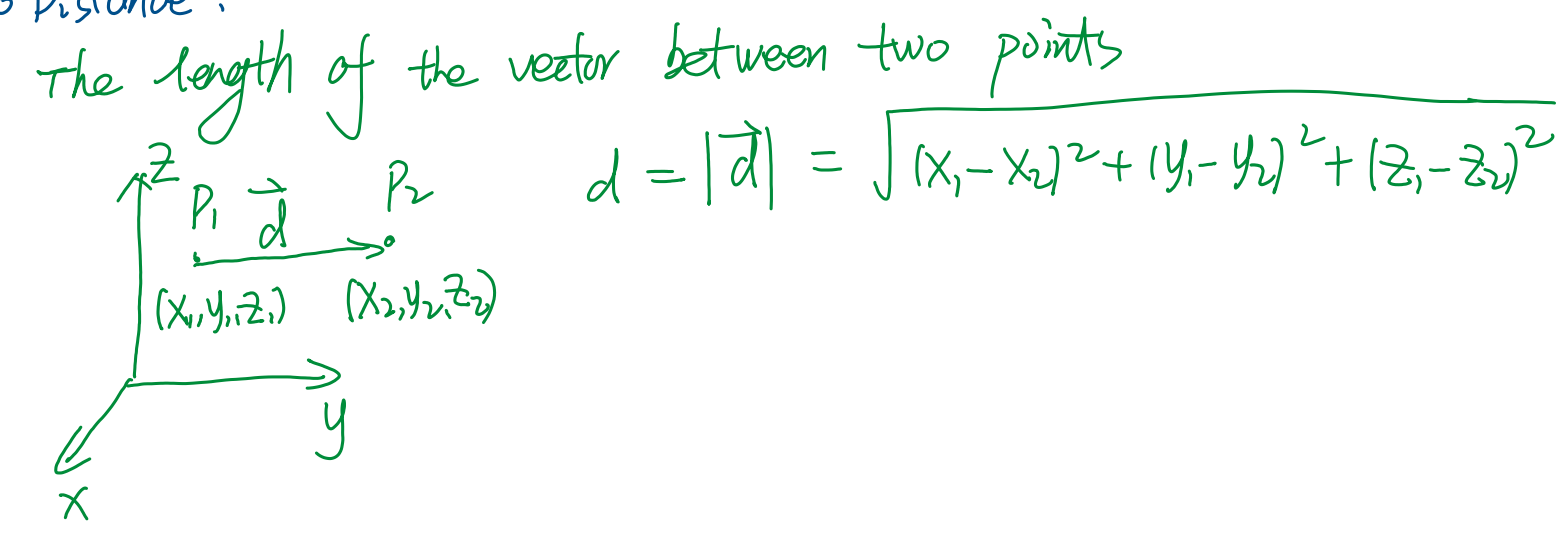


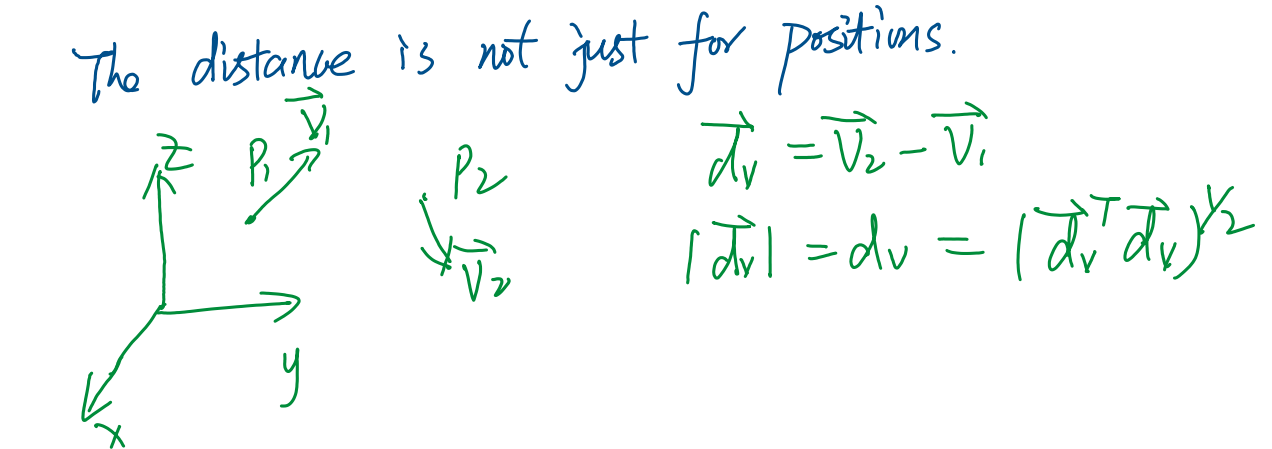
o Distance :

