

Apple® Desktop Bus (ADB™)

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INTRODUCTION

The purpose of this application note is to introduce a PIC16CXXX based ADB interface which can be used as a basis for the development of custom ADB devices. This application note describes; the hardware involved, a general purpose ADB protocol handler, and an example application task. The example software application supports a single key keyboard to the Macintosh® computer (Figure 1).

OVERVIEW

ADB licensing from Apple Computer.

Described as a peripheral bus used on almost all Macintoshes (except for the Macintosh 128, 512K, and Plus) for keyboards, mice, etc.

Communication between the ADB task and the application task takes place using several flags. The flags indicate whether there is data received that needs to be sent to the Macintosh, or if data from the Macintosh needs to be sent by the application.

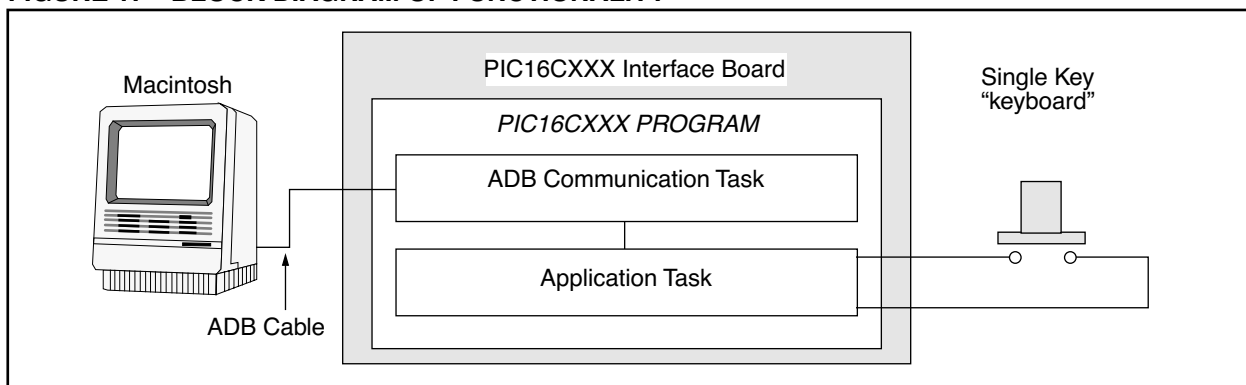
EXPLANATION OF ADB TECHNOLOGY

ADB is an asynchronous pulse-width communication protocol supporting a limited number of devices. All devices share a single I/O wire in a multi-drop master/slave configuration in which any slave device may request service. This is accomplished through a wired OR negative logic arrangement.

The ADB cable is composed of four wires: +5V, gnd, ADB signal, and power-on (of the Macintosh). The signal wire communicates ADB input and output using an open collector type signal. The number of devices is limited by the addressing scheme and a maximum current draw of 500 mA.

Every ADB device has a default address at start-up assigned by Apple. If there are device address conflicts, the protocol supports the reassignment of device addresses at start-up. The software in the PIC16CXXX discussed here is designed to easily modify the device address to make the PICmicro™ appear as another ADB device for testing and development.

FIGURE 1: BLOCK DIAGRAM OF FUNCTIONALITY



Macintosh, and ADB™ (Apple Desktop Bus) are trademarks/registered trademarks of Apple Computer, Inc.

No device issues commands, except the host. However, devices are permitted to request service during specific time intervals in the signal/Command protocol. A Service Request is referred to as an "Srq". The signal protocol communication is accomplished by pulling the ADB line low for various time intervals.

The host controls the flow of data through issuance of specific signal sequences and by issuing several types of Commands. The basic command types are Talk, Listen, Flush, and Reserved. Each command has a component called a "Register" indicator which specifies the storage area affected by the command type. The following is a summary explanation of each of the commands. The complete specifications are available from Apple, as listed in the Resources section of this application note.

PROTOCOL ASSUMPTIONS

The ADB protocol is defined with a number of general assumptions about its use. These assumptions have driven the general philosophy of the communication sequences. It is assumed that the devices on the ADB are used for human input and each are used one at a time, such as a keyboard and a mouse. It is also assumed that the user's transfer time from one device to another is relatively slow. This does not mean that the protocol is limited to these assumptions but rather that the protocol is optimized towards this type of use. This is made very evident in the host polling logic, where the host continues to poll the last device communicated with until another device issues an Srq. Consequently, if another device issues an Srq, the device being communicated with (or the host) may need to retransmit.

ADB Elements:

The ADB protocol has two components, a Signal protocol and a Command/Data protocol. These two elements are intertwined. The Signal protocol is differentiated in most cases by timing periods during which the ADB signal is low. The Apple ADB specification allows $\pm 3\%$ tolerance timing of the signals from the host and $\pm 30\%$ by the devices. The signals are:

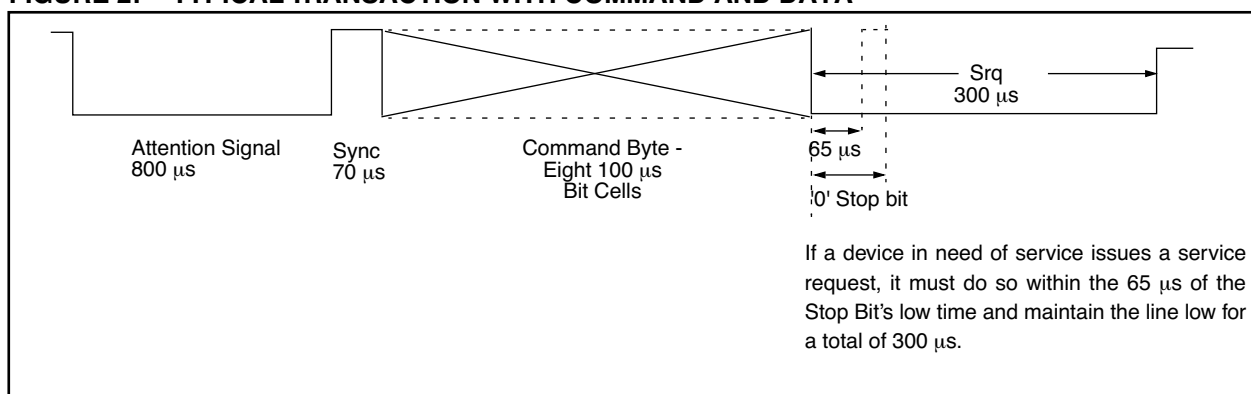
- Reset: signal low for 3 ms.
- Attention: signal low for 800 μ s.
- Sync: signal high for 70 μ s.
- Stop-to-Start-Time (T1t): signal high for between 65 and 160 μ s.
- Service Request (Srq): signal low for 300 μ s.

After device initialization, in general, all communication through the ADB is accomplished through the following event sequence initiated by the host:

1. Attention signal
2. Sync signal
3. command packet
4. T1t signal
5. data packet transfer

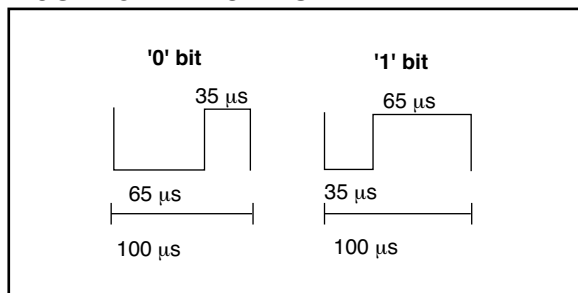
Depending upon the command, the device may or may not respond with a data packet. Service requests are issued by the devices during a very specific time at the end of the reception of the command packet.

FIGURE 2: TYPICAL TRANSACTION WITH COMMAND AND DATA



The command packets and the data packets are the constructs used to communicate the digital information. The method of representing data bits is accomplished in a signal timing construct called a **bit cell**. Each **bit cell** is a 100 μs period. Data '1's and '0's are defined by the proportions of the bit cell time period when the line is low and then high. A '1' bit is represented by the line low for 35 μs , and high for 65 μs . Conversely, A '0' bit is represented by the line low for 65 μs , and high for 35 μs (Figure 3).

FIGURE 3: BIT CELLS



The **Command Packet**, received from the host, follows an Attention signal and a Sync signal. It consists of an 8-bit command byte and a '0' command stop bit. The command byte may be broken down into two nibbles. The upper nibble is a 4-bit unique device address. The lower nibble is defined as a Global or Reserved command for all devices, or a Talk, Listen, or Flush Command for a specific device. Also contained in the lower nibble is a "Register" designator which further details the Command. The importance of the Command Stop Bit Cell is that **Srqs' can only be issued by a device to the host during the Command Stop Bit Cell low time if the device address is not for the device wishing service.** The Host controls when Srq's are allowed through the Command protocol. The Tlt signal and Data Packet transfer, which are part of every Command packet signal sequence, are overridden if an Srq is issued by any device.

A **Data Packet** is the data sent to, or received from, the host. Its length is variable from 2 to 8 bytes. The structure is a '1' start bit, followed by 2 to 8 bytes, ending with a '0' stop bit. The Apple ADB documentation refers to the data packet sent or requested as Device Data "Registers". This does not necessarily indicate a specific place in memory. In this PIC16CXXX implementation, each Data Register has been limited to two PIC16CXXX register bytes. The ADB specification allows each Data Register to hold between two and eight bytes. They are referenced in the Command byte as "register" 0, 1, 2, or 3. Data Register 3 has special significance. It holds the special status information bits (such as whether Srq's are allowed), the Device Address, and the Device Handler ID. Commands are further defined by the "register id" sent in the Command data packet.

For example, if the Host issues the Command in binary of 0010 1100, it would be interpreted as "Device 2, Talk Register 0". The complete definition of the Commands and data registers are described in detail in the ADB specifications supplied by Apple.

PIC16CXXX ADB PROTOCOL PROGRAM EVENT SEQUENCE

Overview

At power-on the host will generate a Reset signal. The purpose of Reset is to initialize the devices on the ADB line. This includes determining the addresses of each device, and resolving device address conflicts if there are any. Once the device addresses are determined, each device waits to be commanded or issues an Srq if it requires service from the host and is not being addressed by the host. After Reset processing, the ADB Protocol Task monitors the ADB line for the Attention/Sync/Command signal sequence. The PIC16CXXX program differentiates the signal timing.

Note: The signal detection routines check to see if the Application Task needs service after each event and after the falling edge of the Attention signal is detected.

Command interpretation is accomplished during the low signal time of the Stop Bit cell of the Command packet. Response to the Command must occur after the minimum time of the Stop to Start time period (Tlt), which is 160 μs , but before the max Tlt time of 240 μs . When a device has issued an Srq, it waits to be addressed by the host. If the next Command received is not for that device, it issues the Srq again. The normal response to an Srq will be a Talk Command from the host.

Detailed Description

Start-up

Upon start-up, the Reset routine is executed, looking for the ADB line to be high. When the line is high, an initialization routine is executed during which registers are cleared or loaded with default values. The only exception is a register for generating a random address used in the address conflict resolution process.

Reset

During a Reset condition, default values are loaded, such as the Default Device Address and Handler ID (a piece of information used by the host to identify the type of device). If more than one device has the same address, there is a sequence of events to resolve address conflicts described in the Implementation section. The host assigns a unique address to each device. The Reset condition only takes place once, during start-up, except under unusual conditions, such as testing this program.

Attention Routine

When the Reset routine is complete, the Attention Signal routine is executed, looking for the line to go low and then high. This low time is monitored to be within range of the Attention Signal Timing. If the timing is below the minimum threshold, the routine aborts to start over again looking for the line to go low at the beginning of the Attention Signal. If the low time is exceeded, the routine aborts to the Reset Signal routine.

Sync Signal Routine

When the line transitions to high, the Sync Signal routine looks for the line to go low at the start of the first bit of the Command Byte. If the Sync high time is exceeded, the routine aborts to the Attention Signal.

Command Routine

The Command routine detects and decodes the next 8 bit-cells as the Command Byte. The routine must first determine if the device address given is for itself. If the routine determines that the device address in the Command matches the stored device addresses, then it may do one of two things; issue an Srq to the host by holding the line low, or go on to check if the Command is Global to all devices. If the command is Global, the routine determines the specific Command and executes the routine for that Global Command. After execution of the Command routine it then goes back to look for the Attention Signal.

When a device is addressed, it determines whether the Command is to Talk, Listen, or Flush data, for the specified Data Register number. If the Command is for Data Register 3, there are special considerations described for this program in the Implementation section later in this application note. If the Command is to Flush, the routine clears the data in the specified register. The ADB specification defines the action of the Flush Command to be device specific. For a Talk Command or Listen Command, the device then waits for the Tlt signal. When the Command is to Talk, the device sends the data bytes from the specified register and a Data Stop Bit after the Tlt minimum time. For a Listen Command, the device receives data for the specified register.

When the data has been Flushed, Sent, or Received, the device then returns to monitoring for the Attention signal again.

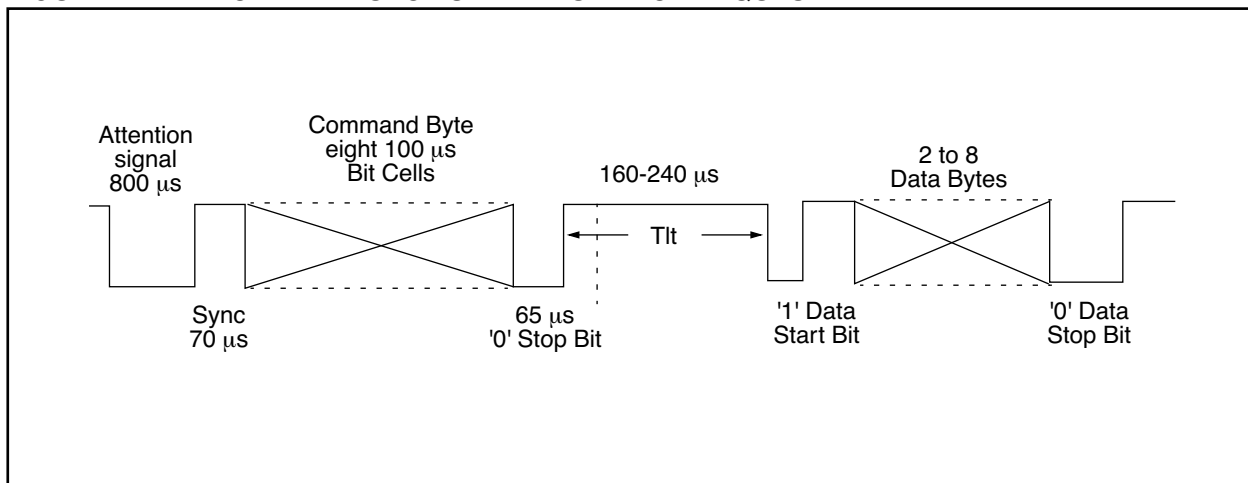
Note 1: In this PIC16CXXX program, the Application Task is serviced before looking for the Attention signal.

Note 2: If at any time the line is low or high outside of the timing ranges, the program aborts to check if an Attention or Reset signal has been issued by the Host. In the case of sending Data, the program goes first to the Collision routine.

Sending Data to the Host

Data is sent only in response to a Talk Command. For every data bit cell, the line is tested to go high at the proper time. If the line is still low, a collision has occurred. When a collision is detected, a collision flag is set, and the program aborts to look for a Command signal sequence.

FIGURE 4: TYPICAL TRANSACTION WITH SERVICE REQUEST



IMPLEMENTATION

Hardware

The hardware of this circuit is fairly simple. The circuit is powered via the +5V and GND wires of the ADB cable. The ADB I/O wire is connected to pin RA0 with a pull-up resistor to 5V. The T0CKI pin is tied to GND. The Master Clear (\overline{MCLR}) pin is tied to 5V.

