

Bound within Boundaries: How Well Do Protected Areas Match Movement Corridors of Their Most Mobile Protected Species?

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April 5, 2021

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Running Title: Connectivity across a Transfrontier Conservation Area.

Keywords: dispersal, habitat selection, integrated step selection function,
Kavango-Zambezi Transfrontier Conservation Area, landscape connectivity, African wild
dog, movement

Abstract

1. Conserving and managing large portions of land to connect wildlife reserves is an increasingly used strategy to maintain and restore connectivity among wildlife populations. Boundaries of such conservation areas are often determined based on expert opinion and socio-political constraints, yet the extent to which they match species' movement corridors is rarely examined. This is mainly due to a lack of data, particularly on wide-ranging movement behavior such as dispersal. Nevertheless, empirically assessing the adequacy of protected areas is key for the implementation of targeted management actions and efficient use of limited conservation funds.
2. Between 2011 and 2019, we collected high-resolution GPS data on 16 dispersing African wild dog (*Lycaon pictus*) coalitions from a free-ranging population in the Kavango-Zambezi Transfrontier Conservation Area (KAZA-TFCA). Spanning five countries and 520'000 km² the KAZA-TFCA is the world's largest transboundary conservation area and a prime example for international conservation efforts. We used integrated step selection analysis to estimate habitat selection of dispersers and to create a permeability surface for the KAZA-TFCA. We compared landscape permeability across different regions within the KAZA-TFCA as well as outside its boundaries. Lastly, we calculated least-cost paths and corridors to verify that major movement routes were adequately encompassed within the KAZA-TFCA.
3. Permeability within the boundaries of the KAZA-TFCA was more than double compared to areas outside it. Furthermore, we observed a five-fold permeability difference among the five KAZA-TFCA countries. We also showed that major movement corridors of wild dogs ran within the KAZA-TFCA, although some minor routes remained formally unprotected.
4. Differences in permeability were mainly related to different degrees of human activities across regions, and to the presence or absence of rivers, swamps and open water. The relationship between permeability and other landscape features was less pronounced.
5. *Synthesis and Applications:* In this study, we showed how pertinent dispersal data of a highly mobile species can be used to empirically evaluate the adequacy of already-existing or planned protected areas. Furthermore, we observed regional differences in landscape permeability that highlight the need for a coordinated effort towards maintaining or restoring connectivity, especially where transboundary dispersal occurs.

1 Introduction

2 Connectivity among subpopulations is a crucial pre-requisite for many species to thrive
3 and persist (Fahrig, 2003). Accordingly, preserving and protecting movement corridors be-
4 tween wildlife reserves has become a task of utmost importance (Doerr et al., 2011; Rudnick
5 et al., 2012), resulting in an ever-growing number of large and often transboundary pro-
6 tected areas. While boundaries of such areas are often drawn according to expert opinion
7 and socio-political needs, subjective assessments have revealed deficiencies in the past (Cle-
8 venger et al., 2002; Pullinger and Johnson, 2010). Thus, an empirical evaluation of the
9 adequacy of already-existing or planned protected areas using pertinent animal movement
10 data is paramount for targeted use of valuable and scarce conservation funds (Pullinger and
11 Johnson, 2010).

12 In recent years, a growing body of research has used animal relocation data to identify
13 movement corridors and assess connectivity at large scales (e.g. Chetkiewicz et al., 2006;
14 Squires et al., 2013; Elliot et al., 2014). Identification of potential movement corridors typi-
15 cally relies on the estimation of permeability surfaces, which return the ease or willingness at
16 which the focal species traverses a specific landscape (Sawyer et al., 2011). Such surfaces are
17 created based on species' relative selection strengths (Avgar et al., 2017), which can be quan-
18 tified using a suite of selection functions (Zeller et al., 2012). Specifically, selection strengths
19 are estimated by comparing spatial covariates (e.g. environmental and anthropogenic) at
20 locations visited by the animal to the same spatial covariates at locations available to the
21 animal (Zeller et al., 2012). Importantly, selection functions require adequate landscape
22 and relocation data that are representative of the process being studied (Diniz et al., 2019).
23 Altough selection during residence and dispersal may coincide (Fattebert et al., 2015), it
24 appears that relocation data collected on dispersing individuals outperforms data collected
25 on resident individuals in the detection of large-scale movement corridors (Elliot et al., 2014;
26 Abrahms et al., 2017; Diniz et al., 2019). Nevertheless, dispersal data is inherently difficult
27 to collect and remains scarce in the connectivity literature (Vasudev et al., 2015). As such,
28 most permeability surfaces upon which movement corridors are identified are created using
29 relocation data collected on resident individuals. This has likely limited our ability to mean-
30 ingfully assess the effectiveness of protected areas in securing connectivity for their protected
31 species.

32 One initiative that aims at restoring and enhancing connectivity across large scales is the
33 Kavango-Zambezi Transfrontier Conservation Area (KAZA-TFCA), which constitutes the
34 world's largest transfrontier conservation area, spanning over 520'000 km² and five coun-

tries (www.kavangozambezi.org). While the KAZA-TFCA was originally set to facilitate movements of African elephants (*Loxodonta africana*; Tshipa, 2017), it is also key to the conservation of other wide-ranging species such as African wild dogs (*Lycaon pictus*; Woodroffe and Sillero-Zubiri, 2012; Cozzi et al., 2020), lions (*Panthera leo*; Elliot et al., 2014; Cushman et al., 2018), and cheetahs (*Acinonyx jubatus*; Weise et al., 2017). To date, however, few studies have attempted to assess the adequacy of the KAZA-TFCA using global positioning system (GPS) relocation data of its protected species at large spatial scales (Elliot et al., 2014; Tshipa, 2017; Brennan et al., 2020). Thus, how well the boundaries of the KAZA-TFCA reflect natural movement patterns and dispersal corridors of its most mobile protected species is virtually unknown.

