transformations

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```
[]: import cv2 as cv
     import numpy as np
     #Read image
     img = cv.imread('Images/cat.jpg')
     cv.imshow('Cat', img)
    ranslation
[]: def translate(img, x, y):
       transMat = np.float32([[1,0,x], [0,1,y]])
       dimensions = (img.shape[1], img.shape[0])
       return cv.warpAffine(img, transMat, dimensions)
    -x \rightarrow Left -y \rightarrow Up x \rightarrow Right y \rightarrow Down
[]: translated = translate(img, -100, 100)
     cv.imshow('Translated', translated)
    otation
[]: def rotate(img, angle, rotPoint=None):
       (height, width) = img.shape[:2]
[]: if rotPoint is None:
         rotPoint = (width//2, height//2)
[]: rotMat = cv.getRotationMatrix2D(rotPoint, angle, 1.0)
       dimensions = (width, height)
[]: return cv.warpAffine(img, rotMat, dimensions)
[]: rotated = rotate(img, -45)
     cv.imshow('Rotated', rotated)
[]: rotated_rotated = rotate(rotated, -45)
     cv.imshow('Rotated Rotated', rotated_rotated)
```

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