This circuit uses a 4 MHz crystal as a timing reference, but higher values may be substituted. The software is designed to accommodate higher frequencies.

A pushbutton switch is used as the single key of the "keyboard." One side is connected to port RB1 with a pull-up resistor to 5V, and the other side to GND. An LED is used to indicate that the 'key' has been pressed, with the positive side connected to pin RB0 and the negative side to GND.

Software

The program designated as "Application Tasks," has two sections, one is setup to switch between a protocol support task for the ADB signal decode and processing, and the other section is the Application Task, in this case a single key "keyboard" routine. The ADB protocol task has priority. The first section of the code is the ADB protocol task, the second section is the Application Task, "Keyboard." The two tasks communicate through flags which indicate that data needs to be sent, or that data has been received.

The Keyboard Task is run at two times; 1) during the Attention Signal, 2) between the end of the Data Stop Bit and the beginning of the Attention Signal. The Keyboard Tasks is given up to 500 μ s during the Attention Signal, and 900 μ s during the time between the end of the Data Stop Bit and the beginning of the Attention Signal. It is important to note here that the other tasks MUST NOT AFFECT TMR0 or the ADB time variable that the Attention Signal is using to keep track of the RTCC.

Timing

Timing is accomplished by first loading a constant into a time variable. This constant represents the maximum limit for the current routine, which may not necessarily be the maximum timing range for the current Signal. The TMR0 value is loaded into the working register, and subtracted from the time variable. The Carry bit of the STATUS register is tested to see if it is set or clear. If the bit is clear, the current timing limit has been exceeded. Further action is taken based on this status. It is important to keep the constant away from 255, or rollover may occur, giving inaccurate results. The prescaler is applied to the TMR0 as necessary.

The following are the timing ranges used by this program for ADB signals:

Reset	> 824 μ s
Attention	776-824 μ s
Sync	72 μ s
Bit Cell	Up to 104 μ s
'1' Bit low time	< 50 μ s
'0' Bit low time	> 50 < 72 μ s
Stop bit	0 Bit
Stop to Start (Tlt)	140-260 μ s
Service Request (Srq)	300 μ s

Note: The range of values given for 0 Bit, 1 Bit and Tlt timing are slightly wider than those given in the ADB specification.

How Address Conflicts are Resolved

During the start-up process the host sends a "Talk Register 3" command to each device address, and waits for a response. When a device recognizes that the Host issued a "Talk Register 3" command, it responds by sending a random address. During the transfer of each Bit Cell of the random address the signal line is monitored for the expected signal level. If the signal is not what is expected there is an address conflict. If the address is sent successfully, the host will respond with a Listen Command to that device. The command will have a new Device Address to which that device will move. The device then only responds to commands at the new address.

If there is a conflict, where two devices have the same default address, and respond at the same time, the device that finds the line low when it expects it to be high, immediately stops transmitting because it has determined that a collision has occurred. The device which detected the collision marks its address as unmovable and therefore ignores the address move Command, a Listen Register 3 Command. The device maintains the unmovable address condition until it has executed a successful response to the Talk Register 3 Command.

The host continues sending a Talk Register 3 Command at the same address until there is a time-out and no device responds. This is how conflicts are resolved when more than one device has the same address; for example, if two keyboards are connected.

Program Sequence:

Words in parenthesis, (), accompanying the TITLES are Labels of procedures in the corresponding code.

Start-up / IDLE (Start)

Start by configuring the ADB pin on PORTA and the Switch Pin on PORTB as inputs, and tri-stating the rest of PORTA and PORTB as outputs.

INITIALIZE DEFAULT VALUES WHEN THE LINE IS HIGH (Reset)

Look for the line to be high, and when it is, clear or initialize registers to default values.

LOOK FOR ATTENTION OR RESET (AttnSig)

Look for the line to go low, when it does, clear TMR0 and time how long it is low. An Attention Signal has occurred if the line went high between 776 and 824 μ s. If the low time is measured to less than 776 μ s, another signal has occurred and the program aborts, looking for the Attention Signal again. When the low time is measured to greater than 824 μ s, the program interprets this timing as a Reset Signal. The program starts over again, waiting for the line to be high, and when it is, performs a Reset initialization.

Note: The keyboard task is performed during the Attention Signal (Task_2).

LOOK FOR SYNC SIGNAL (SyncSig; calls Srq)

The Sync Signal is the high time between the rising edge of the Attention Signal and the falling edge of the first bit of the Command.

GET THE COMMAND (Command; calls Get_Bit)

Look for the Command; a combination of eight '0' and '1' bits. **The MSb is sent first.** This is achieved by calling the Get_Bit routine, which checks whether the maximum Bit Cell time is exceeded, if not, it looks for the rising edge at the end of the bit. When the bit is received, it is rotated into a variable, and the end of the bit cell is expected. When the falling edge of the next bit is detected, the routine clears TMR0 and returns to Command, which calls Get_Bit again until all 8-bits of the Command have been received.

ISSUE A SERVICE REQUEST IF NECESSARY (Srq)

If data needs to be sent to the Host, a Service Request (Srq) is issued by holding the line low while the Stop Bit is being received during the Stop-to-Start time (T1t) which is between the end of the Command Stop Bit and the beginning of the Data Start Bit.

LOOK FOR STOP BIT (CmdStop)

Look for the Stop Bit (a '0' bit of 65 μ s) that comes after the last Command Byte.

INTERPRET THE COMMAND (AddrChk)

After the command has been received, determine if the address belongs to this device. If the address is not for this device, determine if the command is global for all devices and if so, do that command. If this is not a Global/Reserved Command, call the Service Request (Srq) Routine to see if an Srq should be issued to the Host, and do so if necessary, then return to get the Attn Signal. If the Address is for this device determine whether it is a Talk, Listen, or Flush Command, and go to the specified Command routine.

SENDING DATA (Talk; calls T1t)

If the command was interpreted to be a Talk Command addressed to this device, call the Stop-to-Start Time (T1t) routine. When the T1t routine has completed, determine if this is a Talk Register 3 Command. If so, return a Random Address as part of the two bytes sent to the Host. If this is not a Talk Register 3 Command, determine if data needs to be sent. If so, send the Data Start Bit (a '1'), two bytes of data from the indicated register, and a Stop Bit (a '0'). If not, abort to the Attention Signal. If at any time the transmission of Data is interrupted, abort to the Collision routine. Only after a complete transmission should the flags be cleared indicating a successful transmission.

Note: The ADB Specification indicates data may be between two and eight bytes long. The limitations of the PIC16C54/55/56 parts allow only two bytes of data to be sent by this program due to limited register space. If more than two bytes of data must be sent, use the PIC16C57.

RECEIVING DATA (Listen; calls T1t)

If the command was interpreted to be a Listen Command addressed to this device, call the Stop-to-Start Time (T1t) routine. When the T1t routine has completed, receive the rest of the Data Start Bit, 2 Data Bytes, and Data Stop Bit. When the data has been received, determine whether this is a Listen Register 3 Command. If this is a Listen Register 3 Command, interpret what the command is. If this is a conditional Address Change Command, determine if this Device's Address is moveable at this time. If not, abort to the Attention Signal. If so, change the device to the new address and go run the Second Application Task. If this is not a Listen Register 3 Command, move the data into the specified register and go run the Second Application Task.

LOOK FOR THE STOP TO START TIME (T_{1t})

After the Command and Stop Bit, the Talk or Listen routines call the Tlt routine. Tlt looks for the line to go low. If the line went low before the minimum Tlt Time, see if this is a Talk Command. If this is a Talk Command, abort to the Collision routine. If this is a Listen Command, abort to the Attention Signal.

If the minimum Tlt time passes and the line is high, see if the Talk routine called the Tlt, if so, go wait for until the middle of the Tlt, then return to the Talk routine to send the Data Start Bit, Data Bytes, and Stop Bit. If at any time the line goes low during the Tlt and the Talk routine called it, abort to the Collision routine.

If the Listen routine did call Tlt, look for the line to go low at the beginning of the Data Start Bit. When the line goes low, return for the rest of the Start Bit. If the line doesn't go low before the maximum Tlt time is up, abort to the Attention Signal.

THE KEYBOARD TASK IS PERFORMED BETWEEN THE END OF THE DATA STOP BIT AND THE ATTENTION SIGNAL (Task_2)

The Keyboard Task checks to see if the key has been pressed. When the key is pressed, indication flags are set and an LED is turned on until the key has been debounced. The flags allow the key to be debounced, Srq(s) to be sent to the Host, and indicate to the Talk routine that Data needs to be sent. Two bytes of data are loaded into Register 0 representing a key-down code and a flag is set indicating to the ADB task that data needs be sent to the host. When the key-down codes have been sent, the key-up codes are loaded into Register 0. When the key-up codes have been sent and the key has been debounced, the flags are cleared. The final routine of Task_2 decides whether to return to the beginning or middle of the Attention Signal.

FIGURE 5: APPLE DESKTOP BUS PIC16CXXX FLOWCHART

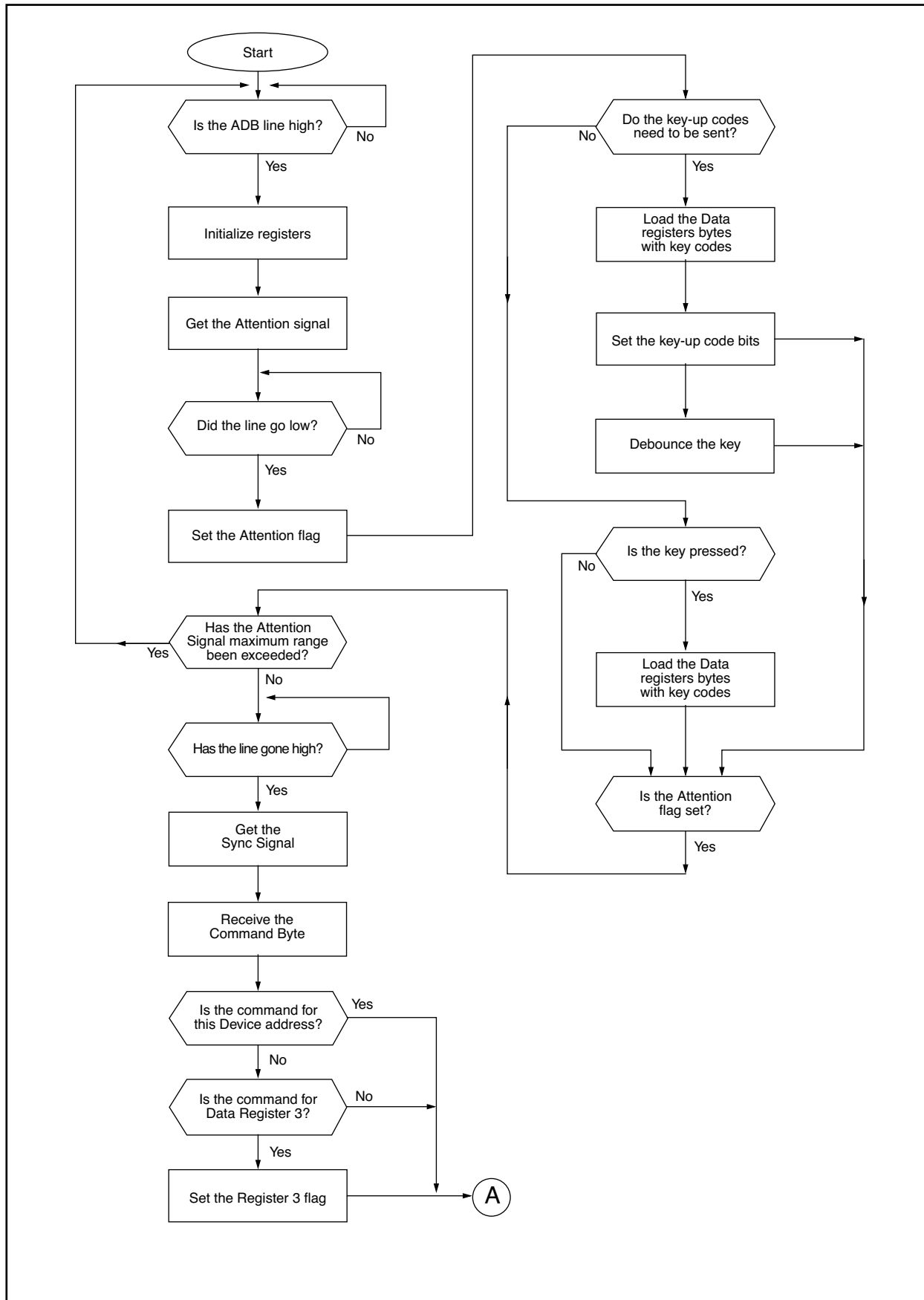
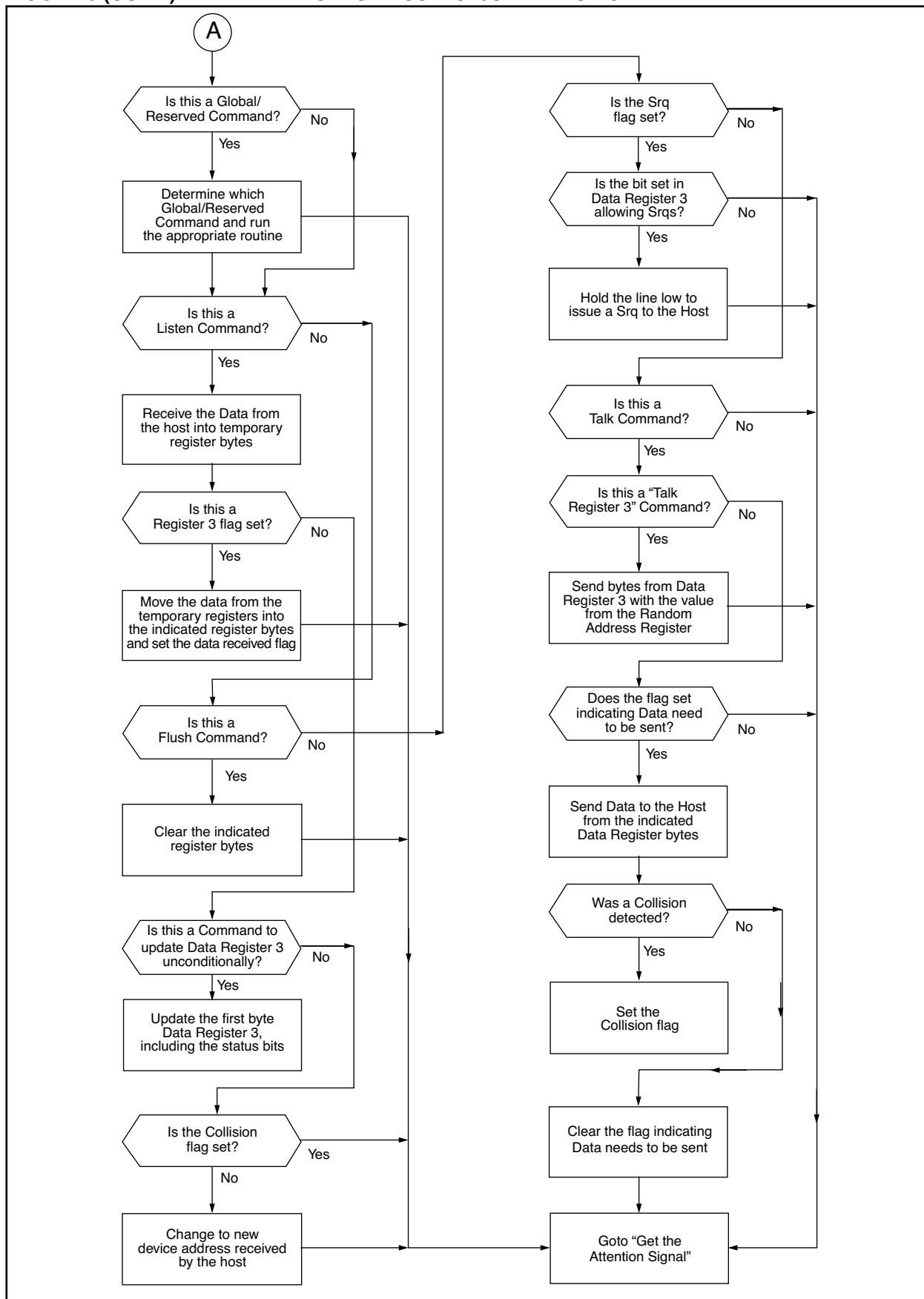


