# High-Order Generalized Hidden Markov Model for DNA Regulatory Sequences Classification

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# **Background**

#### The Genome

The genome of every organism contains the inherited information that defines its complex structure and function. The genome is built out of Deoxyribonucleic acid (DNA) molecule, that is a built out of two chains of nucleotides units that form a double helix shape. Each nucleotide is built our of 4 different types bases: cytosine, guanine, adenine or thymine or in short A,C,G and T. The nucleotides are organized in pairs called base pairs where each of the paired nucleotides are complimentary to each other and provide redundancy.

Proteins are macromolecoles, which carry various roles and functions within organisms. They are built out of 20 different amino acids, which order and structure is encoded inside genetic segments in the genome called genes. Through the transcription and translation processes, the genes are expressed and result in the formation of proteins. In the transcription process the gene is read and transcribed into a single strand sequence of RNA. Later, the RNA molecules are translated into a sequence of amino acids that constitute a protein.

#### Genes

Gene sequences are built out fragmented introns and exons, where only the exons becomes the RNA molecules that translates into proteins while the introns are spliced away beforehand. Although the exons alone hold the recipe for the construction of the organism's proteins, the complexity of the organism is not a product of their number or their length. For example, the humans and Caenorhabditis elegans roundworms both have about 19,000 genes (Ezkurdia et al., 2014; Ainscough et al., 1998), with roughly the same total exon length and number, although the human body is vastly more diverse and complex. The source for the organisms complexity differences is attributed to the gene regulation mechanism. The human genome is 3.23 Gb long, and it is estimated that gene regulation regions involve 10-20% of it (Pennacchio et al., 2015), compared to exon regions that involve only 1% (Ng et al., 2009).

#### **Enhancers**

Enhancers are non-coding regulatory DNA sequences that play a key role in the regulation transcription of genes. In humans there are hundreds of thousands of enhancers, scattered over the non-coding regions of the genome, and their length are usually between 100-1000 bp. When activated, the DNA folding draws the enhancer spatially closer to another type of regulatory element called promoter, resulting in the translation of a gene adjacent to the promoter (see figure 1). The enhancer's target gene is the expressed gene from this activation process. It can be located up to a megabase upstream or downstream from their activating enhancer (Williamson et al., 2011), and are orientation independent to it. Moreover, the gene-enhancer connection is not exclusive, and the common case is that each enhancer has several target genes and vice versa (Fishilevich et al., 2017).

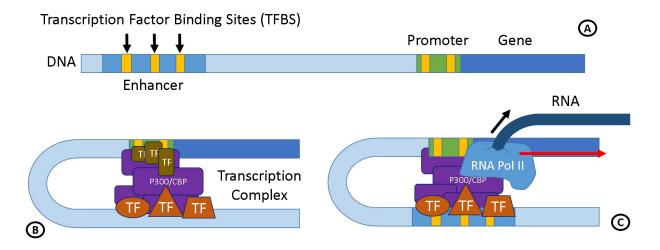


Figure: A) An enhancer and its distal target gene. B) The DNA folds and the attached with transcription factors draw other co-factor proteins that together form the transcription complex. C) The RNA Polymerase II is recruited and while moving along the gene it generates a new RNA molecule that is transcribed off the gene sequence.

In VISTA Project (Visel et al., 2007), mouse fertilized eggs where injected enhancers sequences, adjacent to LacZ reporter gene, encoding enzyme with blue color. The injected DNA sequences bared no epigenetic information and integrated in an arbitrary position in the mouse genome. The transgenic embryos where photographed after 11.5 days and, for some of the DNA sequences, a similar pattern was present over several instances. These results imply that for many DNA sequences, the DNA code alone possess the potential to become a tissue specific enhancer, even without epigenetic information.

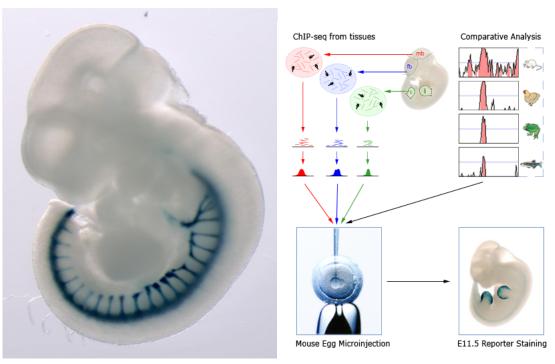


Figure: Transgenic mouse embryo in the 11.5 day. As an fertilized egg a synthetic enhancer sequence was injected, which is related to the dorsal root ganglia spinal neurons. The enhancer became activated and caused the expression of the blue color marker gene that was coupled to it. Taken from Vista Enhancer Browser, experiment hs-51 embryo 2.

#### **Transcription Factor Binding**

Transcription factors (TF) are proteins that bind to the DNA, and together with other co-factor proteins initiate the gene transcription process. TFs tend to bind to certain transcription factor binding sites (TFBS), which are motifs of nucleotides on

the DNA with average length of 12 bp in humans (Kulakovskiy et al., 2011) that are conserved between species (Doniger et al., 2005). On genome-wide association studies (GWAS) done with ChIP-seq method, different TFs have different distributions of TFBS they are observed attached to (Khan et al., JASPA, 2018).

Both enhancers and promoters contain TFBSs that are critical for the their correct regulatory operation. Multiple studies have shown that genetic alternations in TFBS can affect the expression of the regulated gene and are a major cause of different human diseases (Kreimer et al., 2017; Miguel-Escalada et al., 2015; Soldner et al., 2016; Smemo S., 2012; Benko et al., 2009; Emison et al., 2005; Lettice et al., 2003). From the sequence aspect, enhancers and promoters have a similar structure of a background nucleotide sequence with distribution different from other part of the genome, with TFBS motifs tiled inside this background sequence.

The enrichment of TFBS is a good predictor for the location of promoter and enhancer regulatory regions and the type of cells they will be active in. Folding of DNA allows the enhancer-promoter interactions, in which the TFs take major part. Once bounded to the DNA, the TFs recruit other cofactor proteins to them, and together they form a transcription preinitiation complex (PIC), a very large assembly of proteins. Out of the tens of proteins constructing the PIC, the sub-unit RNA Polymerase (RNA pol II) has the role of transcribing the adjacent gene. it opens the double stranded DNA, so that one strand of nucleotides is exposed and becomes a template for RNA synthesis.

#### **PWMs**

Generating a compact model for estimating the binding potential of a DNA sequence to a TF, i.e.  $P(x_{1:n}|binding)$ , is not trivial as might seem on first look. The peaks of the ChIP-seq data are used as the ground truth of TF binding locations, from which the model is built. Position weight matrix (PWM) is a commonly used simplistic method to address this task. The underlying assumption of the PWM model is that every position in the DNA sequence has an independent probability to attach to the TF, and therefore the total binding probability is a multiplication of all the per-position probabilities in the motif:

$$P(x_{1:n}|binding) = \prod_{i \in [n]} P(x_i|binding)$$

Where n is the size of relevant sequence. The size of the sequence that is affected by the binding event is derived from the physical characteristics of the TF.

 $P(x_i|binding)$  is estimated by counting the nucleotides frequency in every position of the observed binding sites, which are the ChIP-seq peaks. For a motif of length J, this probability estimation is stored in a PWM matrix W as followed: $W_{i,j} = \frac{1}{N}\sum_{k\in N} 1(X_{i,k} = j)$  where  $i \in [J]$  the position in the motif and  $j \in [4]$  the nucleotide index of A,C,G and T.

From a generative model point of view, the sequence is generated by a TFBS motifs emission system. For this needs, the log of the matrix often comes handy for calculation of  $log(L(W;x_{1:n}))$ , the log of the probability that a motif was generated by a PWM W. This calculation is done be a convolution of log(W) on a one-hot encoding of the sequence.

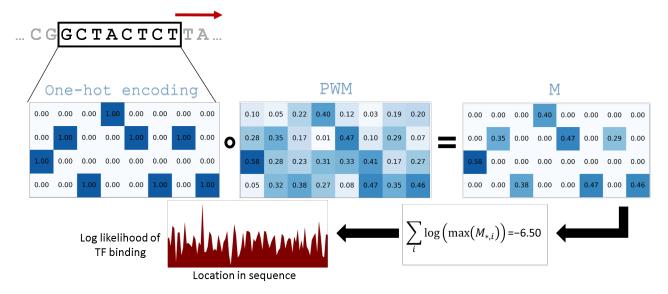


Figure 2: a sub-sequence out of the DNA is represented in a one-hot encoding, then entry-wise multiplied with the PWM. Then, the sum of the logs of the maximal values of each column in the result matrix is calculated, which is the log likelihood of the TF binding to the sub-sequence. This log likelihood is calculated for each location in the sequence, where location with high values indicate high likelihood of TF binding.

#### **Inter TFBS Sequences and Conservation**

Conserved non-coding elements (CNE) reside in clusters, usually with low gene density but with vicinity to genes. Typically, CNE are structured in arrays known as genomic regulatory block (GRB), with a mean length of 1.4 Mb (Akalin et al., 2009). The correlation between conservation of non-coding region and enhancer functionality is not strong. Some verified enhancers are weakly or not conserved between species (Friedli et al., 2010; Rosin et al., 2013; Taher et al., 2011; Lindblad-Toh et al., 2011) and some highly conserved areas in the mouse genome are not associated to regulatory activity and their deletion and yielded viable mice (Ahituv et al., 2007). Nevertheless, an assay of elements with 100% sequence identity of over 200 bp between human and mouse found that 50% showed enhancers activity in mice (Visel et al., 2007). The reason for such ultraconservation of 200 bp sequences when the TFBS is only 4-8 bp long is unclear. It is possible that these conserved sequences are actually long assembly of overlapping TFBS or that the enhancer has another function as a eRNA, that the exact nature of its mechanisms is no understood (Kim et al., 2010; Andersson et al., 2014).

## **Epigenetics**

Almost all cells in every organism contain its genome, but only part of genome is active in any specific cell. Cells of different types and in different operation modes differ by gene expression patterns. The reason for that lies in regulation components that are outside of the genomic sequence. The location and presence of TFBS, background nucleotides distribution and other sequence related properties are not enough to explain regulatory role of regions in the genome.

Several epigenetic features (which do not involve the nucleotides sequence directly) correlate with enhancer regions in the genome:

- Accessibility
- TF & cofactors binding
- Histone modifications
- DNA methylation

These properties and mechanisms have measurable features that lie on top of the genome. Their combination is the main source of identification for enhancer regions in the genome. Each cell has its own epigenetic features, in a binaric form, e.g. a specific part of the genome can be either accessible, or not. When several similar cells from the same tissue sample are measured, a frequency or count of the feature is measured per DNA loci, and generates epigenetic data. The epigenetic data is commonly used as the ground truth indication for enhancer sequences, as done for the human genome in the ENCODE project.

#### Accessibility

In eukaryotes, the DNA is packed around a structure of 8 histone proteins, together forming a nucleosome core. The location of the nucleosome binding is not random over the DNA sequence, but has a tendency for specific DNA binding sites (Cutter et al., 2015). DNA that is wrapped around a nucleosome has a lesser probability to interact with proteins, as it is physically inaccessible. Both the enhancer, the promoter and the gene need to be accessible for a successful transcription.

Since the scenario of TF binding on an enhancer requires an accessible DNA region, I hypersensative sites are used for detecting a potential DNA cleavages that have the potential of being regulatory elements, in usually a better resolution than histone marks.

