

6.034 FALL 2020

RECITATION 9: SVMs

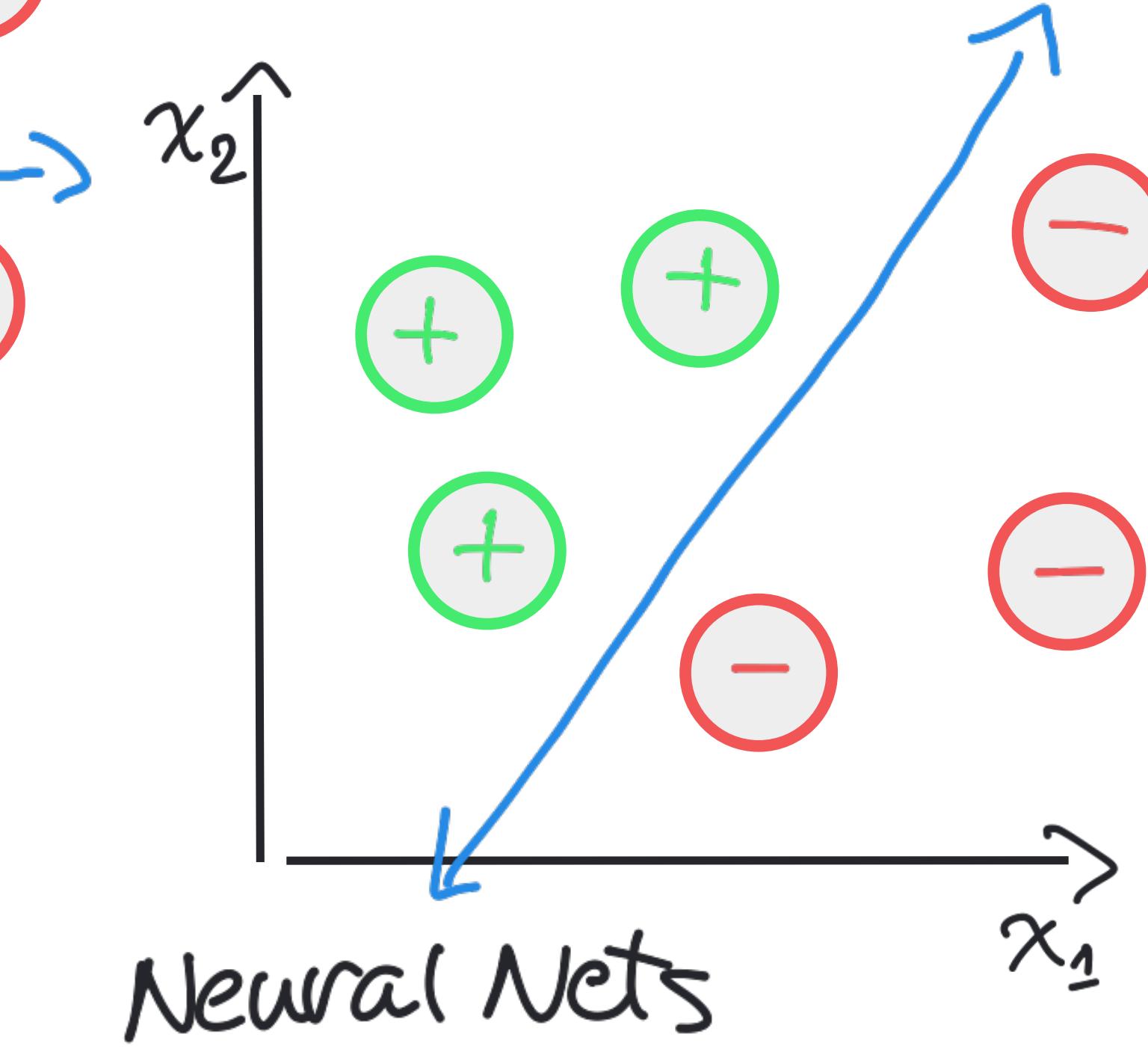
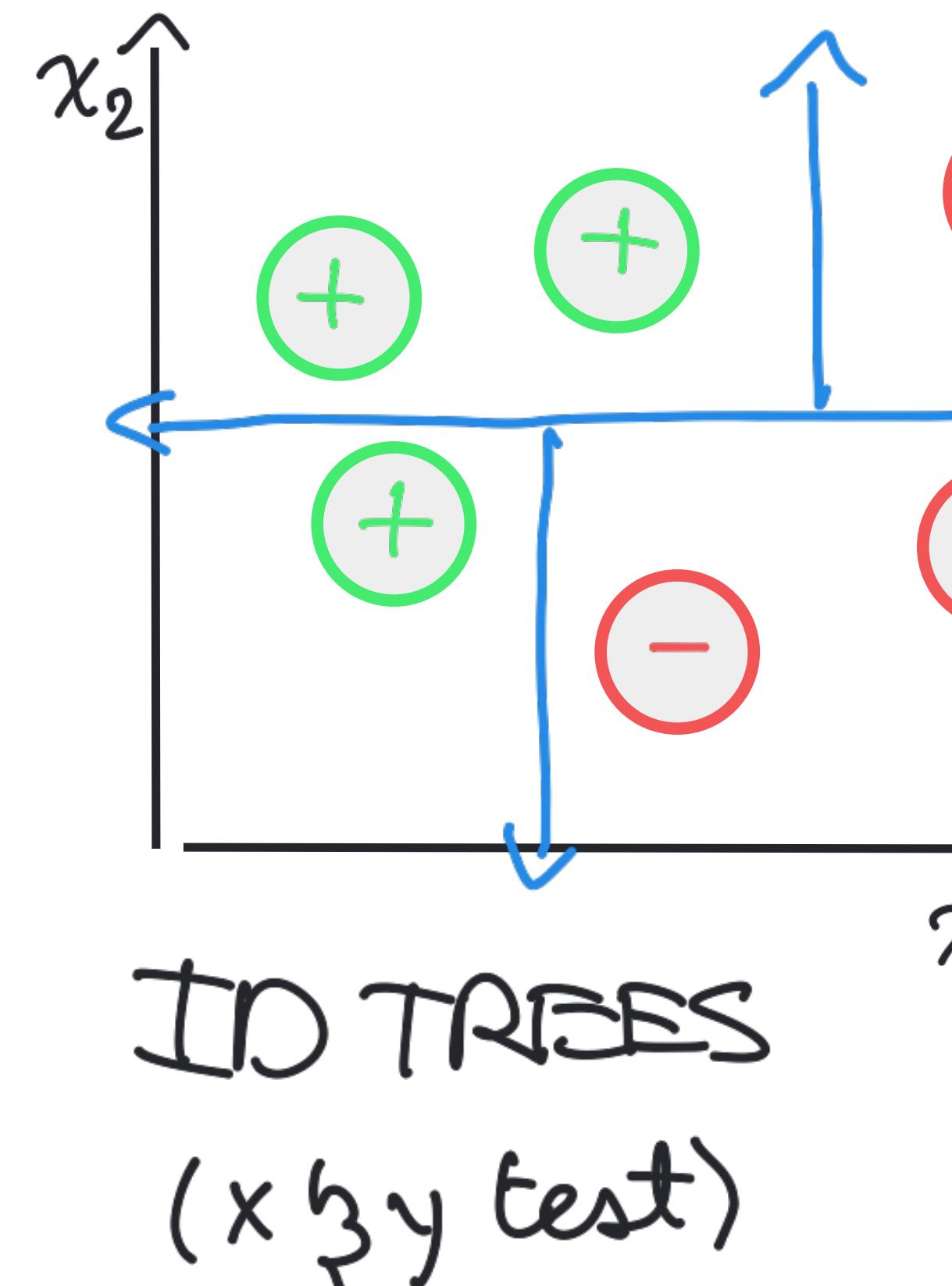
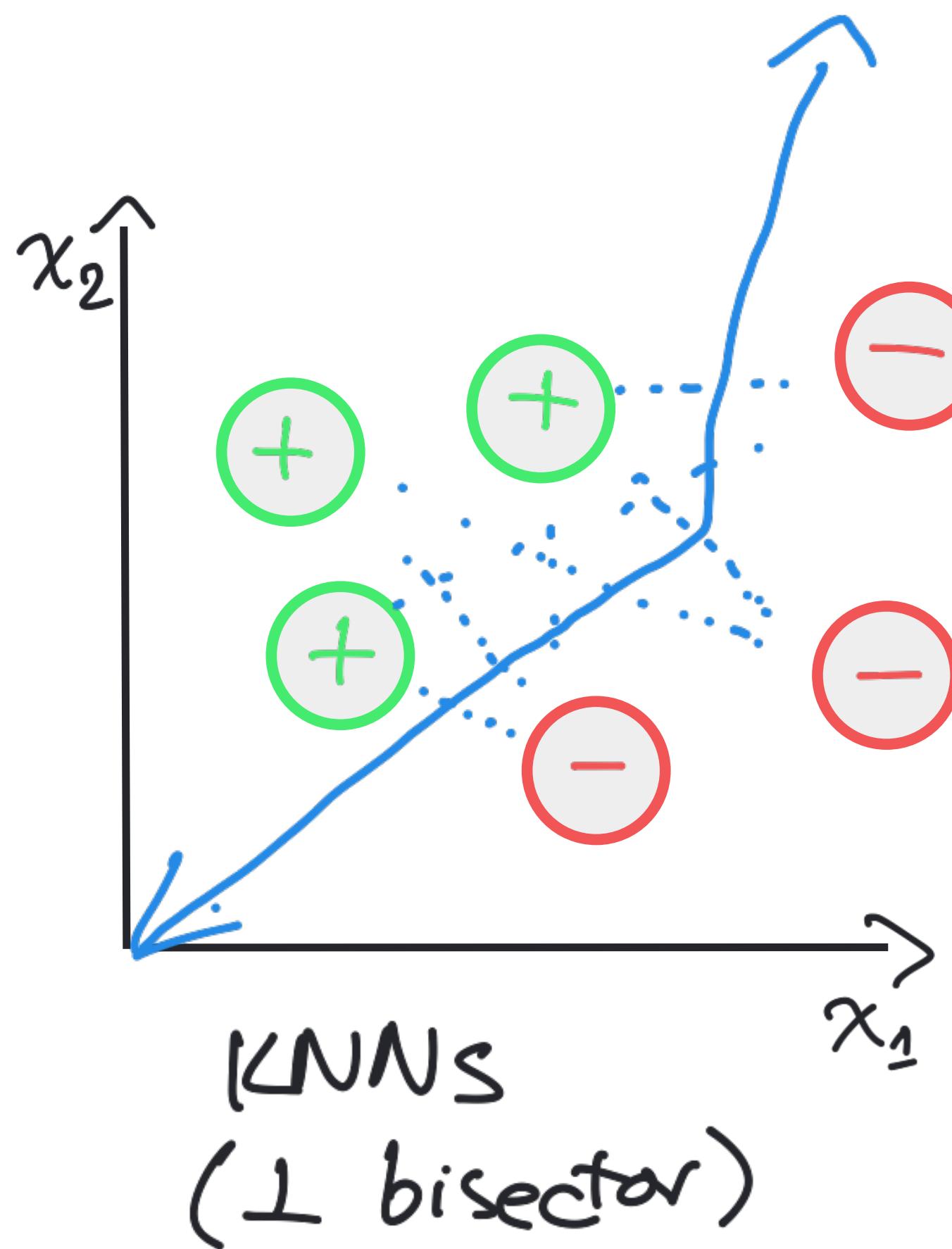
□ DRAW SVM BOUNDARY \nparallel GUTTER

