

The Setting

We work in a compact, riemanian, orientable, smooth Manifold (M, g) of dimension m together with a Morse-Smale funktion

$$f : M \rightarrow \mathbb{R} \quad (1)$$

We assume that q is a critical point of index $k+1$ and p is a critical point of index k . we define $f(q) = b$ and $f(p) = a$ and assume that there is no kritical point in $f^{-1}(a, b) \subseteq M$. We define the sub and superlevelsets

$$M^t := \{x \in M | f(x) \leq t\} \quad \text{and} \quad M_t := \{x \in M | f(x) \geq t\}, \quad (2)$$

and the constants

$$c \in (a, b) \quad , \quad \varepsilon > 0 \text{ small} \quad , \quad T > 0 \text{ big} . \quad (3)$$

With this we define the sets:

$$N_q := \{x \in M_c | f(\varphi_{-T}(x)) \leq b + \varepsilon\}, \quad (4)$$

$$L_q := \{x \in N_q | f(x) = c\}, \quad (5)$$

$$N_p := \{x \in M^c | f(\varphi_T(x)) \geq a - \varepsilon\}, \quad (6)$$

$$L_p := \{x \in N_p | f(\varphi_T(x)) = a - \varepsilon\}, \quad (7)$$

and finally:

$$C := N_p \cup N_q, \quad (8)$$

$$B := N_p \cup L_q, \quad (9)$$

$$A := L_p \cup (L_q \overset{\circ}{-} N_p). \quad (10)$$

Lemma 0.0.1. *We claim that*

1. (N_q, L_q) is a regular index pair for q .
2. (C, B) is an index pair for q .
3. (N_p, L_p) is a regular index pair for p .
4. (B, A) is an index pair for p .
5. N_p is a tubular neighbourhood of $W(\rightarrow p) \cap M^c$.

Lemma 0.0.2. *Let $\psi : U \rightarrow V$ be a chart. Then the gradient has the local form:*

$$\text{grad}(f) \circ \psi^{-1} = \sum_{i,j} g^{ij} \frac{\partial f \circ \psi^{-1}}{\partial x^i} \frac{\partial}{\partial x^j}$$

Here, g^{ij} denotes the smooth functions given by the coordinates of the function $x \mapsto (g_{ij}(x))$ that defines the coordinate representation of the gradient in x .

Proof. Assume that $v, w \in \Gamma(TM)$ such that $v = \sum_i v^i \frac{\partial}{\partial x^i}$ and $w = \sum_i w^i \frac{\partial}{\partial x^i}$. Then $g(v, w) = \sum_{i,j} g_{ij} v^i w^j$. Suppose that $\text{grad}(f) = \sum_j G^j \frac{\partial}{\partial x^j}$ and q is the coordinate map $T\mathbb{R} \rightarrow \mathbb{R}$ in each tangent space. Then by definition of the gradient we have:

$$\frac{\partial}{\partial x^j}(f) = q \circ df\left(\frac{\partial}{\partial x^j}\right) = q \circ \frac{\partial f}{\partial x^j} = g(\text{grad}(f), \frac{\partial}{\partial x^j}) = \sum_{ij} g_{ij} G^j$$

Hence, □

Definition 0.0.3 (Jacobian of the Gradient). The gradient is a section into the tangent bundle, $\text{grad}(f) : M \rightarrow TM$. Let $\psi : M \supseteq U \rightarrow V \subseteq \mathbb{R}^m$ be a chart. The coordinate map q_ψ on TU assigns to a vector $v \in T_p M$ (where $p \in U$ with $\psi(p) = x$) its components with respect to the basis $\left(\frac{\partial}{\partial x^i}\Big|_p\right)$, i.e., $q_\psi(v) = (v^1, \dots, v^m)$ if $v = \sum_{i=1}^m v^i \frac{\partial}{\partial x^i}\Big|_p$. We define the Jacobian of the gradient with respect to the chart ψ as the Jacobian matrix of the coordinate representation of the gradient in this chart:

$$J(\text{grad}(f))_\psi(x) := J\left(q_\psi \circ \text{grad}(f) \circ \psi^{-1}\right)(x) = \left(\frac{\partial(q_\psi \circ \text{grad}(f) \circ \psi^{-1})_i}{\partial x_j}(x)\right)_{ij}$$