#### **Histone Marks**

Chromatin modifications signatures, also called histone marks, are predictive of enhancer position and activity status (Visel et al., 2007; Heintzman et al., 2009; Fernandez et al., 2012). The histone marks are considered to contain a certain histone code which encode complex information, additionally to the DNA, regarding the transcription regulation and other aspects. Comparing to other epigenetic information, and especially DNA methylation (Przybilla et al., 2012), chromatin modifications have a short time-scale of seconds or hours (Hayashi-Takanaka et al., 2011), hence they are considered part of the dynamic changes of the cell's modes.

H3K4me1 and H3K27ac are among the predominant histone marks of active enhancers, where H3K4me1 are enriched on transcribed genes and enhancers prior to activation (Calo et al., 2013), and is thought to precede the H3K27ac modification (Creyghton et al., 2010; Rada-Iglesias et al., 2011; Zentner et al., 2011) which is known to occur during the activation. Other histone marks that are present on active enhancers and are used for their detection are H3K9ac (Ernst et al., 2011; Karmodiya et al., 2012; Karmodiya et al., 2012; Zentner et al., 2011) and H3K18ac (Jin et al., 2011). Even though H3K27ac have been identified as an important mark for distinguishing active enhancers from poised enhancers (Creyghton et al., 2010), it is not enough as its own since when present alongside H3K4me3 it is an indication for active promoters (Heintzman et al., 2007). In contrast, H3K27ac absence and H3K4me1and H3K27me3 enrichment are typical for poised enhancers (Creyghton et al., 2010).

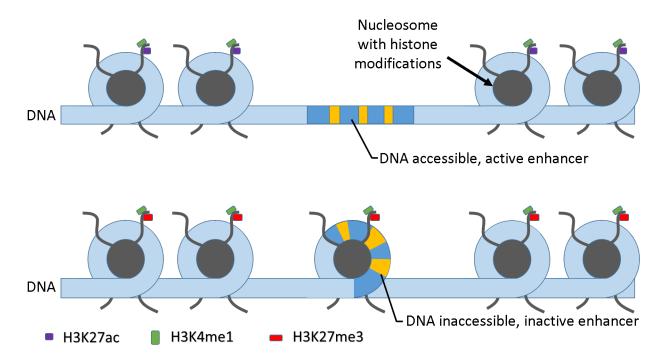


Figure 3: The accessibility of the enhancer's sequence and its surrounding histone marks are connected to its regulatory activity state. On the upper part an active enhancer sequence that is accessible for protein interaction needed for transcription, where as on the lower part an inactive enhancer is inaccessible since it is wrapped around a nucleosome.

#### **DNA Methylation**

DNA methylation at cytosine and CpG sites has been involved in genome silencing in multiple processes (Jones et al., 2012), and has been documented as largely correlated with gene expression inhibition when present in promoters. In enhancer elements, anti-correlation was found between DNA methylation density and enrichment of active enhancer histone marks and TF binding (Stadler et al., 2011; Thurman et al., 2012), although the cause and consequence relationship underlying these correlations is not yet clear.

#### **Epigenetics Limitation**

The currently most accurate method for predicting the location of tissue specific enhancers in a genome wide scale, is analyzing the histone marks and TF and cofactors presence using ChIP-seq from a cell line or from a tissue, combined with DNase I hypersensative (DHS).

Several approaches have faced the problem of locating enhancers by modeling gene expression based on epigenetic marks. However, these models rely on experimental data, and are inherently limited to the specific tissues we can extract and isolate for epigenetic examination. Furthermore, such models do no supply a classification of enhancers for new variation found in the population. Another disadvantage is the need for live cells for the verification of the regulatory activity of a sequence. The ultimate goal of an efficient computational method for predicting and explaining the reason for the functional nature of sequences in-silico has produced positive, yet far from sufficient results in the last years, as reviewed in (Kleftogiannis et al., 2016).

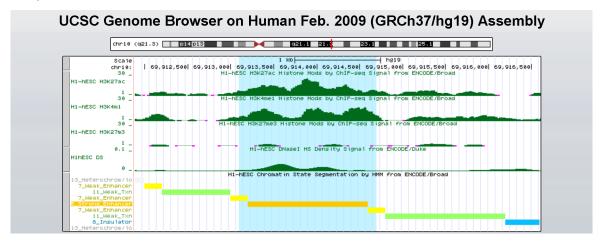


Figure 4: Epigenetic feature tracks measured by ENCODE, taken from the tenth chromosome of a H1-hESC cell line. High-lighted in light blue, the peaks of the H3K27ac (1st green plot) and H3K4me1 (2nd green plot) histone marks and the DNaseI hyper sensitivity feature (4th green plot) together with the lack of H3K27me3 (3rd green plot) signal are indication of an active enhancer, as indicated by the ChromHMM classification (bottom). Note the decrease between the two peaks of H3K27ac and H3K4me1 is located on top of the increase of the DNaseI hyper sensitivity, which implies a cleavage in between two nucleosomes with modifications.

#### **Previous Work**

There are several achievements in the task of predicting epigenetic and regulatory properties of DNA elements given only their sequence using machine learning algorithms. DeepSEA (Zhou and Troyanskaya, 2015) deep convolutional neural network (DCNN) is fed with 1000 bp DNA sequence and predicts an output vector of 919 binary features which represents the chromatin modifications of 200 bp bin in the center of the input sequence. The training labels used are the chromatin modification are extracted from ENCODE and Roadmap Epigenomics data releases.

Basset (Khan et al., JASPA, 2018) also used DCNN with known PWM as weights initialization on ENCODE and Roadmap Epigenomics data to predict a binary vector that represents accessibility in 164 cell types based on 600 bp DNA sequence. In DeepBind (Alipanahi et al., 2015) a DCNN was used to predict binding of 538 TFs and 194 RNA binding proteins from DNA sequences of varying lengths. In gkm-SVM (Beer et al., 2014), gapped kmers presence indicator vector were used as features for an SVM classifier to predict the role of DNA sequences with varying lengths.

ChromHMM (Ernst and Kellis, 2012) is a widely used software that tackles the problem of analyzing the epigenetic data for concluding roles in the genomic sequence. The algorithm uses chromatin mark reads, threshold to binary values, as input to HMM which then allows classifying the genome state in each position in the genome.

A disadvantage of these method is their need for a training data of known regulatory elements or with epigenetic data, which is commonly obtained from GWAS surveys done on 127 obtained human cell types in the Roadmap and ENCODE projects (Kundaje et al., 2015; Ernst et al., 2011). The number of different cell types in the human body is estimated to be higher than 2200 (Diehl et al., 2016), and so we cannot know in certainty the number and location of tissue specific enhancers active in most of these cell types.

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HOP-HMM extends the algorithm of Kaplan et al., 2011 (Kaplan et al., 2012), which also contains hidden states that emit TFBS sampled from PWMs to predict enhancers location in the genome. Both algorithms are part of the generalized hidden Markov model (gHMM) family, which are HMM variants that contain hidden states that may emit multiple observed variables. Although HMM variants using higher-order HMM, in which the transition and emission are dependent on previous hidden states where used previously (Ferguson, 1980; Preez, 1998), an HMM variant in which the emission is dependent on previous emissions is a less researched field.

#### **Data Representation**

The DNA sequence, when read from cells, is usually stored in files, such as .fa, as a sequence of letters A,C,G and T. For an algorithm to process it, the characters are mapped into integers 1,2,3 and 4 respectively. For many algorithms, such as in DeepSEA, Basset, and our HOP-Baum-Welch, it is more suitable to represent the DNA sequence in a one-hot encoding as described in figure 3.

A common feature extraction technique is representing a DNA sequence as a vector of the in-sequence frequencies of all the possible kmer as used in gkm-SVM. In this technique, similarly to the bag of words technique in text analysis and natural language processing, the order of the kmer locations is sacrificed for a more meaning-oriented, structured and fixed-length data encoding.

## **Research Question**

The main mission of this research is to locate genomic regions with potential enhancer activity, both in cell types from which we have epigenetic data and from cell types we don't.

It has been shown in vivo (Visel et al., 2007) that the insertion of an enhancer sequence and an adjacent target gene will often cause an activation of the target gene in mice. The transgenic mice shows the activation of the inserted enhancer although it was inserted to an arbitrary location in the genome and without epigenetic information. This strengthen the possibility that classifying sequences as enhancers could be achieved even without the epigenetic information, which is in missing for many types of cells.

TODO: remove duplication from background. add: the conclusion\ hypothesis raised by the mouse experiment is that the info is in the DNA, not the epigenetics. if the hypothesis is true, it raises the research question, can we recognize enhancer from the sequence? explain why HMM - the structure\ composition of the enhancer.

### **Markov Models**

Markov model (Markov, 1906) is a stochastic model named after Andrey Markov, a Russian mathematician. In a Markov model, at any time the model is at one of m states  $\{S_1,...,S_m\}$ , where the first state is sampled from a distribution  $\pi_i = P(y_1 = S_i)$  and the probability of transitions between the states is denoted by  $T_{i,j} = P(y_t = S_i | y_{t-1} = S_j)$ . The model's travel over the states is called a Markov process, and the sequence of states visited in the process is called a Markov chain.

The likelihood of a Markov chain X generated by a Markov  $Model\theta = \{\pi, T\}$  is a joint probability of the first state and all following transition, which due to the independence between transition events can be written as:

$$L(\theta;X) = P_{\theta}(x_0, x_1, ..., x_L) = \pi_{x_0} \cdot T_{x_0, x_1} \cdot T_{x_1, x_2} \cdot ... \cdot T_{x_{L-1}, x_L}$$

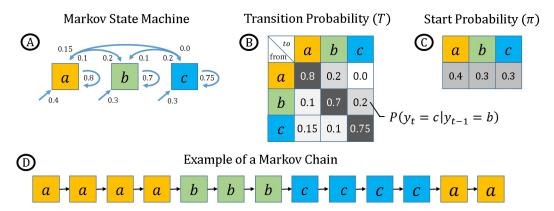


Figure 6: A) Markov model with 3 states (yellow green and blue). B,C) The model starts with a state sampled from  $\pi$ , and travels between the states with a transition distribution T. D) The model can generate Markov chains of states, where the transition between the states is conditioned on the previous state alone, causing the Markov process to be memoryless.

#### **Generative & Discriminative Models**

There are a two main distinguished approaches in the machine learning models, the generative models and discriminative models. Both assumes an observed variables X and target variables Y, also commonly referred to as labels.

- The generative models assume a joint probability P(X,Y). Using the data one can estimate the distribution P(X,Y), then from it estimate P(Y|X). It is assumed that such a model can generate the random instances of the data either as pairs of (x,y) or generate instances of x given y.
- Discriminative models assume conditional probability P(Y|X), which is estimated directly from the data.

In classification problems, the task at hand is to arrive from the observed X to its label Y, e.g. given a DNA sequence X, deciding its role label Y. Both models eventually use the P(Y|X) estimation to base their classification. Namely, classifying a data samplex by  $y_{est} = argmax_y P(Y = y|X = x)$ .

Discriminative models are more widely used than generative models. They are often easier to use and build since they require less assumptions on the origin or generation of the data. For example, a discriminative model such as a DNN classifying the role of DNA sequence assumes very little on the way the DNA sequence is related to it's role and generated based on it, but instead it finds features in the sequence that indicate its role. Such a model often gives very little for later understanding of the nature of the data generation process, and can generate no new data later for other uses.

#### **Hidden Markov model**

Multiple signal processing algorithms have been used in computational biology, and HMM is especially popular among them. Hidden Markov model (HMM) is a statistical model proposed by Leonard Baum (Baum et al., 1966) and is based on the Markov model for modeling regions with alternating frequencies of patterns and symbols. It was used extensively in various engineering fields since the 1980s, especially in speech recognition (Rabiner & Juang, 1993), handwriting recognition (Hu et al., 1996) and digital communication (Turin and Sondhi, 1993) and was adopted in the computational biology field.

