Set 13: Parametric Curves

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Parametric Curves

- Consider a curve in \mathbb{R}^2 .
- Parametric form (x(t), y(t)) for $t_0 \le t \le t_n$ and $t \in \mathbb{R}$.
- Implies an ordering to the points.
- The interval can be adjusted to yield any length or rate of motion.
- Used in phase plane representation of behavior of a dynamical system.
- May have sample points of an underlying system.
- May have points in a plane from a graphics application.
- Order can be chosen and imposed on the parameter.
- Want a smooth curve to indicate the shape of the point collection.

Parametric Curves

A circle can be parameterized as

$$(\sin \omega t, \cos \omega t)$$

Frequency ω can be set to dictate the velocity around the circle as a function of t.

Suppose you had points on the circle

$$(x_i, y_i), 0 \le i \le n$$

Could draw the curve with

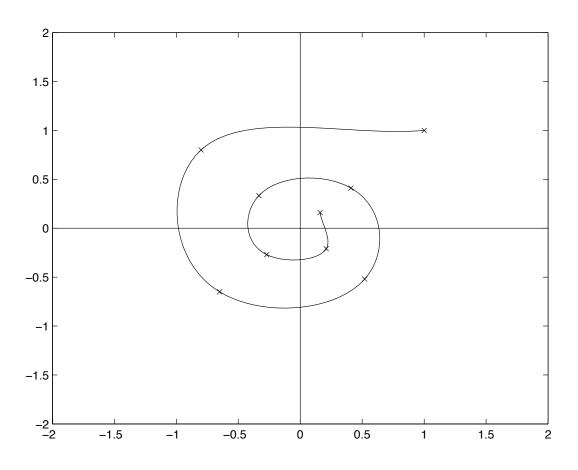
- simple linear connections
- piecewise Lagrange of any degree
- splines of any degree

Parameterization

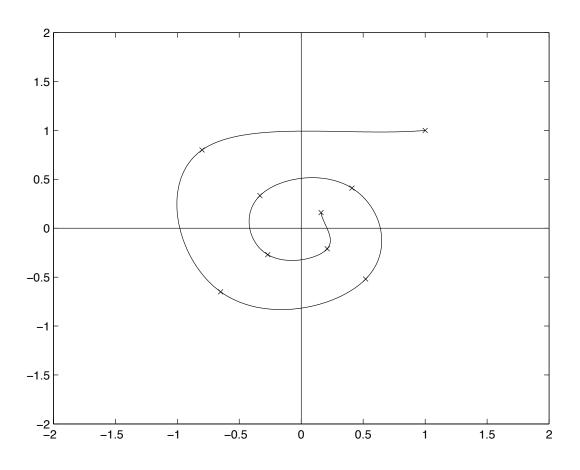
Given $(x_i, y_i), 0 \le i \le n$

Want parametric form (x(t), y(t)) for $t_0 \le t \le t_n$ but t is not implicit in the data.

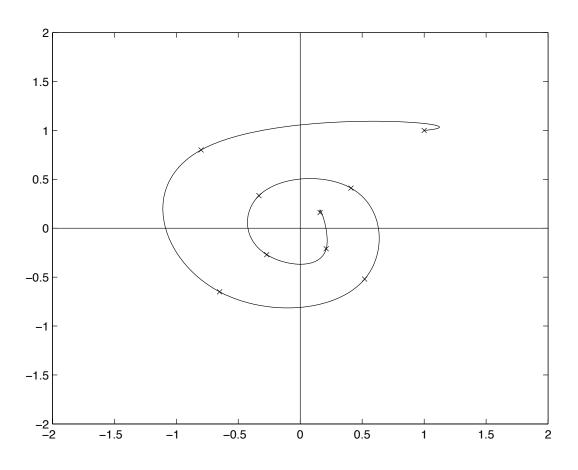
- Simple uniform scale
 - $t_0 \le t \le t_n$ with $t_0 = 0$ and $t_n = 1$
 - (x_i, y_i, t_i) with $t_i = i/n$
- Cumulative length scale
 - $t_0 \le t \le t_n$ with $t_0 = 0$ and $t_n = L$
 - $-t_i = \sum_{k=1}^i \ell_k \ 1 \le i \le n \text{ and } \ell_k = \|(x_k, y_k) (x_{k-1}, y_{k-1})\|_2$
- Fit sets (t_i, x_i) and (t_i, y_i) separately with a spline or other piecewise interpolating curve.
- For a closed curve add (t_{n+1}, x_0) (t_{n+1}, y_0) to each.



