DATA and SETTINGS

The following bit of code allows the connection to the google drive cloud storage.

```
    # Setting up google drive
    from google.colab import drive
    drive.mount('/content/gdrive', force_remount=True)
    import sys
    sys.path.append('/content/gdrive/MyDrive/Colab Notebooks')
```

Now, the main modules used for the code:

```
7. import my_utils as mu8. import torch9. from torch import nn
```

The train and test dataset are now loaded using the *load_data_fashion_mnist()* function in the *my_utils* module (renamed *mu*) and a batch size of 256 samples.

```
11.# Read training and test data from fashion mnist dataset
12.batch_size = 256
13.train_iter, test_iter = mu.load_data_fashion_mnist(batch_size)
```

THE MODEL

The model of the net has one backbone block with two MLPs. Each MLP is made of two linear functions and one activation function, and the layers are implemented in a sequence using 'nn. Sequential'.

```
15. class Net(torch.nn.Module):
16.
       def __init__(self, num_inputs, num_hidden, num_outputs):
17.
         super(Net, self).__init__()
18.
19.
20.
         self.num hidden = num hidden
21.
         self.num inputs = num inputs
22.
         self.num_outputs = num_outputs
23.
24.
         self.backbone mlp1 = nn.Sequential(
                              nn.Linear(num hidden, num hidden),
25.
26.
                              nn.ReLU(),
                              nn.Linear(num_hidden, num_hidden))
27.
28.
29.
         self.backbone_mlp2 = nn.Sequential(
                              nn.Linear(num_inputs, num_inputs),
30.
31.
                              nn.ReLU(),
                              nn.Linear(num_inputs, num_inputs))
32.
33.
       def forward(self, x)
34.
35.
         x = Stem(x, 7)
36.
37.
         # Transpose image before first backbone mlp
38.
         x = torch.transpose(x, 1, 2)
```

The Stem and Classifier functions are implemented in the forward method of the net.

Stem:

The Stem is defined as a class method and is used to split the input image tensor into N number of square patches, vectorise the patches and finally output a feature matrix $X \in \mathbb{R}^{N \times d}$, with d = features.

```
50. def Stem(self, x, PATCH SIZE):
51.
52.
         A function to split the input image into square patches
         and then rearrange the pixels in each patch.
53.
54.
         The input image of size (h, w)
55.
         is rearranged into (num_patches, patch_size^2).
56.
         - PATCH_SIZE is the lenght of the square patch in pixels
57.
58.
         (i.e. 7x7 patch: PATCH_SIZE=7).
59.
60.
         - num_patches is the number of patches in the image,
61.
         it is calculated by dividing the image size by the patch size
         1.1.1
62.
         PATCH SIZE
63.
64.
         num patches = (28//PATCH SIZE)**2
         unfold = nn.Unfold(kernel_size=(7,7), stride=(7,7))
65.
66.
         x_divided = x.unfold(2, PATCH_SIZE, PATCH_SIZE)\
67.
68.
                      .unfold(3, PATCH_SIZE, PATCH_SIZE)
69.
70.
         x_divided = x_divided.reshape( -1, num_patches,\
                                        PATCH_SIZE, PATCH_SIZE)
71.
72.
73.
         return x_divided.reshape(-1, num_patches, PATCH_SIZE**2)
```

Classifier:

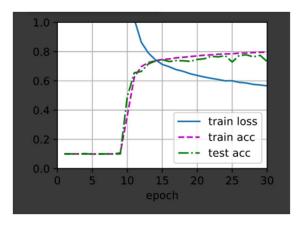
The classifier is also declared as a class method to extract the mean feature vector $x \in \mathbb{R}^d$ from the feature matrix. The mean features will be directly used for the classification and training process.

TRAINING SCRIPT

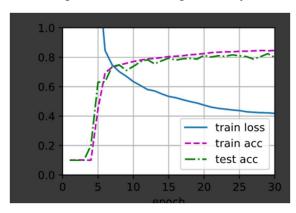
```
87.# Defined in file: ./chapter_linear-networks/softmax-regression-scratch.md
88. def train_epoch_ch3(net, train_iter, loss, updater):
       """The training loop defined in Chapter 3."""
89.
90.
       # Set the model to training mode
91.
       if isinstance(net, torch.nn.Module):
92.
           net.train()
93.
       # Sum of training loss, sum of training accuracy, no. of examples
94.
       metric = mu.Accumulator(3)
95.
       for X, y in train iter:
           # Compute gradients and update parameters
96.
97.
           y_hat = net(X)
           1 = loss(y_hat, y)
98.
99.
           if isinstance(updater, torch.optim.Optimizer):
100.
                 updater.zero_grad()
101.
                 1.backward()
102.
                 updater.step()
103.
                 metric.add(float(1) * len(y), mu.accuracy(y_hat, y),
104.
                            y.size().numel())
105.
             else:
106.
                 1.sum().backward()
                 updater(X.shape[0])
107.
                 metric.add(float(1.sum()), mu.accuracy(y_hat, y), y.numel())
108.
109.
         # Return training loss and training accuracy
         return metric[0] / metric[2], metric[1] / metric[2]
110.
111.
112. def train ch3(net, train iter, test iter, loss, num epochs, updater):
         """Train a model (defined in Chapter 3).""
113.
114.
         animator = mu.Animator(xlabel='epoch',xlim=[0, num_epochs],ylim=[0, 1
  ],
115.
                             legend=['train loss', 'train acc', 'test acc'])
116.
         for epoch in range(num_epochs):
             train_metrics = train_epoch_ch3(net, train_iter, loss, updater)
117.
118.
             test acc = mu.evaluate accuracy(net, test iter)
119.
             animator.add(epoch + 1, train_metrics + (test_acc,))
120.
         train_loss, train_acc = train_metrics
         print('train final accuracy: ', train_acc)
121.
122.
         print('test final loss: ', train_loss)
123.
         print('test final accuracy: ', train_acc)
```

RESULTS

Several attempt where made adjusting the learning rate (between 0.6 and 0.2) and weight decay (between 0.0002 and 0.0007)



Learning rate = 0.2, weight decay = 0.0005



Learning rate = 0.6, weight decay = 0.0002

The following results were achieved using the following parameters:

- num_inputs, num_hidden, num_outputs = 49, 16, 10
- learning rate = 0.5
- weight decay = 0.0002
- epochs = 30
- loss = nn.CrossEntropyLoss()
- optimizer = torch.optim.SGD(net.parameters(), lr=lr, weight_decay=wd)

