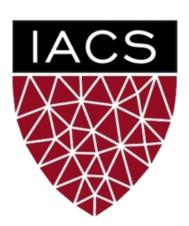
### Lecture #20: Variational Autoencoders

AM 207: Advanced Scientific Computing

Stochastic Methods for Data Analysis, Inference and Optimization

Fall, 2020









# Outline

- 1. Applications of generative models
- 2. Inference for deep generative models: VAEs

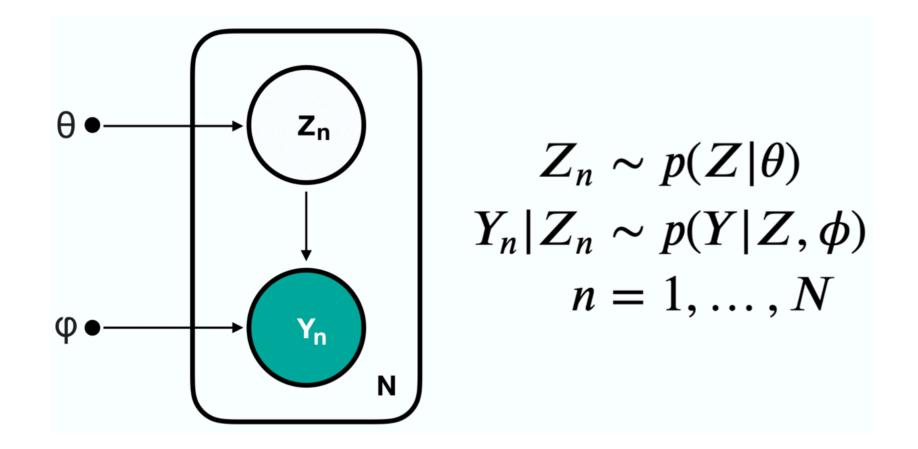


Applications of generative models



### **Review of Latent Variable Models**

Recall that models that include an observed variable Y and at least one unobserved variable Z are called *latent variable models*. In general, our model can allow Y and Z to interact in many different ways. Earlier this semester, we studied models with one type of interaction:





## **Factor Analysis Models**

In Lectures #9 and #10, we concentrated on Gaussian Mixutre Models. But in Lecture #9, we introduced *factor analysis models*, where we posit that the observed data Y with many measurements is generated by a small set of unobserved factors Z:

$$Z_n \sim \mathcal{N}(0, I),$$
  
 $Y_n | Z_n \sim \mathcal{N}(f_{\mu,\Sigma}(Z_n), \Phi),$ 

where  $f_{\mu,\Sigma}$  is a **linear function** of  $Z_n$ , in particular,  $f_{\mu,\Sigma}(Z_n) = \mu + \Lambda Z_n$ ;  $n = 1, \ldots, N$ ,  $Z_n \in \mathbb{R}^{D'}$  and  $Y_n \in \mathbb{R}^D$ . We typically assume that D' is much smaller than D.

### **Applications**

Factor analysis models are useful for biomedical data, where we typically measure a large number of characteristics of a patient (e.g. blood pressure, heart rate, etc), but these characteristics are all generated by a small list of health factors (e.g. diabetes, cancer, hypertension etc). Building a good model means we may be able to infer the list of health factors of a patient from their observed measurements.



### **Motivation for Generative Models**

The factor analysis model:

$$Z_n \sim \mathcal{N}(0, I),$$
  
 $Y_n | Z_n \sim \mathcal{N}(f_{u,\Sigma}(Z_n), \Phi),$ 

where  $f_{\mu,\Sigma}$  is a **linear function** of  $Z_n$  with parameters  $\mu, \Sigma$ .

This is an example of a *generative model*, that is, after learning the parameters  $\mu$ ,  $\Sigma$  of f, we can **generate** synthetic data by sampling  $Z_n \sim \mathcal{N}(0, I)$  and then generating a synthetic observation by sampling  $Y_n | Z_n \sim \mathcal{N}(f_{\mu,\Sigma}(Z_n), \Phi)$ .

In many applications, like health care, where data collection is an financially and time-wise costly operation, synthetic data from a generative model can be extremely useful!

