## The Setting

We work in a compact, riemanian, orientable, smooth Manifold (M, g) of dimension m together with a Morse-Smale funktion

$$f: M \to \mathbb{R} \tag{1}$$

We assume that q is a critical point of index k+1 and p is a critical point of index k. we define f(q) = b and f(p) = a and assume that there is no kritical point in  $f^{-1}(a,b) \subseteq M$ . We define the sub and superlevelsets

$$M^t := \{x \in M | f(x) \le t\} \quad \text{and} \quad M_t := \{x \in M | f(x) \ge t\}, \tag{2}$$

and the constants

$$c \in (a, b)$$
 ,  $\varepsilon > 0$  small ,  $T > 0$  big . (3)

With this we define the sets:

$$N_q := \left\{ x \in M_c \middle| f(\varphi_{-T}(x)) \le b + \varepsilon \right\},\tag{4}$$

$$L_q := \left\{ x \in N_q | f(x) = c \right\},\tag{5}$$

$$N_p := \left\{ x \in M^c \middle| f(\varphi_T(x)) \ge a - \varepsilon \right\},\tag{6}$$

$$L_p := \left\{ x \in N_p \middle| f(\varphi_T(x)) = a - \varepsilon \right\},\tag{7}$$

and finally:

$$C := N_n \cup N_q \,, \tag{8}$$

$$B \coloneqq N_p \cup L_q \,, \tag{9}$$

$$A \coloneqq L_p \cup (L_q - N_p). \tag{10}$$

## Lemma 0.0.1. We claim that

- 1.  $(N_q, L_q)$  is a regular index pair for q.
- 2. (C,B) is an index pair for q.
- 3.  $(N_p, L_p)$  is a regular index pair for p.
- 4. (B,A) is an index pair for p.
- 5.  $N_p$  is a tubular neighbourhood of  $W(\rightarrow p) \cap M^c$  .

**Lemma 0.0.2.** Let  $\psi: U \to V$  be a chart. Then the gradient has the local form:

$$\operatorname{grad}(f) \circ \psi - 1 = \sum_{i,j} g^{ij} \frac{\partial f \circ \psi^{-1}}{\partial x^i} \frac{\partial}{\partial x^j}$$

Here,  $g^{ij}$  denotes the smooth functions given by the coordinates of the function  $x \mapsto (g_{ij}(x))$  that defines the coordinate representation of the gradient in x.

*Proof.* Assume that  $v, w \in \Gamma(TM)$  such that  $v = \sum_i v^i \frac{\partial}{\partial x^i}$  and  $w = \sum_i w^i \frac{\partial}{\partial x^i}$ . Then  $g(v, w) = \sum_{i,j} g_{ij} v^i w^i$ . Suppose that  $\operatorname{grad}(f) = \sum_j G^j \frac{\partial}{\partial x^i}$  and q is the coordinate map  $T\mathbb{R} \to \mathbb{R}$  in each tangend space. Then by definition of the gradient we have:

$$\frac{\partial}{\partial x^{j}}(f) = q \circ \mathrm{d}f(\frac{\partial}{\partial x^{j}}) = q \circ \frac{\partial f}{\partial x^{j}} = g(\mathrm{grad}(f), \frac{\partial}{\partial x^{j}}) = \sum_{ij} g_{ij}G^{j}$$

**Definition 0.0.3** (Jacobian of the Gradient). The gradient is a section into the tangent bundle,  $\operatorname{grad}(f): M \to TM$ . Let  $\psi: M \supseteq U \to V \subseteq \mathbb{R}^m$  be a chart. The coordinate map  $q_{\psi}$  on TU assigns to a vector  $v \in T_pM$  (where  $p \in U$  with  $\psi(p) = x$ ) its components with respect to the basis  $\left(\frac{\partial}{\partial x^i}\Big|_p\right)$ , i.e.,  $q_{\psi}(v) = (v^1, \dots, v^m)$  if  $v = \sum_{i=1}^m v^i \frac{\partial}{\partial x^i}\Big|_p$ . We define the Jacobian of the gradient with respect to the chart  $\psi$  as the Jacobian matrix of the coordinate representation of the gradient in this chart:

$$J(\operatorname{grad}(f))_{\psi}(x) \coloneqq J\left(q_{\psi} \circ \operatorname{grad}(f) \circ \psi^{-1}\right)(x) = \left(\frac{\partial (q_{\psi} \circ \operatorname{grad}(f) \circ \psi^{-1})_{i}}{\partial x_{j}}(x)\right)_{ij}$$