□ CALCULATING \vec{w} , b \nparallel α VALUES

□ KERNEL TRICK

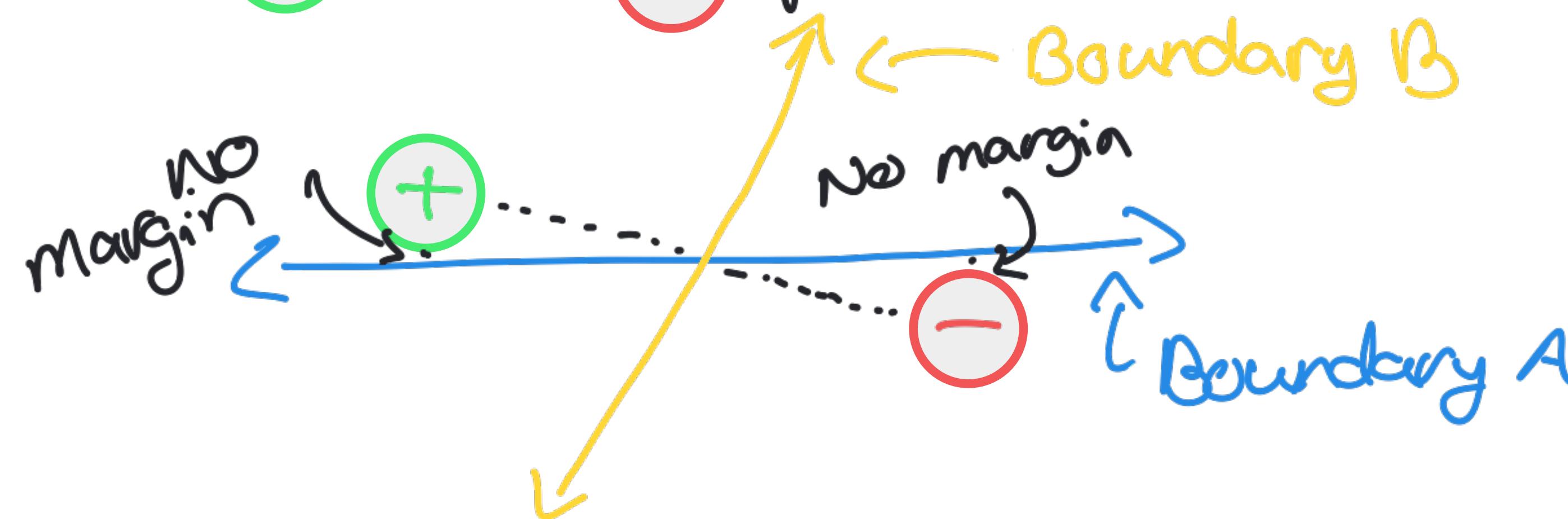
SUPERVISED MACHINE LEARNING

Goal*: Draw boundaries



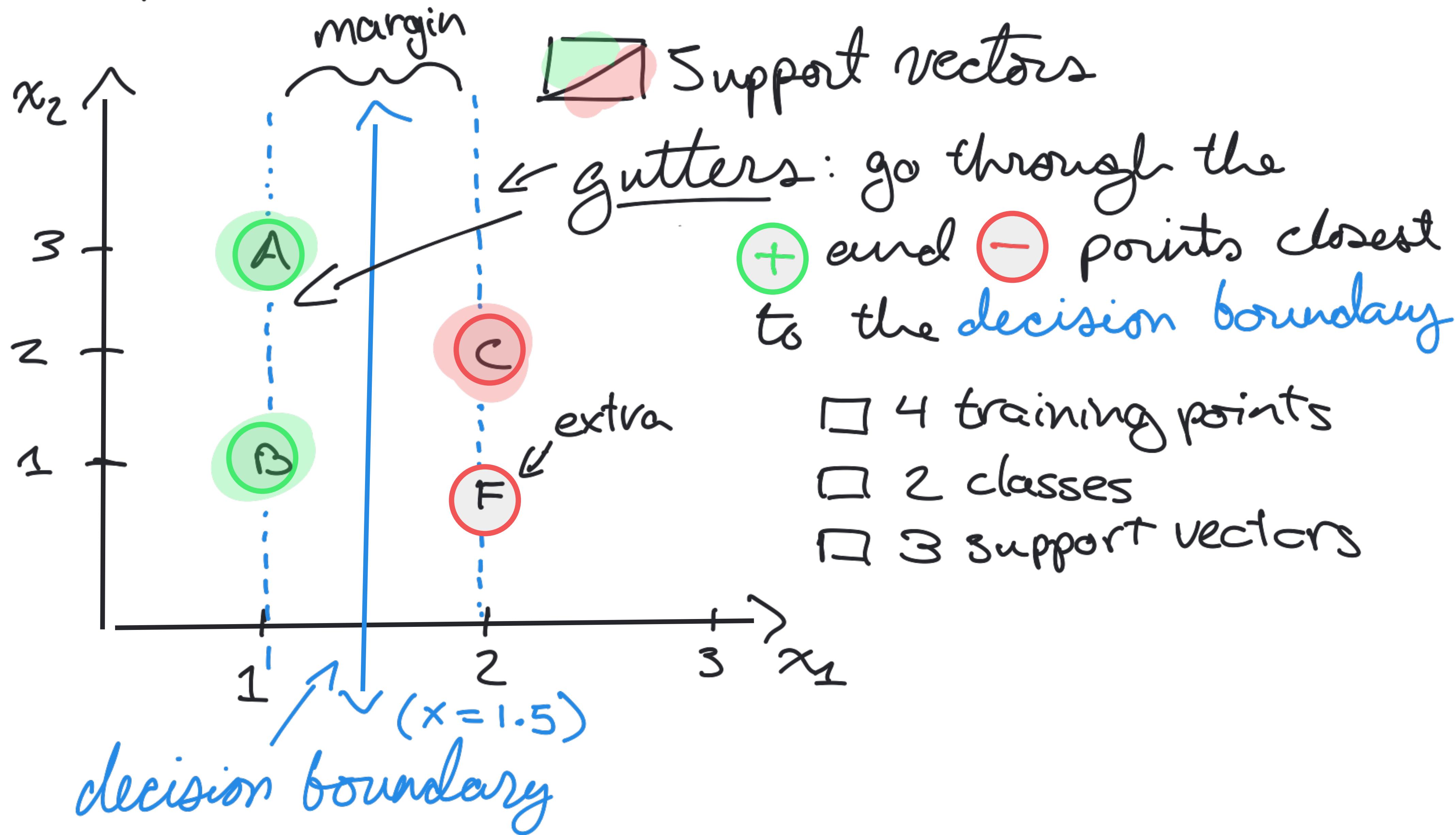
Support Vector Machines

- Binary (+/-) classifier
- Numerical classifier (NOT symbolic)
- Draws a single decision boundary to maximize margin width between $\textcircled{+}$ and $\textcircled{-}$ points

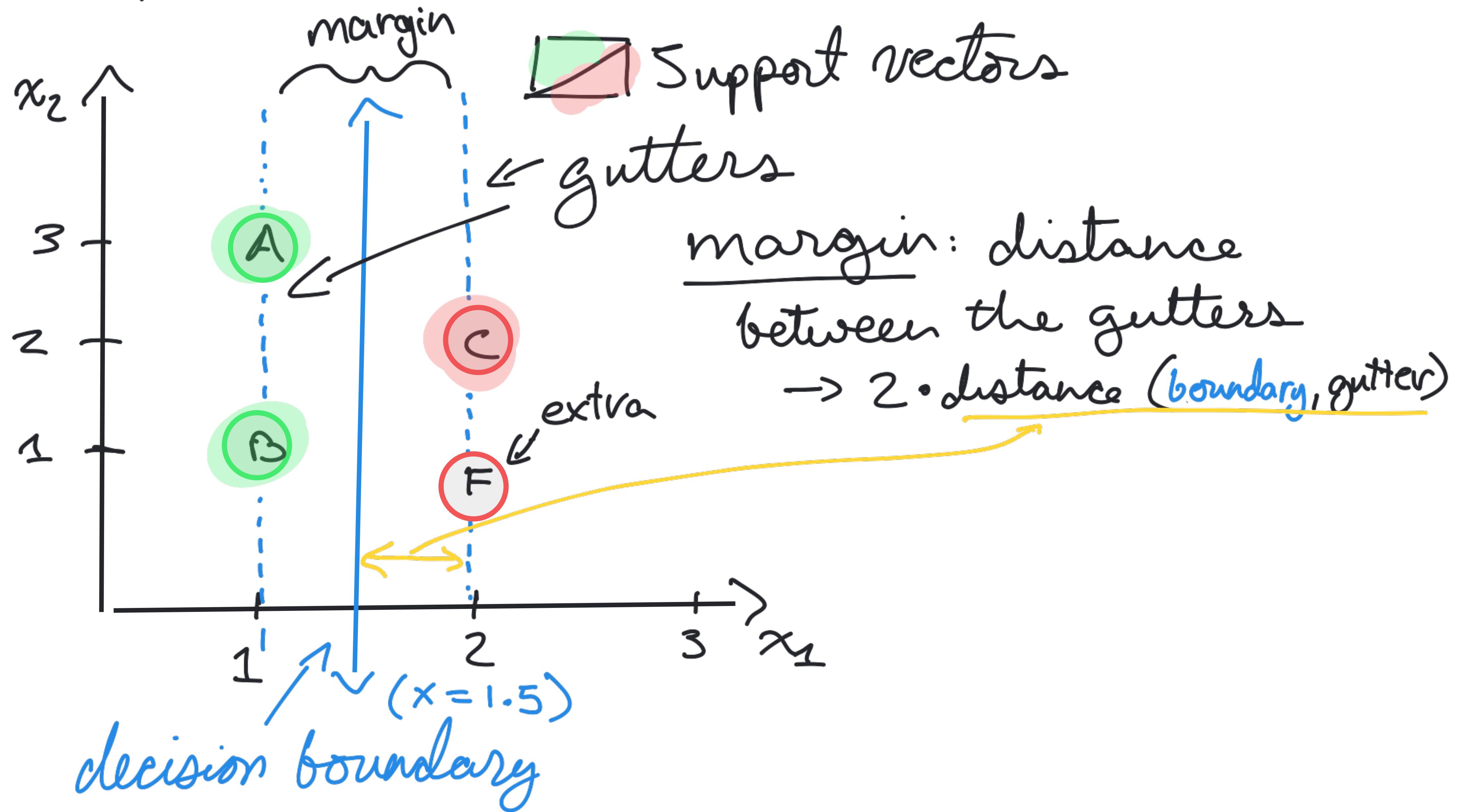


Prefer **B** to **A** due to the larger margins.

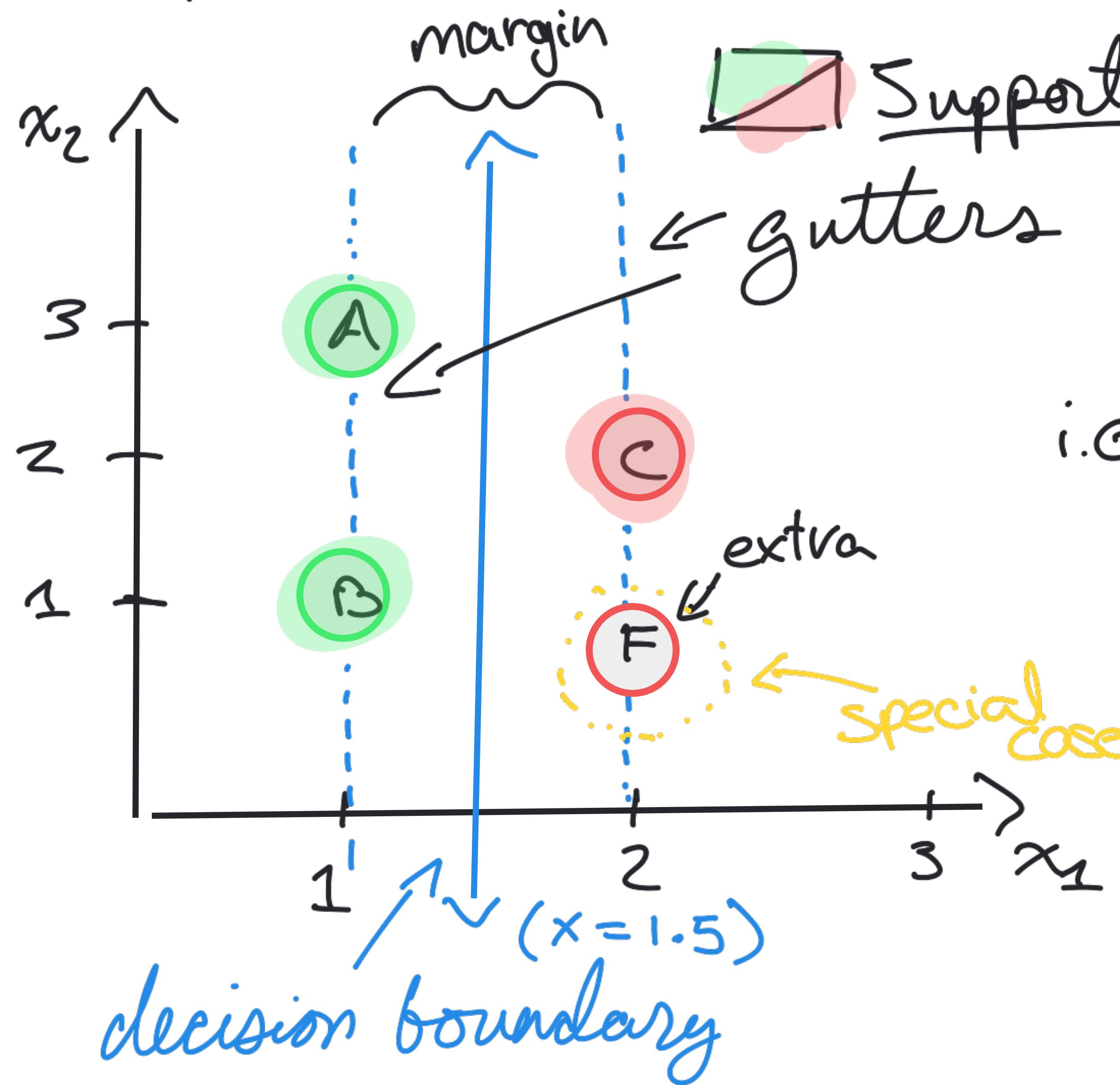
Support Vector Machines



Support Vector Machines



Support Vector Machines

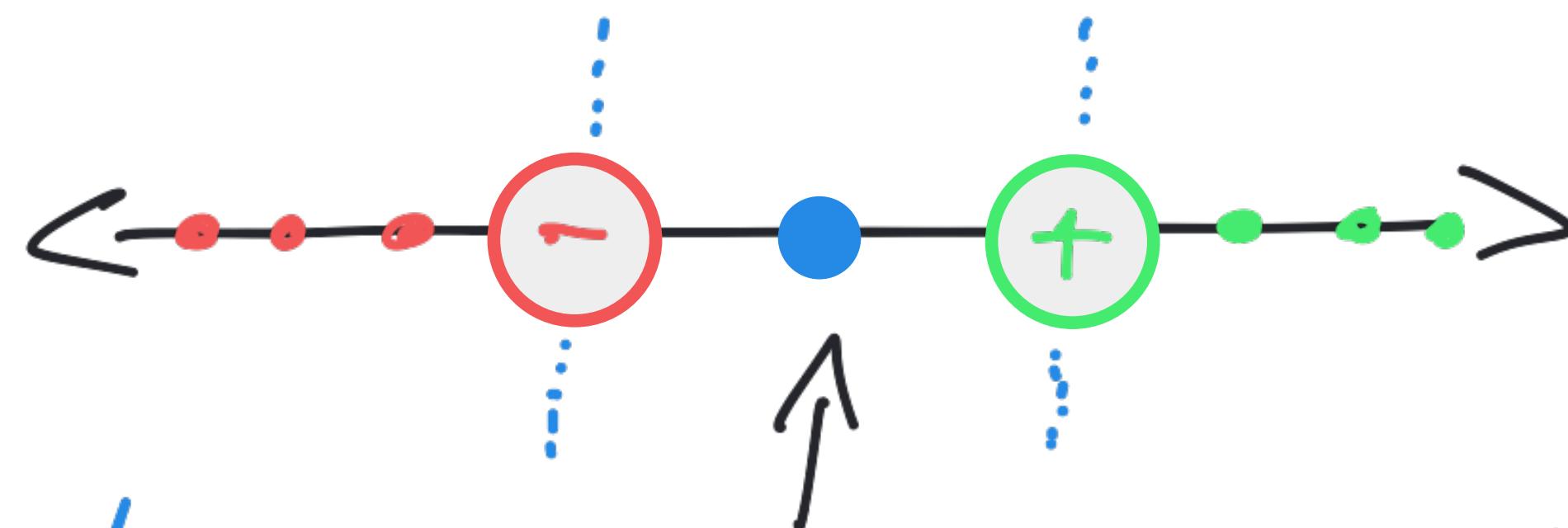


Support vectors: any point that **defines** the **decision boundary**
i.e. if a support vector is removed, the **boundary will change**

Support Vector Machines

Cases of Support Vectors :

10:

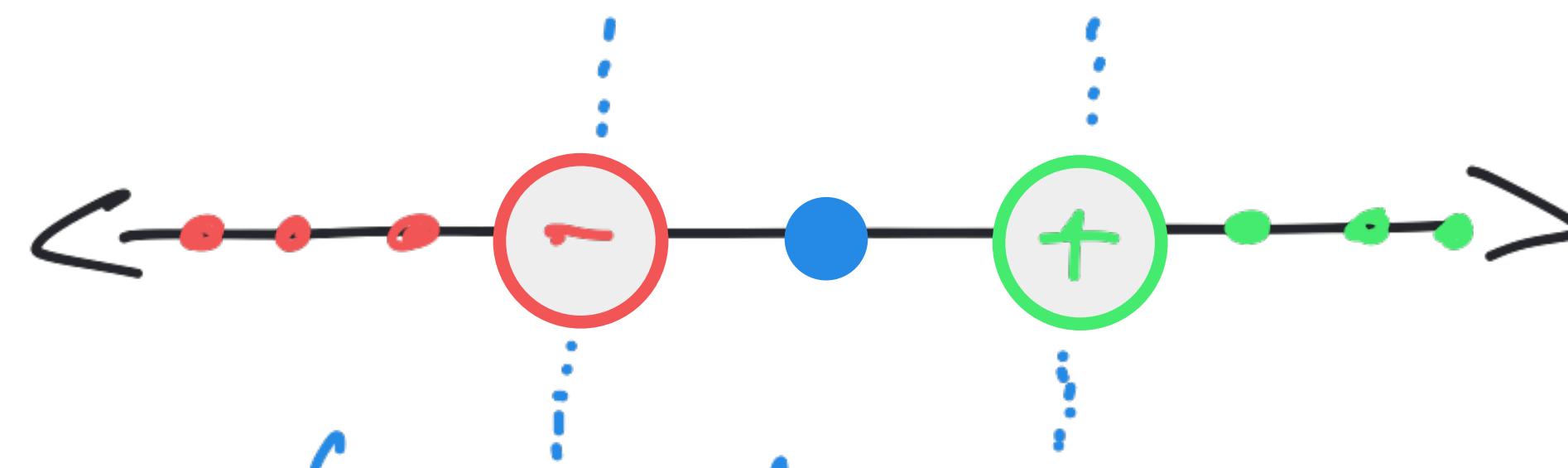


- Decision boundary is a point
- Only 2 support vectors

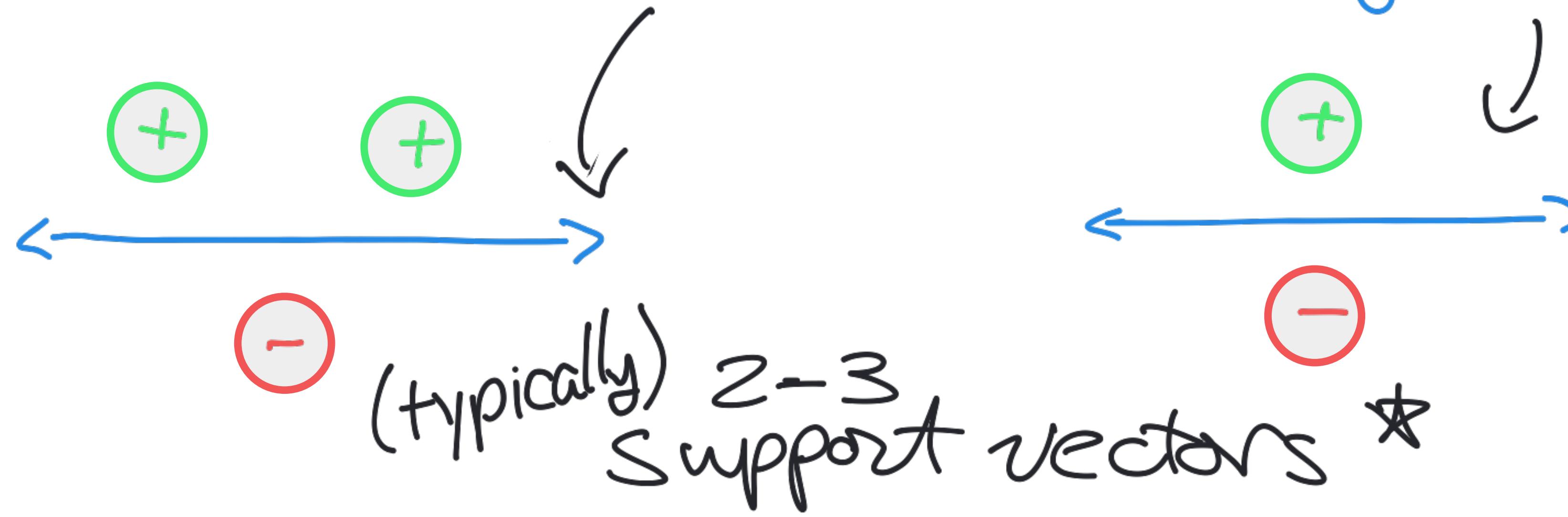
Support Vector Machines

Cases of Support Vectors :

1D:



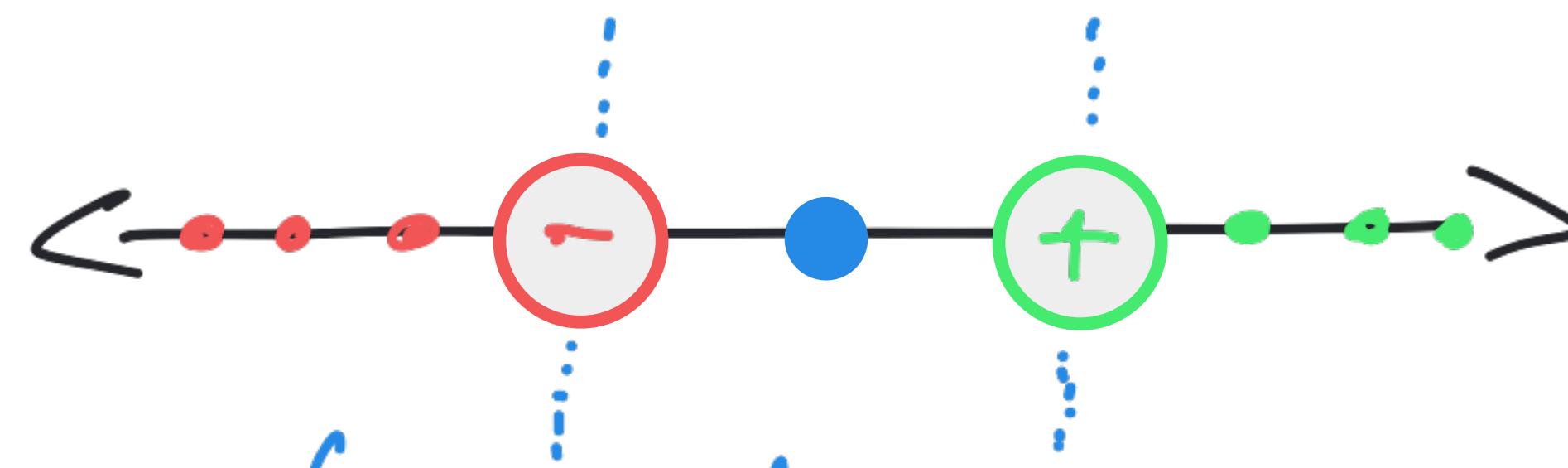
2D: Decision boundary is a line



Support Vector Machines

Cases of Support Vectors :

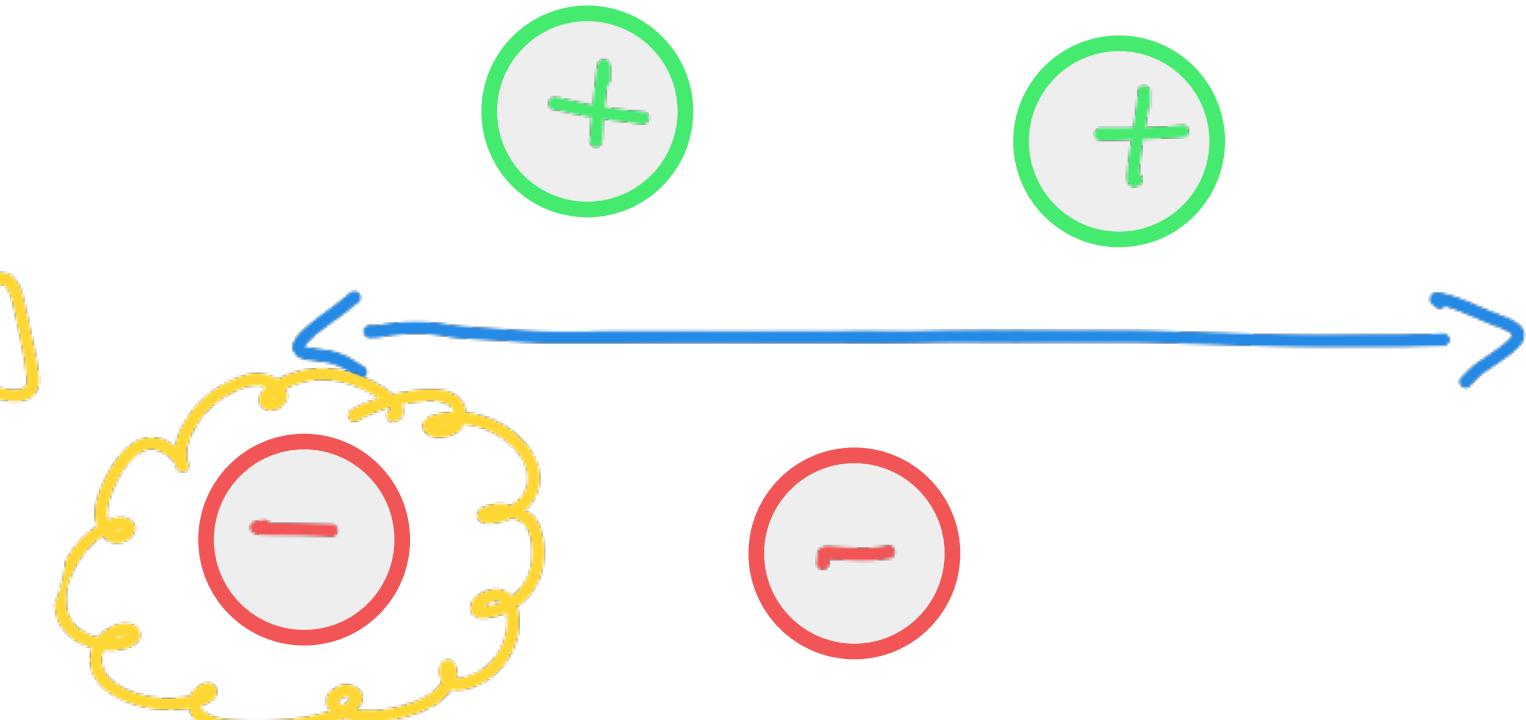
1D:



2D: Decision boundary is a line

Suppose I add the
following point...

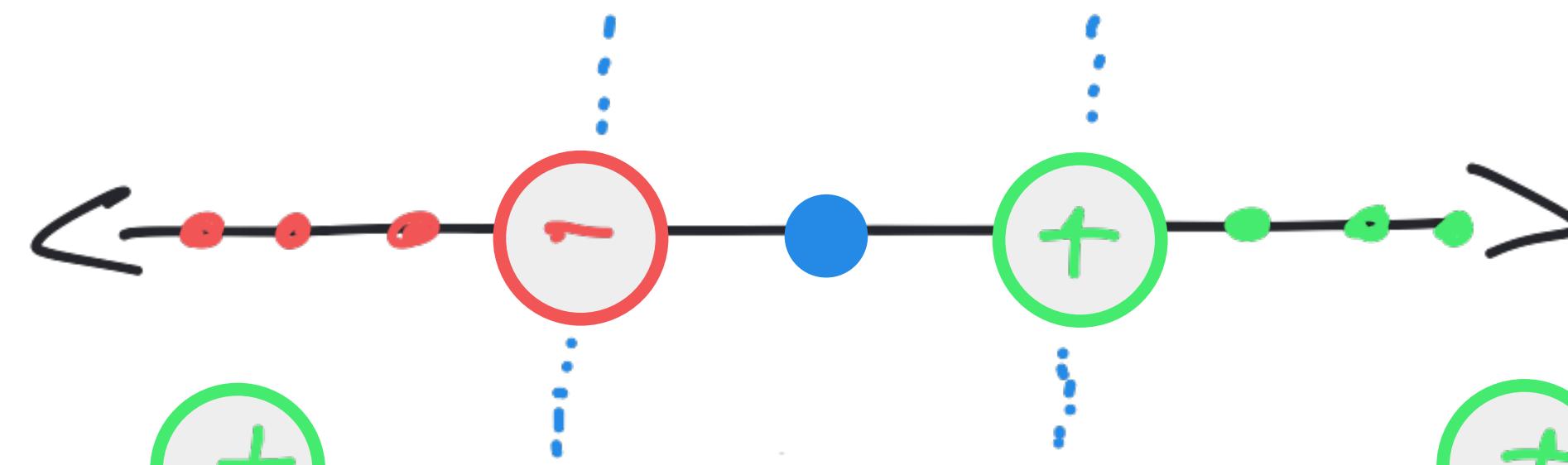
The notion of support
vector becomes more
ambiguous



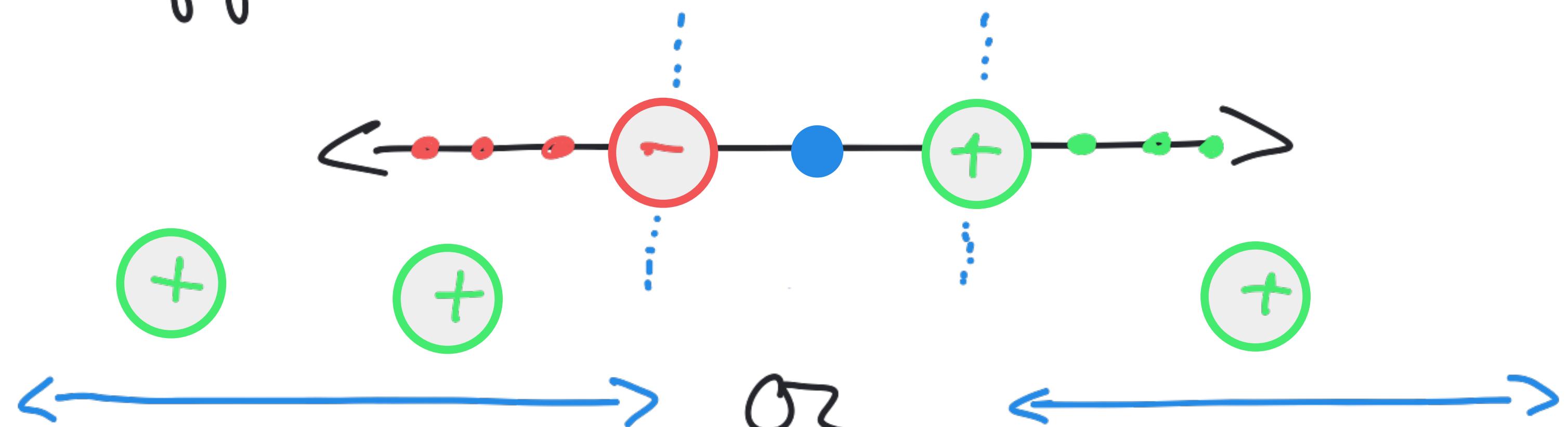
Support Vector Machines

Cases of Support Vectors :

1D:

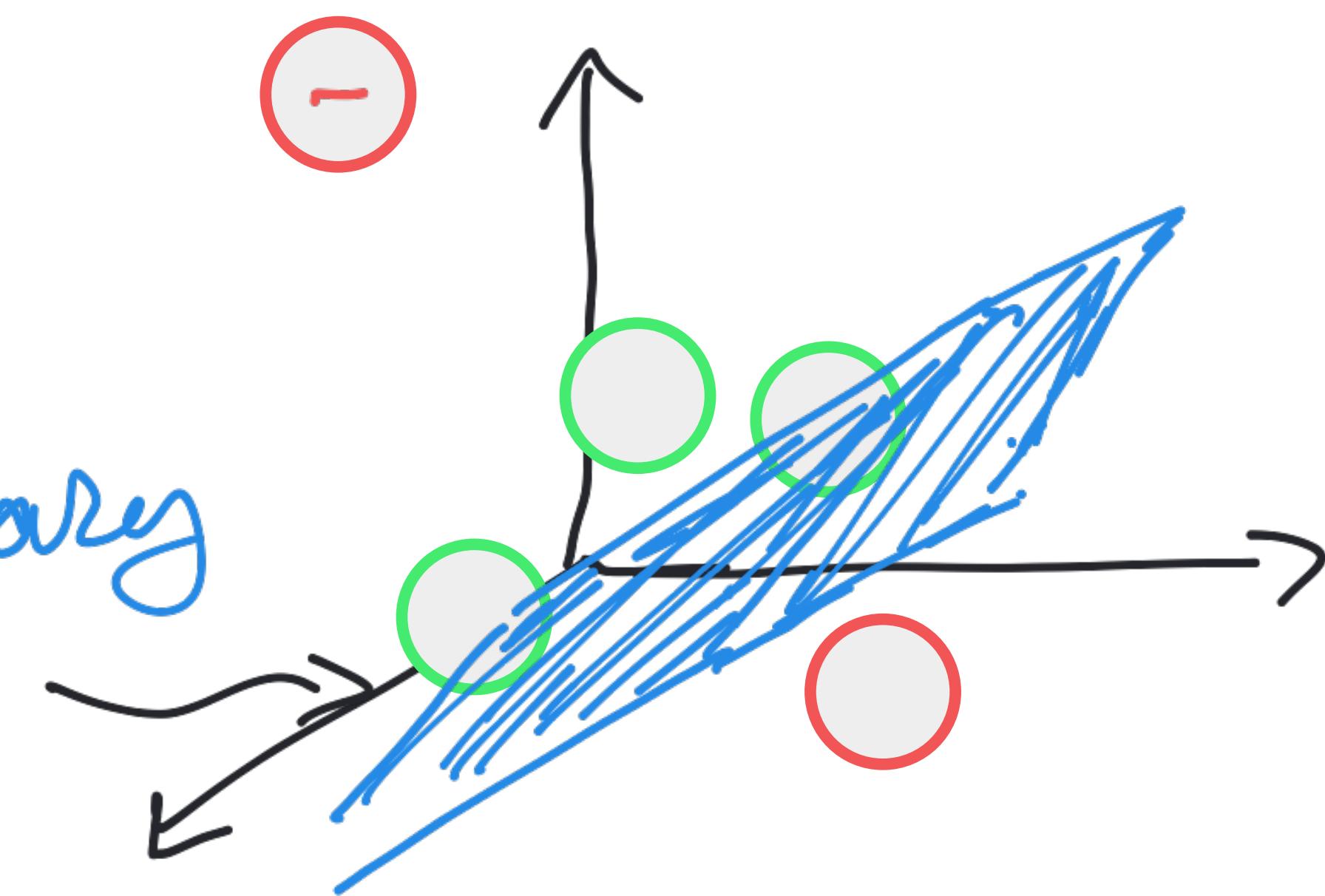


2D:



3D:

*Decision boundary
is a surface*

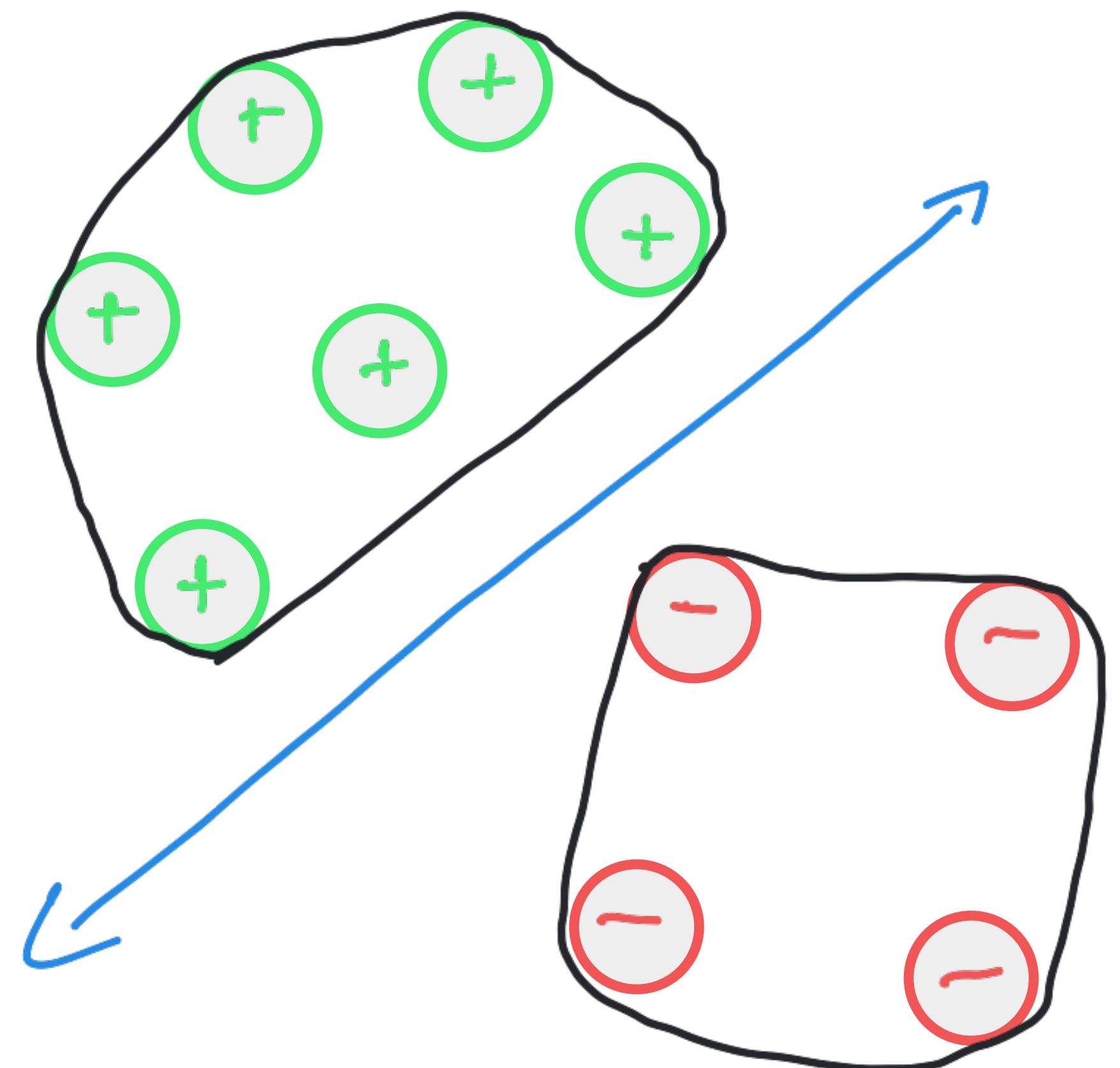


Convex Hull Method

- A way of visualizing the decision boundary when it may be hard to see initially
- Imagine you stretch a rubber band around $+$ s and $-$ s

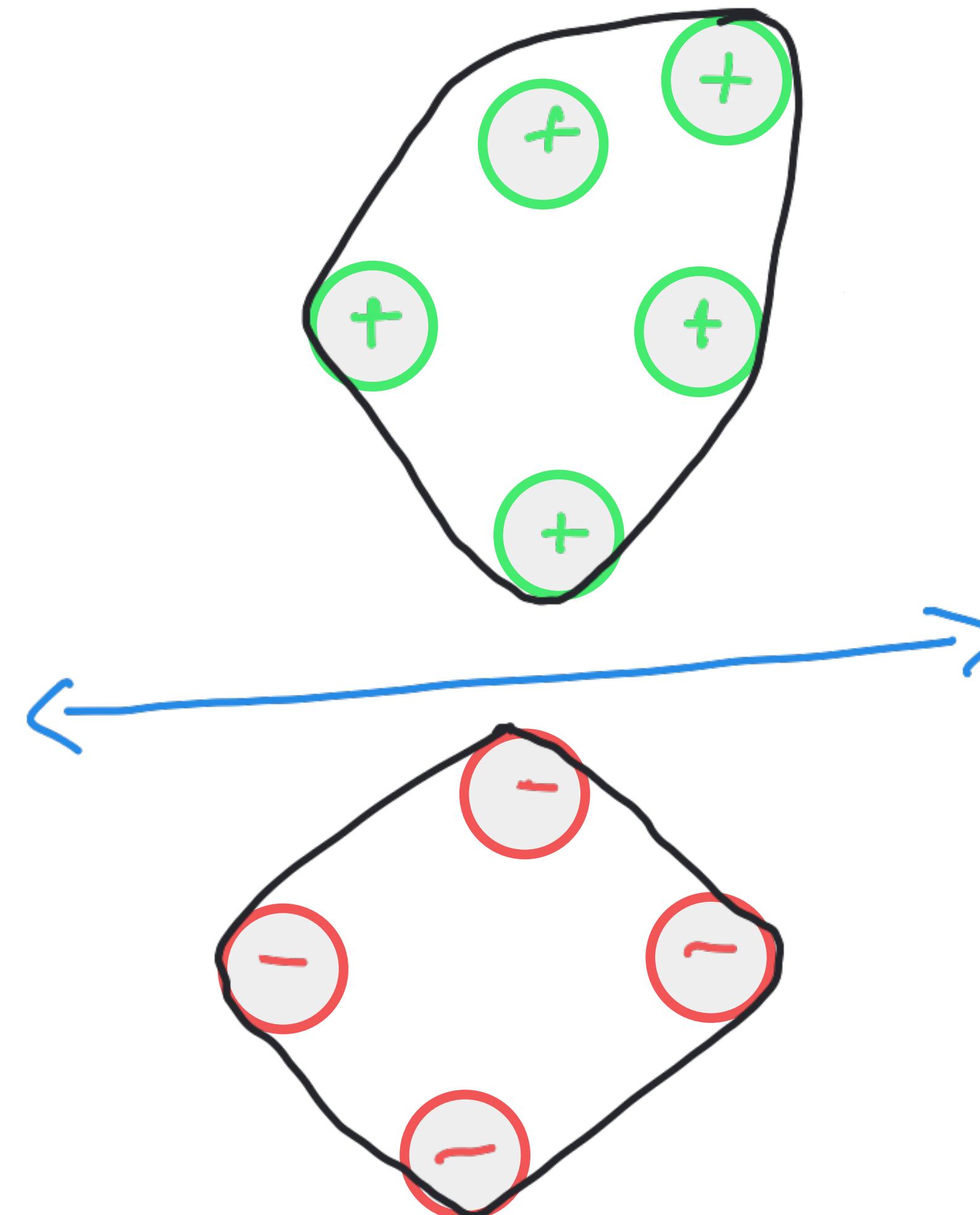
Convex Hull Method

Case 1:



- line \nmid point
- decision boundary
is \parallel to the line
- 2/3 support vectors

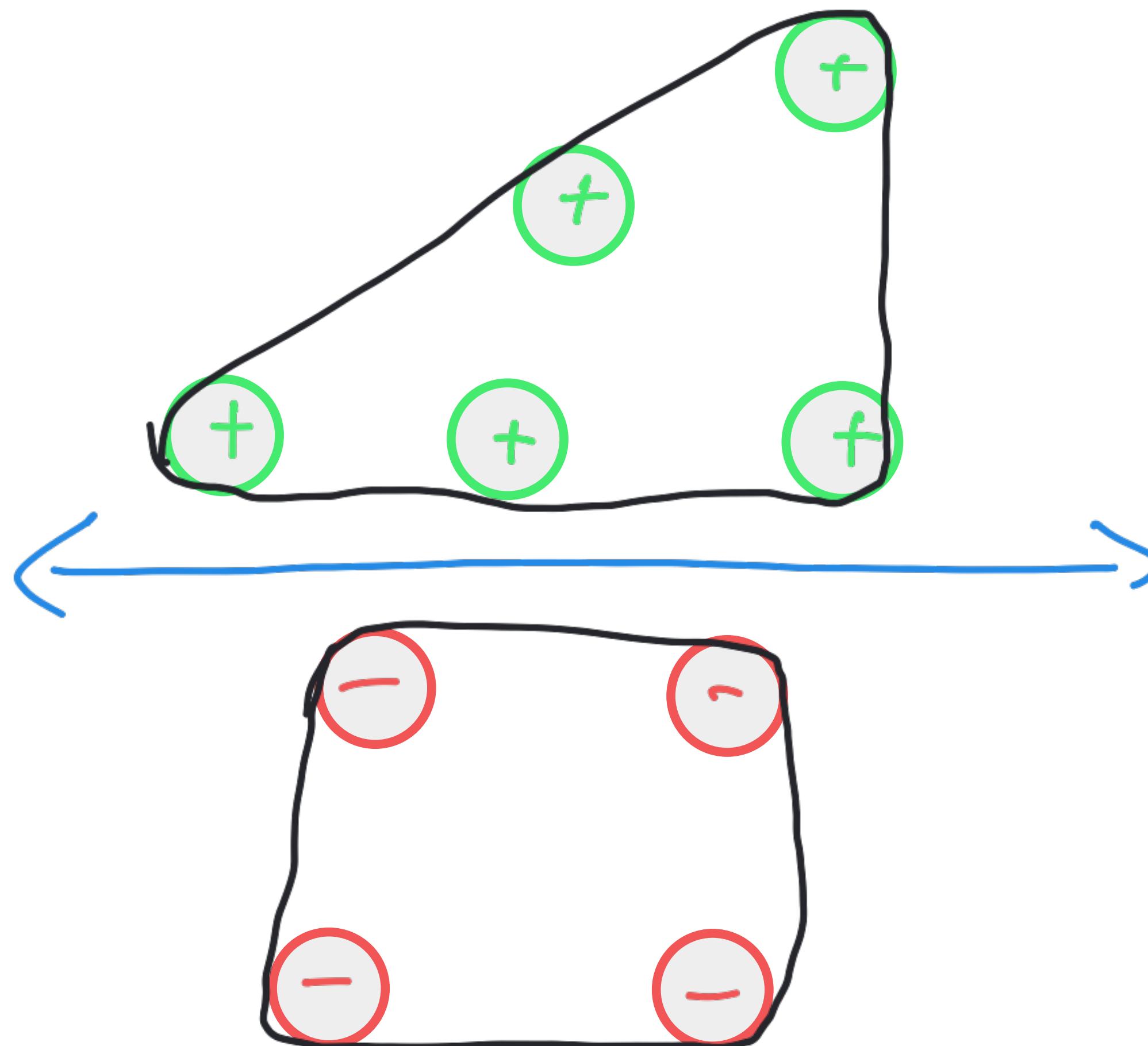
Convex Hull Method



Case 2:

- 2 points
- decision boundary
is \perp to the line
connecting the points
(KNNs)
- 2 support vectors

Convex Hull Method



Case 3:

- 2 lines
- Decision boundary is halfway between the 2 lines
- 2/3 support vectors*

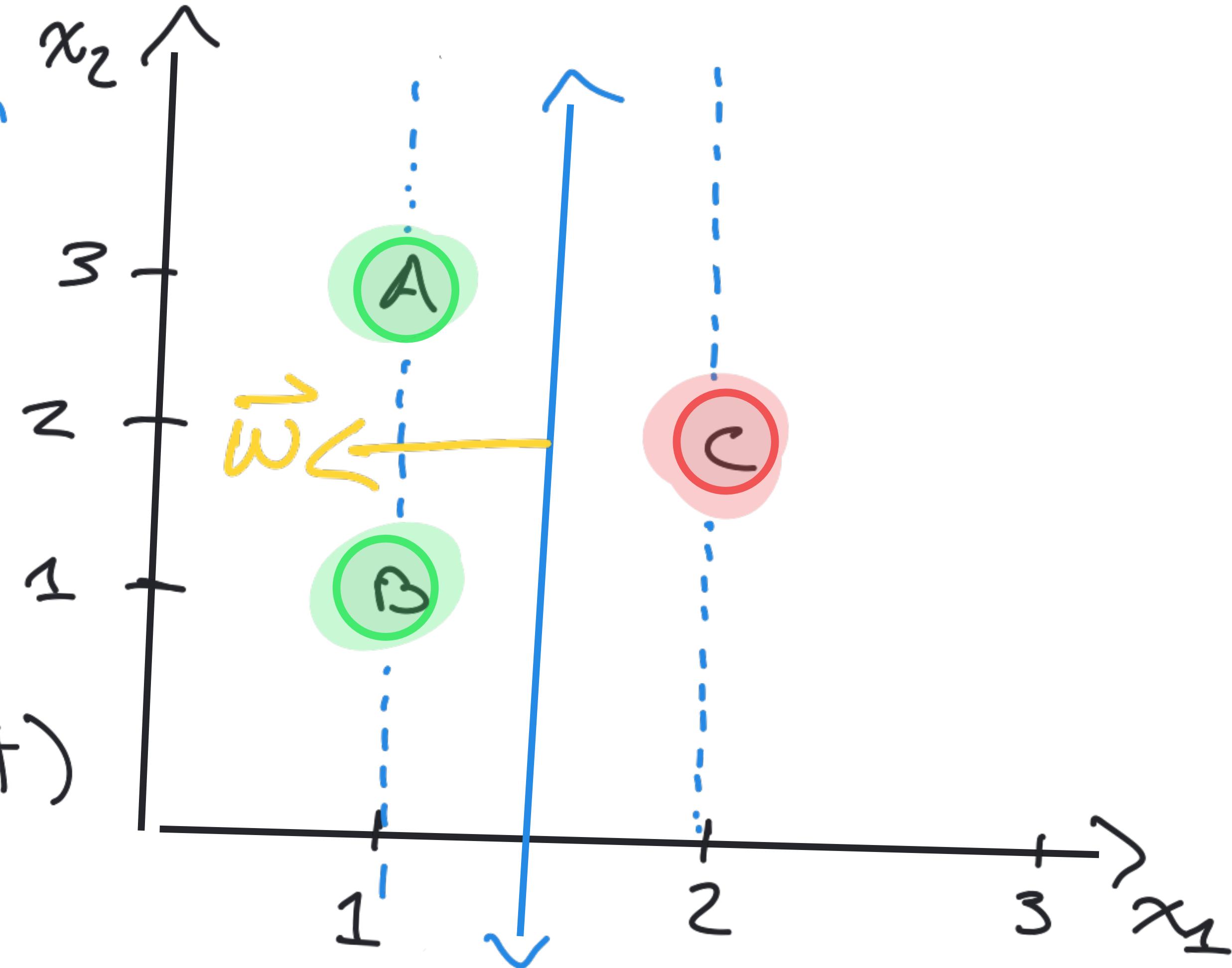
HOW TO DO IT

\vec{w} : normal vector 1
to the decision

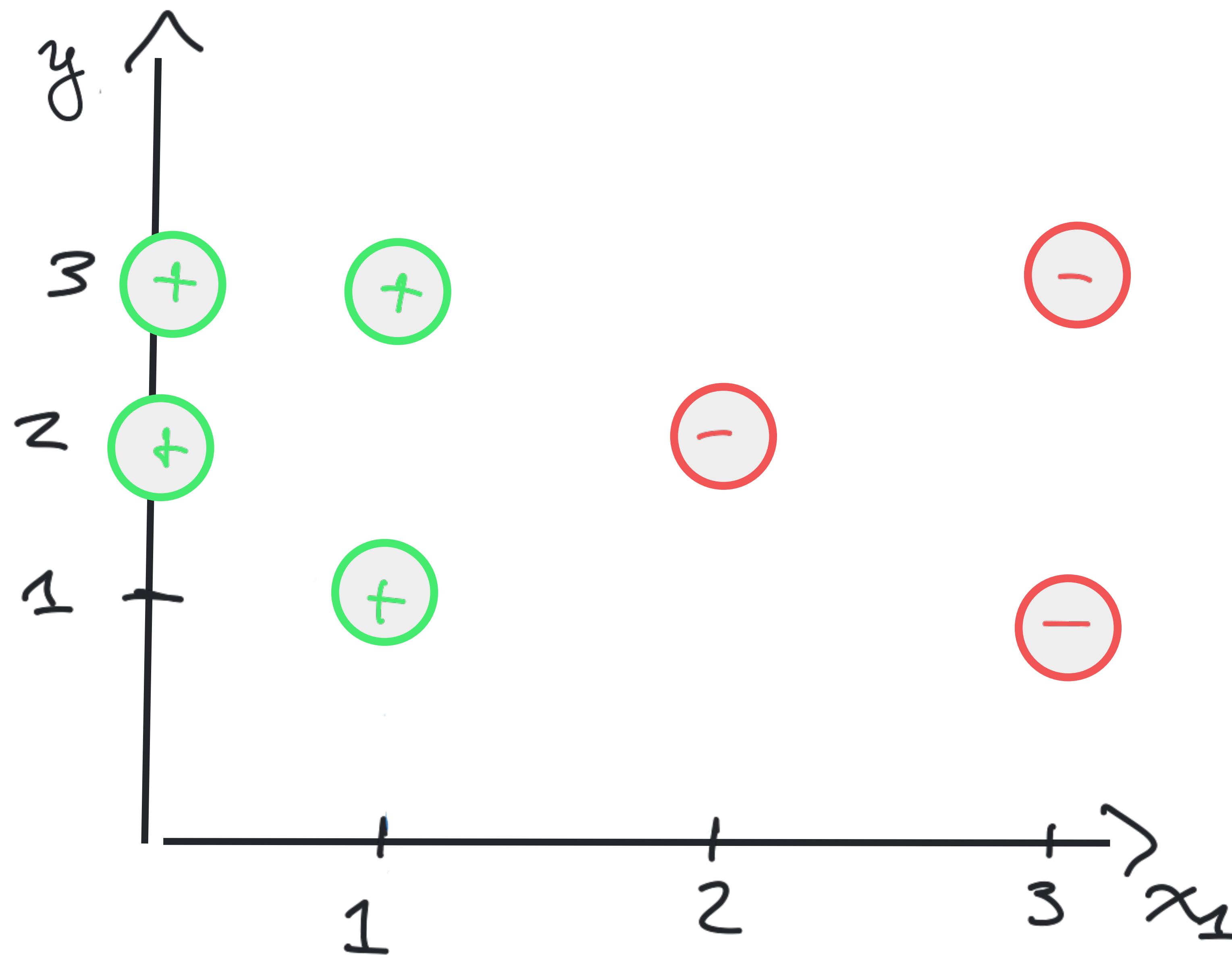
boundary and
points toward

the $+$

b : offset
(a.k.a. y-intercept)

