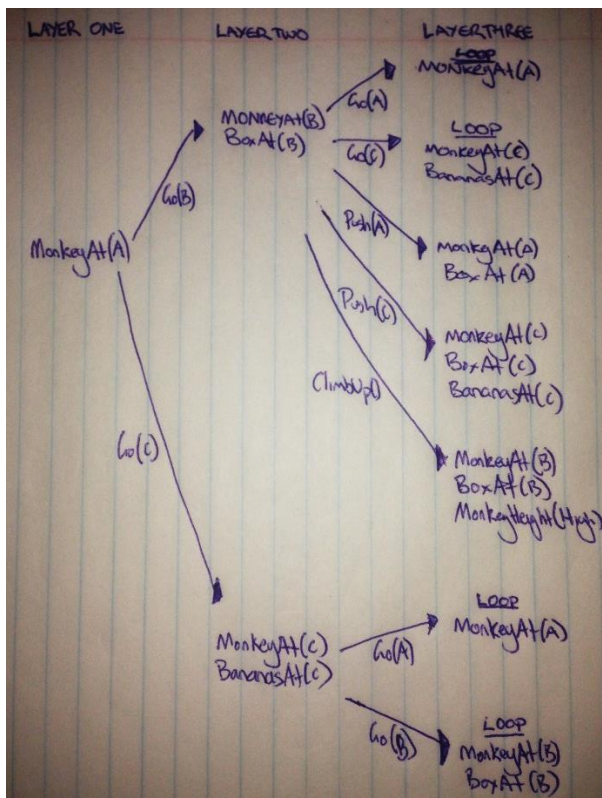


Part One: Classical Planning – Monkey and Bananas

1. INIT ($\text{MonkeyAt}(A) \wedge \text{MonkeyHeight}(\text{Low}) \wedge \text{MonkeyHold}(\neg \text{Bananas}) \wedge \text{BoxAt}(B) \wedge \text{BoxHeight}(\text{Low}) \wedge \text{BananasAt}(C) \wedge \text{BananasHeight}(\text{High})$)
GOAL ($\text{MonkeyHold}(\text{Banana})$)
2. ACTION(Go(x),
PRECOND: $\text{MonkeyAt}(\neg x)$
EFFECT: $\text{MonkeyAt}(x)$)
ACTION(Push(x),
PRECOND: $\text{MonkeyAt}(y) \wedge \text{BoxAt}(y)$
EFFECT: $\text{MonkeyAt}(x) \wedge \text{BoxAt}(x)$)
ACTION(ClimbUp(),
PRECOND: $\text{MonkeyAt}(x) \wedge \text{BoxAt}(x) \wedge \text{MonkeyHeight}(\text{Low})$
EFFECT: $\text{MonkeyAt}(x) \wedge \text{BoxAt}(x) \wedge \text{MonkeyHeight}(\text{High})$)
ACTION(ClimbDown(),
PRECOND: $\text{MonkeyAt}(x) \wedge \text{BoxAt}(x) \wedge \text{MonkeyHeight}(\text{High})$
EFFECT: $\text{MonkeyAt}(x) \wedge \text{BoxAt}(x) \wedge \text{MonkeyHeight}(\text{Low})$)
ACTION(Grasp(),
PRECOND: $\text{MonkeyAt}(x) \wedge \text{BoxAt}(x) \wedge \text{BananasAt}(x) \wedge \text{MonkeyHeight}(\text{High}) \wedge \text{BananasHeight}(\text{High}) \wedge \text{MonkeyHold}(\neg \text{Bananas})$
EFFECT: $\text{MonkeyHold}(\text{Bananas})$)
ACTION(Ungrasp(),
PRECOND: $\text{MonkeyHold}(\text{Bananas})$
EFFECT: $\text{MonkeyHold}(\neg \text{Bananas})$)
- 3.



4. Initial State: MonkeyAt(A)
Action 1: Go(B)
State 1: MonkeyAt(B) \wedge BoxAt(B)
Action 2: Push(C)
State 2: MonkeyAt(C) \wedge BoxAt(C) \wedge BananasAt(C)
Action 3: ClimbUp()
State 3: MonkeyAt(C) \wedge BoxAt(C) \wedge BananasAt(C) \wedge MonkeyHeight(High)
Action 4: Grasp()
State 4 (Goal): MonkeyAt(C) \wedge BoxAt(C) \wedge BananasAt(C) \wedge MonkeyHeight(High) \wedge MonkeyHold(Bananas)

Part Two: Job Shop Scheduling

1. $t_1 = 0$
 $t_2 = 10$
 $t_3 = 50$
 $t_4 = 50$
 $t_5 = 90$
 $t_6 = 90$
2. $J_1 = 65$
 $J_2 = 125$
 $J_3 = 110$
Makespan = 125
3. Step 0:
Partial solution: (empty, no action is scheduled)
 $\text{earliestIdleTime}(M_1) = 0, \text{earliestIdleTime}(M_2) = 0$
 $\text{earliestReadyTime}(O_{11}) = 0, \text{earliestReadyTime}(O_{12}) = \infty$
 $\text{earliestReadyTime}(O_{21}) = 10, \text{earliestReadyTime}(O_{22}) = \infty$
 $\text{earliestReadyTime}(O_{31}) = 20, \text{earliestReadyTime}(O_{32}) = \infty$

