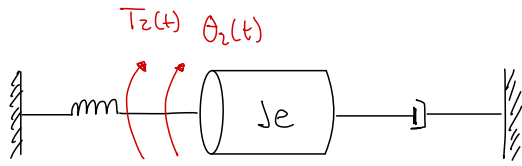


Celaya González David Alejandro.



$$T_2(s) = (J_e s^2 + D e s + K_e) \theta_2(s)$$

$$K_e = k_1 + k_2 \left( \frac{N_1}{N_2} \right)^2 + k_3 \left( \frac{N_1}{N_2} \right)^2 + \left( \frac{N_3}{N_4} \right)^2$$

$$J_e = J_2 + J_1 \left( \frac{N_2}{N_1} \right)^2 + J_3 \left( \frac{N_3}{N_4} \right)^2$$

$$D_e = D \left( \frac{N_3}{N_4} \right)^2$$

$$\Rightarrow G(s)$$

$$G(s) = \frac{\theta_2(s)}{T_2(s)} = \frac{1}{(J_e s^2 + D e s + K_e)}$$

$$G(s) = \frac{1}{\left[ J_2 + J_1 \left( \frac{N_2}{N_1} \right)^2 + J_3 \left( \frac{N_3}{N_4} \right)^2 s^2 + D \left( \frac{N_3}{N_4} \right)^2 s + K_2 + k_1 \left( \frac{N_2}{N_1} \right)^2 + k_3 \left( \frac{N_3}{N_4} \right)^2 \right]}$$