Hidden Markov model (HMM) is a model that travels over hidden states in a Markov process, and while doing so it emits variables called observed variables. As the Markov model, HMM is an generative model and it assumes the existence of a joint probability  $P(x_{1:L}, y_{1:L})$  that is derived from the compact parameters  $\theta$ . As a generative model, HMM relies on the assumption that the observed DNA sequence  $X = x_1, ..., x_L$  can be generated by a parameterized model  $\theta$ , and has an hidden state sequence  $Y = y_1, ..., y_L$  that are generated alongside it. In this generation process, a single observed variable is emitted per step of the model, and so the observed sequence is generated with the same length as the hidden Markov chain. The observed variables  $V_1, ..., V_n$  are sampled from an emission distribution  $E_{i,j} = P(x_i = V_j | y_i = S_i)$ , that is conditioned on the hidden state of the model. Similarly to the Markov model, the distribution to the first hidden state is marked as  $\pi$  and the transition distribution is marked as T.

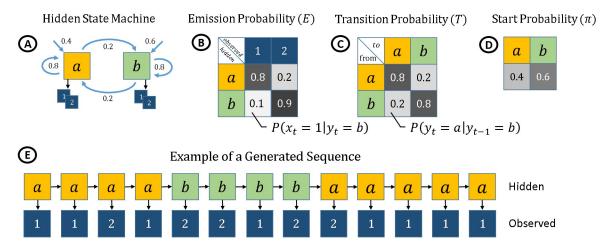


Figure 7: A) a HMM with 2 hidden states. B) The observed variables (dark blue) are emitted by the hidden state at their location, sampled from the discrete conditional distribution E. C,D) The hidden states (yellow and green) behave as Markov model states with starting and transition probabilities, $\pi$  and T. E) The output of the model is a observable sequence with an underlying hidden sequence. The hidden sequence is a Markov chain, where on each step the hidden state emits a single observed variable.

In the case where the observable sequence is made out of DNA, we can assume the DNA sequence is composed out of 4 types of regions: genes, promoter enhancers and background regions. Each of these types will have different nucleotide frequency, and we assume the DNA sequence was generated by a HMM with underlying sequence of 4 hidden states, one for each region type. The emitted observed DNA sequence x is determined by the underlying hidden sequence y that describes the "mode" of the sequence in each position.

#### **HMM Likelihood and Posterior Probability**

Having a HMM with  $\theta$  on hand, two questions arise given an observed sequence x:

- What is the likelihood that x was generated by the HMM? $P_{\theta}(x_{1:L})$
- What is the probability of a hidden state at every location? $P_{\theta}(y_t = j|x_{1:L})$

The two probabilities in the questions above are the likelihood and the posterior probabilities of HMM.

As in many generative models, HMM's likelihood function  $\mathcal{L}(\theta|x_{1:L})$  which we want to compute can be split by the total probability law to the sum of all possible hidden sequences:

$$\mathcal{L}(\theta|x_{1:L}) = P_{\theta}(x_{1:L}) = \sum_{y_{1:L} \in [m]^L} P_{\theta}(x_{1:L}, y_{1:L})$$
(1)

The probability  $P_{\theta}(x_{1:L})$  is called the incomplete-data likelihood function and the probability  $P_{\theta}(x_{1:L}, y_{1:L})$  is called the complete-data likelihood function. In the case of HMM with parameters  $\theta$ , the complete-data can be calculated by:

$$P_{\theta}(x_{1:L}, y_{1:L}) = P_{\theta}(y_1) \cdot P_{\theta}(x_1|y_1) \cdot \prod_{i=2}^{N} P_{\theta}(y_i|y_{i-1}) \cdot P_{\theta}(x_i|y_i) = \pi_{y_1} E_{y_1, x_1} \prod_{i=2}^{L} T_{y_{i-1}, y_i} E_{y_i, x_i}$$
(2)

Although the complete-data likelihood computation is linear-by-L, computing the incomplete-data with all possible hidden sequences would be exponential-by-L and is not efficient.

An alternative method, which answers both the likelihood and the posterior questions above, is a method that utilizes the Markovian memoryless feature of HMM. It is the Forward-Backward algorithm (Rabiner, 1989), a method that dynamically calculates two matrices,  $\alpha$  and  $\beta$ , both of size  $m \times L$ . The values of  $\alpha$  and  $\beta$  hold:

#### Algorithm 1 Forward Algorithm

#### **Input:**

 $x_{1:L}$  - Observed DNA sequence

#### Algorithm:

$$\begin{split} &for \, j = [1,...,m]: \\ &\alpha_{j,1} = \pi_j \cdot E_{j,x_1} \\ &for \, t = [2,...,L]: \\ &for \, j = [1,...,m]: \\ &\alpha_{j,t} = \sum_{j' \in [m]} \alpha_{j',t-1} \cdot T_{j',j} \cdot E_{j,x_t} \end{split}$$

$$\alpha_{j,t} = P_{\theta} \left( y_t = j, x_{1:t} \right)$$

$$\beta_{j,t} = P_{\theta} \left( x_{t+1:L} | y_t = j \right)$$

#### Forward Algorithm

The forward probabilities matrix  $\alpha$  holds the probability that a sequence  $x_{1:t}$  was emitted and that the hidden sequence ended with j:

$$\alpha_{j,t} = P_{\theta} \left( y_t = j, x_{1:t} \right)$$

It is calculated the dynamic algorithm:

The building of the table is based on the HMM basic assumptions that each hidden state  $y_t$  is dependent only on the previous one  $y_{t-1}$  and that each observed variable  $x_t$  is dependent only on its hidden state that emitted it  $y_t$ .

$$\alpha_{j,t} = P_{\theta} (y_t = j, x_{1:t}) = P_{\theta} (x_t | y_t = j, x_{1:t-1}) \cdot P_{\theta} (y_t = j, x_{1:t-1})$$

$$= P_{\theta} (x_t | y_t = j) \cdot \sum_{j' \in [m]} P_{\theta} (y_t = j, y_{t-1} = j', x_{1:t-1}) =$$

$$= P_{\theta} (x_t | y_t = j) \cdot \sum_{j' \in [m]} P_{\theta} (y_t = j | y_{t-1} = j') \cdot P_{\theta} (y_{t-1} = j', x_{1:t-1}) =$$

$$= E_{j,x_t} \cdot \sum_{j' \in [m]} T_{j',j} \cdot \alpha_{j',t-1}$$

#### **Backwards Algorithm**

The backwards probabilities matrix  $\beta$  holds the probability that a sequence  $x_{t+1:L}$  was emitted given the hidden state at position t had value j:

$$\beta_{j,t} = P_{\theta} \left( x_{t+1:L} | y_t = j \right)$$

It is calculated by the dynamic algorithm:

This matrix building process is similarly explained by:

$$\beta_{j,t} = P_{\theta}(x_{t+1:L}|y_t = j) = \sum_{j' \in [m]} P_{\theta}(y_{t+1} = j', x_{t+1:L}|y_t = j) = \prod_{j' \in [m]} P_{\theta}(x_{t+1:L}|y_t = j) = \prod_{j' \in [m]} P_{\theta}(x_{t+1:L}|y_t$$

#### Algorithm 2 Backward Algorithm

#### **Input:**

X - Observed DNA sequence

#### Algorithm:

$$\begin{split} \beta_{1:m,L} &= 1 \\ for t &= [L-1,...,1] : \\ for j &= [1,...,m] : \\ \beta_{j,t} &= \sum_{j' \in [m]} \beta_{j',t+1} \cdot T_{j,j'} \cdot E_{j',x_t} \end{split}$$

$$\begin{split} &= \sum_{j' \in [m]} P_{\theta} \left( x_{t+2:L} | y_t = j \right) \cdot P_{\theta} \left( x_{t+1} | y_t = j, y_{t+1} = j' \right) \cdot P_{\theta} \left( y_{t+1} = j' | y_t = j \right) = \\ &= \sum_{j' \in [m]} P_{\theta} \left( x_{t+2:L} | y_{t+1} = j' \right) \cdot P_{\theta} \left( x_{t+1} | y_{t+1} = j' \right) \cdot P_{\theta} \left( y_{t+1} = j' | y_t = j \right) = \\ &= \sum_{j' \in [m]} \beta_{j',t+1} \cdot E_{j',x_{t+1}} \cdot T_{j,j'} \end{split}$$

Once we obtain  $\alpha$  and  $\beta$  probabilities, the incomplete-data likelihood of HMM can be linearly calculated:

$$P_{\theta}(x_{1:L}) = \sum_{j \in [m]} P_{\theta}(y_t = j, x_{1:t}) = \sum_{j \in [m]} \alpha_{j,L}$$

And now the posterior probability can be computed:

$$P_{\theta}(y_{t} = j | x_{1:L}) = \frac{P_{\theta}(y_{t} = j, x_{1:L})}{P(x_{1:L})} = \frac{P_{\theta}(y_{t} = j, x_{1:t}) \cdot P_{\theta}(x_{t+1:L} | y_{t} = j)}{P(x_{1:L})} = \frac{\alpha_{j,t} \cdot \beta_{j,t}}{P_{\theta}(x_{1:L})}$$

HMM Limitations Although HMM is simple and efficient, applying it on DNA sequences has a major disadvantage which is the inherit Markovian lack-of-memory property. This property means that on every step of the model, the next state is dependent only on the previous state, without further history consideration. For the task of emitting a motif, where each position has a different emission distribution depending on the location in the motif, a HMM model would need to contain different hidden states per position in the motif. This means that for an HMM to be able to emit even a small number of short motifs, it needs to hold a large number of states that require learning a large number of parameters, e.g. for the ability to emit 50 motifs of length 5, an HMM needs to have over 60,000 parameters. Furthermore, the enhancer modeling task at hand is even more complex, since we would like to model multiple enhancers and backgrounds states, each having different probability of emitting motifs and unique k-order emission distribution when not in those motifs. For our data structure prior assumption the required number of model's parameters would have been about 10<sup>7</sup>, large enough to introduce problems such as unfeasible memory complexity and overfitting.

A common way to avoid overfitting the data when training machine learning models is reducing the model's complexity by fixing some of its parameters. Our proposed HOP-HMM addresses both the memory issue and the overfitting issue while remaining equivalent to a regularized HMM with a large number of states with fixed parameters. Namely, most of the transition probabilities are fixed to zero and therefore never stored in memory, and some of the emission probabilities are predetermined and are fixed during the training. This allows us to learn a model with the enhancer prior assumptions of motifs and high-order emission without overfitting, and with reasonable memory complexity.

#### **Higher Order HMM**

A way that was previously used to increase the complexity of HMM in the aspect of higher conditioning order is by making the transition and emission dependent on previous hidden states (Mari et al., 1997; Preez, 1998; Lee and Lee, 2006). Although these HMM variants are capable of expressing the complex structure of a DNA sequence (different k-mers frequencies in the genomic regions), the number of parameters required for this task tends to be high. With the increase of the assumed

complexity of the structure of the DNA sequence, the number of hidden states needed raises. This increase of parameters therefore calls for parameters fixing for avoiding overfitting in the learning process.

Instead depending on the previous hidden states, we suggest here the use of high-order emission which depends on previous emitted observable variables. This HMM variant fits better to the locality nature for the task of emission k-mer structures, and only requires  $O\left(m^2+4^K\right)$  compared to  $O\left(m^K\right)$  parameters, where m is the number of hidden states, and K is the number of previous states in the dependency.

