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# AIDA Trigger logic unit (TLU)

Tuesday 24<sup>th</sup> October, 2017

Board FMC\_TLU\_v1E .

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## Introduction

This manual describes the AIDA Trigger Logic Unit (TLU) designed for the AIDA-2020 project by David Cussans<sup>1</sup> and Paolo Baesso<sup>2</sup>.

The unit is designed to be used in High Energy Physics beam-tests and provides a simple and flexible interface for fast timing and triggering signals at the AIDA pixel sensor beam-telescope.

The current version of the hardware is an evolution of the EUDET-TLU and the miniTLU and is shipped in a metallic case that includes an Field Programmable Gate Array (FPGA) board and the TLU Printed Circuit Board (PCB): the FPGA is responsible for all the logic functions of the unit, while the PCB contains the clock chip, discriminator and interface blocks needed to communicate with other devices.

The current version of the PCB is FMC\_TLU\_v1E and is designed to plug onto a carrier FPGA board like any other FPGA Mezzanine Card (FMC) mezzanine board, although its form factor does not comply with the ANSI-VITA-57-1 standard.

### 1.1 Overview

The AIDA TLU provides timing and synchronization signals to test-beam readout hardware.

The hardware can provide an internally generated low-jitter 40 MHz clock or can accept and external clock reference.

It accepts the asynchronous trigger signals from up to six external sources, such as beam-scintillators, and generate synchronous signals (including global trigger or control signals) to send to up to four devices under tests. The logic function used to generate the trigger can be defined by the user among all the possible logic combinations of the inputs.

Depending on the chosen mode of operation, the TLU can accept busy signals

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or other veto signals from Device Under Test (DUT)s and react accordingly, for instance avoinding any further trigger until all the busy signals have been de-asserted.

Whenever a global trigger is generated by the unit, a 48-bit time-stamp is attached to it. This time stamp is based on the 40 MHz clock. Additionally ??? The configuration parameters and data are sent and received via the IPbus. IPbus is a simple way to control and communicate TCA-based hardware via the UDP/IP protocol.

#### 1.2 FPGA

The TLU is shipped with an FPGA board already programmed with the latest version of the firmware needed to operate the unit.

The firmware developed at University of Bristol is targeted to work with the Enclustra AX3 board, which must be plugged onto a PM3 base, also produced by Enclustra. The firmware is written on the FPGA using a Joint Test Action Group (JTAG) interface. Typically a breakout board will be required to connect the Xilinx programming cable to the Enclustra PM3. All these components are included in the TLU enclosure so the user can upload a new version of the firmware by simply connecting a Universal Serial Bus (USB)-B cable in the back panel of the unit.

At the time of writing this work<sup>3</sup> the AX3 is the only FPGA for which a firmware has been developed. However, we plan to ship future versions of the TLU with a custom made FPGA designed by Samer Kilani.

### Note



If the FPGA detects a programming cable connected it will not load the firmware from its memory after a power cycle. It is recommended to leave the USB cable disconnected from the back panel unless there is the intention to re-program the firmware.

### 1.3 Power

The TLU requires 12 V to operate. Power can be provided using the circular jack on the back panel of the unit.

During normal operation the current drawn by the unit is about 0.5 A.

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## **TLU Hardware**

Board FMC\_TLU\_v1E is an evolution of the miniTLU designed at the University of Bristol (UoB). The board shares a few features with the miniTLU but also introduces several improvements. This chapter illustrates the main features of the board to provide a general view of its capabilities and an understanding of how to operate it in order to communicate with the DUTs.

### 2.1 Inputs and interfaces

### **FMC**

The board must be plugged onto a FMC carrier board with an FPGA in order to function correctly. The connection is achieved using a low pin count FMC connector. The list of the pins used and the corresponding signal within the FPGA are provided in appendix at page 43.

#### Device under test

The DUTs are connected to the TLU using standard size High-Definition Multimedia Interface (HDMI) connectors<sup>1</sup>.

In the current version of the hardware, up to four DUTs can be connected to the board. In this document the connectors will be referred to as HDMI1, HDMI2, HDMI3 and HDMI4.

The connectors expect 3.3 V Low Voltage Differential Signaling (LVDS) signals and are bi-directional, i.e. any differential pair can be configured to be an output (signal from the TLU to the DUT) or an input (signals from the DUT to the TLU) by using half-duplex line transceivers. Figure 2.1 illustrates how the differential pairs are connected to the transceivers.

<sup>&</sup>lt;sup>1</sup>In the miniTLU hardware there were miniHDMI connectors.

**HDMI PIN HDMI Signal Name Enable Signal Name** ENABLE\_CLK\_TO\_DUT 1 HDMI\_CLK ENABLE\_DUT\_CLK\_FROM\_FPGA 2 GND ENABLE\_CLK\_TO\_DUT 3 HDMI\_CLK \* ENABLE\_DUT\_CLK\_FROM\_FPGA 4 CONT ENABLE\_CONT\_FROM\_FPGA 5 GND CONT\* ENABLE\_CONT\_FROM\_FPGA 6 7 BUSY ENABLE\_BUSY\_FROM\_FPGA 8 GND 9 BUSY\* ENABLE\_BUSY\_FROM\_FPGA 10 SPARE ENABLE\_SPARE\_FROM\_FPGA 11 GND 12 SPARE\* ENABLE\_SPARE\_FROM\_FPGA 13 n.c. 14 HDMI\_POWER 15 TRIG ENABLE\_TRIG\_FROM\_FPGA 16 TRIG\* ENABLE\_TRIG\_FROM\_FPGA 17 GND 18 n.c. 19 n.c.

Table 2.1: HDMI pin connections.

### Note



The input part of the transceiver is configured to be always on. This means that signals going *into* the TLU are always routed to the logic (FPGA). By contrast, the output transceivers have to be enabled and are off by default: signal sent from the logic to the DUTs cannot reach the devices unless the corresponding enable signal is active.

Table 2.1 shows the pin naming and the corresponding output enable signal. The clock pairs have two different enable signals to select the clock source (see section 3 for more details). In general only one of the clock sources should be active at any time.

The enable signals can be configured by programming two General Purpose Input/Output (GPIO) bus expanders via Inter-Integrated Circuit (I<sup>2</sup>C) interface as described in section 2.4.

In terms for functionalities, the four HDMI connectors are identical with

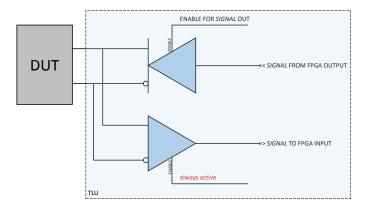


Figure 2.1: Internal configuration of the HDMI pins for the DUTs. The path from the DUT to the FPGA is always active. The path from the FPGA to the DUT can be enabled or disabled by the user.

one exception: the clock signal from HDMI4 can be used as reference for the clock generator chip mounted on the hardware. For more details on this functionality refer to section 3.

### SFP cage

FMC\_TLU\_v1E hosts a Small Form-factor Pluggable (SFP) cafe and a Clock and Data Recovery (CDR) chip that can be used to decode a data stream over optical/copper interface. The data from the stream is routed to the FPGA while the clock can be fed to the Si5345 to provide a clock reference.

### 2.2 Clock LEMO

The board hosts a two-pin LEMO connector that can be used to provide a reference clock to the clock generator (see section 3) or to output the clock from the TLU to the external world, for instance to use it as a reference for another TLU. The signal level is 3.3 V LVDS.

As for the differential pairs of the DUTs, the pins of this connector are wired to a transceiver configured to always accept the incoming signals. The outgoing direction must be enabled by using the ENABLE\_CLK\_TO\_LEMO signal, which can be configured using the bus expander described in in section 2.4.

### 2.3 Trigger inputs

Board FMC\_TLU\_v1E can accept up to six trigger inputs over the LEMO connectors labelled IN\_1, IN\_2, IN\_3, IN\_4, IN\_5 and IN\_6. The FMC\_TLU\_v1E

	Output			
	DAC2(Ic2)	DAC1 (Ic1)		
Threshold 0	1			
Threshold 1	0			
Threshold 2		3		
Threshold 3		2		
Threshold 4		1		
Threshold 5		0		

Table 2.2: DAC outputs and corresponding threshold inputs.

uses internal high-speed<sup>2</sup> discriminators to detect a valid trigger signal. The voltage thresholds can be adjusted independently for each input in a range from -1.3 V to +1.3 V with 40  $\mu$ V resolution.

The adjustment is performed by writing to two 16-bit Digital to Analog Converter (DAC)s via I<sup>2</sup>C interface as described in section 2.4.

The DACs can either use an internal reference voltage of 2.5 V or an external one of 1.3 V provided by the TLU: it is recommended to choose the external one by configuring the appropriate register in the devices.

The correspondence between DAC slave and thresholds is shown in table 2.2.

### 2.4 $I^2C$ slaves

The I<sup>2</sup>C interface on the FMC\_TLU\_v1E can be used to configured several features of the board.

