Dimension Reduction

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Outline

What is dimension reduction?

Why do we do dimension reduction?

(Some) Properties of high dimensional random variables

Principal Components Analysis

- ▶ Can (loosely) think of dimension reduction as a map, DR, operating on the data space, \mathcal{X} , which creates a summary of its operand, $\mathbf{x} \in \mathcal{X}$.
- ▶ What do we want from a summary?
 - ► Remove irrelevant information
 - Remove redundant information
 - Retain useful information
 - ... It should take less effort to read (process) but still contain salient points

In other words

- $ightharpoonup size(\mathbf{x}) (less effort to process)$
- ▶ BUT "useful" dimension reduction should satisfy Useful Information(DR(x)) \approx Useful Information(x)
- "Ideally" we have Useful Information(DR(x)) = Useful Information(x) "sufficient" dimension reduction

Example: Regression Interested in $F(y|\mathbf{x})$. Sufficient dimension reduction for this problem, DR, satisfies $F(y|DR(\mathbf{x})) = F(y|\mathbf{x})$

- ▶ Example: Subset selection $DR(\mathbf{x}) = A^{\top}\mathbf{x}$, where $p \times p'$ matrix A has ith column e_j , and $\hat{\beta}_j$ is the ith included covariate
- ► Sensible to have $A_{,i} = e_j$ if:
 - ► Measurements in **x** correspond directly to physical quantities
 - We don't only want to make inference on $F(y|DR(\mathbf{x}))$ but also the map DR
- not necessarily sensible in general
 - "modern" data may be derived from features extracted from non-Euclidean objects (network summaries, spectral decompositions of time series, etc.)
 - ▶ We only care about F(y|DR(x))

- ▶ We will assume data occupy \mathbb{R}^p
- We will only consider linear dimension reduction
- We will not assume (necessarily) that the individual features (dimensions) are informative
- $ightharpoonup DR(\mathbf{x}) = V^{\top}\mathbf{x}, \ V \in \mathbb{R}^{p \times p'} \ (\text{or similar})$
 - ▶ frequently we want $||A_{,i}|| = 1 \ \forall i$ (don't change the scale after "transformation")
 - For some problems it is necessary to consider orthogonal A, i.e. $A_{,i}^{\top}A_{,j}=0$ for $i\neq j$
 - Sometimes this arises incidentally from the problem description

Why do we do dimension reduction?

- Computational issues (make the data easier to process)
- Correlated features (remove redundant information)
- Overfitting (don't focus on spurious details)
- ► The "quirks" of high dimensional data (other things for which I didn't think of an analogy)

Computational Issues

- ► The most obvious challenge in high dimensions
- ▶ Trivially: "Data matrix $X \in \mathbb{R}^{n \times p}$ has more columns than data matrix $Y \in \mathbb{R}^{n \times p'}$ (p > p'), and so it takes more memory and computational effort to work with X than with Y"
- When is it worth doing dimension reduction solely for computational benefits?

$$ightharpoonup \Longleftrightarrow Cost(ilde{X} \leftarrow DR(X)) + Cost(Process(ilde{X})) < Cost(Process(X))$$

Computational Issues

Example: Linear regression

- ► Each $\mathbf{x}_i \in \mathbb{R}^p$, $i \in \{1, ..., n\}$
- ▶ Computational cost of the basic problem is $\mathcal{O}(p^2(n+p))$
- ► (Poor) Heuristic dimension reduction: Remove "highly correlated" combinations of variables
 - ightharpoonup compute all correlations $\mathcal{O}(p^2)$
 - recover \tilde{p} (maybe unknown) variables
 - new cost $\mathcal{O}(p^2 + \tilde{p}^2(n + \tilde{p}))$
 - ▶ for $\tilde{p} \in o_{(P)}(p)$ as $p \to \infty$ (e.g. $\tilde{p} \leq_{(P)} Kp^{\delta}$ for some $K > 0, 0 < \delta < 1$) this will "always" be beneficial as p grows

