Frame - [10]/s[8]n [100]ms
Sample Rate   - [10]/s
Participant Speed - [20]
Minimum Distance   - [70]
Sensor Range   - [45]
Neighbour Range   - [80]
Obstacle Repulsion - [40]
Cohesion Physics   - [5]
Repulsion Physics - [15]
Obstacle Physics   - [100]
Destination Physics - [100]
Concave Physics   - [100]
DESTINATION MODE.
NOT RECORDING.
 INFINITE RUN.
NOT PROCESSING.
NEIGHBOUR RENDERING.
NO PERIMETER
CONVEX COMPRESS.

PySwarm
By N. Eliot
0.2.7