Table 2.3 lists all the valid addresses and the corresponding slave on the board. The Enclustra lines refer to slaves located on the PM3 board; these slaves can be ignored with the exception of the bus expander. The Enclustra expander is used to enable/disable the I<sup>2</sup>C lines going to the FMC connector.

#### Note



After a power cycle the Enclustra expander is configured to disable the  $I^2C$  interface pins. This means that it is impossible to communicate to any  $I^2C$  slave on the TLU until the expander has been enabled.

The interface is enable by setting bit 7 to 0 on register 0x01 of the Enclustra expander.

Once the interface is enabled it is possible to read and write to the devices listed in the top part of table 2.3.

The user should reference the manual of each individual component to determine the register that must be addressed. The rest of this section is meant to provide an overview of the slave functionalities.

 $<sup>^2500\</sup>pm30$  ps propagation delay.

2.4. *l*<sup>2</sup>C SLAVES 7

**FUNCTION** CHIP ID **ADDRESS** IC1 AD5665RBRUZ DAC1 0x1F IC2 DAC2 AD5665RBRUZ 0x13 IC5 24AA025E48T **EEPROM** 0x50 IC6 PCA9539PW I2C Expander1 0x74 IC7 I2C Expander2 PCA9539PW 0x75 IC8 ADN2814ACPZ CDR 0x60 Clock Generator IC8 9 Si5345A 0x68 Enclustra slaves Enclustra Bus Expander 0x21 Enclustra System Monitor 0x21Enclustra EEPROM 0x54 Enclustra slave 0x64

Table 2.3: I<sup>2</sup>C addresses of the TLU.

#### DAC

Each DAC has four outputs that can be configured independently. DAC1 is used to configure the thresholds of the first four trigger inputs; DAC2 configures the remaining two thresholds.

The DACs should be configured to use the TLU voltage reference of  $1.3~\rm V$ . In these conditions, writing a value of  $0x00000~\rm to$  a DAC output will set the corresponding threshold to  $-1.3~\rm V$  while a value of 0xFFFF will set it to  $+1.3~\rm V$ .

#### **EEPROM**

The Electrically Erasable Programmable Read-Only Memory (EEPROM) located on the board contains a factory-set unique number, used to identify each FMC\_TLU\_v1E unequivocally. The number is comprised of six bytes written in as many memory locations.

The identifier is always in the form: 0xD8 80 39 XX XX with the top three bytes indicating the manufacturer and the bottom three unique to each device.

### Bus expander

The expanders are used as electronic switched to enable and disable individual lines. Each expander has two 8-bit banks; the values of the bits, as well as their direction (input/output) can be configured via the I<sup>2</sup>C interface. For the purpose of the TLU, all the expander pins should be configured as outputs since they must drive the enable signals on the DUT transceivers.

### Clock and data recovery chip

The CDR is used in conjunction with the SFP cage to recover data and clock from the incoming bit stream. The functionality has not yet been implemented

in the firmware so the I<sup>2</sup>C slave can be ignored for now.

### **Clock generator**

The clock for FMC\_TLU\_v1E can be generated using various external or internal references (see section 3 for further details). In order to reduce any jitter from the clock source and to provide a stable clock, the board hosts a Si5345 clock generator that needs to be configured via I<sup>2</sup>C interface.

The configuration involves writing  $\sim$ 380 register values. A configuration file, containing all the register addresses and the corresponding values, can be generated using the ClockBuilder tool available from Silicon Labs.

The registers addresses between 0x026B and 0x0272 contain user-defined values that can be used to identify the configuration version: it is advisable to check those registers and check that they contain the correct code to ensure that the chip is configured according to the TLU specifications. As an indication, files generated for the current version of the TLU should have a configuration identifier in the form TLU1E\_XX, where XX is a sequential number.

### **TLU Producer**



When using the TLU producer to configure hardware, the location of the configuration file can be specified by setting the CLOCK\_CFG\_FILE value in the *conf* file for the producer. If no value is specified, the software will look for the configuration file ../conf/confClk.txt i.e. if the euRun binary file is located in ./eudaq/bin, then the default configuration file should reside in ./eudaq/conf. The configuration will produce an error if the file is not found.

# Clock

The TLU can use various sources to produce a stable 40 MHz clock<sup>1</sup>. A Low-voltage Positive Emitter-Coupled Logic (LVPECL) crystal provides the reference 50 MHz clock for a Si5345A jitter attenuator. The Si5345A can accept up to four clock sources and use them to generate the required output clocks. In FMC\_TLU\_v1E the possible sources are: differential LEMO connector LM1\_9, one of the four HDMI connectors (HDMI4), a CDR chip connected to the SFP cage. The fourht input is used to provide a zero-delay feedback loop. The low-jitter clock generated by the Si5345A can be distributed to up to ten recipients. In the TLU these are: the four DUTs via HDMI connectors, the differential LEMO cable, the FPGA, connector J1 as a differential pair (pins 4 and 6) and as a single ended signal (pin 8). The final output is connected to the zero-delay feedback loop.

The DUTs can receive the clock either from the Si5435A or directly from the FPGA: when provided by the clock generator, the signal name is CLK\\_TO\\_DUT and is enabled by signal ENABLE\_CLK\_TO\_DUT; when the signal is provided directly from the FPGA the line used is DUT\_CLK\_FROM\_FPGA and is enabled by ENABLE\_DUT\_CLK\_FROM\_FPGA.

The firmware uses the clock generated by the Si5345A except for the block enclustra\_ax3\_pm3\_infra which relies on a crystal mounted on the Enclustra board to provide the IPBus functionalities (in this way, at power up the board can communicate via IPBus even if the Si5345A is not configured).

### 3.1 Input selection

The Si5345 has four inputs that can be selected to provide the clock alignment; the selection can be automatic or user-defined. For further details on this aspect the user should consult the chip documentation.

<sup>&</sup>lt;sup>1</sup>For some applications a 50 MHz clock will be required instead

IN\_SEL

Register Name	Hex Address [Bit Field]	Function
	0x0536[1:0]	Selects manual or automatic switching modes.
		Automatic mode can be revertive or non-revertive.
		Selections are the following:
CLK_SWITCH_MODE		00 Manual
		01 Automatic non-revertive
		02 Automatic revertive
		03 Reserved
IN SEL REGCTRL	0x052A [0]	0 for pin controlled clock selection
IN_SEL_REGUIRE		1 for register controlled clock selection

0 for IN0 1 for IN1

2 for IN2

3 for IN3 (or FB\_IN)

Table 3.1: Si5345 Input Selection Configuration.

### 3.2 Logic clocks registers

LogicClocksCSR: in the new TLU the selection of the clock source is done by programming the Si5345. As a consequence, there is no reason to write to this register. Reading it back returns the status of the PLL on bit 0, so this should read 0x1.

0x052A [2:1]

# **DUT** signals

In the old versions of the TLU the direction of the signals on the HDMI\* connectors were pre-defined. The new hardware has separate lines for signals going into the TLU and signals out of the TLU. See section 2.1 for further details.

# **Trigger inputs**

The six inputs on the TLU can be used to generate a global trigger that is then issued to all the DUTs.

Each input has a programmable voltage discriminator that can be configured in the range [-1.3: 1.3] V.

All the inputs are protected by clamping diodes that limit the input voltage in the range [-5:+5] V.

### 5.1 Trigger logic

The TLU has six trigger inputs than can be used to generate a valid trigger event. The number of possible different trigger combinations is  $2^6=64$  so a 64-bit word can be used to decide the valid combinations. In the hardware the 64-bit word is split into two 32-bit words (indicated as Most Significant Bit (MSB) and Least Significant Bit (LSB) word) and the rules to generate the trigger can be specified by the user by writing in the two 32-bit registers TriggerPattern\_highW and TriggerPattern\_lowW: the first stores the 32 most significative bits of the trigger word, the latter stores the least significative bits.

The user can select any combination of the trigger inputs and declare it a valid trigger pattern by setting a 1 in the corresponding trigger configuration word. Tables 5.1 and 5.2 show an example of how to determine the trigger configuration words: whenever a valid trigger combination is encountered, the user should put a 1 in the corresponding row under the PATTERN column. The pattern thus obtained is the required word to write in the configuration register.

It is important to note that this solution allows the user to set veto pattern as well: for instance if only word 31 from table 5.1 were picked, then the TLU would only register a trigger when the combination  $\overline{I_5} * I_4 * I_3 * I_2 * I_1 * I_0$  was presented at its inputs. In other words, in this specific case  $I_5$  would act as a veto signal and the TLU would **not** produce a global trigger if  $I_5$ =1.

The default configuration in the firmware is Hi= 0xFFFFFFF, Low= 0xFF-

Table 5.1: Example of configuration word for the least significative bits of the trigger registers: the only valid configuration is represented by  $\overline{I_5}$  +  $I_4$  +  $I_3$  +  $I_2$  +  $I_1$  +  $I_0$ , i.e. a trigger is accepted if all the inputs, except  $I_5$ , present a logic 1 at the same time. The user would then write the resulting word 0x80000000 in the TriggerPattern\_lowW register.