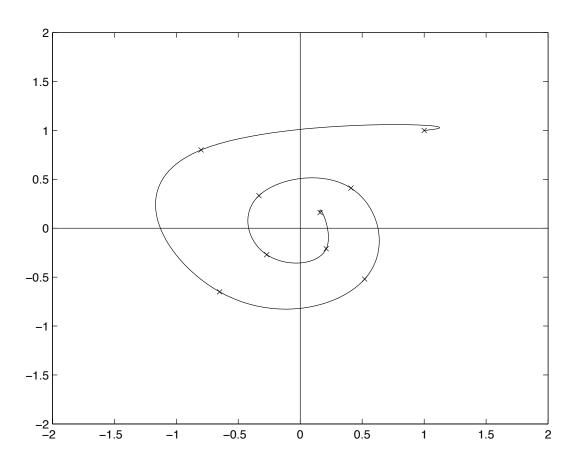
Ts'=d form, first divided difference boundary, arclength



Ts'=d form, first divided difference boundary, uniform

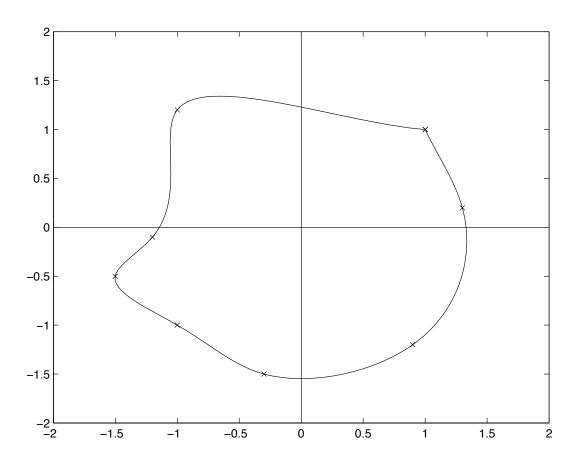


Ts'=d form, negative first divided difference boundary, arclength



Ts'=d form, negative first divided difference boundary, uniform

Closed Curve Data



Ts' = d form, first divided difference boundary, arclength. Where is (x_0, y_0) ?

Non-interpolating Curve

- In graphics, the points may not correspond to points on a curve.
- They may be 'anchor points' defined by a user to produce a particular shape.
- Points may be dragged interactively to affect shape
- Points may be added to affect shape.
- Parametric interpolation is no longer appropriate.
- Bezier curves or B-spline curves

