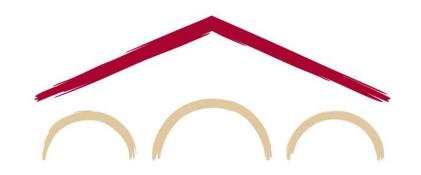
Natural Language Processing with Deep Learning CS224N/Ling284



John Hewitt

Lecture 8: Self-Attention and Transformers

Adapted from slides by Anna Goldie, John Hewitt

Lecture Plan

- 1. From recurrence (RNN) to attention-based NLP models
- 2. The Transformer model
- 3. Great results with Transformers
- 4. Drawbacks and variants of Transformers

Reminders:

Extra details are in the brand new lecture notes, wooooo!

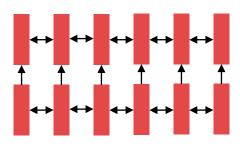
Assignment 4 due a week from today!

Final project proposal out tonight, due Tuesday, Feb 14 at 4:30PM PST!

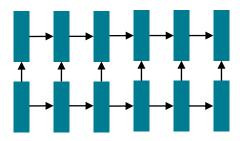
Please try to hand in the project proposal on time; we want to get you feedback quickly!

As of last lecture: recurrent models for (most) NLP!

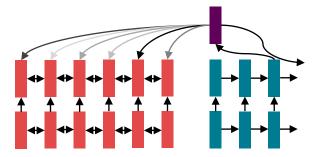
 Circa 2016, the de facto strategy in NLP is to encode sentences with a bidirectional LSTM: (for example, the source sentence in a translation)



 Define your output (parse, sentence, summary) as a sequence, and use an LSTM to generate it.

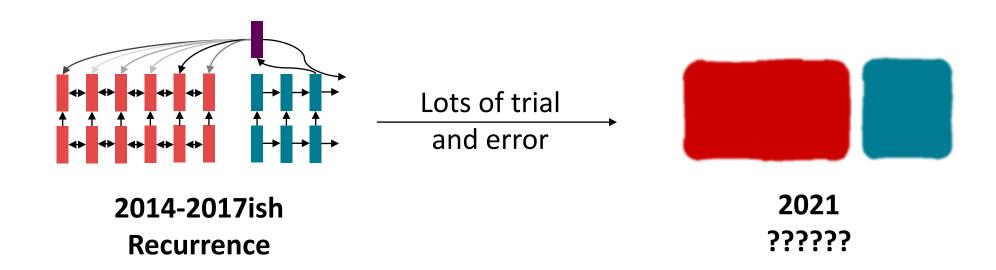


 Use attention to allow flexible access to memory



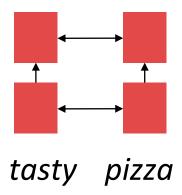
Today: Same goals, different building blocks

- Last week, we learned about sequence-to-sequence problems and encoder-decoder models.
- Today, we're not trying to motivate entirely new ways of looking at problems (like Machine Translation)
- Instead, we're trying to find the best building blocks to plug into our models and enable broad progress.

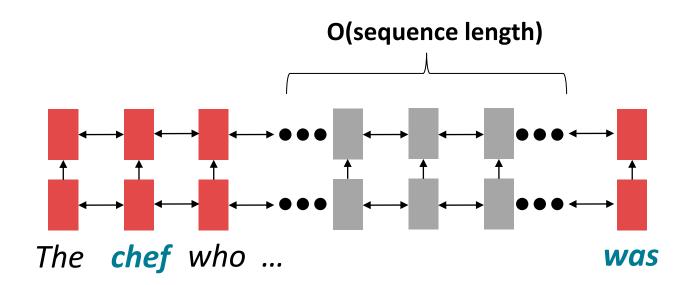


Issues with recurrent models: Linear interaction distance

- RNNs are unrolled "left-to-right".
- This encodes linear locality: a useful heuristic!
 - Nearby words often affect each other's meanings

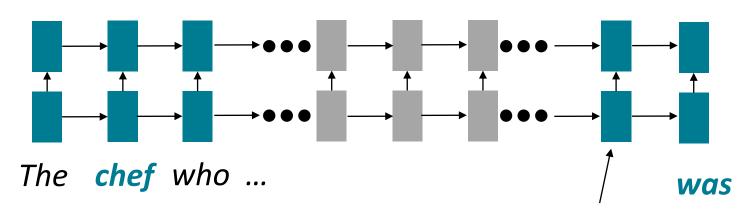


 Problem: RNNs take O(sequence length) steps for distant word pairs to interact.



Issues with recurrent models: Linear interaction distance

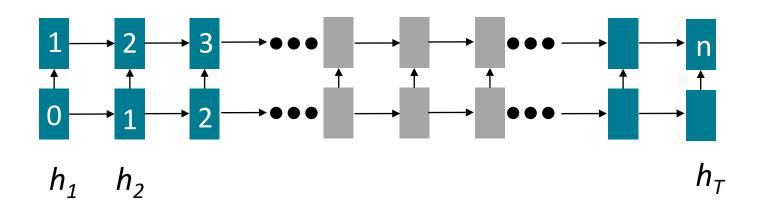
- O(sequence length) steps for distant word pairs to interact means:
 - Hard to learn long-distance dependencies (because gradient problems!)
 - Linear order of words is "baked in"; we already know linear order isn't the right way to think about sentences...



Info of *chef* has gone through O(sequence length) many layers!

Issues with recurrent models: Lack of parallelizability

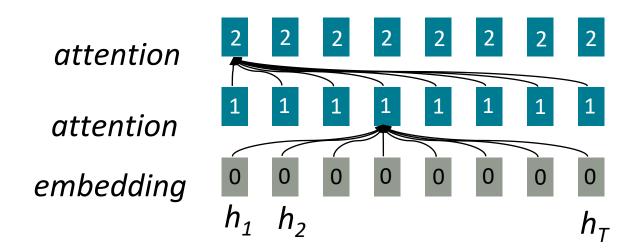
- Forward and backward passes have O(sequence length)
 unparallelizable operations
 - GPUs can perform a bunch of independent computations at once!
 - But future RNN hidden states can't be computed in full before past RNN hidden states have been computed
 - Inhibits training on very large datasets!