#### **Generalized HMM**

### TODO: ask Tommy for a gHMM that states that emit multiple variables to cite

Generalized hidden Markov models (gHMM) are a family of variants of HMM, some of which contain hidden states that emit zero or multiple observable variables. Applied on DNA, these models can assume and learn a TFBS frequency across DNA sequences. It is a way to generalize emission of the HMM, and the EM algorithm can be adjusted to accommodate such generalization, as we will demonstrate in our EM adaptation.

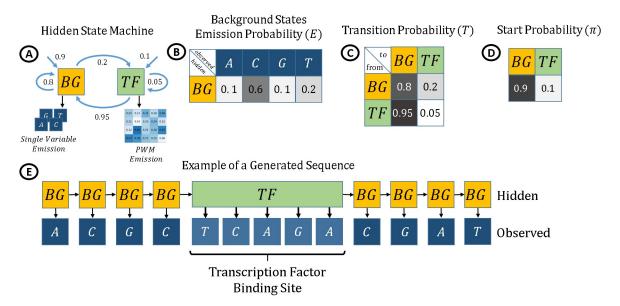


Figure: A) A gHMM with background hidden state (yellow) and TF hidden state. As in regular HMM, the emission of the background hidden state is sampled from E (B), the hidden states transitions and are sampled from T (C) and start hidden state is sampled from  $\pi$  (D). E) Unlike regular HMM, the emission of the TF hidden state is sampled from a PWM, which generates motif of 6 observable variables.

## **HOP-HMM**

Here we present HOP-HMM, a variant model of HMM, that is well fitted to utilize the structure of enhancers containing TFBSs inside them, due to the TFBS emitting TF-states that take part in the generation process of the sequence.

HOP-HMM extends the algorithm of Kaplan et al., 2011 (Kaplan et al., 2012), which also contains hidden states emitting TFBS sampled from PWMs to predict enhancers location in the genome. Both algorithms are part of the generalized hidden Markov model (gHMM) family, which are HMM variants that contain hidden states that may emit multiple observed variables. Although HMM variants using higher-order HMM, in which the transition and emission are dependent on previous hidden states where used previously (Ferguson, 1980; Preez, 1998), an HMM variant in which the emission is dependent on previous emissions is a less researched field.

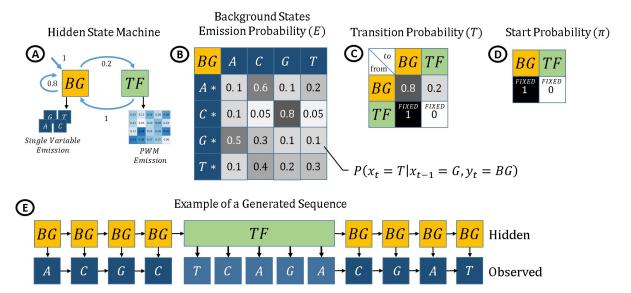


Figure 9: A small HOP-HMM that similarly to gHMM in figure 8, has one background-state that emits a single observable variable, and one TF-state which emits a TFBS sampled from its PWM. Unlike gHMM, in HOP-HMM TF-state can not be the start hidden state and the emission of the background-state is of order two (o=2), meaning it is conditioned on the previous observable variable.

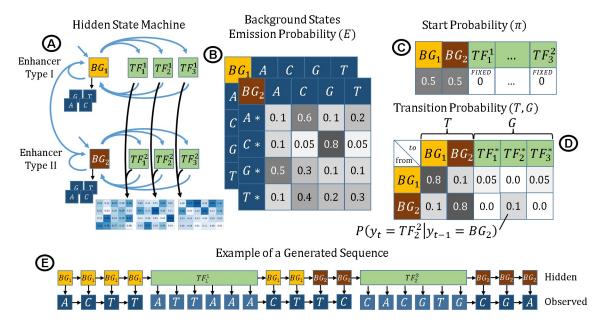


Figure 10: A) A more complex HOP-HMM with two background-state  $BG_1$  and  $BG_2$ , where each has 3 TF-states. B) each of the background-states has its own 2-order emission distribution in a 4x4 matrix. C) The start hidden state distribution  $\pi$  allows only background-states to start the hidden sequence. D) The transition probability is held by matrices T and G. E) The example generated sequence is built out of two types of sequences, each has its own TFBS frequency and background nucleotide bigram frequency, representing two alternating types of enhancers.

## **Hidden States Indexing**

We use two indices to describe a hidden-state:

- Background-states are indexed as (j,0) where  $j \in [m]$  and m is the number background-states.
- TF-states are indexed as (j,l) where  $j \in [m], l \in [k]$ . and k is the number of TF-states each of the background-states has.

For example, in figure 10 we see a HOP-HMM with m=2 and k=3 and a total of 8 hidden-states. The TF-state indexed (j,l) belongs to the (j,0) background-state (see figure 11), and the model can transfer into (j,l) only from (j,0). Note that we used simpler notation in figures 9 and 10 for readability.

## **Hidden State Machine**

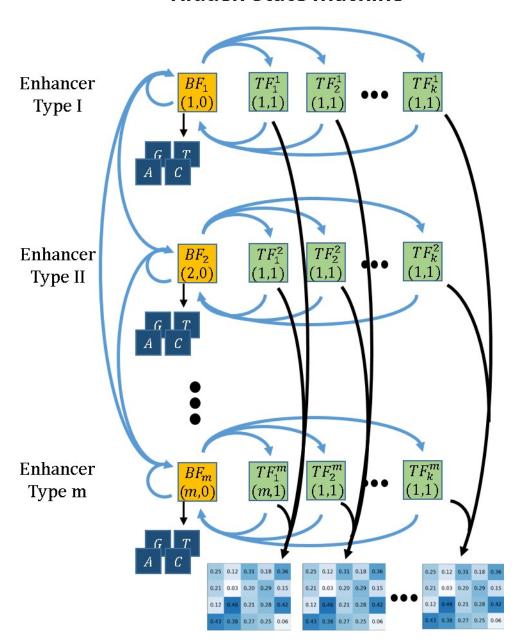


Figure 11: general hidden states graph of HOP-HMM. Each row represents a sequence type, where each of the *m* background-states (yellow) has *k*TF-states (green). Not all transitions are possible, moving between the rows is possible only by a background-state to background-state transition.

While most background-states represent an enhancer type, we also would like to have background regions in between the enhancer. For that end we predefine one or more background-states as non-enhancers, by restricting the probability of transferring from these background-states into their TF-states.

#### **Emission**

HOP-HMM is defined with k PWMs $W_1, W_2, ..., W_k$  that remain fixed during training. Each of the k PWMs is shared with m TF-states, e.g. the PWM $W_l$ , where  $l \in [k]$ , is shared between subs-states(1,l),(2,l),...,(m,l) and is used for the TF-state emission sampling. The PWMs vary in their column amounts (as the different TFBSs vary in length), where each column represents a nucleotide distribution at that position. When the model enters a TF-state, it emits a motif by sampling from a PWM column by column independently, as described in Figure 3.

The background-states, denoted as (1,0), (2,0), ..., (m,0), are responsible for the emission of inter-TFBS parts of the enhancers lacking long motifs. Similarly to regular states in HMM, background-states emit single nucleotides, where their emission is conditional on the previous of letters emitted in the DNA sequence. The emission from background-states is done by sampling a nucleotide from the distributions stored in E tensor. E dimension is o+1, and its size is  $m \times 4 \times 4 \times ... \times 4$  (with o fours) and its values are describe the emission probability  $E_{j,x_{t-o+1},x_{t-o+2},...,x_t} = P(x_t|y_t = (j,0),x_{t-o+1},...,x_{t-1})$ , meaning that when  $x_t$  is sampled by the model, the preceding o-1 observed variables are used as indices of the tensor for getting emission probability vector  $E_{j,x_{t-o+1},x_{t-o+2},...,x_{t-1},*}$ .

For the first variables emitted in the sequence, the missing dimensions of the preceding variables are summed to form the probability vector, e.g. if t = o - 1, a single variable is missing for emitting  $x_t$  and the distribution used for emission sampling is  $\sum_{i \in [4]} \frac{E_{j,i,x_1,\dots,x_{t-1}}}{\frac{1}{4}}$ .

#### **Transition**

In HOP-HMM, the first hidden state in a sequence can only be a background-state. The first background-state, as in HMM, is chosen by sampling from  $\pi$ , a probability vector  $\pi_j = P(y_1 = (j,0))$ . Once in a background-state, the model can only transit into a small subset of states, and since most of the possible transition are not allowed, a single transition matrix from all states to all states would be sparse. Instead, as described in figure 4, we hold only the possible transition probabilities in two matrices, representing the two types of allowed transitions:

- T for background-state to background-state transitions,  $am \times m$  matrix where  $T_{j_1,j_2} = P(y_{t+1} = (j_2,0)|y_t = (j_1,0))$ .
- G for background-state to TF-state transitions  $am \times k$  matrix where  $G_{j,l} = P(y_{t+1:t+|W_t|} = (j,l)|y_t = (j,0))$ .

When in a background-state, after the observable variable emission, the model samples its next hidden state from a probability vector that is a concatenation of a row in T and a row in G. If a TF-state is chosen, after the TF-state's motif emission, the model returns back to the background-state to emit another single observable variable and so on.

### **Full Transition Probability**

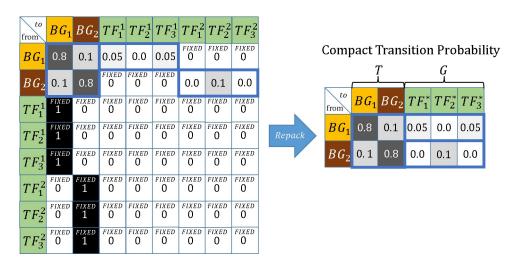


Figure 12: Instead of holding a single sparse 8x8 transition matrix, an alternative compact form holds only the non-fixed transition probabilities, split into T and G matrices. The transitions non-fixed transitions probabilities are in between background-states, and between background-states to their TF-states (marked in blue). A concatenation of a row in T and G holds the probability of the next hidden-state given the current background-state.

# **Baum-Welch Algorithm**

To be able to learn a DNA sequence with a HMM, we need to find parameters of the model that best explain the input sequence x. Formally, given the observed DNA sequence  $x_{1:L}$  where L is the length of the sequence, we would like find the parameters that maximize the incomplete-likelihood:

$$\theta^* = argmax_{\theta} \mathcal{L}\left(\theta | x_{1:L}\right)$$

Even though the incomplete-data likelihood of HMM in (1) is derivable by  $\theta$ , optimizing it involves a summation of exponential-by-L complete-data elements, which is infeasible. Instead, the strategy of the EM algorithm is to optimize the expected value of the complete-data log-likelihood  $log\left(P\left(x_{1:L},y_{1:L}|\theta'\right)\right)$  where  $\theta'$  is the model's parameters from previous EM iteration (or guessed parameters in the first iteration) and while assuming a fixed observed X, as it is our DNA sequence. For this task we can formally define our target function Q:

$$Q(\theta, \theta') = E_Y \left[ log(P_{\theta}(x_{1:L}, y_{1:L})) | x_{1:L}, \theta' \right] = \sum_{y \in [m]^N} log(P_{\theta}(x_{1:L}, y_{1:L})) P_{\theta'}(x_{1:L}, y_{1:L})$$
(3)

Note that here, E is expressing an expected value and not the HMM emission probability. Every EM iteration is built of two parts: the E-step and the M-step. In the E-step we calculate the probabilities needed for the maximization of Q and in the M-step we infer the  $\theta$  that maximizes it. Although this seemingly still requires an exponential summation, we can use a dynamic programming approach to overpass it, with the cost of  $O(N \cdot m)$  memory usage.