**Lemma 0.0.4.** Let g be a metric and  $\varphi_t(x)$  be the flow associated to  $-\operatorname{grad}(f)$  meaning

$$\frac{\mathrm{d}}{\mathrm{d}t}\Big|_{t_0}\varphi_t(x) = -\mathrm{grad}(f)(\varphi_{t_0}(x))$$

Let furthermore,  $\psi: U \to V$  be a chart. If  $t_0$  is small enough and  $x \in U$  such that  $\varphi_t(x) \in U$ , then

$$\frac{\partial}{\partial t}\psi\circ\varphi_{t_0}(\psi^{-1})(x)=$$

**Lemma 0.0.5.** Let  $t \in \mathbb{R}$  be small enough and  $\varphi_t : M \to M$  be the flow map corresponding to the negative gradient. Assume that U is the domain of a chart  $\psi$  and  $p \in U$  such that  $\varphi_t(p) \in U$ . Then the linear map  $d\varphi_t|_p : T_pM \to T_{\varphi_t(p)}M$  has a

local representation in the coordinates induced by  $\psi$  given by:

$$q_{\psi(\varphi_t(p))} \circ d\varphi_t|_p \circ q_{\psi(p)}^{-1} = \exp\left(-J(\operatorname{grad}(f))_{\psi}(\psi(p)) \cdot t\right)$$

where  $J(\operatorname{grad}(f))_{\psi}(\psi(p))$  is the Jacobian matrix of the gradient evaluated at the coordinates of p.

*Proof.* We will inspect what differebtial equation the map  $q_{\psi(\varphi_t(p))} \circ d\varphi_t|_p \circ q_{\psi(p)}^{-1}$  solves and hence we differentiate:

$$\frac{\partial}{\partial t} \left( q_{\psi(\varphi_{t}(p))} \circ d\varphi_{t} \Big|_{p} \circ q_{\psi(p)}^{-1} \right) = \frac{\partial}{\partial t} J(\psi \circ \varphi_{t}(\psi^{-1}(x)))$$

$$= \frac{\partial}{\partial t} \left( \frac{\partial \left( \psi \circ \varphi_{t}(\psi^{-1}(x)) \right)_{i}}{\partial x^{j}} \right)_{ij}$$

$$= \left( \frac{\partial}{\partial t} \frac{\partial \left( \psi \circ \varphi_{t}(\psi^{-1}(x)) \right)_{i}}{\partial x^{j}} \right)_{ij}$$

$$= \left( \frac{\partial}{\partial x^{j}} \frac{\partial}{\partial t} \left( \psi \circ \varphi_{t}(\psi^{-1}(x)) \right)_{i} \right)_{ij}$$

$$= \left( \frac{\partial}{\partial t} \frac{\partial}{\partial x^{j}} \left( \psi \circ \varphi_{t}(\psi^{-1}(x)) \right)_{i} \right)_{ij}$$

**Lemma 0.0.6.** Let  $\psi$  be a coordinate system arround a critical point p. I.e.  $\psi: p \in U \to V$  with  $\psi(p) = 0$  and let  $\left(\frac{\partial}{\partial x_1}\Big|_x, \ldots, \frac{\partial}{\partial x_m}\Big|_x\right)$  be the induced basis of  $T_xM$  Then the jacobean of the gradient

$$J(\operatorname{grad}(f))_{\psi}(0) = \sum_{k} g^{ki}(0) \frac{\partial^{2} f \circ \psi^{-1}}{\partial x_{j} \partial x_{k}}$$
(11)

where  $(g^{ki}(x))$  denotes the matrix corresponding to the gradient in  $T_xM$  with respect to the basis  $\left(\frac{\partial}{\partial x_1}\Big|_x,\ldots,\frac{\partial}{\partial x_m}\Big|_x\right)$ .

