# WLE.rmd

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Monday, August 18, 2014

# Examination of Weight Lifting Exercises Dataset

#### Introduction

Six young healthy participants were asked to perform one set of 10 repetitions of the Unilateral Dumbbell Biceps Curl in five different fashions: exactly according to the specification (Class A), throwing the elbows to the front (Class B), lifting the dumbbell only halfway (Class C), lowering the dumbbell only halfway (Class D) and throwing the hips to the front (Class E).

Their movements were monitored using four detectors strapped to their forearm, upperarm, waist and to the dumbbell itself. For feature extraction a sliding window approach was used with different lengths from 0.5 second to 2.5 seconds, with 0.5 second overlap. In each step of the sliding window approach the features on the Euler angles (roll, pitch and yaw), as well as the raw accelerometer, gyroscope and magnetometer readings were calculated.

The training data for this project are available here: https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv

The test data are available here: https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv

The data for this report comes from this source: http://groupware.les.inf.puc-rio.br/har.

#### Method

The algorithm selected to predict the quality of execution variable (classe) is random forest. This uses a decision tree approach with bootstrapping to generate a "forest" of potential trees. New trees are developed by restricting the number of variables that can be randomly selected at each node. This increases the variance between the trees improving the prediction accuracy.

The random forest methodology was chosen because: -It is unexcelled in accuracy among current algorithms for class prediction. -It runs efficiently on large data bases. -It can handle thousands of input variables without variable deletion. -It gives estimates of what variables are important in the classification.

#### Download and read files

The files are downloaded and read. The training file is named "training" and the testing file is named "validation"

```
training<- read.csv( "./data/training.csv")
validation <- read.csv( "./data/testing.csv")</pre>
```

## Preprocess files

Some rows represent a summary of previous observations (the 2.5sec window as opposed to the 0.5). As the test data file does not provide this data our training and validation data files need to exclude them as well.

The measurements described in the introduction represent four measurement devices providing four measures each in three dimensions. This provides 48 predictors plus the predicted variable (classe). The next step of the preprocessing is to reduce the files to these 49 rows. This requires the removal of all extraneous variables (names, time, etc) which might give invalid correlations.

No further preprocessing was undertaken as the random forest method is not sensitive to issues of skewness etc..

```
library(caret)

## Warning: package 'caret' was built under R version 3.1.1

## Loading required package: lattice
## Loading required package: ggplot2

training <- training[training$new_window=="no",]
training <- training[,c(8:10,37:48,60:68,84:86,113:124,151:160)]
nzv <- nearZeroVar(training,saveMetrics=T)
dim(training)

## [1] 19216    49

validation <- validation[,c(8:10,37:48,60:68,84:86,113:124,151:160)]</pre>
```

Finally we checked that the remaining predictors are valid by ensuring that they do not have a near zero variance (none do, see appendix). This gave a data frame of 19216 rows and 49 columns.

#### Create a training and testing set

The random forest uses a bootstrap method to estimates out of bag error (oob). This is used to estimate the optimal mtry (number of variables available for selection at each node) and hence does not provide an independent test of the accuracy of the final model.

Therefore the training file needs to be split into a training file (on which the model is built) and a teating file which will allow for cross validation and the calculation of the out of sample error

```
inTraining <- createDataPartition(y=training$classe,p=0.6,list=FALSE)
training <- training[inTraining,]
testing <- training[-inTraining,]</pre>
```