Numbers indicate min # of steps before a state can be computed

If not recurrence, then what? How about attention?

- Attention treats each word's representation as a query to access and incorporate information from a set of values.
 - We saw attention from the **decoder** to the **encoder**; today we'll think about attention **within a single sentence**.
- Number of unparallelizable operations does not increase with sequence length.
- Maximum interaction distance: O(1), since all words interact at every layer!



All words attend to all words in previous layer; most arrows here are omitted

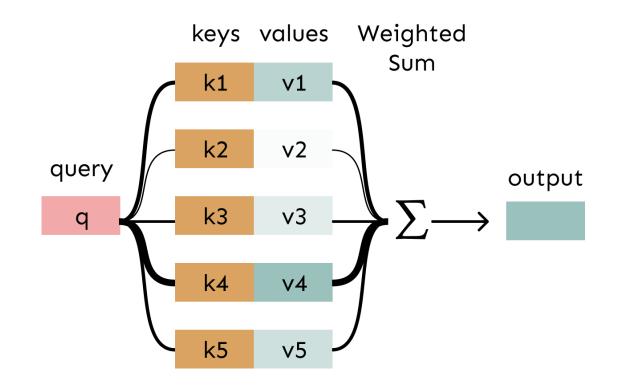
Attention as a soft, averaging lookup table

We can think of attention as performing fuzzy lookup in a key-value store.

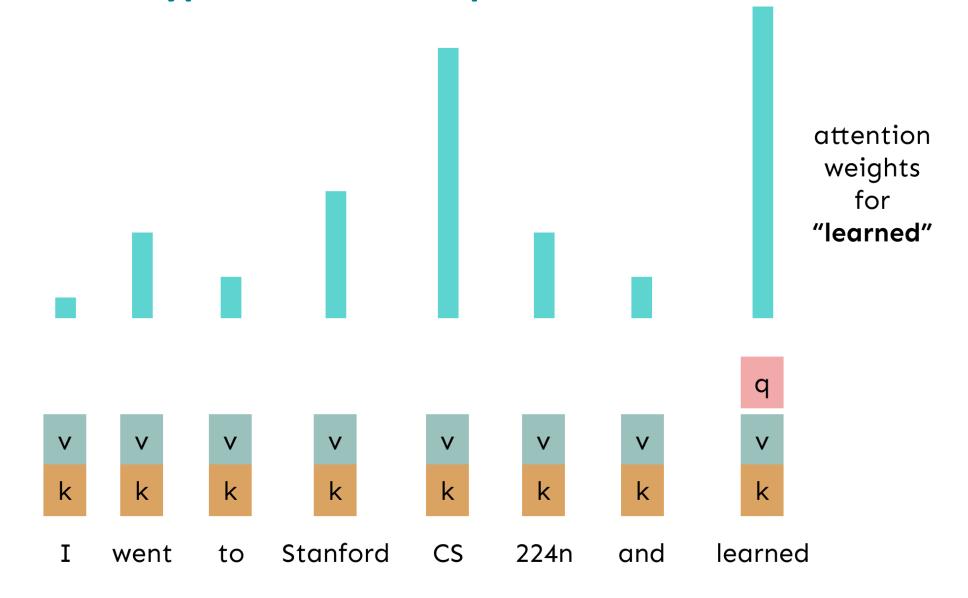
In a **lookup table**, we have a table of **keys** that map to **values**. The **query** matches one of the keys, returning its value.

keys values $\begin{array}{c|cccc}
a & v1 \\
\hline
 & v2 \\
\hline
 & c & v3 \\
\hline
 & d & v4 & v4 \\
\hline
 & e & v5 \\
\end{array}$

In **attention**, the **query** matches all **keys** *softly*, to a weight between 0 and 1. The keys' **values** are multiplied by the weights and summed.



Self-Attention Hypothetical Example



Self-Attention: keys, queries, values from the same sequence

Let $\mathbf{w}_{1:n}$ be a sequence of words in vocabulary V, like Zuko made his uncle tea.

For each w_i , let $x_i = Ew_i$, where $E \in \mathbb{R}^{d \times |V|}$ is an embedding matrix.

1. Transform each word embedding with weight matrices Q, K, V, each in $\mathbb{R}^{d\times d}$

$$q_i = Qx_i$$
 (queries) $k_i = Kx_i$ (keys) $v_i = Vx_i$ (values)

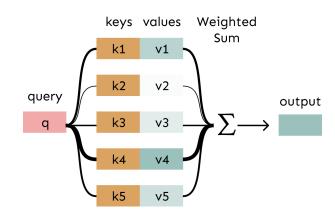
2. Compute pairwise similarities between keys and queries; normalize with softmax

$$e_{ij} = q_i^T k_j$$

$$\alpha_{ij} = \frac{\exp(e_{ij})}{\sum_{j'} \exp(e_{ij'})}$$

3. Compute output for each word as weighted sum of values

$$o_i = \sum_i \alpha_{ij} v_i$$



Barriers and solutions for Self-Attention as a building block

Barriers

Solutions

 Doesn't have an inherent notion of order!

Fixing the first self-attention problem: sequence order

- Since self-attention doesn't build in order information, we need to encode the order of the sentence in our keys, queries, and values.
- Consider representing each sequence index as a vector

$$p_i \in \mathbb{R}^d$$
, for $i \in \{1,2,...,n\}$ are position vectors

- Don't worry about what the p_i are made of yet!
- Easy to incorporate this info into our self-attention block: just add the $m{p}_i$ to our inputs!
- Recall that x_i is the embedding of the word at index i. The positioned embedding is:

$$\widetilde{\boldsymbol{x}}_i = \boldsymbol{x}_i + \boldsymbol{p}_i$$

In deep self-attention networks, we do this at the first layer! You could concatenate them as well, but people mostly just add...

Position representation vectors through sinusoids

• Sinusoidal position representations: concatenate sinusoidal functions of varying periods:

$$p_i = \begin{bmatrix} \sin(i/10000^{2*1/d}) \\ \cos(i/10000^{2*1/d}) \\ \vdots \\ \sin(i/10000^{2*\frac{d}{2}/d}) \\ \cos(i/10000^{2*\frac{d}{2}/d}) \end{bmatrix}$$
 is since the sequence of the se

- Pros:
 - Periodicity indicates that maybe "absolute position" isn't as important
 - Maybe can extrapolate to longer sequences as periods restart!
- Cons:
 - Not learnable; also the extrapolation doesn't really work!