The length of the vector between two points



$d = |\vec{d}| = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2}$

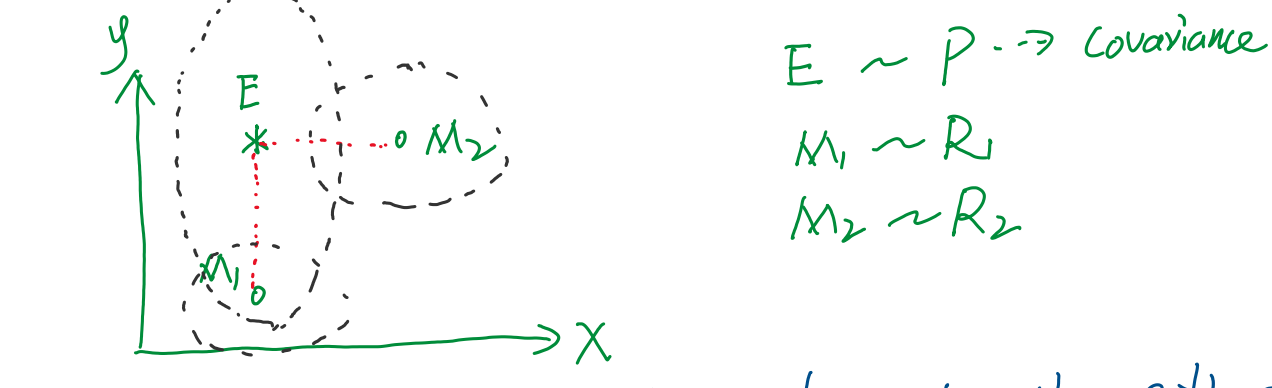
The distance is not just for positions.



$\vec{d} = \vec{P}_2 - \vec{P}_1$
 $|\vec{d}| = d = \sqrt{(\vec{d}^T \vec{d})}^{\frac{1}{2}}$

o Distance for estimation system.

- Distance between estimate and measurement.



$E \sim P \rightarrow \text{covariance}$
 $M_1 \sim R_1$
 $M_2 \sim R_2$

which measurement is closer to the estimate?

1) By crude observation : M_2 is closer.

2) Probabilistic view : M_1 is closer.

o Mahalanobis Distance

- Definition:

Consider a point A with covariance C, and a point B, the Mahalanobis distance is:

$$d^2 = (\vec{x}_B - \vec{x}_A)^T C^{-1} (\vec{x}_B - \vec{x}_A)$$

- Connection with Gaussian Distribution.

p.d.f. for multivariate Gaussian Distribution:

$$f = \frac{1}{\sqrt{\det(2\pi C)}} \exp\left(-\frac{1}{2} \vec{x}^T C^{-1} \vec{x}\right)$$

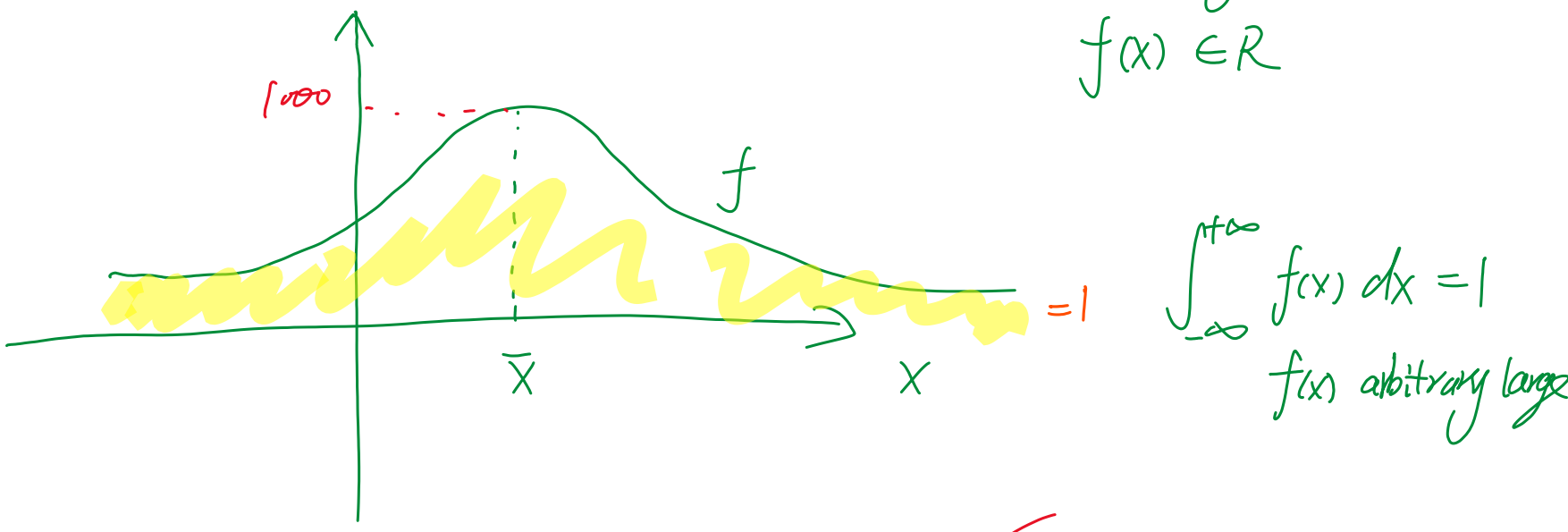
$\rightarrow d$: Mahalanobis distance

tip: f is the probability density not probability.

Normal distribution:

Probability ≤ 1

$f(x) \in \mathbb{R}$



o Matlab program for Mahalanobis distance. ✓