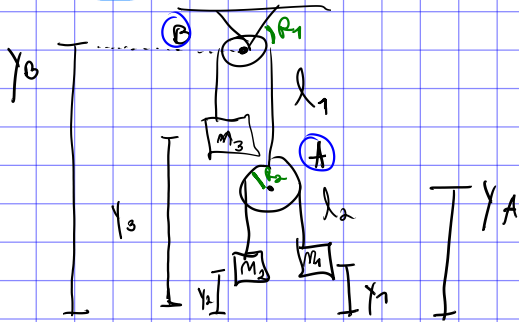


① Parcial de hoy 14 feb en 8 días (21 feb)

② hoy preparaval de física.

ejercicio:



$$l_1 = (y_B - y_3) + \pi R_1 + (y_3 - y_1)$$

$$l_2 = (y_A - y_2) + \pi R_2 + (y_A - y_1)$$

con estos puedo relacionar la aceleración:

$$0 = (a_B - a_3) + (a_B - a_1)$$

$$0 = (-a_3 - a_1) \Rightarrow a_3 = -a_1$$

$$0 = 2a_1 - a_2 - a_1$$

$$0 = -2a_3 - a_2 - a_1$$

$$2a_3 + a_2 + a_1 = 0 \quad (1)$$

$$(2) \quad T_1 - m_3 g = m_3 a_3$$

$$(3) \quad T_1 - 2T_2 = m_A a_A \Rightarrow T_1 = 2T_2$$

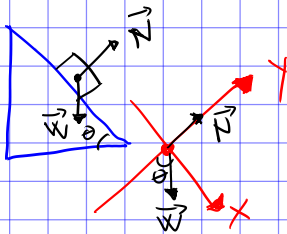
masa de la polea es despreciable

$$(4) \quad T_2 - m_1 g = m_1 a_1$$

$$(5) \quad T_2 - m_2 g = m_2 a_2$$

① incógnitas $T_1 = ? , T_2 = ?$
 $a_1, a_2, a_3 = ?$

Experimento de gálibo



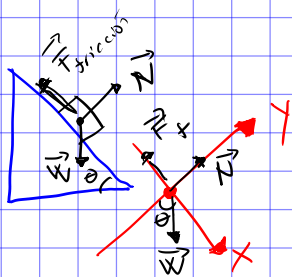
$$(Mg) \cdot \sin(\theta) = m g$$

\uparrow $g \sin(\theta) = a$

$$\sum F_x = W \sin(\theta)$$

$$\sum F_y = N - W \cos(\theta) = 0$$

Fricción → caso estático (quieto)
→ caso dinámico (movimiento)



⊙ la fricción es proporcional a la Normal

$$\vec{F}_{\text{fricción}} \propto \vec{N}$$

$$\vec{F}_{\text{fricción}} = \underbrace{\mu}_{\text{coef. de fricción}} \vec{N}$$

⊙ Caso estático

$$① \sum f_x = mg \cdot \text{sen}(\theta) - \vec{F}_{\text{fricción}} = 0$$

$$② \sum f_y = N - mg \cos(\theta) = 0$$

$$N = mg \cos(\theta)$$

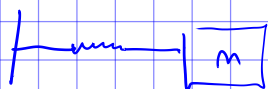
$$\begin{aligned} \sum F_x = mg \cdot \text{Sen}(\theta) - \vec{F}_{\text{fricción}} &= mg \text{sen}(\theta) - \mu N = 0 \\ &= mg \text{Sen}(\theta) - \mu mg(\cos \theta) = 0 \\ \text{Sen}(\theta) &= \mu (\cos(\theta)) \\ \mu &= \tan(\theta) \end{aligned}$$

