

Deep Learning

Supervised Learning with non-linear models

before: $h_{\theta}(x) = \theta^T \phi(x)$ non-linear in x
Kernel Methods linear in θ

Other non-linear models

eg. $h_{\theta}(x) = \sqrt{\theta_1^2 x + \theta_3 x_4} + \sqrt{\theta_5 x_8}$

dataset $\{(x^{(i)}, y^{(i)})\}_{i=1}^n$ $x^{(i)} \in \mathbb{R}^d$, $y^{(i)} \in \mathbb{R}$
 $h_{\theta}(x) : \mathbb{R}^d \rightarrow \mathbb{R}$

Cost/Loss J^n

$$J^{(i)}(\theta) = (y^{(i)} - h_{\theta}(x^{(i)}))^2 \quad \text{mean-squared loss}$$

Cost J^n for entire dataset

$$J(\theta) = \frac{1}{n} \sum_{i=1}^n J^{(i)}(\theta)$$

Optimization Objective

$$\min_{\theta} J(\theta)$$

Gradient Descent

$$\theta := \theta - \alpha \nabla J(\theta)$$

Stochastic Gradient Descent (SGD)

for $i = 1$ to Niter

Sample j from $\{1 \dots n\}$ uniformly
 $\theta := \theta - \alpha \nabla J^{(j)}(\theta)$

Mini-batch SGD

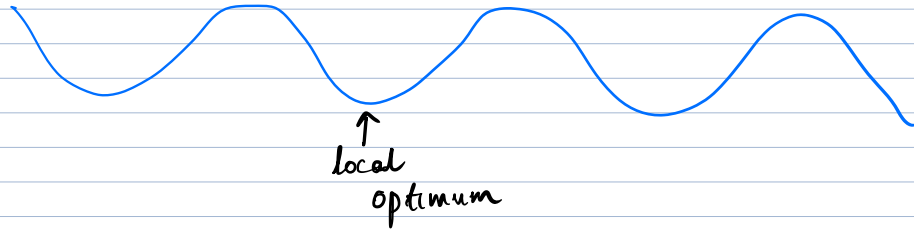
- Computing B gradients $\nabla^{(j_1)}(\theta) \dots \nabla^{(j_B)}(\theta)$
together is faster than individual computation

Mini-batch SGD

for $i = 1$ to N_{iter}

Sample B examples $\{j_1, \dots, j_B\}$ from $\{1, \dots, n\}$ without replacement

$$\theta_i = \theta - \frac{\alpha}{B} \sum_{k=1}^B \nabla J^{(j_k)}(\theta)$$



remaining questions

① how to define $h_\theta(x)$

② how to compute gradient

— Logistic Regression

— Neural Networks

— computational power

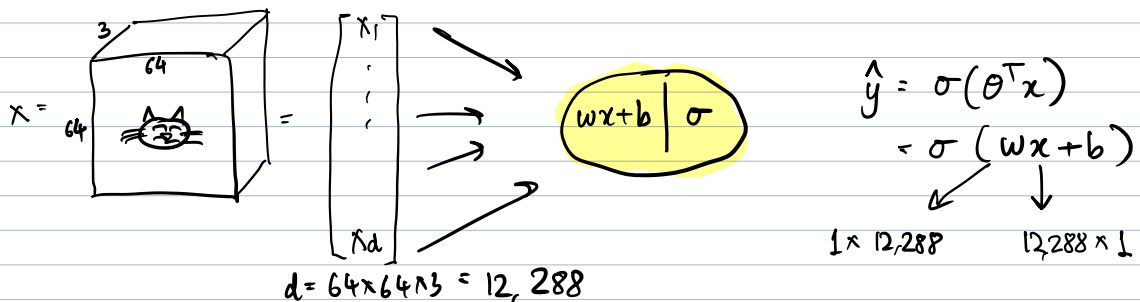
— data available

— algorithms

① Logistic Regression

goal: Find cats in images

$1 \rightarrow$ presence of cat
 $0 \rightarrow$ absence of cat



- i) Initialize w, b

\downarrow \downarrow
weights bias
- ii) Find optimal w, b
- iii) Use $\hat{y} = \sigma(wx + b)$ to predict

