

Frame - [10]/s [3]n [100]ms  
Sample Rate - [10]/s  
Participant Speed - [20]  
Minimum Distance - [70]  
Sensor Range - [45]  
Neighbour Range - [80]  
Obstacle Repulsion - [40]  
Cohesion Physics - [5]  
Repulsion Physics - [15]  
Obstacle Physics - [100]  
Destination Physics - [100]  
Concave Physics - [100]  
DESTINATION MODE.  
NOT RECORDING.  
INFINITE RUN.  
PROCESSING.  
NEIGHBOUR RENDERING.  
FULL DETECTION (NE ALG)  
CONVEX COMPRESS.

PySwarm  
By M. Eliot  
0.2.7