Lemma 0.0.4. *Let g be a metric and $\varphi_t(x)$ be the flow associated to $-\text{grad}(f)$ meaning*

$$\frac{d}{dt}\Big|_{t_0} \varphi_t(x) = -\text{grad}(f)(\varphi_{t_0}(x))$$

Let furthermore, $\psi : U \rightarrow V$ be a chart. If t_0 is small enough and $x \in U$ such that $\varphi_t(x) \in U$, then

$$\frac{\partial}{\partial t} \psi \circ \varphi_{t_0}(\psi^{-1})(x) =$$

Lemma 0.0.5. *Let $t \in \mathbb{R}$ be small enough and $\varphi_t : M \rightarrow M$ be the flow map corresponding to the negative gradient. Assume that U is the domain of a chart ψ and $p \in U$ such that $\varphi_t(p) \in U$. Then the linear map $d\varphi_t\Big|_p : T_p M \rightarrow T_{\varphi_t(p)} M$ has a*

local representation in the coordinates induced by ψ given by:

$$\frac{\partial}{\partial x} \psi \circ \varphi_t(\psi^{-1}(x)) = \exp \left(-q_\psi \circ \text{grad}(f) \psi^{-1} \cdot t \right).$$

Proof. For this we consider the function $(t, x) \mapsto \psi \circ \varphi_t(\psi^{-1}(x)) : \mathbb{R} \times U \rightarrow U$ For fixed x we can calculate

$$q_\psi \frac{d}{dt} \varphi_t(\psi^{-1}(x)) = -q_\psi \circ \text{grad}(f)(\varphi_t(\psi^{-1}(x)))$$

and by changing the order of integration we have:

$$\begin{aligned} \frac{\partial}{\partial t} \frac{\partial}{\partial x} \psi \circ \varphi_t(\psi^{-1}(x)) &= \frac{\partial}{\partial x} \frac{\partial}{\partial t} \psi \circ \varphi_t(\psi^{-1}(x)) \\ &= \frac{\partial}{\partial x} q_\psi \frac{d}{dt} \varphi_t(\psi^{-1}(x)) \\ &= -\frac{\partial}{\partial x} q_\psi \circ \text{grad}(f)(\varphi_t(\psi^{-1}(x))) \\ &= -\frac{\partial}{\partial x} q_\psi \circ \text{grad}(f) \left(\psi^{-1} \circ \psi \circ \varphi_t(\psi^{-1}(x)) \right) \\ &= -\frac{\partial}{\partial x} \left(q_\psi \circ \text{grad}(f) \circ \psi^{-1} \right) \frac{\partial}{\partial x} \left(\psi \circ \varphi_t(\psi^{-1}(x)) \right) \end{aligned}$$

Hence by the theory of linear differential equation with $\frac{\partial}{\partial x} \psi \circ \varphi_0(\psi^{-1}(x)) = 1_m$ we have:

$$\frac{\partial}{\partial x} \psi \circ \varphi_t(\psi^{-1}(x)) = \exp \left(-q_\psi \circ \text{grad}(f) \circ \psi^{-1} \cdot t \right).$$

□

Lemma 0.0.6. Let ψ be a coordinate system around a critical point p . I.e. $\psi : p \in U \rightarrow V$ with $\psi(p) = 0$ and let $\left(\frac{\partial}{\partial x_1} \Big|_x, \dots, \frac{\partial}{\partial x_m} \Big|_x \right)$ be the induced basis of $T_x M$ Then the jacobian of the gradient

$$J(\text{grad}(f))_\psi(0) = \sum_k g^{ki}(0) \frac{\partial^2 f \circ \psi^{-1}}{\partial x_j \partial x_k} \quad (11)$$

where $(g^{ki}(x))$ denotes the matrix corresponding to the gradient in $T_x M$ with respect to the basis $\left(\frac{\partial}{\partial x_1} \Big|_x, \dots, \frac{\partial}{\partial x_m} \Big|_x \right)$.