Step 1:
Partial solution: O_{11} at $t = 0$
 $\text{earliestIdleTime}(M_1) = 50, \text{earliestIdleTime}(M_2) = 0$
 $\text{earliestReadyTime}(O_{11}) = 0, \text{earliestReadyTime}(O_{12}) = 50$
 $\text{earliestReadyTime}(O_{21}) = 10, \text{earliestReadyTime}(O_{22}) = \infty$
 $\text{earliestReadyTime}(O_{31}) = 20, \text{earliestReadyTime}(O_{32}) = \infty$

Step 2:
Partial solution: $O_{11} O_{21}$ at $t = 10$
 $\text{earliestIdleTime}(M_1) = 50, \text{earliestIdleTime}(M_2) = 40$
 $\text{earliestReadyTime}(O_{11}) = 0, \text{earliestReadyTime}(O_{12}) = 50$
 $\text{earliestReadyTime}(O_{21}) = 10, \text{earliestReadyTime}(O_{22}) = 40$
 $\text{earliestReadyTime}(O_{31}) = 20, \text{earliestReadyTime}(O_{32}) = \infty$

Step 3:

Partial solution: $O_{11} O_{21} O_{22} O_{12}$ at $t = 50$

$\text{earliestIdleTime}(M_1) = 85$, $\text{earliestIdleTime}(M_2) = 75$

$\text{earliestReadyTime}(O_{11}) = 0$, $\text{earliestReadyTime}(O_{12}) = 50$

$\text{earliestReadyTime}(O_{21}) = 10$, $\text{earliestReadyTime}(O_{22}) = 40$

$\text{earliestReadyTime}(O_{31}) = 20$, $\text{earliestReadyTime}(O_{32}) = \infty$

Step 4:

Partial solution: $O_{11} O_{21} O_{22} O_{12} O_{31}$ at $t = 85$

$\text{earliestIdleTime}(M_1) = 125$, $\text{earliestIdleTime}(M_2) = \text{idle}$

$\text{earliestReadyTime}(O_{11}) = 0$, $\text{earliestReadyTime}(O_{12}) = 50$

$\text{earliestReadyTime}(O_{21}) = 10$, $\text{earliestReadyTime}(O_{22}) = 40$

$\text{earliestReadyTime}(O_{31}) = 20$, $\text{earliestReadyTime}(O_{32}) = 125$

Step 5:

Partial solution: $O_{11} O_{21} O_{22} O_{12} O_{31} O_{32}$ at $t = 125$

$\text{earliestIdleTime}(M_1) = \text{idle}$, $\text{earliestIdleTime}(M_2) = 145$

$\text{earliestReadyTime}(O_{11}) = 0$, $\text{earliestReadyTime}(O_{12}) = 50$

$\text{earliestReadyTime}(O_{21}) = 10$, $\text{earliestReadyTime}(O_{22}) = 40$

$\text{earliestReadyTime}(O_{31}) = 20$, $\text{earliestReadyTime}(O_{32}) = 125$

Step 6:

Final solution: $O_{11} O_{21} O_{22} O_{12} O_{31} O_{32}$ at $t = 145$

$\text{earliestIdleTime}(M_1) = \text{idle}$, $\text{earliestIdleTime}(M_2) = \text{idle}$

$\text{earliestReadyTime}(O_{11}) = 0$, $\text{earliestReadyTime}(O_{12}) = 50$

$\text{earliestReadyTime}(O_{21}) = 10$, $\text{earliestReadyTime}(O_{22}) = 40$

$\text{earliestReadyTime}(O_{31}) = 20$, $\text{earliestReadyTime}(O_{32}) = 125$

4. $J_1 = 75$

$J_2 = 85$

$J_3 = 145$

Makespan = 145

FCFS is better in makespan

5. If one solution is better in one way i.e. makespan, that does not mean the solution rule is better than the rule, as the job completion times on average could be lower in using the other rule.

Part Three: Vehicle Routing

1. $R_1 = (1, 2, 3, 5, 1)$

$R_2 = (1, 6, 8, 4, 1)$

$R_3 = (1, 7, 9, 10, 1)$

2. $R_1 = (1, 2, 3, 5, 1) = 1 + 1 + 1 + 2.24 = 5.24$

$R_2 = (1, 6, 8, 4, 1) = 1.41 + 1.41 + 1.41 + 3.16 = 7.39$

$R_3 = (1, 7, 9, 10, 1) = 2.23 + 3.16 + 2 + 5.39 = 12.78$

$5.24 + 7.39 + 12.78 = 25.41$