#### Build model

As already explained the random forest method was adopted. However because the default approach was too computationally demanding for my PC the "traincontrol" argument was used. This provided for a 4 fold cross validation.

```
modFit <- train(classe~.,data=training,method="rf",trControl = trainControl(method = "cv", number = 4,
## Loading required package: randomForest
## Warning: package 'randomForest' was built under R version 3.1.1
## randomForest 4.6-10
## Type rfNews() to see new features/changes/bug fixes.
## Warning: package 'e1071' was built under R version 3.1.1
## + Fold1: mtry= 2
## - Fold1: mtry= 2
## + Fold1: mtry=25
## - Fold1: mtry=25
## + Fold1: mtry=48
## - Fold1: mtry=48
## + Fold2: mtry= 2
## - Fold2: mtry= 2
## + Fold2: mtry=25
## - Fold2: mtry=25
## + Fold2: mtry=48
## - Fold2: mtry=48
## + Fold3: mtry= 2
## - Fold3: mtry= 2
## + Fold3: mtry=25
## - Fold3: mtry=25
## + Fold3: mtry=48
## - Fold3: mtry=48
## + Fold4: mtry= 2
## - Fold4: mtry= 2
## + Fold4: mtry=25
## - Fold4: mtry=25
## + Fold4: mtry=48
## - Fold4: mtry=48
## Aggregating results
## Selecting tuning parameters
## Fitting mtry = 25 on full training set
print(modFit)
## Random Forest
## 11532 samples
      48 predictors
##
```

```
5 classes: 'A', 'B', 'C', 'D', 'E'
##
##
## No pre-processing
## Resampling: Cross-Validated (4 fold)
##
## Summary of sample sizes: 8649, 8648, 8649, 8650
##
## Resampling results across tuning parameters:
##
##
           Accuracy Kappa Accuracy SD
                                          Kappa SD
##
     2
           1
                             9e-04
                                          0.001
                     1
                             7e-04
                                          9e-04
##
     20
           1
                     1
                             0.002
                                          0.003
##
##
## Accuracy was used to select the optimal model using the largest value.
## The final value used for the model was mtry = 25.
```

The model indicated the optimal mtry was 25 and this adopted model gives an accuracy of 0.988.

#### Predict result on test data

To calculate out of sample error this model was applied to the testing data and its results compared to the actual classe values using the confusion matrix function.

```
pred <- predict(modFit,testing)
print(confusionMatrix(pred,testing$classe))</pre>
```

```
## Confusion Matrix and Statistics
##
##
             Reference
                             С
                                  D
                                       Ε
## Prediction
                  Α
                       В
##
             A 1345
                       0
                             0
                                  0
                                        0
                                        0
             В
                  0
                     863
                                  0
##
                             0
             С
                  0
                          818
                                        0
##
                       0
                                  0
##
             D
                  0
                       0
                             0
                                731
                                        0
##
            Ε
                       0
                             0
                                  0
                                     867
##
## Overall Statistics
##
##
                   Accuracy: 1
##
                     95% CI: (0.999, 1)
##
       No Information Rate: 0.291
##
       P-Value [Acc > NIR] : <2e-16
##
##
                      Kappa: 1
##
    Mcnemar's Test P-Value : NA
##
## Statistics by Class:
##
                         Class: A Class: B Class: C Class: D Class: E
##
                             1.000
                                      1.000
                                                1.000
## Sensitivity
                                                          1.000
                                                                    1.000
## Specificity
                             1.000
                                      1.000
                                                1.000
                                                          1.000
                                                                    1.000
```

##	Pos Pred Value	1.000	1.000	1.000	1.000	1.000
##	Neg Pred Value	1.000	1.000	1.000	1.000	1.000
##	Prevalence	0.291	0.187	0.177	0.158	0.188
##	Detection Rate	0.291	0.187	0.177	0.158	0.188
##	Detection Prevalence	0.291	0.187	0.177	0.158	0.188
##	Balanced Accuracy	1.000	1.000	1.000	1.000	1.000

The confusion matrix predicts 0 out of sample error and therefore there is no opportunity to improve the model.

## Predict results for 20 test cases

Finally the model is used to predict the classe variable for the 20 test cases provided. It correctly predicts all 20

```
answers <- predict(modFit,validation)
print(answers)

## [1] B A B A A E D B A A B C B A E E A B B B
## Levels: A B C D E</pre>
```