DEC	I5	I4	I3	I2	I1	I0	PATTERN	CONFIG. WORD		$2^n$
0	0	0	0	0	0	0	0			1
1	0	0	0	0	0	1	0			2
2	0	0	0	0	1	0	0	0		4
3	0	0	0	0	1	1	0			8
4	0	0	0	1	0	0	0		1	16
5	0	0	0	1	0	1	0	0		32
6	0	0	0	1	1	0	0			64
7	0	0	0	1	1	1	0			128
8	0	0	1	0	0	0	0			256
9	0	0	1	0	0	1	0	0		512
10	0	0	1	0	1	0	0	1		1024
11	0	0	1	0	1	1	0			2048
12	0	0	1	1	0	0	0		1	4096
13	0	0	1	1	0	1	0	0	LOWEST 32-bits	8192
14	0	0	1	1	1	0	0		2-b	16384
15	0	0	1	1	1	1	0		Г3	32768
16	0	1	0	0	0	0	0		ES	65536
17	0	1	0	0	0	1	0	0	[2]	131072
18	0	1	0	0	1	0	0		9	262144
19	0	1	0	0	1	1	0			524288
20	0	1	0	1	0	0	0		]	1048576
21	0	1	0	1	0	1	0	0		2097152
22	0	1	0	1	1	0	0			4194304
23	0	1	0	1	1	1	0			8388608
24	0	1	1	0	0	0	0		]	16777216
25	0	1	1	0	0	1	0	0		33554432
26	0	1	1	0	1	0	0			67108864
27	0	1	1	0	1	1	0			134217728
28	0	1	1	1	0	0	0		]	268435456
29	0	1	1	1	0	1	0	8		536870912
30	0	1	1	1	1	0	0	$\mathbb{I}$		1073741824
31	0	1	1	1	1	1	$\vdash$			2147483648

Table 5.2: Example of the most significative word of the register: a valid trigger is obtained when the inputs show the same configuration as row DEC 36, 37, 38, 39, 41, 43 and 63. These configuration are in logic OR with that presented in table 5.1. The resulting configuration word is 0x80000AF0.

DEC	I5	I4	I3	I2	I1	IO	PATTERN	CONFIG. WORD		2 <sup>n</sup>
32	1	0	0	0	0	0	0			1
33	1	0	0	0	0	1	0	0		2
34	1	0	0	0	1	0	0	1		4
35	1	0	0	0	1	1	0			8
36	1	0	0	1	0	0	1			16
37	1	0	0	1	0	1	1			32
38	1	0	0	1	1	0	1	]		64
39	1	0	0	1	1	1	П			128
40	1	0	1	0	0	0	0			256
41	1	0	1	0	0	1	1	₹		512
42	1	0	1	0	1	0	0			1024
43	1	0	1	0	1	1	1			2048
44	1	0	1	1	0	0	0			4096
45	1	0	1	1	0	1	0	0	HIGHEST 32-bits	8192
46	1	0	1	1	1	0	0		32-1	16384
47	1	0	1	1	1	1	0		T	32768
48	1	1	0	0	0	0	0		ES	65536
49	1	1	0	0	0	1	0	0	HE	131072
50	1	1	0	0	1	0	0		Ĭ	262144
51	1	1	0	0	1	1	0			524288
52	1	1	0	1	0	0	0			1048576
53	1	1	0	1	0	1	0	0		2097152
54	1	1	0	1	1	0	0			4194304
55	1	1	0	1	1	1	0			8388608
56	1	1	1	0	0	0	0			16777216
57	1	1	1	0	0	1	0	0		33554432
58	1	1	1	0	1	0	0	]		67108864
59	1	1	1	0	1	1	0	1		134217728
60	1	1	1	1	0	0	0			268435456
61	1	1	1	1	0	1	0			536870912
62	1	1	1	1	1	0	0	1 ~		1073741824
63	1	1	1	1	1	1		]		2147483648

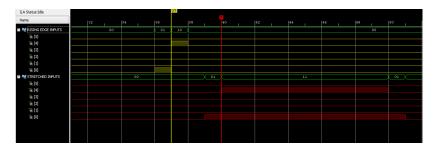


Figure 5.1: Input pulses (yellow) and corresponding stretched signals (red). Input 0 is stretched by 10 cycles, input 4 by 8, hence the difference in pulse widths.

FEFFFE, which means that as long as any trigger input fires, a trigger will be generated. These words are loaded in the FPGA every time the firmware is flushed.

### **Trigger logic definition**



The user should pay attention to what trigger logic they want to define in order to avoid confusion in the data.

A "1" in the logic table means that the corresponding input must be active to produce a valid trigger. Similarly, a "0" indicates that the corresponding input must be inactive (i.e. is a veto, not an ignore). Any change in input configuration will cause the logic to re-assess the trigger status. The following section gives a brief example.

### Bit 0 meaning



A 1 in the lowest bit of the LSB word indicates that  $\overline{I_5}$  \*  $\overline{I_4}$  \*  $\overline{I_3}$  \*  $\overline{I_2}$  \*  $\overline{I_1}$  \*  $\overline{I_0}$  is a valid trigger combination, so the TLU will produce a trigger when all the inputs are unactive (i.e. even if all the inputs are unplugged). Apart from very specific cases, this is generally not a desired behaviour.

### Example

In this example we have connected a pulser to two inputs of the TLU, namely IN\_1 and IN\_5. The inputs fire with a small, random delay with respect to each other.

In order to ensure that the signals overlap adequately, we use the *stretch* register (see chapter 5.1) to increase the length of the pulses: we extend in0 to 10 clock cycles and in4 to 8 clock cycles, where the clock has a frequency of 160 MHz. The resulting signals are shown in figure 5.1.

We can now define the trigger logic to be used to assert a valid trigger: we

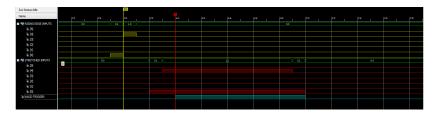


Figure 5.2: Trigger configuration 0x00020000. The valid trigger (blue) is asserted only when both signals are high. This condition occurs at frame 39. The trigger is asserted on the following frame.

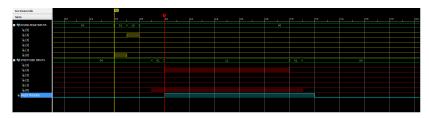


Figure 5.3: Trigger configuration 0x00020002. The valid trigger (blue) is asserted if IN\_1 is high OR when IN\_1 and IN\_5 are both high at the same time.

only consider the lower 32-bits of the trigger word and see how different values can produce very different results.

- Trigger LSB word= 0x00020000. This indicates that the only valid trigger combination occurs when both IN\_1 and IN\_5 are high. The valid trigger goes high 1 clock cycle after this condition is met and remains high up to 1 clock cycle after the condition is no longer valid. This is illustrated in figure 5.2.
- Trigger LSB word= 0x00020002. This indicates that a valid trigger is achieved in two separated configurations (in logic OR): when both inputs are high at the same time (as in the previous case) or if IN\_1 is active on its own. This is illustrated in figure 5.3. It can be seen that the valid trigger is asserted immediately one clock cycle after IN\_1 is high and remains high as long as this condition is met. One might assume that specifying the combination with IN\_5 is redundant, but the following example should show that this is not the case.
- Trigger LSB word= 0x000000002. This indicates that the only valid configuration is the one where only IN\_1 is high. It is important to understand that in this configuration all other inputs act as veto. This might produce unexpected results if the user is not careful<sup>1</sup>.

 $<sup>^{1}</sup>$ Specifically, pulse stretch, pulse delay and trigger logic must be configured correctly to avoid unwanted results.

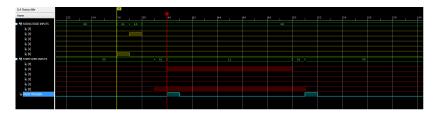


Figure 5.4: Trigger configuration 0x00000002. The valid trigger (blue) is asserted only when IN\_1 is active on its own. As such, two separated trigger pulses are produced because IN\_5 goes high and returns low before IN\_1.

In figure 5.4 it is possible to see that the logic produces two separated trigger valid pulses, both shorter than the ones in previous examples: the first one is due to IN\_1 going high while IN\_5 is low. As soon as IN\_5 goes high, the trigger condition is no longer met. When IN\_5 returns low, a trigger condition is met again because IN\_1 is still high. In this specific case, the double pulse is caused by the different width of the pulses.

### 5.2 Stretch and delay

The trigger logic is designed to detect edge transitions<sup>2</sup> at the trigger inputs and produce a pulse for each transition detected. The pulse has an initial duration of one clock cycle (f= 160 MHz, one cycle 6.25 ns) and occurs on the next rising edge of the 160 MHz internal clock.