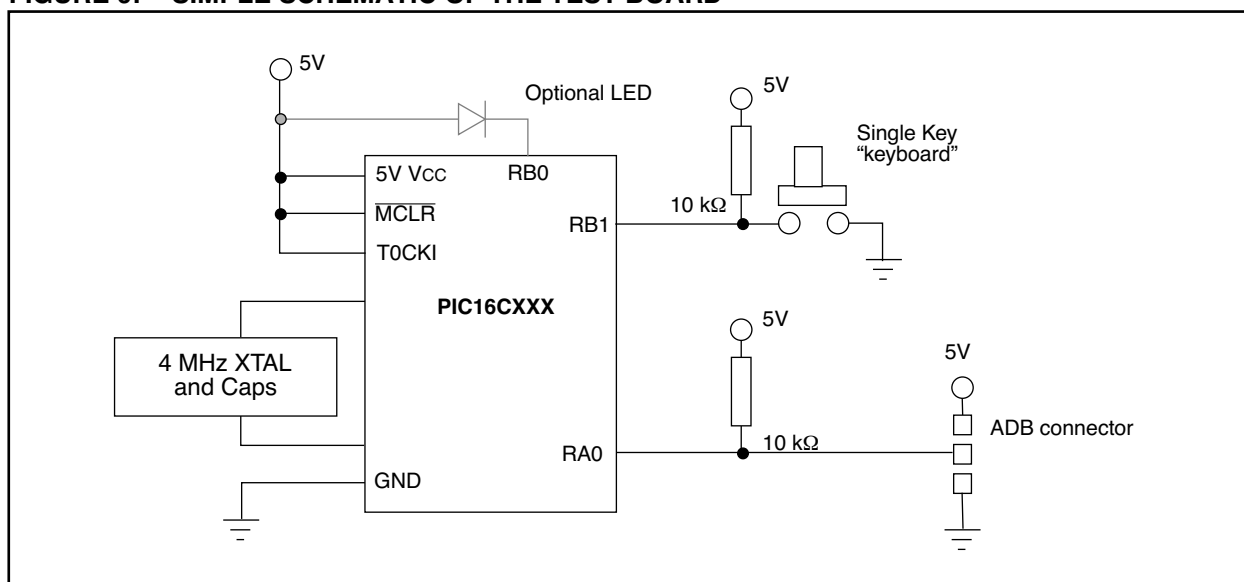
FIGURE 5 (CONT.): APPLE DESKTOP BUS PIC16CXXX FLOWCHART



SUGGESTIONS ABOUT MODIFYING THE CODE

1. If high crystal frequencies are used, a divider equate (equ) at the beginning of the timing section of the equates allows an easy adaptation for all established timing definitions.
2. The second application task may occur as a communication task with another PIC16CXXX device by using the three other I/O lines on PORTA, although test code for this has not yet been written. Two of the lines would be used as ready-to-send (one for each PIC16CXXX). The third would be used as a data line, using low signals as '0' bits, and high signals as '1' bits. Additionally, all eight lines on PORTB may be used as well.

FIGURE 6: SIMPLE SCHEMATIC OF THE TEST BOARD



RESOURCES

Apple Publications and Support Software

MacTech Magazine (formerly MacTutor) is a publication dedicated to supporting the Macintosh. They have had several articles regarding the Apple Desktop Bus. They publish a CD-ROM that contains all of their articles from 1984 to 1992. Also, single disks are available (ask for #42).

MacTech Magazine can be contacted at:

P.O. Box 250055
Los Angeles, CA 90025-9555
310 575-4343 FAX 310 575-0925
Applelink: MACTECHMAG
Internet: info@xplain.com

Apple licenses the ADB technology. They can be contacted at:

20525 Mariani Ave.
Cupertino, CA 95014
Attn: Software Licensing

- Apple Keyboard, extended, specification drawing #062-0168-A.
- Apple Desktop specification drawing #062-0267-E.
- Apple Desktop connector, plug, Mini DIN drawing #519-032X-A.
- Engineering Specification, Macintosh transceiver interface, ADB drawing #062-2012-A.
- Apple keyboard, specification drawing #062-0169-A.
- Developer CD series, Tool Chest Edition, August 1993 contains:
 - Folder = Tool Chest: Devices and Hardware: Apple Desktop Bus
 - ADB Analyzer
 - ADB Parser (most complete environment)
 - ADB Lister
 - ADB ReInit
 - ADB Tablet code samples

WFT Electronics offers free assistance in procuring necessary ADB info. Contact Gus Calabrese, Rob McCall, Dave Evink at:

4555 E. 16th Ave.
Denver, CO 80220
303 321-1119 FAX 303-321-1119 Applelink:
WFT
Internet: Gus_Calabrese@onenet-bbs.orgA

AUTHOR / CREDITS

Rob McCall developed the majority of the PIC16CXX ADB code. He also wrote most of the application note. Gus Calabrese, Dave Evink, and Curt Apperson supported this effort. Dave works with Gus, Rob, and Curt in developing a variety of embedded processor products.

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Please check the Microchip BBS for the latest version of the source code. Microchip's Worldwide Web Address: www.microchip.com; Bulletin Board Support: MCHIPBBS using CompuServe® (CompuServe membership not required).

APPENDIX A: ADB.ASM

MPASM 01.40 Released

ADB.ASM 1-16-1997 17:26:35

PAGE 1

LOC	OBJECT CODE	LINE	SOURCE TEXT
	VALUE		
00001		LIST	P = 16C56, n = 66, c=132, E=0, N=60
00002		;	
00003		;	*****A113-0004
00004		;	
00005		;	ADB.ASM *** This program is for PIC16C5x microcontrollers:
00006		;	
00007		;	Program: ADB.ASM
00008		;	Revision Date:
00009		;	1-16-97 Compatibility with MPASMWIN 1.40
00010		;	
00011		;	*****
00012		;	
00013		;	**TESTING - The purpose of this program is to emulate a keyboard that
00014		;	is Apple Desktop Bus (ADB) based. The program allows the PIC to
00015		;	appear to the Macintosh computer as a keyboard with a single key.
00016		;	The code isdesigned to easily modify the device address to make the
00017		;	PIC appear as another ADB device,which has its own proprietary
00018		;	functions.
00019		;	*****
00020		;	
00021		;	OVERVIEW OF ENTIRE PROGRAM:
00022		;	This program is setup to switch between a communication task with the
00023		;	the Apple Desktop Bus (ADB), and another application task.
00024		;	The ADB communication task has priority.
00025		;	All communication with the ADB is done using a single i/o line to
00026		;	the PIC, line RA0 on Port A.
00027		;	The second application may occur as a communication task with
00028		;	another PIC chip as follows:
00029		;	Communication with the second PIC may be achieved by using the three
00030		;	other i/o lines on Port A. Two of the lines would be used as
00031		;	ready-to-send (one for each PIC). The third would be used as a data
00032		;	line, using low signals as 0 bits, and high signals as 1 bits.
00033		;	Additionally, all eight lines on PORTB may be used as well.
00034		;	
00035		;	***** ADB COMMUNICATION TASK *****
00036		;	
00037		;	**** A BRIEF DESCRIPTION OF THE ADB COMMUNICATION SEQUENCE:
00038		;	
00039		;	STARTUP ----- initialize the TMR0 prescaler & Tri-States PORTA
00040		;	
00041		;	Look for the following signals and/or take appropriate actions:
00042		;	RESET ----- a high line, then initialize default register values
00043		;	ATTENTION ----- Attention signal, (there is enough time during this
00044		;	signal to allow other tasks to be performed)
00045		;	COMMAND ----- 8 Command bits followed by a Stop Bit
00046		;	INTERPRET ----- Decide whether the Host is addressing this Device,
00047		;	if so, decide what Command the Host issued
00048		;	if not, see if the Command is global to all Devices,
00049		;	also determine if the other Application needs to
00050		;	issue a Service to the Host.
00051		;	Tlt ----- The time between the Stop bit of the Command byte and
00052		;	the Start Time of the data being received/sent. Also
00053		;	referred to as Stop to Start Time.
00054		;	SERVICE REQUEST - in order for a Device to alert the Host that it has

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00055 ;          data to send, the line is held down after the Command Stop
00056 ;          Bit (continuing on from the Tlt).
00057 ;   DATA -- a Data Start Bit, followed by 2 Data Bytes (up to as
00058 ;             many as 8 Bytes), and a final Stop Bit
00059 ;
00060 *****
00061 ;
00062 ; THE FOLLOWING IS A MORE DETAILED DESCRIPTION OF THE PROGRAM SEQUENCE:
00063 ;
00064 ; NOTE: words in parenthesis accompanying the TITLES are Labels of
00065 ; procedures corresponding in the code below.
00066 ;
00067 ;*** STARTUP / IDLE *** (Start) ***
00068 ; Startup by setting the ADB pin on PORTA as an input and tri-stating the
00069 ; rest as outputs. The routine then goes to the Reset routine.
00070 ; NOTE: For testing, pin RB1 is is set as an input, and the rest of PORTB
00071 ; is tri-stated as an output.
00072 ;
00073 ;*** INITIALIZE DEFAULT VALUES WHEN THE LINE IS HIGH *** (Reset) ***
00074 ; Look for the line to be high, and when it is, initializes the
00075 ; registers to default values.
00076 ;
00077 ;*** LOOK FOR ATTENTION OR RESET *** (AttnSig) ***
00078 ; Look for the line to go low, when it does, clear the TMR0 and time how
00079 ; long it's low.
00080 ; An Attention Signal has occurred when the line goes high between 776 and
00081 ; 824 usecs.
00082 ; If the low time is measured less than 776 usecs, another signal has
00083 ; occurred and the program aborts, looking for the Attention Signal
00084 ; again. When the low time is measured greater than 824 usecs, the program
00085 ; interprets this timing as a Reset Signal. The program starts over
00086 ; again, waiting for the line to be high, and when it is, performs a
00087 ; Reset initialization.
00088 ;*** OTHER APPLICATION TASKS MAY BE PERFORMED DURING
00089 ;          THE ATTENTION SIGNAL *** (Task_2) ***
00090 ; The time during which the Attention signal takes place allows a second
00091 ; state to occur. The other task(s) is/are given up to 500 usecs during
00092 ; the Attention Signal (900 usecs are given to the 2nd Task during the
00093 ; time between the end of the Data Stop Bit and the beginning of
00094 ; the Attention Signal.
00095 ; It is important to note here that the other task(s) MUST NOT AFFECT
00096 ; THE Timer0 or the time variable (TimeVar) that the Attention Signal is
00097 ; using to keep track of the TMR0.
00098 ;
00099 ;***** NOTE:
00100 ; If at any time during the detection of the Signals below, the line is
00101 ; low or high outside of timing ranges, the routine aborts to see if an
00102 ; Attention or Reset signal has been issued by the Host, or, in the
00103 ; case of sending Data, to the Collision routine.
00104 ;
00105 ;*** LOOK FOR SYNC SIGNAL *** (SyncSig) ***
00106 ; The Sync Signal is the high time between the rising edge of the
00107 ; Attention Signal and the falling edge of the first bit of the Command.
00108 ;
00109 ;*** GET THE COMMAND *** (Command; calls GetBit) ***
00110 ; Look for the Command, a combination of eight 0 and 1 bits, MSB sent
00111 ; first. This is achieved by calling a the GetBit routine which checks
00112 ; whether the maximum time is exceeded, if not, looks for the rising edge
00113 ; at the end of the bit. When the bit is received, it is rotated into a
00114 ; variable, and the end of the bit cell is expected. When the falling
00115 ; edge of the next bit is detected, the routine clears TMR0 and
00116 ; returns to Command, which calls GetBit again until all 8 bits of the
00117 ; Command have been received.
00118 ;*** ISSUE A SERVICE REQUEST IF NECESSARY *** (Srq) ***
00119 ; If data needs to be sent to the Host, issue a Service Request (Srq) by
00120 ; holding the line low while the Stop Bit is being recieved, during the

