AMA2111 Mathematics I

Homework 1 Solution

1. Find all the cubic roots of $\frac{(\sqrt{3}-i)^{10}}{(-1+\sqrt{3}i)^7}$ and plot them in the complex plane.

Solution: Since

$$\sqrt{3} - i = 2e^{-i\frac{\pi}{6}}, \quad -1 + \sqrt{3}i = 2e^{i\frac{2}{3}\pi},$$

we have

$$\frac{(\sqrt{3}-i)^{10}}{(-1+\sqrt{3}i)^7} = \frac{2^{10}e^{-i\frac{10\pi}{6}}}{2^7e^{i\frac{14}{3}\pi}} = 2^3e^{-i\frac{19}{3}\pi} = 2^3e^{-i\frac{1}{3}\pi}.$$

The cubic roots are

$$z_k = 2e^{-i\frac{1}{9}\pi + i\frac{6k\pi}{9}}, \quad k = 0, 1, 2.$$

That is

$$z_0 = 2e^{-i\frac{1}{9}\pi}, \quad z_1 = 2e^{i\frac{5}{9}\pi}, \quad z_2 = 2e^{i\frac{11}{9}\pi}.$$

2. Consider the linear system

$$\begin{bmatrix} 1 & 3 & 2 & -1 \\ -2 & -5 & -2 & 3 \\ -1 & 0 & a & 5 \\ 3 & 7 & 2 & a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ b \\ 2 \end{bmatrix}.$$

- (a) Find the conditions satisfied by a and b such that the system has
 - i. no solutions;
 - ii. infinitely many solutions;
 - iii. a unique solution.

Also solve the system when it has infinitely many solutions.

(b) Consider the vectors
$$\boldsymbol{v}_1 = \begin{bmatrix} 1 \\ -2 \\ -1 \\ 3 \end{bmatrix}$$
, $\boldsymbol{v}_2 = \begin{bmatrix} 3 \\ -5 \\ 0 \\ 7 \end{bmatrix}$, $\boldsymbol{v}_3 = \begin{bmatrix} 2 \\ -2 \\ a \\ 2 \end{bmatrix}$, $\boldsymbol{v}_4 = \begin{bmatrix} -1 \\ 3 \\ 5 \\ a \end{bmatrix}$ and $\boldsymbol{v}_5 = \begin{bmatrix} 1 \\ 0 \\ b \\ 2 \end{bmatrix}$ in \mathbb{R}_4 .

- i. Find the conditions satisfied by a and b such that the span of v_1, v_2, v_4 and v_5 is \mathbb{R}_4 .
- ii. Find the conditions satisfied by a and b such that v_3, v_4 and v_5 are linearly dependent and write v_3 as a linear combination of v_4 and v_5 , if possible.

Solution. (a) Reduce the augmented matrix to the row-echelon form:

$$\begin{bmatrix} 1 & 3 & 2 & -1 & 1 \\ -2 & -5 & -2 & 3 & 0 \\ -1 & 0 & a & 5 & b \\ 3 & 7 & 2 & a & 2 \end{bmatrix} \xrightarrow{\substack{r_2+2r_1\to r_2\\r_3+r_1\to r_3\\r_4-3r_1\to r_4\\0}} \begin{bmatrix} 1 & 3 & 2 & -1 & 1 \\ 0 & 1 & 2 & 1 & 2 \\ 0 & 3 & a+2 & 4 & b+1 \\ 0 & -2 & -4 & a+3 & -1 \end{bmatrix} \xrightarrow{\substack{r_3-3r_2\to r_3\\r_4+2r_2\to r_4\\0}} \begin{bmatrix} 1 & 3 & 2 & -1 & 1 \\ 0 & 1 & 2 & 1 & 2 \\ 0 & 0 & a-4 & 1 & b-5 \\ 0 & 0 & 0 & a+5 & 3 \end{bmatrix}.$$

When $a \neq 4$ and $a \neq -5$, the system has a unique solution.

When a = -5, the last row of the row-echelon form gives 0 = 3, so the system has no solution.

