## Set 12: Splines – Part 2

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#### **Splines, Error, and Extrema**

The results concerning splines relative to the function f(x) interpolated and to other splines address three main properties:

• energy in a function

$$\int_{a}^{b} (g(x))^{2} dx = ||g||_{2}^{2}$$

curvature and total curvature of a function

$$\kappa(g) = \frac{g''(x)}{(1 + (g(x)')^2)^{3/2}}$$
$$\int_a^b (\kappa(x))^2 dx$$

approximation error

$$||f-s||_{\infty}$$

#### **Extremal Property**

**Theorem 12.1** (Ueberhuber). Given f(x), let  $w(x) \in C^2[a, b]$  be any interpolating function, i.e.,  $w(x_i) = f(x_i)$ , satisfying any one of the sets of boundary conditions:

1. 
$$w''(a) = w''(b) = 0$$

2. 
$$w'(a) = f'(a)$$
 and  $w'(b) = f'(b)$ 

3. 
$$w(a) = w(b), w'(a) = w'(b) \text{ and } w''(a) = w''(b)$$

If s(x) is the interpolating cubic spline of f(x) satisfying the same set of boundary conditions then

$$||s''||_2^2 \le ||w''||_2^2$$

i.e., the integral is minimal when w(x) = s(x) over all appropriate interpolating w(x).

## Curvature

If  $|w'(x)| \ll 1$  or if  $(w'(x))^2$  is almost constant then

$$\int_{a}^{b} (\kappa(x))^{2} dx \approx \int_{a}^{b} (w''(x))^{2} dx = \|w''(x)\|_{2}^{2}$$

So the spline has minimal curvature.

It may be the case, that the assumptions on w' are not valid. In such a case a cubic interpolating spline **may** have undesirable oscillation. Techniques are available to address this, see, e.g., Ueberhuber.

## **Boundary Conditions**

Natural boundary condition

$$s''(a) = s''(b) = 0$$

• Periodic boundary condition – assumes f(a) = f(b)

$$s''(a) = s''(b)$$
 and  $s'(a) = s'(b)$ 

• Hermite boundary conditions

$$s' = f'(a) \text{ and } s'(b) = f'(b) \tag{1}$$

$$s''(a) = f''(a) \text{ and } s''(b) = f''(b)$$
 (2)

### **Boundary Conditions**

- Hermite boundary conditions (derivative-free form)
  - Define two cubic interpolation polynomials,  $c_1(x)$  and  $c_2(x)$ , based on  $(x_0, x_1, x_2, x_3)$  and  $(x_{n-3}, x_{n-2}, x_{n-1}, x_n)$ .
  - Use the value of the first or second derivatives of  $c_1(x)$  and  $c_2(x)$

$$s' = c'_1(a) \text{ and } s'(b) = c'_2(b)$$
 (3)

$$s''(a) = c_1''(a) \text{ and } s''(b) = c_2''(b)$$
 (4)

Not-a-knot boundary conditions

$$s'''_{-}(x_1) = s'''_{+}(x_1)$$
 and  $s'''_{-}(x_{n-1}) = s'''_{+}(x_{n-1})$  (5)

Hall and Meyer (Jour. Approx. Theory V 16, 1976) show the following result:

**Theorem 12.2.** If s(x) be a cubic interpolating spline for  $f(x) \in C^4[a,b]$  and boundary conditions (1) or (2) then

$$||f^{(j)} - s^{(j)}||_{\infty} \le C_j h^{4-j} ||f^{(4)}||_{\infty}$$

for j = 0, 1, 2, 3 where

$$C_0 = 5/384$$
,  $C_1 = 1/24$ ,  $C_2 = 3/8$ ,  $C_3 = (\beta + \beta^{-1})/2$ 

where  $\beta$  is the ratio of the largest interval size, h, to the smallest interval size.

- $C_0$  and  $C_1$  are optimal over all nonzero  $f \in C^4$  and meshes with distinct points.
- So we have uniform convergence of s, s' and s'' to f, f' and f'' as  $h \to 0$  and for s''' when  $\beta$  is uniformly bounded.
- ullet Other degrees of smoothness for f and other boundary conditions have also been analyzed in the literature.