Correlated Features

- When features (dimensions/columns in the data matrix) are highly correlated, "standard inference" can be misleading
- ▶ In the extreme as $\rho \to \pm 1$, $X_{,i} \approx aX_{,j} + b$ for $a,b \in \mathbb{R}$
- ightharpoonup Mathematically [1, X] is close to a matrix with non-full rank
- ► Why is this a problem?
 - ightharpoonup [1, X]'[1, X] has high condition number (hard to invert)
 - ► The SS objective in regression looks like a "half-pipe", some gradient based methods fail to converge in reasonable time
- ► Affects inference in the effect it has on variance of regression coefficients, for example.
- ► At a higher, more generic level, if columns in *X* are close to linearly dependent, I can (almost) recreate some using others, so their presence is redundant (they don't add much information)

Overfitting

- Standard (supervised) methods fit a model by minimising training error
 - e.g. SS in regression
- Complex models (with too many dfs/decision variables/parameters) can fit data "too well".
- will fit the "noise" as well as the "signal"
- ▶ No obvious way to decompose a posteriori
- (Can also be a problem for unsupervised learning... "overlearning")

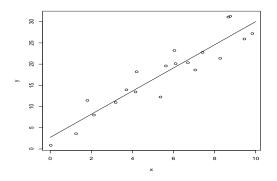
Overfitting

- ► If S/N ratio is high a more parsimonious model should first pick up the signal
- ► If S/N ratio is low... not for us to consider here
- The change from "reasonable" to "terrible" can occur suddenly

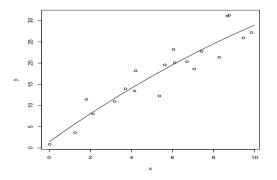
Example:

$$X \sim U[0, 10]$$

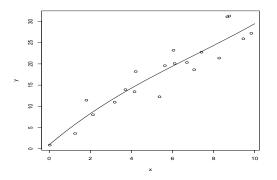
 $Y_i \sim N(1 + 3x_i, 3^2)$
consider $\hat{y} = polynomial(x, d), d = 1, ..., 10$



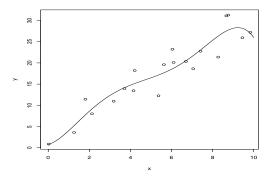
 $R'^2 = 0.865$, ANOVAp-value $\mathcal{O}(10^{-9})$ $\mathbb{E}[SSerror(Model, X_{n+1})] \approx 9.8$



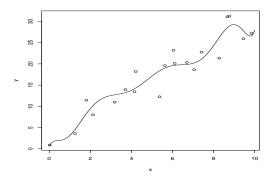
 $R'^2 = 0.861$, ANOVAp-value $\mathcal{O}(10^{-8})$ $\mathbb{E}[SSerror(Model, X_{n+1})] \approx 9.9$



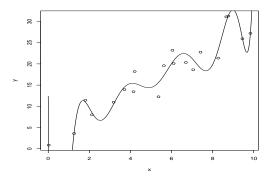
 $R'^2=0.877$, ANOVAp-value $\mathcal{O}(10^{-7})$, no individual "significant" $\hat{\beta}$'s $\mathbb{E}[SSerror(Model, X_{n+1})]\approx 9.9$



 $R'^2=0.889$, ANOVAp-value $\mathcal{O}(10^{-6})$, no individual "significant" $\hat{\beta}$'s $\mathbb{E}[SSerror(Model, X_{n+1})] \approx 10.9$



 $R'^2=0.902$, ANOVAp-value $\mathcal{O}(10^{-4})$, no individual "significant" $\hat{\beta}$'s $\mathbb{E}[SSerror(Model, X_{n+1})] \approx 11.7$



 $R'^2=0.950$, ANOVAp-value $\mathcal{O}(10^{-5})$, ALL individual "significant" $\hat{\beta}$'s $\mathbb{E}[SSerror(Model, X_{n+1})] \approx 240.9$