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```
00121 ;Stop-to-Start time (Tlt) between the end of the Command Stop bit and
00122 ;the beginning of the Data Start Bit.
00123 ;
00124 ;*** LOOK FOR STOP BIT *** (CmdStop)
00125 ;Look for the Stop Bit (a 0 bit of 65 usecs) that comes after the last
00126 ;Command Byte.
00127 ;
00128 ;*** INTERPRET THE COMMAND *** (AddrChk) ***
00129 ;After the Command has been received, determine if the Address belongs to
00130 ;this Device.
00131 ;If the Address is not for this Device determine if the command is
00132 ;global for all Devices and if so, do that command.
00133 ;If this is not a Global/Reserved command, call the Service Request (Srqr)
00134 ;routine to see if an Srqr should to be issued to the Host, and do so if
00135 ;necessary, then return to get the Attn Signal.
00136 ;If the Address is for this Device determine whether it is a Talk,
00137 ;Listen, or Flush Command, and go to the specified command routine.
00138 ;
00139 ;**IF COMMAND IS TALK OR LISTEN, LOOK FOR STOP TO START TIME ** (Tlt) **
00140 ;After the Command and Stop Bit (a 0 bit) the Talk or Listen routine
00141 ;calls the Tlt routine:
00142 ;look for the line to go low,
00143 ;if the line went low before the Min. Tlt Time, see if this is a Talk
00144 ;Command if this is a Talk Command, abort to the Collision routine
00145 ;if this is a Listen Command, abort to the Attention Signal
00146 ;if the Min. Tlt time passes & the line is high,
00147 ;see the Talk routine called the Tlt,
00148 ;if so, go wait for until the middle of the Tlt, then return to
00149 ;Talk to send the Data Start Bit, Data Bytes, and Stop Bit.
00150 ;if at any time the line goes low during the Tlt, abort to the
00151 ;Collision routine
00152 ;if Listen called the Tlt,
00153 ;look for the line to go low as the beginning of the Data Start Bit
00154 ;if the line goes low, return for the rest of the Start Bit
00155 ;if the line doesn't go low before the Max. Tlt time,
00156 ;abort to the Attention Signal
00157 ;
00158 ;*** SENDING DATA *** (Talk) ***
00159 ;If the Command was interpreted to be a Talk Command addressed to this
00160 ;Device, call the Stop-to-Start Time (Tlt) routine.
00161 ;When the Tlt routine has completed, determine if this is a Talk Register
00162 ;3 Command. If so, and if so, return a Random Address as part of the
00163 ;two bytes sent to the Host.
00164 ;if this is not a Talk Register 3 Command, determine if Data needs to be
00165 ;sent. If so, send the Data Start Bit (a '1'), two bytes of Data,
00166 ;and a Stop Bit (a '0'). If not, abort to the Attention Signal
00167 ;If at any time the transmission of Data is interrupted, abort to the
00168 ;Collision routine. Only after a complete transmission should the
00169 ;flags be cleared indicating a successful transmission.
00170 ;NOTE: The ADB Spec. indicates data may be between 2 and 8 bytes long.
00171 ;The limitations of the PIC 16C54/55/56 parts allow only 2 bytes of data
00172 ;to be sent by this program due to limited register space. If more than
00173 ;2 bytes of data must be sent, use the PIC16C57.
00174 ;
00175 ;*** RECEIVING DATA *** (Listen) ***
00176 ;If the Command was interpreted to be a Listen Command addressed to this
00177 ;Device, call the Stop-to-Start Time (Tlt) routine.
00178 ;When the Tlt routine has completed, receive the rest of the Data
00179 ;Start Bit, 2 Data Bytes, and Data Stop Bit.
00180 ;When the Data has been received, determine whether this is a Listen
00181 ;Register 3 Command.
00182 ;if this is a Listen Register 3 Command, interpret what the Command
00183 ;is. If this is a conditional Address change command, determine if
00184 ;this Device's Address is moveable at this time. If not, abort to the
00185 ;Attention Signal. If so, change the Device to the new Address and
00186 ;go run the Second Application Task.
```

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00187 ; if this is not a Listen Register 3 Command, move the Data into the
00188 ; specified register and go run the Second Application Task.
00189 ;
00190 ;*****
00191 ;
00192 ;*** TIMING ALGORITHM ***
00193 ; Timing for ADB signals is done by clearing the TMR0, loading a constant
00194 ; into a time variable, subtracting the TMR0 from the variable,
00195 ; This process is looped until the either the Carry Bit in the Status
00196 ; Register is clear, indicating the amount of time in the time variable
00197 ; has elapsed, or the condition of the data line has been met.
00198 ; If the line goes high or low at an inappropriate time, an error has
00199 ; occurred, and the current operation should be aborted.
00200 ;
00201 ; NOTE: The minimum and maximum values given below for 0 bit, 1 bit, and
00202 ; Tlt timing are slightly shorter and longer than those given in
00203 ; the ADB specification.
00204 ; The following are the timing ranges used
00205 ; by this program for ADB signals:
00206 ; Reset .....Greater Than 824 usecs
00207 ; Attention.....776-824 usecs
00208 ; Sync.....72 usecs
00209 ; Bit Cell.....Up to 104 usecs
00210 ; 1 Bit.....32-40 usecs
00211 ; 0 Bit.....60-72 usecs
00212 ; Stop bit.....60-72 usecs
00213 ; Stop to Start (Tlt)....140-260 usecs
00214 ; Service Request (Srql).....300 usecs
00215 ;
00216 ;
00217 ; A SOMEWHAT GRAPHICAL REPRESENTATION OF THE TIMING SIGNAL RANGES (in
00218 ; usecs):
00219 ; |-----|-----|-----|
00220 ;          30-40    60-70    100
00221 ;          1 Bit   0 Bit   End of Bit Cell
00222 ;
00223 ; |-----|-----|
00224 ;          140-260    300
00225 ;          Tlt      Srql
00226 ;
00227 ; |-----|-----|-----|-----|-----|-----|-----|-----|-----|
00228 ; 0          776      824   Greater than 824....
00229 ; Signal invalid in this area-----| AttnSig   Reset
00230 ;
00231 ;*****
00232 ;
00233 ;***** THE PROGRAM BEGINS HERE *****
00234
00235     include "p16c5X.inc" ; default EQUates for the PIC registers
00001 LIST
00002 ; P16C5X.INC Standard Header File, Version 3.30 Microchip Technology
00224 LIST
00236
000001FF 00237 PIC54 equ 1FFh ; Define the Reset Vector for 16c54.
00238
00000000 00239 NULL equ 00h ; used for returning nothing from a called routine
00240
00000000 00241 LSB equ 00h ; Least Significant Bit
00000007 00242 MSB equ 07h ; Most Significant Bit
00243
00000000 00244 FALSE equ 00h ; For Boolean tests
00000001 00245 TRUE equ 01h
00246
00247     include "adb.equ" ; ADB EQUates
00001 ;***** ADB.EQU Header-sets up EQUates *****
00002

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00003 ;*** TESTING *** BITS USED IN TESTING FOR I/O
00004
00005 ; *** BOOLEANS USED TO SELECT PART BEING USED
00006 ; Only One Part May Be selected at a time
00000000 00007 C54      equ      FALSE ;TRUE
00000000 00008 C55      equ      FALSE
00000001 00009 C56      equ      TRUE  ;FALSE
00000000 00010 C57      equ      FALSE
00011
00000000 00012 LED      equ      00h   ; ***AN LED ON LINE RB0 INDICATES SWITCH PRESSED
00000001 00013 Switch  equ      01h   ; ***'Switch' USED FOR A SWITCH ON LINE RB1 AND
00014 ; *** AS A FLAG IN FLAGS2 FOR DEBOUNCING
00015
00000038 00016 SHIFT   equ      38h
00000012 00017 BANG    equ      12h
00018
00000008 00019 DEBOUNC equ      08h   ; *** #OF TIMES TO LOOP TO ALLOW DEBOUNCE OF SWITCH
00020
00021
00022
00023
00024 ; *** BIT ASSIGNMENTS FOR I/O LINES & TRI-STATING
00025
00000000 00026 ADB      equ      00h   ; Line used for ADB - pin XX (16C54)
00000001 00027 RA1      equ      01h   ; May be used as a Clock line TO another PIC
00000002 00028 RA2      equ      02h   ; May be used as a Clock line FROM another PIC
00000003 00029 RA3      equ      03h   ; May be used as a Data line between two PICs
00030
00000001 00031 TRI_IN   equ      01h   ; tri-state for ADB pin as input
00000000 00032 TRI_OUT  equ      00h   ; tri-state for ADB pin as output
00033
00034
00035 ;*** MISC. CONSTANTS
00036
00000008 00037 BYTE      equ      08h   ; Receive 8 bits in Command; count from 8 to 0
00000002 00038 DEF_ADD  equ      02h   ; default device address to start with (kybd)
00000003 00039 DEF_HND  equ      03h   ; default Handler Id. to start with (std. kybd)
00000008 00040 OFFSET   equ      08h   ; offset to RAM address of the array of ADB
00041 ; Data storage registers
00042
00043
00044 ;*** COMMAND MASKS:          MASK BITS FROM COMMAND REGISTER FOR:
00045
0000000F 00046 DEVMASK  equ      0Fh   ;lower nibble holds Command (Talk, etc.) & Reg. #
000000F0 00047 ADDRMSK  equ      0F0h   ;upper nibble holds the Device Address Number
0000000F 00048 CMDNIBL  equ      0Fh   ;Command nibble from the address
0000000C 00049 CMDTYPE  equ      0Ch   ;Upper 2 Command bits indicate Talk, Listen, etc.
00000003 00050 REGMASK  equ      03h   ;Data Register Number bits from Command Nibble
0000001F 00051 FSRMASK  equ      1Fh   ;FSR bits from the Command Nibble for RAM Address
00052
00053
00054 ;*** DATA COMMAND MASKS:      MASK DATA REGISTER 3a FOR:
00055
0000000F 00056 LOW_NBL  equ      0Fh   ; Lower nibble from the 1st Data byte
000000F0 00057 HI_NIBL  equ      0F0h   ; Upper nibble from the 1st Data byte
00058
00059
00060 ;*** CONSTANTS FOR MASKING OUT COMMAND NIBBLES (C_ indicates Command)
00061
00062 ; used to XOR if this is a:
0000000C 00063 C_TALK   equ      0Ch   ; Talk Command
00000008 00064 C_LISTN  equ      08h   ; Listen Command
00000000 00065 C_RESET  equ      00h   ; Reset Command
00000001 00066 C_FLUSH  equ      01h   ; Flush Command
00000004 00067 C_RES_1  equ      04h   ; Reserved Command 1
00000002 00068 C_RES_2  equ      02h   ; Reserved Command 2

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00000003      00069 C_RES_3 equ      03h      ;   Reserved Command 3
00070
00071
00072 ;*** DATA HANDLER ID MASKS: MASK DATA REGISTER 3b FOR:
00073
000000FF      00074 SELFTST equ      0FFh      ; Self-Test mode
00000000      00075 LISTEN1 equ      0h        ; unconditional address change
000000FE      00076 LISTEN2 equ      0FEh      ; address change if no collision detected
000000FD      00077 DEV_ACT equ      0FDh      ; address change if device activator is depressed
00078
00079
00080 ;BITS USED IN THE UPPER NIBBLE OF REGISTER 3a FOR SPECIAL ADB STATUS BITS
00081
00000004      00082 Resrvd3 equ      04h        ; reserved (Always 0)
00000005      00083 Srq_Bit equ      05h        ; determines if Host will accept Service Requests
00000006      00084 ExpEvt equ      06h        ; indicates an Exceptional Event should take place
00000007      00085 Always0 equ      07h        ; always set to 0
00086
00087
00088 ;ADB FLAG BITS IN THE "FLAGS1" REGISTER (F1 indicates 1st Flags register)
00089
00000000      00090 F1Attn equ      00h        ; set to know if 2nd Task taking place during Attn
00000001      00091 F1Reg3 equ      01h        ; Register 3 is being addressed
00000002      00092 F1Talk equ      02h        ; indicates to Tlt routine this is a Talk Command
00000003      00093 F1Stop equ      03h        ; set to indicate the Data Stop Bit is being sent
00000004      00094 F1Lstn equ      04h        ; indicates to Tlt routine this is a Listen Command
00000005      00095 F1Sent1 equ      05h        ; 1st byte of Data Register has been sent
00000006      00096 F1Rcvd1 equ      06h        ; 1st byte of Data Register has been received
00000007      00097 F1Clsln equ      07h        ; set to indicate that a collision occurred
00098
00099
00100 ;*** FLAG BITS IN THE "FLAGS2" REGISTER (F2 indicates 2nd Flags register)
00101
00000000      00102 F2Srq equ      00h        ; indicate that Srq should be issued
00103 ;
00104 F2DActv equ      02h        ; change address if Device Activator is Depressed
00000002      00105 F2STest equ      03h        ; set to indicate a device Self Test to be performed
00000003      00106 F2SFail equ      04h        ; set to indicate that the Device Self-Test Failed
00000004      00107 F2DRcvd equ      05h        ; set when data is received for 2nd Application Task
00000005      00108 F2DSend equ      06h        ; set to indicate to Talk that Data needs to be sent
00000006      00109 F2DMore equ      07h        ; set in 2nd Task to indicate Data remains to be sent
00110
00111
00112 ;*** TIMING DEFINITIONS
00113 ;
00114 ; These values currently used for clock at 4Mhz:
00000004      00114 PrSclr1 equ      .4        ; this is used when TMR0 is being prescaled
00000001      00115 PrSclr2 equ      .1        ; this is used when TMR0 is not prescaled
00116
000000C2      00117 ATT_MIN equ      .776/PrSclr1 ; Attn lower limit:800 - 3% tolerance=776 usecs
000000CE      00118 ATT_MAX equ      .824/PrSclr1 ; Attn upper limit:800 + 3% tolerance=824 usecs
0000007D      00119 TSK2MIN equ      .500/PrSclr1 ; time given to 2nd Task during Attn Signal
000000E1      00120 TSK2MAX equ      .900/PrSclr1 ; time given to 2nd Task after Data Sent/Received
00000048      00121 SYNC equ      .72/PrSclr2 ; Sync with extra tolerance after Attn detect
00000032      00122 BIT_TST equ      .50/PrSclr2 ; if time is < 50 = 1 bit, & > 50 = 0 bit
00000048      00123 MAX_BIT equ      .72/PrSclr2 ; Maximum time line can be low for a bit
00000068      00124 BITCELL equ      .104/PrSclr2 ; Maximum time for a bit cell = 104 usecs
0000008C      00125 TLT_MIN equ      .140/PrSclr2 ; Stop to Start minimum time = 140 usecs
000000FA      00126 TLT_MAX equ      .250/PrSclr2 ; Stop to Start maximum time = 260 usecs
000000B4      00127 TLT_MID equ      .180/PrSclr2 ; Stop to Start median time = 208 usecs
0000004A      00128 SRQ_MAX equ      .296/PrSclr1 ; amount of time to hold for a Service ReQuest
00129
00130 ;NOTE: for Timer0 timing of sending bits, some extra time is allowed for
00131 ;instruction cycles between the end of the bit and the start of the next
00132 ; bit
00000016      00133 LOW1BIT equ      .22/PrSclr2 ; low time for a 1 bit
00000032      00134 HI_1BIT equ      .50/PrSclr2 ; hi time for a 1 bit

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00000038      00135 LOW0BIT equ  .56/PrSclr2  ; low time for a 0 bit
00000014      00136 HI_0BIT equ  .20/PrSclr2  ; hi time  for a 0 bit
00137
00138
00139 ;*** ADB DATA REGISTERS - 2 BYES FOR EACH OF REGISTERS 0, 1, 2, and 3
00140
0008      00141 ADB_REG ORG   08h      ; ORIGIN FOR ADB DATA REGISTERS
0008      00142 Reg0a  RES   01h      ; 8
0009      00143 Reg0b  RES   01h      ; 9
000A      00144 Reg1a  RES   01h      ; A
000B      00145 Reg1b  RES   01h      ; B
000C      00146 Reg2a  RES   01h      ; C
000D      00147 Reg2b  RES   01h      ; D
000E      00148 Reg3a  RES   01h      ; E
000F      00149 Reg3b  RES   01h      ; F
00150
00151
00152 ;* VARIABLE REGISTERS FOR STORAGE, FLAGS, THE TIME VARIABLE,
00153 ;  THE COUNTER, & RANDOM VALUES
00154
0010      00155 STORAGE ORG   10h      ; ORIGIN FOR MISC. DATA VARIABLES
0010      00156 TmpReg1 RES   01h      ; 10 - temporary registers where Data is sent from &
0011      00157 TmpReg2 RES   01h      ; 11 - received; NOTE: THESE 2 MUST BE IN THIS ORDER