When a = 4, we conduct the row operation once more:

$$\begin{bmatrix} 1 & 3 & 2 & -1 & 1 \\ 0 & 1 & 2 & 1 & 2 \\ 0 & 0 & 0 & 1 & b - 5 \\ 0 & 0 & 0 & 9 & 3 \end{bmatrix} \xrightarrow{r_4 - 9r_3 \to r_4} \begin{bmatrix} 1 & 3 & 2 & -1 & 1 \\ 0 & 1 & 2 & 1 & 2 \\ 0 & 0 & 0 & 1 & b - 5 \\ 0 & 0 & 0 & 0 & 48 - 9b \end{bmatrix}.$$

When $48 - 9b \neq 0$, namely, $b \neq \frac{16}{3}$, the system has no solution. Otherwise, $b = \frac{16}{3}$, the system has infinitely many solutions. In summary,

2

- when $a \neq 4$ and $a \neq -5$, the system has a unique solution;
- when a = -5 or $\begin{cases} a = 4 \\ b \neq \frac{16}{3} \end{cases}$, the system has no solution;
- when a=4 and $b=\frac{16}{3}$, the system has infinitely many solutions. Now, the system is equivalent to

$$\begin{cases} x_1 + 3x_2 + 2x_3 - x_4 = 1 \\ x_2 + 2x_3 + x_4 = 2 \\ x_4 = \frac{1}{3} \end{cases} \Rightarrow \begin{cases} x_1 = -\frac{11}{3} + 4s \\ x_2 = \frac{5}{3} - 2s \\ x_3 = s \\ x_4 = \frac{1}{3} \end{cases}.$$

(b) (i) According to the row operations in (a), we have

$$[\boldsymbol{v}_1 \ \boldsymbol{v}_2 \ \boldsymbol{v}_4 \ \boldsymbol{v}_5] \rightarrow \begin{bmatrix} 1 & 3 & -1 & 1 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 1 & b-5 \\ 0 & 0 & a+5 & 3 \end{bmatrix} \xrightarrow{r_4-(a+5)r_3\rightarrow r_4} \begin{bmatrix} 1 & 3 & -1 & 1 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 1 & b-5 \\ 0 & 0 & 0 & 3-(a+5)(b-5) \end{bmatrix}.$$

When $(a+5)(b-5) \neq 3$, the vectors $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_4$ and \mathbf{v}_5 are linearly independent, and thus, their spanned space is \mathbb{R}_4 .

(ii)

$$\left[m{v}_3 \; m{v}_4 \; m{v}_5
ight] = \left[egin{array}{cccc} 2 & -1 & 1 \ -2 & 3 & 0 \ a & 5 & b \ 2 & a & 2 \end{array}
ight] \longrightarrow \left[egin{array}{cccc} 1 & -rac{1}{2} & rac{1}{2} \ 0 & 1 & rac{1}{2} \ 0 & 0 & b - rac{3a}{4} - rac{5}{2} \ 0 & 0 & 1 - a \end{array}
ight].$$

To make $\mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5$ be linearly dependent, we need 1 - a = 0 and $b - \frac{3a}{4} - \frac{5}{2} = 0$, namely, a = 1 and $b = \frac{13}{4}$.

Therefore, when a=1 and $b=\frac{13}{4}$, the vectors $\mathbf{v}_3, \mathbf{v}_4, \mathbf{v}_5$ are linearly dependent. Now, the equation $t_3\mathbf{v}_3 + t_4\mathbf{v}_4 + t_5\mathbf{v}_5 = \mathbf{0}$ is equivalent to

$$\begin{cases} t_3 - \frac{1}{2}t_4 + \frac{1}{2}t_5 = 0 \\ t_4 + \frac{1}{2}t_5 = 0 \end{cases} \Rightarrow \begin{cases} t_3 = -\frac{3}{4}s \\ t_4 = -\frac{1}{2}s \\ t_5 = s \end{cases}$$

Then, we have

$$-\frac{3}{4}v_3 - \frac{1}{2}v_4 + v_5 = 0 \quad \Rightarrow \quad v_3 = -\frac{2}{3}v_4 + \frac{4}{3}v_5.$$

3

3. Let
$$A = \begin{bmatrix} 2 & 2 & 1 \\ 1 & 1 & -1 \\ -2 & 4 & 5 \end{bmatrix}$$
.

Find a nonsingular matrix P and a diagonal matrix D such that $A = PDP^{-1}$. Solution.

