

David Alex

dgeorgealex@gmail.com | 508-523-4272 | <https://portfolio-steel-tau-50.vercel.app/>

EDUCATION

Worcester Polytechnic Institute | Worcester, MA

May 2025

Bachelor of Science in Robotics Engineering

- Relevant Coursework: Industrial Robotics, Robotic Navigation, Robotic Manipulation, Embedded Computing in Engineering Design, Control Engineering, Mechanical Applications in Robotics, Sensing and Perception in Robotics
- Research: YOLO Vision, Voice Commands, & End Effector Manipulation on a 3D-Printed Humanoid Robot advised by Pradeep Radhakrishnan and Taylor Andrews
- Club: Captain of the WPI Valorant E-sports Team

PROJECTS

End Effector Manipulation on a 3D-Printed Humanoid Robot:

Simulation Researcher

September 2024 – May 2025

- Simulated the humanoid robot using CoppeliaSim, by testing trajectory planning, inverse kinematics, and library implementations
- Implemented the IKPY python library to compute inverse and forward kinematics, which uses a URDF to describe the robot's geometries and joint positions
- Utilized object detection, face meshing, and OpenAI speech recognition to construct human-robot interaction
- Conducted contactless temperature checks using an IR thermometer and Inverse Kinematics

Mobile Robot for Autonomous SLAM-Based Navigation Using LIDAR and MCL:

Developer

October 2024 – December 2025

- Developed an autonomous mobile robot capable of SLAM using LIDAR sensor data
- Implemented Monte Carlo Localization to perform accurate state estimation
- Integrated the A* algorithm and obstacle avoidance to navigate efficiently through the map
- Designed and tested frontier-based exploration algorithms to enable the robot to discover and map uncharted areas
- Utilized ROS to simulate and visualize with Gazebo and RViz and on a real map

Industrial Robotics Coursework:

Developer

March 2025 – May 2025

- Operated a UR5e collaborative robot using the teach pendant to program and execute motion paths, perform pick-and-place tasks, and test workspace limits
- Developed and simulated robotic work cells using ABB IRB 1600 (serial) and IRB 360 FlexPicker (parallel) robots for a case packing and palletizing system
- Implemented object detection, smart components, conveyor logic, and coordinate frames to simulate dynamic object handling and multi-robot collaboration.
- Optimized pick-and-place operations for real-world manufacturing environment and motion programming (RAPID) to achieve precision manipulation and synchronization

TECHNICAL SKILLS

Languages: Python, MATLAB, RAPID, C, C++, Java, Racket

Tools: UR5E Industrial Robot, ROS, ROS2, Linux, CoppeliaSim, RobotStudio, SolidWorks, GitHub, Fusion 360, VSCode