publicVar: string + publicVar: string - privateVar2: int # protectedVar: float + public_methode(in var: int var2:int , out returnVar: int): int - private_methode(in var:int): void # protected_methode(type): type

Hardware Classes

Movment		
-class Motor		
- float speed_x		
- float speed_y		

- void calc_speed(???)

-void init

Motor
- pinNumber : int
+ speed : float (-100 backwards to +100 Front)
- init : void
- set_speed : void

Utility and sonstiges

Utility
- pinNumber
- QSting make_xml_from_string (QString Tag, QString Data) : Qstring xml
- QSting make_xml_from_vektor (QString Tag, QVektor Data) : Qstring xml

Log
- pathToLogfile
+ field: type
+ save_logs
- loading_logs

Camera
Λ
- qualityVideo
- start_video
- stop_video

FPGA - pinNumber :int + speed: float - init : void - set_speed: void

Communiacion

Communication
- pinNumber
- baud
- port
- ip adresse
- ensenal
+sending_mesage_hardware
- error_alarm
+ reciving_mesage
- setBaudRate
- setDataBits
- setParity
- setFlowControl
- open
- close

Wirel	essCommunicatio	n
- ensenal		
- ip adres	se	
- init : void	<u> </u>	
- on_conr	nection: void	
- error_ala	arm : void	
- on_Rea	d_Read: void	
- on_New	_Data: void	

_	
	SerialCommunication
	- pinNumber
	- baud
	+ sending_mesage_hardware
	+ reciving_mesage
	- error_alarm