# LAMBDA ARCHITECTURE Speed layer: Real-time views

**BIS2013** 

**Database Systems** 

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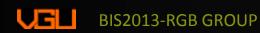
2<sup>nd</sup> Huy Huynh

3<sup>rd</sup> Tin Ho



# Agenda

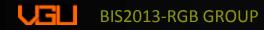
Hai Vo	The Speed Layer	
	Computing & Storing real-time views	
Huy Huynh	Challenges of incremental algorithms	
	Asynchronous versus synchronous updates	
Tin Ho	Expiring real-time views	
	Cassandra: an example speed layer view	
	Conclusion	V



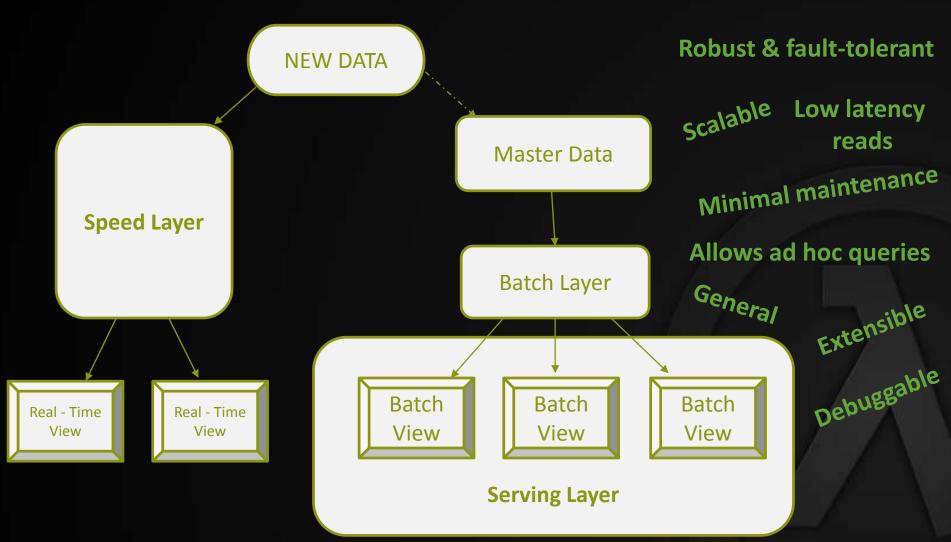
#### **Motivation**

The update latency requirements vary a great deal between applications.

Some applications require updates to propagate immediately, while in other applications a latency of a few hours is fine.



#### Motivation





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## Speed Layer vs Batch Layer

The speed layer is similar to the batch layer in that it produces views based on data it receives.

Incremental updates as opposed to recomputation updates.

Only produces views on recent data vs produces views on the entire dataset.



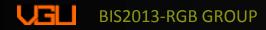
#### **Speed Layer**

Processing data on a smaller scale

Requires databases that support random reads and random writes

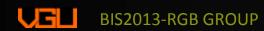
More complex and thus more prone to error.

The speed layer views are transient.

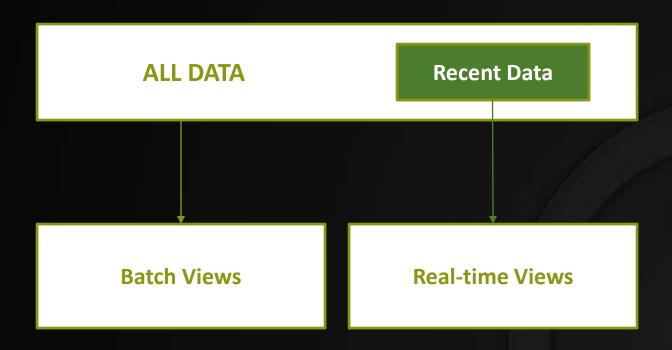


#### Two major facets of the speed layer

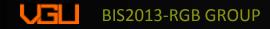
Storing the real-time views and processing the incoming data stream so as to update those views



