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to % Complete	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
st Assigned																				
Slack Cost	115d 0	0	0	0 p06	0	0	0	0 P//	0	0	0	42d 0	0	0	0	20d 0	0	0	0	0
Duration	10d	-	-	25d (100	-	10d	13d	70	10d	12d	73d ,	70		-	22d :	-	10d	٦	20d
~	10d 1	5d 5d	5d 5d	-	10d 10	5d 5d	10d 10	13d 1:	3d 3d	10d 10	12d 13	23d 2:		98 p8	8d 8d	22d 23	7d 7d	10d 10	5d 5d	20d 20
Finish	ene 2	dic 26	ene 2	feb 6	ene 16	ene 23	feb 6	feb 25	feb 11	feb 25	mar 13	abr 15		abr 3	abr 15	may 15	abr 24	may 8	may 15	jun 12
Start	dic 20	dic 20	dic 27	ene 3	ene 3	ene 17	ene 24 f	feb 7	feb 7 f	feb 12 f	feb 26	mar 14		mar 25	abr 4	abr 16	abr 16	abr 25	may 9	may 16
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	Study of the state of the art	Read previous work on the field	ılatforms	Basic framework development	nodel	up simulator	Development of basic control software	of gaits	ection	ion	trol algorithm	Development of remaining software	Communication-related software	Module distributed controller		Hardware platform development	Design and manufacture PCB	Design and manufacture mechanical module	Test results with hardware platform	and Thesis
Name	Study of the s	Read previous	Test existing platforms	Basic framewo	Basic digital model	Select and setup simulator	Development o	Optimization of gaits	Algorithm selection	Gait optimization	Distributed control algorithm	Development	Communicatio	Module distrib	Test results	Hardware plat	Design and ma	Design and ma	Test results wit	Documentation and Thesis
WBS											1	1	5.1	5.2	5.3		6.1	6.2	6.3	