Overfitting

- ▶ With enough degrees of freedom we can obtain 0 training error
- **Example:** Linear regression

$$X \in \mathbb{R}^{p \times n}, p > n$$

 $y = \beta X$ is underdetermined $\Rightarrow \exists$ solution β for ANY y
 $\therefore \hat{y}_i = y_i, \ \forall i$

But there may be no (true) relationship between any elements of X and y

► In the last example we had the benefit of visualisation, but not always possible

- ► High dimensional random variables display some surprising "quirks"
- Some may be at first surprising, but even with minimal consideration are easy to explain
 - ► **Example** "All the mass of a uniform random variable over the hyper-cube lies on the surface"

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- Some may be at first surprising, but even with minimal consideration are easy to explain
- Others are just plain elusive (at least to me)
 - ► Example "All the mass of a uniform random variable over the hyper-cube lies on the surface"

Let $\mathbf{U}^p \sim U[0,1]^p$, then for any $0 < \epsilon < 1$

$$\lim_{
ho o\infty}\mathbb{P}\left(d(\mathbf{U}^{
ho},\mathsf{boundary}[0,1]^{
ho})<rac{1}{
ho^{\epsilon}}
ight)=1$$

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ight)=1$$

Or the weaker but maybe easier to interpret For any $\delta>0$

$$\lim_{p o \infty} \mathbb{P}\left(d(\mathbf{U}^p, \mathsf{boundary}[0,1]^p) < \delta\right) = 1$$

► Why?

► Why?

$$d(\mathbf{u}^p, \mathsf{boundary}[0, 1]^p) \ge 1/p^\epsilon$$

 $\Rightarrow \mathsf{min} \, \mathbf{u}^p \ge 1/p^\epsilon$
 $\iff \mathbf{u}^p_i \ge 1/p^\epsilon, \ \forall i \in \{1, ..., p\}$

$$\Rightarrow \mathbb{P}\left(d(\mathbf{U}^p,\mathsf{boundary}[0,1]^p)<rac{1}{p^\epsilon}
ight)\geq 1-\mathbb{P}(\mathbf{U}^p_i\geq 1/p^\epsilon,\;orall i)$$

$$=1-\left(1-rac{1}{p^\epsilon}
ight)^p$$

$$rac{as\;p o\infty}{}1$$

- ► The same is true of many other solids, including the sphere **Example:** "All the mass of a uniform random variable over the unit sphere lies on the surface"
- ▶ Slightly less obvious results also hold for the sphere **Example:** "All the mass of a uniform random variable over the unit sphere lies at the equator" That is, if $\mathbf{U} \sim U(\mathcal{S}^{p-1})$ then for any $\epsilon > 0$

$$\lim_{p o\infty}\mathbb{P}\left(-\epsilon<\mathsf{U}_1<\epsilon
ight)=1$$

- Some appear surprising, and remain so even after consideration
- ► **Example:** "As dimension increases the relative distance between random points becomes more uniform"

- Some appear surprising, and remain so even after consideration
- **Example:** "As dimension increases the relative distance between random points becomes more uniform" **Theorem** [?] For $p ∈ \mathbb{N}$ let $X_1^p, ..., X_n^p$ be i.i.d. p dimensional random variables (with each component of X_1^p having the same distribution, F, with finite, non-zero second moment). Define

$$DMIN_p := \min\{d(X_i^p, X^p)|i \in \{1, ..., n\}\}\$$

 $DMAX_p := \max\{d(X_i^p, X^p)|i \in \{1, ..., n\}\},$

(where X^p has the same distribution as X_1^p). Then

$$\frac{DMAX_p}{DMIN_p} \to_P 1$$
, as $p \to \infty$

Proof:

Proof:

Consider

$$\frac{1}{p}d(X_1^p,X^p)^2=\frac{1}{p}\sum_{i=1}^p(X_{1,i}^p-X_i^p)^2.$$

- ▶ WLLN $\Rightarrow \frac{1}{p}d(X_1^p, X^p)^2 \to_P \mathbb{E}[D^2] \neq 0$, where D is the difference between two independent random variables with distribution function F.
- $ightharpoonup : rac{1}{p} \max\{d(X_1^p, X^p)^2, ..., d(X_n^p, X^p)^2\} \to_P \mathbb{E}[D^2].$ similarly for min.
- Simplifying and taking square root gives the result.