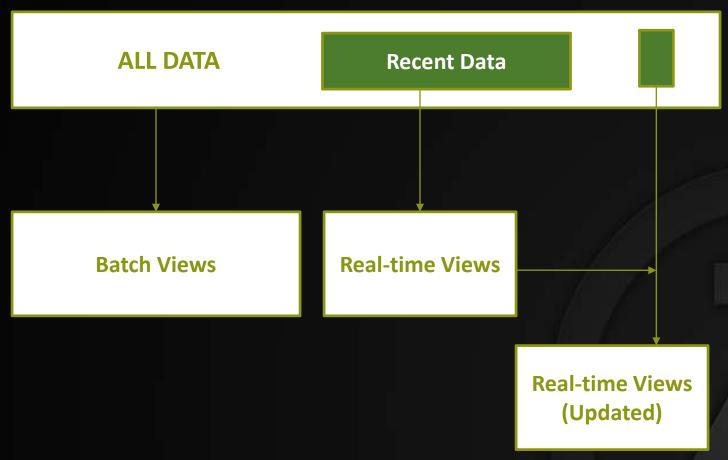
### **Computing Real-time Views**



**Real-time View = function (recent data)** 



## **Computing Real-time Views**



Real-time View = function (new data, previous real-time view)

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#### **Storing Real-time Views**

Low-latency random reads, and using incremental algorithms necessitates low-latency random updates

NoSQL database i.e. Cassandra

Random reads Random writes

Scalability

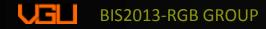
Fault-tolerant



# Challenges of incremental computation

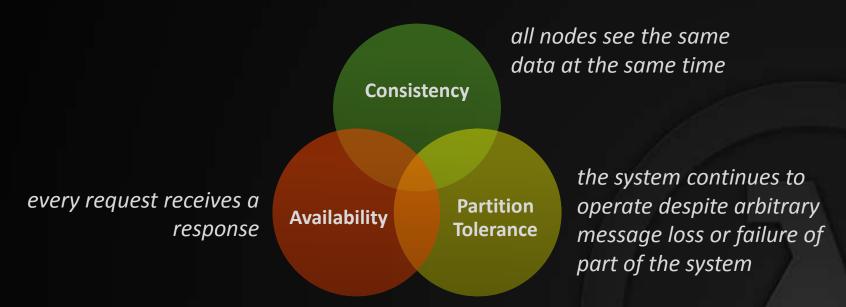
Incremental algorithms are less general and less human fault-tolerant, but higher performance

Challenge in a real-time context: the interaction between incremental algorithms and the CAP theorem



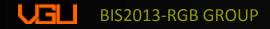
#### The CAP Theorem

"You can have at most two of Consistency, Availability, and Partition-tolerance"



"When a distributed data

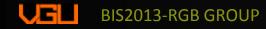
system is Partitioned, it can be Consistent or Available but not both"



#### C vs A

When you choose consistency, sometimes a query will receive an error instead of an answer

