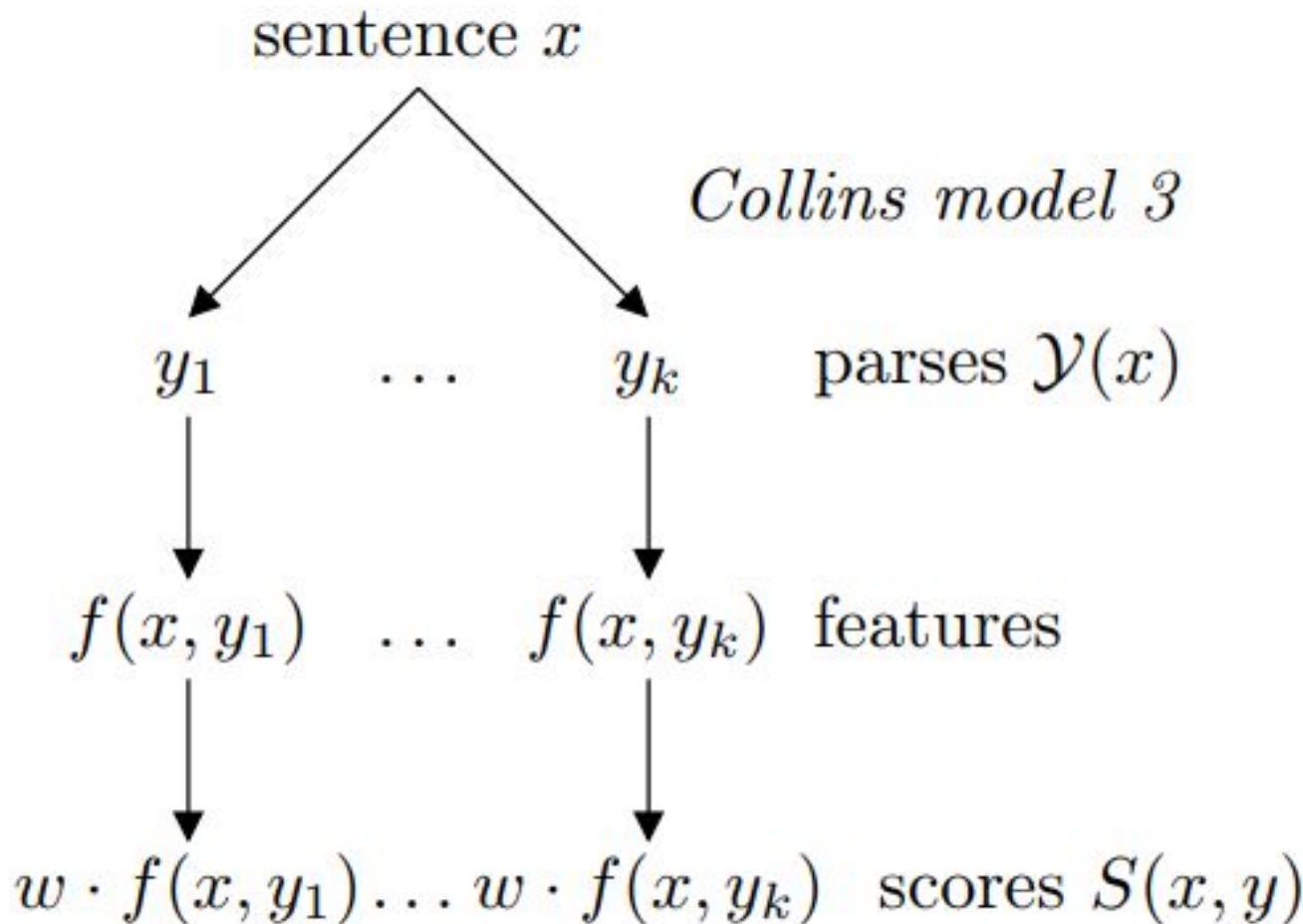
# To summarize

---

- Can solve Structural versions of Max-Ent and SVMs
  - our feature model factors into reasonably local, non-overlapping structures (why?)
- Issues?
  - Limited Scope of Features