Proof. Let q_ψ denote the koordinate function $TU \rightarrow R^m$ induced from the basis $\left(\frac{\partial}{\partial x_1} \Big|_x, \dots, \frac{\partial}{\partial x_m} \Big|_x \right)$. then the gradient in ψ reads:

$$q_\psi \circ \text{grad}(f) = \left(\sum_k g^{k1} \frac{\partial f \circ \psi^{-1}}{\partial x_k}, \dots, \sum_k g^{km} \frac{\partial f \circ \psi^{-1}}{\partial x_k} \right)$$

Hence, we can differentiate:

$$\begin{aligned}\frac{\partial}{\partial x} Q \circ \text{grad}(f) \circ \psi^{-1} &= \left(\frac{\partial}{\partial x_j} \sum_k g^{ki} \frac{\partial f \circ \psi^{-1}}{\partial x_k} \right)_{ij} \\ &= \left(\sum_k \left[\frac{\partial g^{ki}}{\partial x_j} \frac{\partial f \circ \psi^{-1}}{\partial x_k} + g^{ki} \frac{\partial^2 f \circ \psi^{-1}}{\partial x_j \partial x_k} \right] \right)_{ij}.\end{aligned}$$

and now in $p = \psi^{-1}(0)$ we have

$$\left. \frac{\partial}{\partial x} Q \circ \text{grad}(f) \circ \psi^{-1} \right|_0 = \left(\sum_k \left[g^{ki}(0) \frac{\partial^2 f \circ \psi^{-1}}{\partial x_j \partial x_k} \right] \right)_{ij}.$$

□

Theorem 0.0.7 (Sylvester's Law of Inertia). *Let $A \in \text{Mat}(n, \mathbb{R})$ be symmetric and let $T, T' \in \text{GL}(n, \mathbb{R})$ and $k, k', l, l' \in \mathbb{N}$ such that*

$$T^t \circ A \circ T = \begin{pmatrix} 1_k & 0 & 0 \\ 0 & -1_l & 0 \\ 0 & 0 & 0_{n-k-l} \end{pmatrix} \text{ and } T'^t \circ A \circ T' = \begin{pmatrix} 1_{k'} & 0 & 0 \\ 0 & -1_{l'} & 0 \\ 0 & 0 & 0_{n-k'-l'} \end{pmatrix}$$

then $k = k'$, $l = l'$ and $\text{rank}(A) = k + l$.

Proof. Since T, T' are invertible we have that

$$k + l = \text{rank}(T^t \circ A \circ T) = \text{rank}(A) = \text{rank}(T'^t \circ A \circ T') = k' + l'. \quad (12)$$

Hence it suffices to show that $k = k'$. Which we will do by proofing the claim:

$$k = \max \{ \dim(U) \mid U \subseteq \mathbb{R}^n \text{ subspace such that } x^t A x > 0 \ \forall x \in U \setminus \{0\} \}$$

So we start by showing „ \leq “: Denote the first k columns of T with x_1, \dots, x_k . They form a basis of \mathbb{R}^n and with $0 \neq x = \sum_{i=1}^k \lambda_i x_i$ we have that by bilinearity

$$x^t A x = \sum_{i=1}^k \lambda_i x_i^t A x = \sum_{i,j=1}^k \lambda_i \lambda_j x_i^t A x_j = \sum_{i=1}^k (\lambda_i)^2 \geq 0. \quad (13)$$

This concludes the first inequality.