Each pulse can be stretched and delayed in integer numbers of clock cycles to compensate for differences in cable length. Two separate 5-bit registers are used for the task: the value written in the registers will stretch/delay the pulse by a corresponding number of clock cycles.

Diagram 5.5 shows the effect of the delay and stretch words on the trigger logic.

Further details on how to configure the stretch and delay values are provided in section 8.

<sup>&</sup>lt;sup>2</sup>Currently only negative edges are registered. A future firmware version will implement user-selectable positive or negative edge detection.

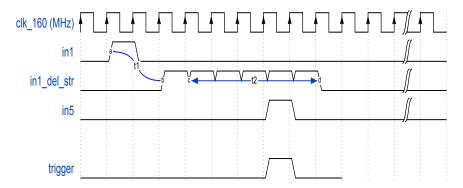


Figure 5.5: Effect of the stretch and delay values. In 1 is delayed by 2 clock cycles (t1=12.5 ns) and stretched by 5 clock cycles (t2=31.25 ns) to create a coincidence window with in 5 and produce the resulting trigger signal.

#### 5.3 Event buffer

The event buffer IPBus slave has four registers. Writing to EventFifoCSR will reset the First In First Out (FIFO). Reading from either of the register will put their data on the IPBus data line.

Reading from EventFifoCSR returns the following:

- bit 0: FIFO empty flag
- bit 1: FIFO almost empty flag
- bit 2: FIFO almost full flag
- bit 3: FIFO full flag
- bit 4: FIFO programmable full flag
- other bits: 0

The status register (SerdesRst) is as follows:

- bit 0: reset the ISERDES
- bit 1: reset the trigger counters
- bit 2: calibrate IDELAY: This seems to be disconnected at the moment.
- bit 3: fixed to 0
- bit 4, 5: status of thresholdDeserializer(Input0). When the IDELAY modules (prompt, delayed) have reached the correct delay, these two bits should read 00.
- bit 6, 7: status of thresholdDeserializer(Input1)
- bit 8, 9: status of thresholdDeserializer(Input2)
- bit 10, 11: status of thresholdDeserializer(Input3)
- bit 12, 13: status of thresholdDeserializer(Input4)
- bit 14, 15: status of thresholdDeserializer(Input5)
- bit 16, 19: fixed to 0
- bit 20: s\_deserialized\_threshold\_data(Input0)(7)
- bit 21: s\_deserialized\_threshold\_data(Input1)(7)
- bit 22: s\_deserialized\_threshold\_data(Input2)(7)
- bit 23: s\_deserialized\_threshold\_data(Input3)(7)
- bit 24: s\_deserialized\_threshold\_data(Input4)(7)

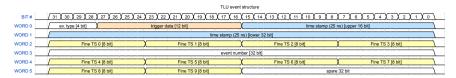


Figure 5.6: Event structure

• bit 25: s\_deserialized\_threshold\_data(Input5)(7)

9 bits are used to determine trigger edges. 8 are from the deserializers, 1 is added as the LSB and is the MSB from the previous word.

## **Functions**

The following is a list of files containing the code for the TLU:

- ./eudaq2/user/eudet/misc/fmctlu\_runcontrol.ini: initialization file for the hardware. The location of the file can be passed to the EUDAQ code in the Graphic User Interface (GUI).
- ./eudaq2/user/eudet/misc/fmctlu\_runcontrol.conf:
   configuration file. It contains all the parameters to be loaded in the TLU
   at the beginning of the run. If this file is not found, EUDAQ will use
   a list of default settings. The location of the file (and its name) can be
   passed to the EUDAQ code in the GUI.
- ./eudaq2/user/eudet/misc/fmctlu\_connection.xml: define the IP address and address map of the TLU. The one listed is the default location for the file. A different location can be specified with the ConnectionFile option in the *conf* file for the TLU.
- ./eudaq2/user/eudet/misc/fmctlu\_address.xml: address map for the TLU. The location of the file is specified in the fmctlu\_connection.xml file.
- ./eudaq2/user/eudet/misc/fmctlu\_clock\_config.txt: configuration for the Si5345 clock chip. In order for the hardware to work a configuration file must be present. Those listed are the default name and location for the file; a different file can be specified with the CLOCK\_CFG\_FILE option in the *conf* file for the TLU.
- ./eudaq2/user/eudet/module/src/FMCTLU\_Producer.cc: eudaq producer for the TLU. Contains the methods to initialize, configure, start, stop the TLU producer.
- ./eudaq2/user/eudet/hardware/src/FmctluController.cc: Contains the definition of the hardware class for the TLU and the methods to set and read from its hardware, such as clock chip, DAC, etc. This

lever is abstract with respect to the actual hardware, so that if a future version of the board uses different components it should be possible to re-use this code.

- ./eudaq2/user/eudet/hardware/include/FmctluController.hh: Headers for the controller.
- ./eudaq2/user/eudet/hardware/src/FmctluController.cxx: Executable for the controller.
- ./eudaq2/user/eudet/hardware/src/FmctluHardware.cc:
  This is the code that deals with the actual hardware on the TLU, and contains specific instructions for the chips mounted in the current version. It contains several classes for the ADC, the clock chip, the I/O expanders etc.
- ./eudaq2/user/eudet/hardware/include/FmctluHardware.hh: Header for the hardware.
- ./eudaq2/user/eudet/hardware/src/FmctluI2c.cc: core functions used to read and write from I<sup>2</sup>C compatible slaves.
- ./eudaq2/user/eudet/hardware/include/FmctluI2c.hh: Headers for the I<sup>2</sup>C core.

### 6.1 Functions

enableClkLEMO Enable or disable the output clock to the differential LEMO connector.

**enableHDMI** Set the status of the transceivers for a specific HDMI connector. When enable= False the transceivers are disabled and the connector cannot send signals from FPGA to the outside world. When enable= True then signals from the FPGA will be sent out to the HDMI.

In the configuration file use  $\mathtt{HDMIx\_on} = 0$  to disable a channel and  $\mathtt{HDMI1\_on} = 1$  to enable it (x can be 1, 2, 3, 4).

NOTE: the other direction is always enabled, i.e. signals from the DUTs are always sent to the FPGA.

NOTE: Clock source must be defined separately using SetDutClkSrc (DUTClkSrc in python script).

NOTE: this is called DUTOutputs on the python scripts.

GetFW dsds

getSN dsd

I2C\_enable dsd

InitializeClkChip

**InitializeDAC** 

InitializeIOexp

InitializeI2C

PopFrontEvent

ReadRRegister

ReceiveEvents

ResetEventsBuffer

**SetDutClkSrc** Set the clock source for a specific HDMI connector. The source can be set to 0 (no clock), 1 (Si5345) or 2 (FPGA). In the configuration file use HDMIx\_on = N to select the source (x can be 1, 2, 3, 4, N is the clock source).

NOTE: this is called DUTClkSrc on python scripts.

**SetPulseStretchPk** Takes a vector of six numbers, packs them (5-bits each) and sends them to the PulseStretch register.

### SetThresholdValue

**setTrgPattern** Writes two 32-bit words to define the trigger pattern for the inputs. See section 5 for details.

SetWRegister

SetUhalLogLevel

# **IPBus Registers**

version Returns the current version of firmware used to program the TLU

#### **DUTINTERFACES**

**DUTMaskW** Writing to this register allows to define which DUTs are active when in AIDA mode. The lower 4 bits of the register can be used to define the status of the DUTs: 1 for active, 0 for masked. hdmi1 is defined by bit 0, hdmi2 is defined by bit 1, hdmi3 is defined by bit 2, hdmi4 is defined by bit 3.

**IgnoreDUTBusyW** Writing to this register allows to ignore the busy signal from a particular DUT while in AIDA mode. The lower 4 bits are used to define the status for each device. A 1 indicates that the logic should ignore busy signals from the specific DUT.

**IgnoreShutterVetoW** The LSB of this register can be written to define whether the DUT should ignore the shutter veto signal. Normally, when the shutter signal is asserted the DUT reports busy. If this bit is flag the DUT will ignore the shutter signal.

**DUTInterfaceModeW** Write register to define the mode of operation for a DUT. Two bits per device can be used to define the mode; currently only two modes are available (AIDA, EUDET) but the second but is reserved for additional modes introduced in the future.