*Proof.* Let  $q_{\psi}$  denote the koordinate funktion  $TU \to R^m$  induced from the basis  $\left(\frac{\partial}{\partial x_1}\big|_x, \dots, \frac{\partial}{\partial x_m}\big|_x\right)$ . then the gradient in  $\psi$  reads:

$$q_{\psi} \circ \operatorname{grad}(f) \circ \psi^{-1} = \left(\sum_{k} g^{k1} \frac{\partial f \circ \psi^{-1}}{\partial x_{k}}, \dots, \sum_{k} g^{km} \frac{\partial f \circ \psi^{-1}}{\partial x_{k}}\right)$$

Hence, we can calculate Hence, we can differentiate:

$$\frac{\partial}{\partial x} Q \circ \operatorname{grad}(f) \circ \psi^{-1} = \left( \frac{\partial}{\partial x_j} \sum_{k} g^{ki} \frac{\partial f \circ \psi^{-1}}{\partial x_k} \right)_{ij}$$
$$= \left( \sum_{k} \left[ \frac{\partial g^{ki}}{\partial x_j} \frac{\partial f \circ \psi^{-1}}{\partial x_k} + g^{ki} \frac{\partial^2 f \circ \psi}{\partial x_j \partial x_k} \right] \right)_{ij}.$$

and now in  $p = \psi - 1(0)$  we have

$$\left. \frac{\partial}{\partial x} Q \circ \operatorname{grad}(f) \circ \psi^{-1} \right|_{0} = \left( \sum_{k} \left[ g^{ki}(0) \frac{\partial^{2} f \circ \psi^{-1}}{\partial x_{j} \partial x_{k}} \right] \right)_{ij}.$$

**Theorem 0.0.7** (Sylvesters Law of Inertia). Let  $A \in \text{Mat}(n, \mathbb{R})$  be symmetric and let  $T, T' \in \text{GL}(n, \mathbb{R})$  and  $k, k', l, l' \in \mathbb{N}$  such that

$$T^{t} \circ A \circ T = \begin{pmatrix} 1_{k} & 0 & 0 \\ 0 & -1_{l} & 0 \\ 0 & 0 & 0_{n-k-l} \end{pmatrix} \text{ and } T'^{T} \circ A \circ T' = \begin{pmatrix} 1_{k'} & 0 & 0 \\ 0 & -1_{l'} & 0 \\ 0 & 0 & 0_{n-k'-l'} \end{pmatrix}$$

then k = k', l = l' and rank(A) = k + l.

*Proof.* Since T, T' are invertible we have that

$$k + l = \operatorname{rank}(T^t \circ A \circ T) = \operatorname{rank}(A) = \operatorname{rank}(T'^T \circ A \circ T') = k' + l'. \tag{12}$$

Hence it suffices to show that k = k'. Which we will do by proofing the claim:

$$k = \max \left\{ \dim(U) | U \subseteq \mathbb{R}^n \text{ subspace such that } x^t A x > 0 \ \forall x \in U \setminus \{0\} \right\}$$

So we start by showing ": Denote the first k colomus of T with  $x_1, ..., x_k$ . They form a basis of  $\mathbb{R}^n$  and with  $0 \neq x = \sum_{i=1}^k \lambda_i x^i$  we have that by bilinearity

$$x^{T} A x = \sum_{i=1}^{k} \lambda_{i} x_{i}^{T} A x = \sum_{i,j=1}^{k} \lambda_{i} \lambda_{j} x_{i}^{T} A x_{j} = \sum_{i=1}^{k} (\lambda_{i})^{2} \ge 0.$$
 (13)

This conculdes the first inequality.

Now let U be any k-dimensional subspace such that for all non zero  $x \in U$   $x^T A x > 0$ . By a calculation analog to the one above we have that for any  $x \in W := \operatorname{span}(x_{k+1}, \dots x_n)$  the number  $x^t A x$  is less or equal to zero. Hence,  $W \cap U = \{0\}$  and with this we conclude:

$$\dim(U) = \dim(U+W) - \dim(W) + \dim(U \cap W) \le (k + (n-k)) - (n-k) + 0 = k.$$
 (14)

This is the last inequality proving the statement.

**Lemma 0.0.8.** Assume that  $\psi: U \to V$  is a chart and  $L: \mathbb{R}^m \to \mathbb{R}^m$  a linear function. Then the diagramm

$$T_p M \xrightarrow{q_{\psi|_p}} \mathbb{R}^m \downarrow_L$$

$$\mathbb{R}^m$$

commutes for all  $p \in U$ .