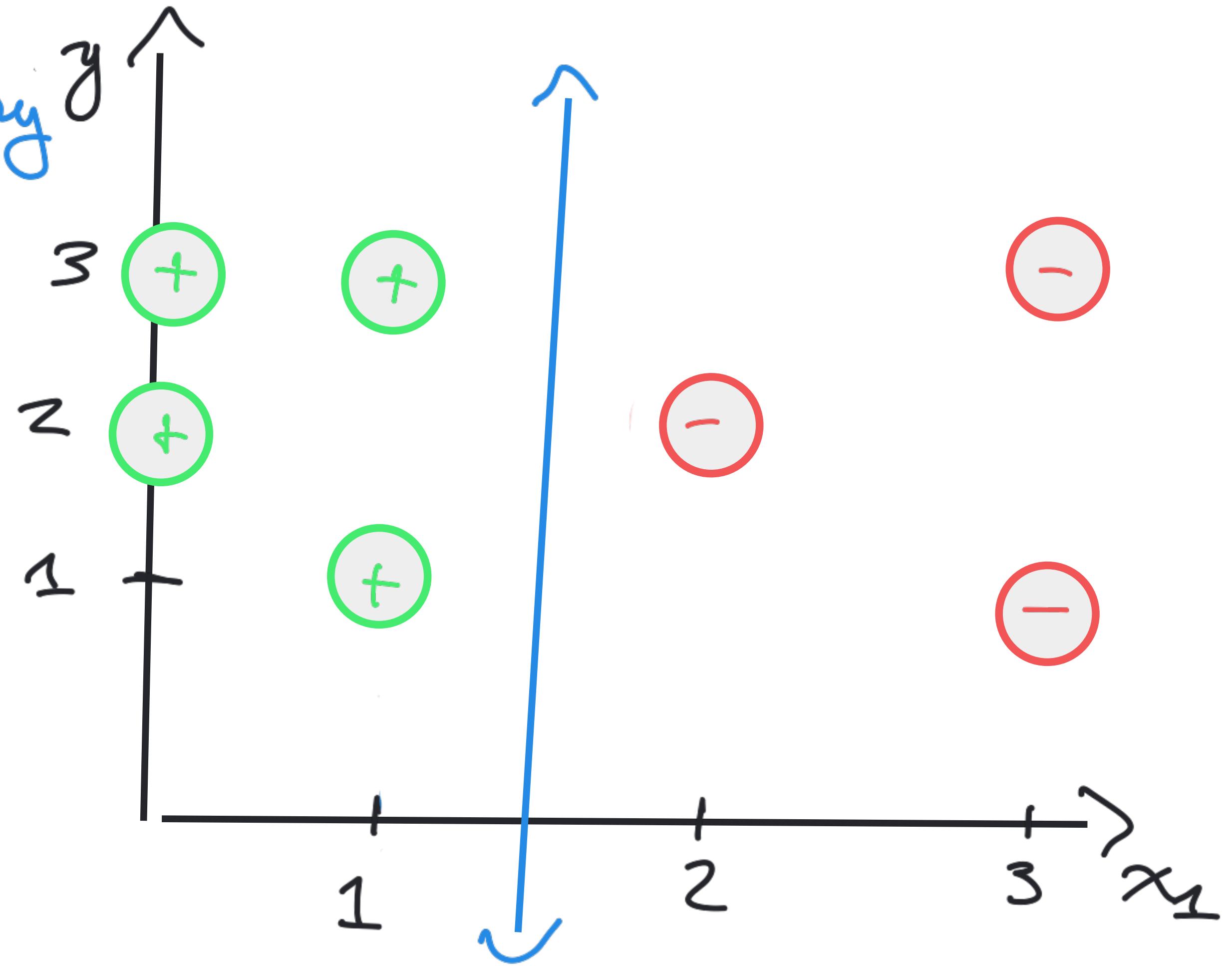


HOW TO DO IT



HOW TO DO IT

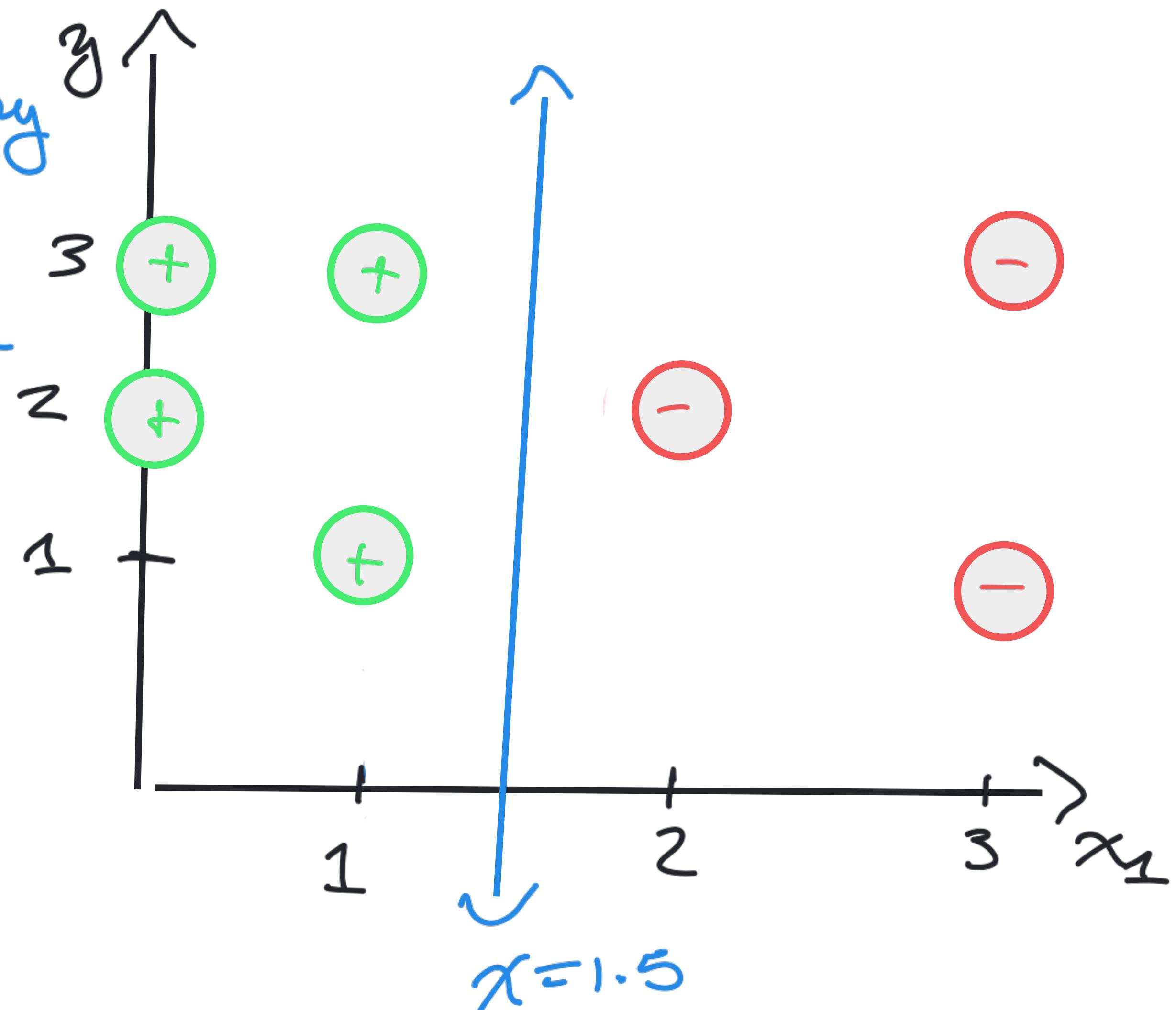
i) Draw decision boundary



HOW TO DO IT

- 1) Draw decision boundary
- 2) Write the equation
for the boundary line

$$x = 1.5$$



HOW TO DO IT

1) Draw decision boundary

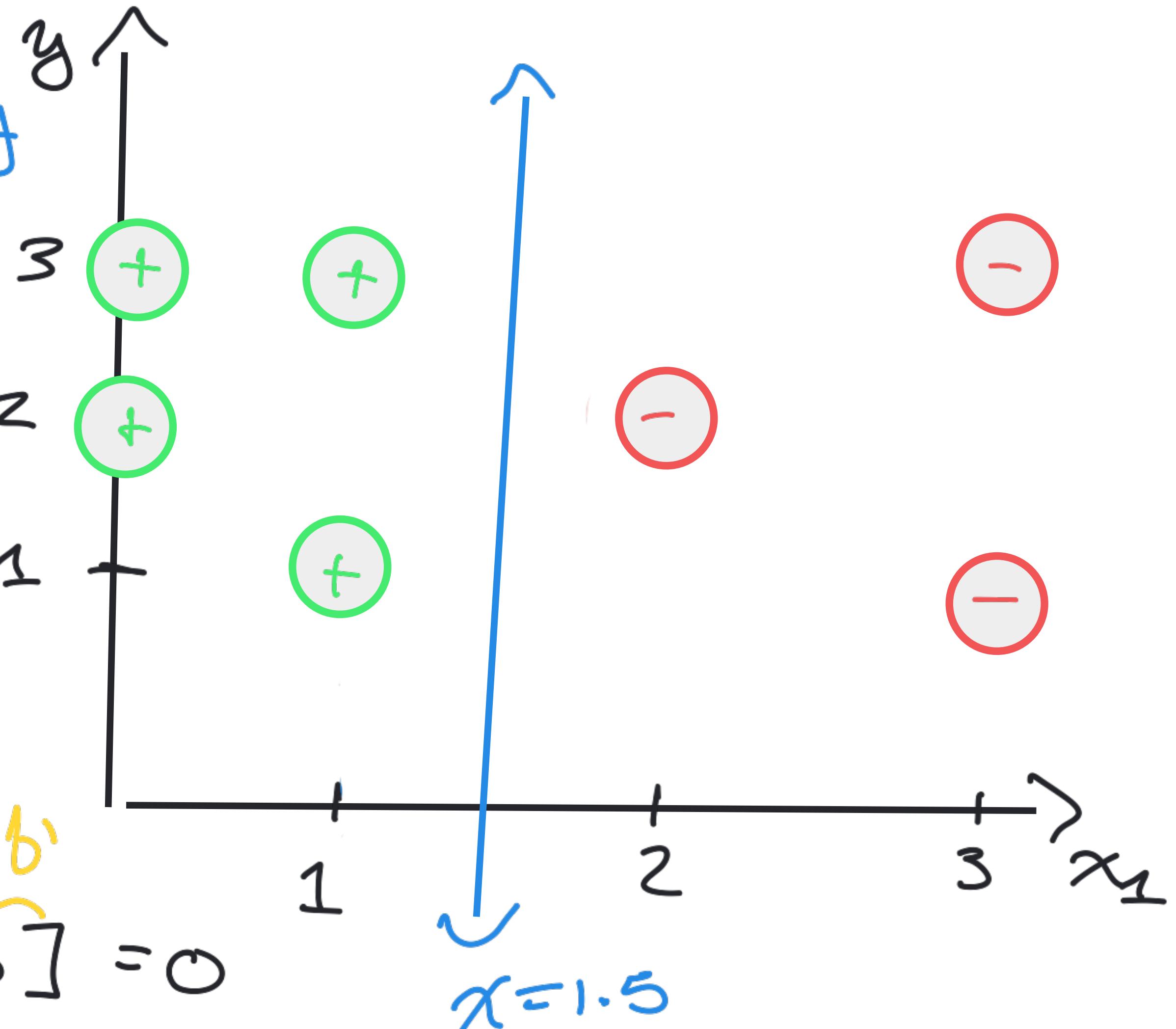
2) Write the equation
for the boundary line

3) Rewrite equation in
the form $\vec{w}\vec{x} + b = 0$

$$(1)x + (0)y = 1.5$$

$$(1)x + (0)y - 1.5 = 0$$

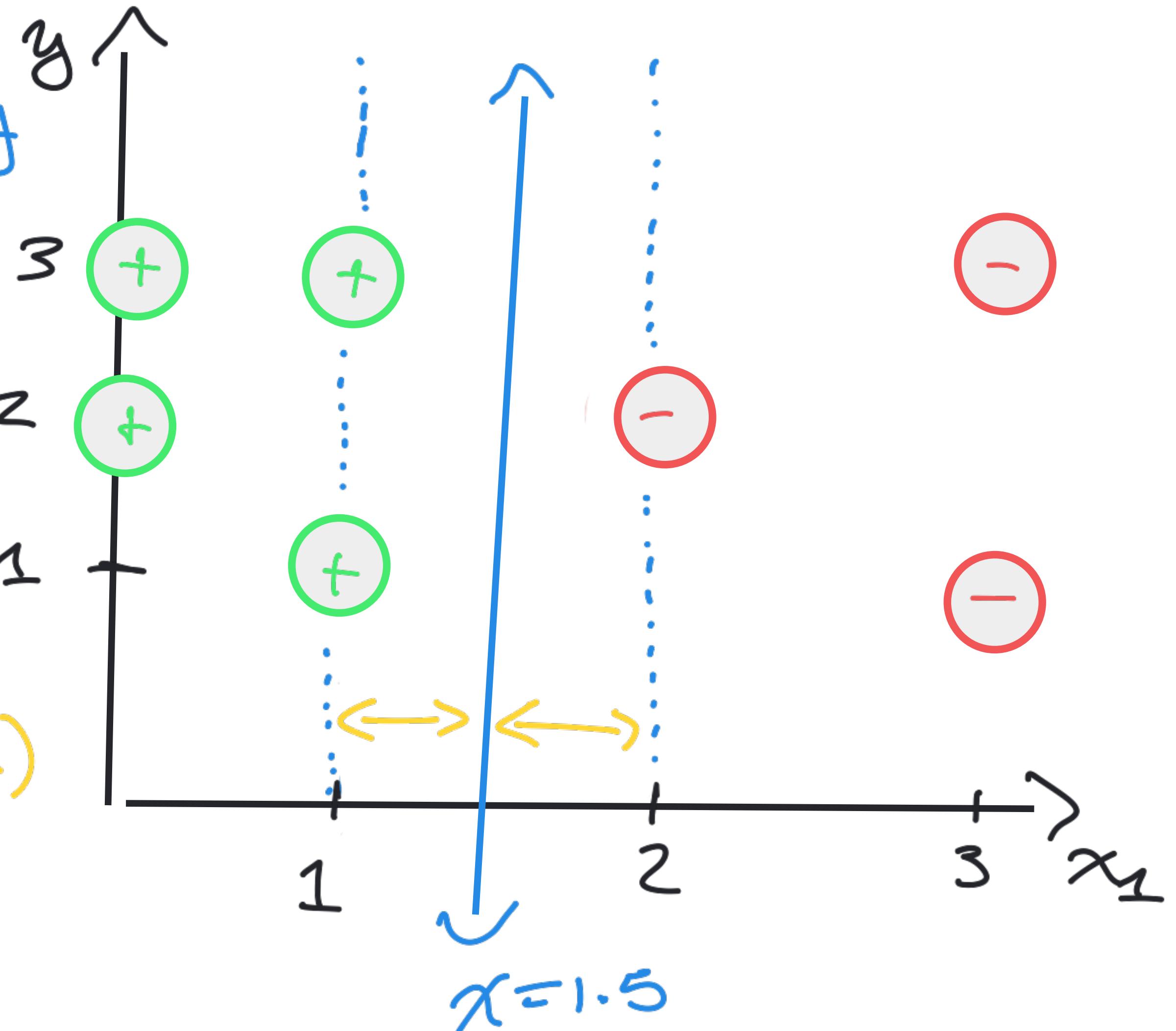
$$\begin{bmatrix} \vec{w} \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} b \\ -1.5 \end{bmatrix} = 0$$



HOW TO DO IT

- 1) Draw decision boundary
- 2) Write the equation for the boundary line
- 3) Rewrite equation in the form $\vec{w} \cdot \vec{x} + b = 0$
- 4) Scale $\vec{w} \cdot \vec{x} + b = 0$
so the marginwidth (m)

$$m = \frac{2}{\|\vec{w}\|}$$



HOW TO DO IT

□ Equation 1: $\vec{\omega} \vec{x} + b = 0$

$$\rightarrow [1 \ 0] \begin{bmatrix} x \\ y \end{bmatrix} - 1.5 = 0 \Rightarrow \vec{\omega}' = [1 \ 0]$$

□ Equation 2: $m = \frac{2}{\|\vec{\omega}\|}$

$$\Rightarrow (1) = \frac{2}{\|\vec{\omega}\|}$$

$$\|\vec{\omega}\| = 2^*$$

Now we know $\|\vec{\omega}\|$ and
that it should point
toward

HOW TO DO IT

□ Equation 1: $\vec{w} \cdot \vec{x} + b = 0$
 $\rightarrow [1 \ 0] \begin{bmatrix} x \\ y \end{bmatrix} - 1.5 = 0 \Rightarrow \vec{w} = [1 \ 0]$

□ Equation 2: $m = \frac{2}{\|\vec{w}\|} \Rightarrow \|\vec{w}\| = 2$

□ Equation 3: gutter constraint
- \forall points: $\text{sign}(\vec{w} \cdot \vec{x} + b) = y_i$ $y_i \rightarrow$ classification
of point x_i

- $t/$ points **on the gutter**:

$$\vec{w} \cdot \vec{x} + b = \pm 1$$

HOW TO DO IT

Apply equation 3 onto point C:

$$[1 \ 0] \begin{bmatrix} 2 \\ z \end{bmatrix} - 1.5 = -1$$

$$= 0.5 \neq -1$$

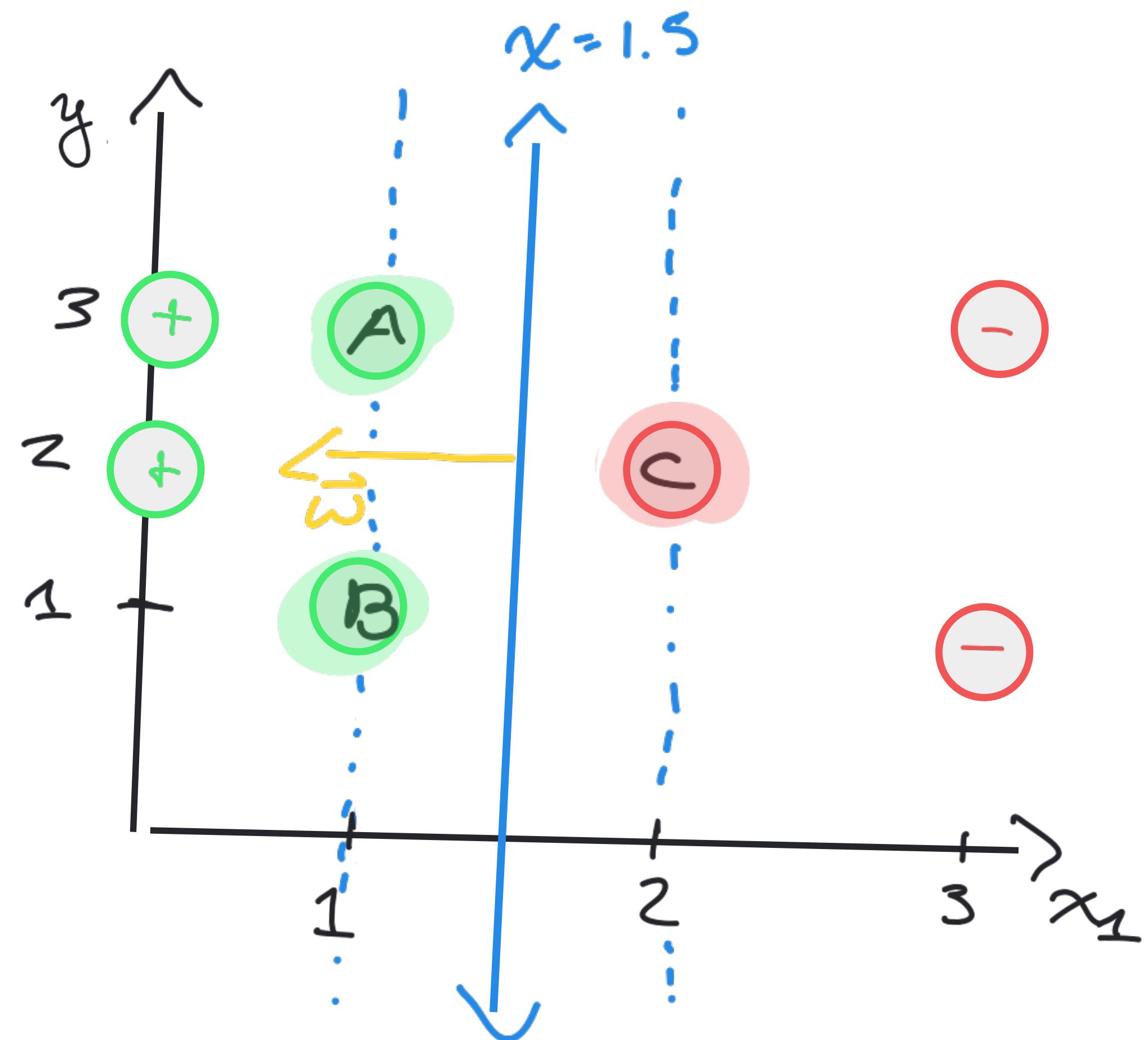
So we need to scale

\vec{w} ' and b'