$$L = - [y \log \hat{y} + (1-y) \log (1-\hat{y})]$$

$$w := w - \alpha \frac{\partial L}{\partial w}$$

$$b := b - \alpha \frac{\partial L}{\partial b}$$

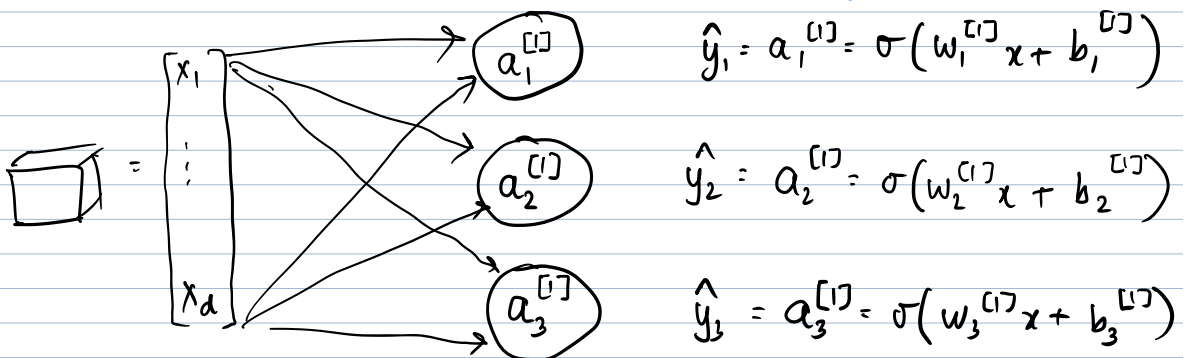
$$\sigma' = \sigma(1-\sigma)$$

parameters = 12,288 + L

neuron = linear + activation

Model = Architecture + parameters
1 neuron w, b

Goal 2.0 : Find cat / lion / iguana in images



square brackets $[] \equiv$ layer

subscripts \equiv identify neuron within layer

$a_2^{[1]} \leftarrow$ 1st layer

$a_2 \leftarrow$ 2nd neuron in 1st layer

param = 3(d+1)

Dataset: images + labels

$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ cat

$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ lion

$\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ iguana

one hot encoding



$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \begin{matrix} \text{cat} \\ \text{non} \end{matrix}$$

Goal 3.0: add constraint: unique animal in image

$$\square = \begin{bmatrix} x_1 \\ \vdots \\ x_d \end{bmatrix}$$

$$\cancel{a_1^{[1]}} \quad z_1^{[1]}$$

$$\cancel{a_2^{[1]}} \quad z_2^{[1]}$$

$$\cancel{a_3^{[1]}} \quad z_3^{[1]}$$

$$e^{z_1^{[1]}} / \sum_{k=1}^3 e^{z_k^{[1]}}$$

$$e^{z_2^{[1]}} / \sum_{k=1}^3 e^{z_k^{[1]}}$$

$$e^{z_3^{[1]}} / \sum_{k=1}^3 e^{z_k^{[1]}}$$

Softmax

$$\hat{y}_1 = \sigma(w_1^{[1]} x + b_1^{[1]})$$

$z_1^{[1]}$

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\# \text{ parameters} = 3(d+1)$$

How to train?

Loss function

$$\mathcal{L}_{3N} = - \sum_{k=1}^3 \left[y_k \log \hat{y}_k + (1-y_k) \log (1-\hat{y}_k) \right]$$

$$\mathcal{L}_{CE} = - \sum_{k=1}^3 y_k \log \hat{y}_k$$

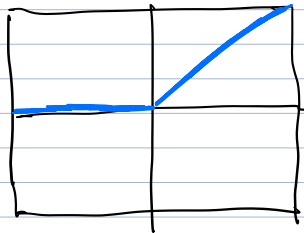
↑
cross
entropy

Qⁿ: Instead of predicting 1/0, predict age of cat?