*Proof.* We show this by showing the inverse: For any  $v \in \mathbb{R}^m$  we have the two  $(q_\psi|_p)^{-1} \circ L^{-1}(v)$  and  $(q_{\psi \circ L}|p)^{-1}$  and claim that they are the same. Assume that  $L^{-1} = (\lambda_{ij})_{ij}$ ,  $\psi(p) = x_0, \ L(x_0) = \tilde{x_0}, \ (v^1, \dots v^m) = v \in \mathbb{R}^m$  and denote the basis of  $T_pM$  coming from the chart  $\psi$  by  $\left(\frac{\partial}{\partial x^i}|_p\right)_i$  and the one coming from  $L^{-1} \circ \psi$  by  $\left(\frac{\partial}{\partial \tilde{x}^i}|_p\right)_i$ . We now calculate for  $f_p \in \mathcal{E}_pM$ :

$$\begin{aligned}
& \left[ (q_{\psi \circ L}|_{p})^{-1}(v) \right] (f_{p}) = \sum_{i} v^{i} \frac{\partial}{\partial \tilde{x}^{i}}|_{p} (f_{p}) \\
&= \sum_{i} v^{i} \frac{\partial}{\partial x^{i}}|_{\tilde{x}_{0}} (f \circ \psi^{-1} \circ L^{-1}) \\
&= \sum_{i} v^{i} \sum_{j} \frac{\partial f \circ \psi^{-1}}{\partial x^{j}}|_{x_{0}} \cdot \frac{\partial L_{j}^{-1}}{\partial x^{i}}|_{\tilde{x}_{0}} \\
&= \sum_{i,j} v^{i} \frac{\partial}{\partial x^{j}}|_{p} (f_{p}) \cdot \lambda_{ji} \\
&= \sum_{i,j} v^{i} q_{\psi}|_{p}^{-1} (e_{j}) (f_{p}) \cdot \lambda_{ji} \\
&= \left[ q_{\psi}|_{p}^{-1} (\sum_{i,j} v^{i} \lambda_{ji} e^{j}) \right] (f_{p}) \\
&= \left[ q_{\psi}|_{p}^{-1} (L^{-1}(v)) \right] (f_{p})
\end{aligned}$$

This concludes the proof.

**Theorem 0.0.9** (Simultaneous Diagonalisation of Quadratic Forms). Let p be a critical point of a Morse function f on a manifold M and let g(p) be the Riemannian metric on  $T_pM$ . Then there exists a Morse chart  $\psi$  arround p such that the representation of g(p) in the basis induced by the Morse chart is given by a a diagonal matrix  $diag(\mu_1, \ldots \mu_m)$  with  $\mu_i > 0$  for all i.

Proof. The quadratic form of  $f \circ \psi^{-1} - f(p)$  in the coordinates of any Morse chart  $\psi$  is  $q_H(v) = v^T H v$ . The quadratic form induced by the Riemannian metric g(p) is  $q_G(v) = v^T G v$ , where  $v \in \mathbb{R}^m$  are the coordinate vectors with respect to the Morse chart. To be precise this means for  $v, w \in \mathbb{R}^m$ :

$$g \circ (q_{\psi}|_{p} \oplus q_{\psi}|_{p})(v, w) = v^{T}Gw$$
 and  $f \circ \psi^{-1}(v) = f(p) + v^{T}Hv$ .

We now aim to manipulate  $\psi$  such that G becomes diagonal: Since g(p) is positive definite, G is also positive definite, and H is symmetric.

Consider the generalized eigenvalue problem  $Hv = \lambda Gv$ . Since H and G are real symmetric matrices and G is positive definite, this problem has m real eigenvalues  $\lambda_1, \ldots, \lambda_m$  and corresponding eigenvectors  $v_1, \ldots, v_m$ , which can be chosen to be orthogonal with respect to the bilinear form defined by G, such that  $v_i^T G v_j = \delta_{ij}$ , since if  $v_i$  and  $v_j$  are different eigenvectors with respect to different eigenvalues, we can calculate:

$$v_j^T H v_i = (H v_j)^T v_i = \lambda_j (G v_j)^T v_i = \lambda_j v_j^T G(v_i) \quad \text{and} \quad v_j^T H v_i = v_j^T \lambda_i G(v_i) = \lambda_i v_j^T G(v_i).$$

Hence we have the equality

$$\lambda_j (Gv_j)^T v_i = \lambda_i v_j^T G(v_i) \Leftrightarrow \underbrace{(\lambda_j - \lambda_i)}_{\neq 0} v_j^T G(v_i) = 0$$

Hence all eigenspaces are orthogonal and we can use Gram Schmitt to make the bases of the eigenspaces orthogonal and by rescaling orthonormal.

