

Python Script for Grim's Heart:

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Import numpy as np  
From scipy.integrate import solve_ivp  
Import matplotlib.pyplot as plt # Optional for plotting
```

Def closure\_gap(G):

```
    """Compute Delta = det(G) – tr(G)^2 / 4"""  
    Det_G = np.linalg.det(G)  
    Tr_G = np.trace(G)  
    Return det_G – (tr_G ** 2) / 4
```

Def commutator(G, J):

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    """Compute [G, J] = G J – J G"""  
    Return G @ J – J @ G
```

Def dynamical\_law(t, flat\_G, J):

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    """Flattened version for solve_ivp: dot{G} = Delta [G,J] – 2 Delta^2 G"""  
    G = flat_G.reshape(2, 2)  
    Delta = closure_gap(G)  
    dG = Delta * commutator(G, J) – 2 * (Delta ** 2) * G  
    return dG.flatten()
```

```
J = np.array([[0, -1], [1, 0]]) # Rotation matrix
```

Def simulate\_bulge(initial\_G):

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    """Simulate one trajectory until Delta > -1e-10, return final eigenvalue ratio"""
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Def event(t, y): # Termination event

    G = y.reshape(2, 2)

    Return closure_gap(G) + 1e-10 # Halt when Delta >= -1e-10

Event.terminal = True

Event.direction = 1 # Only from below


Sol = solve_ivp(dynamical_law, [0, 10], initial_G.flatten(), args=(J,),

    Method='DOP853', rtol=1e-8, atol=1e-10, events=event)

If sol.status == 1: # Event triggered

    Final_G = sol.y[:, -1].reshape(2, 2)

    Eigvals = np.linalg.eigvals(final_G)

    Abs_eig = np.abs(eigvals)

    Ratio = np.max(abs_eig) / np.min(abs_eig) if np.min(abs_eig) > 0 else np.inf

    Return ratio

Return np.nan # Failed sim


# Run over 1000 random initial conditions (Delta_0 < 0)

N_runs = 1000

Ratios = []

For _ in range(n_runs):

    G0 = np.random.uniform(-1, 1, (2, 2))

    If closure_gap(G0) < 0: # Only valid starts

        Ratio = simulate_bulge(G0)

        If not np.isnan(ratio):

            Ratios.append(ratio)

```

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Mean_ratio = np.mean(ratios)

Std_ratio = np.std(ratios)

Print(f"Mean bulge ratio over {len(ratios)} runs: {mean_ratio:.4f} ± {std_ratio:.0e}")

# Optional: Plot a single trajectory's Delta evolution

G_example = np.array([[0.5, -0.2], [0.1, 0.3]]) # Example with Delta < 0

Sol_example = solve_ivp(dynamical_law, [0, 5], G_example.flatten(), args=(J,),  

dense_output=True)

T = np.linspace(0, 5, 100)

Deltas = [closure_gap(sol_example.sol(ti).reshape(2,2)) for ti in t]

Plt.plot(t, deltas)

Plt.xlabel('Time')

Plt.ylabel('Delta')

Plt.title('Approach to Instability Threshold')

Plt.show()

```