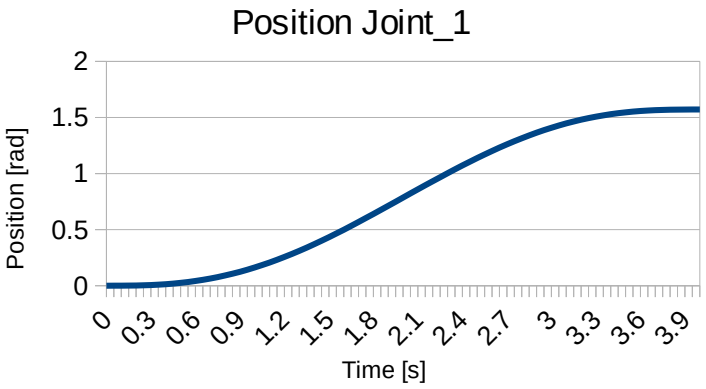
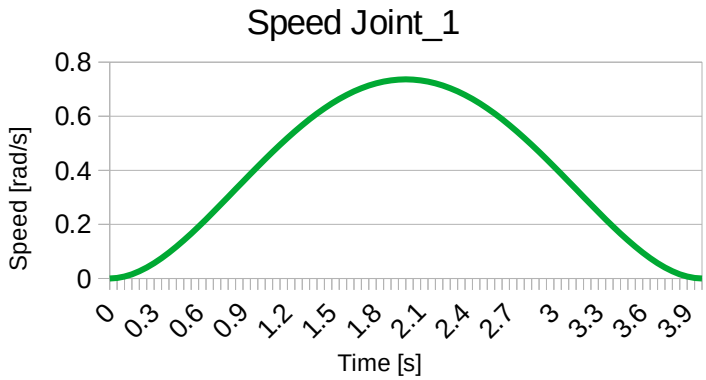
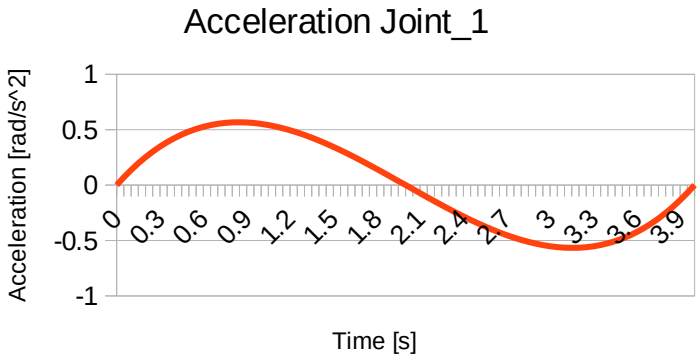
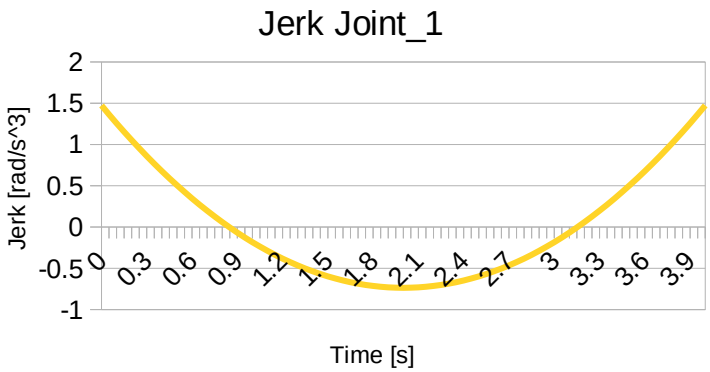
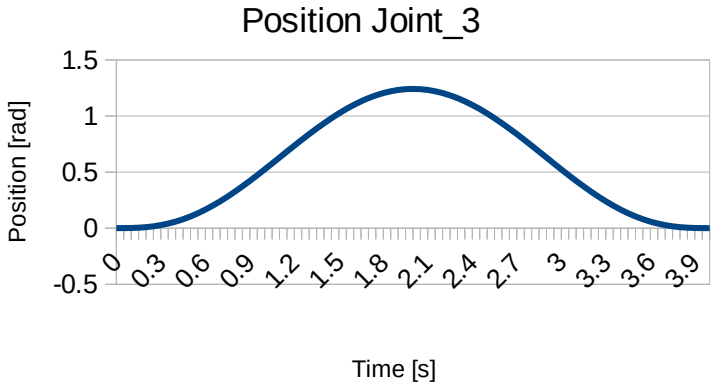
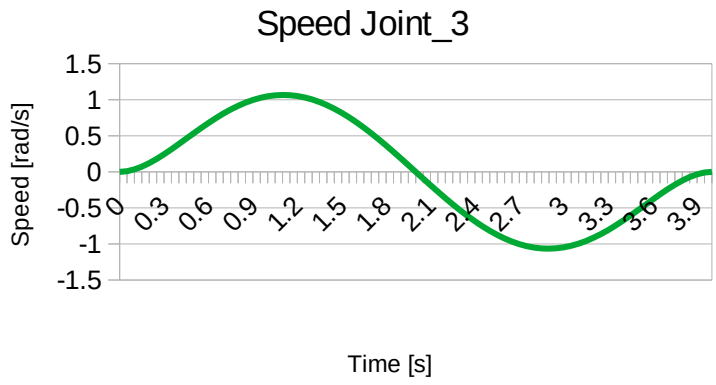