Using equations (2) and (3) allows us to split the Q function to three independent parts.

$$\begin{split} Q\left(\theta, \theta'\right) &= \sum_{y \in [m]^{N}} log \pi_{y_{1}} \cdot P_{\theta'}\left(x_{1:L}, y_{1:L}\right) \\ &+ \sum_{y \in [m]^{N}} \left(\sum_{t \in 2...L} log T_{y_{t-1}, y_{t}}\right) \cdot P_{\theta'}\left(x_{1:L}, y_{1:L}\right) \\ &+ \sum_{y \in [m]^{N}} \left(\sum_{t \in [L]} log E_{y_{t}, x_{t}}\right) \cdot P_{\theta'}\left(x_{1:L}, y_{1:L}\right) \end{split}$$

then by manipulating the summation and the state sequence cases could be simplified to

$$\begin{split} Q\left(\theta,\theta'\right) &= \sum_{j \in [m]} log \pi_{j} \cdot P_{\theta'}\left(x_{1:L}, y_{1} = j\right) \\ &+ \sum_{t \in 2...L} \sum_{j_{1}, j_{2} \in [m]} log T_{j_{1}, j_{2}} \cdot P_{\theta'}\left(x_{1:L}, y_{t-1} = j_{1}, y_{t} = j_{2}\right) \\ &+ \sum_{t \in [L]} \sum_{j \in [m]} log E_{j, x_{t}} \cdot P_{\theta'}\left(x_{1:L}, y_{t} = j\right) \end{split}$$

Each of the three parts could be derived and maximized independently using a Lagrange multipliers, under the following probability constrains:

$$\sum_{j\in[m]}\pi_j=1$$

$$\sum_{j_2\in[m]}T_{j_1,j_2}=1 \text{ for all } j_1\in[m]$$

$$\sum_{b \in [n]} E_{j,b} = 1 \text{ for all } j \in [n]$$

where m is the number of different hidden states and n is the number of different observed variables (4 in our case of DNA). The first part is maximized using Lagrange multiplier $\lambda$ :

$$\frac{\partial}{\partial \pi_j} \left( \sum_{j' \in [m]} log \pi_{j'} P_{\theta'} \left( x_{1:L}, y_1 = j' \right) + \lambda \left( \sum_{j' \in [m]} 1 - \pi_{j'} \right) \right) = 0$$

we derive the equations and get  $\frac{P_{\theta'}(x_{1:L},y_1=j)}{\pi_j} = \lambda$  for  $j \in [m]$ . Then we multiply each equation by the denominator and sum these m equations to receive  $\lambda = P_{\theta'}(x_{1:L})$ , which yields:

$$\pi_{j} = \frac{P_{\theta'}(x_{1:L}, y_{1} = j)}{P_{\theta'}(x_{1:L})} = P_{\theta'}(y_{1} = j | x_{1:L}) \tag{4}$$

We may follow the Lagrange multipliers method in the second and third parts, from which we'll receive:

$$T_{j_1,j_2} = \frac{\sum_{t \in 2...L} P_{\theta'}(x_{1:L}, y_{t-1} = j_1, y_t = j_2)}{\sum_{t \in 2...L} P_{\theta'}(x_{1:L}, y_{t-1} = j_1)} = \frac{\sum_{t \in 2...L} P_{\theta'}(y_{t-1} = j_1, y_t = j_2 | x_{1:L})}{\sum_{t \in 2...L} P_{\theta'}(y_{t-1} = j_1 | x_{1:L})}$$
(5)

and

$$E_{j,b} = \frac{\sum_{t \in [L]} P_{\theta'}(x_{1:L}, y_t = j) \, 1_b(x_t)}{\sum_{t \in [L]} P_{\theta'}(x_{1:L}, y_t = j)} = \frac{\sum_{t \in [L]} P_{\theta'}(y_t = j | x_{1:L}) \, 1_b(x_t)}{\sum_{t \in [L]} P_{\theta'}(y_t = j | x_{1:L})}$$
(6)

where 
$$1_b(x_t) = \begin{cases} 1 & b = x_t \\ 0 & otherwise \end{cases}$$

After stating the intentions of each EM iteration in (4), (5) and (6), we now need to calculated them in order to successfully learn the HMM parameters. Specifically, notice that to resolve all the parameters update states in (4), (5) and (6), it is enough to calculate the two terms during the E-step:

$$P_{\alpha'}\left(y_t = j|x_{1:L}\right) \tag{7}$$

$$P_{\theta'}(y_{t-1} = j_1, y_t = j_2 | x_{1:L})$$
(8)

We will calculate these terms by using the Forward-Backward algorithm.

#### **Auxiliary Probabilities**

Having the forward and backward probability matrices  $\alpha$  and  $\beta$ , we now have all that is needed to calculate(8) and (9), using once more the HMM conditional independence in our calculations. Here we used the fact that

We denote the terms values of (7) as  $\gamma$ , a matrix of size  $L \times m$ :

$$\gamma_{t,j} = P\left(y_t = j | X, \theta'\right) = \frac{P\left(y_t = j, x_{1:L} | \theta'\right)}{P\left(x_{1:L} | \theta'\right)} = \frac{P\left(x_{1:L} | y_t = j, \theta'\right) \cdot P\left(y_t = j | \theta'\right)}{P\left(x_{1:L} | \theta'\right)} = \frac{P\left(y_t = j, x_{1:t}\right) \cdot P\left(x_{t+1:L} | y_t = j\right)}{\sum_{j' \in [m]} P\left(y_t = j', x_{1:t}\right) \cdot P\left(x_{t+1:L} | y_t = j'\right)} = \frac{\alpha_{j,t} \cdot \beta_{j,t}}{\sum_{j' \in [m]} \alpha_{j',t} \cdot \beta_{j',t}}$$

And we denote the values of (8) as  $\xi$ , a matrix of size  $L - 1 \times m \times m$ :

$$\begin{aligned} \xi_{t,j_{1},j_{2}} &= P\left(y_{t-1} = j_{1}, y_{t} = j_{2} | x_{1:L}, \theta'\right) = \frac{P\left(y_{t-1} = j_{1}, y_{t} = j_{2}, x_{1:L} | \theta'\right)}{P\left(x_{1:L} | \theta'\right)} = \\ &= \frac{P\left(y_{t-1} = j_{1}, x_{1:t-1}\right) \cdot P\left(y_{t} = j_{2} | y_{t-1} = j_{1}\right) \cdot P\left(x_{t} | y_{t} = j_{2}\right) \cdot P\left(x_{t+1:L} | y_{t} = j_{2}\right)}{\sum_{j' \in [m]} P\left(y_{t} = j, x_{1:t}\right) \cdot P\left(x_{t+1:L} | y_{t} = j\right)} = \\ &= \frac{\alpha_{j_{1},t-1} \cdot T_{j_{1},j_{2}} \cdot E_{j_{2},x_{t}} \cdot \beta_{j',t}}{\sum_{j' \in [m]} \alpha_{j',t} \cdot \beta_{j',t}} \end{aligned}$$

## **Baum-Welch Algorithm for HOP-HMM**

Since the transitions and emissions assumptions of HOP-HMM are different, the complete-data likelihood requires different calculation for the EM algorithm to hold. The Baum-Welch algorithm can be adjusted to infer the parameters of the HOP-HMM variant  $\theta = \{\pi, E, G, T\}$  from a DNA sequence X. As in the regular Baum-Welch algorithm covered in the previous section, given a sequence X at each EM iteration we calculate and optimize a Q function:

$$\begin{split} Q\left(\theta,\theta'\right) &= \sum_{j \in [m]} log \pi_{j} \cdot P_{\theta'}\left(x_{1:L},y_{1} = (j,0)\right) \\ &+ \sum_{t \in 2...L} \sum_{j_{1},j_{2} \in [m]} log T_{j_{1},j_{2}} \cdot P_{\theta'}\left(x_{1:L},y_{t-1} = (j_{1},0),y_{t} = (j_{2},0)\right) \\ &+ \sum_{t \in 2...L} \sum_{j \in [m],l \in [k]} log G_{j,l} \cdot P_{\theta'}\left(x_{1:L},y_{t-1} = (j,0),y_{t} = (j,l)\right) \\ &+ \sum_{t \in [L]} \sum_{j \in [m]} log E_{j,x_{t}} \cdot P_{\theta'}\left(x_{1:L},y_{t} = (j,0)\right) \\ &+ \sum_{t \in [L]} \sum_{l \in [k]} log L_{W}(x_{t:t+|W_{l}|}) \cdot P_{\theta'}\left(x_{1:L},y_{t:t+|W_{l}|} = (j,l)\right) \end{split}$$

where  $L_W(\bar{x})$  is the likelihood of the TFBS $\bar{x}$  to be emitted by PWM $W:L_M(\bar{x})=P(\bar{x}|W)=\prod_{i\in\{1,...,|\bar{x}|\}}W_{\bar{x}_i,i}$ . The last component, with the TFBS likelihood does not contain elements from  $\theta$ , therefore it is not optimized in the m-steps.

The  $\theta$  which optimizes Q, i.e.  $\theta_{max} = argmax_{\theta}Q(\theta, \theta')$ , is built similarly as in the regular Baum-Welch algorithm, as following:

$$\pi_{j} = \frac{P_{\theta'}\left(x_{1:L}, y_{1} = (j, 0)|\theta'\right)}{P_{\theta'}\left(x_{1:L}|\theta'\right)} = P_{\theta'}\left(y_{1} = (j, 0)|x_{1:L}\right) \tag{9}$$

$$T_{j_1,j_2} = \frac{\sum_{t \in 2...L} P_{\theta'}(x_{1:L}, y_{t-1} = (j_1, 0), y_t = (j_2, 0))}{\sum_{t \in 2...L} P_{\theta'}(x_{1:L}, y_{t-1} = (j_1, 0))} = \frac{\sum_{t \in 2...L} P_{\theta'}(y_{t-1} = (j_1, 0), y_t = (j_2, 0) | x_{1:L})}{\sum_{t \in 2...L} P_{\theta'}(y_{t-1} = (j_1, 0) | x_{1:L})}$$
(10)

$$G_{j,l} = \frac{\sum_{t \in 2...L} P_{\theta'}(x_{1:L}, y_{t-1} = (j, 0), y_t = (j, l))}{\sum_{t \in 2...L} P_{\theta'}(x_{1:L}, y_{t-1} = (j, 0))} = \frac{\sum_{t \in 2...L} P_{\theta'}(y_{t-1} = (j, 0), y_t = (j, l) | x_{1:L})}{\sum_{t \in 2...L} P_{\theta'}(y_{t-1} = (j, 0) | x_{1:L})}$$
(11)

and

$$E_{j,b_{1},\dots,b_{o}} = \frac{\sum_{t \in o,\dots,L} P_{\theta'}(x_{1:L}, y_{t} = (j,0)) 1_{b_{1},\dots,b_{o}}(x_{t-o+1,\dots,t})}{\sum_{t \in o,\dots,L} P_{\theta'}(x_{1:L}, y_{t} = (j,0))} = \frac{\sum_{t \in o,\dots,L} P_{\theta'}(y_{t} = (j,0)|X) 1_{b_{1},\dots,b_{o}}(x_{t-o+1,\dots,t})}{\sum_{t \in o,\dots,L} P_{\theta'}(y_{t} = (j,0)|x_{1:L})}$$

$$(12)$$

#### Algorithm 3 HOP Forward Algorithm

#### **Input:**

X - Observed DNA sequence

#### Algorithm:

$$for j = [1, ..., m]:$$

$$\alpha_{j,1} = \pi_j \cdot E_{j,x_1}$$

$$for t = [2, ..., L]:$$

$$for j = [1, ..., m]:$$

$$\alpha_{j,t} = \sum_{j' \in [m]} \alpha_{j',t-1} \cdot T_{j',j} \cdot E_{j,x_{t-o+1},...,x_t}$$

$$+ \sum_{l \in [k]} \alpha_{j,t-|W_l|-1} \cdot G_{j,l} \cdot L_{W_l} \left(x_{t-|W_l|}, ..., x_{t-1}\right) \cdot E_{j,x_{t-o+1},...,x_t}$$
sub-state transitions