0012      00158 RegNum  RES   01h      ; 12 - holds current ADB Data Reg.#-NOT a RAM address
0013      00159 RAMaddr RES   01h      ; 13 - holds RAM address of ADB Data Reg.#
0014      00160 Flags1  RES   01h      ; 14 - two Flags registers used by ADB & 2nd
0015      00161 Flags2  RES   01h      ; 15 - Application Task
0016      00162 CmdByte RES   01h      ; 16 - holds the Command Byte
0017      00163 BitCntr RES   01h      ; 17 - counts down when sending or receiving bits
0018      00164 Random  RES   01h      ; 18 - stores Random Address sent in Talk routine
0019      00165 TimeVar  RES   01h      ; 19 - used with TMR0 for all ADB timing
001A      00166 Tsk2Var RES   01h      ; 1A - used with TMR0 for timing during 2nd Task
00167
00168
00169 ;*** REGISTERS STILL AVAILABLE
00170
001B      00171 TmpCtrl1 RES   01h      ; 1B
001C      00172 TmpFlg1 RES   01h      ; 1C
001D      00173 TmpFlg2 RES   01h      ; 1C
001E      00174 TmpFlg3 RES   01h      ; 1D
001F      00175 TmpFlg4 RES   01h      ; 1E
00176
00177
0000      00178 PROGRAM ORG   00h      ; origin for program
00248      include "adb.sub"      ; ADB Sub-Routines - these must be included
00001 ;*****
00002 ;*****
00003 ; *****      THE FOLLOWING ARE SUB-ROUTINES      *****
00004 ; *****      CALLED BY THE MAIN PROGRAM      *****
00005 ;*****
00006 ;*****
00007
00008 ;*** SWITCH PRESCALER BETWEEN WDT AND Timer0 *** (PrScale, NoPrScl) ***
00009 ;*** THIS PROCEDURE, DOCUMENTED IN SPEC. SHEET SECTION 9.1, IS INTENDED
00010 ;*** TO PREVENT UNEXPECTED RESET CONDITION
00011
00012 ;*** PrScale ROUTINE CALLED AT END OF AttnSig AND Srq SIGNALS
0000 0004      00013 PrScale clrwtd      ; Change prescaler from WDT to TMR0
0001 0C01      00014      movlw  b'00000001' ; BINARY - set to prescale TMR0
0002 0002      00015      option      ; Clear 4th bit from right to select TMR0
0003 0061      00016      clrf      TMR0      ; last 3 bits set prescale value as 1:4
0004 0800      00017      retlw  NULL      ; this gives a good ratio to monitor the
00018      ; timing for Reset and Attention signals and
00019      ; the 2nd Application Task
00020
00021 ;***NoPrScl ROUTINE CALLED AT BEGINNING OF SyncSig AND END OF Srq SIGNALS

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0005 0061      00022 NoPrSc1 clrf    TMR0          ; Change prescaler from TMR0 to WDT
0006 0C08      00023      movlw    b'00001000' ; Set 4th bit from right to select WDT
0007 0002      00024      option
0008 0004      00025      clrwdt
0009 0C08      00026      movlw    b'00001000'
000A 0002      00027      option
000B 0800      00028      retlw    NULL
00029
00030 ;*****
00031
00032 ;*GET INCOMING BIT & INTERPRET WHETHER IT'S A '1' OR A '0' *** (Get_Bit)*
00033 ;** Get_Bit CALLED BY COMMAND AND LISTEN ROUTINES
00034 ; Get the bit, find out whether it's less than or greater than 50 usecs,
00035 ; if < than 50 usecs, it's a '1' bit
00036 ; if > than 50 usecs, it's a '0' bit
00037 ; if it's a '1' bit, set LSB in the reg. pointed to by the FSR (Command
00038 ; Byte) if it's a '0' bit, do nothing to the LSB
00039 ; then look for the end of the Bit Cell (104 usecs max.)
00040 ; if the maximum Bit time of (72 usecs) or maximum Bit Cell time is
00041 ; exceeded, abort to the Attn Signal
00042
000C 0201      00043 Get_Bit movf    TMR0,W ; Check the time, then check if the line went high:
000D 0099      00044      subwf    TimeVar,W ; See if more than BIT_TST usecs have passed
000E 0703      00045      btfss    STATUS,C ; if not, check whether the line went high
000F 0AAB      00046      goto     AttnSig ; if so, abort to the Attn Signal
0010 0705      00047      btfss    PORTA,ADB ; Check whether the line went high
0011 0A0C      00048      goto     Get_Bit ; if line is still low, loop again
0012 0C32      00049      movlw    BIT_TST ; if line went high, see if it's a '1' or a '0'
0013 0039      00050      movwf    TimeVar ; as the bit has not yet been determined yet,
0014 0400      00051      bcf      INDF,LSB ; ensure the LSB in the indirect address is '0'
0015 0201      00052      movf     TMR0,W ; Get the time
0016 0099      00053      subwf    TimeVar,W ; if time < 50 usecs, it's a '1' bit
0017 0603      00054      btfsc    STATUS,C ; if time > 50 usecs and < 72, it's a '0' bit
0018 0500      00055      bsf      INDF,LSB ; if it's a 1, set LSB in the address FSR points
0019 0C68      00056      movlw    BITCELL ; to Check whether the Max. Bit Cell time of
001A 0039      00057      movwf    TimeVar ; 104 usecs has been exceeded
001B 0201      00058 CellChk movf    TMR0,W ; Check the time, then check the line
001C 0099      00059      subwf    TimeVar,W ; See if more than Max. Bit Cell usecs have
001D 0703      00060      btfss    STATUS,C; passed if not, look for the line to go low again
001E 0AAB      00061      goto     AttnSig ; if so, abort to the Attn Signal or Reset
001F 0605      00062      btfsc    PORTA,ADB ; Check the line for the start of another bit
0020 0A1B      00063      goto     CellChk ; if the line is still high, loop CelChk1 again
0021 0061      00064      clrf     TMR0 ; if the line went low, clear the TMR0 & return
0022 0800      00065      retlw    NULL ; for another bit or to interpret the Command
00066
00067 ;*****
00068 ;* DETERMINE IF THIS IS A GLOBAL COMMAND TO ALL DEVICES *** (Globals) *
00069 ;** Globals CALLED BY AddrChk
00070
00071 Globals movf    TmpReg2,W ; Check whether the Command is for all devices
00072      xorlw    C_RES_1 ; retrieve the Command Type (the upper 2 bits
00073      btfsc    STATUS,Z ; of the Command nibble)
00074      goto     Reserv1 ; test for this being the first Reserved
00075      movf     TmpReg1,W ; Command retrieve the whole Command Nibble
00076      xorlw    C_RES_2 ; test for this being the second Reserved Command
00077      btfsc    STATUS,Z
00078      goto     Reserv2
00079      movf     TmpReg1,W ; retrieve the whole Command Nibble
00080      xorlw    C_RES_3 ; test for this being the third Reserved Command
00081      btfsc    STATUS,Z
00082      goto     Reserv3
00083      xorlw    C_RESET ; test for this being Reset Command
00084      btfsc    STATUS,Z
00085      goto     Reset
00086      retlw    NULL
00087

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```

00088 ;*****
00089
00090 ;* MASK OUT COMMAND NIBBLE AND REG.# BITS FROM THE COMMAND *** (MaskCmd)*
00091 ; NOTE: This routine should only be called once during any single ADB
00092 ; transaction, from either AddrChk or CmmndChk
00093
0033 0216 00094 MaskCmd movf  CmdByte,W ; Mask the Command to save the Data Reg. # bits &
0034 0E0F 00095         andlw  CMDNIBL  ; the Command Type bits (Listen, Talk, etc.):
0035 0030 00096         movwf  TmpReg1   ; save the Command nibble
0036 0E0C 00097         andlw  CMDTYPE  ; mask the upper 2 Command Type bits (Talk, etc.)
0037 0031 00098         movwf  TmpReg2   ; save the upper 2 Command Type bits
0038 0216 00099         movf  CmdByte,W : extract the Data Register number:
0039 0E03 00100         andlw  REGMASK  ; mask out Data Reg. number from Command Nibble
003A 0032 00101         movwf  RegNum   ; save the Data Reg. bits
003B 0024 00102         movwf  SR      ; save pointer to Data Reg. in File Select Reg.
00103         ; in order to setup RAM address where start
00104         ; of Data for this Reg. will be stored
003C 0403 00105 SaveRAM bcf      STATUS,C; clear Carry bit so it doesn't wrap around
003D 0364 00106         rlf      FSR,F  ; multiply by 2 to get 1st Byte of RAM addr
003E 0564 00107         bsf      FSR,03h ; add array offset for Send/Receive/Flush Reg.
003F 0204 00108         movf  FSR,W   ; by setting bit of 1st RAM address, which
0040 0E1F 00109         andlw  FSRMASK ; is ORG'd in ADB.EQU equates
0041 0033 00110         movwf  RAMaddr ; mask out the RAM address of Data Reg. Number
0042 0800 00111         retlw  NULL   ; save RAM address of Data Reg. and return
00112
00113 ;*****
00114
00115 ;*** ISSUE A SERVICE REQUEST IF NECESSARY *** (Srq; may call LineLow) ***
00116 ;*** CALLED BY AddrChk
00117 ; see if the Srq Flag is set, if not, return, otherwise:
00118 ; change the prescaler to TMR0 since this takes longer than 255 usecs,
00119 ; load the SRQTIME of 300 usecs into the TimeVariable,
00120 ; call LineLow to:
00121 ; keep checking the time to see if 300 usecs have passed,
00122 ; let the line go high again,
00123 ; and see if the line is high, and if not, abort, if it is,
00124 ; change the prescaler back to WDT, and return
00125
0043 0715 00126 Srq      btfss   Flags2,F2Srq ; see if the Srq flag is set,
0044 0800 00127         retlw  NULL           ; if not, return
0045 0900 00128         call   PrScale          ; switch the prescaler to TMR0
0046 0C00 00129         movlw  TRI_OUT      ; tri-state PORTA to make the ADB an output
0047 0005 00130         tris   PORTA
0048 0C4A 00131         movlw  SRQ_MAX
0049 0976 00132         call   LineLow
004A 0905 00133         call   NoPrScl      ; change the prescaler back to WDT
004B 0800 00134         retlw  NULL
00135
00136 ;*****
00137
00138 ;*** Tlt - TIME FROM STOP BIT TO START BIT *** (Tlt) ***
00139 ;*** CALLED BY EITHER Talk OR Listen ROUTINES
00140 ; Loop checking the time, then checking the line to see if it went low
00141 ; if at any time the line goes low,
00142 ; see if this is a Talk Command,
00143 ; if it is a Talk Command, go to the Collision routine
00144 ; if the line goes low before the minimum Tlt time, abort to Attn Signal
00145 ; if the line is high longer than TLT_Min usecs,
00146 ; see if this is a Talk Command, and if it is, wait for the mid-point,
00147 ; and return to Send the Start Bit, Data Bytes, & the Stop Bit
00148 ; if it's not a Talk Command, see if it's a Listen Command, and if so,
00149 ; load Tlt_Max for TimeVariable, and look for the line to go
00150 ; low as the beginning of the Start Bit,
00151 ; if more than Tlt_Max usecs pass, abort to Attn Signal
00152 ; if the line goes low and this is a Listen Command,
00153 ; clear the TMR0 & return to get the rest of the Start Bit

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00154
004C 0C8C      00155 Tlt      movlw   TLT_MIN      ; Look for Stop-to-Start-Time, Tlt
004D 0039      00156      movwf   TimeVar      ; Check the time, then check the line
004E 0201      00157 TltChk1 movf    TMR0,W      ; See if more than TLT_MIN usecs have passed
004F 01B8      00158      xorwf   Random,F      ; (ensure the Talk R3 address is Random with
0050 0099      00159      subwf   TimeVar,W      ; XOR) by checking whether Carry bit is set
0051 0703      00160      btfss   STATUS,C      ; after subtraction
0052 0A5D      00161      goto    ChkFlag      ; if TLT_MIN usecs passed, see what Command
0053 0605      00162      btfsc   PORTA,ADB      ; this is if not, check whether the line went
0054 0A4E      00163      goto    TltChk1      ; low if the line is still high, keep looping
0055 0654      00164      btfsc   Flags1,F1Talk; if line went low, see if this is a Talk
0056 0B5A      00165      goto    Collisn      ; Command if it is, there was a Collision,
0057 0201      00166      movf    TMR0,W      ; abort otherwise, check the time
0058 0099      00167      subwf   TimeVar,W      ; see if TLT_MIN usecs passed,
0059 0703      00168      btfss   STATUS,C      ; if not, abort to Attn Signal, too little
005A 0AAB      00169      goto    AttnSig      ; time passed when the line went low
005B 0061      00170      clrf    TMR0      ; if it's not a Talk Command, clear the TMR0
005C 0800      00171      retlw   NULL      ; and return for the rest of the Start Bit
00172
005D 0654      00173 ChkFlag btfsc   Flags1,F1Talk ; Check whether to Talk or Listen
005E 0A6D      00174      goto    TltTalk      ; if Talk, wait for mid-point of Tlt time
005F 0794      00175      btfss   Flags1,F1Lstn ; if Listen, continue to look for Start Bit
0060 0800      00176      retlw   NULL      ; if neither flag is set, abort, something's
0061 0CFA      00177      movlw   TLT_MAX      ; wrong Load TimeVariable to check for
0062 0039      00178      movwf   TimeVar      ; upper limit of Tlt time
0063 0201      00179 TltChk2 movf    TMR0,W      ; See if TLT_MAX usecs have been exceeded
0064 0099      00180      subwf   TimeVar,W      ; by checking whether Carry bit is set
0065 0703      00181      btfss   STATUS,C      ; after subtraction
0066 0AAB      00182      goto    AttnSig      ; if so, abort to Attn Signal
0067 0605      00183      btfsc   PORTA,ADB      ; if not, check whether the line went low
0068 0A63      00184      goto    TltChk2      ; if line is still high, check the time again
0069 0654      00185      btfsc   Flags1,F1Talk ; if line went low, see if this is a Talk
006A 0B5A      00186      goto    Collisn      ; Command if so, there was a Collision
006B 0061      00187      clrf    TMR0      ; if it's not a Talk Command, return to get
006C 0800      00188      retlw   NULL      ; the rest of the Start Bit from Host
00189
006D 0CB4      00190 TltTalk movlw   TLT_MID      ; Load TimeVariable so Talk will send Start
006E 0039      00191      movwf   TimeVar      ; Bit at about the mid-point of the Tlt
006F 0201      00192 TltChk3 movf    TMR0,W      ; See if TLT_MID usecs have been exceeded
0070 0099      00193      subwf   TimeVar,W      ; by checking whether Carry bit is set
0071 0703      00194      btfss   STATUS,C      ; after subtraction
0072 0800      00195      retlw   NULL      ; if time was exceeded, return to send Start Bit
0073 0605      00196      btfsc   PORTA,ADB      ; if not, check whether the line went low
0074 0A6F      00197      goto    TltChk3      ; if line is still high, check the time again
0075 0B5A      00198      goto    Collisn      ; if the line went low, abort to Collision
00199
00200 ;*****
00201
00202 ;*** MAKE LINE GO LOW TIME IN TimeVar AS A '1' OR '0' BIT***(LineLow)***
00203 ;*** CALLED BY Talk OR Srq
00204
0076 0039      00205 LineLow movwf   TimeVar      ;
0077 0201      00206 Low_Tmp movf    TMR0,W      ; Check the clock,
0078 0099      00207      subwf   TimeVar,W      ; loop until TimeVar usecs have passed
0079 0603      00208      btfsc   STATUS,C;
007A 0A77      00209      goto    Low_Tmp      ;
007B 0C01      00210      movlw   TRI_IN      ; Tri-state PORTA to make ADB line an input
007C 0005      00211      tris    PORTA      ; again and let the line go high
007D 0061      00212      clrf    TMR0      ; and clear TMR0
007E 0000      00213      nop      ; Allow the ADB Port line to stabilize
007F 0000      00214      nop      ; Allow the ADB Port line to stabilize
0080 0705      00215      btfss   PORTA,ADB      ; check if the line is still low, if so, a
0081 0B5A      00216      goto    Collisn      ; Collision occurred
0082 0800      00217      retlw   NULL      ; if not, return to load high time for rest of bit
00218