Position Joint_1
Position [rad]
2
1.5
1
0.5
0
0 0.3 0.6 0.9 1.2 1.5 1.8 2.1 2.4 2.7 3 3.3 3.6 3.9
Time [s]

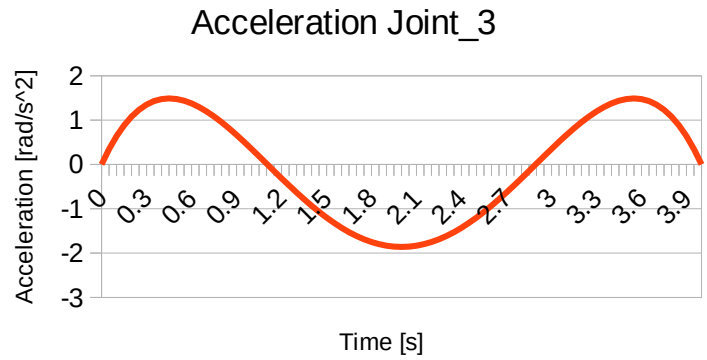

Speed Joint_1
Speed [rad/s]
0.8
0.6
0.4
0.2
0
0 0.3 0.6 0.9 1.2 1.5 1.8 2.1 2.4 2.7 3 3.3 3.6 3.9
Time [s]

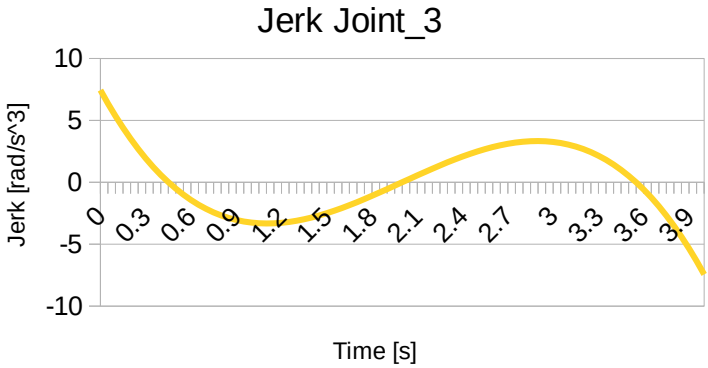

Acceleration Joint_1
Acceleration [rad/s^2]
1
0.5
0
-0.5
-1
0 0.3 0.6 0.9 1.2 1.5 1.8 2.1 2.4 2.7 3 3.3 3.6 3.9
Time [s]


Jerk Joint_1
Jerk [rad/s^3]
2
1.5
1
0.5
0
-0.5
-1
0 0.3 0.6 0.9 1.2 1.5 1.8 2.1 2.4 2.7 3 3.3 3.6 3.9
Time [s]


Position Joint_3
Position [rad]
1.5
1
0.5
0
-0.5
0 0.3 0.6 0.9 1.2 1.5 1.8 2.1 2.4 2.7 3 3.3 3.6 3.9
Time [s]


Speed Joint_3
Speed [rad/s]
1.5
1
0.5
0
-0.5
-1
-1.5
0 0.3 0.6 0.9 1.2 1.5 1.8 2.1 2.4 2.7 3 3.3 3.6 3.9
Time [s]


Acceleration Joint_3
Acceleration [rad/s^2]
2
1
0
-1
-2
-3
0 0.3 0.6 0.9 1.2 1.5 1.8 2.1 2.4 2.7 3 3.3 3.6 3.9
Time [s]


Jerk Joint_3
Jerk [rad/s^3]
10
5
0
-5
-10
0 0.3 0.6 0.9 1.2 1.5 1.8 2.1 2.4 2.7 3 3.3 3.6 3.9
Time [s]