$$c \cdot ([1 \ 0] \begin{bmatrix} 2 \\ z \end{bmatrix} - 1.5) = -1$$

$$c \cdot (0.5) = -1$$

$$c = -2$$



HOW TO DO IT

Apply equation 3 onto point C:

$$-2([1 \ 0] \begin{bmatrix} 2 \\ z \end{bmatrix} - 1.5) = -1$$

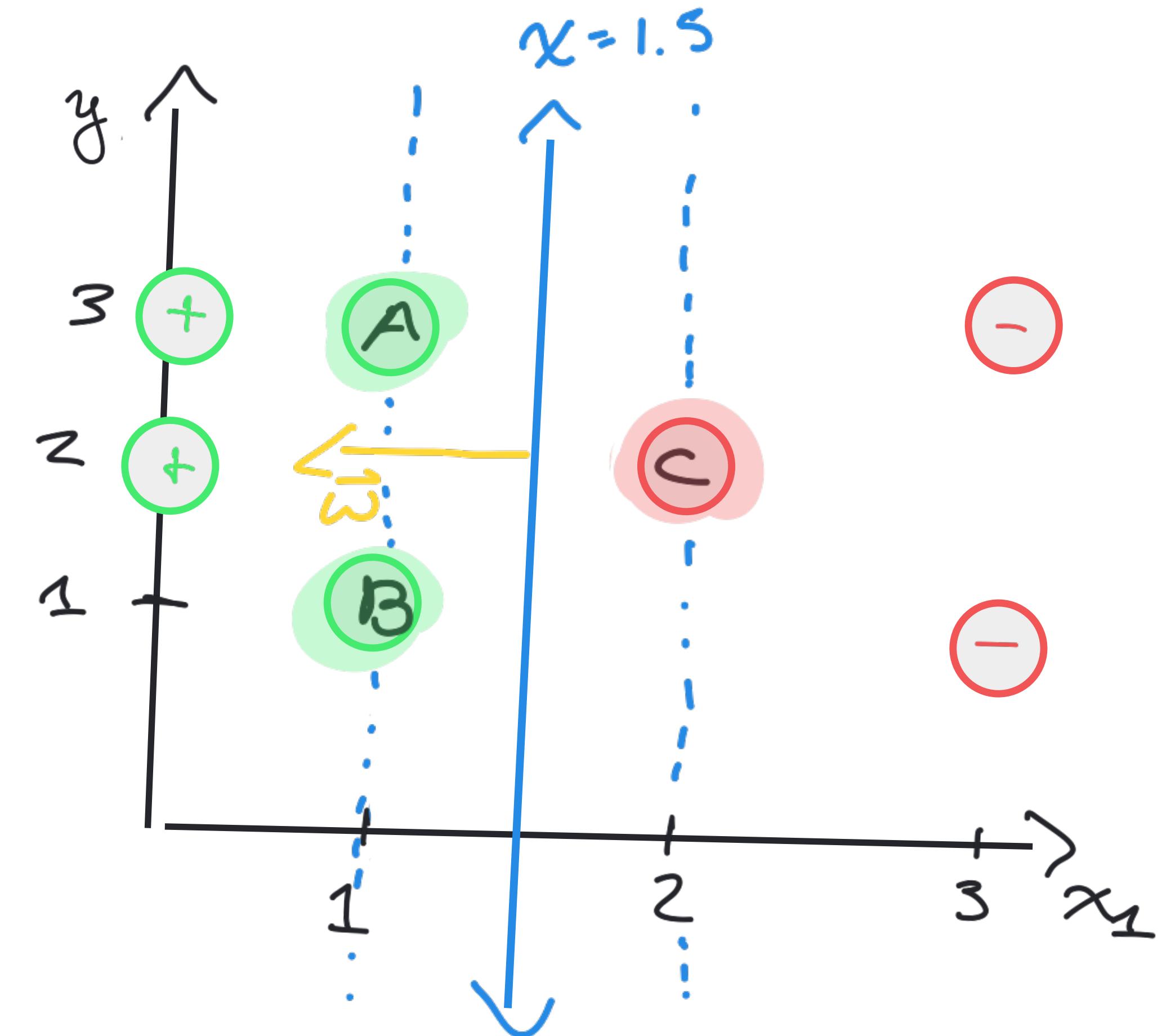
$$= [-2 \ 0] \begin{bmatrix} 2 \\ z \end{bmatrix} + 3 = -1$$

$$= -1 = -1 \quad \checkmark$$

$$\Rightarrow [-2 \ 0] \cdot \vec{x}_i + [3] = y_i$$

$$\vec{w} = [-2, 0]$$

$$b = [3]$$



$\vec{w} = [-2, 0] \leftarrow \star$ This is consistent with our findings from equation 2

HOW TO DO IT

Calculating α values (Lagrange multipliers)

- α : how much a point supports the boundary
- via sequential optimization of the margin
- iteratively adjust α for each point to maximize the margin

HOW TO DO IT

Calculating α values (Lagrange multipliers)

1) For all non-support vectors: $\alpha = 0$

otherwise, point is support vector and
lies on the gutter: $\alpha > 0$

Equation 4

$$2) \sum_{\substack{\text{Support} \\ \text{vector } i}} \alpha_i y_i = 0 \iff \sum_{\substack{+ \text{ support} \\ \text{vectors}}} \alpha_+ = \sum_{\substack{- \text{ support} \\ \text{vectors}}} \alpha_-$$

Equation
5

$$3) \sum_{\substack{\text{Support} \\ \text{vectors } i}} \alpha_i y_i \vec{x}_i = \vec{\omega} \iff \vec{\omega} = \sum_{\substack{+ \text{ support} \\ \text{vectors}}} \alpha_+ \vec{x}_+ - \sum_{\substack{- \text{ support} \\ \text{vectors}}} \alpha_- \vec{x}_-$$

HOW TO DO IT

Apply equation 4 onto points A, B, C, D:

$$\alpha_A + \alpha_B - \alpha_C - \alpha_D = 0$$

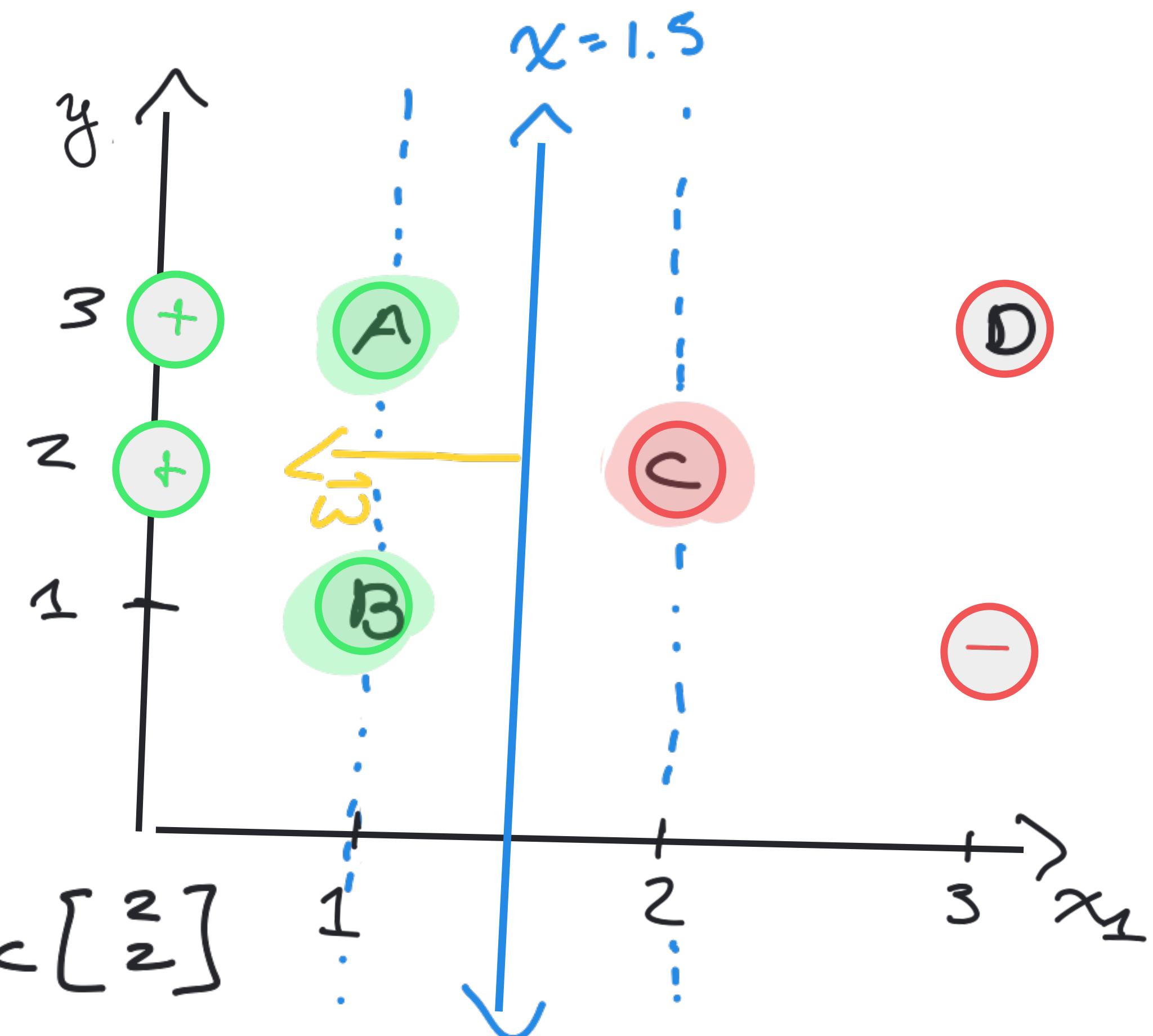
$$\Rightarrow \alpha_A + \alpha_B = \alpha_C + \cancel{\alpha_D}^0$$

Apply equation 5

$$\begin{bmatrix} -2 \\ 0 \end{bmatrix} = \alpha_A \begin{bmatrix} \frac{1}{3} \end{bmatrix} + \alpha_B \begin{bmatrix} \frac{1}{1} \end{bmatrix} - \alpha_C \begin{bmatrix} \frac{2}{2} \end{bmatrix}$$

$$\hookrightarrow -2 = \alpha_A + \alpha_B - 2\alpha_C$$

$$\hookrightarrow 0 = 3\alpha_A + \alpha_B - 2\alpha_C$$



HOW TO DO IT

Now there is a system of ...

- 3 equations
- 3 unknowns

$$0 = \alpha_A + \alpha_B - \alpha_C$$

$$-2 = \alpha_A + \alpha_B - 2\alpha_C$$

$$0 = 3\alpha_A + \alpha_B - 2\alpha_C$$

$$\alpha_A = \alpha_B = 1$$

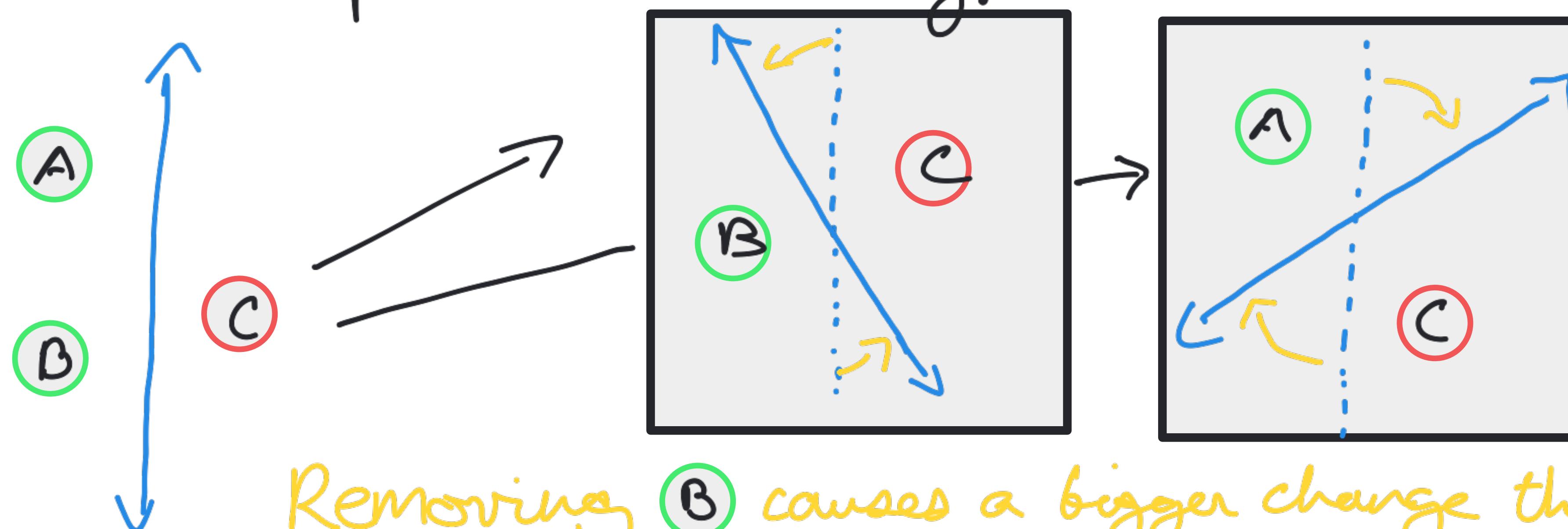
↗ $\alpha_A = \alpha_B$ because A & B are symmetric around C

$$\alpha_C = 2$$

↗ α_C is larger because it supports the boundary by itself

HOW TO DO IT

- What happens to α_s when margins increase?
margin width $\uparrow \rightarrow m \uparrow = \frac{2}{\|\vec{w}\|} \uparrow \Rightarrow \|\vec{w}\| \downarrow = \alpha_s \downarrow$
- What if points are not symmetric?