Across the KAZA-TFCA, the African wild dog (*Lycaon pictus*) represents a highly mobile and endangered flagship species for conservation efforts. Once widespread across the entire Sub-Saharan continent, wild dogs have been widely extirpated through human persecution, habitat destruction, and disease outbreaks (Woodroffe and Sillero-Zubiri, 2012). For these reasons, viable populations mainly occur in spatially scattered subpopulations within protected areas (Woodroffe and Ginsberg, 1999; Woodroffe and Sillero-Zubiri, 2012; Van der Meer et al., 2014). Within these subpopulations, wild dogs form cooperative breeding packs of up to thirty individuals (Creel and Creel, 2002), whose social structure is strongly governed by the process of dispersal (McNutt, 1996; Behr et al., 2020). Both males and females disperse from their natal pack, either alone or in same-sex dispersing coalitions, and search for unrelated mates and a suitable territory to settle (McNutt, 1996; Cozzi et al., 2020; Behr et al., 2020). During dispersal, wild dogs can cover several hundred kilometers and cross international borders (Masenga et al., 2016; Woodroffe et al., 2019; Cozzi et al., 2020). Despite the importance of dispersal for the long-term viability of this species, little empirical information is available on habitat selection and potential movement barriers during dispersal. The few studies that have collected dispersal data have shown that dispersers quickly move over large distances, avoid human-dominated landscapes and areas densely covered by trees, but prefer proximity to water (Masenga et al., 2016; Woodroffe et al., 2019; O'Neill et al., 2020; Cozzi et al., 2020).

Here, we collected and analyzed GPS relocation data on 16 dispersing wild dogs in as many dispersing coalitions from a free-ranging population in northern Botswana to assess the adequacy of the KAZA-TFCA in securing connectivity. We estimated relative selection strengths towards environmental and anthropogenic landscape features, and used the obtained coefficients to predict a permeability surface spanning the entire KAZA-TFCA.

69 We then investigated how landscape permeability varied regionally and internationally, and
70 we compared permeability within and outside the KAZA-TFCA boundaries. Finally, we
71 calculated least-cost paths and corridors to identify major movement routes and to verify
72 that these were successfully covered by the KAZA-TFCA.

73 **2 Materials and Methods**

74 **2.1 Study Area**

75 The study area (centered at -17°13'9"S, 23°56'4"E; Figure 1a) was outlined by a rectangu-
76 lar bounding box stretching over 1.3 Mio km² and encompassing the entire KAZA-TFCA
77 (Figure 1b). The KAZA-TFCA lies in the basins of the Okavango and Zambezi rivers and
78 includes parts of Angola, Botswana, Namibia, Zimbabwe, and Zambia. With a total area of
79 over 520'000 km² it constitutes the earth's largest transboundary conservation area and is
80 characterized by diverse landscapes, including savanna, grassland, and dry or moist wood-
81 land habitats. Rainfall in the study area is seasonal and lasts from November to March.
82 The KAZA-TFCA also comprises the Okavango Delta, which represents a highly dynamic
83 hydrological flood-pulsing system (McNutt, 1996; Wolski et al., 2017). The extent of the
84 flood in the delta greatly changes within and between years, depending on the amount
85 of rain that descends from the catchment areas in Angola and reaches the distal ends of
86 the delta between July and August (Figure S4). The flood drastically affects surrounding
87 landscapes, so that during maximum extent (ca. 12'000 km²) the delta becomes a patchy
88 conglomerate of swamps, open water, and islands, whereas these structures run dry when
89 the flood retracts to its minimum extent (ca. 5'000 km²; Wolski et al., 2017). Despite 36
90 national parks (NPs) and other protected areas, there is considerable human influence in
91 some regions of the KAZA-TFCA, mainly originating from farms, human density, and road
92 traffic.

93 **2.2 GPS Relocation Data**

94 We used a population of free-ranging African wild dogs inhabiting the Okavango Delta in
95 northern Botswana as a source population for dispersing individuals. This population has
96 been extensively studied since 1989 (McNutt, 1996; Cozzi et al., 2013, 2020; Behr et al.,
97 2020). Between 2011 and 2019, we systematically collected GPS relocation data on 16
98 coalitions of dispersing African wild dogs (7 female and 9 male coalitions). Candidate
99 dispersing individuals were identified based on age, number of same-sex siblings, pack size,

and presence of unrelated individuals of the opposite sex in their pack (McNutt, 1996; Behr et al., 2020). Selected individuals were immobilized according to protocols described in Osofsky et al. (1996), and fitted with GPS/Satellite radio collars (*Vertex Lite*; *Vectronic Aerospace GmbH, Berlin, Germany*) while still with their natal pack. Collars weighed 330g, accounting for about 1.5% of a wild dog's body weight. A 5cm long decomposable cotton piece was added to the collar belt to guarantee collar drop-off after about 12-18 months. All required procedures were undertaken and supervised by a Botswana-registered wildlife veterinarian. During dispersal, GPS collars were programmed to record a GPS relocation every 4 hours and to regularly transmit data via iridium satellite system to a base station.

Because we were interested in dispersal behavior only, we discarded any GPS data collected while individuals were still with their natal packs and after settlement in a new territory (Cozzi et al., 2020). We identified the exact time of emigration and settlement based on direct field observations and through visual inspection of the net squared displacement (NSD) metric. NSD quantifies the squared Euclidean distance of a relocation to a reference point (Börger and Fryxell, 2012), which in our case was the center of the dispersing coalition's natal home range. Thus, dispersal was deemed to have started when a coalition had left its natal home range and continued until the NSD metric remained stationary, indicating that the coalition had successfully settled (Figure S1 in Supporting Information). In our analysis, we did not differentiate between male and female dispersing coalitions, for previous research found little differences between sexes during dispersal (Woodroffe et al., 2019; Cozzi et al., 2020).

2.3 Spatial Covariates

To investigate relative selection strengths of dispersing wild dogs, we used a set of georeferenced covariates (Figure 2) that we aggregated in the categories *land cover*, *protection status*, and *anthropogenic*. *Land cover* comprised the covariates water cover (binary), distance to water (continuous), percentage cover by shrubs/grassland (continuous), and percentage cover by trees (continuous). To capture the pulsing behavior of the Okavango Delta, we classified satellite imagery and frequently updated layers for water cover and corresponding layers depicting distance to water. *Protection status* contained a binary covariate, indicating whether an area was protected or not. *Anthropogenic* included covariates rendering the presence of roads (binary), the distance to roads (continuous), and a proxy for human influence (continuous) that took into account human density, farming, and roads. We prepared all covariates as spatial raster layers from freely available online services and

133 from remotely sensed satellite imagery. To ensure a consistent resolution (i.e. cell-size or
134 grain) across covariates, we coarsened or interpolated all layers to a resolution of 250m x
135 250m. For further details on the preparation and source of each covariate, see Appendix
136 A.3. We performed processing and manipulation of data as well as all spatial and statistical
137 analyses using R, version 3.6.1 (R Core Team, 2019).