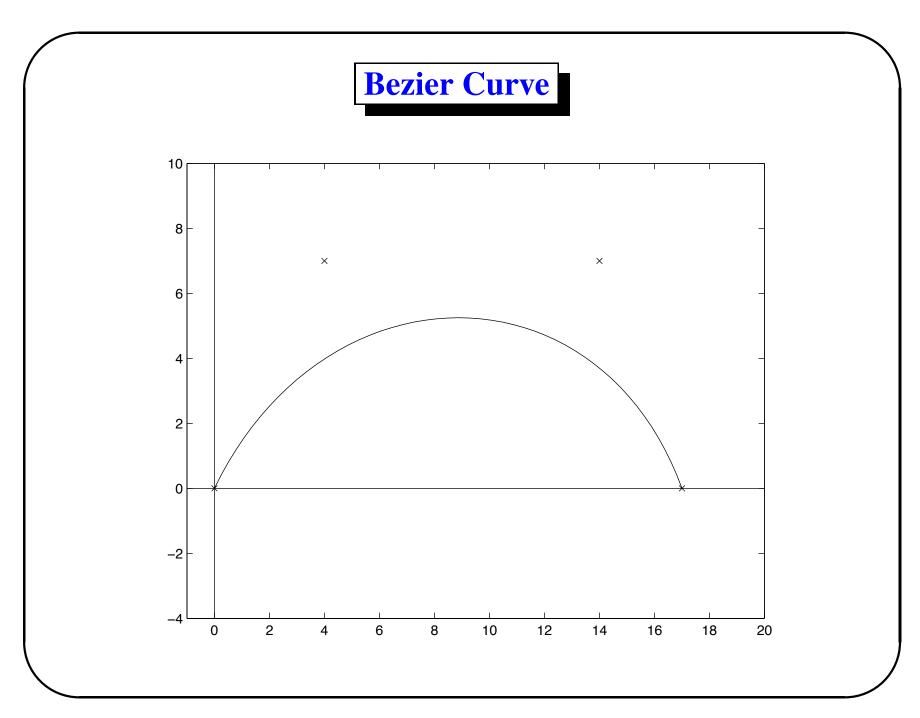
Bezier Curves

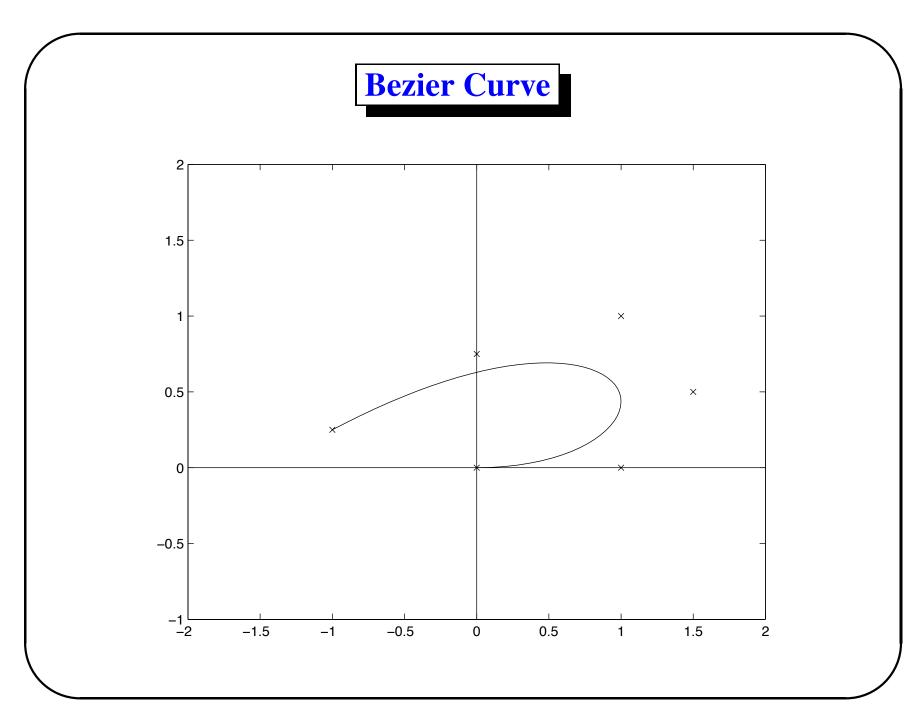
Recall the Bernstein basis polynomials on $0 \le t \le 1$,