Position representation vectors learned from scratch

• Learned absolute position representations: Let all p_i be learnable parameters! Learn a matrix $p \in \mathbb{R}^{d \times n}$, and let each p_i be a column of that matrix!

- Pros:
 - Flexibility: each position gets to be learned to fit the data
- Cons:
 - Definitely can't extrapolate to indices outside 1, ..., n.
- Most systems use this!
- Sometimes people try more flexible representations of position:
 - Relative linear position attention [Shaw et al., 2018]
 - Dependency syntax-based position [Wang et al., 2019]

Barriers and solutions for Self-Attention as a building block

Barriers

- Doesn't have an inherent notion of order!

Solutions

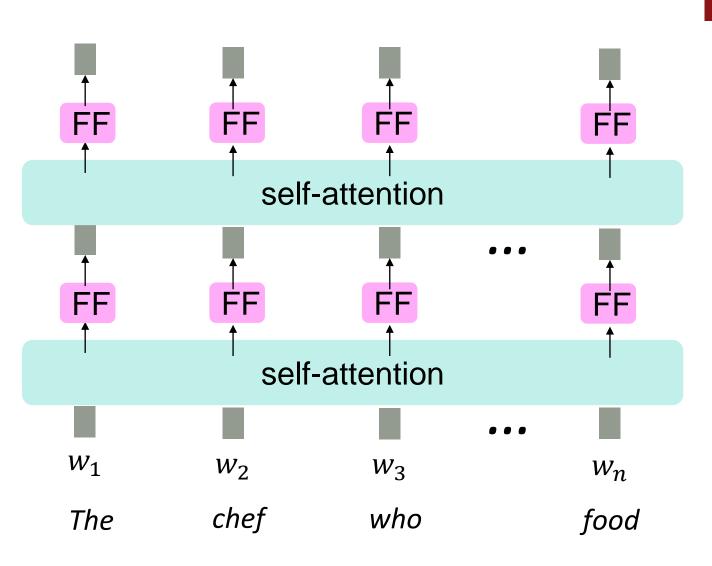
 Add position representations to the inputs

Adding nonlinearities in self-attention

- Note that there are no elementwise nonlinearities in self-attention; stacking more self-attention layers just re-averages value vectors (Why? Look at the notes!)
- Easy fix: add a feed-forward network to post-process each output vector.

$$m_i = MLP(\text{output}_i)$$

= $W_2 * \text{ReLU}(W_1 \text{ output}_i + b_1) + b_2$



Intuition: the FF network processes the result of attention

Barriers and solutions for Self-Attention as a building block

Barriers

- Doesn't have an inherent notion of order!
- No nonlinearities for deep learning magic! It's all just weighted averages
- Need to ensure we don't "look at the future" when predicting a sequence
 - Like in machine translation
 - Or language modeling

Solutions

- Add position representations to the inputs
- Easy fix: apply the same feedforward network to each selfattention output.

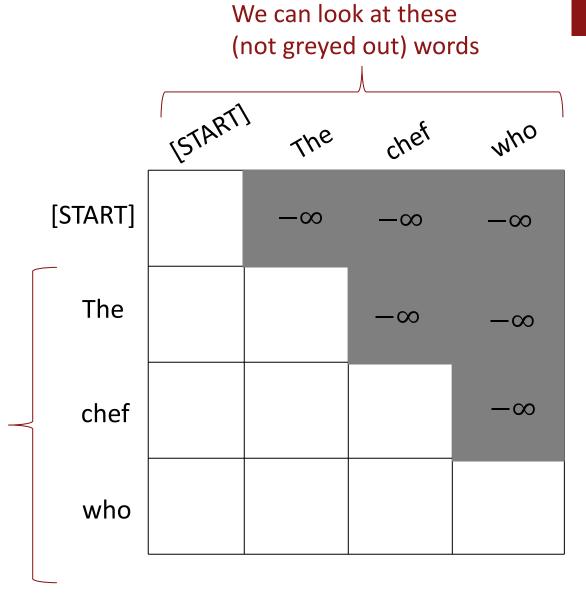
Masking the future in self-attention

 To use self-attention in decoders, we need to ensure we can't peek at the future.

 At every timestep, we could change the set of keys and queries to include only past words. (Inefficient!)

 To enable parallelization, we mask out attention to future words by setting attention scores to -∞.

For encoding these words $e_{ij} = \begin{cases} q_i^{\mathsf{T}} k_j, j \le i \\ -\infty, i > i \end{cases}$



Barriers and solutions for Self-Attention as a building block

Barriers

- Doesn't have an inherent notion of order!
- No nonlinearities for deep learning magic! It's all just weighted averages
- Need to ensure we don't "look at the future" when predicting a sequence
 - Like in machine translation
 - Or language modeling

Solutions

- Add position representations to the inputs
- Easy fix: apply the same feedforward network to each selfattention output.
- Mask out the future by artificially setting attention weights to 0!

Necessities for a self-attention building block:

Self-attention:

the basis of the method.

Position representations:

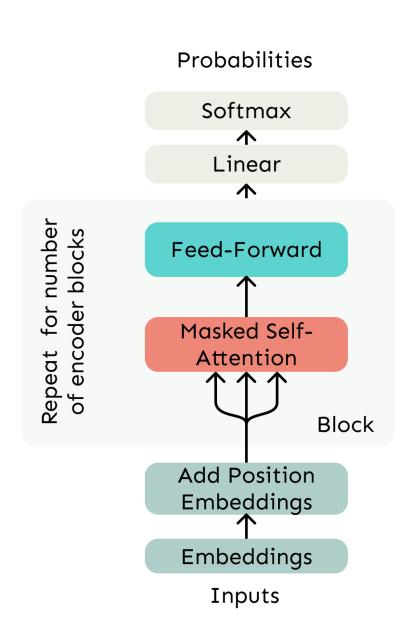
• Specify the sequence order, since self-attention is an unordered function of its inputs.