Hence to complete the EM iteration, the three missing components in (9), (10), (11), (12) are:

$$P_{\theta'}(y_t = (j,0)|x_{1:L}) \tag{13}$$

$$P_{\theta'}(y_{t-1} = (j_1, 0), y_t = (j_2, 0)|x_{1:L})$$
(14)

$$P_{\mathbf{A}'}(y_{t-1} = (j,0), y_t = (j,l)|x_{1:L})$$
(15)

For the calculation of these probabilities, we will need to calculate the forward and backward probabilities, and then few other auxiliary terms. The forward and backward probabilities are only for indicating the sequence entering-to and exiting-from background-states:

$$\alpha_{i,t} = P(y_t = (j,0), x_{1:t})$$

$$\beta_{j,t} = P(x_{t+1:L}|y_t = (j,0))$$

#### **HOP-Forward Algorithm**

We calculate  $\alpha$  of size  $m \times L$ , iterating over t = 1, 2, ..., L as following:

Calculation notes: In the beginning of the sequence, when  $1 \le t < o$ , part of the preceding observable variables are missing. Since E has o+1 dimensions,  $E_{j,x_1,\dots,x_t}$  is not defined, so we define it here as  $E_{j,x_1,\dots,x_t} = \sum_{b_1,\dots,b_{o-t} \in \{A,C,G,T\}} \frac{1}{4^{o-t}} \cdot E_{j,b_1,\dots,b_{o-t},x_1,\dots,x_t}$ 

that is the expected probability upon possible preceding variables. We used the fact that  $P(A) = \sum_{b \in B} P(b) \cdot P(A|b)$  and the assumption that the observable variables preceding the sequence came from a uniform distribution,  $P(x_i) = \frac{1}{4}$  where i < 1. Also, when summing the TF-state transition part  $l \in [k]$ , the PWMs $W_l$  with length equal or bigger than t + 1 are not part of the summation.

#### **HOP-Backward Algorithm**

For  $\beta$  of size  $m \times L$ , we iterating over t = L, L - 1, ..., 1 as following:

Note that when  $t > L - |W_l|$ , there are missing observable variables to fully calculate the TF-state transition. In these situations this contribution of these component to the summation is zero, meaning our HOP-HMM as the behavior of avoiding a transition into a TF-state when the PWM is too long to fit into the sequence X length.

#### Algorithm 4 HOP Backward Algorithm

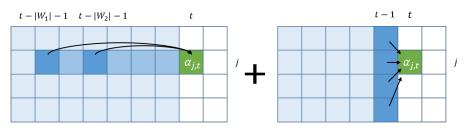
#### **Input:**

X - Observed DNA sequence

#### Algorithm:

$$\begin{split} \beta_{1:m,L} &= 1 \\ for t &= [L-1,...,1]: \\ for j &= [1,...,m]: \\ \beta_{j,t} &= \underbrace{\sum_{j' \in [m]}^{j' \in [m]} \beta_{j',t+1} \cdot E_{j',x_{t-o+2},...,x_{t+1}} \cdot T_{j,j'}}_{\text{base-state transitions}} \\ &+ \underbrace{\sum_{l \in [k]} \beta_{j,t+|W_l|+1} \cdot L_{W_l} \left(x_{t+1},...,x_{t+|W_l|}\right) \cdot E_{j,x_{t-o+|W_l|+2},...,x_{t+|W_l|+1}} \cdot G_{j,l}}_{\text{sub-state transitions}} \end{split}$$

#### Forward Algorithm



#### **Backward Algorithm**

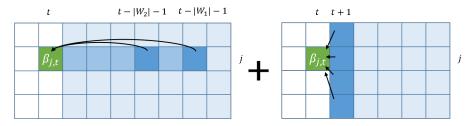


Figure 5: In our version of the forward-backward algorithm, each of the  $\alpha$  and  $\beta$  cells are filled from both the adjacent background-states transitions and the background-states preceding or proceeding the motifs emitted by the TF-states.

## Forward Algorithm Explanation

We will now explain why the described dynamic calculation result with  $\alpha_{j,t} = P(y_t = (j,0), x_{1:t})$  and  $\beta_{j,t} = P(x_{t+1:L}|y_t = (j,0))$ , starting with the forward probabilities  $\alpha$ . From the law of total probability, the probability  $\alpha_{j,t}$  is the sum of probabilities of all the possible transition that ended in the background-state (j,0):

$$\alpha_{j,t} = P(y_t = (j,0), x_{1:t}) = \sum_{j' \in [m]} P(y_{t-1} = (j',0), y_t = (j,0), x_{1:t}) + \sum_{l \in \{1,\dots,k\}} P(y_{t-|W_l|:t-1} = (j,l), y_{t-|W_l|-1} = (j,0), x_{1:t})$$

We could develop the right term of a TF-state transition using the chain rule:

$$\begin{split} P\left(y_{t-|W_l|:t-1} = (j,l), y_{t-|W_l|-1} = (j,0), x_{1:t}\right) &= P\left(y_{t-|W_l|-1} = (j,0), x_{1:t-|W_l|-1}\right) \cdot \\ & \cdot P\left(y_{t-|W_l|:t-1} = (j,l)|y_{t-|W_l|-1} = (j,0), x_{1:t-|W_l|-1}\right) \\ & \cdot P\left(x_{t-|W_l|:t-1}|y_{t-|W_l|:t-1} = (j,l), y_{t-|W_l|-1} = (j,0), x_{1:t-|W_l|-1}\right) \\ & \cdot P\left(x_t|y_t = (j,0), x_{1:t-1}, y_{t-|W_l|:t-1} = (j,l), y_{t-|W_l|-1} = (j,0)\right) \end{split}$$

Because of  $x_t$  is dependent on only  $y_t$  (and also  $x_{t-o:t-1}$  if  $y_t$  is a background-state) and  $y_t$  is dependent on only  $y_{t-1}$ , we can simplify the probabilities:

$$\begin{split} P\left(y_{t-|W_{l}|:t-1} = (j',l), y_{t-|W_{l}|-1} = (j,0), x_{1:t}\right) &= P\left(y_{t-|W_{l}|-1} = (j,0), x_{1:t-|W_{l}|-1}\right) \\ &\cdot P\left(y_{t-|W_{l}|:t-1} = (j,l)|y_{t-|W_{l}|-1} = (j,0)\right) \\ &\cdot P\left(x_{t-|W_{l}|:t-1}|y_{t-|W_{l}|:t-1} = (j,l)\right) \\ &\cdot P\left(x_{t}|y_{t} = (j,0), x_{t-\sigma;t-1}\right) \end{split}$$

We can now replace the received terms with the components of  $\theta$  and with already filled  $\alpha$  cells:

$$P\left(y_{t-|W_l|:t-1}^i = (j,l), y_{t-|W_l|-1}^i = (j,0), x_{1:t}^i\right) = \alpha_{j,t-|W_l|-1} \cdot G_{j,l} \cdot L_{W_l}\left(x_{t-|W_l|}, ..., x_{t-1}\right) \cdot E_{j,x_{t-o+1},...,x_t}$$

This process is similar to the background-state transition. Using the chain rule:

$$P(y_{t-1} = (j',0), y_t = (j,0), x_{1:t}) = P(y_{t-1} = (j',0), x_{1:t-1})$$

$$P(y_t = (j,0)|y_{t-1} = (j',0), x_{1:t-1})$$

$$P(x_t|y_t = (j,0), y_{t-1} = (j',0), x_{1:t-1})$$

Using the conditional independencies to simplify the probabilities:

$$P(y_{t-1} = (j',0), x_{1:t-1}) \cdot P(y_t = (j,0)|y_{t-1} = (j',0)) \cdot P(x_t|y_t = (j,0), x_{1:t-1}) =$$

$$= \alpha_{j',t-1} \cdot T_{j',j} \cdot E_{j,x_{t-0}+1,\dots,x_t}$$

#### **Backward Algorithm Explanation**

For the backward probabilities  $\beta$ , the explanation is similar. The main difference between the regular HMM backward probability is the condition on the o-1 preceding observable variables  $x_{t-o+2:t}$ , which are necessary for the background-state emission is conditional on them.

Using the law of total probability:

$$P(x_{t+1:L}|y_t = (j,0), x_{t-o+2:t}) = \underbrace{\sum_{j'} P\left(y_{t+1} = (j',0), x_{t+1:L}|y_t = (j,0), x_{t-o+2:t}\right)}_{\text{base-state transition}} + \underbrace{\sum_{l} P\left(y_{t+1:t+|W_l|} = (j,l), y_{t+|W_l|+1} = (j,0), x_{t+1:L}|y_t = (j,0)\right)}_{\text{sub-state transition}}$$

For the background-state transition term, we can use the chain rule and the Markovian independence of the transitions and emissions:

$$P(y_{t+1} = (j',0), x_{t+1:L}|y_t = (j,0), x_{t-o+2:t}) =$$

$$= P(x_{t+2:L}|y_{t+1} = (j',0), y_t = (j,0), x_{t-o+2:t+1}) \cdot P(x_{t+1}|y_{t+1} = (j',0), y_t = (j,0), x_{t-o+2:t}) \cdot$$

$$\cdot P(y_{t+1} = (j',0)|y_t = (j,0), x_{t-o+2:t}) =$$

$$= P(x_{t+2:L}|y_{t+1} = (j',0), x_{t-o+3:t+1}) \cdot P(x_{t+1}|y_{t+1} = (j',0), x_{t-o+2:t}) \cdot P(y_{t+1} = (j',0)|y_t = (j,0)) =$$

$$= \beta_{j',t+1} \cdot E_{j',x_{t-o+2},...,x_{t+1}} \cdot T_{j,j'}$$

For the TF-state transition term, we use once more the chain rule, followed the simplification using the conditional independencies:

$$\begin{split} P\left(y_{t+1:t+|W_{l}|} = (j,l), y_{t+|W_{l}|+1} = (j,0), x_{t+1:L}|y_{t} = (j,0)\right) = \\ P\left(x_{t+|W_{l}|+2:L}|x_{t+1:t+|W_{l}|+1}, y_{t+1:t+|W_{l}|} = (j,l), y_{t+|W_{l}|+1} = (j,0), y_{t} = (j,0)\right) \cdot \\ \cdot P\left(x_{t+|W_{l}|+1}|x_{t+1:t+|W_{l}|}, y_{t+1:t+|W_{l}|} = (j,l), y_{t+|W_{l}|+1} = (j,0), y_{t} = (j,0)\right) \cdot \\ \cdot P\left(x_{t+1:t+|W_{l}|}|y_{t+1:t+|W_{l}|} = (j,l), y_{t+|W_{l}|+1} = (j,0), y_{t} = (j,0)\right) \cdot \\ \cdot P\left(y_{t+1:t+|W_{l}|} = (j,l), y_{t+|W_{l}|+1} = (j,0)|y_{t} = (j,0)\right) = \\ = P\left(x_{t+|W_{l}|+2:L}|y_{t+|W_{l}|+1} = (j,0)\right) \cdot P\left(x_{t+|W_{l}|+1}|y_{t+|W_{l}|+1} = (j,0)\right) \cdot \\ \cdot P\left(x_{t+1:t+|W_{l}|}|y_{t+1:t+|W_{l}|} = (j,l)\right) \cdot P\left(y_{t+1:t+|W_{l}|} = (j,l), y_{t+|W_{l}|+1} = (j,0)|y_{t} = (j,0)\right) = \\ = \beta_{j,t+|W_{l}|+1} \cdot E_{j,x_{t-o+|W_{l}|+1}, \dots, x_{t+|W_{l}|+1}} \cdot L_{W_{l}}\left(x_{t+1}, \dots, x_{t+|W_{l}|}\right) \cdot G_{j,l} \end{split}$$