138 **2.4 Habitat Selection Model**

139 We used an integrated step selection function (iSSF; Avgar et al., 2016) to investigate
140 dispersers' relative selection strengths towards the above-mentioned spatial covariates. That
141 is, we paired each realized step (i.e. the connecting line between two consecutive GPS
142 relocations; Turchin, 1998) with 24 random steps that were generated by sampling turning
143 angles from a uniform distribution $U(-\pi, +\pi)$ and step lengths from a gamma distribution
144 fitted to realized steps (Avgar et al., 2016). A realized step and its 24 associated random
145 steps formed a stratum and received a unique identifier. Along each step, we extracted
146 the above-mentioned covariates (Table S3), standardized extracted values using a z-score
147 transformation, and checked for correlation using Pearson's Correlation Coefficient r . None
148 of the covariates were overly correlated ($|r| > 0.6$; Latham et al., 2011) and we retained
149 all of them for modeling. Our habitat selection model then assumed that dispersing wild
150 dogs assigned a selection score $w(x)$ of the following exponential form to each realized and
151 random step (Fortin et al., 2005):

$$w(x) = \exp(\beta_1 x_1 + \beta_2 x_2 + \dots + \beta_n x_n) \quad (\text{Equation 1})$$

152 The selection score $w(x)$ of a step depended on its associated covariates (x_1, x_2, \dots, x_n) , as
153 well as on the animal's relative selection strengths towards these covariates $(\beta_1, \beta_2, \dots, \beta_n)$.
154 To estimate relative selection strengths (i.e. the β 's) for each covariate, we used mixed effects
155 conditional logistic regression analysis as suggested by Muff et al. (2020). We implemented
156 their method using the R-package *glmmTMB* (Brooks et al., 2017) and used dispersing
157 coalition ID to model random slopes. We also modelled random intercepts with an arbitrary
158 high variance of 10^6 to make use of the poisson trick (see Muff et al., 2020). We defined three
159 movement metrics, namely the cosine of the turning angle ($\cos(ta)$), the step length (sl) and
160 the logarithm of the step length ($\log(sl)$), as core covariates and ran stepwise forward model
161 selection based on Akaike's Information Criterion (AIC; Burnham and Anderson, 2002) for
162 all other covariates. The inclusion of movement metrics served to reduce biases in estimated
163 habitat selection coefficients that may have arisen due to movement behavior (Avgar et al.,

¹⁶⁴ 2016). To validate the predictive power of the most parsimonious habitat selection model,
¹⁶⁵ we ran k-fold cross-validation for case-control studies as described in Fortin et al. (2009)
¹⁶⁶ (details in Appendix A.5).

¹⁶⁷ 2.5 Permeability Surface

¹⁶⁸ Using the most parsimonious habitat selection model, we predicted a permeability surface
¹⁶⁹ spanning the entire extent of the KAZA-TFCA. That is, we applied Equation 1 to our
¹⁷⁰ spatial covariates and calculated the selection score $w(x)$ for each raster cell. Because our
¹⁷¹ representation of water was dynamic, we collapsed all dynamic water maps into a single
¹⁷² map using areas that were covered by water in at least 10% of the cases. We used the
¹⁷³ resulting map to also calculate a layer returning the distance to water. Because the delta
¹⁷⁴ only covers 5% of the KAZA-TFCA, we considered the use of a single water map to be
¹⁷⁵ appropriate. To reduce the influence of outliers in predicted permeability scores, we followed
¹⁷⁶ Squires et al. (2013) and curtailed predicted scores between the 1st and 99th percentile of
¹⁷⁷ their original values. To compare permeability across different regions, we normalized the
¹⁷⁸ permeability surface to a range between 0 (most impermeable) and 1 (most permeable),
¹⁷⁹ and we determined median permeability within and outside the KAZA-TFCA, within and
¹⁸⁰ outside formally protected areas, and within each of the five KAZA-TFCA countries.

¹⁸¹ 2.6 Least-Cost Paths and Corridors

¹⁸² To identify potential movement corridors of dispersing wild dogs, we specified source points
¹⁸³ and calculated factorial least-cost paths (LCPs) as well as factorial least-cost corridors
¹⁸⁴ (LCCs) among them (Elliot et al., 2014). To select source points, we followed the om-
¹⁸⁵ nidirectional *go-through* approach proposed by Koen et al. (2014) and placed 68 regularly
¹⁸⁶ spaced source points along the map border (Koen et al., 2014; Pitman et al., 2017). While
¹⁸⁷ this approach tends to identify high connectivity towards the map boundaries, it reduces
¹⁸⁸ potential biases caused by the selection of unreasonable source points (Koen et al., 2014). To
¹⁸⁹ assess the sensitivity of our results with respect to the location of source points, we reran the
¹⁹⁰ same analysis using 68 source points located within protected areas that are large enough to
¹⁹¹ sustain viable wild dog populations (further details and corresponding results in Appendix
¹⁹² A.9). In either case, the 68 source points resulted in 2'278 unique pairwise combinations and
¹⁹³ therefore 2'278 unique LCPs and LCCs. We computed factorial LCPs and LCCs between
¹⁹⁴ source points using the R-package *gdistance* (details in Appendix A.6). After computation,
¹⁹⁵ we tallied overlapping LCPs and LCCs, respectively, into single connectivity maps. Because

¹⁹⁶ LCPs return discrete paths, whereas LCCs return continuous corridors, we present both
¹⁹⁷ methods. R-codes showcasing the main steps for sections 2.5 to 2.6 can be downloaded from
¹⁹⁸ GitHub (<https://github.com/DavidDHofmann/LeastCostAnalysis>).

¹⁹⁹ 3 Results

²⁰⁰ 3.1 Dispersal Events

²⁰¹ In total, we collected 4'169 GPS relocations during dispersal (Figure S2 & Table S1), re-
²⁰² sulting in an average of 261 ($SD = 207$) locations per dispersing coalition. Coalitions on
²⁰³ average dispersed for 48 days ($SD = 44$), covered a mean Euclidean distance of 54 km (SD
²⁰⁴ = 71) and a cumulative distance of 597 km ($SD = 508$).

²⁰⁵ 3.2 Habitat Selection Model

²⁰⁶ Our most parsimonious habitat selection model ($\Delta AIC > 2$ than any alternative model;
²⁰⁷ Table S4) retained the covariates *water*, *distance to water*, *trees*, *shrubs/grassland*, and
²⁰⁸ *human influence*, beside the fixed covariates *cos(ta)*, *sl*, and *log(sl)* (Figure 3a). Dispersers
²⁰⁹ avoided moving through water ($\beta = -0.53$, 95% CI -0.79 to -0.27) but selected for locations
²¹⁰ in its vicinity, although the latter effect was not significant ($\beta = -0.33$, 95% CI = -0.73 to
²¹¹ 0.08). Dispersers avoided areas that were densely covered by trees ($\beta = -0.31$, $CI = -0.47$
²¹² to -0.15) and preferred areas covered by shrubs/grassland ($\beta = 0.25$, 95% CI = 0.07 to
²¹³ 0.42). Finally, dispersers avoided areas that were influenced by humans ($\beta = -0.45$, 95% CI
²¹⁴ = -0.82 to -0.08). Except for *distance to water* ($SD_{RandomEffect} = 0.57$), we observed little
²¹⁵ variation between dispersal coalitions' relative selection strengths ($SD_{RandomEffect} < 0.22$
²¹⁶ for all other covariates, see also Figure S8).

²¹⁷ Results from the k-fold cross-validation suggested that our prediction was significant and
²¹⁸ robust, as highlighted by the fact that the 95%-CIs intervals of $\bar{r}_{s,realized}$ and $\bar{r}_{s,random}$ did
²¹⁹ not overlap (Figure 3b). Likewise, the significant correlation between ranks and correspond-
²²⁰ ing frequencies for realized steps suggested a good fit between predictions and observations
²²¹ (Figure 3b).

²²² 3.3 Permeability Surface

²²³ Our prediction of landscape permeability revealed substantial differences across regions in
²²⁴ the study area (Figure 4). Comparisons of median permeability values (Table 1) showed
²²⁵ that permeability inside the KAZA-TFCA was more than two times as high as permeability

226 outside it. Permeability varied by country, with a five-fold permeability difference among
227 them. Angola and Botswana were characterized by comparably highly permeable landscapes,
228 Zimbabwe and Zambia were relatively impermeable, and Namibia ranged in between the two
229 extremes (Table 1). Visual inspection of our covariate layers indicated that high permeability
230 in Angola and Botswana was mainly related to a combination of low human influence, low
231 tree cover, high shrubs/grassland cover, and a close distance to water. Although swamps,
232 wetlands, and permanent water themselves provided little permeability, their surroundings
233 acted as strong attractants to dispersers. The low permeability that characterized Zambia
234 and Zimbabwe, on the other hand, was mainly caused by substantial human influence.
235 Albeit the KAZA-TFCA covered most permeability hot-spots, several highly permeable
236 regions remained uncovered by its borders. Across all countries, protected areas provided
237 roughly double the permeability of unprotected landscapes (Table 1).

238 **3.4 Least-Cost Paths & Least-Cost Corridors**

239 Our least-cost analysis revealed three major movement corridors of which all were well-
240 contained within the KAZA-TFCA boundaries (Figure 5). One major corridor ran SE-NW
241 and connected the Okavango-Linyanti ecosystem in Botswana with Luengue-Luiana NP in
242 Angola. A second corridor ran W-E between Chobe NP in Botswana and Zimbabwe's
243 Hwange NP. A third major corridor ran NE-SW, completely across unprotected areas, and
244 connected Kafue NP in Zambia with more central regions of the KAZA-TFCA. Several
245 minor corridors branched off from these three major corridors; these included a south-
246 ward connection between the Okavango-Linyanti and the Central Kalahari Game Reserve,
247 a southwesterly corridor connecting Luengue-Luiana NP with Namibia's Khaudum NP, and
248 a northeasterly extension of the Hwange corridor into Zimbabwe's Matusadona NP. Accord-
249 ing to our predictions, the landscapes in the Okavango-Linyanti region were the highest
250 frequented dispersal routes within the KAZA-TFCA (Figure 5b). Our model did not de-
251 tect any significant direct corridors between Zimbabwe and Zambia or Zambia and Angola,
252 and only a very limited W-E direct connection between the Okavango region and Namibia's
253 Khaudum NP. Except for the corridor into the Central Kalahari National Park, our model
254 did not detect any significant connectivity outside the boundaries of the KAZA-TFCA. Fur-
255 thermore, we found little to no direct connectivity between peripheral points; that is, most
256 paths and corridors connecting two adjacent peripheral points ran through more central
257 regions before heading towards their destination at the periphery (Figure 5).

258 **4 Discussion**

259 We used GPS relocation data collected on dispersing African wild dogs to investigate whether
260 their main movement corridors are contained within the boundaries of the world's largest
261 transboundary conservation area, namely the KAZA-TFCA. Our analysis suggests that the
262 KAZA-TFCA indeed encompasses all major corridors of African wild dogs, demonstrating
263 the potential value of such an initiative. We thus exemplified how pertinent dispersal data
264 of a highly mobile species can be used to assess the adequacy of already existing or planned
265 protected areas. Our approach is neither limited to the African wild dog, nor to our study
266 area and thus applicable to any study system. All covariates used throughout this study
267 are readily available on a global scale and many of them are likely to be important deter-
268 minants of movement behavior, landscape permeability, and connectivity for other species
269 (Zeller et al., 2012; Thurfjell et al., 2014). Interestingly, our predicted network of least
270 cost-paths and corridors for African wild dogs shows surprising similarities to corridors of
271 dispersing lions inhabiting the same ecosystem (Elliot et al., 2014; Cushman et al., 2018).
272 This not only reinforces confidence in our own predictions but also suggests potential syner-
273 gies for the conservation of these two, and possibly more, species. Expanding our analytical
274 framework to additional species will likely yield important insights on the consistency of
275 inter-specific movement corridors, thus highlighting areas that are exceptionally valuable for
276 the conservation of several species (e.g. Brennan et al., 2020).

277 Our results emphasize that human influences constitute some of the main barriers to
278 connectivity among wild dog populations. This conforms to findings on dispersing wild
279 dogs from eastern Africa (Masenga et al., 2016; O'Neill et al., 2020) but conflicts with
280 findings from South Africa by Davies-Mostert et al. (2012), who reported a high willingness
281 of dispersers to cross human-dominated landscapes. Such differences may arise from the fact
282 that our model infers preferences by comparing *used* and *available* habitats, whereas Davies-
283 Mostert et al. (2012) only recorded net dispersal distances, thereby precluding such an
284 analysis. Thus, we believe that differences to Davies-Mostert et al. (2012) may be explained
285 by the unavailability of alternative routes through natural landscapes, which may have forced
286 dispersers in South Africa to cross human dominated landscapes despite a strong aversion to
287 do so. In this regard, our representation of dispersal corridors and the resulting connectivity
288 appear conservative, as dispersers may be able to make the best out of a bad situation and
289 cross landscapes characterized by considerably unfavorable conditions (Palomares et al.,
290 2000; Elliot et al., 2014). Nevertheless, successful conservation of this species relies on
291 policymakers' and local authorities' willingness and ability to provide and conserve natural

292 areas that remain free from anthropogenic pressures. This is not only paramount in light
293 of increasing connectivity and facilitating dispersal, but also in terms of reducing human-
294 caused mortality during dispersal. In fact, previous studies have shown that human-caused
295 mortality represents a major threat to wild dogs' ability to disperse (Woodroffe et al., 2019;
296 Cozzi et al., 2020).

297 Besides human influence, we identified water as additional obstacle to dispersal. This
298 corroborates earlier studies showing that water bodies are almost impenetrable to resident
299 packs (Abrahms et al., 2017) and only infrequently crossed by dispersing individuals (Cozzi
300 et al., 2020). An accurate and dynamic representation of water is thus imperative and
301 particularly relevant in seasonal or flood-pulsing ecosystems such as the Okavango Delta.

302 Although dispersers avoided moving through water, they selected locations in its vicinity.
303 This behavior may be caused by the occurrence of prey close to water (Bonyongo, 2005). For
304 the same reason, however, competitors such as lions, spotted hyenas, and resident wild dogs
305 may also use areas close to water (Valeix et al., 2010), thereby occasionally forcing dispersing
306 wild dogs to switch behavior and move into prey-poorer areas away from water (Creel and
307 Creel, 2002; Mills and Gorman, 1997). This may explain the large confidence intervals
308 for the corresponding β -estimate of *distance to water*. Given the influence that resident
309 conspecifics, competitors, and prey can have on dispersers (Cozzi et al., 2018; Armansin
310 et al., 2019) future studies should strive to collect and incorporate intra- and interspecific
311 relationships into analyses of landscape connectivity.

312 Overall, our findings on habitat selection during dispersal coincide with findings from
313 dispersing wild dogs in Kenya (O'Neill et al., 2020) and Tanzania (Masenga et al., 2016),
314 suggesting that there are strong commonalities between dispersers from these very different
315 ecosystems. Thus, despite wild dogs' ability to cope with diverse habitats and adapt to
316 changing conditions (Woodroffe, 2011), the fundamental factors included in our study appear
317 to influence wild dogs from other ecosystems alike. Nevertheless, expanding our analysis to
318 dispersers emigrating from other source populations would invaluable contribute to our
319 understanding of dispersal.

320 Locally, we identified the Okavango-Linyanti region as a potential dispersal hub through
321 which dispersing wild dogs gain access to more peripheral regions of the KAZA-TFCA.
322 It appears that the absence of human activities, the central position within the KAZA-
323 TFCA, and the presence of relatively impermeable water bodies (e.g. Okavango Delta,
324 Linyanti Swamp) funnel dispersal movements, resulting in a highly frequented corridor.
325 Furthermore, the lack of permeable areas between peripheral source points often resulted

326 in corridors stretching longer Euclidean distances, in an arc-shaped route via a stretch of
327 suitable habitat through the Okavango-Linyanti ecosystem. This is an expected outcome
328 in case structural and functional connectivity coincide, i.e. when dispersers follow suitable
329 habitats to disperse (Fattebert et al., 2015; Hauenstein et al., 2019). The key role of the
330 Okavango-Linyanti region for overall connectivity within the KAZA-TFCA thus calls for
331 actions to secure its protection status in the future. While the region is currently a Wildlife
332 Management Area, it has neither the status of a National Park nor that of a Game Reserve.
333 A similar case of non-formally protected but key dispersal landscape is represented by the
334 area south of Kafue NP in Zambia, for which a disruption of its main and narrow dispersal
335 corridor or high disperser mortality due for example to human persecution or vehicle collision
336 would result in considerable isolation of its subpopulations. We also revealed a potential
337 southwards corridor between the Okavango-Linyanti ecosystem and the Central Kalahari
338 National Park. Elliot et al. (2014) and Cushman et al. (2018) identified a similar corridor for
339 dispersing lions, suggesting that upholding and protecting a link between those ecosystems
340 is pivotal. Some areas through which the corridor runs are neither part of the KAZA-TFCA
341 nor profit from any form of protection status. Human presence and activities along the
342 national road that longitudinally traverses this corridor may limit functional connectivity
343 (Cozzi et al., 2020).

344 Our approach of identifying movement corridors based on pre-defined start and end
345 points implicitly assumes that individuals know the end point of their dispersal journey and
346 that they have almost complete knowledge of associated movement costs (Panzacchi et al.,
347 2016). Since dispersers often move into unknown territory, this may not necessarily be the
348 case (Abrahms et al., 2017; Cozzi et al., 2020). However, specification of pre-defined end
349 points might not be necessary, as the parametrized iSSF model can be used as mechanistic
350 movement model to simulate dispersal from known source points, yet without restricting
351 the domain of potential end points (Signer et al., 2017). Consequently, movement corridors
352 would emerge more naturally as the result of a myriad of simulated dispersal events (Allen
353 et al., 2016; Zeller et al., 2020).

354 Besides estimating corridors, individual based simulations may be used to generate per-
355 meability surfaces (Avgar et al., 2016; Signer et al., 2017). Such simulation based surfaces
356 have been shown to reduce the risk of overestimating permeability ($w(x)$) and consequently
357 connectivity, particularly in areas that lie far from suitable habitats (Signer et al., 2017).
358 While a simulation-based approach is conceptually straightforward, computational require-
359 ments for such a large spatial extent as the KAZA-TFCA are very high, making the use of

360 this approach challenging. We therefore urge future studies to optimize the simulation of
361 movement from iSSFs to capture a more mechanistic model of dispersal.

362 Our work shows how dispersal data of a highly mobile species can be used to identify
363 movement corridors and to assess the adequacy of protected areas. In our case, the predicted
364 movement corridors of African wild dogs were well contained within the boundaries of the
365 world's largest transboundary conservation area, namely the KAZA-TFCA, suggesting that
366 it will significantly contribute to the long-term viability of this species. Moreover, our
367 connectivity network allowed revealing potential dispersal hubs through which dispersers
368 gain access to more remote regions of the study area. Finally, our investigations showed
369 that human influence constitutes one of the main barriers to dispersal and substantially
370 reduces landscape connectivity. Successful conservation of wide-ranging species, such as
371 exemplified by the African wild dog, will therefore be contingent on the willingness of local
372 authorities, policymakers, and land managers to preserve areas that remain free from human
373 strains. Ultimately, our work contributes to the growing field of connectivity studies and
374 provides an easily expandable framework for assessing the adequacy of already-existing or
375 planned protected areas.

376 **5 Authors' Contributions**

377 D.D.H., D.M.B., A.O. and G.C. conceived the study and designed methodology; D.M.B.,
378 G.C., and J.W.M. collected the data; D.D.H. and D.M.B. analysed the data; G.C. and A.O.
379 assisted with modelling; D.D.H., D.M.B., and G.C. wrote the first draft of the manuscript
380 and all authors contributed to the drafts at several stages and gave final approval for pub-
381 lication.

382 **6 Data Availability Statement**

383 GPS movement data of dispersing coalitions available via the Dryad Digital Repository
384 doi:10.5061/dryad.dncjsxkzn (Hofmann et al., 2021). R-code showcasing the main steps for
385 sections 2.5 to 2.6 can be obtained through GitHub (<https://github.com/DavidDHofmann/LeastCostAnalysis>).
386

³⁸⁷ **7 Acknowledgements**

³⁸⁸ We thank the Ministry of Environment and Tourism of Botswana for granting permission to
³⁸⁹ conduct this research. We thank C. Botes, I. Clavadetscher, and G. Camenisch for assisting
³⁹⁰ with wild dog immobilizations. We also thank B. Abrahms for sharing her data of three
³⁹¹ dispersing wild dogs. Furthermore, we are indebted to Prof. J. Fieberg, who consulted all
³⁹² statistical aspects of this work and P. Wolski, from the Okavango Research Institute, who
³⁹³ assisted us in generating dynamic water maps. We also thank the anonymous reviewers for
³⁹⁴ their valuable comments and suggestions. This study was funded by Albert-Heim Stiftung,
³⁹⁵ Basler Stiftung für Biologische Forschung, Claraz Foundation, Idea Wild, Jacot Foundation,
³⁹⁶ National Geographic Society, Parrotia Stiftung, Stiftung Temperatio, Wilderness Wildlife
³⁹⁷ Trust Foundation, Forschungskredit der Universität Zürich, and a Swiss National Science
³⁹⁸ Foundation Grant (31003A_182286) to A. Ozgul.

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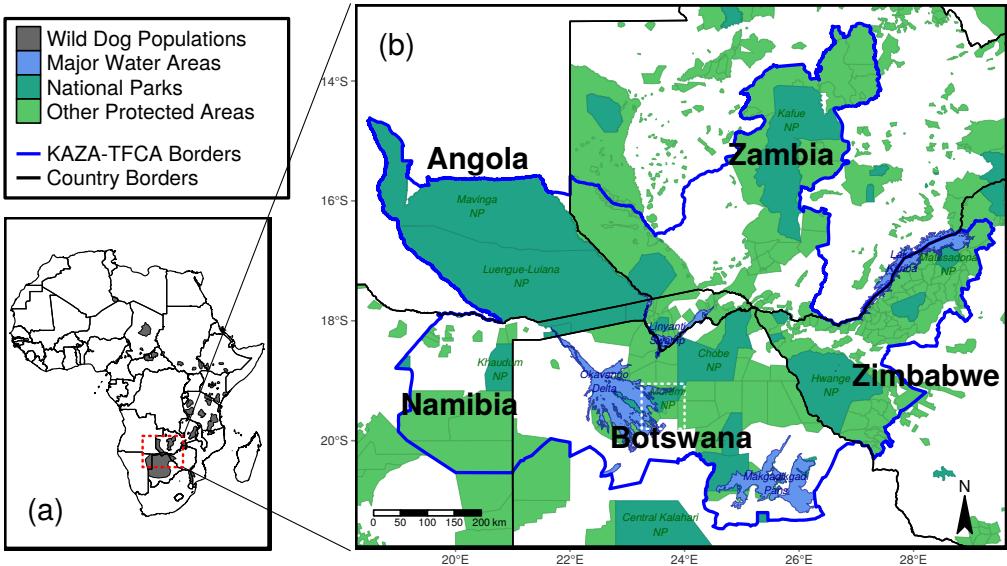


Figure 1: Overview of our study area. (a) The red dotted rectangle depicts the study area, which was confined by a bounding box encompassing the entire KAZA-TFCA. Gray areas indicate remaining wild dog populations according to the IUCN (Woodroffe and Sillero-Zubiri, 2012). (b) The white rectangle illustrates the area within which dispersing coalitions were collared. Since Game Reserves in Botswana virtually serve the same purpose as National Parks, we use the terms interchangeably for this region.

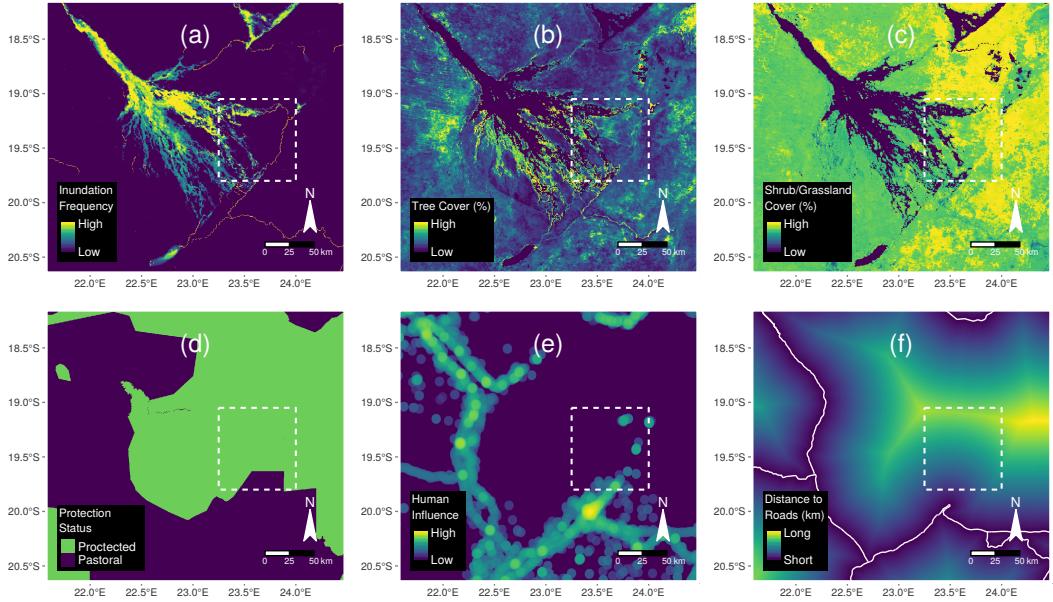


Figure 2: Overview of spatial covariates that we included in our models. We prepared all covariates for the entire study area but for better visibility we only plot them for the surroundings of the Okavango Delta. The white rectangle in each plot depicts the area within which dispersing coalitions were collared. (a) Averaged layer of all dynamic (binary) water maps. (b) Percentage cover of trees. (c) Percentage cover of shrubs/grassland. Anything that was not covered by trees or shrubs/grassland was deemed to be bare land. (d) Protection status of the area. (e) Human influence proxy composed of human density, farms, and roads. (f) Distance to nearest road (white lines depict actual roads).

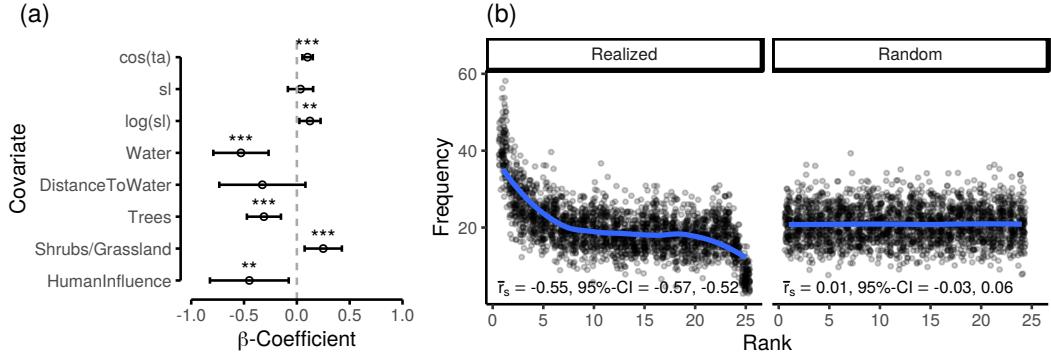


Figure 3: (a) Estimated selection coefficients from the most parsimonious habitat selection model. Negative coefficients indicate avoidance of a covariate, positive coefficients selection of a covariate. ta = turning angle, sl = step length. Whiskers delineate the 95%-CIs for estimated parameters. Significance codes: ** $p < 0.05$, *** $p < 0.01$. (b) Results from the k-fold cross validation for case-control studies. The left graph shows rank frequencies of *realized* steps according to predictions, whereas the right graph shows rank frequencies of *randomly selected* steps according to predictions. \bar{r}_s indicates the mean correlation coefficient resulting from 100 repetitions of the k-fold cross validation. The blue smoothing line was fitted using a locally weighted polynomial regression and serves to aid the eye in detecting the trends. Correlation coefficients suggest that our prediction was significant and robust, evidenced by the fact that the confidence intervals of $\bar{r}_{s,realized}$ and $\bar{r}_{s,random}$ did overlap and by the fact that there was strong and significant correlation between ranks and associated frequency for realized steps.

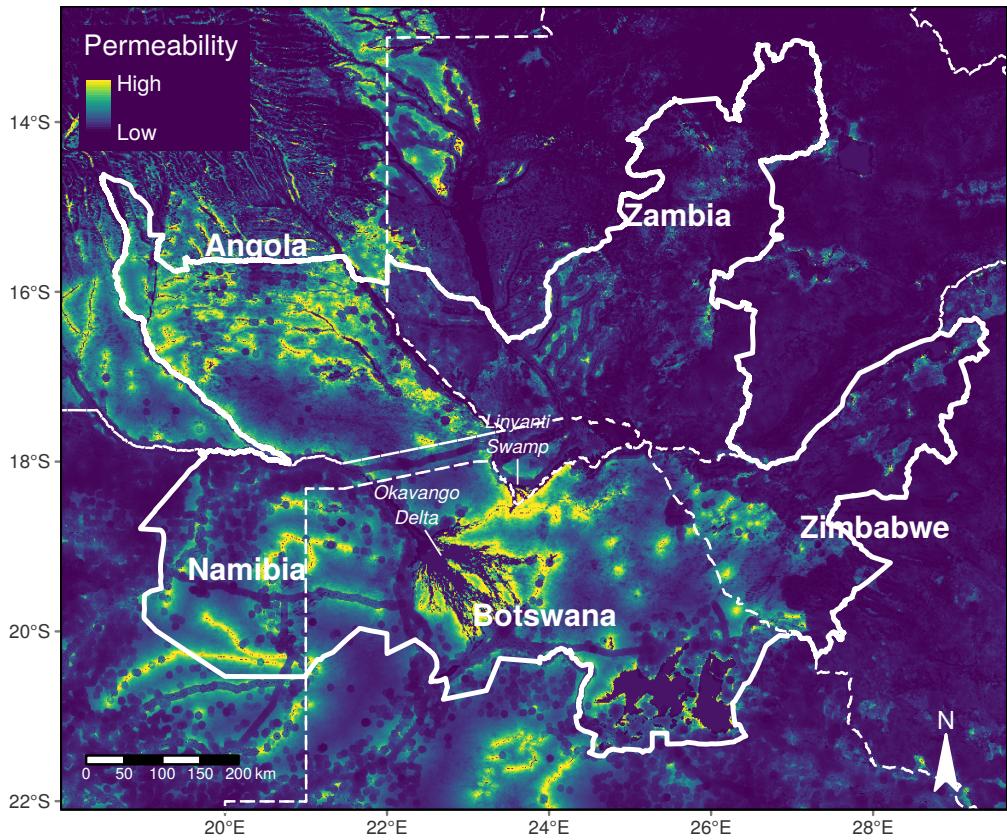


Figure 4: Predicted permeability surface for the extent of the KAZA-TFCA. Permeability was predicted by calculating selection scores $w(x) = \exp(\beta_1 x_1 + \beta_2 x_2 + \dots + \beta_n x_n)$ for each raster cell based on the raster cell's underlying covariates (x_i) and estimated selection strength (β_i). Areas that dispersers find easy to traverse are depicted in bright colors. Bold white lines delineate the borders of the KAZA-TFCA, whereas dashed white lines show country borders.

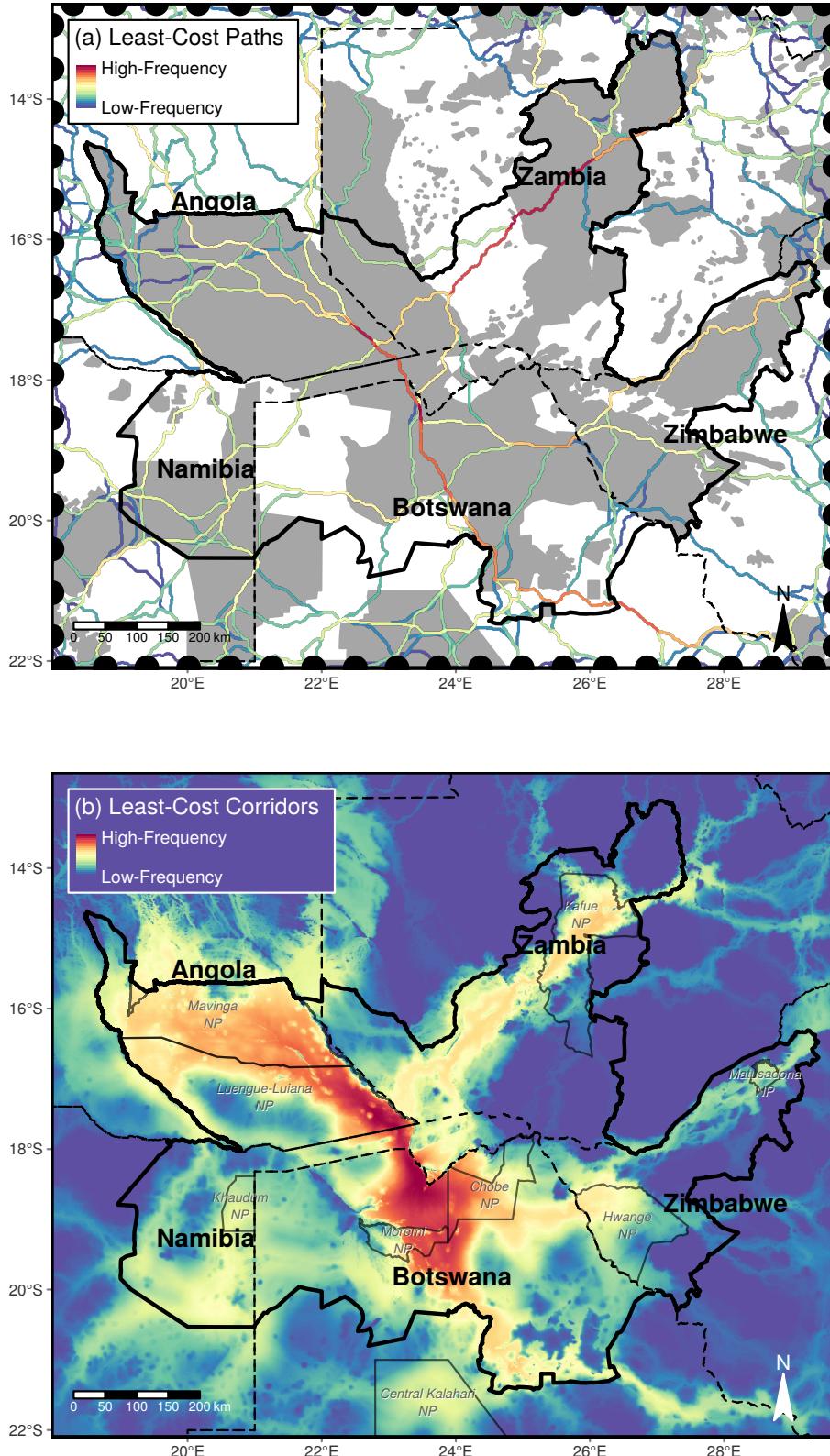


Figure 5: (a) Source points (black semicircles along the map border) and corresponding least-cost paths between them. Continuous black lines indicate the borders of the KAZA-TFCA, whereas dashed black lines delineate country-borders. (b) Least-cost corridors between the same source points as illustrated in subfigure (a). For ease of spatial reference, we also labeled some national parks (NPs, in dark-grey).

Table 1: Comparison of median permeability (interquantile range in brackets) across countries, separated into areas within and outside the KAZA-TFCA, as well as within and outside formally protected areas. High values indicate high permeability, whereas low values correspond to low permeability.

Country	KAZA-TFCA		Protection Status		
	Inside	Outside	Protected	Pastoral	Overall
Angola	0.35 (0.41)	0.12 (0.32)	0.35 (0.41)	0.12 (0.32)	0.19 (0.38)
Botswana	0.24 (0.30)	0.14 (0.16)	0.27 (0.35)	0.14 (0.18)	0.18 (0.25)
Namibia	0.20 (0.30)	0.12 (0.17)	0.22 (0.30)	0.10 (0.14)	0.14 (0.24)
Zambia	0.05 (0.09)	0.02 (0.05)	0.04 (0.09)	0.03 (0.05)	0.03 (0.06)
Zimbabwe	0.06 (0.16)	0.05 (0.04)	0.07 (0.17)	0.04 (0.04)	0.05 (0.06)
Overall	0.15 (0.29)	0.06 (0.14)	0.14 (0.30)	0.06 (0.14)	0.08 (0.21)