**Theorem 12.3.** (Beatson SIAM J. Num. Analysis, V 23, 1986, also see Ueberhuber) Let s(x) be a cubic interpolating spline for  $f(x) \in C^1[a,b]$  at distinct nodes  $x_i$  for  $0 \le i \le n$  with  $n \ge 5$  for boundary conditions (3), (5), and (4). Let  $h = \max_i h_i = \max_{1 \le i \le n} (x_i - x_{i-1})$ . It follows that on  $[x_{i-1}, x_i]$ 

$$\|(s-f)^{(k)}\|_{\infty} \le \begin{cases} C_1 \lambda_1^{-1} h_1^{1-k} \omega(f';h) & i=1\\ C_1 h_i^{1-k} \omega(f';h) & 2 \le i \le n-1\\ C_1 \mu_{n-1}^{-1} h_n^{1-k} \omega(f';h) & i=n \end{cases}$$

where k = 0, 1, h is the largest interval size,  $\lambda_i = h_{i+1}/(h_{i+1} + h_i)$ ,  $\mu_i = 1 - \lambda_i$ ,  $1 \le i \le n - 1$ , and

$$\omega(f^{(j)};h) = \max(|f^{(j)}(u) - f^{(j)}(v)| : u, v \in [a, b], |u - v| \le h)$$

is the modulus of continuity of  $f^{(j)}$ .

**Theorem 12.4.** (Beatson SIAM J. Num. Analysis, V 23, 1986, also see Ueberhuber) Let s(x) be a cubic interpolating spline for  $f(x) \in C^{j}[a, b]$  at distinct nodes  $x_{i}$  for  $0 \le i \le n$  with  $n \ge 5$  for boundary conditions (3), (5), and (4). Let  $h = \max_{i}(x_{i} - x_{i-1})$ . It follows that on  $[x_{i-1}, x_{i}]$ 

$$\|(s-f)^{(k)}\|_{\infty} \le C_2 h_i^{2-k} h^{j-2} \omega(f^{(j)}; h) \quad 1 \le i \le n$$

for j = 2 or j = 3 and k = 0, 1, 2, where h is the largest interval size, and

$$\omega(f^{(j)};h) = \max(|f^{(j)}(u) - f^{(j)}(v)| : u, v \in [a, b], |u - v| \le h)$$

is the modulus of continuity of  $f^{(j)}$ .

### **Summary of Uniform Convergence**

**Lemma 12.5.** For boundary conditions (3), (4), (5) and with  $f \in C^j[a, b]$  for j = 1, 2, 3 and k = 0, 1, 2

$$\|(s-f)^{(k)}\|_{\infty} = O(h^{j-k} \omega(f^{(j)};h))$$

$$\|(s-f)^{(k)}\|_{\infty} = O(h^{j-k+1})$$
 if  $f^{(j)}$  is Lipschitz continuous

For boundary conditions (1), (2), and with  $f \in C^4[a, b]$ 

$$||s - f||_{\infty} = O(h^4)$$

### **Derivation via Basis**

- Given a partition  $\pi$  the linear space of cubic splines,  $S_3(\pi)$ , has dimension n+3.
- Find a basis for  $S_3(\pi)$  consisting of n+3 linearly independent cubic splines.
- Determine interpoloatory spline by computing the n+3 coefficients of its expansion

$$s(x) = \sum_{1}^{n+3} \alpha_i \rho_i(x)$$

given  $f_0, \ldots, f_n$ .

- Many bases are possible, e.g., cardinal splines (see text)
- B-splines are often used.

## **B-splines**

Assume we have uniformly space nodes  $x_i = x_0 + i \frac{(b-a)}{n}$   $0 \le i \le n$ . Introduce 4 additional nodes,  $x_{-2} < x_{-1} < x_0$ , and  $x_{n+2} > x_{n+1} > x_n$ .

**Definition 12.1.** Let h = (b - a)/n. The function  $B_i(t)$  defined by

$$B_{i}(x) = \frac{1}{h^{3}}(x - x_{i-2})^{3}, \text{ if } x_{i-2} \leq x \leq x_{i-1}$$

$$= \frac{1}{h^{3}}(h^{3} + 3h^{2}(x - x_{i-1}) + 3h(x - x_{i-1})^{2} - 3(x - x_{i-1})^{3}), \text{ if } x_{i-1} \leq x \leq x_{i}$$

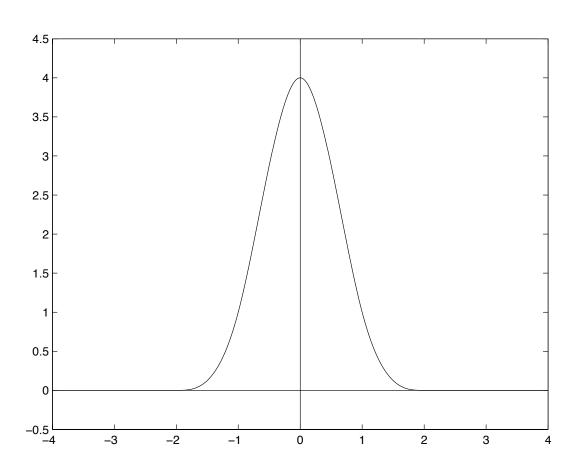
$$= \frac{1}{h^{3}}(h^{3} + 3h^{2}(x_{i+1} - x) + 3h(x_{i+1} - x)^{2} - 3(x_{i+1} - x)^{3}), \text{ if } x_{i} \leq x \leq x_{i+1}$$

$$= \frac{1}{h^{3}}(x_{i+2} - x)^{3}, \text{ if } x_{i+1} \leq x \leq x_{i+2}$$

$$= 0, \text{ otherwise}$$

is a cubic B-spline.