## **Appendix**

```
print(nzv)
```

```
##
                     freqRatio percentUnique zeroVar
## roll_belt
                         1.086
                                     6.83805
                                               FALSE FALSE
## pitch_belt
                         1.037
                                     9.53893
                                               FALSE FALSE
## yaw_belt
                         1.047
                                    10.10616
                                               FALSE FALSE
## gyros_belt_x
                         1.051
                                     0.72336
                                               FALSE FALSE
## gyros_belt_y
                                     0.35908
                                               FALSE FALSE
                         1.149
## gyros belt z
                         1.071
                                     0.87948
                                               FALSE FALSE
                                               FALSE FALSE
## accel_belt_x
                         1.059
                                     0.85346
## accel belt y
                                     0.74417
                                               FALSE FALSE
                         1.115
## accel_belt_z
                                     1.55600
                                               FALSE FALSE
                         1.081
## magnet_belt_x
                         1.089
                                     1.70171
                                               FALSE FALSE
## magnet_belt_y
                         1.097
                                     1.55079
                                               FALSE FALSE
## magnet_belt_z
                         1.019
                                     2.37302
                                               FALSE FALSE
## roll_arm
                                    13.75937
                                               FALSE FALSE
                        51.154
## pitch_arm
                        85.282
                                    15.96066
                                               FALSE FALSE
## yaw_arm
                        32.282
                                    14.89904
                                               FALSE FALSE
                         1.024
                                     3.34617
                                               FALSE FALSE
## gyros_arm_x
## gyros_arm_y
                         1.451
                                     1.95150
                                               FALSE FALSE
## gyros_arm_z
                         1.119
                                     1.29059
                                               FALSE FALSE
## accel_arm_x
                         1.018
                                     4.04351
                                               FALSE FALSE
## accel_arm_y
                                     2.78414
                                               FALSE FALSE
                         1.169
## accel_arm_z
                         1.139
                                     4.12157
                                               FALSE FALSE
## magnet_arm_x
                         1.012
                                     6.96295
                                               FALSE FALSE
## magnet arm y
                         1.045
                                     4.53268
                                               FALSE FALSE
## magnet_arm_z
                         1.028
                                     6.57785
                                               FALSE FALSE
```

```
## roll dumbbell
                          1.038
                                     83.75312
                                                FALSE FALSE
## pitch_dumbbell
                          2.248
                                     81.22398
                                                FALSE FALSE
## yaw dumbbell
                          1.132
                                     83.02456
                                                FALSE FALSE
## gyros_dumbbell_x
                          1.010
                                      1.25416
                                                FALSE FALSE
## gyros_dumbbell_y
                          1.271
                                      1.44151
                                                FALSE FALSE
## gyros dumbbell z
                          1.053
                                      1.06682
                                                FALSE FALSE
## accel dumbbell x
                                      2.21170
                                                FALSE FALSE
                          1.006
## accel_dumbbell_y
                          1.062
                                      2.41986
                                                FALSE FALSE
## accel dumbbell z
                          1.150
                                      2.12323
                                                FALSE FALSE
## magnet_dumbbell_x
                          1.094
                                      5.84929
                                                FALSE FALSE
## magnet_dumbbell_y
                          1.189
                                      4.38177
                                                FALSE FALSE
## magnet_dumbbell_z
                          1.027
                                      3.51270
                                                FALSE FALSE
## roll_forearm
                         11.726
                                     11.23543
                                                FALSE FALSE
## pitch_forearm
                         64.576
                                     15.09679
                                                FALSE FALSE
## yaw_forearm
                         15.236
                                     10.29871
                                                FALSE FALSE
## gyros_forearm_x
                          1.050
                                      1.54559
                                                FALSE FALSE
## gyros_forearm_y
                          1.043
                                      3.84055
                                                FALSE FALSE
## gyros forearm z
                          1.112
                                      1.58201
                                                FALSE FALSE
## accel_forearm_x
                                      4.13197
                                                FALSE FALSE
                          1.143
## accel forearm y
                          1.050
                                      5.20920
                                                FALSE FALSE
## accel_forearm_z
                          1.019
                                      3.01311
                                                FALSE FALSE
## magnet_forearm_x
                          1.013
                                      7.92569
                                                FALSE FALSE
## magnet_forearm_y
                                                FALSE FALSE
                          1.256
                                      9.72627
## magnet forearm z
                          1.018
                                      8.75833
                                                FALSE FALSE
## classe
                          1.471
                                      0.02602
                                                FALSE FALSE
```

#### References

Velloso, E.; Bulling, A.; Gellersen, H.; Ugulino, W.; Fuks, H. Qualitative Activity Recognition of Weight Lifting Exercises. Proceedings of 4th International Conference in Cooperation with SIGCHI (Augmented Human '13) . Stuttgart, Germany: ACM SIGCHI, 2013