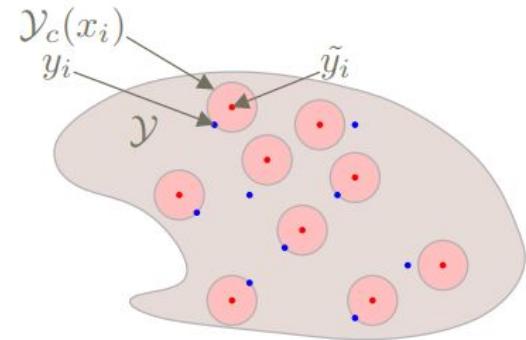
# Reranking





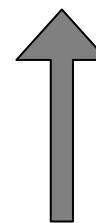
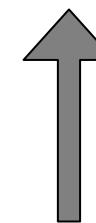
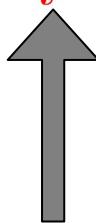
# Training the reranker

- Training Data:  $((x_1, y_1), \dots, (x_n, y_n))$
- Generate candidate parses for each  $x$



- Loss function:

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_i \left( \max_{\mathbf{y}} (\mathbf{w}^\top \mathbf{f}_i(\mathbf{y}) + \ell_i(\mathbf{y})) - \mathbf{w}^\top \mathbf{f}_i(\mathbf{y}_i^*) \right)$$





# Baseline and Oracle Results

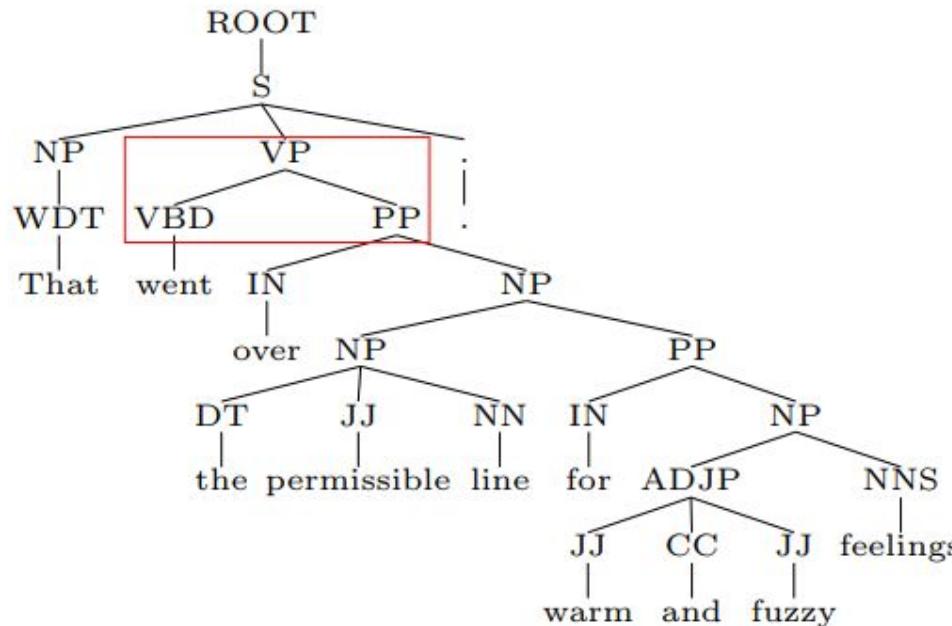
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- Training corpus: 36,112 Penn treebank trees, development corpus 3,720 trees from sections 2-21
  - Collins Model 2 parser failed to produce a parse on 115 sentences
  - Average  $|\mathcal{Y}(x)| = 36.1$
  - Model 2  $f$ -score = 0.882 (picking parse with highest Model 2 probability)
  - Oracle (maximum possible)  $f$ -score = 0.953  
(i.e., evaluate  $f$ -score of closest parses  $\tilde{y}_i$ )
- ⇒ Oracle (maximum possible) error reduction 0.601