Nonlinearities:

- At the output of the self-attention block
- Frequently implemented as a simple feedforward network.

Masking:

- In order to parallelize operations while not looking at the future.
- Keeps information about the future from "leaking" to the past.

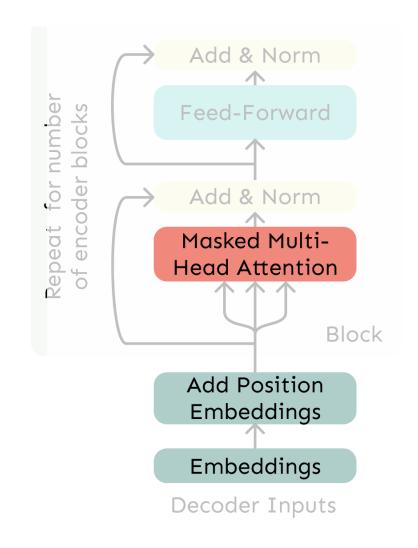


Outline

- 1. From recurrence (RNN) to attention-based NLP models
- 2. The Transformer model
- 3. Great results with Transformers
- 4. Drawbacks and variants of Transformers

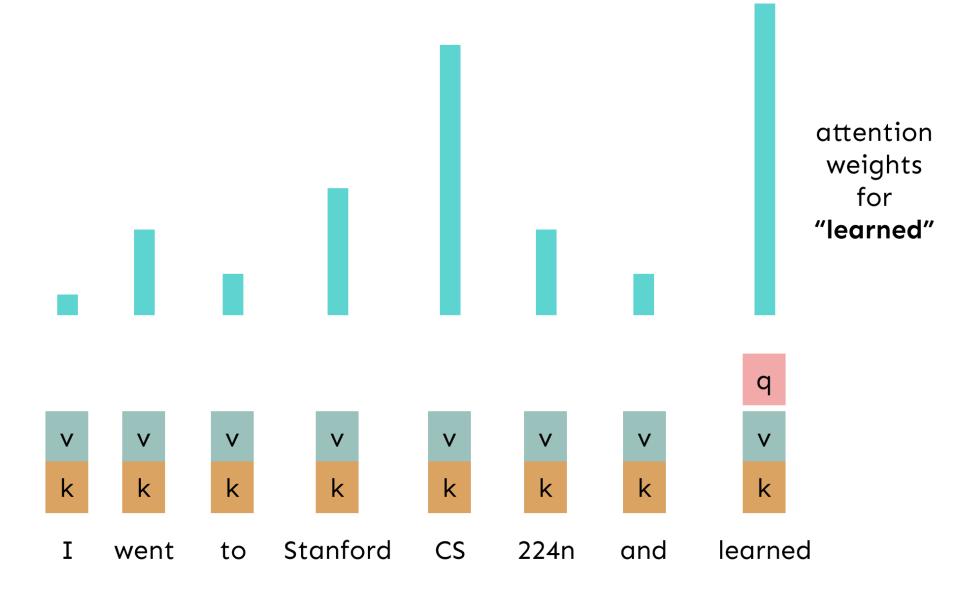
The Transformer Decoder

- A Transformer decoder is how we'll build systems like language models.
- It's a lot like our minimal selfattention architecture, but with a few more components.
- The embeddings and position embeddings are identical.
- We'll next replace our selfattention with multi-head selfattention.

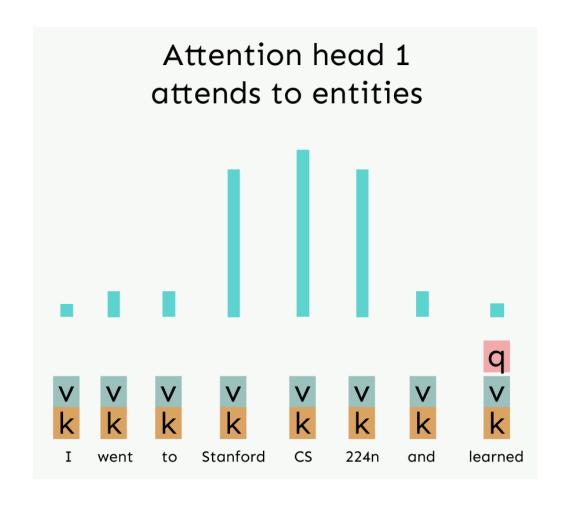


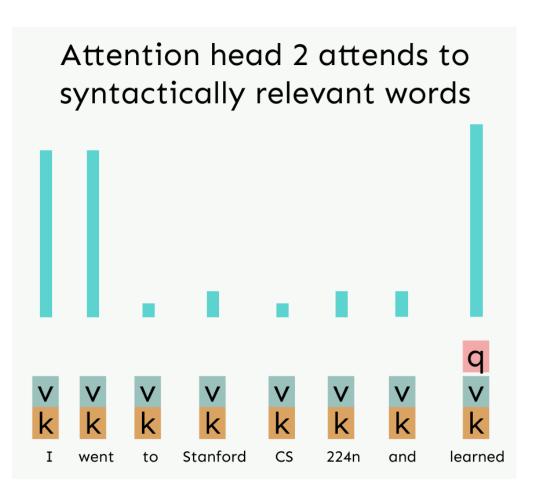
Transformer Decoder

Recall the Self-Attention Hypothetical Example



Hypothetical Example of Multi-Head Attention





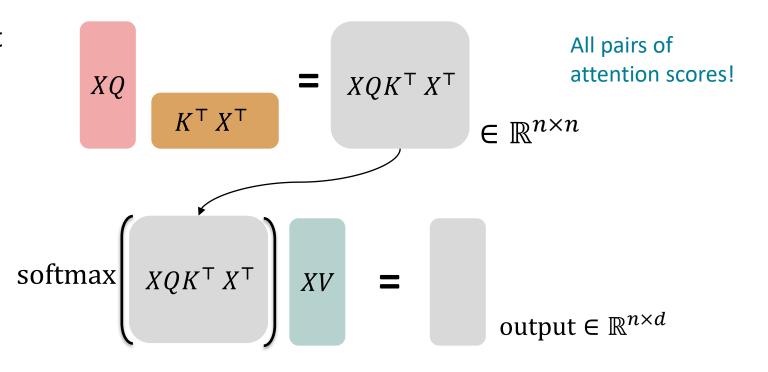
I went to Stanford CS 224n and learned

Sequence-Stacked form of Attention

- Let's look at how key-query-value attention is computed, in matrices.
 - Let $X = [x_1; ...; x_n] \in \mathbb{R}^{n \times d}$ be the concatenation of input vectors.
 - First, note that $XK \in \mathbb{R}^{n \times d}$, $XQ \in \mathbb{R}^{n \times d}$, $XV \in \mathbb{R}^{n \times d}$.
 - The output is defined as output = $\operatorname{softmax}(XQ(XK)^{\top})XV \in \in \mathbb{R}^{n \times d}$.

