

Python Script for Grim's Heart:

Import numpy as np

From scipy.integrate import solve_ivp

Import matplotlib.pyplot as plt # Optional for plotting

Def closure_gap(G):

"""Compute $\Delta = \det(G) - \text{tr}(G)^2 / 4$ """

Det_G = np.linalg.det(G)

Tr_G = np.trace(G)

Return $\det_G - (\text{tr_G}^2) / 4$

Def commutator(G, J):

"""Compute $[G, J] = GJ - JG$ """

Return $G @ J - J @ G$

Def dynamical_law(t, flat_G, J):

"""Flattened version for solve_ivp: $\dot{G} = \Delta [G, J] - 2 \Delta^2 G$ """

G = flat_G.reshape(2, 2)

Delta = closure_gap(G)

dG = $\Delta * \text{commutator}(G, J) - 2 * (\Delta^2) * G$

return dG.flatten()

J = np.array([[0, -1], [1, 0]]) # Rotation matrix

Def simulate_bulge(initial_G):

"""Simulate one trajectory until $\Delta > -1e-10$, return final eigenvalue ratio"""

```
Def event(t, y): # Termination event
```

```
    G = y.reshape(2, 2)
```

```
    Return closure_gap(G) + 1e-10 # Halt when Delta >= -1e-10
```

```
Event.terminal = True
```

```
Event.direction = 1 # Only from below
```

```
Sol = solve_ivp(dynamical_law, [0, 10], initial_G.flatten(), args=(J,),
```

```
                Method='DOP853', rtol=1e-8, atol=1e-10, events=event)
```

```
If sol.status == 1: # Event triggered
```

```
    Final_G = sol.y[:, -1].reshape(2, 2)
```

```
    Eigvals = np.linalg.eigvals(Final_G)
```

```
    Abs_eig = np.abs(eigvals)
```

```
    Ratio = np.max(abs_eig) / np.min(abs_eig) if np.min(abs_eig) > 0 else np.inf
```

```
    Return ratio
```

```
Return np.nan # Failed sim
```

```
# Run over 1000 random initial conditions (Delta_0 < 0)
```

```
N_runs = 1000
```

```
Ratios = []
```

```
For _ in range(n_runs):
```

```
    G0 = np.random.uniform(-1, 1, (2, 2))
```

```
    If closure_gap(G0) < 0: # Only valid starts
```

```
        Ratio = simulate_bulge(G0)
```

```
    If not np.isnan(ratio):
```

```
        Ratios.append(ratio)
```

```

Mean_ratio = np.mean(ratios)

Std_ratio = np.std(ratios)

Print(f"Mean bulge ratio over {len(ratios)} runs: {mean_ratio:.4f} ± {std_ratio:.0e}")

# Optional: Plot a single trajectory's Delta evolution

G_example = np.array([[0.5, -0.2], [0.1, 0.3]]) # Example with Delta < 0

Sol_example = solve_ivp(dynamical_law, [0, 5], G_example.flatten(), args=(J,),
dense_output=True)

T = np.linspace(0, 5, 100)

Deltas = [closure_gap(sol_example.sol(ti).reshape(2,2)) for ti in t]

Plt.plot(t, deltas)

Plt.xlabel('Time')

Plt.ylabel('Delta')

Plt.title('Approach to Instability Threshold')

Plt.show()

```