The bit pairs are packed from the LSB starting with hdmi1 (bits 0, 1), hdmi2 (bits 2, 3), hdmi3 (bits 4, 5), hdmi4 (bits 6, 7).

bit pair X0: EUDETbit pair X1: AIDA

**DUTInterfaceModeModifierW** Write register. This register only affects the EUDET mode of operation. For each DUT two bits can be configured although cyrrently only the lower of the pair is considere. The bit packing

Table 7.1: IPBus register

NODE	SUBNODE	ADDRESS	MASK	PERMISSION
version		0x1		r
DUTInterfaces		0x1000		
	DUTMaskW	0x0		w
	IgnoreDUTBusyW	0x1		w
	IgnoreShutterVetoW	0x2		w
	DUTInterfaceModeW	0x3		w
	DUTInterfaceModeModifierW	0x4		w
	DUTInterfaceModeR	0xB		r
	DUTInterfaceModeModifierR	0xC		r
	DUTMaskR	0x8		r
	IgnoreDUTBusyR	0x9		r
	IgnoreShutterVetoR	0xA		r
Shutter		0x2000		
	ShutterStateW	0x0		w
	PulseT0	0x1		w
i2c_master		0x3000		
	i2c_pre_lo	0x0	0xFF	r/w
	i2c_pre_hi	0x1	0xFF	r/w
	i2c_ctrl	0x2	0xFF	r/w
	i2c_rxtx	0x3	0xFF	r/w
	i2c_cmdstatus	0x4	0xFF	r/w
eventBuffer		0x4000		
	EventFifoData	0x0		r
	EventFifoFillLevel	0x1		r
	EventFifoCSR	0x2		r/w
	EventFifoFillLevelFlags	0x3		r
Event_Formatter		0x5000		
	Enable_Record_Data	0x0		r/w
	ResetTimestampW	0x1		w
	CurrentTimestampLR	0x2		r
	CurrentTimestampHR	0x3		r
triggerInputs		0x6000		
	SerdesRstW	0x0		W
	SerdesRstR	0x8		r
	ThrCount0R	0x9		r
	ThrCount1R	0xA		r
	ThrCount2R	0xB		r
	ThrCount3R	0xC		r
	ThrCount4R	0xD		r
	ThrCount5R	0xE		r
triggerLogic	D	0x7000		
	PostVetoTriggersR	0x10		r
	PreVetoTriggersR	0x11		r
	InternalTriggerIntervalW	0x02		W
	InternalTriggerIntervalR	0x12		r
	TriggerVetoW	0x04		W
	TriggerVetoR	0x14		r
	ExternalTriggerVetoR	0x15		r
	PulseStretchW	0x06		W
	PulseStretchR	0x16		r
	PulseDelayW	0x07		W
	PulseDelayR	0x17		r
	TriggerHoldOffW	0x08		w
	TriggerHoldOffR	0x18		r
	AuxTriggerCountR	0x19		r
	TriggerPattern_lowW	0x0A		w
	TriggerPattern_lowR	0x1A		r
	TriggerPattern_highW	0x0B		w
	TriggerPattern_highR	0x1B		r
logic_clocks		0x8000		
	LogicClocksCSR	0x0		r/w
	LogicRst	0x1		W

is done in a manner similar to the DUTInterfaceMode. Set bit high to allow asynchronous veto using DUT\_CLK when in EUDET mode.

**DUTInterfaceModeR** Read the content of the DUTInterfaceMode register.

**DUTInterfaceModeModifierR** Read status of the DUTInterfaceMode register.

**DUTMaskR** Read the status of the DUTMask register.

**IgnoreDUTBusyR** Read the status of the IgnoreDUTBusy register.

**IgnoreShutterVetoR** Read the status of the IgnoreShutterVeto word (only the last bit is meanigful).

#### **SHUTTER**

**ShutterStateW** The LSB of this register is propagated to the DUTs as shutter signal. This is the signal that the DUTs receive on the cont line.

**PulseT0** Writing to this register will cause the firmware to generate a T0 signal.

**I2C\_MASTER** This section includes registers used to talk to the I<sup>2</sup>C bus.

i2c\_pre\_lo Lower part of the clock pre-scaler value. The pre-scaler is used to reduce the clock frequency of the bus and make it compatible with the I<sup>2</sup>C slaves on the board.

i2c\_pre\_hi Higher part of the clock pre-scaler value.

i2c\_ctrl

i2c\_rxtx

i2c\_cmdstatus

### **EVENTBUFFER**

**EventFifoData** Returns the content of the FIFO. In the current firmware implementation the memory can hold 8192 words (32-bit).

**EventFifoFillLevel** Read register. Returns the number of words written in the FIFO. The lowest 14-bits are the actual data.

**EventFifoCSR** Read or write register. When read it returns the status of the FIFO. Five flags are returned:

- bit 0: empty. Asserted when the FIFO is empty.
- bit 1: almost empty. Asserted when one word remains in the FIFO.
- bit 2: almost full. Asserted when the FIFO can only accept one more word before becoming full.
- bit 3: full. In the current firmware the FIFO can hold 8192 words before filling up.
- bit 4: programmable full. This signal is asserted when the number of words in the FIFO is greater than or equal to the assert threshold (8181). It is de-asserted when the number of words in the FIFO is less than the negate threshold (8180).

When any value is written to this register the FIFO is reset.

EventFifoFillLevelFlags Does not do anything? REMOVE CHECK

### **EVENT\_FORMATTER**

**Enable\_Record\_Data** Read and write register. When written, **CHECK** When read returns the content of the enable record word.

**ResetTimestampW** Write register. Writing any value to this register will cause the firmware to produce a retest timestamp signal (high for one clock cycle of clk\_4x\_logic). At the moment it does not seems to be connected to anything. CHECK

CurrentTimestampLR CHECK

CurrentTimestampHR CHECK

### **TRIGGERINPUTS**

**SerdesRstW** Write register for the SerDes control.

- bit 0: set this bit to reset the ISERDES
- bit 1: set this bit to reset the input trigger counters
- bit 2: s\_calibrate\_delay

SerdesRstR Read register for the SerDes control.

**ThrCount0R** Read register. Returns the number of pulses above threshold for the trigger input.

**ThrCount1R** Read register. Returns the number of pulses above threshold for the trigger input.

- **ThrCount2R** Read register. Returns the number of pulses above threshold for the trigger input.
- **ThrCount3R** Read register. Returns the number of pulses above threshold for the trigger input.
- **ThrCount4R** Read register. Returns the number of pulses above threshold for the trigger input.
- **ThrCount5R** Read register. Returns the number of pulses above threshold for the trigger input.

#### **TRIGGERLOGIC**

- **PostVetoTriggersR** Read register. Returns the number of triggers recorded in the TLU after the veto is applied. These are the triggers actually sent to the DUTs.
- **PreVetoTriggersR** Read register. Returns the number of triggers recorded in the TLU before the veto is applied. This is used for debugging purposes.
- **InternalTriggerIntervalW** Write the number of clock cycles to be used as period for the internal trigger generator. If this number is smaller than 5 then the triggers are disabled. Otherwise the period is number -2.
- **InternalTriggerIntervalR** Read the value written in InternalTriggerIntervalW.
- **TriggerVetoW** Write register. The value written to the LSB of this register is used to generate a veto signal. This can be used to put switch the TLU status: if the bit is asserted the logic will not send new triggers to the DUTs. If the bit is reset the board will process new triggers.
- **TriggerVetoR** Read the content of the TriggerVeto register.
- **ExternalTriggerVetoR** Read register. Bit 0 of this register reports the veto status (1 for veto active, 0 for no veto). The veto is active if the TLU buffer is full or if one of the DUTs is sending a veto signal.
- **PulseStretchW** Write the stretch word for the trigger pulses. The original trigger pulses collected at a trigger input can be stretched by N cycles of the 4x clock (160 MHz, 6.25 ns). N is a number between 0 and 31. The stretched pulse is always at least as long as the original input.
  - The stretch values can be written in the conf file using the parameters  $inX\_STR$  (X=[0...5]).
  - The six words for the inputs are packed in a single 32-bit word written to this register according to the format shown in table 7.2.

**PulseStretchR** Returns the content of the PulseStretch word.

**PulseDelayW** Write the delay word for the trigger pulses. The original pulse is delayed by *N* clycles of the 4x clock (160 MHz, 6.25 ns). *N* is a number between 0 and 31. The six words for the inputs are packed in a single 32-bit word written to this register according to the format shown in table 7.2.

The delay values can be written in the conf file using the parameters  $inX_DEL(X=[0...5])$ .

**PulseDelayR** Returns the content of the PulseDelay word.

**TriggerHoldOffW** Does not do anything? CHECK

TriggerHoldOffR Read the previous register... CHECK

AuxTriggerCountR Auxiliary trigger counter. Used for debug.

**TriggerPattern\_lowW** Write register for the lower 32-bits of the trigger pattern. This pattern is used to select the combinations of trigger signals that produce a valid trigger in the TLU. See section 5.1 for details.

**TriggerPattern\_lowR** Read register for the lower 32-bits of the trigger pattern. This pattern is used to select the combinations of trigger signals that produce a valid trigger in the TLU. See section 5.1 for details.

**TriggerPattern\_highW** Write register for the higher 32-bits of the trigger pattern. This pattern is used to select the combinations of trigger signals that produce a valid trigger in the TLU. See section 5.1 for details.

**TriggerPattern\_highR** Read register for the higher 32-bits of the trigger pattern. This pattern is used to select the combinations of trigger signals that produce a valid trigger in the TLU. See section 5.1 for details.