First, take the query-key dot products in one matrix multiplication: $XQ(XK)^{T}$

Next, softmax, and compute the weighted average with another matrix multiplication.



Multi-headed attention

- What if we want to look in multiple places in the sentence at once?
 - For word i, self-attention "looks" where $x_i^T Q^T K x_j$ is high, but maybe we want to focus on different j for different reasons?
- We'll define multiple attention "heads" through multiple Q,K,V matrices
- Let, $Q_{\ell}, K_{\ell}, V_{\ell} \in \mathbb{R}^{d \times \frac{d}{h}}$, where h is the number of attention heads, and ℓ ranges from 1 to h.
- Each attention head performs attention independently:
 - output_{ℓ} = softmax $(XQ_{\ell}K_{\ell}^{\mathsf{T}}X^{\mathsf{T}})*XV_{\ell}$, where output_{ℓ} $\in \mathbb{R}^{d/h}$
- Then the outputs of all the heads are combined!
 - output = [output₁; ...; output_h]Y, where $Y \in \mathbb{R}^{d \times d}$
- Each head gets to "look" at different things, and construct value vectors differently.

Multi-head self-attention is computationally efficient

- Even though we compute h many attention heads, it's not really more costly.
 - We compute $XQ \in \mathbb{R}^{n \times d}$, and then reshape to $\mathbb{R}^{n \times h \times d/h}$. (Likewise for XK, XV.)
 - Then we transpose to $\mathbb{R}^{h \times n \times d/h}$; now the head axis is like a batch axis.
 - Almost everything else is identical, and the matrices are the same sizes.

First, take the query-key dot products in one matrix multiplication: $XQ(XK)^{T}$

 $= XQK^{\mathsf{T}}X^{\mathsf{T}}$ $= XQK^{\mathsf{T}}X^{\mathsf{T}}$ $\in \mathbb{R}^{3 \times n \times n}$

Next, softmax, and compute the weighted average with another matrix multiplication.

output $\in \mathbb{R}^{n \times d}$

Scaled Dot Product [Vaswani et al., 2017]

- "Scaled Dot Product" attention aids in training.
- When dimensionality d becomes large, dot products between vectors tend to become large.
 - Because of this, inputs to the softmax function can be large, making the gradients small.
- Instead of the self-attention function we've seen:

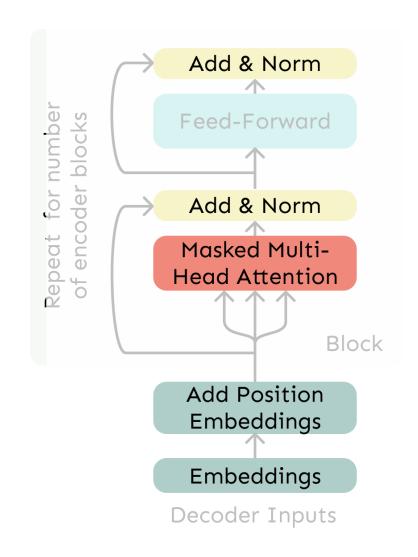
$$\operatorname{output}_{\ell} = \operatorname{softmax}(XQ_{\ell}K_{\ell}^{\mathsf{T}}X^{\mathsf{T}}) * XV_{\ell}$$

• We divide the attention scores by $\sqrt{d/h}$, to stop the scores from becoming large just as a function of d/h (The dimensionality divided by the number of heads.)

output_{$$\ell$$} = softmax $\left(\frac{XQ_{\ell}K_{\ell}^{\mathsf{T}}X^{\mathsf{T}}}{\sqrt{d/h}}\right) * XV_{\ell}$

The Transformer Decoder

- Now that we've replaced selfattention with multi-head selfattention, we'll go through two optimization tricks that end up being:
 - Residual Connections
 - Layer Normalization
- In most Transformer diagrams, these are often written together as "Add & Norm"



Transformer Decoder

The Transformer Encoder: Residual connections [He et al., 2016]

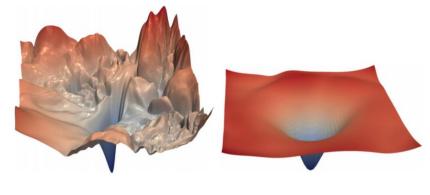
- Residual connections are a trick to help models train better.
 - Instead of $X^{(i)} = \text{Layer}(X^{(i-1)})$ (where i represents the layer)

$$X^{(i-1)}$$
 Layer $X^{(i)}$

• We let $X^{(i)} = X^{(i-1)} + \text{Layer}(X^{(i-1)})$ (so we only have to learn "the residual" from the previous layer)



- Gradient is great through the residual connection; it's 1!
- Bias towards the identity function!