### **Auxiliary Probabilities**

Using the forward and the backward probability matrices, we are ready to calculate the auxiliary probabilities (13) (14) (15). The first probability that will help us for that task is  $\psi$ , a matrix of size  $m \times k \times L$ :

$$\psi_{j,l,t} = P(y_t = (j,0), y_{t+1} = (j,l), X) = P(y_t = (j,0), y_{t+1} = (j,l), y_{t+|W_l|+1} = (j,0), X) =$$

$$= P(y_t = (j,0), y_{t+1} = (j,l), y_{t+|W_l|+1} = (j,0), x_{1:t+|W_l|+1}) \cdot P(x_{t+|W_l|+2:L}|y_{t+|W_l|+1} = (j,0), x_{1:t+|W_l|+1}) =$$

$$= P(x_{1:t}, y_t = (j,0)) \cdot P(y_{t+1} = (j,l)|y_t = (j,0)) \cdot P(x_{t+1:t+|W_l|}|y_{t+1:t+|W_l|} = (j,l)) \cdot$$

$$\begin{split} \cdot P\left(x_{t+|W_{l}|+1}|y_{t+|W_{l}|+1} = (j,0)\right) \cdot P\left(x_{t+|W_{l}|+2:L}|y_{t+|W_{l}|+1} = (j,0), x_{t+|W_{l}|-o+3:t+|W_{l}|+1}\right) = \\ \\ = \alpha_{j,t} \cdot G_{j,l} \cdot L_{W_{l}}\left(x_{t+1}, ..., x_{t+|W_{l}|}\right) \cdot E_{j,x_{t+|W_{l}|-o+2}, ..., x_{t+|W_{l}|+1}} \cdot \beta_{j,t+|W_{l}|+1} \end{split}$$

The second probability, is of the observed sequence X:

$$P(X) = \sum_{j \in [m]} \left( lpha_{j,t} \cdot eta_{j,t} + \sum_{l \in [k], \ t' \in [|W_l|]} \psi_{j,l,t-s} 
ight)$$

Now we can calculate probability (13) of the background-state at a given position given the sequence X, denoted as  $\gamma$  of  $sizem \times L$ :

$$\gamma_{j,t} = P(y_t = (j,0)|X) = \frac{P(y_t = (j,0), x_{1:t}) \cdot P(x_{t+1:L}|x_{1:t}, y_t = (j,0))}{P(x_{1:L})} =$$

$$= \frac{P(y_t = (j,0), x_{1:t}) \cdot P(x_{t+1:L}|x_{t-o+1:t}, y_t = (j,0))}{P(x_{1:L})} = \frac{\alpha_{j,t} \cdot \beta_{j,t}}{P(x_{1:L})}$$

The probability (14) is the background-state to background-state transition given the sequence X, denoted as  $\xi$  of size  $m \times m \times L$ :

$$\begin{split} \xi_{j_{1},j_{2},t} &= P(y_{t-1} = (j_{1},0), y_{t} = (j_{2},0) | x_{1:L}) = \frac{P(y_{t-1} = (j_{1},0), y_{t} = (j_{2},0), x_{1:L})}{P(x_{1:L})} = \\ &= \frac{P(x_{1:t-1}, y_{t-1} = (j_{1},0), y_{t} = (j_{2},0)) \cdot P(x_{t:L} | y_{t} = (j_{2},0), x_{1:t-1})}{P(x_{1:L})} = \\ &= \frac{P(x_{1:t-1}, y_{t-1} = (j_{1},0)) \cdot P(y_{t} = (j_{2},0) | y_{t-1} = (j_{1},0)) \cdot P(x_{t} | y_{t} = (j_{2},0), x_{1:t-1}) \cdot P(x_{t+1:L} | y_{t} = (j_{2},0), x_{1:t-1})}{P(x_{1:L})} = \\ &= \frac{\alpha_{j_{1},t-1} \cdot T_{j_{1},j_{2}} \cdot E_{j_{2},x_{t-o+1},...,x_{t}} \cdot \beta_{j_{2},t}}{P(x_{1:L})} \end{split}$$

Finally, the probability (15) is the background-state to background-state transition given the sequence X, denoted as  $\xi$  of size  $m \times k \times L$ :

$$\eta_{j,l,t} = P(y_{t-1} = (j,0), y_t = (j,l)|x_{1:L}) = \frac{\psi_{j,l,t}}{P(x_{1:L})}$$

Now with (13), (14), (15) at hand, we can calculate  $\theta_{max}$  by assigning them at (9), (10), (11), (12).

#### **HOP Baum-Welch**

To conclude, the total EM algorithm for HOP-HMM:

## Algorithm 5 HOP Baum-Welch

```
Input: X - Observed DNA sequence Algorithm:

for s=[1...MAX_EM_ITERATIONS]:

//e-step

\alpha = \text{hop\_forward\_alg}(x_{1:L})

\beta = \text{hop\_backward\_alg}(x_{1:L})

for j = [1, ..., m], l = [1, ..., k], t = [1, ..., L]:

\psi_{j,l,t} = \begin{cases} \alpha_{j,t} \cdot G_{j,l} \cdot L_{W_{l_1}}(x_{t+1:t+|W_{l_1}|}) \cdot E_{j,x_{t+|W_{l_1}|-o+2}....x_{t+|W_{l_1}|+1}} \cdot \beta_{j,t+|W_{l_1}|+1} & |t+|W_{l_1}|+1 \leq L \\ 0 & |t+|W_{l_1}| = L \end{cases}

for j = [1, ..., m], t = [1, ..., L]:

\gamma_{j,t} = \frac{\alpha_{j,t} \cdot \beta_{j,t}}{p_{t,t}}

for j = [1, ..., m], l_t = [1, ..., L]:

\eta_{j,l,t} = \frac{\alpha_{j,t}}{p_{t,t}}

for j = [1, ..., m], j_2 = [1, ..., m], t = [1, ..., L]:

\xi_{j_1,j_2,t} = \frac{\alpha_{j,t-1}T_{j_1,j_2}\cdot E_{j_2,x_{t-1},...,x_t}\cdot \beta_{j_2,t}}{p_{t,t}}

//m-step

for j = [1, ..., m]:

\pi_j = \gamma_{j,1}

for h_1, ..., h_0 = [1, ..., 1], ..., [4, ..., 4]:

E_{j,h_1,h_2,...,h_0} = \frac{\sum_{l \in 0,...,l} \gamma_{j,l} \cdot h_{l_1...,h_0} \cdot (x_{t-0+1}...,x_t)}{\sum_{l \in 0,...,l} \gamma_{j,l}}

for j = [1, ..., k]:

G_{j,l} = \frac{\sum_{l \in 2,...,l} \gamma_{j,l}}{\sum_{l \in l,...,l} \gamma_{j,l}}}

for j = [1, ..., m]:

T_{j,j_2} = \frac{i \sum_{l \in l,...,l} \gamma_{j,l}}{\sum_{l \in l,...,l} \gamma_{j,l}}}
```

#### **Learning Multiple Sequences at Once**

If  $\theta$  converged, break EM for loop

The algorithm here is described for learning a single sequence of observable variables X. For learning the parameters  $\theta$  from multiple sequences at once, we can use the same method as introduced in the original paper of Baum-Welch algorithm (Rabiner, 1989), which calculates the E step probabilities for every sequence, and in the m-step sums all positions from all sequence for the parameters update.

## Classifying DNA a Sequence

One of the goals of the HMM and HOP-HMM learning process described above is to be able to classify the DNA sequences by deciding their hidden state per location. After the Baum-Welch algorithm procedure, we might want to reach that goal by choosing per position the max-likelihood hidden state. In the HOP-HMM case, this means getting the hidden sequence:

$$y_t^* = argmax_{(j,l)}P(y_t = (j,l)|x_{1:L})$$

## Algorithm 6 HOP-Viterbi Algorithm

```
Input:
```

```
\theta- HOP-HMM parameters\{E, T, G, \pi\}
    X - Observed DNA sequence
Algorithm:
   V_{j,1}^{1} = \pi_{j} \cdot E_{j,x_{1}}

V_{j,1}^{2} = 0

fort = [2,...,L]:
        for j = [1, ..., m]:
           create two vectors:
           A = \{V_{j',t-1} \cdot T_{j',j} \cdot E_{j,x_{t-o+1},...,x_l} | j' \in [m]\}
B = \{V_{j,t-|W_l|-1} \cdot G_{j,l} \cdot L_{W_l} (x_{t-|W_l|},...,x_{t-1}) \cdot E_{j,x_{t-o+1},...,x_t} | l \in [k]\}
            V_{i,t}^1 = max(A \cup B)
           V_{j,t}^2 = \begin{cases} (argmax(A), 0) & max(A) > max(B) \\ (j, argmax(B)) & otherwise \end{cases}
   y_L = \left(argmax_j V_{j,L}^1, 0\right)
   t=L
    while t > 1:
       (j,l) = V_{y_t[0],t}^2
       if l = 0:# if the hidden state at t-1 is a background-state
           y_{t-1} = (j,0)
           t = t - 1
       else:
            y_{t-|W_l|:t-1} = (j,l)
           y_{t-|W_t|-1} = y_t
           t = t - |W_1| - 1
```

Although simple to calculate with the  $\gamma$  auxiliary probability, such a hidden sequence could be problematic. Each hidden state maximizes the likelihood at its location, but the hidden sequence together with its transitions might not be the maximal likelihood one, and in fact might even include illegal transition (with probability 0).

Our task here is reaching the hidden sequence that maximizes the likelihood of the observed sequence, where all the sequence is considered:

$$y_{1:L}^* = argmax_{y_{1:L}} P(y_{1:L}|x_{1:L})$$
(16)

#### **HOP-Viterbi Algorithm**

A common way to derive the hidden sequence that maximizes (16) is the Viterbi algorithm, which is similar to the Forward algorithm. The main differences between the two algorithms are the usage of max instead of summing over the possible transitions on each step of the dynamic algorithm, and keeping information of the chosen maximal value used via the argmax function. The HOP-HMM adaptation to this algorithm includes supporting the TF-states and the high order emission of the background-states.