### LOGIC\_CLOCKS

**LogicClocksCSR** This is a read/write register. The write function is now obsolete and should be removed. Reading from this register returns the status of the PLL lock: bit 0 is the locked value of the pll (1= locked).

**LogicRst** Writing a 1 in the LSB of this register will reset the PLL and the clocks used by the TLU firmware. It needs to be checked for bugs.

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Table 7.2: Packing scheme for values in registers used to define the pulse stretch and delay.

	0		0 <b>9</b>
	1	0	b1
	2	Input <sub>0</sub>	b2
	3		p3
	4		<b>b</b> 4
	2		P0
	9		b1
	7	Input 1	p2
	8	Г	p3
	6		p4
	10		P0
	11	7	b1
	12	Input 2	b2
	13	I	p3
e	14		p4
r value	15		P0
Register val	16	Input 3	b1
R	17		b2
	18		p3
	19		p4
	20		P0
	21		b1
	22	† 1ndu	b2
	23	I	p3
	24		b4
	52		09
	56		b1
	22	Input 5	P2
	28	I	p3
	59		p4
	30	×	×
	31	×	×

## **Chapter 8**

## **EUDAQ Parameters**

List of parameters that are parsed by the EUDAQ run control GUI to configure the TLU.

The parameters must be included in the INI or CONF file passed to the main window (see fig.8.1).

Not all parameters are needed; if one of the parameters is not present in the files, the code will generally assume a default value, indicated in brackets in the following document [type, default].

### 8.1 INI file

initid [string, "0"] Does not serve any purpose in the code but can be useful to identify configuration settings used in a specific run. EUDAQ will store this information in the run data.

ConnectionFile [string, "file://./FMCTLU\_connections.xml"] Name of

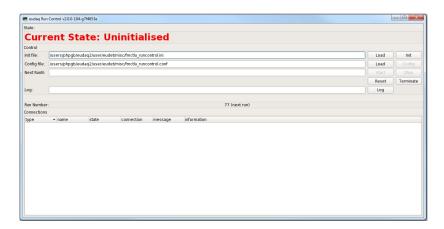


Figure 8.1: Main user iterface of the EUDAQ framework.

- the xml file used to store the information required to communicate with the hardware, such as its IP address and the location of the address map. The default location indicates a file that must be located in the bin folder.
- **DeviceName** [string, "fmctlu.udp"] The name of the type of hardware to be contacted by the IPBus.
- **TLUmod** [string, "1e"] Version of the TLU hardware. Reserved for future use.
- **nDUTs** [positive int, 4] Number of DUT in the current TLU. This is for future upgrades and should not require editing by the user.
- **nTrgIn** [positive int, 6] Number of trigger inputs in the current TLU. This is for future upgrades and should not require editing by the user.
- **I2C\_COREEXP\_Addr** [positive int, 0x21] I<sup>2</sup>C address of the core expander mounted on the Enclustra board. This is not required if a different FPGA is used. See section 2.4 for further details.
- $I2C\_CLK\_Addr$  [positive int, 0x68]  $I^2C$  address of Si5345 clock generator installed on the TLU.
- I2C\_DAC1\_Addr [positive int, 0x13]  $I^2C$  address of DAC installed on the TLU. The DAC is used to configure the threshold of the trigger inputs.
- **I2C\_DAC2\_Addr** [positive int, 0x1F] I<sup>2</sup>C address of DAC installed on the TLU. The DAC is used to configure the threshold of the trigger inputs.
- **I2C\_ID\_Addr** [positive int, 0x50] I<sup>2</sup>C address the unique ID EEPROM installed on the TLU. The chip is used to provide a unique identifier to each kit.
- **I2C\_EXP1\_Addr** [positive int, 0x74]  $I^2C$  address the bus expander used to select the direction of the HDMI pins on the board.
- **I2C\_EXP2\_Addr** [positive int, 0x75]  $I^2C$  address the bus expander used to select the direction of the HDMI pins on the board.
- **intRefOn** [boolean, false] If true, the DACs installed on the TLU will use their internal voltage reference rather than the one provide externally.
- VRefInt [float, 2.5] Value in volts for the internal reference voltage of the DACs. The voltage is chosen by the chip manufacturer. This is only used if intRefOn= true.
- VRefExt [float, 1.3] Value in volts for the external reference voltage of the DACs. The voltage is determined by a circuit on the TLU and the value of this parameter must reflect such voltage. This is only used if intRefOn= false.

8.2. CONF FILE 37

**CONFCLOCK** [boolean, true] If true, the clock chip Si5345 will be reconfigured when the INIT button is pressed (see figure fig.8.1). The chip is configured via I<sup>2</sup>C interface using a specific text file (see next parameter). After a power cycle, the chip is not configured and must be reconfigured to operate the TLU correctly.

CLOCK\_CFG\_FILE [string, "./../user/eudet/misc/fmctlu\_clock\_config.txt"]
 Name of the text file used to store the configuration values of the Si5345.
 The file can be generate using the Clockbuilder Pro software provided by SiLabs.

### 8.2 CONF file

- confid [string, "0"] Does not serve any purpose in the code but can be useful to identify configuration settings used in a specific run. EUDAQ will store this information in the run data.
- **verbose** [int, 0] Defines the level of output messages from the TLU. 0 indicates minimum output.
- **HDMI1\_set** [unsigned int, 0b0001] Defines the source of the signal on the pins for the HDMI1 connector. A 1 indicates that each pin pair is an driven by the TLU, a 0 that they are left floating (with respect to the TLU). This can be used to define the signal direction on each pin pair. The order of the pairs is as follow:
  - bit 0= CONT, bit 1= SPARE, bit 2= TRIG, trig 3= BUSY. Note that the direction of the DUTClk pair is defined in a separate parameter.

Example to configure the connector to work with an EUDET device:

- in this configuration the BUSY line is driven by the device under test, so it is an input for the TLU and should not be driven by it (bit 3= 0)
- TRIGGER line is an output for the TLU so is driven by it (bit 2= 1)
- SPARE line is used to provide control signals, such as the reset signal to initialize the devices at the start of a run  $(T_0)$ . It should be configured as driven by the TLU (bit 1=1)
- CONT is used by the TLU to issue control commands and should be configured as a signal driven by the TLU (bit 0= 1).
- Therefore the value of this parameter would be 0x7 (b1110).
- HDMI2\_set [unsigned int, 0b0001] Defines the direction of the pins for the HDMI2 connector.
- HDMI3\_set [unsigned int, 0b0001] Defines the direction of the pins for the HDMI3 connector.
- HDMI4\_set [unsigned int, 0b0001] Defines the direction of the pins for the HDMI4 connector.

- HDMI1\_clk [unsigned int, 1] Defines if the DUTClk pair on the HDMI connector must be driven by the TLU and, if so, what clock source to use. A 0 indicates that the pins are not driven by the TLU. 1 indicates that pins will by driven with the clock produced from the on-board clock chip Si5345. 2 indicates that the driving clock is obtained from the FPGA. Example to configure the connector to work with an EUDET device: in this scenario the clock is driven by the DUT so the parameter should be set to 0. Example to configure the connector to work with an AIDA device: in this scenario the clock is driven by the TLU so the parameter should be set to either 1 or 2 (by default 1).
- **HDMI2\_clk** [unsigned int, 1] Defines the driving signal on the corresponding HDMI connector.
- **HDMI3\_clk** [unsigned int, 1] Defines the driving signal on the corresponding HDMI connector.
- **HDMI4\_clk** [unsigned int, 1] Defines the driving signal on the corresponding HDMI connector.
- **LEMOclk** [boolean, true] Defines whether a driving clock is to be provided on the differential LEMO connector of the TLU. By default (value= 1), the clock is driven from the clock chip. If the value is set to 0 no clock will be driven.
- in0\_STR [unsigned int, 0] Defines the number of clock cycles used to stretch a pulse once a trigger is detected by the discriminator on input 0. This feature allows the user to modify the pulses that are then fed into the trigger logic within the TLU. A minimum lenght of 6.25 ns is provided if the value is 0. Any extra clock cycle extend the pulse by 6.25 ns (160 MHz clock). An example of the effect on the stretch setting is shown in figure 5.1.
- in0\_DEL [unsigned int, 0] Defines the delay, in 160 MHz clock cycles, to be assigned to the discriminated pulse from input 0, in order to process the logic for the trigger. This can be used to compensate for differences in cable lengths for the signals used to create a trigger.
- in1\_STR [unsigned int, 0] Same as in1\_STR but for input 1.
- in1\_DEL [unsigned int, 0] Same as in1\_DEL but for input 1.
- in2\_STR [unsigned int, 0] Same as in1\_STR but for input 2.
- in2\_DEL [unsigned int, 0] Same as in1\_DEL but for input 1.
- in3\_STR [unsigned int, 0] Same as in1\_STR but for input 3.
- in3\_DEL [unsigned int, 0] Same as in1\_DEL but for input 1.