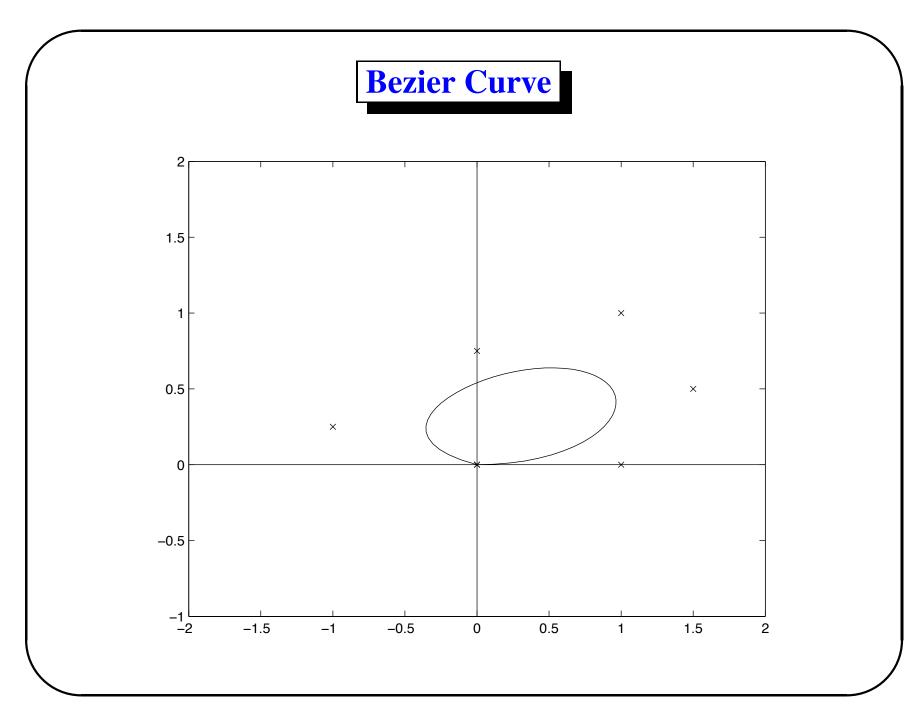
$$\phi_{n,k}(t) = \binom{n}{k} t^k (1-t)^{n-k}$$

The Bezier curve uses $p_i = (x_i, y_i)$, $0 \le i \le n$, as weights to form (x(t), y(t)).

$$\mathcal{B}_n(t) = \sum_{k=0}^n p_k \phi_{n,k}(t)$$







DeCasteljau's Algorithm

Due to the recursive properties of the basis functions, we have an elegant characterization of $\mathcal{B}_n(t)$.

$$p_{1,i} = (1-t)p_i + tp_{i+1}, \quad 0 \le i \le n-1$$

$$p_{2,i} = (1-t)p_{1,i} + tp_{1,i+1}, \quad 0 \le i \le n-2$$

$$\vdots$$

$$p_{n,0} = (1-t)p_{n-1,0} + tp_{n-1,1}$$

$$\mathcal{B}_n(t) = p_{n,0}$$

B-spline Curves

- The Bezier curve is often replaced by the B-spline curve that uses $p_i = (x_i, y_i), 0 \le i \le n$, as weights to form (x(t), y(t)).
- Two sets of points of interest:
 - 1. the control points, p_i , $0 \le i \le n$
 - 2. the knots t_i , $0 \le i \le m$, in the parameter t that define the splines
- Bernstein basis functions replaced by B-splines of degree d.
- It has the form

$$C(t) = \sum_{i=0}^{n} p_i B_{d,i}(t)$$

B-spline Curves

- $B_{d,i}(t)$ involves knots $t_i, t_{i+1}, \ldots, t_{i+d}, t_{i+d+1}$
- need n + d + 2 knots to define $B_{d,i}(t)$, $0 \le i \le n$ and, in general, must have m = n + d + 1
- knots can be simple or have multiplicity k

$$t_i = t_{i+1} = \dots = t_{i+k-1}$$

- manipulating multiplicity affects shape
- first and last knot with multiplicity d+1 clamps curve to first and last point.
- repeating knots and control points closes the curve
- control points and knots can be set separately