[no residuals]

[residuals]

[Loss landscape visualization, Li et al., 2018, on a ResNet]

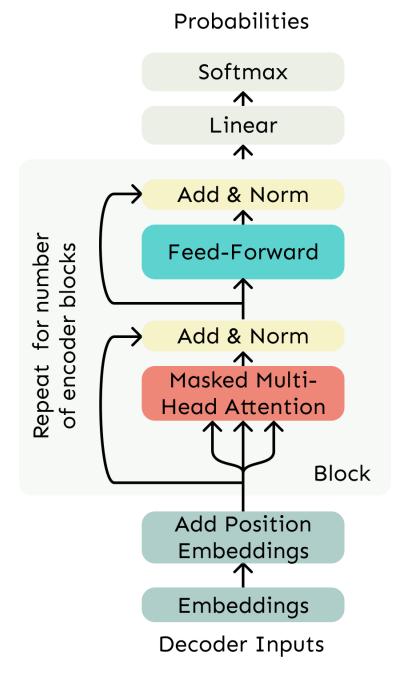
The Transformer Encoder: Layer normalization [Ba et al., 2016]

- Layer normalization is a trick to help models train faster.
- Idea: cut down on uninformative variation in hidden vector values by normalizing to unit mean and standard deviation within each layer.
 - LayerNorm's success may be due to its normalizing gradients [Xu et al., 2019]
- Let $x \in \mathbb{R}^d$ be an individual (word) vector in the model.
- Let $\mu = \sum_{i=1}^{d} x_i$; this is the mean; $\mu \in \mathbb{R}$.
- Let $\sigma = \sqrt{\frac{1}{d} \sum_{j=1}^{d} (x_j \mu)^2}$; this is the standard deviation; $\sigma \in \mathbb{R}$.
- Let $\gamma \in \mathbb{R}^d$ and $\beta \in \mathbb{R}^d$ be learned "gain" and "bias" parameters. (Can omit!)
- Then layer normalization computes:

$$\text{Output} = \frac{x - \mu}{\sqrt{\sigma} + \epsilon} * \gamma + \beta$$
 Normalize by scalar mean and variance Modulate by learned elementwise gain and bias

The Transformer Decoder

- The Transformer Decoder is a stack of Transformer Decoder Blocks.
- Each Block consists of:
 - Self-attention
 - Add & Norm
 - Feed-Forward
 - Add & Norm
- That's it! We've gone through the Transformer Decoder.



The Transformer Encoder

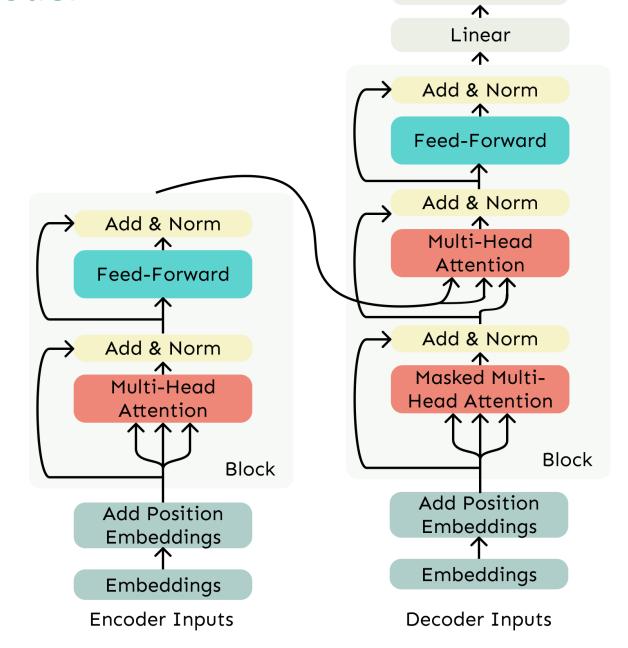
- The Transformer Decoder constrains to unidirectional context, as for language models.
- What if we want bidirectional context, like in a bidirectional RNN?
- This is the Transformer
 Encoder. The only difference is
 that we remove the masking
 in the self-attention.

Softmax Linear 小 Add & Norm for number blocks Feed-Forward encoder Add & Norm Repeat Multi-Head Attention oę Block Add Position Embeddings **Embeddings Decoder Inputs**

Probabilities

The Transformer Encoder-Decoder

- Recall that in machine translation, we processed the source sentence with a bidirectional model and generated the target with a unidirectional model.
- For this kind of seq2seq format, we often use a Transformer Encoder-Decoder.
- We use a normal Transformer Encoder.
- Our Transformer Decoder is modified to perform crossattention to the output of the Encoder.

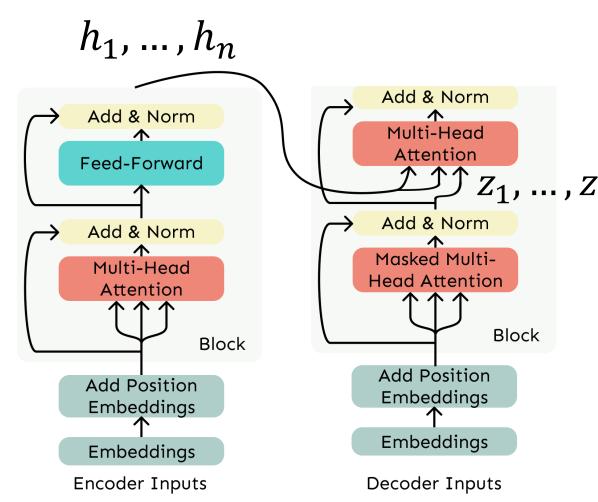


Probabilities

Softmax

Cross-attention (details)

- We saw that self-attention is when keys, queries, and values come from the same source.
- In the decoder, we have attention that looks more like what we saw last week.
- Let $h_1, ..., h_n$ be **output** vectors **from** the Transformer **encoder**; $x_i \in \mathbb{R}^d$
- Let $z_1, ..., z_n$ be input vectors from the Transformer **decoder**, $z_i \in \mathbb{R}^d$
- Then keys and values are drawn from the encoder (like a memory):
 - $k_i = Kh_i$, $v_i = Vh_i$.
- And the queries are drawn from the decoder, $q_i = Qz_i$.



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Great Results with Transformers

First, Machine Translation from the original Transformers paper!

Model	BL	EU	Training Co	Training Cost (FLOPs)		
Model	EN-DE	EN-FR	EN-DE	EN-FR		
ByteNet [18]	23.75					
Deep-Att + PosUnk [39]		39.2		$1.0 \cdot 10^{20}$		
GNMT + RL [38]	24.6	39.92	$2.3 \cdot 10^{19}$	$1.4 \cdot 10^{20}$		
ConvS2S [9]	25.16	40.46	$9.6 \cdot 10^{18}$	$1.5 \cdot 10^{20}$		
MoE [32]	26.03	40.56	$2.0 \cdot 10^{19}$	$1.2 \cdot 10^{20}$		
Deep-Att + PosUnk Ensemble [39]		40.4		$8.0 \cdot 10^{20}$		
GNMT + RL Ensemble [38]	26.30	41.16	$1.8 \cdot 10^{20}$	$1.1\cdot 10^{21}$		
ConvS2S Ensemble [9]	26.36	41.29	$7.7\cdot10^{19}$	$1.2 \cdot 10^{21}$		

Great Results with Transformers

Next, document generation!