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**trigMaskHi** [unsigned int32, 0] This word represents the most significative bits of the 64-bits used to determine the trigger mask.

A detailed explanation of how to determine the correct word is provided in section 5.1.

- **trigMaskLo** [unsigned int32, 0] This word represents the least significative bits of the 64-bits used to determine the trigger mask.
  - A detailed explanation of how to determine the correct word is provided in section 5.1.
- **DUTMask** [unsigned int, 0x1] This mask indicates which HDMI inputs have an AIDA device connected. Each of the lowest four bits correspond to a connector (bit 0= DUT1, bit 1= DUT2, bit 2= DUT3, bit 3= DUT4). If the bit is set to 1 the TLU expects a device connected and exchanging signals according to the mode selected (see DUTMaskMode).
- **DUTMaskMode** [unsigned int, 0xFF] Defines the mode of operation of the device connected to a specific HDMI port.

Two bits are needed for each device, so bits 0,1 refer to HDMI1, bits 2, 3 refer to HDMI2, etc. Currently only the lower bit of each pair is needed to specify if the device is in AIDA mode (bX1) or EUDET mode (bx0). Example: to configure device 1 and 2 as EUDET and the rest as AIDA, the parameters should be set to 11-11-x0-x0, i.e. 0xF0 (but 0xFA, 0xF2 and 0xF8 would also work the same). See also section 7.

- DUTMaskModeModifier [unsigned int, 0xF] This mask only affects EUDET mode. Each of the lower 4 bits correspond to a device. If the device is in EUDET mode, it can assert DUTClk to produce a global veto in the triggers. This behaviour occurs if the corresponding bit is set to 1. If the bit is set to 0, asserting the DUTClk from the device will not produce a global veto.
- **DUTIgnoreBusy** [unsigned int, 0xF] This mask tells the TLU to ignore the BUSY signal from a specific device, either in AIDA or EUDET mode. If the device is in AIDA mode, this means that further triggers will be issued while the device is busy. If the device is in EUDET mode, this means that the TLU will not pause while they are in the handshake phase. In turn, this means that the device will likely receive events where the trigger number does not increase sequentially by one.
- **DUTIgnoreShutterVeto** [unsigned int, 0x1] Set bit to 1 to tell the DUT to ignore the shutter signal.
- **EnableRecordData** [boolean, true] if set to 1, enable the data recording in the TLU.

**InternalTriggerFreq** [unsigned int, 0] Defines the rate of the trigger generated internally by the TLU, in Hz: if 0, the internal triggers are disabled. Any other value activates the internal trigger generator with frequency equal to the parameter. Values above 160 MHz are coerced to 160 MHz.

## Chapter 9

# **EUDAQ Producer**

## Current structure of a fmctlu producer event:

```
<Type>2149999981</Type>
<Extendword>171577627</Extendword>
  <Description>Ex0Tg</Description>
<Flag>0x00000018</Flag>
  <RunN>0</RunN>
  <StreamN>0</StreamN>
  <EventN>0</EventN>
  <Block_Size>0</Block_Size>
<SubEvents>
     <Size>1</Size>
    <Event>
      Tags>
<Tag>PARTICLES=89</Tag>
<Tag>SCALER0=93</Tag>
<Tag>SCALER1=93</Tag>
<Tag>SCALER1=93</Tag>
<Tag>SCALER3=0</Tag>
<Tag>SCALER3=0</Tag>
<Tag>SCALER4=0</Tag>
         <Tag>SCALER5=0</Tag>
<Tag>TEST=110011</Tag>
          <Tag>trigger=</Tag>
       </Tags>
       <Block_Size>0</Block_Size>
     </Event>
  </SubEvents>
</Event>
```

### Type ??

#### ExtendWord ??

### Description

Flag Independent from producer. See the EUDAQ documentation for details.

RunN

StreamN

**EventN** 

TriggerN Both in the event and subevent this is written byt the producer with
 ev->SetTriggerN(trigger\_n);

**Timestamp** The event timestamp is currently always 0. subevent timestamps is written by the producer The ev->SetTimestamp(ts\_ns, ts\_ns+25, false);. The top line (0x000000105b44f91, in the example) is coarse time stamp multiplied by 25, so it represents the time in nanoseconds. The bottom one (4390670225) is the same number but written in decimal format instead of hexadecimal.

PARTICLES Number of pre-veto triggers recorded by the TLU: the trigger logic can detect a valid trigger condition even when the unit is vetoed. In this case no trigger is issued to the DUTs but the number of such triggers is stored as number of particles. ev->SetTag("PARTICLES", std::to\_string(pt));

SCALER# Number of triggers edges seen by the specific discriminator.
 ev->SetTag("SCALER", std::to\_string(sl));

**???** Event type from TLU is missing?

??? Input trig, i.e. the actual firing inputs shoud be in TRIGGER but there seems to be nothing there