00219 ;* MAKE LINE GO HIGH FOR REST OF BIT CELL TIME IN TimeVar *** (LineHi)*

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00220 ;*** CALLED BY Talk
00221
0083 0039 00222 LineHi movwf TimeVar ; Let the line go high for a pre-designated time
0084 0201 00223 Hi_Tmp movf TMR0,W ; Check the clock,
0085 0099 00224 subwf TimeVar,W; loop until TimeVar usecs have passed
0086 0603 00225 btfsc STATUS,C ;
0087 0A84 00226 goto Hi_Tmp ;
0088 0705 00227 btfss PORTA,ADB; check if the line is still high,
0089 0B5A 00228 goto Collisn ; if not, a Collision occurred, Abort
008A 0674 00229 btfsc Flags1,F1Stop; if this is the end of the Data Stop Bit,
008B 0800 00230 retlw NULL ; don't let the line go low again, just return
008C 0C00 00231 movlw TRI_OUT ; if still high, start sending a bit to the Host
008D 0005 00232 tris PORTA ; tri-state PORTA to make the ADB an output and
008E 0061 00233 clrf TMR0 ; return
008F 0800 00234 retlw NULL ;
00235
00236 ;*****
00237 ;*****
00238 ; ***** END OF SUB-ROUTINES *****
00239 ;*****
00240 ;*****
00241 ; here to ensure being in the first
00250 ; half of the memory page when called.
00251
00252 IntData macro DataCmd,Routine ; Macro goes to an appropriate Listen Reg.3
00253 movf TmpReg2,W ; interprets the Data Command received by
00254 xorlw DataCmd ; comparing the 2nd byte to a Data
00255 btfsc STATUS,Z ; Command constant
00256 goto Routine ; it then goes to the appropriate routine
00257 endm
00258
00259 ;
00260 ;*** CONDITIONAL ASSEMBLY DETERMINED BY LIST DIRECTIVE
00261 ;
00262 ifdef __16C56
00263 include "5657macro.mod" ; macros for the 2nd Application Task
00001 ;
00002 ;*** LoadEm MACRO USED FOR TESTING DURING 2ND APPLICATION TASK
00003 ;*** ONLY FOR PART 16c56/57
00004 ;
00000004 00005 H equ 04h ; *** THESE ARE USED AS KEYS PRESSED WHEN PART
0000000E 00006 E equ 0Eh ; *** IS SELECTED FOR 16C56/57
00000025 00007 L equ 25h
0000001F 00008 O equ 1Fh
00000031 00009 SP equ 31h
0000000D 00010 WW equ 0Dh ; W is already defined in the PICREG5X.EQU file
0000000F 00011 R equ 0Fh
00000002 00012 D equ 02h
00000024 00013 RETRN equ 24h
000000FF 00014 FILLCHR equ 0FFh ; 'fill character' as described in spec.
00015 ;
00016 ;
00017 LoadEm macro Ctr,Bit,Dest,RegA,RegB; Macro used to load registers and
00018 btfss Ctr,Bit ; set flags for Key-Up Transition Codes
00019 goto Dest ; Bits are cleared as the data is sent
00020 movlw Reg0a
00021 movwf FSR
00022 movlw RegA ; load data to be sent from register A
00023 movwf INADDR
00024 incf FSR,F
00025 movlw RegB ; load data to be sent from register B
00026 movwf INADDR ; load data to be sent from register B
00027 bsf Flags2,F2DSend; Data now needs to be sent to the host
00028 bsf Flags2,F2Srq ; Until all data has been sent, Srq's may
00029 btfsc Flags2,F2STest; be sent. See if Key Transition Codes
00030 goto KeyUp ; should be sent if so, go set the bits

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00031      bsf      Flags2,F2STest; if not, set bits so they'll be next time
00032      bcf      Ctr,Bit      ; clear the bit so next data will be sent
00033      goto     DBounce      ; and go debounce the switch
00034      endm
00035
00036
00037
00264      endif          ; the program is for a 16C56
00265      ifdef      __16C57      ; or 16C57 part
00266      include    "5657macro.mod"
00267      endif
00268
00269 ;*****
00270 ;*****
00271 ; THE MAIN PROGRAM STARTS BELOW
00272 ;*****
00273 ;*****
00274
0090 0C01      00275 Start movlw   TRI_IN      ; Start off by making the ADB pin an
0091 0005      00276      tris     PORTA      ; input on PORTA
0092 0405      00277      bcf      PORTA,ADB ; make line will go low when tris'd as an output
00278
00279 ; *** THIS I/O SETUP ROUTINE IS USED FOR TESTING WITH AN LED ON RB0
00280 ; *** AND A SWITCH ON RB1
0093 0C02      00281 TSTING1 movlw   b'00000010'; Make RB0 an output (for the LED) and
0094 0006      00282      tris     PORTB      ; RB1 an input (for the normally open switch)
0095 0406      00283      bcf      PORTB,LED ; Make sure the LED is off to begin with
00284
00285 ;*****
00286
0096 0705      00287 Reset btfss   PORTA,ADB ; Reset Signal - loop until the line is high,
0097 0A96      00288      goto     Reset      ; then initialize Registers
00289
0098 0070      00290 Init  clrf     TmpReg1   ; Initialization routine
0099 0071      00291      clrf     TmpReg2   ; Clear variables
009A 0072      00292      clrf     RegNum    ; NOTE: No need to clear variable register
009B 0073      00293      clrf     RAMaddr   ; 'Random' as it is XOR'd in other routines
009C 0074      00294      clrf     Flags1    ; to produce a random Address for the 'Talk
009D 0075      00295      clrf     Flags2    ; Reg. 3' Command
009E 0077      00296      clrf     BitCntr   ;
009F 0068      00297      clrf     Reg0a     ; Clear ADB Storage Data Register Variables
00A0 0069      00298      clrf     Reg0b
00A1 006A      00299      clrf     Reg1a
00A2 006B      00300      clrf     Reg1b
00A3 006C      00301      clrf     Reg2a
00A4 006D      00302      clrf     Reg2b
00303
00A5 0C02      00304      movlw   DEF_ADD   ; Register 3 has special Default Data set at
00A6 002E      00305      movwf   Reg3a     ; Reset: load Register 3a with Default Device
00A7 05AE      00306      bsf      Reg3a,Srq_Bit; Address allow Service Requests of Host
00A8 05CE      00307      bsf      Reg3a,ExpEvt; include the Exceptional Event bit as
00308      ;default * NOTE: at this time, this Device
00309      ; doesn't process for Exceptional Events
00A9 0C03      00310      movlw   DEF_HND   ;
00AA 002F      00311      movwf   Reg3b     ; load Register 3b with Default Device Handler ID
00312
00313 ;*****
00314
00315 ;*** LOOK FOR ATTENTION OR RESET *** (AttnSig) ***
00316 ; Look for the line being low, when it is, see if the line went high.
00317 ; During that time, allow the 2nd Application Task to be performed for a
00318 ; limited amount of time, then return to Attn Signal
00319 ; if the line went high, did it go high within the 776-824 usec range?
00320 ; if so, go on to get the Command
00321 ; if not, goto the Reset routine
00322 ; IN DETAIL:

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00323 ; look at the line
00324 ; if the line is not yet low,
00325 ; loop until it goes low, & clear the TMR0
00326 ; Loop with Minimum Time: check the time
00327 ; if the time is less than the Attention Minimum usecs,
00328 ; check whether the line has gone high,
00329 ; if the line has not gone high,
00330 ; loop again checking the time
00331 ; if the line has gone high,
00332 ; check whether the Min. usecs have passed
00333 ; if not, Abort; too little time went by.
00334 ; if so, go on to look for the Sync signal
00335 ; Loop with Maximum Time: load the Maximum Time Variable & check
00336 ; the time if the time is less than the Attention Maximum usecs,
00337 ; check whether the line has gone high,
00338 ; if the line has not gone high,
00339 ; loop again checking the time
00340 ; if the line has gone high before Max. Attention usecs have passed,
00341 ; go on to look for the Sync signal
00342 ; if the time is greater than the Attention Maximum usecs,
00343 ; abort to Reset
00344
00345 ;*****
00346
00AB 0201 00347 AttnSig movf    TMR0,W          ; Look for Attn between ATT_MIN - ATT_MAX usecs
00AC 07F4 00348         btfss   Flags1,F1Cllsn; this is a good time to use the TMR0 and
00AD 01B8 00349         xorwf   Random,F          ; Pseudo-Random Address
00AE 0605 00350         btfsc   PORTA,ADB          ; See if the line went low
00AF 0AAB 00351         goto    AttnSig           ; Loop to AttnSig until the line goes low
00B0 0900 00352         call    PrScale           ; Switch prescaler to TMR0 for > 250 usec count
                                00353         ; during Attn Signal
00B1 0CC2 00354         movlw   ATT_MIN          ;
00B2 0039 00355         movwf   TimeVar       ; use TimeVariable to subtract from ATT_MIN usecs
                                00356
00B3 0076 00357 CleanUp clrf    CmdByte       ; Clear the Command Byte
00B4 0070 00358         clrf    TmpReg1          ; Clear the temporary Data registers
00B5 0071 00359         clrf    TmpReg2          ; NOTE: No need to clear variable register
00B6 0072 00360         clrf    RegNum          ; 'Random' clear the current Register Number
00B7 0073 00361         clrf    RAMAddr        ; register clear the register holding the RAM
                                00362         ; Address of the 1st byte of where Data is stored
00B8 0514 00363         bsf     Flags1,F1Attn; Set this bit to indicate to the 2nd Task
                                00364         ; that it should Return to the AttnMin routine
00B9 0434 00365         bcf     Flags1,F1Reg3      ; Clear Flags: Data-for-Register 3
00BA 0454 00366         bcf     Flags1,F1Talk      ; Talk
00BB 0474 00367         bcf     Flags1,F1Stop      ; Data-Stop-Bit-is-being-sent
00BC 0494 00368         bcf     Flags1,F1Lstn      ; Listen
00BD 04B4 00369         bcf     Flags1,F1Sent1     ; Sent-1st-Byte
00BE 04D4 00370         bcf     Flags1,F1Rcvd1     ; Received-1st-Byte
                                00371
00BF 0C7D 00372         movlw   TSK2MIN          ; load Task 2 Time Variable with amount allowed
00C0 003A 00373         movwf   Tsk2Var          ; during Attn Signal
00C1 0BCB 00374         goto    Task_2          ; This space allows running a second application
                                00375         ; NOTE: BE SURE TO RETURN TO ATTNMIN BEFORE 750
                                00376         ; usecs HAVE PASSED, AND DON'T LET THE OTHER
                                00377         ; APPLICATION AFFECT THE Timer0 or TimeVar.
                                00378
00C2 0201 00379 AttnMin movf    TMR0,W          ; Check the time, then check the line
00C3 0099 00380         subwf   TimeVar,W        ; See if more than ATT_MIN usecs have passed
00C4 0703 00381         btfss   STATUS,C          ; if not, check the line
00C5 0ACD 00382         goto    AttnMax          ; if so, go check time/line again in AttnMax
00C6 0705 00383         btfss   PORTA,ADB          ; Check for line being high & if so, check time
00C7 0AC2 00384         goto    AttnMin          ; if line is still low, loop again
00C8 0201 00385         movf    TMR0,W          ; if line is high, see if time is in range
00C9 0099 00386         subwf   TimeVar,W        ; by checking whether Carry bit is
00CA 0703 00387         btfss   STATUS,C          ; set after subtraction
00CB 0AAB 00388         goto    AttnSig          ; If time <= Min, look for Attn Signal again

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00CC 0AD6      00389      goto      SyncSig      ; If time > Min, go get Sync signal
                                00390
00CD 0CCE      00391 AttnMax movlw   ATT_MAX      ; Load the TimeVariable to check for the
00CE 0039      00392      movwf      TimeVar      ; maximum amount of time for Attn Signal
00CF 0201      00393 AttnTmp movf     TMR0,W       ; Check the time, then check the line
00D0 0099      00394      subwf      TimeVar,W     ; See if more than ATT_MAX usecs have passed
00D1 0703      00395      btfss      STATUS,C      ; if not, check the line
00D2 0A96      00396      goto      Reset         ; if so, Abort to Reset;too much time has passed
00D3 0705      00397      btfss      PORTA,ADB     ; Check for the line to going high
00D4 0ACF      00398      goto      AttnTmp        ; if the line isn't high, loop AttnMax again
00D5 0061      00399      clrf       TMR0          ; if the went high, go get the Sync signal
                                00400
                                00401 ;*****
                                00402
                                00403 ;*** LOOK FOR SYNC SIGNAL *** (SyncSig) ***
00404 ; This routine checks the timing between the rising edge of the Attention
00405 ; Signal & a falling edge indicating the start of the 1st Command bit.
00406 ; At the end of the Attn Signal routine, the line went high, and
00407 ; the TMR0 was cleared.
00408 ; Check the TMR0,
00409 ; if the 72 usec limit is exceeded,
00410 ; abort to the Attn Signal
00411 ; if the 72 usec limit is not exceed,
00412 ; check the line
00413 ; if the line went low (as the first bit of the Command),
00414 ; go on to get the 8 Command Bits
00415 ; if the line is still high,
00416 ; loop to check TMR0 again
00417
00418 ;*****
00419
00D6 0905      00420 SyncSig call     NoPrSc1      ; Get the Sync Signal which follows the Attn
00D7 0C48      00421      movlw      SYNC         ; Signal Turn off prescaler; timing counts are
00D8 0039      00422      movwf      TimeVar      ; < 255 usecs and load the timing the for the
00D9 0099      00423 SyncTmp subwf     TimeVar,W   ; Sync Signal See if more than SYNC usecs
00DA 0703      00424      btfss      STATUS,C      ; have passed if not, go check the line
00DB 0AAB      00425      goto      AttnSig        ; if so, Abort to Attn Signal
00DC 0605      00426      btfsc      PORTA,ADB     ; Check for the line to go low
00DD 0AD9      00427      goto      SyncTmp        ; if the line is still high, loop again
00DE 0061      00428      clrf       TMR0          ; if low, clear TMR0 & go on to get the Command
                                00429
                                00430 ;*****
                                00431
                                00432 ;*** GET THE COMMAND: 8 BITS & STOP BIT *** (Command) ***
00433 ; The Sync Signal was detected when the line went low after approximately
00434 ; 70 usecs. This low line is the first bit of the Command. This
00435 ; routine receives 8 bits, followed by a '1' Stop bit.
00436
00437 ; IN DETAIL:
00438 ; initialize a counter for counting down as the bits come in
00439 ; call Get_Bit to receive each bit, MSB first, & rotate it into the
00440 ; CmdByte register, where the Command Byte is stored.
00441 ; After returning from GetBit, decrement the counter.
00442 ; when all 8 bits have been received, clear TMR0 (to allow looking
00443 ; for the Stop bit, or holding down the line for an SRQ), and go on to
00444 ; Interpret the Command.
00445
00446 ; In GetBit, get the time,
00447 ; if the time is greater than 72 usecs,
00448 ; abort to the Attn Signal
00449 ; if the time is less than 72 usecs,
00450 ; check if the line went high
00451 ; if line is still low,
00452 ; loop to check the time again
00453 ; if the line went high,
00454 ; determine whether the line went high before or after 50 usecs

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00455 ; if the line went high before 50 usecs, rotate a 1 bit into CmdByte reg.
00456 ; if the line went high after 50 usecs, rotate a 0 bit into CmdByte reg.
00457 ; after getting a bit, check if the line went low (the start of the next
00458 ; bit) if the max. Cell Bit time (104 usecs) is exceeded, abort to Attn
00459 ; Signal when the line goes low, clear TMR0 and return to get another