When you choose availability, at best you will have where eventual consistency



# Replication in Distributed system



Sally	New York
_	
Joe	Paris
Maria	Tokyo

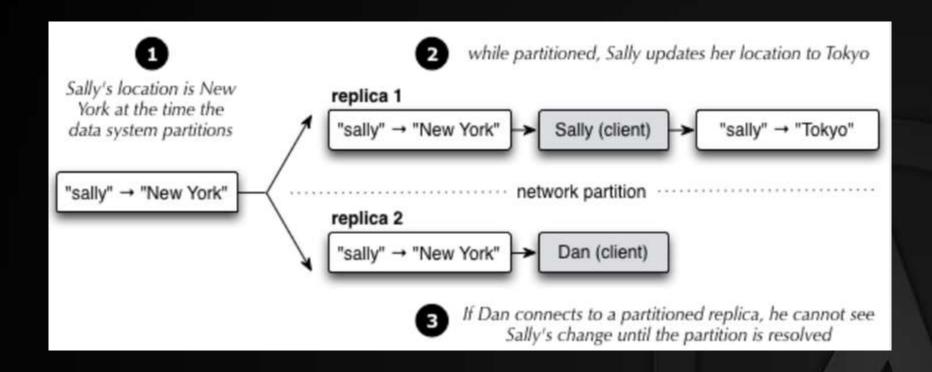


Sally	New York
Maria	Tokyo



Sally	New York
Maria	Tokyo

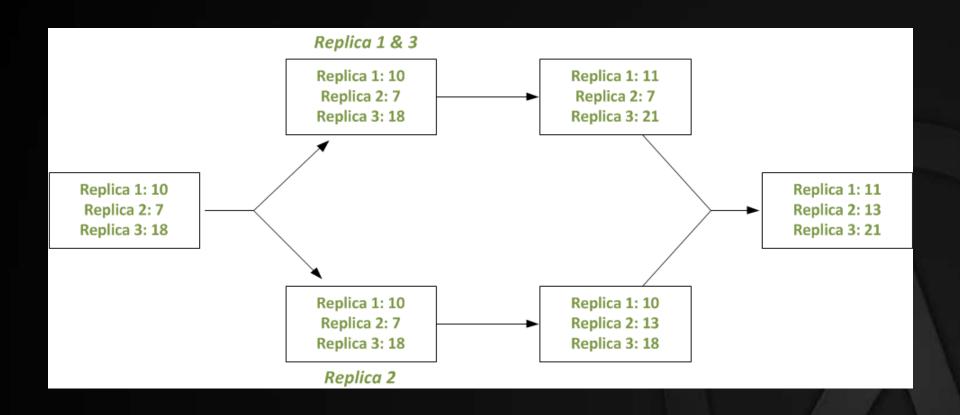
#### **Eventual consistency**





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## **Eventual consistency counting**



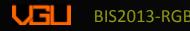


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# Interaction between the CAP theorem and incremental algorithms

Complexity in a real-time eventually consistent context

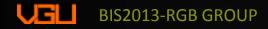
Read and repair algorithms are needed



#### Keep calm with Lambda

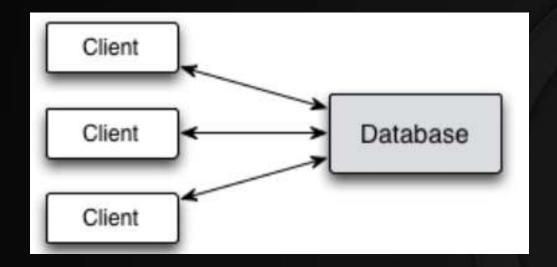
Unfortunately there is no escape from this complexity if you want eventual consistency in the speed layer

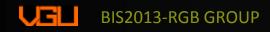
If the real-time view becomes corrupted, the batch/serving layers will later automatically correct the mistake in the serving layer views



### Synchronous updates

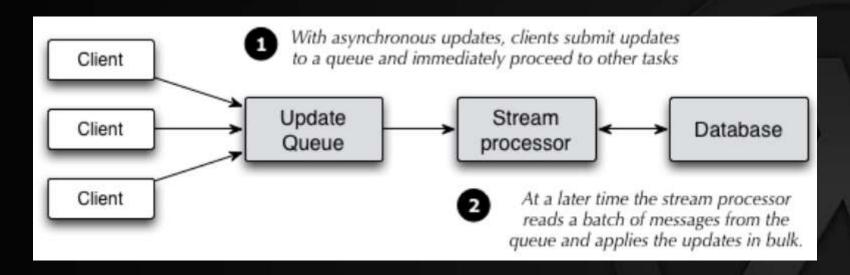
The application issues a request directly to the database and blocks until the update is processed





### Asynchronous updates

Asynchronous update requests are placed in a queue with the updates occurring at a later time





# Asynchronous versus synchronous updates

**Synchronous** 

**Asynchronous** 

Fast

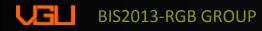
Slower

Coordinate the update with other aspects of the application

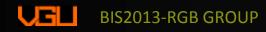
Not coordinate

May overload the database

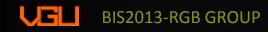
Not overload the database

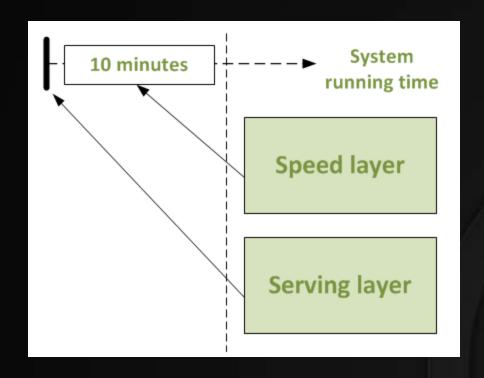


Since the simpler batch and serving layers continuously override the speed layer, the speed layer views only need to represent data yet to be processed by the batch computation workflow