Let  $L = [v_1|...|v_m]$  be the matrix whose columns are these G-orthonormal eigenvectors. The linear change of coordinates y = Lz leads to new coordinates z. In these new coordinates, the quadratic forms transform as follows:

$$q_G(y) = y^T G y = (Lz)^T G(Lz) = z^T L^T G L z = z^T I z = \sum_{i=1}^m z_i^2$$
  
 $q_H(y) = y^T H y = (Lz)^T H(Lz) = z^T L^T H L z$ 

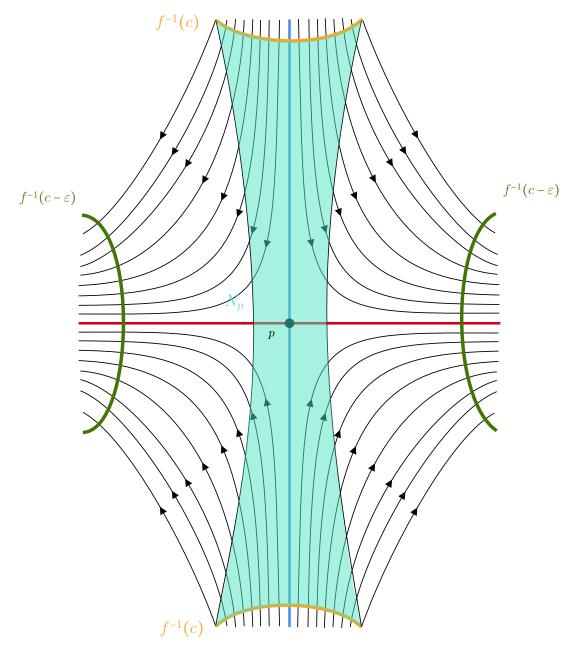
Since  $Hv_i = \lambda_i Gv_i$ , we have  $L^T H L = \operatorname{diag}(\lambda_1, \ldots, \lambda_m)$ . The eigenvalues  $\lambda_i$  are real and have the same signature as the eigenvalues of H (l negative, m-l positive). This is true to sysvesters law of inertia. By a further scaling of the  $v_i$  and a reordering the matrix  $L^T H L$  can be brought into the form  $\operatorname{diag}(-1, \ldots, -1, 1, \ldots, 1)$ . (by doing this however, the matrix  $L^T G L$  becomes  $L^T G L = \operatorname{diag}(\mu_1, \ldots, \mu_m)$  with  $\mu_j > 0 \, \forall j$ ). If  $\psi$  is the Morse chart we started with, then  $L^{-1} \circ \psi$  is the new Morse chart:

$$f \circ (\psi^{-1} \circ L)(y) = f \circ \psi^{-1}(L(y)) = q_H(L(y)) = \sum_{i=1}^l -y_i^2 + \sum_{i=l+1}^m y_i^1$$

Furthermore, we want to inspect the metric  $g|_p:T_pM^2\to\mathbb{R}$  with respect to the chart  $L^{-1}\circ\psi$ -induced basis  $\left(\frac{\partial}{\partial x^1}|_p,\ldots,\frac{\partial}{\partial x^m}|_p\right)$ . By the lemma 0.0.8

$$g(q_{L^{-1} \circ \psi}\big|_p^{-1}, q_{L^{-1} \circ \psi}\big|_p^{-1})(v, w) = g(q_{\psi}\big|_p^{-1}, q_{\psi}\big|_p^{-1})(Lv, Lw) = (Lv)^T GLW = v^T L^T GLw$$

Proof. The statements 1-4 are easy to proof by the definitions. The regularity can be derived from a general fact for pairs (X,Y) in metric spaces: If Y is closed in X and there is a neighbourhood of Y that is open in X such that Y is a strong deformation retract of U. So the only thing left to show is, that  $N_p$  is a tubular neighbourhood. in [MorseTheorySalmbon] in the proof of lemma 3.2 Salamon claims this to be true without a proof (page 119 in the attached source). Similar, in [banyaga2004lectures] Banyaga claims this (also without any argument). I find this difficult to proof, since we cannot use the flow for the map from the normal bundle, as points leave  $N_p$  along the flow: The Set  $N_p$  is sketched in the figure below.