Generative models can also be used to perform imputation of missing data (i.e. fill-in missing covariates of observed data).



### **Motivation for Deep Generative Models**

The problem with the factor analysis model is that marginal distribution of the data Y is a Gaussian distribution, since Y is the result of a Gaussian distribution  $\mathcal{N}(0,I)$  transformed linearly by  $f_{\mu,\Sigma}$ . But in practice, the distribution of real data is complex! That is, we need **nonlinear transformations**.

A deep generative model can be defined as follows:

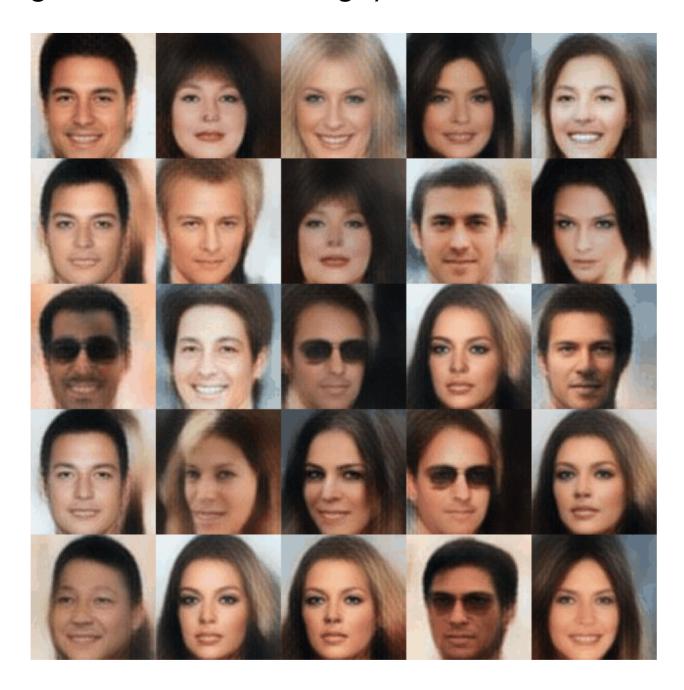
$$Z_n \sim \mathcal{N}(0, I),$$
  
 $Y_n | Z_n \sim \mathcal{N}(f_{\mathbf{W}}(Z_n), \Phi),$ 

where f is a **nonlinear function** of  $Z_n$ , parametrized by a **neural network** with weights W. The deep generative model we will study today, **variational autoencoders**, will have exactly this generative model.



## Generating Data with Variational Autoencoders

For example, if we train a deep generative model (a VAE) to capture the distribution of a set of image data consisting of celebrity faces, we can use this generative model to generate realistic looking synthetic faces:





Inference for deep generative models: VAEs



# Expectation Maximization: Estimating the MLE for Latent Variable Models

Given a deep latent variable model  $p(Y, Z|W) = p(Y|f_W(Z))p(Z)$ , we are interested computing the MLE of parameters W, i.e. the parameters that maximizes the likelihood of the observed data:

$$\mathbf{W}_{\text{MLE}} = \underset{\mathbf{W}}{\operatorname{argmax}} \ \mathcal{E}(\mathbf{W})$$

$$= \underset{\mathbf{W}}{\operatorname{argmax}} \ \log \prod_{n=1}^{N} \int_{\Omega_{Z}} p(y_{n}, z_{n} | \mathbf{W}) dz$$

$$= \underset{\mathbf{W}}{\operatorname{argmax}} \ \log \prod_{n=1}^{N} \int_{\Omega_{Z}} p(y_{n} | f_{\mathbf{W}}(z_{n})) p(z_{n}) dz$$

where  $\Omega_Z$  is the domain of Z.

In the case of factor analysis models and mixture of Gaussian models, we used Expectation Maximization in order to maximize a lower bound of the observed data log-likelihood, the ELBO. How will this work for deep latent variable models?