## **B-spline – Uniform Grid**



## **B-splines**

**Lemma.** The B-spline  $B_i(x)$  is twice continuously differentiable on  $\mathbb{R}$ , and is identically 0 when  $x \geq x_{i+2}$  or  $x \leq x_{i-2}$ .

The set  $\mathcal{B} = \{B_{-1}, B_0, \dots, B_{n+1}\}$  is a basis for  $S_3(\pi)$ .

	$x_{i-2}$	$x_{i-1}$	$x_i$	$x_{i+1}$	$x_{i+2}$
$B_i(x)$	0	1	4	1	0
$B_i'(x)$	0	$\frac{3}{h}$	0	$-\frac{3}{h}$	0
$B_i^{\prime\prime}(x)$	0	$\frac{6}{h^2}$	$-\frac{12}{h^2}$	$\frac{6}{h^2}$	0

## **Cubic Spline Interpolation via B-splines**

**Theorem 12.6.** Given,  $f'_0, f'_n$ ,  $f_i$  and  $x_0 < x_1 < \cdots < x_n$  for  $0 \le i \le n$  the unique cubic spline, s(x), such that

$$s(x_i) = f_i \quad 0 \le i \le n, \quad s'(x_0) = f'_0, \quad s'(x_n) = f'_n$$

is given by  $s(x) = \sum_{i=-1}^{n+1} \alpha_i B_i(x)$  where

$$\begin{pmatrix} -\frac{3}{h} & 0 & \frac{3}{h} & 0 & 0 & 0 & \cdots & 0 \\ 1 & 4 & 1 & 0 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 4 & 1 & 0 & 0 & \cdots & 0 \\ \vdots & & & \ddots & & & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 1 & 4 & 1 \\ 0 & 0 & 0 & 0 & \cdots & -\frac{3}{h} & 0 & \frac{3}{h} \end{pmatrix} \begin{pmatrix} \alpha_{-1} \\ \alpha_{0} \\ \vdots \\ \alpha_{n} \\ \alpha_{n+1} \end{pmatrix} = \begin{pmatrix} f'_{0} \\ f_{0} \\ \vdots \\ f_{n} \\ f'_{n} \end{pmatrix}$$

#### **Cubic Spline Interpolation via B-splines**

*Proof.* The linear system is simply a statement of the conditions imposed on s(x).

$$\alpha_{-1}B'_{-1}(x_0) + \alpha_0 B'_0(x_0) + \dots + \alpha_{n+1}B'_{n+1}(x_0) = f'_0$$

$$\alpha_{-1}B_{-1}(x_0) + \alpha_0 B_0(x_0) + \dots + \alpha_{n+1}B_{n+1}(x_0) = f_0$$

$$\vdots$$

$$\alpha_{-1}B_{-1}(x_n) + \alpha_0 B_0(x_n) + \dots + \alpha_{n+1}B_{n+1}(x_n) = f_n$$

$$\alpha_{-1}B'_{-1}(x_n) + \alpha_0 B'_0(x_n) + \dots + \alpha_{n+1}B'_{n+1}(x_n) = f'_n$$

The matrix is irreducibly diagonally dominant and nonsingular therefore the solution and spline is unique.

**B-splines** 

For a uniform grid the idea behind a B-spline can be explained in terms of forward difference and a basic cubic spline.

Recall the forward difference  $\Delta f_i = f_{i+1} - f_i$  and that  $\Delta^d p(x_i) \equiv 0$  if p(x) is a polynomial with degree d-1 or less.

We seek a cubic spline with limited support, i.e., that is identically 0 outside an interval.

Since we intend to associate the splines with various points (the nodes) and evaluate them over all of  $[x_0, x_n]$  the simplest spline should have two parameters x and t.

## **B-spline – Uniform Grid**

Consider

$$F_t(x) = (x-t)^3_+ = \begin{cases} (x-t)^3, & t \le x \\ 0, & t > x \end{cases}$$

 $F_t(x)$  is twice continuously differentiable with respect to x for a fixed t (and vice versa) but is not three times differentiable.

 $F_t(x)$  is piecewise cubic with respect to t for a fixed x and vice versa.

Note.  $F_t(x)$  has infinite support interval as a function of t with fixed x or vice versa. It also has an unbounded value asymptotically.