⊙ Caso dinámico:

$$① mg \text{sen}(\theta) - \vec{F}_f = ma$$

$$② N - mg \cos(\theta) = 0$$

ley de hooke



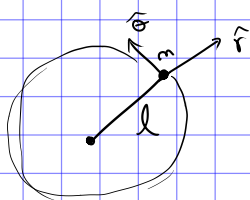
$F \propto \Delta x$ → fuerza es proporcional al Δx

$$F = -k \Delta x = -kx$$

$$\begin{aligned} \sum F_x &= -kx = m \cdot a \\ -kx &= m \ddot{x} \\ m \frac{d^2 x}{dt^2} &= -kx \end{aligned}$$

$$\boxed{\frac{d^2 x}{dt^2} = -\frac{kx}{m}}$$

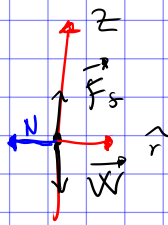
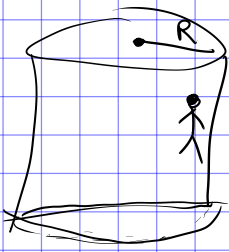
Rotación 2



$$\odot r = l \Rightarrow \dot{r} = \ddot{r} = 0$$

$$\odot \dot{\theta} = \text{cte} = \omega$$

$$\begin{aligned} \sum \vec{F}_{\text{radio}} &= -T = m a_r \\ -T &= m(\ddot{r} - \dot{\theta}^2 r) \\ -T &= -l \omega^2 \\ T &= l \omega^2 \end{aligned}$$



$$\Sigma \vec{F}_r = -\vec{N} = -\omega^2 R$$

$$N = \omega^2 R$$

$$\Sigma F_z = F_s - mg = 0$$

$$N - mg = 0$$

$$N = \frac{mg}{\mu} = \omega^2 R$$

(se normaliza)
centrífuga
a $\omega^2 R$

$$\omega = \sqrt{\frac{mg}{\mu R}}$$

Fuerza gravitacional

$$|\vec{F}_g| = \left| \ominus \frac{M_1 \cdot M_2}{R^2} \right|$$

cte de gravitación universal

$$\vec{F}_g = -\frac{G M_1 M_2}{R^2} \hat{r}$$

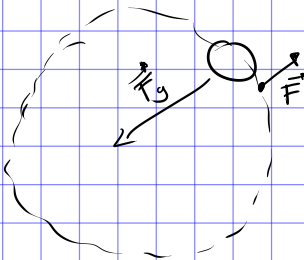
fuerza
atractiva

Análogamente entre electrones

$$\vec{F} = \oplus \frac{k q_1 q_2}{R^2} \hat{r}$$

cargas

fuerza
atractiva
y repulsiva



$$-F_g = -m \omega^2 r$$

$$\frac{G M_1 M_2}{r^2} = m_2 \omega^2 r$$

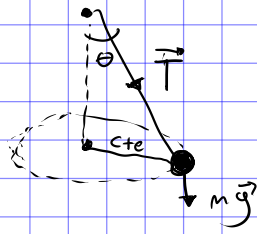
$$\frac{G M_1}{r^3} = \omega^2$$

$$\frac{G M_1}{r^3} = \frac{4\pi^2}{T^2}$$

Si se evalúa para
cualquier planeta
es a prox. cte.

$$\left(\frac{r^3}{T^2} \right) = \frac{G M_1}{4\pi^2}$$

Pendulo conico



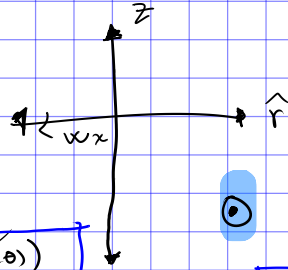
l = longitud de la cuerda.

$$\textcircled{1} \quad -\vec{T}_x = -m\omega^2 r$$

$$T \sin(\theta) = m\omega^2 r$$

$$T \sin(\theta) = m\omega^2 (l \sin(\theta))$$

$$T = m\omega^2 l$$



$$\textcircled{2} \quad T \cos(\theta) - mg = 0$$

$$T = \frac{mg}{\cos(\theta)}$$