Chapter 10

Appendix

## 2.4 Iop view

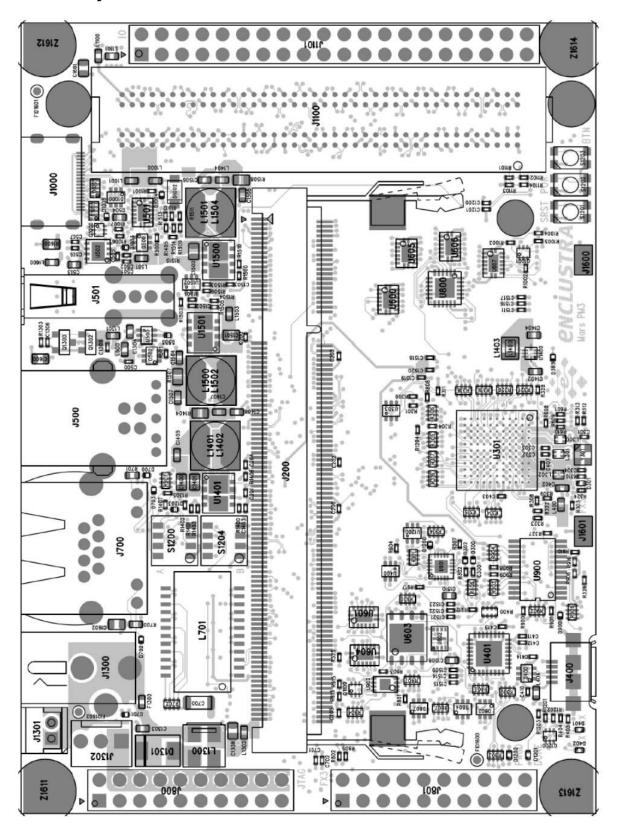


Figure 3: Top view

WOLLAND	CONSTRAINT INSTRUCTION  COT PROPERTY BACKAGE DIN B1 [not north [throughold diser no if0]]]	set_property Factorstinvertigate_poins {timeshold_discr_p_i[3]]} set_property PACKAGE_PIN_C4 [set_points {threshold_discr_p_i[3]}]	set_property PACKAGE_PIN K2 [get_ports {threshold_discr_p_i[2]}]	set_property PACKAGE_PIN C6 [get_ports {threshold_discr_p_i[3]}]	set_property PACKAGE_PIN J4 [get_ports {threshold_discr_p_i[4]}]	set_property PACKAGE_PIN H1 [get_ports {threshold_discr_p_i[5]}]	set_property PACKAGE_PIN A1 [get_ports {threshold_discr_n_i[0]}]	set_property PACKAGE_PIN B4 [get_ports {threshold_discr_n_i[1]}]	set_property PACKAGE_PIN K1 [get_ports {threshold_discr_n_i[2]}]	set_property PACKAGE_PIN C5 [get_ports {threshold_discr_n_i[3]}]	set_property PACKAGE_PIN H4 [get_ports {threshold_discr_n_i[4]}]	set_property PACKAGE_PIN G1 [get_ports {threshold_discr_n_i[5]}]		set_property PACKAGE_PIN T5 [get_ports {sysclk_40_i_p}]	set_property PACKAGE_PIN T4 [get_ports {sysclk_40_i_n}]	set_property PACKAGE_PIN E3 [get_ports {sysclk_50_o_p}]	set_property PACKAGE_PIN D3 [get_ports {sysclk_50_o_n}]	set_property_PACKAGE_PIN_C2 [set_ports {i2c_reset}]	set_property PACKAGE_PIN F6 [get_ports {gpio}]	set_property PACKAGE_PIN C1 [get_ports {clk_gen_rst}]		set_property PACKAGE_PIN P5 [get_ports {cont_i[0]}]	set_property PACKAGE_PIN P3 [get_ports {cont_i[1]}]	set_property PACKAGE_PIN N6 [get_ports {cont_i[2]}]	set_property PACKAGE_PIN L5 [get_ports {cont_i[3]}]	to the second to the second section of the second s	set_property FACKAGE_FIN NIT [Set_ports \spare_i[0]]] set_property PACKAGE_PIN N4 [øet_ports {spare_i[1]}]	set_property_PACKAGE_PIN_N1[get_ports {spare_i[2]}}	set_property PACKAGE_PIN M2 [get_ports {spare_i[3]}]		set_property PACKAGE_PIN R5 [get_ports {triggers_i[0]}]	set_property PACKAGE_PIN R2 [get_ports {triggers_i[1]}]	set_property PACKAGE_PIN T1 [get_ports {triggers_i[2]}]	set_property PACKAGE_PIN V1 [get_ports {triggers_i[3]}]	set_property PACKAGE_PIN T6 [get_ports {busy_i[0]}]	est property DACKAGE DIN 113 [get ports {busy i[11]]	set_property FACMACE_rist O3 [Set_ports [busy_[1]]]	
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100000	PACNAGE_TIM	7 7	: Z	90	4	H1	A1	B4	K1	CS	H4	G1	P17		T4	E3	D3	5	 F6	C1		P5	Р3	N6	51	7	N4 N4	. IZ	M2		R5	R2	T1	V1	T6	113	S &	2
FPGA Side	I A 2.2 D	LA33 P	LA30_P	LA31_P	LA28_P	LA29_P	LA32_N	LA33_N	LA30_N	LA31_N	LA28_N	LA29_N		CLKO_M2C_P	CLK0_M2C_N	CLK1_M2C_P	CLK1_M2C_N	1 A 2 1 B	LA24_N	LA21_N	LA00_P_CC	LA00 N CC	LA01 N CC	LA02 N	LA03_N	200	1A05 N	LA06 N	LA07_N	I 	LA08_N	LA09_N	LA10_N	LA11_N	LA12 N	1413 N	N 1414	5
2	1,01	636	H34	633	H31	630	H38	637	H35	634	Н32	G31		Ь Н4	N H5	P G2	N G3	H25	H29	H26	95	67	60	8H	G10	-	D12	C11	H14		613	D15	C15	H17	G16	210	019	ל <del>ו</del>
Schematic side	FINC_LA	FMC_IA<33>	FMC_LA<30>	FMC_LA<31>	FMC_LA<28>	FMC_LA<29>	FMC_LA*<32>	FMC_LA*<33>	FMC_LA*<30>	FMC_LA*<31>	FMC_LA*<28>	FMC_LA*<29>		FMC_CLK0_M2C_P	FMC_CLK0_M2C_N	FMC_CLK1_M2C_P	FMC_CLK1_M2C_N	FMC 1A<21>	FMC_LA*<24>	- FMC_LA*<21>	FMC_LA<0>	FMC LA*<0>	FMC LA*<1>	FMC_LA*<2>	FMC_LA*<3>	/V/*<	FMC_LA <4×	FMC LA*<6>	FMC_LA*<7>	I	FMC_LA*<8>	FMC_LA*<9>	FMC_LA*<10>	FMC_LA*<11>	FMC LA*<12>	EMC 14*<13>	FMC IA*<14>	57.5
Sch	BEAN TRICKER BACK	BFAM TRIGGER P<1>	BEAM TRIGGER P<2>	BEAM_TRIGGER_P<3>	BEAM_TRIGGER_P<4>	BEAM_TRIGGER_P<5>	BEAM_TRIGGER_N<0>	BEAM_TRIGGER_N<1>	BEAM_TRIGGER_N<2>	BEAM_TRIGGER_N<3>	BEAM_TRIGGER_N<4>	BEAM_TRIGGER_N<5>		CLK_TO_FPGA_P	CLK_TO_FPGA_N	CLK_FROM_FPGA_P	CLK_FROM_FPGA_N	12C RESET N	GPIO	CLK_GEN_RST_N	CLK_GEN_LOL_N	CONT TO FPGA<0>	CONT TO FPGA<1>	CONT TO FPGA<2>	CONT_TO_FPGA<3>	CV VOGE OF EGAGS	SPARE_IO_FFGA<0/	SPARE TO FPGA<2>	SPARE_TO_FPGA<3>	1	TRIG_TO_FPGA<0>	TRIG_TO_FPGA<1>	TRIG_TO_FPGA<2>	TRIG_TO_FPGA<3>	BUSY TO FPGA<0>	BIISY TO EPGA<1>	BUSY TO FPGA<3>	, , , , , , , , , , , , , , , , , , ,

set property PACKAGE PIN 14 feet ports (busy if3]}	Ulcli_Year of Jeer_Till t+ [Ber_Dio State of Jeer_Dio State of Jee	set_property PACKAGE_PIN L3 [get_ports {dut_clk_i[0]}} set_property PACKAGF_PIN F3 [set_ports {dut_clk_i[1]}]	set_property PACKAGE_PIN D2 [get_ports {dut_clk_i]}]	set_property PACKAGE_PIN G3 [get_ports {dut_clk_i[3]}]	set_property PACKAGE_PIN N5 [get_ports {cont_o[0]}]	set_property PACKAGE_PIN P4 [get_ports {cont_o[1]}]	set_property PACKAGE_PIN M6 [get_ports {cont_o[2]}]	set_property PACKAGE_PIN L6 [get_ports {cont_o[3]}]	set_property PACKAGE_PIN L1 [get_ports {spare_o[0]}]	set_property PACKAGE_PIN M4 [get_ports {spare_o[1]}]	set_property PACKAGE_PIN N2 [get_ports {spare_o[2]}]	set_property PACKAGE_PIN M3 [get_ports {spare_o[3]}]	set property PACKAGE PIN R6 [set ports {triggers_o[0]}]	1000 - 10	set_property PACKAGE_PIN P2 [get_ports {triggers_ol_1]}]	set_property PACKAGE_PIN R1 [get_ports {triggers_o[2]}]	set_property PACKAGE_PIN U1 [get_ports {triggers_o[3]}]	set_property PACKAGE_PIN R7 [get_ports {busy_o[0]}]	set_property PACKAGE_PIN U4 [get_ports {busy_o[1]}]	set_property PACKAGE_PIN R8 [get_ports {busy_o[2]}]	set_property PACKAGE_PIN K5 [get_ports {busy_o[3]}]	set_property PACKAGE_PIN K3 [get_ports {dut_clk_o[0]}]	set_property PACKAGE_PIN F4 [get_ports {dut_clk_o[1]}]	set_property PACKAGE_PIN E2 [get_ports {dut_clk_o[2]}]	set_property PACKAGE_PIN G4 [get_ports {dut_clk_o[3]}]		
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<u>4</u>	ţ	១ ជ	 D2	63	NS	P4	M6	97	11	M4	N2	M3	R6	2 2	P2	R1	N1	R7	U4	R8	5		<b>F</b> 4		<b>G4</b>		
N 215 N	N CTA	LA16_N LA17_N_CC	LA18 N CC	LA19_N	LA00_P_CC	LA01_P_CC	LA02_P	LA03_P	LA04_P	LA05_P	LA06_P	LA07_P	I AOS P		LAU9_P	LA10_P	LA11_P	LA12_P	LA13_P	LA14_P	LA15_P	LA16_P	LA17_P_CC	LA18_P_CC	LA19_P		
H20	0.70	G19 D21	C23	H23	95	D8	Н7	69	H10	D11	C10	H13	612	7 7 7	D14	C14	H16	G15	D17	C18	H19	618	D20	C22	H22		
FMC 1A*<15>	751 VI - 101	FMC_LA*<16> FMC_IA*<17>	FMC_LA*<18>	FMC_LA*<19>	FMC_LA<0>	FMC_LA<1>	FMC_LA<2>	FMC_LA<3>	FMC_LA<4>	FMC_LA<5>	FMC_LA<6>	FMC_LA<7>	FMC 1A<8>		FIMIC_LA<9>	FMC_LA<10>	FMC_LA<11>	FMC_LA<12>	FMC_LA<13>	FMC_LA<14>	FMC_LA<15>	FMC_LA<16>	FMC_LA<17>	FMC_LA<18>	FMC_LA<19>		
RUSV TO EPGA<2>	77.45.1-01-150g	DUT_CLK_TO_FPGA<0>	DUT CLK TO FPGA<2>	DUT_CLK_TO_FPGA<3>	CONT_FROM_FPGA<0>	CONT_FROM_FPGA<1>	CONT_FROM_FPGA<2>	CONT_FROM_FPGA<3>	SPARE_FROM_FPGA<0>	SPARE_FROM_FPGA<1>	SPARE_FROM_FPGA<2>	SPARE_FROM_FPGA<3>	TRIG FROM FPGA<0>	TELO EBONA EDONALA	KIG_FKOIM_FPGA<1>	TRIG_FROM_FPGA<2>	TRIG_FROM_FPGA<3>	BUSY_FROM_FPGA<0>	BUSY_FROM_FPGA<1>	BUSY_FROM_FPGA<2>	BUSY_FROM_FPGA<3>	DUT_CLK_FROM_FPGA<0>	DUT_CLK_FROM_FPGA<1>	DUT_CLK_FROM_FPGA<2>	DUT_CLK_FROM_FPGA<3>		