### MAXIMUM LIKELIHOOD ESTIMATION FOR DEEP GENERATIVE MODELS



Since we don't describe  $\mathbf{x}_{a_1}$  we can only Machine described data constituted  $\mathbf{M}_{\text{max}} = \mathbf{x}_{\text{max}}^{\text{max}} \mathbf{x}_{\text{max}}^{\text{max}} + \mathbf{y}_{\text{max}}^{\text{max}} \mathbf{x}_{\text{max}}^{\text{max}} \mathbf{x}_{\text{max}}$ 

$$\frac{\mathsf{THE} \ \mathsf{PROBLEM}:}{\mathsf{PROBLEM}:} \quad \nabla_{\mathsf{NL}} \overset{\mathsf{T}}{\leftarrow} \log \left[ \underset{\mathsf{Plan}}{\overset{\mathsf{Plan}}{\Vdash}} \left[ P_{\mathsf{NL}} (q_{\mathsf{n}} \mid \mathsf{E}_{\mathsf{n}}) \right] = \sum_{\mathsf{n}} \frac{\mathsf{Ne} \left[ \underset{\mathsf{Plan}}{\overset{\mathsf{Plan}}{\Vdash}} \left[ P_{\mathsf{NL}} (q_{\mathsf{n}} \mid \mathsf{E}_{\mathsf{n}}) \right] \right]}{\underset{\mathsf{Plan}}{\overset{\mathsf{Plan}}{\Vdash}} \left[ P_{\mathsf{NL}} (q_{\mathsf{n}} \mid \mathsf{E}_{\mathsf{n}}) \right]} \right] \stackrel{\mathsf{MC}}{\to} \mathsf{ESTRAME}$$

### MAXIMIZING THE ELBO INSTEAD

 $m_{N}^{2}(\log \sum_{i=1}^{N} p_{N}(y_{i}) \ge m_{i}^{2}x$  ELSO(W,q)

INSTERD OF MAXIMITING THE OBSERVED DATA LOG-LIKEUHOOD, WE MAXIMITE THE ELSO

### MAXIMITING THE ELBO

IN EXPECTATION MAXIMITATION:

M STEP: Max ELBO (W, g\*) CAN BE DONE BY GRADIENT DESCENT

$$\nabla_{M} \sum_{n=1}^{N} \underbrace{\mathbb{E}}_{q(kn)} \left[ \log \frac{p_{M}(y_n \mid k_n)}{q(k_n)} \frac{p(k_n)}{q(k_n)} \right] = \sum_{n=1}^{N} \underbrace{\mathbb{E}}_{q(kn)} \left[ \nabla_{M} \log \frac{p_{M}(y_n \mid k_n)}{q(k_n)} \frac{p(k_n)}{q(k_n)} \right]$$

E STEP: Max ELBO (N\*, q.) HAS A SOLUTION (LECTURE # q.)

q! = arg max ELBO(W\*, q) = pw+ (2.1 yx)

THE PROBLEM: IF  $y_n = nn$ , forward  $(2*, N^n) + E$ ,  $p_{N^n} (2*, iy_n)$  is intractable to compute in closed form, unlike the case of Gaussian motivies. AND FACTOR ANALYSIS.

### INNOVATION #4: VARIATIONAL INFERENCE FOR POSTERIOR PW(2-14)

ELBO (W\*, 4)

THE PROBLEM: IF N IS HUGE THEN WE NEED TO KNU VI A HUGE NUMISER OF
TIMES! COMPUTATIONALLY INTRACTABLE!

### INNOVATION #2: AMORTINED INFERENCE

IDEA: IF WE SAW THAT Y==1 AND M=1.01, 62=0.5

THEN IF Y== y=, WE WOULD EXPECT P(3=1y=) = p(2=1y=),

HENCE 6h=61, M=2M=.