Now let U be any k -dimensional subspace such that for all non zero $x \in U$ $x^t A x > 0$. By a calculation analog to the one above we have that for any $x \in W := \text{span}(x_{k+1}, \dots, x_n)$ the number $x^t A x$ is less or equal to zero. Hence, $W \cap U = \{0\}$ and with this we conclude:

$$\dim(U) = \dim(U + W) - \dim(W) + \dim(U \cap W) \leq (k + (n - k)) - (n - k) + 0 = k. \quad (14)$$

This is the last inequality proving the statement. □

Lemma 0.0.8. Assume that $\psi : U \rightarrow V$ is a chart and $L : \mathbb{R}^m \rightarrow \mathbb{R}^m$ a linear function. Then the diagramm

$$\begin{array}{ccc} T_p M & \xrightarrow{q_\psi|_p} & \mathbb{R}^m \\ & \searrow q_{L \circ \psi}|_p & \downarrow L \\ & & \mathbb{R}^m \end{array}$$

commutes for all $p \in U$.

Proof. We show this by showing the inverse: For any $v \in \mathbb{R}^m$ we have the two $(q_\psi|_p)^{-1} \circ L^{-1}(v)$ and $(q_{\psi \circ L}|_p)^{-1}$ and claim that they are the same. Assume that $L^{-1} = (\lambda_{ij})_{ij}$, $\psi(p) = x_0$, $L(x_0) = \tilde{x}_0$, $(v^1, \dots, v^m) = v \in \mathbb{R}^m$ and denote the basis of $T_p M$ coming from the chart ψ by $\left(\frac{\partial}{\partial x^i}\bigg|_p\right)_i$ and the one coming from $L^{-1} \circ \psi$ by $\left(\frac{\partial}{\partial \tilde{x}^i}\bigg|_p\right)_i$. We now calculate for $f_p \in \mathcal{E}_p M$:

$$\begin{aligned} \left[(q_{\psi \circ L}|_p)^{-1}(v)\right](f_p) &= \sum_i v^i \frac{\partial}{\partial \tilde{x}^i}\bigg|_p(f_p) \\ &= \sum_i v^i \frac{\partial}{\partial x^i}\bigg|_{\tilde{x}_0}(f \circ \psi^{-1} \circ L^{-1}) \\ &= \sum_i v^i \sum_j \frac{\partial f \circ \psi^{-1}}{\partial x^j}\bigg|_{x_0} \cdot \frac{\partial L_j^{-1}}{\partial x^i}\bigg|_{\tilde{x}_0} \\ &= \sum_{i,j} v^i \frac{\partial}{\partial x^j}\bigg|_p(f_p) \cdot \lambda_{ji} \\ &= \sum_{i,j} v^i q_\psi|_p^{-1}(e_j)(f_p) \cdot \lambda_{ji} \\ &= \left[q_\psi|_p^{-1}\left(\sum_{i,j} v^i \lambda_{ji} e^j\right)\right](f_p) \\ &= \left[q_\psi|_p^{-1}(L^{-1}(v))\right](f_p) \end{aligned}$$

This concludes the proof. □

Theorem 0.0.9 (Simultaneous Diagonalisation of Quadratic Forms). *Let p be a critical point of a Morse function f on a manifold M and let $g(p)$ be the Riemannian metric on $T_p M$. Then there exists a Morse chart ψ around p such that the representation of $g(p)$ in the basis induced by the Morse chart is given by a diagonal matrix $\text{diag}(\mu_1, \dots, \mu_m)$ with $\mu_i > 0$ for all i .*

Proof. The quadratic form of $f \circ \psi^{-1} - f(p)$ in the coordinates of any Morse chart ψ is $q_H(v) = v^T H v$. The quadratic form induced by the Riemannian metric $g(p)$ is $q_G(v) = v^T G v$, where $v \in \mathbb{R}^m$ are the coordinate vectors with respect to the Morse chart. To be precise this means for $v, w \in \mathbb{R}^m$:

$$g \circ (q_\psi|_p \oplus q_\psi|_p)(v, w) = v^T G w \text{ and } f \circ \psi^{-1}(v) = f(p) + v^T H v.$$

We now aim to manipulate ψ such that G becomes diagonal: Since $g(p)$ is positive definite, G is also positive definite, and H is symmetric.