Idea: Show it locally in a morse chart arround p. Hopefully we can archive, that in such a chart the property  $\varphi_T(x) \geq a - \varepsilon$  translates to  $x = \psi(x_s, x_u)$  where  $||x_u|| \leq T_x$ . Then assume T to be big enough such that for any  $x \in N_p$  there is a chart U arround a point  $x_p \in W(\to p)$  and a  $t_0$  such that  $\varphi_{t_0}(U)$  lives in said morse chart. Finally check if the property required arround said  $x_p$  can be furmulated such that U has a tubular structure. So lets start this procedure! Let

$$\psi: p \in V \to U \subseteq \mathbb{R}^m$$

be a morse chart. Here the function f is of the form

$$f \circ \psi^{-1}(x_s, x_u) = a + x^{s^2} - x^{u^2}$$
.

where  $x^{s^2}$  and  $x^{u^2}$  denotes the sum of all the squares from the morse lemma. Without restrictions we call  $x^s = (x^1, \dots x^l)$  and  $x^u : (x^{l+1}, \dots x^m)$ . Now we inspect the set

$$\psi^{-1}(N_p \cap V) = \left\{ (x^s, x^u) \in U \mid f \circ \varphi_T(\psi^{-1}(x^s, x^u)) \ge a - \varepsilon \right\}. \tag{15}$$

First we inspect the gradient in those local coordinats, i.e.  $x = \psi^{-1}(u)$ :

$$\operatorname{grad}(f)(x) = g^{ik} \frac{\partial f}{x^k} \frac{\partial}{x^i}$$

For now assume that  $g_{ik} = \text{diag}(1, ... 1)$ , i.e. that we work with the euklidean metric. Then the gradient is:

$$\sum_{i,k} \frac{\partial f \circ \psi^{-1}}{\partial x^k} \frac{\partial}{\partial x^i} = 2 \frac{\partial}{x^s} - 2 \frac{\partial}{x^u}.$$

Hence, the flow corresponding to  $\psi_*(-\operatorname{grad}(f))$  is of the form

$$t \mapsto \varphi_t(x) = (e^{-2t}x^s, e^{2t}x^u)$$
.

Assume that  $\varepsilon$  is small enough, such that all  $x \in \psi(N_p \cap V) \setminus W(\to p)$  flow through  $f^{-1}(a-\varepsilon)$  inside of U, i.e. we can formulate the property:

$$f \circ \varphi_T(\psi^{-1}(x^s, x^u)) \ge a - \varepsilon \quad \Leftrightarrow \quad f\left(\psi^{-1}(e^{-2T}x^s, e^{2T}x^u)\right) = a + \left(e^{-2T}x^s\right)^2 - \left(e^{2T}x^u\right)^2 \ge a - \varepsilon \tag{16}$$

This however reads:

$$a + (e^{-2T}x^s)^2 - (e^{2T}x^u)^2 \ge a - \varepsilon \iff (e^{2T}x^u)^2 \le \varepsilon + (e^{-2T}x^s)^2$$

And hence we have that:

$$\psi(N_p \cap V) = \{(x^s, x^u) \in U \mid ||x^u|| \le R(x^s)\}$$

where  $R(x^s)$  is a smooth function. Now let g be a general metric, and  $\psi$  a Morse chart such that g(p) is a diagonal quadratic form wit respect to that morse chart. We now want to interlinear approximate  $\psi \circ \varphi_t \circ \psi^{-1} : U \to U$  which leads to the need of its jacobean: For this we consider the function  $(t,x) \mapsto \psi \varphi_t(\psi^{-1}(x)) : \mathbb{R} \times U \to U$  For fixed x we can calculate

$$q_{\psi} \frac{\mathrm{d}}{\mathrm{d}t} \varphi_t(\psi^{-1}(x)) = -q_{\psi} \mathrm{grad}(f) (\varphi_t(\psi^{-1}(x)))$$

and by changing the order of integration we have:

$$\frac{\partial}{\partial t} \frac{\partial}{\partial x} \psi \varphi_t(\psi^{-1}(x))$$