Removing B causes a bigger change than
removing A $\Rightarrow \alpha_B > \alpha_A$

KERNEL TRICK

- What if the data is not linearly separable?
 - Apply transformations (e.g. polar)
 - Replace the dot product with another Kernel - another function that transforms the space
- current kernel: $k(\vec{u}, \vec{v}) = \vec{u} \cdot \vec{v}$

KERNEL TRICK

□ Current kernel: $K(\vec{u}, \vec{v}) = \vec{u} \cdot \vec{v}$

$$\begin{aligned}\text{class}(\vec{x}_i) &= \text{sign}(\vec{w} \cdot \vec{x}_i + b) \\ &= \text{sign}\left(\left[\sum_j \alpha_j y_j \vec{x}_j\right] \cdot \vec{x}_i + b\right) \\ &= \text{sign}\left(\sum_j \alpha_j y_j (\vec{x}_j \cdot \vec{x}_i) + b\right)\end{aligned}$$

$$\text{class}(\vec{x}_i) = \text{sign}\left(\sum_j \alpha_j y_j \underline{K(\vec{x}_j, \vec{x}_i)} + b\right)$$

□ use kernel to determine whether \vec{x}_i is more similar to \oplus or \ominus

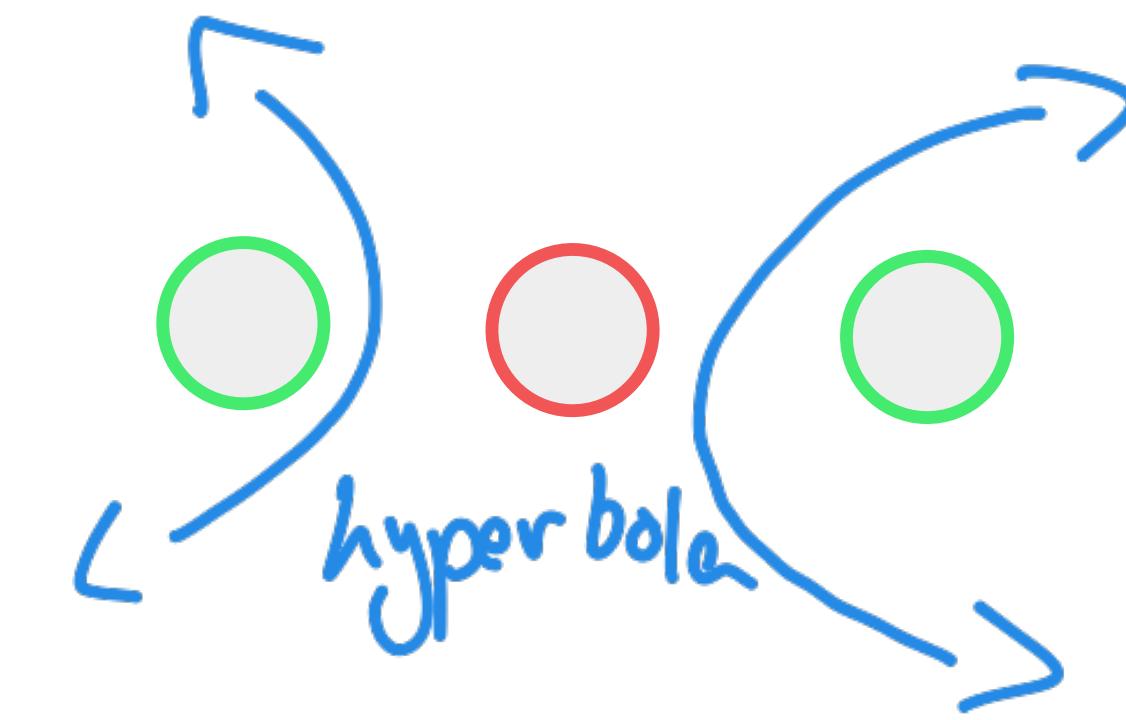
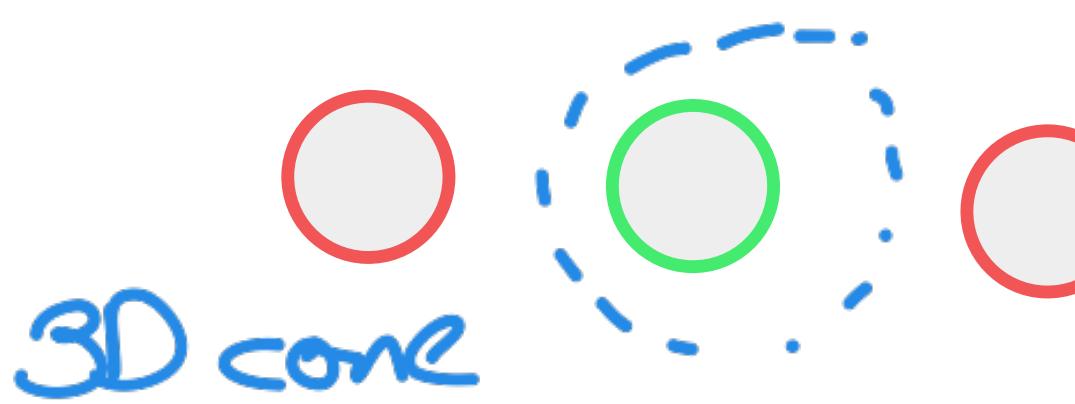
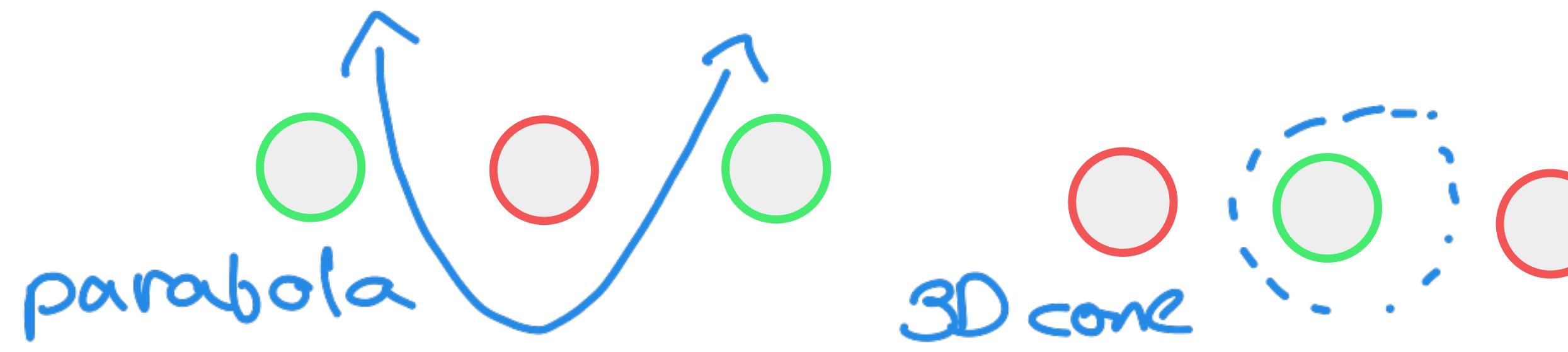
□ A kernel function is a similarity measure

KERNEL TRICK

Common Kernels

linear: $K(\vec{u}, \vec{v}) = \vec{u} \cdot \vec{v} + b$ (line)

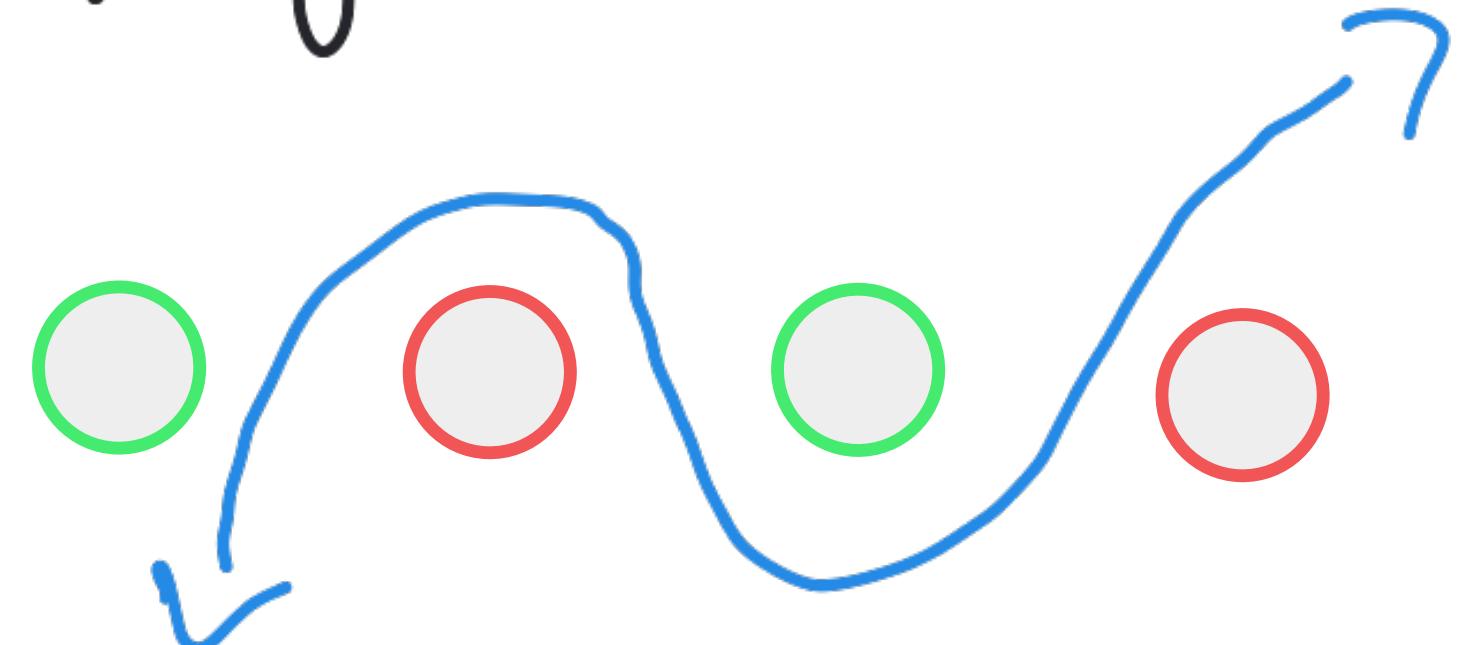
quadratic: $K(\vec{u}, \vec{v}) = (\vec{u} \cdot \vec{v} + b)^2$ (conic section)



KERNEL TRICK

□ Common Kernels

- linear: $K(\vec{u}, \vec{v}) = \vec{u} \cdot \vec{v} + b$ (line)
- quadratic: $K(\vec{u}, \vec{v}) = (\vec{u} \cdot \vec{v} + b)^2$ (conic section)
- polynomial: $K(\vec{u}, \vec{v}) = (\vec{u} \cdot \vec{v} + b)^p$



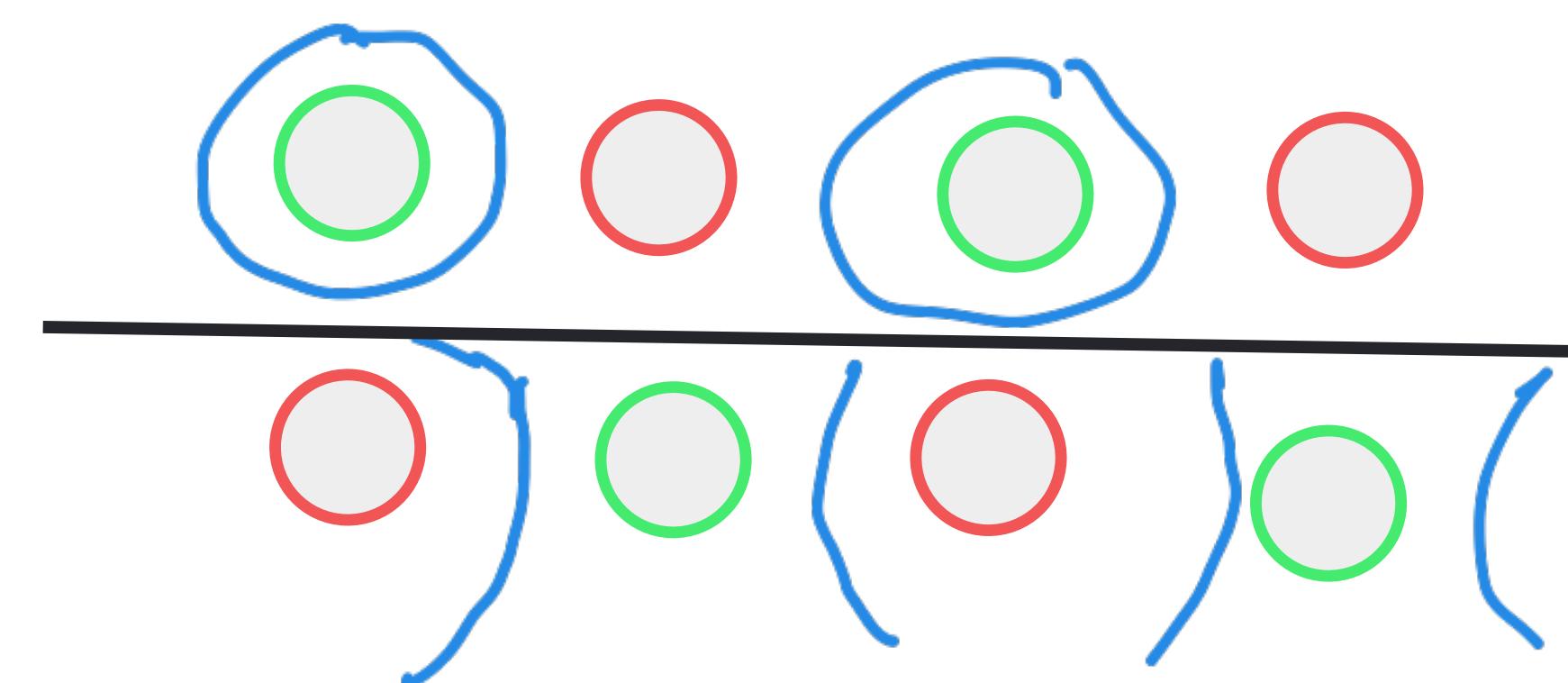
curvedness is indicative
of the degree of the
polynomial (p)

KERNEL TRICK

□ Common Kernels

- linear: $K(\vec{u}, \vec{v}) = \vec{u} \cdot \vec{v} + b$ (line)
- quadratic: $K(\vec{u}, \vec{v}) = (\vec{u} \cdot \vec{v} + b)^2$ (conic section)
- polynomial: $K(\vec{u}, \vec{v}) = (\vec{u} \cdot \vec{v} + b)^p$
- radial basis function: $K(\vec{u}, \vec{v}) = \exp\left(-\frac{1}{\sigma^2} \|\vec{u} - \vec{v}\|^2\right)$
(RBF)

Draws ~circles
around points



can classify
any dataset

SVM SUMMARY

1) For points on the boundary: $\vec{w} \cdot \vec{x} + b = 0$

2) Margin width (m): $m = \frac{2}{\|\vec{w}\|}$

3) Gutter constraint: $\vec{w} \cdot \vec{x} + b = \pm 1$

Points not on gutter: $\text{sign}(\vec{w} \cdot \vec{x} + b) = y$

4) $\sum_{\substack{\text{support} \\ \text{vector } i}} \alpha_i \cdot y_i = 0 \iff \sum_{\substack{+ \text{ support} \\ \text{vector}}} \alpha_+ = \sum_{\substack{- \text{ support} \\ \text{vector}}} \alpha_-$

5) $\vec{w} = \sum_{\substack{\text{support} \\ \text{vector } i}} \alpha_i y_i \vec{x}_i \iff \vec{w} = \sum_{\substack{+ \text{ support} \\ \text{vector}}} \alpha_+ \vec{x}_+ - \sum_{\substack{- \text{ support} \\ \text{vector}}} \alpha_- \vec{x}_-$