$$|A - \lambda I| = \begin{vmatrix} 2 - \lambda & 2 & 1 \\ 1 & 1 - \lambda & -1 \\ -2 & 4 & 5 - \lambda \end{vmatrix} \xrightarrow{r_2 + r_1 \to r_2} \begin{vmatrix} 2 - \lambda & 2 & 1 \\ 3 - \lambda & 3 - \lambda & 0 \\ -2 & 4 & 5 - \lambda \end{vmatrix}$$

$$\xrightarrow{\frac{c_2 - c_1 \to c_2}{2}} \begin{vmatrix} 2 - \lambda & \lambda & 1 \\ 3 - \lambda & 0 & 0 \\ -2 & 6 & 5 - \lambda \end{vmatrix} \xrightarrow{\text{expand along } c_1} (-1)^{2+1} (3 - \lambda) \begin{vmatrix} \lambda & 1 \\ 6 & 5 - \lambda \end{vmatrix}$$

$$= -(\lambda - 3)(\lambda^2 - 5\lambda + 6) = -(\lambda - 2)(\lambda - 3)^2.$$

Therefore, the eigenvalues of A are $\lambda_1 = 2$ and $\lambda_2 = \lambda_3 = 3$. For $\lambda_1 = 2$,

$$A - 2I = \begin{bmatrix} 0 & 2 & 1 \\ 1 & -1 & -1 \\ -2 & 4 & 3 \end{bmatrix} \xrightarrow{r_1 \leftrightarrow r_2 \\ r_3 + 2r_1 \to r_3} \begin{bmatrix} 1 & -1 & -1 \\ 0 & 2 & 1 \\ 0 & 2 & 1 \end{bmatrix} \to \begin{bmatrix} 1 & -1 & -1 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix}.$$

A linearly independent eigenvector corresponding to $\lambda_1 = 2$ is given by

$$\mathbf{v}_1 = \left[\begin{array}{c} 1 \\ -1 \\ 2 \end{array} \right].$$

For $\lambda_2 = \lambda_3 = 3$,

$$A - 3I = \begin{bmatrix} -1 & 2 & 1 \\ 1 & -2 & -1 \\ -2 & 4 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

Two linearly independent eigenvectors corresponding to $\lambda_2 = \lambda_3 = 3$ are given by

$$\mathbf{v}_2 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}.$$

Let

$$P = [\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3] = \begin{bmatrix} 1 & 2 & 1 \\ -1 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix}, \quad D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix},$$

4. Let
$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$
.

- (a) Find the eigenvalues and eigenvectors of A.
- (b) Find an orthogonal matrix Q and a diagonal matrix D such that $A = QDQ^T$.

Solution:

(a)

Step 1 (The eigenvalues): The characteristic polynomial is given by

$$|A - \lambda I| = \begin{vmatrix} 1 - \lambda & 1 & 1 \\ 1 & 1 - \lambda & 1 \\ 1 & 1 & 1 - \lambda \end{vmatrix} \xrightarrow{r_1 - r_2 \to r_1} \begin{vmatrix} -\lambda & \lambda & 0 \\ 1 & 1 - \lambda & 1 \\ 1 & 1 & 1 - \lambda \end{vmatrix}$$
$$\xrightarrow{c_1 + c_2 \to c_2} \begin{vmatrix} -\lambda & 0 & 0 \\ 1 & 2 - \lambda & 1 \\ 1 & 2 & 1 - \lambda \end{vmatrix} = -\lambda[(2 - \lambda)(1 - \lambda) - 2] = -\lambda^2(\lambda - 3).$$

Hence, equation $|A - \lambda I| = 0$ has roots

$$\lambda_1 = \lambda_2 = 0, \quad \lambda_3 = 3.$$

which are eigenvalues of matrix A.

Step 2 (The eigenvectors): The eigenvectors $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$ with respect to eigenvalues $\lambda_1 = \lambda_2 = 0$ satisfy $A\mathbf{v} = 0\mathbf{v} = 0$. This yields linear equation

$$v_1 + v_2 + v_3 = 0.$$

Hence, the degree of freedom is 2. We have $\mathbf{v} = \begin{bmatrix} -s - t \\ s \\ t \end{bmatrix}$, for any $st \neq 0$. We have two linearly independent eigenvectors w.r.t. eigenvalue 0:

$$m{v}_1 = egin{bmatrix} -1 \ 1 \ 0 \end{bmatrix}, \quad m{v}_2 = egin{bmatrix} -1 \ 0 \ 1 \end{bmatrix}.$$

The eigenvector $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$ with respect to eigenvalues $\lambda_3 = 3$ satisfy $A\mathbf{v} = 3\mathbf{v}$.

Solving this system of linear equations, we have $\mathbf{v} = \begin{bmatrix} t \\ t \\ t \end{bmatrix}$ for any $t \neq 0$. Hence,

we have eigenvector w.r.t. eigenvalue 3: $\boldsymbol{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$.