# Experiment 1: Only “old” features

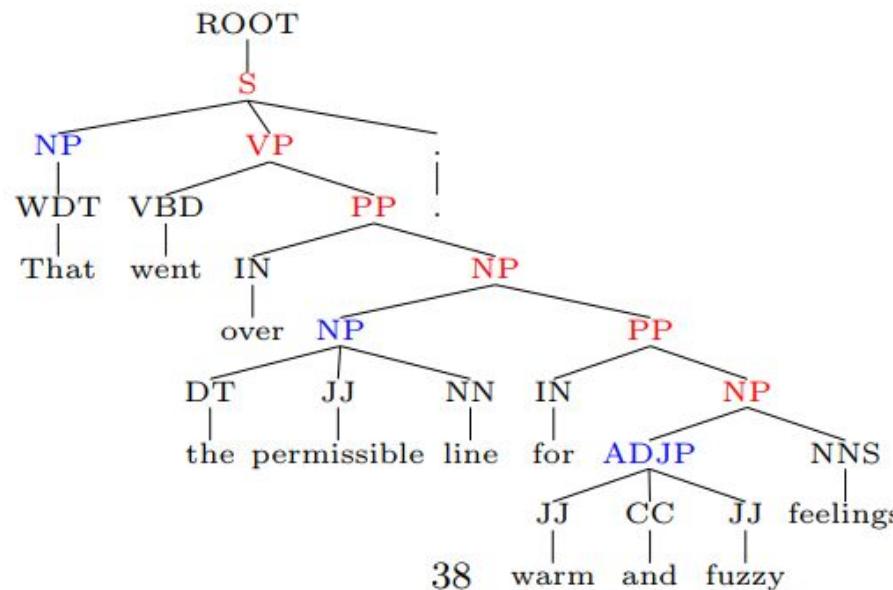
- Features: (1) *log Model 2 probability*, (9717) local tree features
  - Model 2 already conditions on local trees!
  - Feature selection: features must vary on 5 or more sentences
  - Results:  $f$ -score = 0.886;  $\approx 4\%$  error reduction
- ⇒ *discriminative training alone can improve accuracy*





# Right Branching Bias

- The RightBranch feature's value is the number of nodes on the right-most branch (ignoring punctuation)
- Reflects the tendency toward right branching
- LogProb + RightBranch:  $f$ -score = 0.884 (probably significant)
- LogProb + RightBranch + Rule:  $f$ -score = 0.889





# Other Features

---

- Heaviness
  - What is the span of a rule
- Neighbors of a span
- Span shape
- Ngram Features
- Probability of the parse tree
- ...



# Results with all the features

---

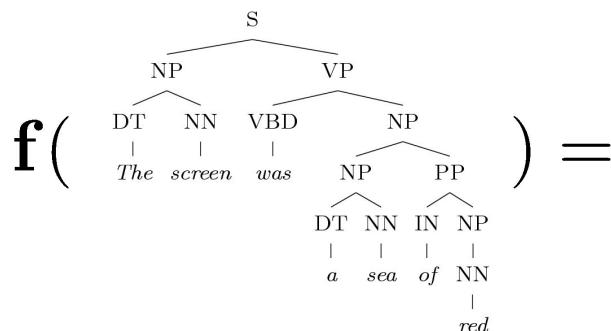
- Features must vary on parses of at least 5 sentences in training data
- In this experiment, 692,708 features
- regularization term:  $4 \sum_j |w_j|^2$
- dev set results: *f-score* = 0.904 (20% error reduction)



# Reranking

- Advantages:

- Directly reduce to non-structured case
- No locality restriction on features



- Disadvantages:

- Stuck with errors of baseline parser
- Baseline system must produce n-best lists
- But, feedback is possible [McCloskey, Charniak, Johnson 2006]
- But, a reranker (almost) never performs worse than a generative parser, and in practice performs substantially better.



# Reranking in other settings

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- Speech recognition
  - Take  $x$  to be the acoustic signal,  $\mathcal{Y}(x)$  all strings in recognizer lattice for  $x$
  - Training data:  $D = ((y_1, x_1), \dots, (y_n, x_n))$ , where  $y_i$  is correct transcript for  $x_i$
  - Features could be  $n$ -grams, log parser prob, cache features
- Machine translation
  - Take  $x$  to be input language string,  $\mathcal{Y}(x)$  a set of target language strings (e.g., generated by an IBM-style model)
  - Training data:  $D = ((y_1, x_1), \dots, (y_n, x_n))$ , where  $y_i$  is correct translation of  $x_i$
  - Features could be  $n$ -grams of target language strings, word and phrase correspondences, ...