THAT IS, WE SHOULD BE ABLE TO PREDICT  $\mathcal{M}_*$ ,  $Z_n$  of  $P(z_n | y_n)$  using  $y_n$ , i.e. we learn a purcton  $\sum_{j=1}^n (y_j) - \mathcal{M}_{j_n}(y_n)$ ,  $Z_n(y_n) \le r$ .  $V^{\phi} = \arg \min_{j=1}^n \sum_{k \in \mathbb{N}} \left[ N(\mu_k(y_n), Z_{p_k}(y_n)) \mid P_{p_k^{(\phi)}}(z_n | y_n) \right]$ 

$$\Rightarrow \text{grawax} \ \sum_{i} \frac{\hat{\sigma}^{i}(s^{s})}{\mathbb{E}} \left[ \ \frac{\hat{\sigma}^{i}(s^{s})}{\hat{\sigma}^{i}(s^{s},\hat{\eta}^{s})} \right]$$

GRADIENT DESCENT: MAXIMITING THE ELBO WITH RESPECT TO V

$$\begin{split} \nabla_{r} & \text{ ELDO } \left( \mathbf{W}^{s}, \mathbf{V} \right) = \nabla_{r} \sum_{\mathbf{x}} \sum_{\mathbf{x} \in \mathcal{X}_{t}} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{p_{r} \left( \mathbf{x}_{x} \right)} \right] \\ &= \sum_{\mathbf{x}} \nabla_{\mathbf{x}} \underbrace{\mathbb{E}}_{r = \mathbf{y} \left( \mathbf{y}_{x} \right)} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ &= \sum_{\mathbf{x}} \underbrace{\mathbb{E}}_{r = \mathbf{y} \left( \mathbf{y}_{x} \right)} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ &= \sum_{\mathbf{x}} \underbrace{\mathbb{E}}_{r = \mathbf{y} \left( \mathbf{y}_{x} \right)} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ &= \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ &= \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ &= \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ &= \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ &= \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ &= \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ &= \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x}, \mathbf{y}_{x} \right)} \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ + \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ + \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x}, \mathbf{y}_{x} \right)}{q_{r} \left( \mathbf{x}_{x}, \mathbf{y}_{x} \right)} \right] \\ + \underbrace{\mathbb{E}}_{r} \left[ \frac{p_{r}$$

### NNOVATION #2: JOINT TRAINING

RATHER THAN COORDINATE ASCENT OVER W AND V HERATIVELY, WE PERFORM GRADIENT DESCENT OVER W  $\frac{1}{2}$  V SIMULTANEOUSLY!

 $\begin{array}{l} & \begin{array}{l} & \\ \nabla_{W_{i}V} \; \mathsf{ELBO}(\; \omega_{i}, \, q_{V}) = \end{array} & \begin{array}{l} \nabla_{W_{i}V} \; \sum_{\boldsymbol{x}} \; \underbrace{\mathbb{E}}_{\boldsymbol{x} \in X_{i}^{\mathsf{D}}(q_{i})} + \mathcal{U}_{\boldsymbol{x}}(\boldsymbol{y}_{u}) + \mathcal{U}_{\boldsymbol{x}}(\boldsymbol{y}_{u})} \; \boldsymbol{y}_{\boldsymbol{x}}) \\ & & \\ & & \\ & & \\ \end{array} \\ & \begin{array}{l} P_{W_{i}} \; (\boldsymbol{x} \geq \boldsymbol{x}^{\mathsf{D}}(q_{i}) + \mathcal{U}_{\boldsymbol{x}}(\boldsymbol{y}_{u}) + \mathcal{U}_{\boldsymbol{x}}(\boldsymbol{y}_{u}) \\ \end{array} \\ & \\ & & \\ & P_{W_{i}} \; (\boldsymbol{x} \geq \boldsymbol{x}^{\mathsf{D}}(q_{i}) + \mathcal{U}_{\boldsymbol{x}}(\boldsymbol{y}_{u}) + \mathcal{U}_{\boldsymbol{x}}(\boldsymbol{y}_{u}) \\ \end{array} \\ \end{array}$ 

$$=\sum_{n}\mathbb{E}\left[\begin{array}{c}\nabla_{w_{n}v}\frac{P_{N}\left(\varepsilon\;\Sigma^{N}\left(g_{n}\right)+\mathcal{M}_{v}\left(g_{n}\right),\;g_{n}\right)}{q_{n}\left(\varepsilon\;\Sigma^{N}\left(g_{n}\right)+\mathcal{M}_{v}\left(g_{n}\right)\right)}\right]$$
Autograp