Consider the generalized eigenvalue problem $Hv = \lambda Gv$. Since H and G are real symmetric matrices and G is positive definite, this problem has m real eigenvalues $\lambda_1, \dots, \lambda_m$ and corresponding eigenvectors v_1, \dots, v_m , which can be chosen to be orthogonal with respect to the bilinear form defined by G , such that $v_i^T G v_j = \delta_{ij}$, since if v_i and v_j are different eigenvectors with respect to different eigenvalues, we can calculate:

$$v_j^T H v_i = (H v_j)^T v_i = \lambda_j (G v_j)^T v_i = \lambda_j v_j^T G(v_i) \quad \text{and} \quad v_j^T H v_i = v_j^T \lambda_i G(v_i) = \lambda_i v_j^T G(v_i).$$

Hence we have the equality

$$\lambda_j (G v_j)^T v_i = \lambda_i v_j^T G(v_i) \Leftrightarrow \underbrace{(\lambda_j - \lambda_i)}_{\neq 0} v_j^T G(v_i) = 0$$

Hence all eigenspaces are orthogonal and we can use Gram Schmitt to make the bases of the eigenspaces orthogonal and by rescaling orthonormal.

Let $L = [v_1 | \dots | v_m]$ be the matrix whose columns are these G -orthonormal eigenvectors. The linear change of coordinates $y = Lz$ leads to new coordinates z . In these new coordinates, the quadratic forms transform as follows:

$$\begin{aligned} q_G(y) &= y^T G y = (Lz)^T G (Lz) = z^T L^T G L z = z^T I z = \sum_{i=1}^m z_i^2 \\ q_H(y) &= y^T H y = (Lz)^T H (Lz) = z^T L^T H L z \end{aligned}$$

Since $H v_i = \lambda_i G v_i$, we have $L^T H L = \text{diag}(\lambda_1, \dots, \lambda_m)$. The eigenvalues λ_i are real and have the same signature as the eigenvalues of H (l negative, $m - l$ positive). This is true to Sylvester's law of inertia. By a further scaling of the v_i and a reordering the matrix $L^T H L$ can be brought into the form $\text{diag}(-1, \dots, -1, 1, \dots, 1)$. (by doing this however, the matrix $L^T G L$ becomes $L^T G L = \text{diag}(\mu_1, \dots, \mu_m)$ with $\mu_j > 0 \ \forall j$). If ψ is the Morse chart we started with, then $L^{-1} \circ \psi$ is the new Morse chart:

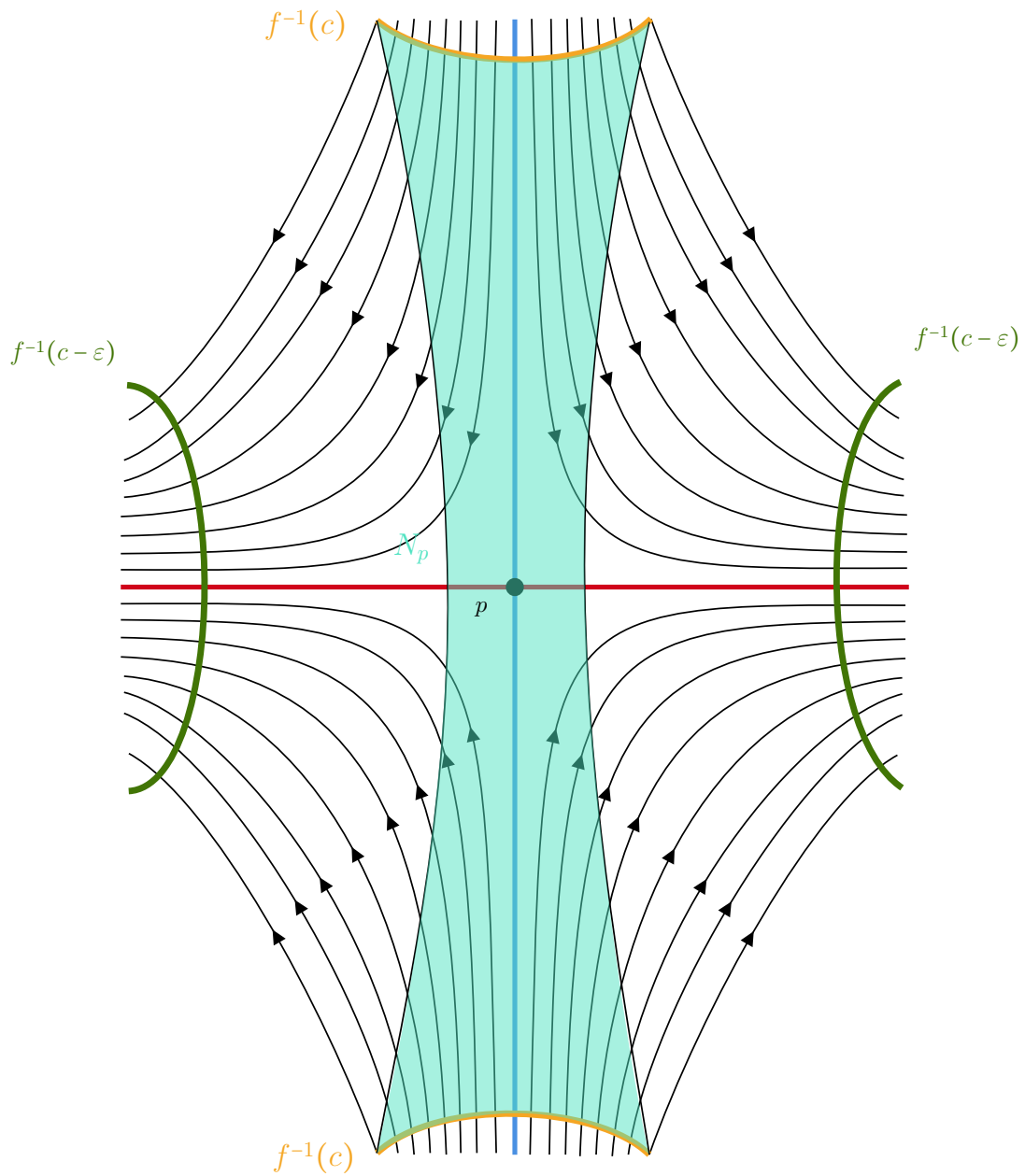
$$f \circ (\psi^{-1} \circ L)(y) = f \circ \psi^{-1}(L(y)) = q_H(L(y)) = \sum_{i=1}^l -y_i^2 + \sum_{i=l+1}^m y_i^2$$

Furthermore, we want to inspect the metric $g|_p : T_p M^2 \rightarrow \mathbb{R}$ with respect to the chart $L^{-1} \circ \psi$ -induced basis $\left(\frac{\partial}{\partial x^1}|_p, \dots, \frac{\partial}{\partial x^m}|_p \right)$. By the lemma 0.0.8

$$g(q_{L^{-1} \circ \psi}|_p^{-1}, q_{L^{-1} \circ \psi}|_p^{-1})(v, w) = g(q_\psi|_p^{-1}, q_\psi|_p^{-1})(Lv, Lw) = (Lv)^T G L W = v^T L^T G L w$$

□

Proof. The statements 1-4 are easy to proof by the definitions. The regularity can be derived from a general fact for pairs (X, Y) in metric spaces: If Y is closed in X and there is a neighbourhood of Y that is open in X such that Y is a strong deformation retract of U . So the only thing left to show is, that N_p is a tubular neighbourhood. in **[MorseTheorySalmbo]** in the proof of lemma 3.2 Salamon claims this to be true without a proof (page 119 in the attached source). Similar, in **[banyaga2004lectures]** Banyaga claims this (also without any argument). I find this difficult to proof, since we cannot use the flow for the map from the normal bundle, as points leave N_p along the flow: The Set N_p is sketched in the figure below.