(b)

Step 3 (Gram-Schmidt process): Notice that

$$\langle \boldsymbol{v}_1, \boldsymbol{v}_3 \rangle = \langle \boldsymbol{v}_2, \boldsymbol{v}_3 \rangle = 0.$$

We normalize $\boldsymbol{v}_2,\ \boldsymbol{v}_3$ and obtain

$$\mathbf{q}_2 = rac{oldsymbol{v}_2}{\|oldsymbol{v}_2\|} = egin{bmatrix} -rac{\sqrt{2}}{2} \ 0 \ rac{\sqrt{2}}{2} \end{bmatrix}, \quad \mathbf{q}_3 = rac{oldsymbol{v}_3}{\|oldsymbol{v}_3\|} = egin{bmatrix} rac{\sqrt{3}}{3} \ rac{\sqrt{3}}{3} \ rac{\sqrt{3}}{3} \end{bmatrix}.$$

For v_1 , we first get the orthogonal part w.r.t. \mathbf{q}_2 , \mathbf{q}_3 :

$$\mathbf{w}_1 = \mathbf{v}_1 - \langle \mathbf{v}_1, \mathbf{q}_2 \rangle \mathbf{q}_2 = \begin{bmatrix} -1/2 \\ 1 \\ -1/2 \end{bmatrix}.$$

Normalize \mathbf{w}_1 and we have

$$\mathbf{q}_1 = \frac{\mathbf{w}_1}{\|\mathbf{w}_1\|} = \begin{bmatrix} -\sqrt{6}/6 \\ \sqrt{6}/3 \\ -\sqrt{6}/6 \end{bmatrix}.$$

Hence, the orthogonal matrix is given by $Q=\begin{bmatrix} -\sqrt{6}/6 & -\sqrt{2}/2 & \sqrt{3}/3\\ \sqrt{6}/3 & 0 & \sqrt{3}/3\\ -\sqrt{6}/6 & \sqrt{2}/2 & \sqrt{3}/3 \end{bmatrix}$ and the diagonal matrix is given by $D=\begin{bmatrix} 0 & 0 & 0\\ 0 & 0 & 0\\ 0 & 0 & 3 \end{bmatrix}$.

5. Solve the differential equation $y' \cos x + \sin^2 y = \cos^2 y$.

Solution: The equation is equivalent to

$$\cos x \frac{dy}{dx} = \cos^2 y - \sin^2 y = \cos(2y)$$

If $\cos(2y) \neq 0$

$$\int \sec(2y)dy = \int \sec x dx$$

$$\frac{1}{2}\ln|\sec(2y)+\tan(2y)|=\ln|\sec(x)+\tan(x)|+C$$

From $\cos(2y) = 0$, we get solutions $y = \frac{k\pi}{2} + \frac{\pi}{4}$, $k \in \mathbb{Z}$.

Therefore
$$\cos(2y) = C[1+\sin(2y)] \left(\frac{\cos x}{1+\sin x}\right)^2$$
. (No need to write.)

6. Solve the differential equation $-xy' + 2y = \ln x$.

Solution: This is a linear equation.

$$y' - \frac{2}{x}y = -\frac{\ln x}{x}$$

Then, we have

$$\ln \mu = \int -\frac{2}{x} dx = \ln x^{-2} \quad \Rightarrow \quad \mu = \frac{1}{x^2}$$

$$\mu y = \int -\frac{\ln x}{x} \mu dx$$

$$\frac{1}{x^2} y = \int -\frac{\ln x}{x} \frac{1}{x^2} dx = \frac{1}{2} x^{-2} \ln x - \frac{1}{2} \int x^{-3} dx = \frac{1}{2} x^{-2} \ln x + \frac{1}{4} x^{-2} + C$$

$$y = \frac{1}{2} \ln x + \frac{1}{4} + C x^2$$

7. Find the explicit y(x) of the initial value problem $y' - \frac{y}{x} = \frac{(x+y)^2}{x^2}$ (x > 0) and y(1) = -2.

Solution: The equation is equivalent to

$$\frac{dy}{dx} - \frac{y}{x} = \left(1 + \frac{y}{x}\right)^2.$$

Let $v = \frac{y}{x}$.

$$x\frac{dv}{dx} + v - v = (1+v)^2.$$

As v(1) = -2, separate variables and we have

$$\int \frac{1}{(v+1)^2} dv = \int \frac{1}{x} dx$$

which gives

$$\int \frac{1}{(v+1)^2} dv = -\frac{1}{v+1} = \ln x + C$$

$$x = 1, \ v = -2 \quad \Rightarrow \quad C = 1$$

$$v+1 = -\frac{1}{\ln x + 1}$$

$$\frac{y}{x} = -1 - \frac{1}{\ln x + 1}$$

Hence,

$$y = -x - \frac{x}{\ln x + 1} = -x \frac{\ln x + 2}{\ln x + 1}.$$