	Model	Test perplexity	ROUGE-L
	seq2seq-attention, $L = 500$	5.04952	12.7
7	Transformer-ED, $L = 500$	2.46645	34.2
	Transformer-D, $L = 4000$	2.22216	33.6
	Transformer-DMCA, no MoE-layer, $L = 11000$	2.05159	36.2
/	Transformer-DMCA, MoE-128, $L = 11000$	1.92871	37.9
	Transformer-DMCA, MoE-256, $L = 7500$	1.90325	38.8
		<u> </u>	

The old standard

Transformers all the way down.

Great Results with Transformers

Before too long, most Transformers results also included **pretraining**, a method we'll go over on Thursday.

Transformers' parallelizability allows for efficient pretraining, and have made them the de-facto standard.

On this popular aggregate benchmark, for example:



All top models are Transformer (and pretraining)-based.

	Rank	(Name	Model	URL	Score
	1	DeBERTa Team - Microsoft	DeBERTa / TuringNLRv4		90.8
	2	HFL iFLYTEK	MacALBERT + DKM		90.7
+	3	Alibaba DAMO NLP	StructBERT + TAPT	ď	90.6
+	4	PING-AN Omni-Sinitic	ALBERT + DAAF + NAS		90.6
	5	ERNIE Team - Baidu	ERNIE	Z'	90.4
	6	T5 Team - Google	T5	Z'	90.3

More results Thursday when we discuss pretraining.

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What would we like to fix about the Transformer?

- Quadratic compute in self-attention (today):
 - Computing all pairs of interactions means our computation grows quadratically with the sequence length!
 - For recurrent models, it only grew linearly!
- Position representations:
 - Are simple absolute indices the best we can do to represent position?
 - Relative linear position attention [Shaw et al., 2018]
 - Dependency syntax-based position [Wang et al., 2019]

Quadratic computation as a function of sequence length

- One of the benefits of self-attention over recurrence was that it's highly parallelizable.
- However, its total number of operations grows as $O(n^2d)$, where n is the sequence length, and d is the dimensionality.

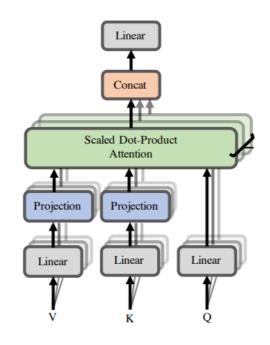


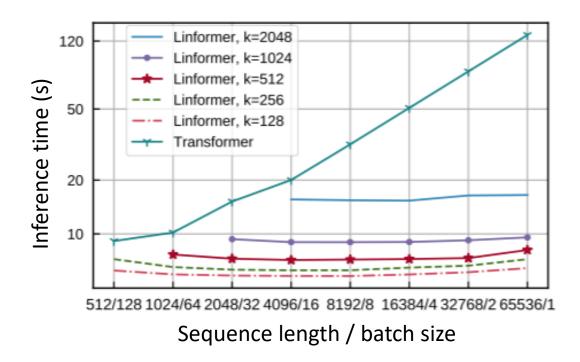
- Think of d as around 1,000 (though for large language models it's much larger!).
 - So, for a single (shortish) sentence, $n \le 30$; $n^2 \le 900$.
 - In practice, we set a bound like n = 512.
 - But what if we'd like $n \ge 50,000$? For example, to work on long documents?

Work on improving on quadratic self-attention cost

- Considerable recent work has gone into the question, Can we build models like Transformers without paying the $O(T^2)$ all-pairs self-attention cost?
- For example, Linformer [Wang et al., 2020]

Key idea: map the sequence length dimension to a lower-dimensional space for values, keys





Do we even need to remove the quadratic cost of attention?

- As Transformers grow larger, a larger and larger percent of compute is outside the self-attention portion, despit the quadratic cost.
- In practice, almost no large Transformer language models use anything but the quadratic cost attention we've presented here.
 - The cheaper methods tend not to work as well at scale.
- So, is there no point in trying to design cheaper alternatives to self-attention?
- Or would we unlock much better models with much longer contexts (>100k tokens?) if we were to do it right?

Do Transformer Modifications Transfer?

 "Surprisingly, we find that most modifications do not meaningfully improve performance."