Idea: Show it locally in a morse chart around p . Hopefully we can archive, that in such a chart the property $\varphi_T(x) \geq a - \epsilon$ translates to $x = \psi(x_s, x_u)$ where $\|x_u\| \leq T_x$. Then assume T to be big enough such that for any $x \in N_p$ there is a chart U around a point $x_p \in W(\rightarrow p)$ and a t_0 such that $\varphi_{t_0}(U)$ lives in said morse chart. Finally check if the property required around said x_p can be formulated such that U has a tubular structure. So lets start this procedure! Let

$$\psi : p \in V \rightarrow U \subseteq \mathbb{R}^m$$

be a morse chart. Here the function f is of the form

$$f \circ \psi^{-1}(x_s, x_u) = a + x^{s^2} - x^{u^2}.$$

where x^{s^2} and x^{u^2} denotes the sum of all the squares from the morse lemma. Without restrictions we call $x^s = (x^1, \dots, x^l)$ and $x^u = (x^{l+1}, \dots, x^m)$. Now we inspect the set

$$\psi^{-1}(N_p \cap V) = \left\{ (x^s, x^u) \in U \mid f \circ \varphi_T(\psi^{-1}(x^s, x^u)) \geq a - \varepsilon \right\}. \quad (15)$$

First we inspect the gradient in those local coordinats, i.e. $x = \psi^{-1}(u)$:

$$\text{grad}(f)(x) = g^{ik} \frac{\partial f}{\partial x^k} \frac{\partial}{\partial x^i}$$

For now assume that $g_{ik} = \text{diag}(1, \dots, 1)$, i.e. that we work with the euklidean metric. Then the gradient is:

$$\sum_{i,k} \frac{\partial f \circ \psi^{-1}}{\partial x^k} \frac{\partial}{\partial x^i} = 2 \frac{\partial}{\partial x^s} - 2 \frac{\partial}{\partial x^u}.$$

Hence, the flow corresponding to $\psi_*(-\text{grad}(f))$ is of the form

$$t \mapsto \varphi_t(x) = (e^{-2t} x^s, e^{2t} x^u).$$

Assume that ε is small enough, such that all $x \in \psi(N_p \cap V) \setminus W(\rightarrow p)$ flow through $f^{-1}(a - \varepsilon)$ inside of U , i.e. we can formulate the property:

$$f \circ \varphi_T(\psi^{-1}(x^s, x^u)) \geq a - \varepsilon \quad \Leftrightarrow \quad f\left(\psi^{-1}(e^{-2T} x^s, e^{2T} x^u)\right) = a + (e^{-2T} x^s)^2 - (e^{2T} x^u)^2 \geq a - \varepsilon \quad (16)$$

This however reads:

$$a + (e^{-2T} x^s)^2 - (e^{2T} x^u)^2 \geq a - \varepsilon \quad \Leftrightarrow \quad (e^{2T} x^u)^2 \leq \varepsilon + (e^{-2T} x^s)^2$$

And hence we have that:

$$\psi(N_p \cap V) = \left\{ (x^s, x^u) \in U \mid \|x^u\| \leq R(x^s) \right\}$$

where $R(x^s)$ is a smooth function. Now let g be a general metric, and ψ a Morse chart centered in p such that $g(p)$ is a diagonal quadratic form with respect to that morse chart. We now want to interlinear approximate $\psi \circ \varphi_t \circ \psi^{-1} : U \rightarrow U$ which leads to the need of its jacobian. By lemma ?? together with the local form of the gradient we have the form:

$$q_\psi \frac{\partial}{\partial x} \Big|_0 \varphi_t(\psi^{-1}(x)) = \exp \left(\sum_k \left(g^{ki}(0) \frac{\partial^2 (f \circ \psi^{-1})}{\partial x^j \partial x^k} \right)_{ij} \right).$$

Now $g^{ki}(0) = \delta_{ik}\mu_k$ with $\mu_i > 0$ for all i and $\frac{\partial^2(f \circ \psi^{-1})}{\partial x^j \partial x^k} = s_k 2\delta_{jk}$ where $s_k = -1$ if $k \leq l$ and $s_k = 1$ else. Hence:

$$\begin{aligned} \frac{\partial}{\partial x} \Big|_0 \psi \circ \varphi_t(\psi^{-1}(x)) &= -\exp(\text{diag}(-2\mu_1 t, \dots, -2\mu_l t, 2\mu_{l+1} t, \dots, 2\mu_m t)) \\ &= \text{diag}(e^{2\mu_1 t}, \dots, e^{2\mu_l t}, e^{-2\mu_{l+1} t}, \dots, e^{-2\mu_m t}) \end{aligned}$$