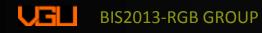
Instead, we present a generic approach for expiring speed layer views that works regardless of the speed layer databases being used. To understand this approach, let's first get an understanding of what exactly needs to be expired each time the serving layer is updated

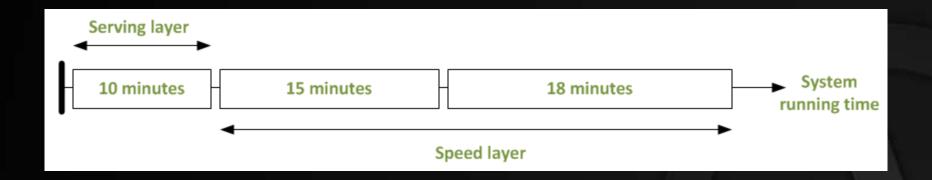






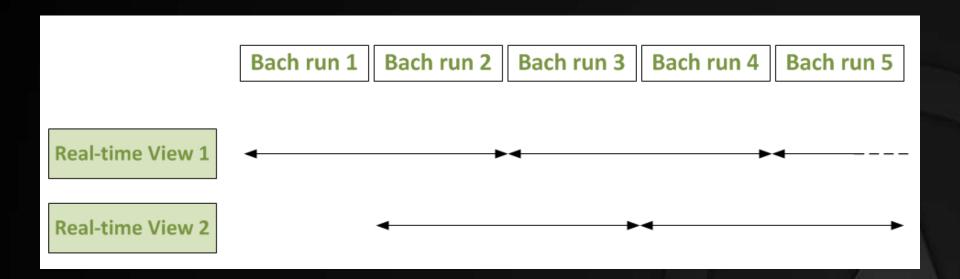


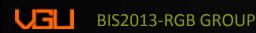






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What do you have ever heard about it?

Column oriented/family database

Key value based database

NOSql database

Real time operational data store

Distributed database

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#### Some definitions:

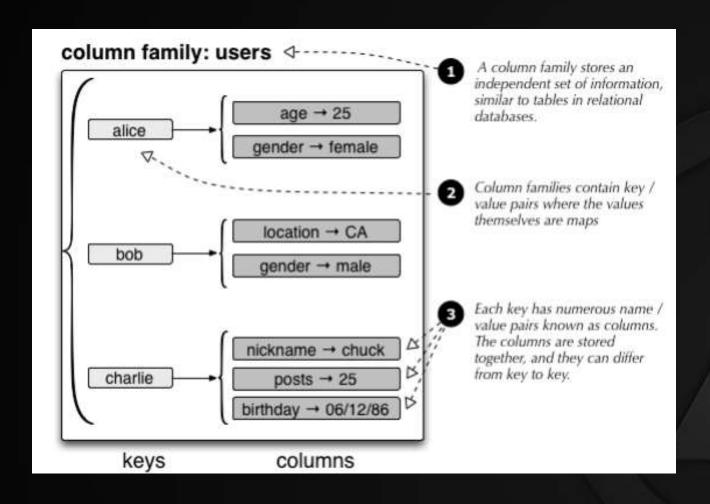
Key space: is the outermost container for data in Cassandra.

Column families: is a container for a collection of rows. Each row contains ordered columns.

Columns: is the most basic unit of data in Cassandra data model. Consists of <a href="key,value,timestamp">key,value,timestamp</a>> triplet.



#### Column family example:





Cassandra features make it suitable for real-time view:

Partitions keys among nodes in cluster:
RandomPatitioner and OrderPreservingPatitioner
Composite columns.



# **Using Cassandra!**





#### Conclusion

Theoretical model of the speed layer

CAP theorem

Incremental computation in stead of batch computation

Store speed layer view (real-time)



#### References

Big Data, Principles and best practices of scalable real-time data system – Nathan Marz