## **Results**

## **Synthetic Sequences**

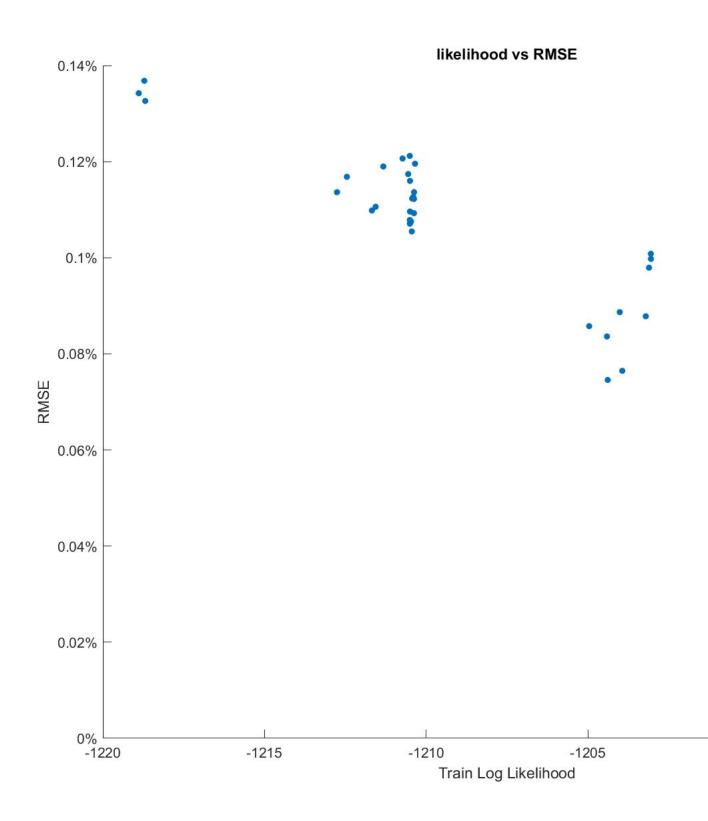
Before applying the algorithm to a real DNA data, we checked its capabilities on synthetic data.

We sampled  $\theta$  parameters, while making sure some background-states had chance to transition into TF-states to mimic enhancers, and some background-states had almost no chance of such transitions, to mimic the PWM lacking background around

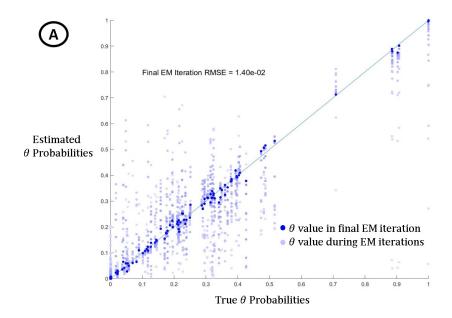
the shoulders of enhancers in the DNA. We marked the sampled $\theta$  as the true $\theta$  which we would like to estimate in the HOP Baum-Welch algorithm. We then generated several sequences using a HOP-HMMs with the true $\theta$ , keeping both the observed and the hidden sequences. Finally, we split the sequences into train and test and estimated a $\theta$  using the train sequences, and measuring its accuracy over both the train and the test sequences.

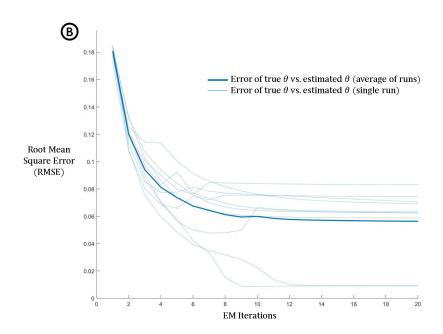
During our experiments, we noticed 2 interesting points:

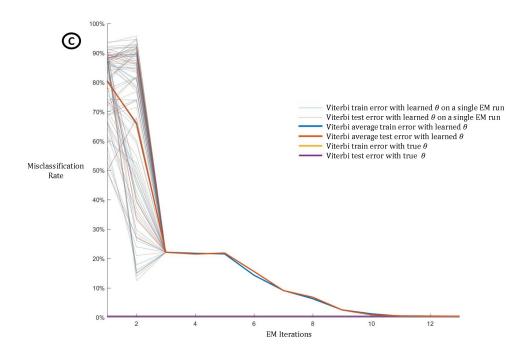
- Running the HOP Baum-Welch algorithm multiple times with different initialization  $\theta$  converged into different result parameters. There is a correlation between the log likelihood yielded by the  $\theta$  estimation and the RMSE between the estimated and true  $\theta$  (see figure 12). This is important since on observed sequences in real data, only the  $\theta$  likelihood is known while the true  $\theta$  is unknown and so it the error. This correlation suggests a strategy of redoing several EM runs, and choosing the one with the highest likelihood will result in an estimation closer to the true  $\theta$ .
- Adding regularization on T in  $\theta$  by limiting it so the major diagonal of T (probability of staying in the same hidden state) is larger than the sum of the rest of its values by a factor caused to convergence to better  $\theta$  estimations, which are closer to the true  $\theta$ .



12: Over multiple runs of HOP-Baum-Welch, a correlation exists between the estimated  $\theta$  likelihood over the learned sequences and the error comparing the true  $\theta$ .







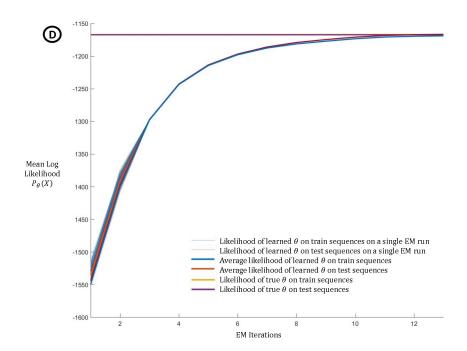


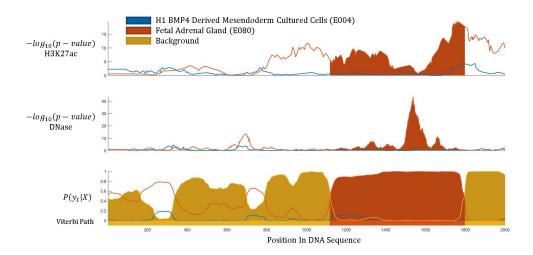
Figure: (A) the EM iterations draws the estimated  $\theta$  values mostly closer to the values of the true  $\theta$ . (B) The error between the true and estimated  $\theta$  decrease, and after a few iterations converge to the same path regardless of the initialization. (C) During the EM iterations, the learned  $\theta$  yields a more accurate Viterbi estimation of the hidden states. Note that not even the true  $\theta$  could produce Viterbi paths that is a perfect match to the true hidden sequences. (D) The mean log likelihood of the sequences increases during the EM iterations. The experiment was done on 500 synthetic sequences (85% train, 15% test), 1000 long. The trained model had 6 hidden background-states with emission order of 2, each background-state had 25 PWMs-states.

#### TODO: confusion graph of the states classification of the Viterbi algo.

## **Roadmap Dataset**

**Perprocessing** downloaded from Roadmap (links) tissues with all the histone mark data (number of tissues). Manipulated bed files with Bedtools, center of peaks +- 500. taking parts with H3K27ac and H3K4me3 and without ...

Choosing the PWMs Part of the definition of a HOP-HMM is a set of PWMs emitted by the TF-states. JASPAR has 719 vertebrates PWMs, and because of limitations related to the implementation of algorithm, we needed to select around 30 out of the possible 719 PWMs. The selected PWMs should be the most indicative for the tissue specific enhancers. In the process of choosing the PWMs, we aim to choose the PWMs that appear in one of the tested enhancers and not the others. we used the correlation (marked as  $L_W$  ( $x_{t-|W|}$ ,..., $x_{t-1}$ ) in above sections) to measure the appearance of a PWM in a sequence in a position in a sequence. We calculated the 3 best matching positions of every PWM in every sequence, and calculated how successful, in terms of AUC-ROC, this sum can separate one sequence type from the other using a threshold.



TODO: Violine graph of the posterior of places Viterbi marked as PWMs and didnt mark as PWMs. violine of the acc. of the places marked by the Viterbi on real DNA. also, deep tool of the acc. and ME3 of these sequences.

TODO: confusion graph of the states classification of the Viterbi algo.

TODO: deeptools: aligned heatmap sequences with the peak of the H3K27ac and post. prob., are they similar?]

Figure: HOP-Viterbi classification of a region classified as an enhancer, ChromHMM classification and the H3K27ac features

#### TODO: Use HUJI theses format, 12 point font size, with 1.5 line spacing

- 1. Opening page including:
- a. Heading "The Hebrew University of Jerusalem the Faculty of Mathematics and Natural Science the Institute of (Chemistry, Life Sciences, Physics, Mathematics, Earth Sciences, Computer Science)
- b. Title of the thesis in Hebrew and English
- c. Author's name (+ student number)
- d. Supervisor's name
- e. "Thesis for Master's degree in Natural Science"
- f. Date of submission in English and Hebrew

- 2. Personal page (dedication etc.)
- 3. Abstract
- 4. Table of contents
- 5. Body of the work
- 6. Bibliography
- 7. Appendices

The body of the work (section 5 above) will include:

- 1. Scientific introduction
- 2. Thesis aims
- 3. Methods (theoretical or experimental part)
- 4. Results
- 5. Discussion and summary.

## References

Ahituv et al., 2007

## Misc

**Pretraining** When sequences are labeled as tissue-specific enhancers are available, it is possible to pretrain a multi-background-state HOP-HMM with them. The E and G parts of such a model could be initialized with parameters taken from a smaller HOP-HMM, trained on 2 class datasets built out of tissue-specific enhancers and background DNA sequences. For each tissue, we build a dataset and trained a 2 background-state HOP-HMM model (one background-state for the enhancer and one for the background) and used the learned parameters of the enhancer background-state to initialize the bigger multi-background-state HOP-HMM.

## TODO: number the chapters and figures

#### **TODO:** abstract

The TF inside the nucleus of specific tissues are thought to be a key factor in the activation of specific enhancer. The TFs form a transcription complex and are connected to the enhancer and promoter sequences on top of the TF binding sites (TFBS). Studies using TFBS of TF present in specific cell types are used to classify cell specific enhancer sequences. show heat map of AUC-ROC results. Between these TFBS, k-mer frequencies varies between enhancers and non regulatory "background" DNA, and was used to classify enhancers from background using only the k-mer distribution (Inbar and tommy, gkm-SVM), and is thought to play a role in spacial properties, nucleosome location and cleavage that cause accessibility of near-by TFBS. Using 44 out of 127 epigenetic data of Roadmap Project to select tissue specific enhancer sequences dataset. In our method, we look for different TFBS and k-mer presence in sequences to classify cell-specific sequences, inside regulatory modules.

#### **TODO: Semi-Supervised Learning Scheme:**

- 1. **Pre-training:** Calculate maximal likelihood initialization parameters  $\theta_0$  with from observed labeled dataset of sequences  $Y_0$  and  $Y_0$
- 2. **Unsupervised learning:** Learn the  $\theta$  given X unlabeled sequences by approximating  $\theta_{best} = argmax_{\theta} \mathcal{L}(\theta|X)$

- 3. **Predicting labels:** Given learned  $\theta$ , infer hidden states Y for unlabeled X
- 4. **Tuning:** Preform hyperparameters optimization

experiment graphs:

per nucleotide binary classification (background vs enhancer) - heatmap (x-location relative to peak, y-sequence index, color-post. probability) use the  $\gamma_{i,*}$  of enhancers where i is the state of the enhancer, pick only the 2000+- around the enhancer's peak, where the center is the max of the H3K27ac signal, showing the sequences are most likely enhancers surrounded by non enhancers .

per sequence mutli-class classification (background vs enhancer) - heatmap (state number, y-sequence index, color-maximal post. probability for the sequence of that state) of  $\gamma$  of enhancers, where the center is the max of the H3K27ac, showing the sequences are most likely enhancers surrounded by non enhancers

per sequence classification

[per sequence binary classification - background vs enhancer]

[per nucleotide binary classification - background vs enhancer]

[per sequence binary classification - background vs enhancer]

#### **TODO: Possible Applications**

labeled enhancer seqs from multiple motifs-> EM to learn E M F per floor + setting  $T = \mathbb{I}_{m \times m}$  -> posterior of whole genome with sliding window -> classify whole genome

learn E M F -> check correlation with TF expression

run EM on whole genome -> posterior of whole genome -> check correlation of posterior to ChIP-Seq of histone modifications E M F T-> posterior of whole genome -> see if known critical SNPs are critical in classification

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