### VARIATIONAL AUTOENCODER CVAE)

A VARIATIONAL AUTOENCOPER IS BOTH A MODEL AND AN INFERENCE METHOD GENERATIVE MODEL:

$$\xi_N \sim p(\xi_N) = N(0, 1)$$
  
 $\xi_N = f_N(\xi_N) + \varepsilon$ ,  $\varepsilon \sim N(0, \varepsilon' 1)$   $\xi$   $f_N$ 

TRAINING OBJECTIVE: Max ELBO (W, Qv)

$$W^{a}, \, V^{a} = \underset{W, \, V}{\text{are max}} \, \, \sum_{s} \underbrace{\mathbb{E}_{\sim N(s, \Sigma)} \left[ \underbrace{\frac{P_{N}\left( \in \Sigma^{V_{s}}(\boldsymbol{q}_{s}) + \mathcal{M}_{v}\left(\boldsymbol{q}_{s}\right), \, \boldsymbol{q}_{s}\right)}{2\sqrt{\left( \in \Sigma^{V_{s}}(\boldsymbol{q}_{s}) + \mathcal{M}_{v}\left(\boldsymbol{q}_{s}\right), \, \boldsymbol{q}_{s}\right)}} \right]$$



### DIFFERENT PRESENTATIONS OF THE ELBO-

I. JOINT PLUS ENTROPY

ELBO (W, 
$$q_v$$
) =  $\sum_{q_v} \left[ \log \frac{p_v(q_v, z_n)}{q_v(z_n)} \right] = \sum_{q_v} \left[ \log p_u(q_v, z_n) - \frac{p_v}{q_v} [\log q_v] \right]$   
=  $\sum_{q_v} \left[ \frac{1}{q_v} \log p_u(q_v, z_n) + H[q_v] \right]$   
Eutropy of

II. EXPECTED LIKELIHOOD MINUS KL

ELBO (W, 
$$q_v$$
) =  $\sum_{q_v} \begin{bmatrix} \log \frac{P_u(q_v + 2v)}{q_v(2v)} \end{bmatrix} = \sum_{n} \begin{bmatrix} \mathbb{E} \left[ \log \frac{P_u(q_v + 2v)}{q_v(2v)} \right] \end{bmatrix}$   
=  $\sum_{n} \begin{bmatrix} \mathbb{E} \left[ \log \frac{q_v(2v)}{q_v(2v)} \right] \end{bmatrix} = \sum_{n} \begin{bmatrix} \mathbb{E} \left[ \log \frac{q_v(2v)}{q_v(2v)} \right] \end{bmatrix}$ 

II. OGSERVED DATA LOG-LIKELIHOOD MINUS KL

$$\mathsf{ELSO}\left(\mathcal{W}, q_{\mathcal{V}}\right) = \sum_{k} \bigsqcup_{q_{\mathcal{V}}} \left[\log \frac{\tilde{P}_{\mathcal{V}}\left(\tilde{y}_{\mathcal{X}_{\mathcal{V}}} \right) e_{\mathcal{V}}}{q_{\mathcal{V}}\left(\tilde{z}_{\mathcal{X}}\right)}\right] = \sum_{k} \bigsqcup_{q_{\mathcal{V}}} \left[\log \frac{\tilde{P}_{\mathcal{W}}\left(\tilde{y}_{\mathcal{X}_{\mathcal{V}}} \right) \tilde{P}_{\mathcal{W}}\left(\tilde{y}_{\mathcal{Y}}\right)}{q_{\mathcal{V}}\left(\tilde{z}_{\mathcal{X}_{\mathcal{V}}}\right) \tilde{P}_{\mathcal{W}}\left(\tilde{y}_{\mathcal{Y}_{\mathcal{V}}}\right)}\right]$$

$$= \sum_{n} \left[ \log \frac{b^{n}(x^{n}|A^{n})}{b^{n}(y^{n})} \cdot b^{n}(h^{n}) \right]$$

# Generating Data with Variational Autoencoders

For example, if we train a deep generative model (a VAE) to capture the distribution of a set of image data consisting of celebrity faces, we can use this generative model to generate realistic looking synthetic faces:

