▼ Image Classification

```
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## CS4375.003
import · numpy · as · np · # · linear · algebra
import pandas as pd # data processing, CSV file I/O (e.g. pd.read csv)
# Visualization
import matplotlib.pyplot as plt
import PIL
import pathlib
import cv2
# Deep Learning
import tensorflow as tf
from tensorflow.keras.applications.vgg16 import VGG16
from tensorflow.keras.applications.vgg16 import preprocess input
from tensorflow.keras.preprocessing import image
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from tensorflow.keras import layers, Sequential
from tensorflow.keras.models import Model
from tensorflow.keras.callbacks import EarlyStopping
# Input data files are available in the read-only "../input/" directory
# For example, running this (by clicking run or pressing Shift+Enter) will list all files und
import os
dataset_path = "/kaggle/input/pizza-not-pizza/pizza_not_pizza"
data dir = pathlib.Path(dataset path)
image count = len(list(dataset path))
print(image_count)
batch size = 128
\# num classes = 10
# epochs = 20
# batch_size = 32
img height = 180
img width = 180
IMG_SHAPE = (img_height, img_width) + (3,)
```

Before going into the image classification models, it is worth mentioning the type of data I found. I used an image classification database that predicts which images contain a pizza in it. The database by itself contains 983 pizza and 983 non pizza pictures. In some of the algorithms, I used a mix of 50% pictures for training and 20% pictures for testing. The reason being that the models would take a long time to fit the data. I used the regular sequential model, the CNN model, the Xception model, and the transfer learning model. In the transfer learning model I included a version where it builds upon the original transfer learning model and improves it using fine tuning.

Using Sequential model

Getting the train and validation datasets from origin.

```
train ds = tf.keras.utils.image dataset from directory(
  dataset path,
  validation_split=0.5,
  subset="training",
  seed=123,
  image size=(img height, img width),
  batch size=batch size)
     Found 1966 files belonging to 2 classes.
     Using 983 files for training.
val_ds = tf.keras.utils.image_dataset_from_directory(
  data dir,
  validation_split=0.2,
  subset="validation",
  seed=123,
  image_size=(img_height, img_width),
  batch size=batch size)
     Found 1966 files belonging to 2 classes.
     Using 393 files for validation.
```

Printing out the names of the directories where the pictures are located. These are going to become the classes.

```
class_names = train_ds.class_names
print(class_names)
    ['not_pizza', 'pizza']
```

Shape of the data.

```
for data, labels in train_ds.take(1):
    print(data.shape)
    print(labels.shape)

    (128, 180, 180, 3)
    (128,)
```

Using matplotlib, we can see some images with their labels from the train dataset. It gives us an idea of the kind of images that are going to be processed.

```
import matplotlib.pyplot as plt

plt.figure(figsize=(10, 10))
for images, labels in train_ds.take(1):
    for i in range(9):
        ax = plt.subplot(3, 3, i + 1)
        plt.imshow(images[i].numpy().astype("uint8"))
        plt.title(class_names[labels[i]])
        plt.axis("off")
```







Going into the train database, we can see the shape the images and labels have.

Creating the sequential image classification model.

```
nizza
num_classes = 2

model = Sequential([
    tf.keras.layers.Flatten(input_shape=(img_height, img_width, 3)),
    tf.keras.layers.Dense(512, activation='relu'),
    tf.keras.layers.Dropout(0.2),
    tf.keras.layers.Dense(512, activation='relu'),
    tf.keras.layers.Dropout(0.2),
    tf.keras.layers.Dropout(0.2),
    tf.keras.layers.Dense(num_classes, activation='softmax'),
])
```

model.summary()

Model: "sequential_1"

Layer (type)	Output	Shape	Param #
flatten_15 (Flatten)	(None,	97200)	0
dense_20 (Dense)	(None,	512)	49766912
dropout_4 (Dropout)	(None,	512)	0
dense_21 (Dense)	(None,	512)	262656
dropout_5 (Dropout)	(None,	512)	0
dense_22 (Dense)	(None,	2)	1026

Total params: 50,030,594 Trainable params: 50,030,594 Non-trainable params: 0

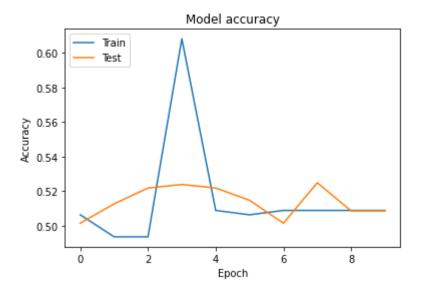
```
model.compile(loss=tf.keras.losses.SparseCategoricalCrossentropy(from logits=True),
      optimizer='rmsprop',
      metrics=['accuracy'])
epochs=10
history = model.fit(
train ds,
validation data=val ds,
epochs=10
)
  Epoch 1/10
  /opt/conda/lib/python3.7/site-packages/keras/backend.py:4907: UserWarning: "`sparse cate
   '"`sparse_categorical_crossentropy` received `from_logits=True`, but '
  Epoch 2/10
  Epoch 3/10
  Epoch 4/10
  Epoch 5/10
  Epoch 6/10
  Epoch 7/10
  Epoch 8/10
  8/8 [=========== ] - 3s 361ms/step - loss: 18.2349 - accuracy: 0.5249
  Epoch 9/10
  8/8 [========== ] - 3s 359ms/step - loss: 0.6906 - accuracy: 0.5086 -
  Epoch 10/10
```

Plotting the accuracy values as the epoch increases, we can see a small trend in the accuracy increasing as the epoch increases.

```
import matplotlib.pyplot as plt

# Plot training & validation accuracy values
plt.plot(history.history['val_accuracy'])
plt.plot(history.history['accuracy'])
plt.title('Model accuracy')
plt.ylabel('Accuracy')
```

```
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```



```
score = model.evaluate(val_ds, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])

Test loss: 0.6887453198432922
   Test accuracy: 0.508905827999115
```

The test accuracy for the regular sequential model was 0.50 on the validation data, which is quite low.

Using CNN modeling

The CNN modeling algorithm allows for a reduction in the dimensionality of the database without it losing its information. From this, we can think that they might produce better results that the sequential model. We also are going to set up the variables we're going to use for the model next.

```
batch_size = 128
num_classes = 2
epochs = 10

normalization_layer = tf.keras.layers.Rescaling(1./255)

normalized_ds = train_ds.map(lambda x, y: (normalization_layer(x), y))
image_batch, labels_batch = next(iter(normalized_ds))
first image = image_batch[0]
```

Similar to the sequential model, we do need to make it sequential but we involve the use of Conv2D and MaxPooling2D, which help deal with high dimensionality.

```
model = Sequential([
    layers.Rescaling(1./255, input_shape=(img_height, img_width, 3)),
    layers.Conv2D(16, 3, padding='same', activation='relu'),
    layers.MaxPooling2D(),
    layers.Conv2D(32, 3, padding='same', activation='relu'),
    layers.MaxPooling2D(),
    layers.Conv2D(64, 3, padding='same', activation='relu'),
    layers.MaxPooling2D(),
    layers.Flatten(),
    layers.Dense(128, activation='relu'),
    layers.Dense(num_classes)
])
```

Model: "sequential_2"

model.summary()

Layer (type)	Output	Shape	Param #
rescaling_1 (Rescaling)	(None,	180, 180, 3)	0
conv2d_36 (Conv2D)	(None,	180, 180, 16)	448
max_pooling2d (MaxPooling2D)	(None,	90, 90, 16)	0
conv2d_37 (Conv2D)	(None,	90, 90, 32)	4640
max_pooling2d_1 (MaxPooling2	(None,	45, 45, 32)	0
conv2d_38 (Conv2D)	(None,	45, 45, 64)	18496
max_pooling2d_2 (MaxPooling2	(None,	22, 22, 64)	0
flatten_16 (Flatten)	(None,	30976)	0
dense_39 (Dense)	(None,	128)	3965056

We're going to compile the model using sparse categorical crossentropy for our loss function and and also are going to fit the model to the train database.

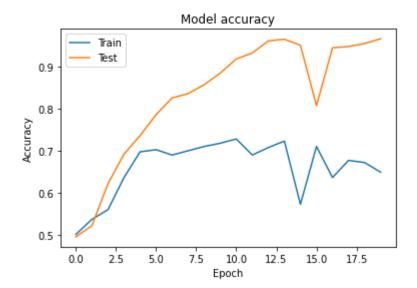
model.compile(loss=tf.keras.losses.SparseCategoricalCrossentropy(from logits=True),

```
optimizer='adam',
       metrics=['accuracy'])
history = model.fit(train_ds,
          batch_size=batch_size,
          epochs=epochs,
          verbose=1,
          validation data=val ds)
  Epoch 1/10
  Epoch 2/10
  8/8 [============= ] - 7s 912ms/step - loss: 0.6947 - accuracy: 0.5331 -
  Epoch 3/10
  8/8 [============ ] - 8s 970ms/step - loss: 0.6868 - accuracy: 0.5738 -
  Epoch 4/10
  8/8 [========== ] - 7s 929ms/step - loss: 0.6532 - accuracy: 0.6267 -
  Epoch 5/10
  8/8 [========== ] - 7s 915ms/step - loss: 0.5986 - accuracy: 0.6928 -
  Epoch 6/10
  Epoch 7/10
  Epoch 8/10
  Epoch 9/10
  8/8 [============ ] - 7s 921ms/step - loss: 0.3209 - accuracy: 0.8871 -
  Epoch 10/10
```

We again are going to plot the results into a matplot graph.

```
# Plot training & validation accuracy values
plt.plot(history.history['val_accuracy'])
plt.plot(history.history['accuracy'])
plt.title('Model accuracy')
```

```
plt.ylabel('Accuracy')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```



As we can see, as the epoch increased, we got better accuracy on our test results, which is a good indicator for the model.

```
score = model.evaluate(val_ds, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])

Test loss: 0.724279522895813
Test accuracy: 0.6921119689941406
```

Overall test accuracy on the validation data was of 0.69, much improved from the regular sequential model for image classification, yet still a little bit unreliable.

Using Xception image classification

The Xception model for image classification is a CNN one. While the CNN model produced earlier was a couple layers deep, Xception is 71 layers deep, making it really robust and accurate. It also can let you load the pretrained version which has been trained by over a million images. Here we're going to train it ourselves.

```
base_model = tf.keras.applications.Xception(
   input shape=(180,180,3),
```

```
include_top=False)
```

We created the base model with the input shape of the images being (180,180), the same we set for other models.

We create the Xception model and then compile it.

model.summary()

Model: "Xception"

Layer (type)	Output	Shape	Param #
xception (Functional)	(None,	6, 6, 2048)	20861480
<pre>global_average_pooling2d_8 (</pre>	(None,	2048)	0
dense_41 (Dense)	(None,	256)	524544
dropout_14 (Dropout)	(None,	256)	0
dense_42 (Dense)	(None,	1)	257

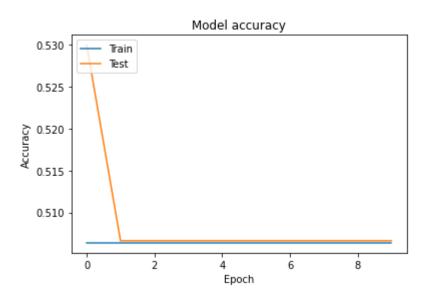
Total params: 21,386,281 Trainable params: 524,801

Non-trainable params: 20,861,480

```
Epoch 1/10
Epoch 2/10
Epoch 3/10
Epoch 4/10
Epoch 5/10
Epoch 6/10
  8/8 [=======
Epoch 7/10
8/8 [======
  Epoch 8/10
Epoch 9/10
Epoch 10/10
```

import matplotlib.pyplot as plt

```
# Plot training & validation accuracy values
plt.plot(history.history['val_accuracy'])
plt.plot(history.history['accuracy'])
plt.title('Model accuracy')
plt.ylabel('Accuracy')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```



```
score = model.evaluate(val_ds, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
```

```
Test loss: 0.0
Test accuracy: 0.5063613057136536
```

We get the same results as the sequential model, which is not what was expected.

▼ Using Transfer Learning model

Transfer learning focuses on using a pretrained model to use on your own model. I will be doing customization on a pretrained model using feature extraction, where we extract the meaningful features learned by a previous network frmo new samples.

```
val_batches = tf.data.experimental.cardinality(val_ds)
test_dataset = val_ds.take(val_batches // 5)
validation_dataset = val_ds.skip(val_batches // 5)

print('Number of validation batches: %d' % tf.data.experimental.cardinality(validation_datase
print('Number of test batches: %d' % tf.data.experimental.cardinality(test_dataset))

   Number of validation batches: 4
   Number of test batches: 0

AUTOTUNE = tf.data.AUTOTUNE

train_dataset = train_ds.prefetch(buffer_size=AUTOTUNE)
validation_dataset = validation_dataset.prefetch(buffer_size=AUTOTUNE)
test_dataset = test_dataset.prefetch(buffer_size=AUTOTUNE)
```

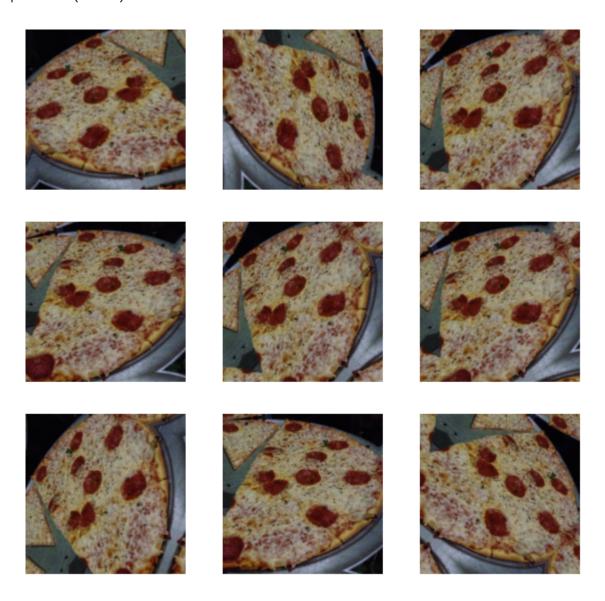
data augmentation provides a good way of diversifying the dataset by applying realistic transformations to the train images. Here we are going to apply it as the dataset is not that large.

```
data_augmentation = tf.keras.Sequential([
  tf.keras.layers.RandomFlip('horizontal'),
  tf.keras.layers.RandomRotation(0.2),
])
```

We can see in the next plot how data augmentation works on a sample image.

```
for image, _ in train_ds.take(1):
  plt.figure(figsize=(10, 10))
  first_image = image[0]
  for i in range(9):
```

```
ax = plt.subplot(3, 3, i + 1)
augmented_image = data_augmentation(tf.expand_dims(first_image, 0))
plt.imshow(augmented_image[0] / 255)
plt.axis('off')
```



We rescale the pixel values.

```
preprocess_input = tf.keras.applications.mobilenet_v2.preprocess_input
rescale = tf.keras.layers.Rescaling(1./127.5, offset=-1)
```

Here is where we create the base model from the pretrained model. We are going to be using MobileNetV2, a model developed by Google, which has a large dataset of 1.4 million images and 1000 classes.

Here is where feature extraction happens. Making the base model not trainable will freeze all of the base model's layers.

```
base_model.trainable = False
```

base_model.summary()

Model: "mobilenetv2_1.00_224"							
Layer (type)	Output	Shap	e		Param #	Connected to	
input_36 (InputLayer)	[(None	===== , 180	, 18	30, 3)	0		
Conv1 (Conv2D)	(None,	90,	90,	32)	864	input_36[0][0]	
bn_Conv1 (BatchNormalization)	(None,	90,	90,	32)	128	Conv1[0][0]	
Conv1_relu (ReLU)	(None,	90,	90,	32)	0	bn_Conv1[0][0]	
expanded_conv_depthwise (Depthw	(None,	90,	90,	32)	288	Conv1_relu[0][0]	•
expanded_conv_depthwise_BN (Bat	(None,	90,	90,	32)	128	expanded_conv_depthw	
expanded_conv_depthwise_relu (R	(None,	90,	90,	32)	0	expanded_conv_depthw	•
expanded_conv_project (Conv2D)	(None,	90,	90,	16)	512	expanded_conv_depthw	•
expanded_conv_project_BN (Batch	(None,	90,	90,	16)	64	expanded_conv_projec	
block_1_expand (Conv2D)	(None,	90,	90,	96)	1536	expanded_conv_projec	

block_1_expand_BN (BatchNormali	(None,	90,	90,	96)	384	block_1_expand[0][0]
block_1_expand_relu (ReLU)	(None,	90,	90,	96)	0	block_1_expand_BN[0]
block_1_pad (ZeroPadding2D)	(None,	91,	91,	96)	0	block_1_expand_relu[(
block_1_depthwise (DepthwiseCon	(None,	45,	45,	96)	864	block_1_pad[0][0]
block_1_depthwise_BN (BatchNorm	(None,	45,	45,	96)	384	block_1_depthwise[0]
block_1_depthwise_relu (ReLU)	(None,	45,	45,	96)	0	block_1_depthwise_BN
block_1_project (Conv2D)	(None,	45,	45,	24)	2304	block_1_depthwise_re
block_1_project_BN (BatchNormal	(None,	45,	45,	24)	96	block_1_project[0][0
block_2_expand (Conv2D)	(None,	45,	45,	144)	3456	block_1_project_BN[0
block_2_expand_BN (BatchNormali	(None,	45,	45,	144)	576	block_2_expand[0][0]
block_2_expand_relu (ReLU)	(None,	45,	45,	144)	0	block_2_expand_BN[0]
block_2_depthwise (DepthwiseCon	(None,	45,	45,	144)	1296	block_2_expand_relu[(
block_2_depthwise_BN (BatchNorm	(None,	45,	45,	144)	576	block_2_depthwise[0]
block_2_depthwise_relu (ReLU)	(None,	45,	45,	144)	0	block_2_depthwise_BN
block_2_project (Conv2D)	(None,	45,	45,	24)	3456	block_2_depthwise_re
block_2_project_BN (BatchNormal	(None,	45,	45,	24)	96	block_2_project[0][0
13 1 2 11 /211	/*:			241	^	17 1 2 1 2 2 2

We create the model based on the base model and the feature extraction.

```
inputs = tf.keras.Input(shape=(180, 180, 3))
x = data_augmentation(inputs)
x = preprocess_input(x)
```

```
x = base_model(x, training=False)
x = global_average_layer(x)
x = tf.keras.layers.Dropout(0.2)(x)
outputs = prediction_layer(x)
model = tf.keras.Model(inputs, outputs)
```

We compile the model with a base learning rate of 0.0001.

model.summary()

Model: "model_14"

Layer (type)	Output Shape	Param #
input_37 (InputLayer)	[(None, 180, 180, 3)]	0
sequential_3 (Sequential)	(None, 180, 180, 3)	0
tf.math.truediv (TFOpLambda)	(None, 180, 180, 3)	0
tf.math.subtract (TFOpLambda	(None, 180, 180, 3)	0
mobilenetv2_1.00_224 (Functi	(None, 6, 6, 1280)	2257984
global_average_pooling2d_9 ((None, 1280)	0
dropout_15 (Dropout)	(None, 1280)	0
dense_43 (Dense)	(None, 1)	1281
Total params: 2,259,265	=======================================	=======

Total params: 2,259,265 Trainable params: 1,281

Non-trainable params: 2,257,984

Fitting the model to the dataset.

```
Epoch 1/10
Epoch 2/10
Epoch 3/10
8/8 [=========== ] - 8s 1s/step - loss: 0.7573 - accuracy: 0.5117 - va
Epoch 4/10
8/8 [=========== ] - 8s 1s/step - loss: 0.7372 - accuracy: 0.5402 - va
Epoch 5/10
Epoch 6/10
Epoch 7/10
Epoch 8/10
8/8 [=========== ] - 8s 1s/step - loss: 0.6201 - accuracy: 0.6399 - va
Epoch 9/10
Epoch 10/10
```

Plotting the result of the transfer learning model, we get the following graph.

```
# Plot training & validation accuracy values
plt.plot(history.history['val_accuracy'])
plt.plot(history.history['accuracy'])
plt.title('Model accuracy')
plt.ylabel('Accuracy')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```

We see the clearest trendline in the transfer learning model, as both the train and test accuracy increase with an increase in epoch.

```
score = model.evaluate(validation_dataset, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])

Test loss: 0.47770369052886963
   Test accuracy: 0.7455470561981201
```

Overall, transfer learning gave a total accuracy of 0.74, similar to that of the CNN model. We'll try and see if by fine tuning the model we can get better results.

▼ Transfer Learning fine tuned

Now we make the base model not be frozen, so its layers can interact with the dataset.

```
base_model.trainable = True
base_model.summary()
```

Model: "mobilenetv2_1.00_224"						i
Layer (type)	Output	Shap	oe .		Param #	Connected to
input_36 (InputLayer)	[(None	, 186	==== 0, 18	30, 3)	0	
Conv1 (Conv2D)	(None,	90,	90,	32)	864	input_36[0][0]
bn_Conv1 (BatchNormalization)	(None,	90,	90,	32)	128	Conv1[0][0]
Conv1_relu (ReLU)	(None,	90,	90,	32)	0	bn_Conv1[0][0]
expanded_conv_depthwise (Depthw	(None,	90,	90,	32)	288	Conv1_relu[0][0]
expanded_conv_depthwise_BN (Bat	(None,	90,	90,	32)	128	expanded_conv_depthw
expanded_conv_depthwise_relu (R	(None,	90,	90,	32)	0	expanded_conv_depthw
expanded_conv_project (Conv2D)	(None,	90,	90,	16)	512	expanded_conv_depthw
expanded_conv_project_BN (Batch	(None,	90,	90,	16)	64	expanded_conv_projec
block_1_expand (Conv2D)	(None,	90,	90,	96)	1536	expanded_conv_projec
block_1_expand_BN (BatchNormali	(None,	90,	90,	96)	384	block_1_expand[0][0]

block_1_expand_relu (ReLU)	(None,	90,	90,	96)	0	block_1_expand_BN[0]
block_1_pad (ZeroPadding2D)	(None,	91,	91,	96)	0	block_1_expand_relu[(
block_1_depthwise (DepthwiseCon	(None,	45,	45,	96)	864	block_1_pad[0][0]
block_1_depthwise_BN (BatchNorm	(None,	45,	45,	96)	384	block_1_depthwise[0]
block_1_depthwise_relu (ReLU)	(None,	45,	45,	96)	0	block_1_depthwise_BN
block_1_project (Conv2D)	(None,	45,	45,	24)	2304	block_1_depthwise_re
block_1_project_BN (BatchNormal	(None,	45,	45,	24)	96	block_1_project[0][0
block_2_expand (Conv2D)	(None,	45,	45,	144)	3456	block_1_project_BN[0
block_2_expand_BN (BatchNormali	(None,	45,	45,	144)	576	block_2_expand[0][0]
block_2_expand_relu (ReLU)	(None,	45,	45,	144)	0	block_2_expand_BN[0]
block_2_depthwise (DepthwiseCon	(None,	45,	45,	144)	1296	block_2_expand_relu[
block_2_depthwise_BN (BatchNorm	(None,	45,	45,	144)	576	block_2_depthwise[0]
block_2_depthwise_relu (ReLU)	(None,	45,	45,	144)	0	block_2_depthwise_BN
block_2_project (Conv2D)	(None,	45,	45,	24)	3456	block_2_depthwise_re
block_2_project_BN (BatchNormal	(None,	45,	45,	24)	96	block_2_project[0][0
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```
global_average_layer = tf.keras.layers.GlobalAveragePooling2D()
feature_batch_average = global_average_layer(feature_batch)

prediction_layer = tf.keras.layers.Dense(1)
prediction_batch = prediction_layer(feature_batch_average)
```

We create the model again with the base model being trainable.

```
inputs = tf.keras.Input(shape=(180, 180, 3))
x = data_augmentation(inputs)
x = preprocess_input(x)
x = base_model(x, training=False)
x = global_average_layer(x)
x = tf.keras.layers.Dropout(0.2)(x)
outputs = prediction_layer(x)
model = tf.keras.Model(inputs, outputs)
```

Model: "model_15"

Layer (type)	Output Shape	Param #
		=======
input_38 (InputLayer)	[(None, 180, 180, 3)]	0
sequential_3 (Sequential)	(None, 180, 180, 3)	0
tf.math.truediv_1 (TFOpLambd	(None, 180, 180, 3)	0
tf.math.subtract_1 (TFOpLamb	(None, 180, 180, 3)	0
mobilenetv2_1.00_224 (Functi	(None, 6, 6, 1280)	2257984
global_average_pooling2d_10	(None, 1280)	0
dropout_16 (Dropout)	(None, 1280)	0
dense_44 (Dense)	(None, 1)	1281

Total params: 2,259,265 Trainable params: 2,225,153 Non-trainable params: 34,112

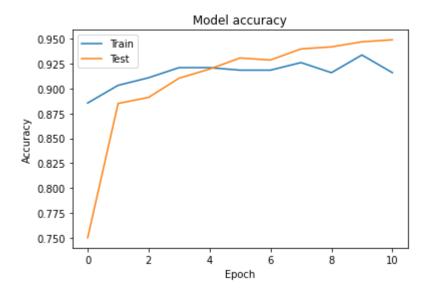
Epoch 12/20

Epoch 13/20

```
Epoch 14/20
Epoch 15/20
Epoch 16/20
8/8 [============ ] - 26s 3s/step - loss: 0.1737 - accuracy: 0.9288 - \
Epoch 17/20
Epoch 18/20
        ==========] - 26s 3s/step - loss: 0.1478 - accuracy: 0.9420 - \
8/8 [========
Epoch 19/20
           8/8 [=====
Epoch 20/20
             ======] - 26s 3s/step - loss: 0.1367 - accuracy: 0.9491 - \
8/8 [======
```

Rendering the plot, we see that we got better results this time around.

```
# Plot training & validation accuracy values
plt.plot(history.history['val_accuracy'])
plt.plot(history.history['accuracy'])
plt.title('Model accuracy')
plt.ylabel('Accuracy')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```



```
score = model.evaluate(validation_dataset, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
```

Test loss: 0.21557176113128662 Test accuracy: 0.9160305261611938 The test accuracy was 0.91, the best out of the models I tested.

▼ Analysis

Looking back to the approaches I took into modeling and testing the data, we can see that there was a clear divide on how the models worked with the train dataset and how that impactes its test accuracy. The lowest algorithms were the sequential and the Xception models. I believe the sequential model was at a low 0.50 due to how rudementary and simple it is. We do not work with high dimensionality like we do with CNN and we do not take into account a previous model to base it off on. The Xception model also had an accuracy of 0.50, which was really surprising as it is based off a CNN model of 71 layers. I believe that the accuracy was low due to how I handled the data. The CNN and transfer learning models were on par, both scoring around 0.70-0.75 on accuracy. The transfer learning model is a CNN one and we made it so the base model was not trainable, making it basically a CNN model, which is why I believe it got similar results to it. The fine tuned transfer algorithm did take into account the base model and made it trainablem which is why I believe it handled the train data better and thus gave a high accuracy of 0.91.

Overall, it was hard to work with these algorithms, as some of them had issues with the shape of the images. That's asloa big reason why I coulnd't work with RNN models, even though I tried. I do take away the functionality that the transfer learning models bring and how easily they can be applied to any dataset.

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