00460 ; bit or interpret the Command if all 8 bits have been received
00461
00462 ;*****
00463
00DF 0C08      00464 Command movlw   BYTE           ; Get the 8 Command Bits - 1st bit already
00E0 0037      00465             movwf   BitCntr      ; started, so count down from 8 to 0
00E1 0C16      00466             movlw   CmdByte    ; rotate bits into CmdByte with indirect
00E2 0024      00467             movwf   FSR        ; address
00E3 0C48      00468 CmdLoop movlw   MAX_BIT    ; Get & rotate a 1 or 0 bit into CmdByte, or
00E4 0039      00469             movwf   TimeVar    ; see if the maximum time is exceeded & abort
00E5 0403      00470             bcf     STATUS,C    ; clear Carry bit to ensure it won't wrap around
00E6 0376      00471             rlf     CmdByte,F  ; rotate in the last bit
00E7 090C      00472             call    Get_Bit    ; and get another one
00E8 02F7      00473             decfsz  BitCntr,F  ; keep looping until 8 bits are received &
00E9 0AE3      00474             goto     CmdLoop    ; rotated when the Command has been received,
00475             ; interpret it
00476 ;*****
00477
00478 ;*** CHECK THE ADDRESS *** (AddrChk; may call MaskCmd, Globals, Srq) ***
00479 ; The Command Stop Bit is a good time to determine if the Host is
00480 ; addressing this Device:
00481 ; test the left nibble of the received byte against the current Address
00482 ; if the Address belongs to this Device,
00483 ; mask out the command and register nibble of the received byte,
00484 ; test it to see whether the Command is to Listen, Talk, or Flush
00485 ; and go to the routine that looks for the end of the Stop Bit
00486 ; if the Command is for another Device,
00487 ; mask the command nibble
00488 ; see if the Command is a global/reserved Command
00489 ; if so, go do the Command
00490 ; if the Command is not global,
00491 ; check the Srq flag to see if another application needs service
00492 ; if the Srq flag is set,
00493 ; go issue a Service Request (Srq)
00494 ; if the Srq flag is not set,
00495 ; go get the Attn Signal
00496
00EA 020E      00497 AddrChk movf     Reg3a,W    ; See if the Command received is for this Device
00EB 0E0F      00498             andlw   DEVMASK    ; by masking off this Device's Address
00EC 0031      00499             movwf   TmpReg2    ; and saving it in a temporary register
00ED 03B1      00500             swapf   TmpReg2,F  ; (received nibbles in Command are reversed)
00EE 0216      00501             movf   CmdByte,W  ; Test if the received Address is for Device,
00EF 0EF0      00502             andlw   ADDRMSK    ; by masking out the Command nibble,
00F0 0191      00503             xorwf   TmpReg2,W  ; compare received Address to current Address
00F1 0643      00504             btfsc   STATUS,Z    ; if Address is for this Device, go get the Stop
00F2 0AF7      00505             goto     CmdStop    ; Bit & see what the Command is for this Device.
00506
00F3 0933      00507             call    MaskCmd    ; Mask the Command Nibbles from the Address
00F4 0923      00508             call    Globals    ; and go see if it was a Global Command
00F5 0943      00509             call    Srq        ; if not, go see if Srq needs to be asserted
00F6 0AAB      00510             goto     AttnSig    ; if not, go get the Attn Signal
00511
00512 ;*****
00513
00514 ;*** LOOK FOR THE COMMAND STOP BIT *** (CmdStop) ***
00515 ; Look for the Stop Bit following the Command Byte. This is not executed
00516 ; if Srq is asserted by this Device.
00517
00F7 0C48      00518 CmdStop movlw   MAX_BIT    ; load the maximum time for a bit low time
00F8 0039      00519             movwf   TimeVar    ;
00F9 0099      00520             subwf   TimeVar,W  ; See if more than the max. # of usecs have

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00FA 0703      00521      btfss   STATUS,C      ; passed if not, go check for the line to go
00FB 0AAB      00522      goto    AttnSig      ; high if so, abort to the Attn Signal
00FC 0705      00523      btfss   PORTA,ADB      ; Check for the line to go high
00FD 0AF7      00524      goto    CmdStop      ; if the line is still low, loop CmdStop
00FE 0061      00525      clrf     TMR0          ; again if high, clear TMR0 as the beginning
                                00526                        ; of the Tlt and go on to interpret Command
                                00527                        ; as Talk, Listen, or Flush.
                                00528
00529 ;*****
00530
00531 ;** INTERPRET THE COMMAND ** (CmmdChk) **
00532 ; Determine first if the command is for Register 3, and set the Reg3 flag
00533 ; if so, then see if the Command is to Talk, Listen, or Flush and go to
00534 ; that routine.
00535
00FF 0933      00536 CmmdChk call    MaskCmd      ; Separate the Command Nibbles into temp. regs.
0100 0712      00537      btfss   RegNum,00h      ; (MaskCmd put Command Type bits into TmpReg1)
0101 0B04      00538      goto    CmdChk2      ; see if the Command is for Register 3
0102 0632      00539      btfsc   RegNum,01h      ; if not, go continue interpreting the Command
0103 0534      00540      bsf      Flags1,F1Reg3; if so, set the Reg. 3 flag indicating this
                                00541                        ; condition for the Talk or Listen routines
                                00542
0104 0211      00543 CmdChk2 movf     TmpReg2,W      ; Test what Command was received &
0105 0F0C      00544      xorlw   C_TALK          ; branch accordingly
0106 0643      00545      btfsc   STATUS,Z      ; test for this being a Talk Command
0107 0B11      00546      goto    Talk
0108 0211      00547      movf     TmpReg2,W
0109 0F08      00548      xorlw   C_LISTN
010A 0643      00549      btfsc   STATUS,Z      ; test for this being a Listen Command
010B 0B5D      00550      goto    Listen
010C 0211      00551      movf     TmpReg2,W
010D 0F01      00552      xorlw   C_FLUSH
010E 0643      00553      btfsc   STATUS,Z      ; test if the Command is to Flush a Register
010F 0BBE      00554      goto    Flush          ; if the Command isn't a Flush, go get
0110 0AAB      00555      goto    AttnSig      ; the Attn Signal
                                00556
00557 ;*****
00558
00559 ;** SEND DATA TO THE HOST ** (Talk; calls Tlt, LineLow, LineHi) **
00560 ; Data is sent to Host from ADB Data Registers using indirect addressing.
00561 ; (TMR0 was cleared in CmmdChk, and timing for Tlt began there)
00562 ; Call the Tlt (Stop to Start Time), which waits for the middle of the
00563 ; Tlt, when the Tlt returns, send a '1' Start Bit,
00564 ; load the first byte of the Data Register into temporary register,
00565 ; send the 1st 8 bits,
00566 ; load the second byte of the Data Register into temporary register,
00567 ; send the 2nd 8 bits,
00568 ; and send a '0' Stop Bit
00569 ; if at anytime during the Tlt, LineLow, or LineHi the ADB line is
00570 ; inappropriately high or low, the routine aborts to the Collision
00571 ; routine. The Collision routine only sets a flag if this is a Talk Reg.
00572 ; 3 Command, indicating a Collision occurred when sending Data for Reg.
00573 ; 3, and goes to get the Attention Signal.
00574 ; Using temporary registers ensures the Data doesn't get cleared until
00575 ; all of it has been sent.
00576
0111 0634      00577 Talk  btfsc   Flags1,F1Reg3      ; if the talk command is for Register 3,
0112 0B1D      00578      goto    SetRndm      ; go create a Random Address and load it into
0113 07D5      00579      btfss   Flags2,F2DSEND      ; TmpReg1 Check whether there is data to
0114 0AAB      00580      goto    AttnSig      ; send if not, let the bus timeout & get Attn
                                00581
0115 0213      00582 SetTmps movf     RAMAddr,W      ; Signal Load the temporary registers with Data
0116 0024      00583      movwf   FSR          ; stored at the appropriate RAM Address for the
0117 0200      00584      movf     INDF,W          ; Register indicated in the Command Byte
0118 0030      00585      movwf   TmpReg1
0119 02A4      00586      incf     FSR,F

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011A 0200	00587	movf INDF,W	;Load 2nd temporary register from 2nd RAM
011B 0031	00588	movwf TmpReg2	;Address where Data is stored
011C 0B29	00589	goto CallTlt	
	00590		
011D 0201	00591	SetRndm movf TMR0,W	;The Address sent to the Host for a Talk Reg.3
011E 0198	00592	xorwf Random,W	;Command must be random to avoid collisions
011F 0E0F	00593	andlw LOW_NBL	;with other Device Addresses during
0120 0030	00594	movwf TmpReg1	;initialization
0121 020E	00595	movf Reg3a,W	;
0122 0EF0	00596	andlw HI_NIBL	;
0123 0130	00597	iorwf TmpReg1,F	;
0124 0634	00598	SetHndl btfsc Flags1,F1Reg3	; if this is a Talk R3 Command,
0125 020F	00599	movf Reg3b,W	; send the Device Handler ID
0126 0695	00600	btfsc Flags2,F2SFail	; if a Device Self-Test was performed and it
0127 0040	00601	clrw	; failed, send the reserved Handler ID of
0128 0031	00602	movwf TmpReg2	; '00h' to indicate the Failed condition
	00603		
0129 0554	00604	CallTlt bsf Flags1,F1Talk	; Set the Talk Flag to indicate to the Tlt
012A 094C	00605	call Tlt	; routine to return for the end of Talk Start Bit
	00606		
012B 0C10	00607	SndStrt movlw TmpReg1	; Send a '1' bit as the Start Bit
012C 0024	00608	movwf FSR	; Use the indirect addressing of the temporary
012D 0C00	00609	movlw TRI_OUT	; registers from which Data will be sent
012E 0005	00610	tris PORTA	; tri-state PORTA to make the ADB an output
012F 0061	00611	clrf TMR0	; clear TMR0 as the beginning of a bit
0130 0C16	00612	movlw LOW1BIT	
0131 0976	00613	call LineLow	; hold the line low for 1/3rd of a Bit Cell
0132 0C32	00614	movlw HI_1BIT	
0133 0983	00615	call LineHi	; let the go line high for rest of the Bit Cell
	00616		
0134 0C08	00617	SetSend movlw BYTE	; Send the data bytes
0135 0037	00618	movwf BitCntr	; Load the counter to send 8 Bits
0136 06E0	00619	SndBits btfsc INDF,MSB	; determine whether to complete the send of
0137 0B3D	00620	goto Send1	; a '1' or '0' bit
	00621		
0138 0C38	00622	Send0 movlw LOW0BIT	; Send a '0' bit
0139 0976	00623	call LineLow	; hold the line low for 2/3rd of a Bit Cell
013A 0C14	00624	movlw HI_0BIT	
013B 0983	00625	call LineHi	; let the line high for the rest of the Bit Cell
013C 0B41	00626	goto Rotate	
	00627		
013D 0C16	00628	Send1 movlw LOW1BIT	; Send a '1' bit
013E 0976	00629	call LineLow	; hold the line low for 1/3rd of a Bit Cell
013F 0C32	00630	movlw HI_1BIT	
0140 0983	00631	call LineHi	; let the line high for the rest of the Bit Cell
	00632		
0141 0403	00633	Rotate bcf STATUS,C	; Rotate out the MSB bit just sent from
0142 0360	00634	rlf INDF,F	; the Temporary Data Register
0143 02F7	00635	decfsz BitCntr,F	; count down as bits are sent
0144 0B36	00636	goto SndBits	; loop until 8 bits are sent
0145 06B4	00637	btfsc Flags1,F1Sent1	; see whether all data has been sent
0146 0B4A	00638	goto SndStop	; if so, go send the Stop Bit
0147 05B4	00639	bsf Flags1,F1Sent1	; if not, set the Sent Flag,
0148 02A4	00640	incf FSR,F	; Then go prepare to send the next 8 bits,
0149 0B34	00641	goto SetSend	; and send the data from the next Data register
	00642		
014A 0C38	00643	SndStop movlw LOW0BIT	; Send a '0' bit to the Host
014B 0976	00644	call LineLow	
014C 0C14	00645	movlw HI_0BIT	
014D 0574	00646	bsf Flags1,F1Stop	; indicate to LineHi that this is the Stop
014E 0983	00647	call LineHi	; Bit let the line go high for 2/3rd of a Bit Cell
014F 04F4	00648	bcf Flags1,F1ClIsn	; a Collision did not occur, clear the flag
0150 0415	00649	bcf Flags2,F2Srq	; an Srq is no longer needed
0151 04D5	00650	bcf Flags2,F2DSend	; the Data has been sent
0152 0634	00651	btfsc Flags1,F1Reg3	; If current Data Reg. is 3, don't allow
0153 0BC7	00652	goto RunTsk2	; Reg. 3 to be cleared (or at least the 1st 2

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0154 0213      00653      movf   RAMAddr,W      ; bytes) clear the Data Registers from which
0155 0024      00654      movwf  FSR              ; the Data was sent via temporary registers
0156 0060      00655      clrf   INDF             ; Clear the registers holding the originalData
0157 02A4      00656      incf   FSR,F           ; which was just sent via the temporary regs.
0158 0060      00657      clrf   INDF             ; Go setup to run the 2nd Application Task for
0159 0BC7      00658      goto   RunTsk2          ; the time between the end of data sent, and
                                           ; the beginning of the next Attention Signal
                                           00659
                                           00660
015A 0634      00661 Collisn btfsc  Flags1,F1Reg3 ; if there was a collision during a Talk
015B 05F4      00662      bsf    Flags1,F1ClIsn ; Reg. 3 Command, then set the Collision
015C 0AAB      00663      goto   AttnSig          ; Flag, otherwise, just abort to Attn Signal
                                           00664
00665 ;*****
00666
00667 ;** RECEIVE DATA FROM THE HOST ** (Listen; calls Tlt, GetBit) **
00668 ; Get the Tlt Signal (Stop to Start Time)
00669 ; Tlt recognizes the beginning of the Start Bit
00670 ; Load indirect address of temporary Data register
00671 ; Get the rest of the Start Bit
00672 ; Receive the first Data byte from the Host into the temporary Data
00673 ; register by calling GetBit - GetBit uses indirect address
00674 ; Set indirect address to 2nd temporary Data register
00675 ; Receive the second Data byte from the Host into the temporary Data
00676 ; register And then receive the Data Stop Bit if the
00677 ; data was not for Reg. 3, move the Data now stored in the temporary
00678 ; Data registers into the RAM locations of the Data register designated
00679 ; in RAMAddr, and go run the 2nd Application Task.
00680 ; if the data was for Reg. 3, go interpret what the Data Command was
00681 ; and take appropriate action.
00682
015D 0594      00683 Listen bsf    Flags1,F1Lstn ; Set Listen Flag to tell Tlt (Stop to Start Time)
015E 094C      00684      call   Tlt              ; to look for the beginning of the Start Bit
015F 0C10      00685      movlw  TmpReg1          ; receive bits into temporary registers
0160 0024      00686      movwf  FSR              ; use indirect addressing to store received Data
0161 0060      00687      clrf   INDF             ; in temporary registers
0162 02A4      00688      incf   FSR,F           ;
0163 0060      00689      clrf   INDF             ; clear any data currently in temporary registers
0164 00E4      00690      decf   FSR,F           ;
0165 0C32      00691      movlw  BIT_TST          ; load the TimeVariable to look for the rest of
0166 0039      00692      movwf  TimeVar          ; the Start Bit
0167 0403      00693      bcf    STATUS,C         ; clear the Carry bit so it doesn't wrap around
0168 090C      00694      call   Get_Bit          ; get the rest of the Start bit