### **B-spline – Uniform Grid**

- We would like local support for the basis functions  $B_i(x)$ .
- Since  $F_t(x)$  is piecewise cubic w/r to x, we know  $\Delta^4$  should have intervals where it is identically 0.

Define K(t) as below and consider its behavior w/r to x and t:

$$K(t) = \Delta^4 F_t(x_0)$$

$$= F_t(x_4) - 4F_t(x_3) + 6F_t(x_2) - 4F_t(x_1) + F_t(x_0)$$

$$= (x_4 - t)_+^3 - 4(x_3 - t)_+^3 + 6(x_2 - t)_+^3 - 4(x_1 - t)_+^3 + (x_0 - t)_+^3$$

### **Behavior of** K(t)

First, we identify the intervals where  $K(t) \equiv 0$ .

- $x_0 < x_1 < x_2 < x_3 < x_4 \le t$ 
  - By definition, for a fixed x,  $(x-t)_+^3 = 0$  for all  $t \ge x$ .

$$- : (x_i - t)^3_+ = 0 \text{ for } 0 \le i \le 4 \text{ and } t \ge x_4$$

$$-: K(t) \equiv 0, \quad t \geq x_4.$$

- $t \le x_0 < x_1 < x_2 < x_3 < x_4$ 
  - By definition, for a fixed t,  $(x-t)^3_+ = (x-t)^3$  for  $x \ge t$ .
  - For  $\forall t \leq x_0$ , the  $F_t(x_i)$  are values of a cubic polynomial in x.

$$- : \Delta^4 F_t(x_0) = 0, \ t \le x_0$$

$$-: K(t) \equiv 0, \quad t \leq x_0.$$

### **Behavior of** K(t)

Only nonzero in  $x_0 \leq t \leq x_4$ .

$$K(t) = (x_4 - t)_+^3 - 4(x_3 - t)_+^3 + 6(x_2 - t)_+^3 - 4(x_1 - t)_+^3 + (x_0 - t)_+^3$$

$$x_0 \le t \le x_1 \to K(t) = (x_4 - t)^3 - 4(x_3 - t)^3 + 6(x_2 - t)^3 - 4(x_1 - t)^3 + 0$$

$$x_1 < t \le x_2 \to K(t) = (x_4 - t)^3 - 4(x_3 - t)^3 + 6(x_2 - t)^3 - 0 + 0$$

$$x_2 < t \le x_3 \to K(t) = (x_4 - t)^3 - 4(x_3 - t)^3 + 0 - 0 + 0$$

$$x_3 < t \le x_4 \to K(t) = (x_4 - t)^3 - 0 + 0 - 0 + 0$$

### **Equivalence to B-splines**

Let  $x_i = x_0 + ih$  and  $x_{i+j} = x_i + jh$  and  $x_2 < t \le x_3$ . We have

$$K(t) = (x_4 - t)^3 - 4(x_3 - t)^3$$

$$= (x_3 - t + h)^3 - 4(x_3 - t)^3$$

$$= h^3 + 3h^2(x_3 - t) + 3h(x_3 - t)^2 - 3(x_3 - t)^3$$

$$= h^3 B_2(t)$$

The equality is easily shown on the other intervals defining  $B_2(t)$ .

**Definition 12.2.** The cubic B-spline is defined by:

$$B_i(t) = \frac{1}{h^3} \Delta^4 F_t(x_{i-2})$$

### **Generalization to Higher Degree**

**Lemma.** Let  $F_{t,m}(x) = (x - t)_{+}^{m}$ . If

$$K_m(t) = \Delta^{m+1} F_{t,m}(x) = \sum_{i=0}^{m+1} {m+1 \choose i} (-1)^i (x_{m+1-i} - t)_+^m$$

then

$$K(t) \equiv 0 \quad t \leq x_0 \quad and \quad t \geq x_{m+1}$$

$$K(t) \in \mathcal{C}^{m-1}$$

$$\therefore K(t) \in S_m(\pi)$$

- The text gives the definition of B-splines for nonuniform nodes in terms of divided differences
- Note there is scale of 6 = 3! applied to all  $B_i(t)$  in the uniform node case in the text.

#### **Example**

Let 
$$m=1$$
. Define  $F_t(x)=(x-t)_+, \quad K(t)=\Delta^2 F_t(x_0).$ 

$$K(t)=(x_2-t)_+-2(x_1-t)_++(x_0-t)_+$$

$$=\begin{cases} (x_2-t) & x_1 \le t \le x_2 \\ (x_2-t)-2(x_1-t) & x_0 \le t \le x_1 \\ 0 & \text{otherwise} \end{cases}$$

$$=\begin{cases} h+(x_1-t) & x_1 \le t \le x_2 \\ h-(x_1-t) & x_0 \le t \le x_1 \end{cases}$$

After scaling with h to get the B-spline, this is the hat function on  $[x_0, x_2]$ .