Hence we can linearly approximate the flow for fixed t in a chart centered at the critical point to get a function $\mathcal{R}: V \rightarrow V$ such that $\mathcal{R} \in \mathcal{O}(\|x\|^2)$:

$$\begin{aligned} \psi \circ \varphi_t(\psi^{-1}(x)) &= \psi \circ \varphi_t(\psi^{-1}(0)) + \left(\frac{\partial}{\partial x} \Big|_0 \psi \circ \varphi_t(\psi^{-1}) \right) x + \mathcal{R}(x) \\ &= \left(\text{diag}(e^{2\mu_1 t}, \dots, e^{2\mu_l t}, e^{-2\mu_{l+1} t}, \dots, e^{-2\mu_m t}) \right) (x) + \mathcal{R}(x) \end{aligned}$$

We give the following definitions:

- $x^u := (x^1, \dots, x^l)$ and $x^s := (x^{l+1}, \dots, x^m)$, and with this we split $x = (x^u, x^s)$.
- $-(x^u)^2 := \sum_{i=1}^l -(x^i)^2$ and $(x^s)^2 := \sum_{i=l+1}^m (x^i)^2$ and hence
$$f \circ \psi^{-1}(x^u, x^s) = a - (x^u)^2 + (x^s)^2.$$
- $e^{2\mu_u t} x^u := (e^{2\mu_1 t} x^1, \dots, e^{2\mu_l t} x^l)$ and similar $e^{-2\mu_s t} x^s := (e^{-2\mu_{l+1} t} x^{l+1}, \dots, e^{-2\mu_m t} x^m)$.
- $\mathcal{R}^u(x)$ and $\mathcal{R}^s(x)$ such that $\mathcal{R}(x) = (\mathcal{R}^u(x), \mathcal{R}^s(x))$

With these notations the calculation above yields:

$$\psi \circ \varphi_t(\psi^{-1}(x))(x^u, x^s) = \left(e^{2\mu_u t} x^u + \mathcal{R}^u(x), e^{-2\mu_s t} x^s + \mathcal{R}^s(x) \right).$$

Now the property of being in $\psi(N_p \cap U)$ reads:

$$\begin{aligned} x \in V \text{ such that } & f(\varphi_T(\psi^{-1}(x))) && \leq a - \varepsilon \\ \Leftrightarrow & (f \circ \psi^{-1})(\psi \circ \varphi_T(\psi^{-1}(x))) && \leq a - \varepsilon \\ \Leftrightarrow & (f \circ \psi^{-1})(e^{2\mu_u T} x^u + \mathcal{R}^u(x), e^{-2\mu_s T} x^s + \mathcal{R}^s(x)) && \leq a - \varepsilon \\ \Leftrightarrow & -\left(-e^{2\mu_u T} x^u + \mathcal{R}^u(x)\right)^2 + \left(e^{-2\mu_s T} x^s + \mathcal{R}^s(x)\right)^2 + \varepsilon && \leq 0 \end{aligned}$$

We now inspect the funktion $F: \mathbb{R}^m \rightarrow \mathbb{R}^l$ given by:

$$\begin{pmatrix} x^1 \\ \vdots \\ x^m \end{pmatrix} \mapsto \begin{pmatrix} -(e^{2\mu_1 T} x^1)^2 & +2e^{2\mu_1 T} x^1 \mathcal{R}^1(x) & +(\mathcal{R}^1(x))^2 & + (e^{-2\mu_s T} x^s + \mathcal{R}^s(x))^2 \\ \vdots & \vdots & \vdots & \\ -(e^{2\mu_l T} x^l)^2 & +2e^{2\mu_l T} x^l \mathcal{R}^l(x) & +(\mathcal{R}^l(x))^2 & \end{pmatrix}.$$

For this funktion we have that

$$\frac{\partial}{\partial x^s} F$$

is non-degenerat, since:

□