Options:

- ① Bucket ages, several neurons to predict
- ② Change activation fⁿ

linear f^n : $f(x) = x$ linear regression



$$f(x) = \begin{cases} x & \text{if } x > 0 \\ 0 & \text{if } x \leq 0 \end{cases}$$

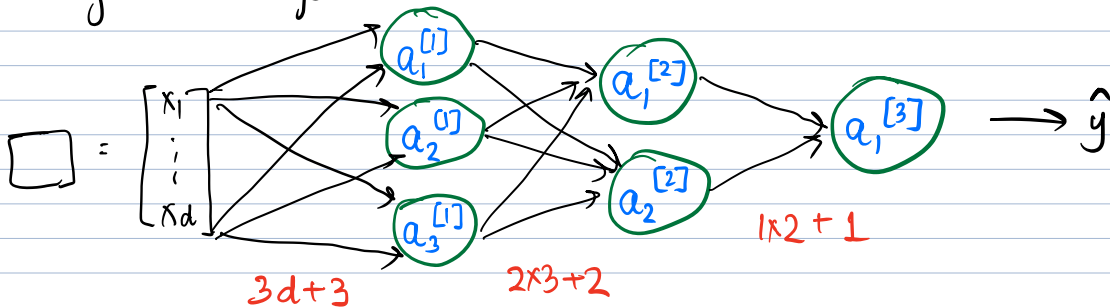
ReLU
Rectified Linear Unit

Modified
loss f^n

$$\|\hat{y} - y\|_1, \quad \|\hat{y} - y\|_2^2$$

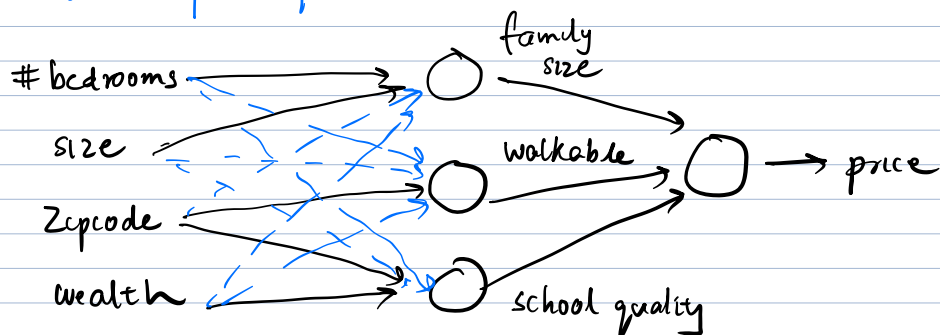
② Neural Networks

goal: image \Rightarrow cat vs. no cat



input layer output layer
hidden layer

House price prediction



Propagation Equation

$$3 \times 1 \rightarrow z^{[1]} = \overset{3 \times d}{w^{[1]}} \overset{d \times 1}{x} + \overset{3 \times 1}{b^{[1]}}$$

$$z^{[1]} = \overset{3 \times d}{w^{[1]}} \overset{d \times n}{X} + \overset{3 \times 1}{b^{[1]}}$$

$$3 \times 1 \rightarrow a^{[1]} = \sigma(z^{[1]})$$

$$2 \times 1 \rightarrow z^{[2]} = \overset{2 \times 3}{w^{[2]}} \overset{3 \times 1}{a^{[1]}} + \overset{2 \times 1}{b^{[2]}}$$

$$2 \times 1 \rightarrow a^{[2]} = \sigma(z^{[2]}) \quad \leftarrow \text{added to fix omission in lecture}$$

$$1 \times 1 \rightarrow z^{[3]} = \overset{1 \times 2}{w^{[3]}} \overset{2 \times 1}{a^{[2]}} + \overset{1 \times 1}{b^{[3]}}$$

$$a^{[3]} = \sigma(z^{[3]})$$

Broadcasting

$$\tilde{b}^{[1]} = \begin{bmatrix} b^{[1]} & \dots & b^{[1]} \end{bmatrix}$$

n copies

$$X = \begin{bmatrix} x^{(1)} & \dots & x^{(n)} \end{bmatrix}$$

$[]$ - layer

$()$ - id of example

capital: batch of examples.

Optimize $w^{[1]} \ w^{[2]} \ w^{[3]} \ b^{[1]} \ b^{[2]} \ b^{[3]}$

Define Loss / cost fn

Backward Propagation