Model	Params	Ops	Step/s	Early loss	Final loss	SGLUE	XSum	WebQ	WMT EnDe
Vanilla Transformer	223M	11.1T	3.50	2.182 ± 0.005	1.838	71.66	17.78	23.02	26.62
GeLU	223M	11.1T	3.58	2.179 ± 0.003	1.838	75.79	17.86	25.13	26.47
Swish	223M	11.1T	3.62	2.186 ± 0.003	1.847	73.77	17.74	24.34	26.75
ELU	223M	11.1T	3.56	2.270 ± 0.007	1.932	67.83	16.73	23.02	26.08
GLU	223M	11.1T	3.59	2.174 ± 0.003	1.814	74.20	17.42	24.34	27.12
GeGLU	223M	11.1T	3.55	2.130 ± 0.006	1.792	75.96	18.27	24.87	26.87
ReGLU	223M	11.1T	3.57	2.145 ± 0.004	1.803	76.17	18.36	24.87	27.02
SeLU	223M	11.1T	3.55	2.315 ± 0.004	1.948	68.76	16.76	22.75	25.99
SwiGLU	223M	11.1T	3.53	2.127 ± 0.003	1.789	76.00	18.20	24.34	27.02
LiGLU	223M	11.1T	3.59	2.149 ± 0.005	1.798	75.34	17.97	24.34	26.53
Sigmoid Softplus	$\frac{223M}{223M}$	$\frac{11.1T}{11.1T}$	3.63	2.291 ± 0.019 2.207 ± 0.011	1.867 1.850	74.31 72.45	17.51 17.65	23.02 24.34	26.30 26.89
RMS Norm	223M	11.1T	3.68	2.167 ± 0.008	1.821	75.45	17.94	24.07	27.14
Rezero Rezero + LaverNorm	$\frac{223M}{223M}$	11.1T 11.1T	3.51	2.262 ± 0.003 2.223 ± 0.006	1.939 1.858	61.69 70.42	15.64 17.58	20.90	26.37 26.29
Rezero + LayerNorm Rezero + RMS Norm	$\frac{223M}{223M}$	11.1T 11.1T	3.26	2.223 ± 0.006 2.221 ± 0.009	1.875	70.42	17.32	23.02	26.29
Fixup	223M	11.1T	2.95	2.382 ± 0.003	2.067	58.56	14.42	23.02	26.31
$24 \text{ layers}, d_{\text{ff}} = 1536, H = 6$	224M	11.1T	3.33	2.200 ± 0.007	1.843	74.89	17.75	25.13	26.89
24 layers, $a_{\text{ff}} = 1536, H = 6$ 18 layers, $d_{\text{ff}} = 2048, H = 8$	223M	11.1T 11.1T	3.38	2.200 ± 0.007 2.185 ± 0.005	1.831	76.45	16.83	24.34	27.10
8 layers, $d_{\text{ff}} = 2048, H = 8$	$\frac{223M}{223M}$	11.1T	3.69	2.183 ± 0.005 2.190 ± 0.005	1.847	74.58	17.69	23.28	26.85
6 layers, $d_{\text{ff}} = 4008, H = 18$ 6 layers, $d_{\text{ff}} = 6144, H = 24$	223M	11.1T	3.70	2.201 ± 0.003	1.857	73.55	17.59	24.60	26.66
Block sharing	65M	11.1T	3.91	2.497 ± 0.037	2.164	64.50	14.53	21.96	25.48
+ Factorized embeddings	45M	9.4T	4.21	2.631 ± 0.007	2.183	60.84	14.00	19.84	25.27
+ Factorized & shared em-	20M	9.1T	4.37	2.907 ± 0.313	2.385	53.95	11.37	19.84	25.19
beddings									
Encoder only block sharing	170M	11.1T	3.68	2.298 ± 0.023	1.929	69.60	16.23	23.02	26.23
Decoder only block sharing	144M	11.1T	3.70	2.352 ± 0.029	2.082	67.93	16.13	23.81	26.08
Factorized Embedding	227M	9.4T	3.80	2.208 ± 0.006	1.855	70.41	15.92	22.75	26.50
Factorized & shared embed-	202M	9.1T	3.92	2.320 ± 0.010	1.952	68.69	16.33	22.22	26.44
dings									
Tied encoder/decoder in-	248M	11.1T	3.55	2.192 ± 0.002	1.840	71.70	17.72	24.34	26.49
put embeddings									
Tied decoder input and out-	248M	11.1T	3.57	2.187 ± 0.007	1.827	74.86	17.74	24.87	26.67
put embeddings	273M	11.1T	3.53	2.195 ± 0.005	1.834	72.99	17.58	23.28	26.48
Untied embeddings Adaptive input embeddings	204M	9.2T	3.55	2.193 ± 0.003 2.250 ± 0.002	1.899	66.57	16.21	24.07	26.48
Adaptive softmax	204M	9.2T	3.60	2.364 ± 0.005	1.982	72.91	16.67	21.16	25.56
Adaptive softmax without	223M	10.8T	3.43	2.229 ± 0.009	1.914	71.82	17.10	23.02	25.72
projection Mixture of softmaxes	232M	16.3T	2.24	2.227 ± 0.017	1.821	76.77	17.62	22.75	26.82
Transparent attention	223M	11.1T	3.33	2.181 ± 0.014	1.874	54.31	10.40	21.16	26.80
Iransparent attention Dynamic convolution	223M 257M	11.1T 11.8T	2.65	2.181 ± 0.014 2.403 ± 0.009	2.047	58.30	12.67	21.16	17.03
Lightweight convolution	224M	10.4T	4.07	2.370 ± 0.009	1.989	63.07	14.86	23.02	24.73
Evolved Transformer	217M	9.9T	3.09	2.220 ± 0.003	1.863	73.67	10.76	24.07	26.58
Synthesizer (dense)	224M	11.4T	3.47	2.334 ± 0.021	1.962	61.03	14.27	16.14	26.63
Synthesizer (dense plus)	243M	12.6T	3.22	2.191 ± 0.010	1.840	73.98	16.96	23.81	26.71
Synthesizer (dense plus al-	243M	12.6T	3.01	2.180 ± 0.007	1.828	74.25	17.02	23.28	26.61
pha)									
Synthesizer (factorized)	207M	10.1T	3.94	2.341 ± 0.017	1.968	62.78	15.39	23.55	26.42
Synthesizer (random)	254M	10.1T	4.08	2.326 ± 0.012	2.009	54.27	10.35	19.56	26.44
Synthesizer (random plus)	292M	12.0T	3.63	2.189 ± 0.004	1.842	73.32	17.04	24.87	26.43
Synthesizer (random plus	292M	12.0T	3.42	2.186 ± 0.007	1.828	75.24	17.08	24.08	26.39
alpha) Universal Transformer	84M	40.0T	0.88	2.406 ± 0.036	2.053	70.13	14.09	19.05	23.91
Universal Transformer Mixture of experts	648M	11.7T	3.20	2.406 ± 0.036 2.148 ± 0.006	1.785	74.55	18.13	24.08	23.91 26.94
Switch Transformer	1100M	11.7T	3.18	2.148 ± 0.000 2.135 ± 0.007	1.758	75.38	18.02	26.19	26.81
Switch Transformer Funnel Transformer	223M	1.9T	4.30	2.133 ± 0.007 2.288 ± 0.008	1.738	67.34	16.26	22.75	23.20
Weighted Transformer	280M	71.0T	0.59	2.378 ± 0.003	1.989	69.04	16.98	23.02	26.30
Product key memory	421M	386.6T	0.25	2.155 ± 0.003	1.798	75.16	17.04	23.55	26.73
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Do Transformer Modifications Transfer Across Implementations and Applications?

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Parting remarks

- Pretraining on Tuesday!
- Good luck on assignment 4!
- Remember to work on your project proposal!