0169 0700      00695      btfss  INDF,LSB         ; it should be a '1' bit
016A 0AAB      00696      goto   AttnSig          ; if not, abort to the Attn Signal
016B 0400      00697      bcf    INDF,LSB         ; don't let the Start Bit be the 1st bit of Data
016C 0C08      00698 SetRecv movlw  BYTE          ; setup to receive 8 bits at a time into the reg.
016D 0037      00699      movwf  BitCnt          ; count down as bits come in
016E 0C48      00700 RcvData movlw  MAX_BIT        ; get & rotate a 1 or 0 bit into Data Reg., and
016F 0039      00701      movwf  TimeVar          ; see if MAX_BIT time is exceeded & if so, abort
0170 0403      00702      bcf    STATUS,C         ; clear Carry bit so it doesn't wrap around
0171 0360      00703      rlf    INDF,F           ; rotate the bit into the Register (the 1st
0172 090C      00704      call   Get_Bit          ; rotation doesn't count)
0173 02F7      00705      decfsz BitCnt,F         ;decrement the counter each time a bit is
0174 0B6E      00706      goto   RcvData          ;received loop until 8 bits are received
0175 06D4      00707      btfsc  Flags1,F1Rcvd1 ; see whether the 2nd Data byte was just
0176 0B7A      00708      goto   RcvStop          ;received if so, go get the Stop Bit
0177 05D4      00709      bsf    Flags1,F1Rcvd1 ; if not, set the Received-1st-Byte Flag,
0178 02A4      00710      incf   FSR,F           ;increment FSR to receive 2nd Byte of the Data
0179 0B6C      00711      goto   SetRecv          ;Reg. & go prepare to receive the next byte
                                           00712
017A 0C48      00713 RcvStop movlw  MAX_BIT        ;Get the '0' Stop Bit
017B 0039      00714      movwf  TimeVar          ;
017C 0201      00715 RecvTmp movf   TMRO,W         ;Check the time, then check if the line went high
017D 0099      00716      subwf  TimeVar,W       ;See if more than MAX_BIT usecs have passed
017E 0703      00717      btfss  STATUS,C         ;if so, abort to Attn Signal
017F 0AAB      00718      goto   AttnSig          ;

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0180 0705    00719      btfss  PORTA,ADB      ; if not, check whether the line went high
0181 0B7C    00720      goto   RecvTmp        ; if still low, loop to check the time again
0182 0C32    00721      movlw  BIT_TST        ; if high, make sure the Stop Bit was '0'
0183 0039    00722      movwf  TimeVar        ; if the time was < BIT_TST, abort to
0184 0201    00723      movf    TMR0,W          ; the Attn Signal
0185 0099    00724      subwf  TimeVar,W        ; if the time was > BIT_TST, the '0' Stop
0186 0603    00725      btfsc  STATUS,C        ; Bit was received
0187 0AAB    00726      goto   AttnSig        ; clear TMR0 so second Task may use idle time
00727
0188 0061    00728  RcvdDat  clrf    TMR0          ; Move Data to registers (unless for Reg 3.)
0189 0634    00729      btfsc  Flags1,F1Reg3    ; see if Data was received for Register 3,
018A 0B94    00730      goto   DataChk        ; if so, go interpret the Listen Reg. 3
018B 0213    00731      movf    RAMAddr,W        ; Command if not, move the received Data bytes
018C 0024    00732      movwf  FSR              ; to their indicated registers using indirect
018D 0210    00733      movf    TmpReg1,W        ; address,
018E 0020    00734      movwf  INDF
018F 02A4    00735      incf    FSR,F
0190 0211    00736      movf    TmpReg2,W
0191 0020    00737      movwf  INDF
0192 05B5    00738      bsf     Flags2,F2DRcvd; set the Data-has-been-received flag,
0193 0BC7    00739      goto   RunTsk2         ; and go prepare to run the 2nd Application Task
00740
00741 ;*****
00742
00743 ;* INTERPRET THE LISTEN REG. 3 COMMAND SENT BY THE HOST *** (DataChk) *
00744 ; This interprets the Data received for Register 3 as one of the
00745 ; following Commands and runs the corresponding routine:
00746 ;
00747 ; Mask the Data Command received using the following Constants passed
00748 ; to the IntData (Interpret Data Command) macro:
00749 ; SELFTEST (FF) - the Device is instructed to do a Self-Test
00750 ; LISTEN1 (00) - unconditionally change Device Address and/or Status bits
00751 ; LISTEN2 (FE) - change only the Device Address, and only change it
00752 ; if the Device Address is marked as movable
00753 ; DEV_ACT (FD) - change Device Address only if the Device Activator is
00754 ; pressed (as defined in Device specification)
00755
00756 DataChk IntData SELFTEST,SlfTest ; see if Data Command is for Self Test
0194 0211    M          movf    TmpReg2,W        ; interprets the Data Command received by
0195 0FF      M          xorlw  SELFTEST        ; comparing the 2nd byte to a Data
0196 0643    M          btfsc  STATUS,Z        ; Command constant
0197 0BA7    M          goto   SlfTest          ; it then goes to the appropriate routine
00757
0198 0211    M          movf    TmpReg2,W        ; to 13) interprets the Data Command
0199 0F00    M          xorlw  LISTEN1        ; received by comparing the 2nd byte to a Data
019A 0643    M          btfsc  STATUS,Z        ; Command constant
019B 0BA9    M          goto   UpDat3a        ; it then goes to the appropriate routine
00758
019C 0211    M          movf    TmpReg2,W        ; interprets the Data Command received by
019D 0FFE    M          xorlw  LISTEN2        ; comparing the 2nd byte to a Data
019E 0643    M          btfsc  STATUS,Z        ; Command constant
019F 0BAF    M          goto   NewAddr        ; it then goes to the appropriate routine
00759
01A0 0211    M          movf    TmpReg2,W        ; interprets the Data Command received by
01A1 0FFD    M          xorlw  DEV_ACT        ; comparing the 2nd byte to a Data
01A2 0643    M          btfsc  STATUS,Z        ; Command constant
01A3 0BAD    M          goto   DevActv        ; it then goes to the appropriate routine
00760
01A4 0211    00761      movf    TmpReg2,W        ; if none of these Commands were given, put
01A5 002F    00762      movwf  Reg3b          ; received Data into Reg. 3b as a new Device the
01A6 0BC7    00763      goto   RunTsk2        ; Handler ID and go prepare to run the 2nd Task
00764
01A7 0575    00765  SlfTest  bsf     Flags2,F2STest ; Tell Device to do a Self-Test during 2nd
01A8 0BC7    00766      goto   RunTsk2        ; Task, and go prepare to run the 2nd Task
00767
01A9 0210    00768  UpDat3a  movf    TmpReg1,W        ; Unconditionally change the Device Address
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00769                                     ; and/or the Status Bits of Reg. 3a
01AA 05C0 00770      bsf    W,ExpEvtnt      ; NOTE: Exceptional Event should remain as
01AB 002E 00771      movwf Reg3a            ; set to a '1' unless otherwise indicated
01AC 0BC7 00772      goto   RunTsk2        ; Go prepare to run the 2nd Application Task
00773
01AD 0755 00774 DevActv btfss  Flags2,F2DActv; if the Device Activator was NOT pressed,
01AE 0BC7 00775      goto   RunTsk2        ; go run the 2nd Application Task,
00776                                     ; if it was, change Device Address, if movable
01AF 06F4 00777 NewAddr btfsc  Flags1,F1ClIsn; If a collision occurred during the last
01B0 0AAB 00778      goto   AttnSig        ; Talk Reg. 3, the Address was marked unmov
01B1 0210 00779      movf   TmpReg1,W      ; able, abort to the Attention Signal.
01B2 0F00 00780      xorlw  FALSE        ;
01B3 0643 00781      btfsc  STATUS,Z      ;
01B4 0AAB 00782      goto   AttnSig
01B5 020E 00783      movf   Reg3a,W        ; Create the new Device Address by masking in
01B6 0EF0 00784      andlw  HI_NIBL       ; the Address received by the host, not allowing
01B7 0031 00785      movwf  TmpReg2       ; the upper nibble Status Bits in Reg. 3a to
01B8 0210 00786      movf   TmpReg1,W      ; be affected.
01B9 0E0F 00787      andlw  LOW_NBL      ;
01BA 0111 00788      iorwf  TmpReg2,W      ; NOTE: Exceptional Event should remain as
01BB 05C0 00789      bsf    W,ExpEvtnt      ; set to a '1' unless otherwise indicated
01BC 002E 00790      movwf  Reg3a        ; when the new Device Address is in place,
01BD 0BC7 00791      goto   RunTsk2        ; go prepare to run the 2nd Application Task
00792
00793 ;*****
00794 ;*** FLUSH THE REGISTER SPECIFIED BY THE COMMAND BYTE *** (Flush) ***
00795
01BE 0213 00796 Flush  movf    RAMaddr,W    ; Clear the Data in the specified Register
01BF 0024 00797      movwf  FSR            ; use indirect address to clear the RAM
01C0 0060 00798      clrf   INDF          ; locations holding the Data
01C1 02A4 00799      incf   FSR,F
01C2 0060 00800      clrf   INDF
01C3 0BC7 00801      goto   RunTsk2
00802
00803 ;*****
00804
01C4 0AAB 00805 Reserv1 goto   AttnSig      ; No action until Reserved Command 1 is defined
00806
00807 ;*****
00808
01C5 0AAB 00809 Reserv2 goto   AttnSig      ; No action until Reserved Command 2 is defined
00810
00811 ;*****
00812
01C6 0AAB 00813 Reserv3 goto   AttnSig      ; No action until Reserved Command 3 is defined
00814
00815 ;*****
00816
00817 ;*** PUT THE CODE FOR OTHER APPLICATION HERE *** (RunTsk2, Task_2) ***
00818
00819 ;      bsf    Flags2,F2SFail ; code would go before here if a Self Test
00820 ;      bcf    Flags2,F2SFail ; was performed and it failed or passed
00821
01C7 0070 00822 RunTsk2 clrf   TmpReg1      ; When finished with Data interpretation,
01C8 0071 00823      clrf   TmpReg2      ; clear the temporary Data registers, and
01C9 0CE1 00824      movlw  TSK2MAX     ; load Task 2 TimeVariable with amount allowed
01CA 003A 00825      movwf  Tsk2Var     ; between end of Data and Attention Signal. If
00826
01CB 0615 00827 Task_2  btfsc  Flags2,F2Srqr ; the Srq Flag has not been cleared, then data
01CC 0BF7 00828      goto   AttnTst      ; must still be sent from 1st Service Request
01CD 0900 00829      call   PrScale     ; Turn on the TMR0 prescale for >250usec count
00830
01CE 0675 00831 Tests   btfsc  Flags2,F2STest ; See if Key-Up transition codes should be
01CF 0BDC 00832      goto   LoadDat      ; sent
01D0 0635 00833      btfsc  Flags2,Switch ; Determine if the Switch has been
01D1 0BED 00834      goto   DBounce      ; de-bounced if not, go timeout

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01D2 0626      00835      btfsc    PORTB,Switch ; Check if Switch is pressed,
01D3 0BF3      00836      goto     Tsk2Tmp      ; if not, go timeout
01D4 05F5      00837      bsf      Flags2,F2DMore; data needs to be sent to the host
01D5 0515      00838      bsf      Flags2,F2Srq  ; and issue a Service Request
01D6 0535      00839      bsf      Flags2,Switch ; set the flag for de-bouncing switch
01D7 0506      00840      bsf      PORTB,LED   ; Turn on LED when Switch is pressed
01D8 0C08      00841      movlw    DEBOUNC
01D9 003B      00842      movwf    TmpCtrl
01DA 06D5      00843      btfsc    Flags2,F2DSend; The last Data was sent correctly if Talk
01DB 0BF3      00844      goto     Tsk2Tmp      ; cleared the DSend flag, if set, goto
                                00845      ; Attn Test to re-send Data
                                00846
01DC 07F5      00847 LoadDat btfss    Flags2,F2DMore; If all the Data has been sent, DMore is
01DD 0BF3      00848      goto     Tsk2Tmp      ; clearif DMore is clear, go time out
01DE 0C38      00849      movlw    SHIFT      ; if DMore is set, Data remains to be sent
01DF 0028      00850      movwf    Reg0a      ; if not, load the Data bytes
01E0 0C12      00851      movlw    BANG
01E1 0029      00852      movwf    Reg0b
01E2 05D5      00853      bsf      Flags2,F2DSend; Data now needs to be sent to the host
01E3 0515      00854      bsf      Flags2,F2Srq  ; Until all data has been sent, Srq's may
01E4 0675      00855      btfsc    Flags2,F2STest; be sent See if Key-Up Transition Codes
01E5 0BE8      00856      goto     KeyUp      ; should be sent if so, go set the bits
01E6 0575      00857      bsf      Flags2,F2STest; if not, set bit so they will be next time
01E7 0BED      00858      goto     DBounce     ; and go debounce the switch
                                00859
01E8 05E8      00860 KeyUp   bsf      Reg0a,07h    ; Set the 7th bit in each register to
01E9 05E9      00861      bsf      Reg0b,07h    ; indicate the Key is up
01EA 0475      00862      bcf      Flags2,F2STest; The Key-Up Transition Code bits have been
01EB 04F5      00863      bcf      Flags2,F2DMore; set All data will have been sent to the
01EC 0BED      00864      goto     DBounce     ; host after this transaction
                                00865
01ED 0726      00866 DBounce btfss    PORTB,Switch ; Check if Switch has been released,
01EE 0BF3      00867      goto     Tsk2Tmp      ; if not, go timeout
01EF 02FB      00868      decfsz   TmpCtrl,F    ; if so, start timed debounce of several
01F0 0BF3      00869      goto     Tsk2Tmp      ; millisecs. before switch is tested again
01F1 0406      00870      bcf      PORTB,LED   ; Turn off LED when Switch is released
01F2 0435      00871      bcf      Flags2,Switch ; clear de-bounce flag
                                00872
01F3 0201      00873 Tsk2Tmp movf     TMR0,W      ; Check the time to see if more than the maximum
01F4 009A      00874      subwf    Tsk2Var,W    ; time limit has been exceeded
01F5 0603      00875      btfsc    STATUS,C    ; if so, go determine what part of Attn Signal
01F6 0BF3      00876      goto     Tsk2Tmp
                                00877
01F7 0714      00878 AttnTst btfss    Flags1,F1Attn ; After this portion of the 2nd Task is
01F8 0AAB      00879      goto     AttnSig      ; complete,If 2nd Task is NOT run during
01F9 0414      00880      bcf      Flags1,F1Attn ; Attn Signal, go get the start of the Attn
01FA 0AC2      00881      goto     AttnMin      ; Signal otherwise, go get the rest of the
                                00882      ; Attn Signal
00883 ;*****
00884
01FF          00885      ORG      PIC54
01FF 0A90      00886 RESETV  goto     Start
                                00887
                                00888      END

```

MEMORY USAGE MAP ('X' = Used, '-' = Unused)

```
0000 : XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX
0040 : XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX
0080 : XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX
00C0 : XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX
0100 : XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX
0140 : XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX
0180 : XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX
01C0 : XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXXXXX XXXXXXXXXXXX---X
```

All other memory blocks unused.

Program Memory Words Used: 508
Program Memory Words Free: 516

Errors : 0
Warnings : 0 reported, 0 suppressed
Messages : 0 reported, 0 suppressed

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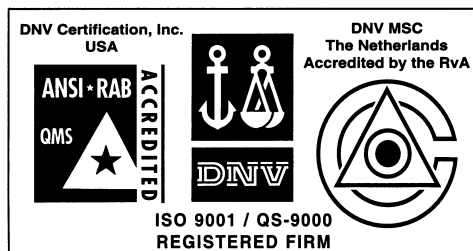
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