Remarks:

- ▶ i.i.d dimensions is not a necessary condition
 - ► Authors discuss many other situations in which it holds
- "Query point" X^p does not have to have the same distribution as X_1^p , but must be independent.
- ▶ Equivalent statement of result: $\forall \epsilon > 0$

$$\lim_{
ho o \infty} \mathbb{P}(\mathit{DMAX}_{
ho} \leq \mathit{DMIN}_{
ho}(1+\epsilon)) = 1.$$

Especially important if data recorded with noise

Principal Components Analysis

- ► (Probably) the most popular dimension reduction technique
- ► Numerous formulations, with the most persuasive (to me) based on "reconstruction error":

$$\min_{V \in \mathbb{R}^{p \times p'}} ||X - XVV'||_F^2,$$

where X has been centered.

- ▶ Here we have $DR(X) = XV^*$ and $XV^*V^{*'}$ can be seen as taking this reduced form of X and putting it "back" into the original input space
 - ► This is not dissimilar from auto-encoders, where the objective is to "find a reduced form of X which can be almost inverted"
 - ► If I can more-or-less "undo" the dimension reduction, then I cannot have lost much information

Principal Components Analysis

- ▶ A common re-formulation is "find the orthonormal *V* which maximises the sum of the variances of the columns of *XV*."
- This re-formulation looks more like a "projection pursuit" formulation:
 - ► Find a projection of the data which is as "interesting as possible": maximise Interestingness(XV)
 - ▶ Projection taken to mean different things in different contexts, is XV or XVV' the projection? In projection pursuit it is XV, whereas in (general) linear algebra it is XVV'
- Why is/might the projection pursuit formulation be preferable?
 - ► Faster computationally
 - Invariant to rotations which are not permutations
- ► Why is/might the first formulation be preferable?
 - Convexity

Robust Principal Components Analysis

- Disclaimer: There are much fancier alternatives in other contexts. I will look only at simple variations from the standard model
- ► We can replace the squared loss with any "loss" function

$$||X - XVV'||_{2}^{F} = \sum_{i,j} (X_{ij} - X_{i:}VV'_{j:})^{2}$$

$$= \sum_{i,j} L(X_{ij}, X_{i:}VV'_{j:})$$

▶ The projection pursuit alternative (now not equivalent) is to maximise $\sum_{i,k} L(c(XV_{:k}), X_{i:}V_{:k})$ where $c(\cdot)$ is some measure of the center of the (projected) sample.

Let's play around in R

- ► We'll just use standard R optimisation for which we'll need objective functions and their gradients
- ▶ We have

$$D_{V}\left(\sum_{i,j}\ell(X_{ij}-X_{i}:VV'_{j}:)\right)=-\ell'(X-XVV')'XV$$
$$-X'\ell'(X-XVV')V$$

Let's play around in R

- ► There are more elegant ways of enforcing orthonormality, but we will use a "deflation" scheme for the projection pursuit formulation:
 - ► First find V_{·1}
 - ► Then repeatedly find the subsequent columns by applying the same procedure applied to the data projected into the null space of the columns found so far
- ▶ To enforce $||V_{:k}|| = 1$ we simply include in the evaluation of the objective the projection onto the unit sphere, i.e., we maximise over $v \in \mathbb{R}^p$

$$\sum_{i=1}^n \ell(c(X\vec{v}) - X_{i:}\vec{v}),$$

where $\vec{v} = v/||v||$, and then set $V_{:k} = \vec{v^*}$

If we set $c(\cdot)$ to be the mean and first center the observations then we have

$$\nabla_{v} \sum_{i=1}^{n} \ell(c(X\vec{v}) - X_{i:}\vec{v}) = \frac{1}{||v||} (I - \vec{v}\vec{v}') X' \ell'(c(X\vec{v}) - X\vec{v})$$